



# Low-Cost Cubesat Attitude Determination

## **Datasheet**

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### 1 Introduction

### 1.1 Project Overview

This project focuses on the development of an attitude determination system for a CubeSat operating in low Earth orbit. The system utilizes data from an onboard magnetometer and a sun sensor (6 Solar panels), to estimate the satellite's orientation relative to the Earth. The core processing and control algorithms are implemented on an ESP32 microcontroller, enabling real-time sensor data acquisition, processing, and attitude estimation.

### 2 Applications

The system is designed for low-budget missions (e.g., university projects, academic missions, research laboratories).

### 3 Project Scope

- Designing and simulating an attitude determination system using magnetometer and sun sensor data
- · Validating the system using test data
- · Hardware implementation
- · Documenting the methodology, results, and potential improvements
- · Providing recommendations for future hardware implementation and integration

## 4 System Design

## 4.1 Overall Architecture

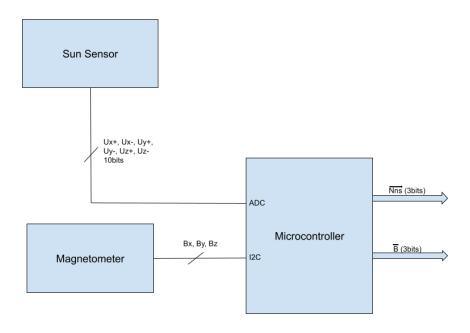


Figure 1: System architecture

### 4.2 System Schematic

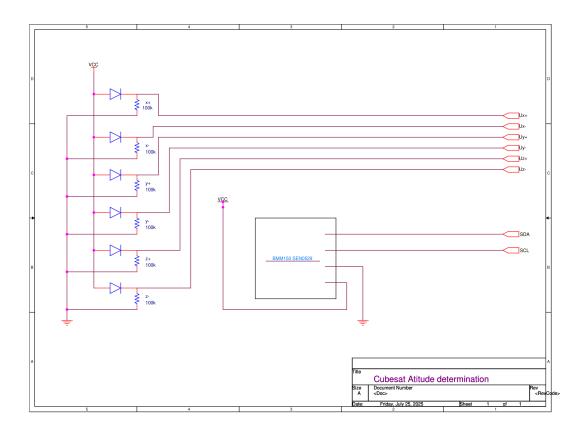


Figure 2: System Schematic

#### 4.3 Hardware

#### **Solar Panel**

The main function of the solar panel is to acquire data about the light intensity on each side of the CubeSat in order to calculate the sun-satellite vector.

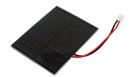


Figure 3: Solar Panel 0.5W



**Magnetometer**The magnetometer's role is to measure the mag-

netic field vector in the satellite's frame.

Figure 4: Magnetometer 3 axis BMM150 SEN0529

#### Microcontroller

The microcontroller combines the data issued from the two sensors in order to determine the attitude of the CubeSat.



Figure 5: Microcontroller ESP32

#### 4.4 Software