



## bq27441-G1 System-Side Impedance Track™ Fuel Gauge

### 1 Features

- Single Series Cell Li-Ion Battery Fuel Gauge
  - Resides on System Board
  - Supports Embedded or Removable Batteries
  - Powered Directly from Battery with Integrated LDO
  - Supports a Low-Value External Sense Resistor (10 mΩ)
- Battery Fuel Gauging Based on Patented Impedance Track™ Technology
  - Reports Remaining Capacity and State-of-Charge (SOC) with Smoothing Filter
  - Automatically Adjusts for Battery Aging, Self-discharge, Temperature, and Rate Changes
  - Battery State-of-Health (Aging) Estimation
- Microcontroller Peripheral Supports:
  - 400-kHz I<sup>2</sup>C Serial Interface
  - Configurable SOC Interrupt or Battery Low Digital Output Warning
  - Internal Temperature Sensor or Host-Reported Temperature

### 2 Applications

- Smartphones, Feature Phones, and Tablets
- Digital Still and Video Cameras
- Handheld Terminals
- MP3 or Multimedia Players

### 3 Description

The Texas Instruments bq27441-G1 fuel gauge is a microcontroller peripheral that provides system-side fuel gauging for single-cell Li-Ion batteries. The device requires minimal user configuration and system microcontroller firmware development.

The bq27441-G1 battery fuel gauge uses the patented Impedance Track™ algorithm for fuel gauging, and provides information such as remaining battery capacity (mAh), state-of-charge (%), and battery voltage (mV).

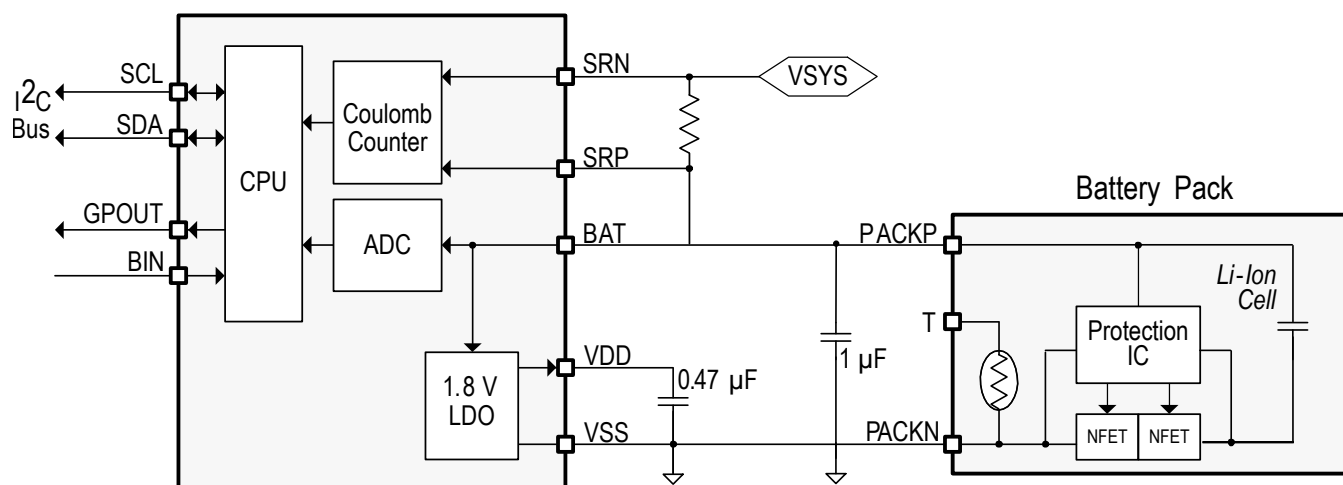
Battery fuel gauging with the bq27441-G1 fuel gauge requires connections only to PACK+ (P+) and PACK– (P–) for a removable battery pack or embedded battery circuit. The tiny, 12-pin, 2.50 mm × 4.00 mm, small outline no-lead (SON) package is ideal for space-constrained applications.

#### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
bq27441-G1	VSON (12)	2.50 mm × 4.00 mm

(1) For all available packages, see the orderable addendum at the end of the datasheet.

### 4 Simplified Schematic



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## 5 Revision History

Changes from Revision B (August 2014) to Revision C	Page
• Changed simplified schematic by adding two 1 $\mu$ F capacitors	1
• Added description for connecting 1- $\mu$ F capacitor	4
• Added information for connecting GPOUT	4
• Changed Handling Ratings to ESD Ratings	5
• Changed connection description for BAT pin	18
• Changed recommend to required	18
• Added arrow to C <sub>BAT</sub> from text	19

Changes from Revision A (January 2014) to Revision B	Page
• Added <i>Handling Ratings</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i> , <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Layout</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section	1
• Changed LiMnO <sub>4</sub> to LiCoO <sub>2</sub>	4
• Updated BAT pin description	4
• Updated BIN pin description	4
• Updated GPOUT pin description	4
• Updated SRN and SRP pin descriptions	4
• Changed the I <sub>lkg</sub> parameters	6

**Changes from Original (November 2013) to Revision A**
**Page**

- Changed the device status from Product Preview to Production Data ..... [1](#)

## 6 Device Comparison Table

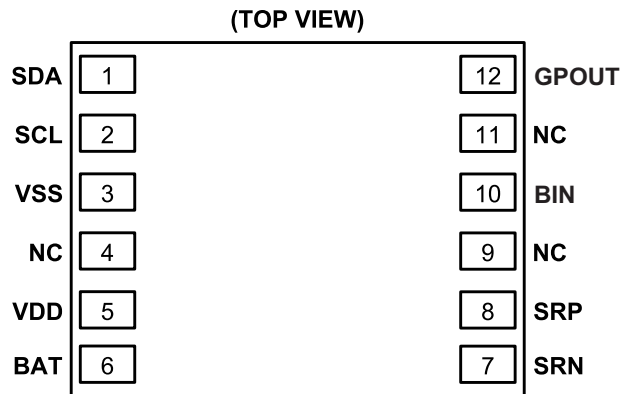
PART NUMBER	BATTERY TYPE	CHEM_ID <sup>(1)</sup>	DM_CODE <sup>(2)</sup>	FIRMWARE VERSION <sup>(3)</sup>
bq27441DRZR-G1A	LiCoO <sub>2</sub> (4.2 V maximum charge)	0x0128	0x48	1.09 (0x0109)
bq27441DRZT-G1A				
bq27441DRZR-G1B	LiCoO <sub>2</sub> (4.3 to 4.35 V maximum charge)	0x0312	0x58	
bq27441DRZT-G1B				

(1) See the *CHEM\_ID* subcommand to confirm the battery chemistry type.

(2) See the *DM\_CODE* subcommand to confirm the Data Memory code.

(3) See the *FW\_VERSION* subcommand to confirm the firmware version.

