

# STATS300A - Lecture 4

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## 1 Announcements

- HW1 due today.
- HW2 will be posted today.

## 2 Recap

We have seen

- Exponential families.
- Data reduction:
  - Sufficiency (all necessary information),
  - Minimal sufficiency (coarest sufficient statistic),
  - Ancillary (useless data),
  - Completeness (contains no useless data).

Today we will look at optimal unbiased estimation but first a refresher on conditional expectations.

### 3 Conditional expectation

(See Keener Chp 1.1) Let  $X$  and  $Z$  be random variables with density  $p(x, z) = p(z|x)p(x)$ . Let  $h$  be a function with finite expectation, that is

$$\int \int |h(x, z)|p(z|x)p(x)dzdx < \infty.$$

Then we define the conditional expectation of  $h$  given  $Z$  as

$$\mathbb{E}[h(X, Z)|X = x] = \int h(x, z)p(z|x)dx.$$

Note that  $\mathbb{E}[h(X, Z)|X]$  is a function of  $x$ . Some properties of conditional expectation are

- (Pull out property)  $\mathbb{E}[h_1(X)h_2(X, Y)|X = x] = h_1(x)\mathbb{E}[h_2(X, Y)|X = x]$ .
- (Tower property)  $\mathbb{E}[\mathbb{E}[h(X, Z)|X]] = \mathbb{E}[h(X, Z)]$ .
- (Independence) If  $X$  and  $Z$  are independent ( $p(z|x) = p(z)$  for all  $x, z$ ), then

$$\mathbb{E}[h(Z)|X = x] = \mathbb{E}[h(Z)].$$

We will use these ideas when studying estimation.

## 4 Estimation

### 4.1 Complete statistics

See TSH Theorem 4.3.1. In a full rank exponential family, the statistic  $(T_1, \dots, T_s)$  is complete.

**Theorem 1.** [Basu's Theorem] *If  $T$  is complete and sufficient for  $\mathcal{P} = \{P_\theta : \theta \in \Omega\}$  and  $A$  is ancillary for  $\mathcal{P}$ , then  $T(X)$  is independent of  $A(X)$  which we write as  $A(X) \perp\!\!\!\perp T(X)$ .*

By independent we mean for all events  $C$ ,  $P_\theta(A(X) \in C | T(X) = t) = P_\theta(A(X) \in C)$ . We will not prove this here but it can be done using the tower property. Here is an application of this theorem.

**Example 1.** Let  $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} N(\mu, \sigma^2)$  where both  $\mu$  and  $\sigma^2$  are unknown. We wish to show that  $\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$  and  $S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$  are independent.

*Proof.* Fix  $\sigma^2$  and consider the model where only  $\mu$  is unknown. This is an exponential family and thus the statistic  $\bar{X}$  is complete and sufficient. Also since we are working with a location model the statistic

$$S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}),$$

has the same distribution as

$$\frac{1}{n-1} \sum_{i=1}^n (Z_i - \bar{Z}),$$

where  $Z_i \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$ . Thus, by Basu's theorem  $S^2 \perp\!\!\!\perp \bar{X}$ . Although we fixed  $\sigma^2$  in the submodel,  $\sigma^2$  was arbitrary and thus  $S^2 \perp\!\!\!\perp \bar{X}$  regardless of  $\mu$  and  $\sigma^2$ .  $\square$

## 4.2 Risk reduction via conditioning

**Definition 1.** Let  $C$  be a convex subspace of a vector space. A function  $f : C \rightarrow \mathbb{R}$  is *convex* if

$$f(\gamma x + (1 - \gamma)y) \leq \gamma f(x) + (1 - \gamma)f(y),$$

for all  $x, y \in C$  and all  $\gamma \in [0, 1]$ . If we have strict inequality for all  $x, y \in C$  and  $\gamma \in (0, 1)$ , then we say that  $f$  is *strictly convex*.

**Theorem 2.** [Jensen's Inequality] Let  $f : C \rightarrow \mathbb{R}$  be convex on an open subset  $C$  with  $P(X \in C) = 1$ . If  $\mathbb{E}[X]$  exists, then

$$f(\mathbb{E}[X]) \leq \mathbb{E}[f(X)].$$

If  $f$  is strictly convex then

$$f(\mathbb{E}[X]) < \mathbb{E}[f(X)],$$

unless  $P(X = \mathbb{E}[X]) = 1$ .

Recall that  $L(\theta, d)$  is the penalty when  $\theta$  is the true parameter and decision  $d$  is made. Also recall that  $R(\theta, \delta) = \mathbb{E}_\theta[L(\theta, \delta(X))]$  is the risk of the decision procedure  $\delta$ .

**Theorem 3.** [Rao-Blackwell] Suppose that  $T$  is sufficient for  $\{P_\theta : \theta \in \Omega\}$  and that  $\delta(X)$  is an estimator with  $\mathbb{E}_\theta|\delta(X)| < \infty$  and  $R(\theta, \delta) < \infty$ . Let  $\eta(T) = \mathbb{E}[\delta(X)|T]$  (which is well-defined because  $T$  is sufficient). Then

(a) If  $L(\theta, \cdot)$  is convex for a fixed  $\theta$ , then

$$R(\theta, \eta) \leq R(\theta, \delta).$$

(b) If  $L(\theta, \cdot)$  is strictly convex for a fixed  $\theta$ , then

$$R(\theta, \eta) < R(\theta, \delta),$$

unless  $\eta(T(X)) = \delta(X)$  with probability 1.

