

# STATS305A - Lecture 12

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10/28/21

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## 1 Announcements

- Etude 2 due today 5pm.
- No class next Tuesday.

## 2 Model Selection and prediction

### 2.1 Motivation

Up to this point we've treated the model  $Y = X\beta + \varepsilon$  as "god-give". This is a bit inaccurate. In real life we will typically have data and no model and have to figure it out and select a model. When selecting a model we have two desiderata:

- Identify important features that are relating  $x$  to our response  $y$ .
- Pure predictive accuracy: how well can we predict  $y$  from  $x$ ?

These two are intertwined. We don't always have to choose one over the other.

### 2.2 Bias/Variance Decomposition

Suppose we are in a setting where  $y = f(x) + \varepsilon$  and  $\mathbb{E}[\varepsilon|x] = 0$ . This is equivalent to having  $f(x) = \mathbb{E}[Y|X = x]$  since if  $\varepsilon = y - f(x)$ , then

$$\mathbb{E}[\varepsilon|x] = \mathbb{E}[y|x] - f(x).$$

Thus  $\mathbb{E}[\varepsilon|x] = 0$  if and only if  $f(x) = \mathbb{E}[y|x]$ . Define  $\sigma^2(x) = \mathbb{E}[\varepsilon^2|x]$  which is the conditional variance of  $\varepsilon$ .

Our goal is to fit a predictor  $\hat{f}$  using a sample  $\{(x_i, y_i)\}_{i=1}^n$ . Note that if we think of the sample of  $\{(x_i, y_i)\}_{i=1}^n$  as random, then the predictor  $\hat{f}$  is random (like how  $\hat{\beta}$  is random in the linear model). Thus we can take the expectation of quantities involving  $\hat{f}$  over all samples  $\{(x_i, y_i)\}_{i=1}^n$ . This idea will be used many times over the course of this lecture.

**Definition 1.** If we have a predictor  $\hat{f}$  of a model  $y = f(x) + \varepsilon$ , then we define the *in-sample (MSE) risk* of  $\hat{f}$  to be

$$R_{in}(\hat{f}) = \mathbb{E} \left[ \frac{1}{n} \sum_{i=1}^n (\hat{f}(x_i) - f(x_i))^2 \right],$$

where the above expectation is taken over all samples  $\{(x_i, y_i)\}_{i=1}^n$  with  $x_i$  fixed. (That is we fix  $x$  and calculate  $\hat{f}$  using different samples  $(x, y)$ , we then calculate the quantity  $\frac{1}{n} \sum_{i=1}^n (\hat{f}(x_i) - f(x_i))^2$  and take the expectation over all samples  $(x, y)$ .)

**Aside 1.** Sometimes the in-sample risk is called the  $L^2(P_n)$  risk. This is because  $R_{in}$  is the expectation of the  $L^2$  norm error of  $\hat{f} - f$  with respect to the distribution

$$P_n = \frac{1}{n} \sum_{i=1}^n \mathbf{1}_{x_i}.$$

**Definition 2.** Sometimes the insample risk is defined with respect to a fresh sample  $\{Y_i^*\}_{i=1}^n$  where

$$Y_i^* = \text{a new sample of } Y_i = f(x_i) + \varepsilon_i^*,$$

where  $\varepsilon_i^*$  is an independent copy of  $\varepsilon_i$ . We then define

$$R_{in}^*(\hat{f}) = \mathbb{E} \left[ \frac{1}{n} \sum_{i=1}^n (Y_i^* - \hat{f}(x_i))^2 \right],$$

where here the expectation is over both  $Y_1, \dots, Y_n$  (used to calculate  $\hat{f}$ ) and over  $Y_1^*, \dots, Y_n^*$  (used to calculate  $(Y_i^* - \hat{f}(x_i))^2$ ).

Note that

$$R_{in}^*(\hat{f}) = \mathbb{E} \left[ \frac{1}{n} \sum_{i=1}^n (Y_i^* - \hat{f}(x_i))^2 \right] \tag{1}$$

$$= \mathbb{E} \left[ \frac{1}{n} \sum_{i=1}^n (Y_i^* - f(x_i))^2 \right] + \mathbb{E} \left[ \frac{1}{n} \sum_{i=1}^n (\hat{f}(x_i) - f(x_i))^2 \right] \tag{2}$$

$$= \frac{1}{n} \sum_{i=1}^n \sigma^2(x_i) + R_{in}(\hat{f}). \tag{3}$$

We call  $\frac{1}{n} \sum_{i=1}^n \sigma^2(x_i)$  the irreducible error.

Now suppose that we have a function  $g : \mathcal{X} \rightarrow \mathbb{R}$  where  $\mathcal{X}$  is the space  $X$  lives in. Note that  $g$  is different to  $\hat{f}$ . The predictor  $\hat{f}$  is something that the depend on the sample  $(x, y)$  used to fit  $\hat{f}$ . The function  $g$  is simply a function. It is a way of taking an  $X$  and producing a number. With this in mind we define

**Definition 3.** Given a function  $g : \mathcal{X} \rightarrow \mathbb{R}$ , the *(MSE) out of sample risk* of  $g$  is

$$R_{out}(g) = \mathbb{E}[(Y - g(X))^2] = \int_{\mathcal{X}} \mathbb{E}[(Y - g(x))^2 | X = x] p(x) dx.$$

Here the expectation is over both  $Y$  and  $X$  (hence out of sample - we are allowing  $X$  to change).

Note that

$$\begin{aligned} R_{out}(g) &= \mathbb{E}[(Y - f(X) + f(X) + g(X))^2] \\ &= \mathbb{E}[(Y - f(X))^2] + \mathbb{E}[(f(X) - g(X))^2] + 2\mathbb{E}[(Y - f(X))(f(X) - g(X))] \\ &= \mathbb{E}[\sigma^2(X)] + \mathbb{E}[(f(X) - g(X))^2]. \end{aligned}$$

We again call  $\mathbb{E}[\sigma^2(X)]$  the irreducible error and we could call  $\mathbb{E}[(f(X) - g(X))^2]$  the error in mean prediction (this last term is just a term John used - he said that there isn't really a term in literature for it).

In the out of sample risk we average over all the  $X$ 's we could possibly draw. In the in sample we fix the value  $x_i$  and average over all possible  $y_i$ . Note that if our data is i.i.d., then

$$R_{out}(g) = \mathbb{E}[(g(X_{n+1}) - Y_{n+1})^2].$$