## 7 Pin Configuration and Functions



### Pin Functions

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NUMBER		
BAT	6	PI, AI	LDO regulator input and battery voltage measurement input. Kelvin sense connect to positive battery terminal (PACKP). Connect a capacitor (1 $\mu$ F) between BAT and V <sub>SS</sub> . Place the capacitor close to the gauge.
BIN	10	DI	Battery insertion detection input. If <b>OpConfig [BI_PU_EN]</b> = 1 (default), a logic low on the pin is detected as battery insertion. For a removable pack, the BIN pin can be connected to V <sub>SS</sub> through a pullup resistor on the pack, typically the 10-k $\Omega$ thermistor; the system board should use a 1.8-M $\Omega$ pullup resistor to V <sub>DD</sub> to ensure the BIN pin is high when a battery is removed. If the battery is embedded in the system, it is recommended to leave <b>[BI_PU_EN]</b> = 1 and use a 10-k $\Omega$ pullup resistor from BIN to V <sub>SS</sub> . If <b>[BI_PU_EN]</b> = 0, then the host must inform the gauge of battery insertion and removal with the <b>BAT_INSERT</b> and <b>BAT_REMOVE</b> subcommands. A 10-k $\Omega$ pullup resistor should be placed between BIN and V <sub>SS</sub> , even if this pin is unused. <b>NOTE:</b> The BIN pin must not be shorted directly to V <sub>CC</sub> or V <sub>SS</sub> and any pullup resistor on the BIN pin must be connected only to V <sub>DD</sub> and not an external voltage rail.
GPOUT	12	DO	This open-drain output can be configured to indicate BAT_LOW when the <b>OpConfig [BATLOWEN]</b> bit is set. By default <b>[BATLOWEN]</b> is cleared and this pin performs an interrupt function (SOC_INT) by pulsing for specific events, such as a change in state-of-charge. Signal polarity for these functions is controlled by the <b>[GPIOPOL]</b> configuration bit. This pin should not be left floating, even if unused; therefore, a 10-k $\Omega$ pullup resistor is recommended. If the device is in shutdown mode, then toggling GPOUT will make the gauge exit shutdown. Therefore, it is recommended to connect GPOUT to a GPIO of the host MCU.
NC	4, 9, 11	—	No internal connection. May be left floating or tied to V <sub>SS</sub> .
SCL	2	DIO	Slave I <sup>2</sup> C serial bus for communication with system (Master). Open-drain pins. Use with external 10-k $\Omega$ pullup resistors (typical) for each pin. If the external pullup resistors will be disconnected from these pins during normal operation, recommend using external 1-M $\Omega$ pullup resistors to V <sub>SS</sub> at each pin to avoid floating inputs.
SDA	1	DIO	
SRN	7	AI	Coulomb counter differential inputs expecting an external 10 m $\Omega$ , 1% sense resistor in the high-side current path. Kelvin sense connect SRP to the positive battery terminal (PACKP) side of the external sense resistor. Kelvin sense connect SRN to the other side of the external sense resistor, the positive connection to the system (VSYS). See the <a href="#">Simplified Schematic</a> . No calibration is required. The fuel gauge is pre-calibrated for a standard 10 m $\Omega$ , 1% sense resistor.
SRP	8	AI	
V <sub>DD</sub>	5	PO	1.8-V regulator output. Decouple with 0.47- $\mu$ F ceramic capacitor to V <sub>SS</sub> . This pin is not intended to provide power for other devices in the system.
V <sub>SS</sub>	3	PI	Ground pin

(1) IO = Digital input-output, AI = Analog input, P = Power connection

## 8 Specifications

### 8.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
V <sub>BAT</sub>	BAT pin input voltage range	–0.3	6	V
V <sub>SR</sub>	SRP and SRN pins input voltage range	–0.3	V <sub>BAT</sub> + 0.3	V
	Differential voltage across SRP and SRN. ABS(SRP – SRN)		2	V
V <sub>DD</sub>	V <sub>DD</sub> pin supply voltage range (LDO output)	–0.3	2	V
V <sub>IOD</sub>	Open-drain IO pins (SDA, SCL)	–0.3	6	V
V <sub>IOPP</sub>	Push-pull IO pins (BIN)	–0.3	V <sub>DD</sub> + 0.3	V
T <sub>A</sub>	Operating free-air temperature range	–40	85	°C
	Storage temperature, T <sub>stg</sub>	–65	150	°C

- (1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 8.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1500	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±250	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 8.3 Recommended Operating Conditions

T<sub>A</sub> = 30°C and V<sub>REGIN</sub> = V<sub>BAT</sub> = 3.6 V (unless otherwise noted)

			MIN	TYP	MAX	UNIT
C <sub>BAT</sub> <sup>(1)</sup>	External input capacitor for internal LDO between BAT and V <sub>SS</sub>	Nominal capacitor values specified. Recommend a 5% ceramic X5R-type capacitor located close to the device.		0.1		μF
C <sub>LDO18</sub> <sup>(1)</sup>	External output capacitor for internal LDO between V <sub>DD</sub> and V <sub>SS</sub>			0.47		μF
V <sub>PU</sub> <sup>(1)</sup>	External pullup voltage for open-drain pins (SDA, SCL, GPOUT)		1.62		3.6	V

- (1) Specified by design. Not production tested.

### 8.4 Thermal Information

	THERMAL METRIC	DRZ (12 PINS)	UNIT
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	64.1	°C/W
R <sub>θJctop</sub>	Junction-to-case (top) thermal resistance	59.8	
R <sub>θJB</sub>	Junction-to-board thermal resistance	52.7	
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.3	
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	28.3	
R <sub>θJCbot</sub>	Junction-to-case (bottom) thermal resistance	2.4	

## 8.5 Supply Current

 $T_A = 30^\circ\text{C}$  and  $V_{\text{REGIN}} = V_{\text{BAT}} = 3.6\text{V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{\text{CC}}^{(1)}$ NORMAL mode current	$I_{\text{LOAD}} > \text{Sleep Current}^{(2)}$		93		$\mu\text{A}$
$I_{\text{SLP}}^{(1)}$ SLEEP mode current	$I_{\text{LOAD}} < \text{Sleep Current}^{(2)}$		21		$\mu\text{A}$
$I_{\text{HIB}}^{(1)}$ HIBERNATE mode current	$I_{\text{LOAD}} < \text{Hibernate Current}^{(2)}$		9		$\mu\text{A}$
$I_{\text{SD}}^{(1)}$ SHUTDOWN mode current	Fuel gauge in host commanded SHUTDOWN mode. (LDO regulator output disabled)		0.6		$\mu\text{A}$

(1) Specified by design. Not production tested.

(2) Wake Comparator Disabled.

## 8.6 Digital Input and Output DC Characteristics

 $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$ , typical values at  $T_A = 30^\circ\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{IH(OD)}}$ Input voltage, high <sup>(2)</sup>	External pullup resistor to $V_{\text{PU}}$	$V_{\text{PU}} \times 0.7$			V
$V_{\text{IH(PP)}}$ Input voltage, high <sup>(3)</sup>		1.4			V
$V_{\text{IL}}$ Input voltage, low <sup>(2) (3)</sup>				0.6	V
$V_{\text{OL}}$ Output voltage, low <sup>(2)</sup>				0.6	V
$I_{\text{OH}}$ Output source current, high <sup>(2)</sup>				0.5	mA
$I_{\text{OL(OD)}}$ Output sink current, low <sup>(2)</sup>				–3	mA
$C_{\text{IN}}^{(1)}$ Input capacitance <sup>(2)(3)</sup>				5	pF
$I_{\text{ikg}}$	Input leakage current (SCL, SDA, BIN)			0.1	$\mu\text{A}$
	Input leakage current (GPOUT)			1	

(1) Specified by design. Not production tested.

(2) Open Drain pins: (SCL, SDA, GPOUT)

(3) Push-Pull pin: (BIN)

## 8.7 LDO Regulator, Wake-up, and Auto-Shutdown DC Characteristics

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ , typical values at  $T_A = 30^{\circ}\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{BAT}}$ BAT pin regulator input		2.45		4.5	V
$V_{\text{DD}}$ Regulator output voltage			1.8		V
$UVLO_{\text{IT+}}$ $V_{\text{BAT}}$ undervoltage lock-out LDO wake-up rising threshold			2		V
$UVLO_{\text{IT-}}$ $V_{\text{BAT}}$ undervoltage lock-out LDO auto-shutdown falling threshold			1.95		V
$V_{\text{WU+}}^{(1)}$ GPOUT (input) LDO Wake-up rising edge threshold <sup>(2)</sup>	LDO Wake-up from SHUTDOWN mode	1.2			V

(1) Specified by design. Not production tested.