*Proof.* For (a),

$$\begin{aligned} R(\theta, \eta) &= \mathbb{E}_\theta[L(\theta, \eta(X))] \\ &= \mathbb{E}_\theta[L(\theta, \mathbb{E}[\delta(X)|T])] \\ &\leq \mathbb{E}_\theta[\mathbb{E}[L(\theta, \delta(X))|T]] \quad (\text{Jensen's inequality}) \\ &= \mathbb{E}_\theta[L(\theta, \delta(X))] \quad (\text{Tower property}) \\ &= R(\theta, \delta). \end{aligned}$$

For (b) we note that this inequality is strict if  $P(\eta(T) \neq \delta(X)) > 0$ . □

The take away

- Under convex loss, a deterministic estimator based on sufficient statistics is as good or better than any other estimator.
- If our loss is strictly convex, then additional randomness deteriorates performance.

**Example 2.**  $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \text{Bern}(\theta)$ ,  $L(\theta, d) = (\theta - d)^2$  and  $\delta(X) = X_1$ . We know that  $T(X) = \sum_{i=1}^n X_i$  is sufficient for this model. Thus Rao-Blackwell states

$$\eta(T) = \mathbb{E}[X_1|T(X)],$$

is at least as good as  $\delta$ . Note that  $\eta(T) = \mathbb{E}[X_i|T]$  by the iid assumption. Thus

$$\begin{aligned}\eta(T) &= \frac{1}{n}(n\eta(T)) \\ &= \frac{1}{n} \left( \sum_{i=1}^n \mathbb{E}[X_i|T] \right) \\ &= \frac{1}{n} \mathbb{E}[T|T] \\ &= \frac{1}{n} T \\ &= \frac{1}{n} \sum_{i=1}^n X_i \\ &= \bar{X}.\end{aligned}$$

Thus Rao-Blackwell recovers the sample average. The risk of  $\delta$  was  $\theta(1-\theta)$  and the risk of  $\eta$  is  $\frac{\theta(1-\theta)}{n}$ .

Consider also the example  $\delta_{\text{goofy}}(X) = 0.5$ . Then  $\eta(T) = \mathbb{E}[0.5|T] = 0.5 = \delta_{\text{goofy}}(X)$  so Rao-Blackwell does not improve our estimator (it also doesn't make it worse). Conditioning reduces variance but it does not reduce bias.

### 4.3 Optimal unbiased estimators

Goal: Find the uniformly minimum risk unbiased estimator (UMRUE). That is we want for a fixed function  $g$

- (a)  $\mathbb{E}_\theta \delta(X) = g(\theta)$ , for all  $\theta \in \Omega$ .
- (b)  $R(\theta, \delta) \leq R(\theta, \delta')$  for all  $\theta \in \Omega$  and all decision procedures  $\delta$  satisfying (a).

A special case is when  $L(\theta, d) = (g(\theta) - d)^2$ , then the UMRUE is also called a UMVUE where the V stands for variance. This is because in this case  $R(\theta, \delta) = \text{bias}^2 + \text{variance} = \text{variance}$ .

**Theorem 4.** [Lehmann-Scheffe] *If  $T$  is complete and sufficient and  $\mathbb{E}_\theta h(T) = g(\theta)$  for all  $\theta$ , then*

- (a)  $h(T)$  is the only function of  $T$  that is unbiased for  $g(\theta)$ .
- (b)  $h(T)$  is the UMRUE if  $L(\theta, \cdot)$  is convex for all  $\theta \in \Omega$ .
- (c)  $h(T)$  is the unique UMRUE if  $L(\theta, \cdot)$  is convex for all  $\theta \in \Omega$  and  $L(\theta_0, \cdot)$  is strictly convex for some  $\theta_0 \in \Omega$ .
- (d)  $h(T)$  is the unique UMVUE.

*Proof.* Suppose  $\mathbb{E}_\theta \tilde{h}(T) = g(\theta)$  for all  $\theta \in \Omega$ , then  $E_\theta[(h - \tilde{h})(T)] = 0$  for all  $\theta \in \Omega$ . Thus  $h - \tilde{h}$  is first order ancillary for  $T$  and since  $T$  is complete, this implies  $h - \tilde{h} = 0$ . Thus  $\tilde{h} = h$  and we have proved part (a).

Suppose  $\delta$  is an unbiased estimator for  $g(\theta)$ . Define  $\eta(T) = \mathbb{E}[\delta(X)|T]$ , then  $\eta(T)$  is unbiased by the tower property and well defined by sufficiency. Since  $\eta(T)$  is a function of  $T$  we have  $\eta(T) = h(T)$  by part (a). Finally by Rao-Blackwell we have for all  $\theta \in \Omega$ .

$$R(\theta, h(t)) = R(\theta, \eta(T)) \leq R(\theta, \delta(X)), \quad (1)$$

thus  $h$  is UMRUE.

Suppose  $L(\theta_0, \cdot)$  is strictly convex, then the inequality (1) is strictly convex unless  $h(T) = \delta(X)$ . This shows that  $h(T)$  is the unique UMRUE.

Finally the case of mean square error is a special case of a strictly convex loss. Thus part (c) implies part (d).  $\square$

#### 4.4 Consequences

As a consequence of this theorem we can do optimal estimation for full rank exponential families as we know their complete sufficient statistics. This theorem also gives us strategies for finding UMRUEs.

- (a)
  - i. Find a complete sufficient statistic  $T$ .
  - ii. Find an unbiased estimator  $\delta$ .
  - iii. Compute  $\mathbb{E}[\delta(X)|T]$ .

Step (iii) may be hard.

- (b)
  - i. Find a complete sufficient statistic  $T$ .
  - ii. Recall that there is at most one unbiased estimator that is a function of  $T$  and that this function is the UMRUE.
  - iii. Solve for  $\delta$  in the equation  $\mathbb{E}_\theta[\delta(T)] = g(\theta)$
- (c) Guess the UMRUE.