(2) If the device is commanded to SHUTDOWN via I<sup>2</sup>C with  $V_{\text{BAT}} > UVLO_{\text{IT+}}$ , a wake-up rising edge trigger is required on GPOUT.

## 8.8 LDO Regulator, Wake-up, and Auto-shutdown AC Characteristics

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ , typical values at  $T_A = 30^{\circ}\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{\text{SHDN}}^{(1)}$ SHUTDOWN entry time	Time delay from SHUTDOWN command to LDO output disable.			250	ms
$t_{\text{SHUP}}^{(1)}$ SHUTDOWN GPOUT low time	Minimum low time of GPOUT (input) in SHUTDOWN before WAKEUP	10			$\mu\text{s}$
$t_{\text{VDD}}^{(1)}$ Initial $V_{\text{DD}}$ output delay			13		ms
$t_{\text{WUVDD}}^{(1)}$ Wake-up $V_{\text{DD}}$ output delay	Time delay from rising edge of GPOUT (input) to nominal $V_{\text{DD}}$ output.		8		ms
$t_{\text{PUCD}}$ Power-up communication delay	Time delay from rising edge of REGIN to the Active state. Includes firmware initialization time.		250		ms

(1) Specified by design. Not production tested.

## 8.9 ADC (Temperature and Cell Measurement) Characteristics

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ; typical values at  $T_A = 30^{\circ}\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{IN(BAT)}}$ BAT pin voltage measurement range	Voltage divider enabled	2.45		4.5	V
$t_{\text{ADC\_CONV}}$ Conversion time			125		ms
Effective resolution			15		bits

(1) Specified by design. Not tested in production.

## 8.10 Integrating ADC (Coulomb Counter) Characteristics

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ; typical values at  $T_A = 30^{\circ}\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{SR}}$ Input voltage range from BAT to SRX pins			BAT $\pm$ 25		mV
$t_{\text{SR\_CONV}}$ Conversion time	Single conversion		1		s
Effective Resolution	Single conversion		16		bits

(1) Specified by design. Not tested in production.

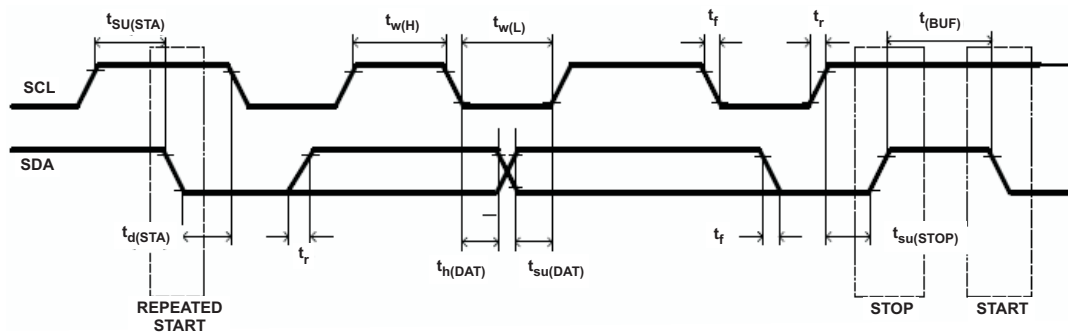
## 8.11 I<sup>2</sup>C-Compatible Interface Communication Timing Characteristics

T<sub>A</sub> = –40°C to 85°C; typical values at T<sub>A</sub> = 30°C and V<sub>REGIN</sub> = 3.6 V (unless otherwise noted)

		MIN	TYP	MAX	UNIT
<b>Standard Mode (100 kHz)</b>					
t <sub>d(STA)</sub>	Start to first falling edge of SCL	4			μs
t <sub>w(L)</sub>	SCL pulse duration (low)	4.7			μs
t <sub>w(H)</sub>	SCL pulse duration (high)	4			μs
t <sub>su(STA)</sub>	Setup for repeated start	4.7			μs
t <sub>su(DAT)</sub>	Data setup time	Host drives SDA	250		ns
t <sub>h(DAT)</sub>	Data hold time	Host drives SDA	0		ns
t <sub>su(STOP)</sub>	Setup time for stop	4			μs
t <sub>(BUF)</sub>	Bus free time between stop and start	Includes Command Waiting Time	66		μs
t <sub>f</sub>	SCL or SDA fall time <sup>(1)</sup>			300	ns
t <sub>r</sub>	SCL or SDA rise time <sup>(1)</sup>			300	ns
f <sub>SCL</sub>	Clock frequency <sup>(2)</sup>			100	kHz
<b>Fast Mode (400 kHz)</b>					
t <sub>d(STA)</sub>	Start to first falling edge of SCL	600			ns
t <sub>w(L)</sub>	SCL pulse duration (low)	1300			ns
t <sub>w(H)</sub>	SCL pulse duration (high)	600			ns
t <sub>su(STA)</sub>	Setup for repeated start	600			ns
t <sub>su(DAT)</sub>	Data setup time	Host drives SDA	100		ns
t <sub>h(DAT)</sub>	Data hold time	Host drives SDA	0		ns
t <sub>su(STOP)</sub>	Setup time for stop	600			ns
t <sub>(BUF)</sub>	Bus free time between stop and start	Includes Command Waiting Time	66		μs
t <sub>f</sub>	SCL or SDA fall time <sup>(1)</sup>			300	ns
t <sub>r</sub>	SCL or SDA rise time <sup>(1)</sup>			300	ns
f <sub>SCL</sub>	Clock frequency <sup>(2)</sup>			400	kHz

(1) Specified by design. Not production tested.

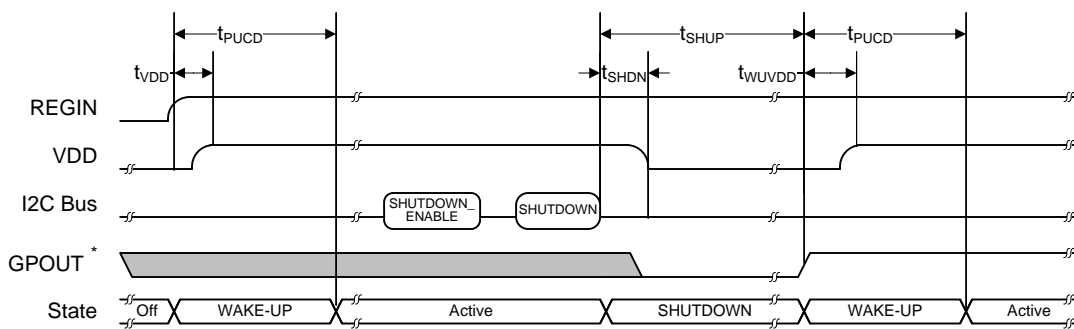
(2) If the clock frequency (f<sub>SCL</sub>) is > 100 kHz, use 1-byte write commands for proper operation. All other transactions types are supported at 400 kHz. (See [I<sup>2</sup>C Interface](#) and [I<sup>2</sup>C Command Waiting Time](#).)



**Figure 1. I<sup>2</sup>C-Compatible Interface Timing Diagrams**



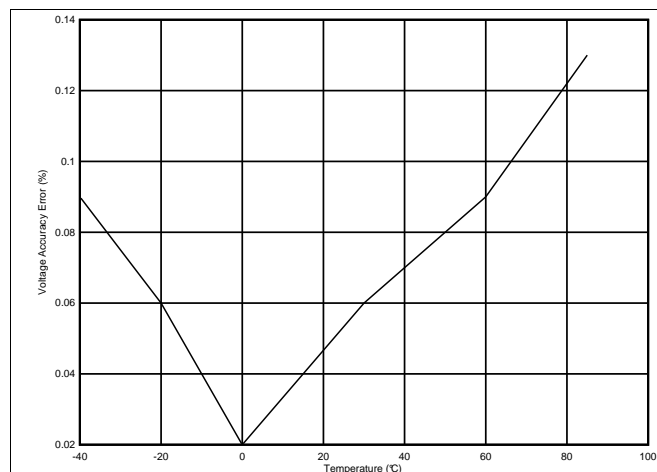
## 8.12 SHUTDOWN and WAKE-UP Timing



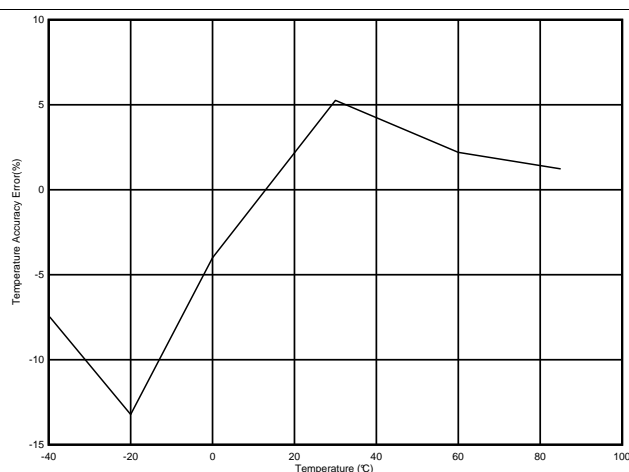
\* GPOUT is configured as an input for wake-up signaling.

**Figure 2. SHUTDOWN and WAKE-UP Timing Diagram**

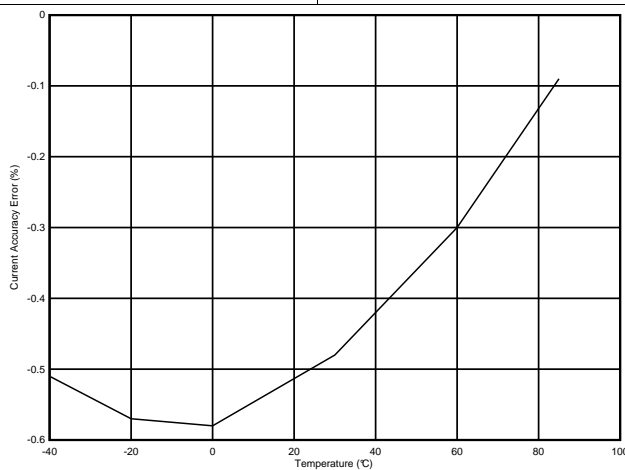
## 8.13 Typical Characteristics



**Figure 3. Voltage Accuracy**



**Figure 4. Temperature Accuracy**



**Figure 5. Current Accuracy**

## 9 Detailed Description

### 9.1 Overview

The fuel gauge accurately predicts the battery capacity and other operational characteristics of a single Li-based rechargeable cell. It can be interrogated by a system processor to provide cell information, such as state-of-charge (SoC).

#### NOTE

The following formatting conventions are used in this document:

**Commands:** *italics* with parentheses() and no breaking spaces, for example, *Control()*.

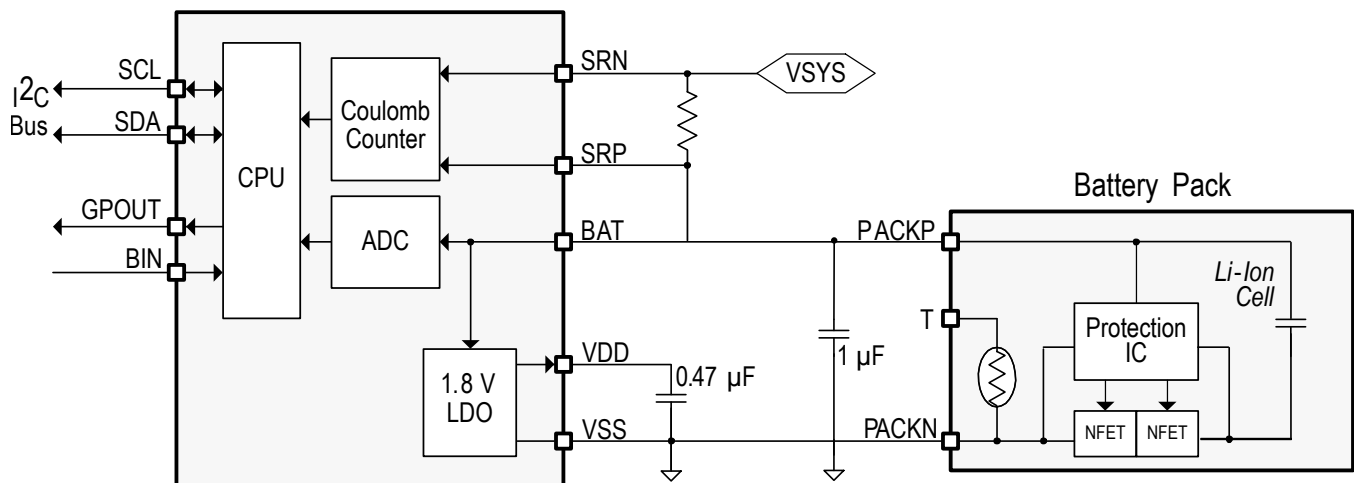
**Data Flash:** *italics*, **bold**, and breaking spaces, for example, ***Design Capacity***.

**Register bits and flags:** *italics* with brackets [ ], for example, *[TDA]*

**Data flash bits:** *italics*, **bold**, and brackets [ ], for example, ***[LED1]***

**Modes and states:** ALL CAPITALS, for example, UNSEALED mode.

### 9.2 Functional Block Diagram



### 9.3 Feature Description

Information is accessed through a series of commands, called *Standard Commands*. Further capabilities are provided by the additional *Extended Commands* set. Both sets of commands, indicated by the general format *Command*), are used to read and write information contained within the control and status registers, as well as its data locations. Commands are sent from system to gauge using the I<sup>2</sup>C serial communications engine, and can be executed during application development, system manufacture, or end-equipment operation.

The key to the high-accuracy gas gauging prediction is Texas Instruments proprietary Impedance Track™ algorithm. This algorithm uses cell measurements, characteristics, and properties to create state-of-charge predictions that can achieve high accuracy across a wide variety of operating conditions and over the lifetime of the battery.

The fuel gauge measures the charging and discharging of the battery by monitoring the voltage across a small-value sense resistor. When a cell is attached to the fuel gauge, cell impedance is computed based on cell current, cell open-circuit voltage (OCV), and cell voltage under loading conditions.

The fuel gauge uses an integrated temperature sensor for estimating cell temperature. Alternatively, the host processor can provide temperature data for the fuel gauge.

More details are found in the *bq27441-G1 Technical Reference Manual* (SLUUAC9).

## 9.4 Device Functional Modes

To minimize power consumption, the fuel gauge has several power modes: INITIALIZATION, NORMAL, SLEEP, and HIBERNATE. The fuel gauge passes automatically between these modes, depending upon the occurrence of specific events, though a system processor can initiate some of these modes directly. More details are found in the *bq27441-G1 Technical Reference Manual* ([SLUUAC9](#)).

## 9.5 Programming

### 9.5.1 Standard Data Commands

The fuel gauge uses a series of 2-byte standard commands to enable system reading and writing of battery information. Each standard command has an associated command-code pair, as indicated in [Table 1](#). Because each command consists of two bytes of data, two consecutive I<sup>2</sup>C transmissions must be executed both to initiate the command function, and to read or write the corresponding two bytes of data. Additional details are found in the *bq27441-G1 Technical Reference Manual* ([SLUUAC9](#)).

**Table 1. Standard Commands**

NAME		COMMAND CODE	UNIT	SEALED ACCESS
<i>Control()</i>	CNTL	0x00 and 0x01	NA	RW
<i>Temperature()</i>	TEMP	0x02 and 0x03	0.1°K	RW
<i>Voltage()</i>	VOLT	0x04 and 0x05	mV	R
<i>Flags()</i>	FLAGS	0x06 and 0x07	NA	R
<i>NominalAvailableCapacity()</i>		0x08 and 0x09	mAh	R
<i>FullAvailableCapacity()</i>		0x0A and 0x0B	mAh	R
<i>RemainingCapacity()</i>	RM	0x0C and 0x0D	mAh	R
<i>FullChargeCapacity()</i>	FCC	0x0E and 0x0F	mAh	R
<i>AverageCurrent()</i>		0x10 and 0x11	mA	R
<i>StandbyCurrent()</i>		0x12 and 0x13	mA	R
<i>MaxLoadCurrent()</i>		0x14 and 0x15	mA	R
<i>AveragePower()</i>		0x18 and 0x19	mW	R
<i>StateOfCharge()</i>	SOC	0x1C and 0x1D	%	R
<i>InternalTemperature()</i>		0x1E and 0x1F	0.1°K	R
<i>StateOfHealth()</i>	SOH	0x20 and 0x21	num / %	R
<i>RemainingCapacityUnfiltered()</i>		0x28 and 0x29	mAh	R
<i>RemainingCapacityFiltered()</i>		0x2A and 0x2B	mAh	R
<i>FullChargeCapacityUnfiltered()</i>		0x2C and 0x2D	mAh	R
<i>FullChargeCapacityFiltered()</i>		0x2E and 0x2F	mAh	R
<i>StateOfChargeUnfiltered()</i>		0x30 and 0x31	%	R
<i>TrueRemainingCapacity()</i>		0x6A and 0x6B	mAh	R

### 9.5.2 Control(): 0x00 and 0x01

Issuing a *Control()* command requires a subsequent 2-byte subcommand. These additional bytes specify the particular control function desired. The *Control()* command allows the system to control specific features of the fuel gauge during normal operation and additional features when the device is in different access modes, as described in [Table 2](#). Additional details are found in the *bq27441-G1 Technical Reference Manual (SLUUAC9)*.

**Table 2. Control() Subcommands**

CNTL FUNCTION	CNTL DATA	SEALED ACCESS	DESCRIPTION
CONTROL_STATUS	0x0000	Yes	Reports the status of device.
FW_VERSION	0x0002	Yes	Reports the firmware version of the device.
DM_CODE	0x0004	Yes	Reports the Data Memory Code number stored in NVM.
PREV_MACWRITE	0x0007	Yes	Returns previous MAC command code.
CHEM_ID	0x0008	Yes	Reports the chemical identifier of the battery profile used by the fuel gauge.
BAT_INSERT	0x000C	Yes	Forces the <i>Flags()</i> [BAT_DET] bit set when the <i>OpConfig</i> [BIE] bit is 0.
BAT_REMOVE	0x000D	Yes	Forces the <i>Flags()</i> [BAT_DET] bit clear when the <i>OpConfig</i> [BIE] bit is 0.
SET_HIBERNATE	0x0011	Yes	Forces <i>CONTROL_STATUS</i> [HIBERNATE] to 1.
CLEAR_HIBERNATE	0x0012	Yes	Forces <i>CONTROL_STATUS</i> [HIBERNATE] to 0.
SET_CFGUPDATE	0x0013	No	Force <i>CONTROL_STATUS</i> [CFGUPMODE] to 1 and gauge enters CONFIG UPDATE mode.
SHUTDOWN_ENABLE	0x001B	No	Enables device SHUTDOWN mode.
SHUTDOWN	0x001C	No	Commands the device to enter SHUTDOWN mode.
SEALED	0x0020	No	Places the device in SEALED access mode.
TOGGLE_GPOUT	0x0023	Yes	Commands the device to toggle the GPOUT pin for 1 ms.
RESET	0x0041	No	Performs a full device reset.
SOFT_RESET	0x0042	No	Gauge exits CONFIG UPDATE mode.
EXIT_CFGUPDATE	0x0043	No	Exits CONFIG UPDATE mode without an OCV measurement and without resimulating to update <i>StateOfCharge()</i> .
EXIT_RESIM	0x0044	No	Exits CONFIG UPDATE mode without an OCV measurement and resimulates with updated configuration data to update <i>StateOfCharge()</i> .

### 9.5.3 Extended Data Commands

Extended data commands offer additional functionality beyond the standard set of commands. They are used in the same manner; however, unlike standard commands, extended commands are not limited to 2-byte words. The number of command bytes for a given extended command ranges in size from single to multiple bytes, as specified in [Table 3](#).

**Table 3. Extended Commands**

NAME	COMMAND CODE	UNIT	SEALED ACCESS <sup>(1) (2)</sup>	UNSEALED ACCESS <sup>(1) (2)</sup>
<i>OpConfig()</i>	0x3A and 0x3B	NA	R	R
<i>DesignCapacity()</i>	0x3C and 0x3D	mAh	R	R
<i>DataClass()</i> <sup>(2)</sup>	0x3E	NA	NA	RW
<i>DataBlock()</i> <sup>(2)</sup>	0x3F	NA	RW	RW
<i>BlockData()</i>	0x40 through 0x5F	NA	R	RW
<i>BlockDataCheckSum()</i>	0x60	NA	RW	RW
<i>BlockDataControl()</i>	0x61	NA	NA	RW
Reserved	0x62 through 0x7F	NA	R	R

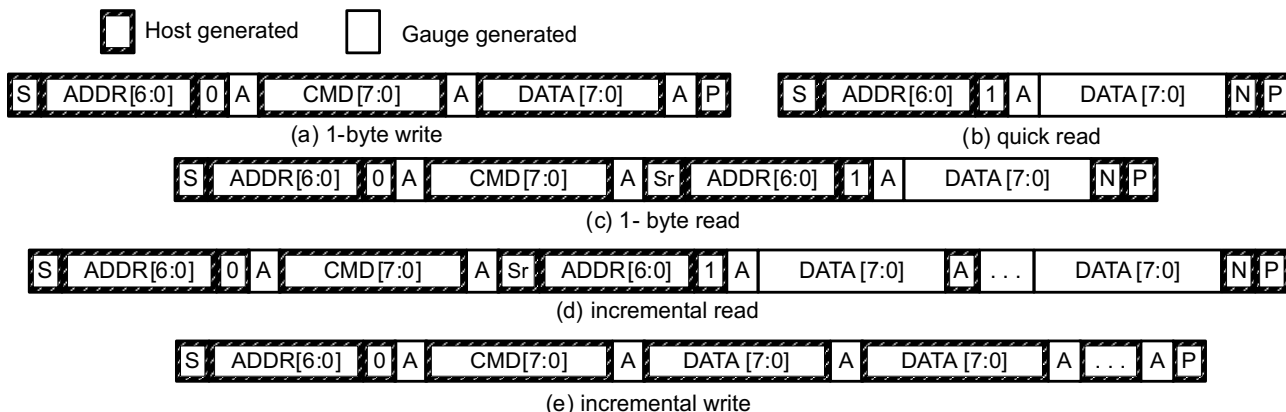
(1) SEALED and UNSEALED states are entered via commands to *Control()* 0x00 and 0x01.

(2) In SEALED mode, data cannot be accessed through commands 0x3E and 0x3F.

## 9.5.4 Communications

### 9.5.4.1 I<sup>2</sup>C Interface

The fuel gauge supports the standard I<sup>2</sup>C read, incremental read, quick read, one-byte write, and incremental write functions. The 7-bit device address (ADDR) is the most significant 7 bits of the hex address and is fixed as 1010101. The first 8 bits of the I<sup>2</sup>C protocol are, therefore, 0xAA or 0xAB for write or read, respectively.

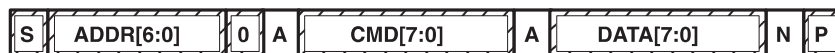


(S = Start, Sr = Repeated Start, A = Acknowledge, N = No Acknowledge, and P = Stop).

The quick read returns data at the address indicated by the address pointer. The address pointer, a register internal to the I<sup>2</sup>C communication engine, increments whenever data is acknowledged by the fuel gauge or the I<sup>2</sup>C master. "Quick writes" function in the same manner and are a convenient means of sending multiple bytes to consecutive command locations (such as two-byte commands that require two bytes of data).

The following command sequences are not supported:

Attempt to write a read-only address (NACK after data sent by master):



Attempt to read an address above 0x6B (NACK command):

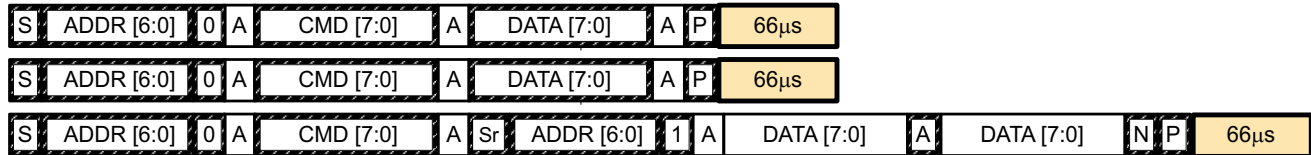


### 9.5.4.2 I<sup>2</sup>C Time Out

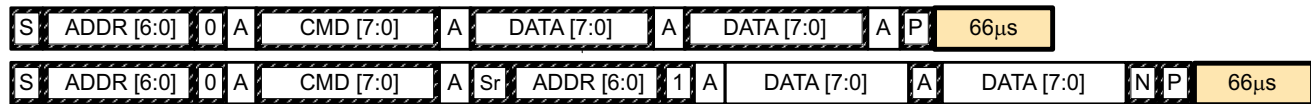
The I<sup>2</sup>C engine releases both SDA and SCL if the I<sup>2</sup>C bus is held low for 2 seconds. If the fuel gauge is holding the lines, releasing them frees them for the master to drive the lines. If an external condition is holding either of the lines low, the I<sup>2</sup>C engine enters the low-power SLEEP mode.

### 9.5.4.3 I<sup>2</sup>C Command Waiting Time

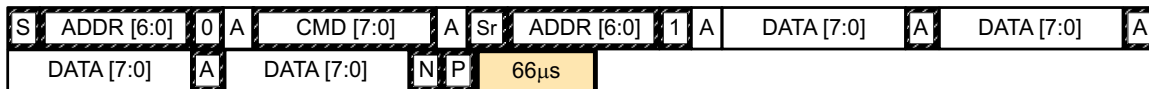
To ensure proper operation at 400 kHz, a  $t_{\text{BUF}} \geq 66 \mu\text{s}$  bus-free waiting time must be inserted between all packets addressed to the fuel gauge. In addition, if the SCL clock frequency ( $f_{\text{SCL}}$ ) is  $> 100 \text{ kHz}$ , use individual 1-byte write commands for proper data flow control. The following diagram shows the standard waiting time required between issuing the control subcommand the reading the status result. For read-write standard command, a minimum of 2 seconds is required to get the result updated. For read-only standard commands, there is no waiting time required, but the host must not issue any standard command more than two times per second. Otherwise, the gauge could result in a reset issue due to the expiration of the watchdog timer.



Waiting time inserted between two 1-byte write packets for a subcommand and reading results  
(required for  $100 \text{ kHz} < f_{\text{SCL}} \leq 400 \text{ kHz}$ )



Waiting time inserted between incremental 2-byte write packet for a subcommand and reading results  
(acceptable for  $f_{\text{SCL}} \leq 100 \text{ kHz}$ )



Waiting time inserted after incremental read

### 9.5.4.4 I<sup>2</sup>C Clock Stretching

A clock stretch can occur during all modes of fuel gauge operation. In SLEEP and HIBERNATE modes, a short  $\leq 100\text{-}\mu\text{s}$  clock stretch occurs on all I<sup>2</sup>C traffic as the device must wake-up to process the packet. In the other modes (INITIALIZATION, NORMAL), a  $\leq 4\text{-ms}$  clock stretching period may occur within packets addressed for the fuel gauge as the I<sup>2</sup>C interface performs normal data flow control.

## 10 Application and Implementation

### NOTE

Information in the following application section is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 10.1 Application Information

The bq27441-G1 fuel gauge is a microcontroller peripheral that provides system-side fuel gauging for single-cell Li-Ion batteries. The device requires minimal configuration and uses One Time Programmable (OTP) Non-Volatile Memory (NVM). Battery fuel gauging with the fuel gauge requires connections only to PACK+ and PACK– for a removable battery pack or embedded battery circuit. To allow for optimal performance in the end application, special considerations must be taken to ensure minimization of measurement error through proper printed circuit board (PCB) board layout. Such requirements are detailed in [Design Requirements](#).

### 10.2 Typical Applications

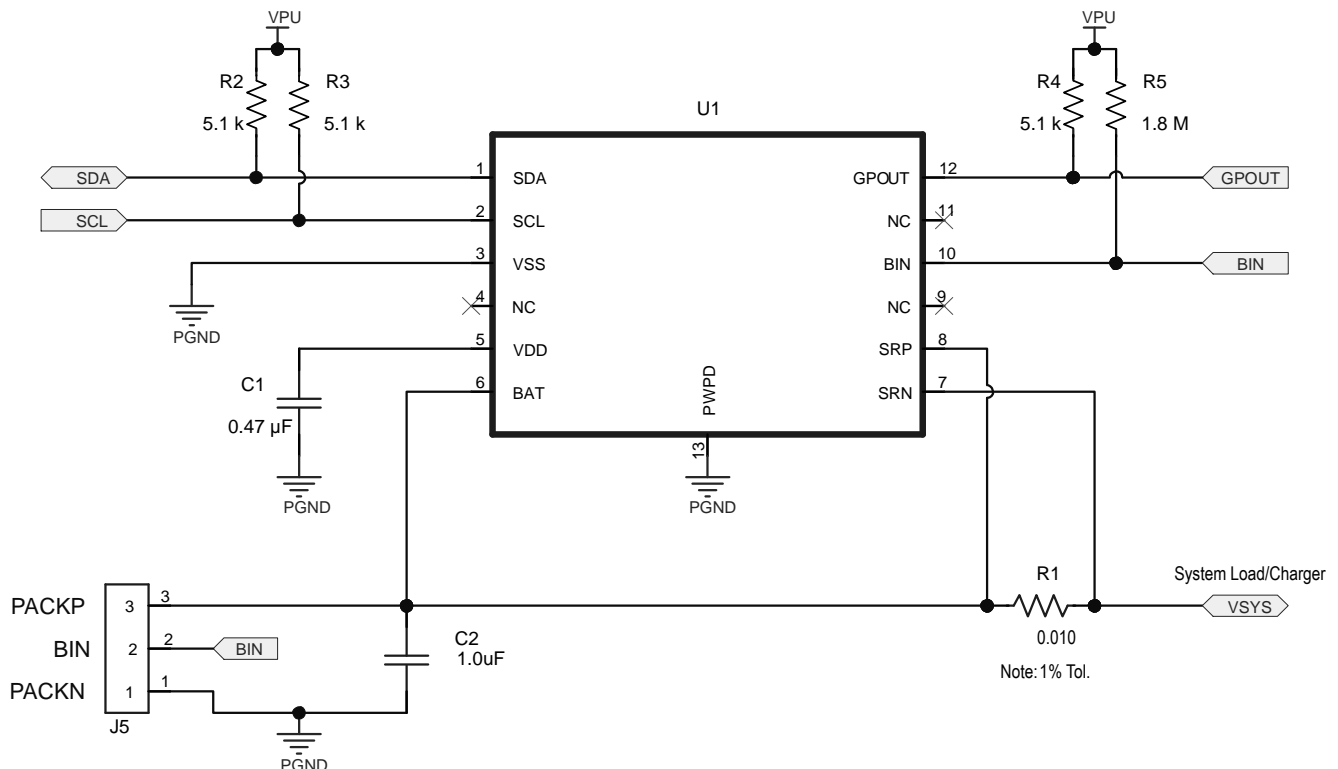


Figure 6. Typical Application

#### 10.2.1 Design Requirements

As shipped from the Texas Instruments factory, many bq27441-G1 parameters in OTP NVM are left in the unprogrammed state (zero) while some parameters directly associated with the CHEMID are preprogrammed. This partially programmed configuration facilitates customization for each end application. Upon device reset, the contents of OTP are copied to associated volatile RAM-based Data Memory blocks. For proper operation, all parameters in RAM-based Data Memory require initialization — either by updating Data Memory parameters in a lab/evaluation situation or by programming the OTP for customer production. Chapter 6 in the *bq27441-G1 Technical Reference Manual* (SLUUAC9) shows the default value and a typically expected value appropriate for most of applications.

## Typical Applications (continued)

### 10.2.2 Detailed Design Procedure

#### 10.2.2.1 BAT Voltage Sense Input

A ceramic capacitor at the input to the BAT pin is used to bypass AC voltage ripple to ground, greatly reducing its influence on battery voltage measurements. It proves most effective in applications with load profiles that exhibit high-frequency current pulses (that is, cell phones) but is recommended for use in all applications to reduce noise on this sensitive high-impedance measurement node.

#### 10.2.2.2 Integrated LDO Capacitor

The fuel gauge has an integrated LDO with an output on the  $V_{DD}$  pin of approximately 1.8 V. A capacitor of value at least 0.47  $\mu$ F should be connected between the  $V_{DD}$  pin and  $V_{SS}$ . The capacitor should be placed close to the gauge IC and have short traces to both the  $V_{DD}$  pin and  $V_{SS}$ .

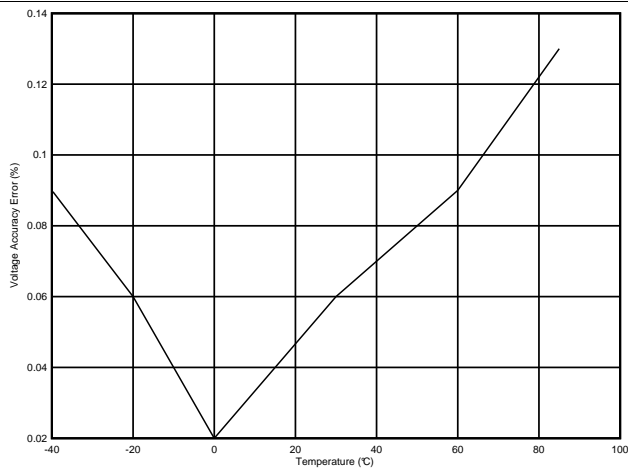
#### 10.2.2.3 Sense Resistor Selection

Any variation encountered in the resistance present between the SRP and SRN pins of the fuel gauge will affect the resulting differential voltage, and derived current, it senses. As such, it is recommended to select a sense resistor with minimal tolerance and temperature coefficient of resistance (TCR) characteristics. The standard recommendation based on best compromise between performance and price is a 1% tolerance, 50 ppm drift sense resistor with a 1-W power rating.

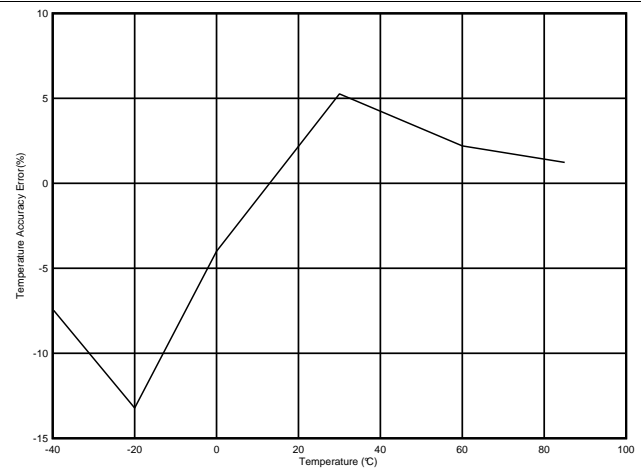


## Typical Applications (continued)

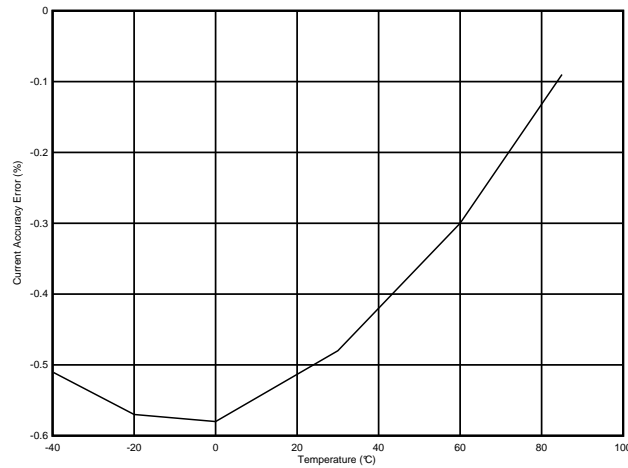
### 10.2.3 Application Curves



**Figure 7. Voltage Accuracy**



**Figure 8. Temperature Accuracy**



**Figure 9. Current Accuracy**

## 11 Power Supply Recommendation

### 11.1 Power Supply Decoupling

The battery connection on the BAT pin is used for two purposes:

- To supply power to the fuel gauge
- To provide an input for voltage measurement of the battery.

A capacitor of value of at least 1  $\mu\text{F}$  should be connected between BAT and  $V_{\text{SS}}$ . The capacitor should be placed close to the gauge IC and have short traces to both the BAT pin and  $V_{\text{SS}}$ .

The fuel gauge has an integrated LDO with an output on the  $V_{\text{DD}}$  pin of approximately 1.8 V. A capacitor of value at least 0.47  $\mu\text{F}$  should be connected between the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ . The capacitor should be placed close to the gauge IC and have short traces to both the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ .

## 12 Layout

### 12.1 Layout Guidelines

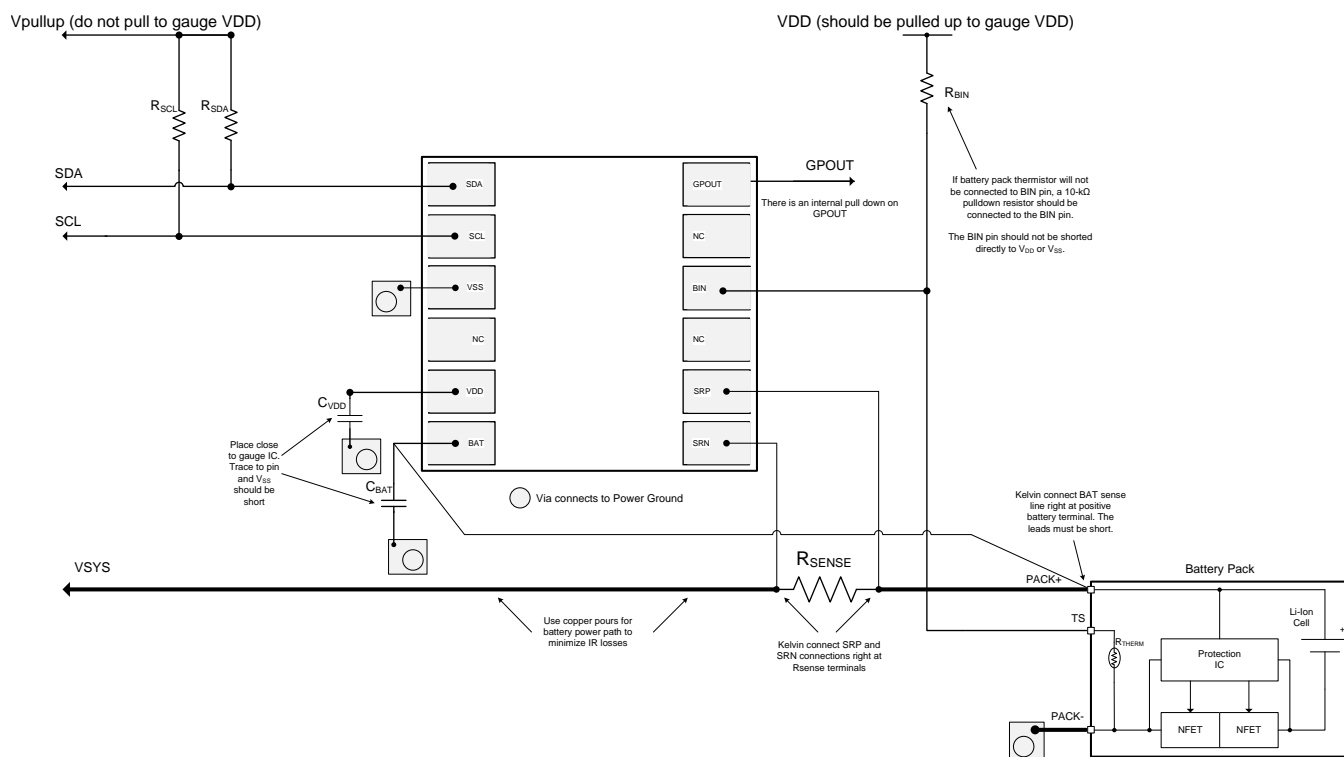
- A capacitor of a value of at least 0.47  $\mu\text{F}$  is connected between the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ . The capacitor should be placed close to the gauge IC and have short traces to both the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ .
- It is required to have a capacitor of at least 1.0  $\mu\text{F}$  connect between the BAT pin and  $V_{\text{SS}}$  if the connection between the battery pack and the gauge BAT pin has the potential to pick up noise. The capacitor should be placed close to the gauge IC and have short traces to both the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ .
- If the external pullup resistors on the SCL and SDA lines will be disconnected from the host during low-power operation, it is recommend to use external 1-M $\Omega$  pulldown resistors to  $V_{\text{SS}}$  to avoid floating inputs to the I<sup>2</sup>C engine.
- The value of the SCL and SDA pullup resistors should take into consideration the pullup voltage and the bus capacitance. Some recommended values, assuming a bus capacitance of 10 pF, can be seen in [Table 4](#).

**Table 4. Recommended Values for SCL and SDA Pullup Resistors**

VPU	1.8 V		3.3 V	
$R_{\text{PU}}$	Range	Typical	Range	Typical
	$400\ \Omega \leq R_{\text{PU}} \leq 37.6\ \text{k}\Omega$	10 k $\Omega$	$900\ \Omega \leq R_{\text{PU}} \leq 29.2\ \text{k}\Omega$	5.1 k $\Omega$

- If the GPOUT pin is not used by the host, the pin should still be pulled up to  $V_{\text{DD}}$  with a 4.7-k $\Omega$  or 10-k $\Omega$  resistor.
- If the battery pack thermistor is not connected to the BIN pin, the BIN pin should be pulled down to  $V_{\text{SS}}$  with a 10-k $\Omega$  resistor.
- The BIN pin should not be shorted directly to  $V_{\text{DD}}$  or  $V_{\text{SS}}$ .
- The actual device ground is pin 3 ( $V_{\text{SS}}$ ).
- The SRP and SRN pins should be Kelvin connected to the  $R_{\text{SENSE}}$  terminals. SRP to the battery pack side of  $R_{\text{SENSE}}$  and SRN to the system side of the  $R_{\text{SENSE}}$ .
- Kelvin connect the BAT pin to the battery PACKP terminal.

## 12.2 Layout Example



**Figure 10. bq27441-G1 Board Layout**

## 13 Device and Documentation Support

### 13.1 Documentation Support

#### 13.1.1 Related Documentation

- *bq27441-G1 Technical Reference Manual* ([SLUUAC9](#))
- *bq27441 EVM: System-Side Impedance Track™ Technology User's Guide* ([SLUUAP4](#))
- *Quickstart Guide for bq27441-G1* ([SLUUAP7](#))
- *Single Cell Gas Gauge Circuit Design* ([SLUA456](#))
- *Key Design Considerations for the bq27500 and bq27501* ([SLUA439](#))
- *Single Cell Impedance Track Printed-Circuit Board Layout Guide* ([SLUA457](#))
- *ESD and RF Mitigation in Handheld Battery Electronics* ([SLUA460](#))

### 13.2 Trademarks

Impedance Track is a trademark of Texas Instruments.  
All other trademarks are the property of their respective owners.

### 13.3 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 13.4 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">BQ27441DRZR-G1A</a>	Active	Production	SON (DRZ)   12	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	BQ27441A
<a href="#">BQ27441DRZR-G1B</a>	Active	Production	SON (DRZ)   12	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	BQ27441B
<a href="#">BQ27441DRZT-G1A</a>	Active	Production	SON (DRZ)   12	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	BQ27441A
<a href="#">BQ27441DRZT-G1B</a>	Active	Production	SON (DRZ)   12	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	BQ27441B

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ27441DRZR-G1A	SON	DRZ	12	3000	330.0	12.4	2.8	4.3	1.2	4.0	12.0	Q2
BQ27441DRZR-G1B	SON	DRZ	12	3000	330.0	12.4	2.8	4.3	1.2	4.0	12.0	Q2
BQ27441DRZT-G1A	SON	DRZ	12	250	180.0	12.4	2.8	4.3	1.2	4.0	12.0	Q2
BQ27441DRZT-G1B	SON	DRZ	12	250	180.0	12.4	2.8	4.3	1.2	4.0	12.0	Q2

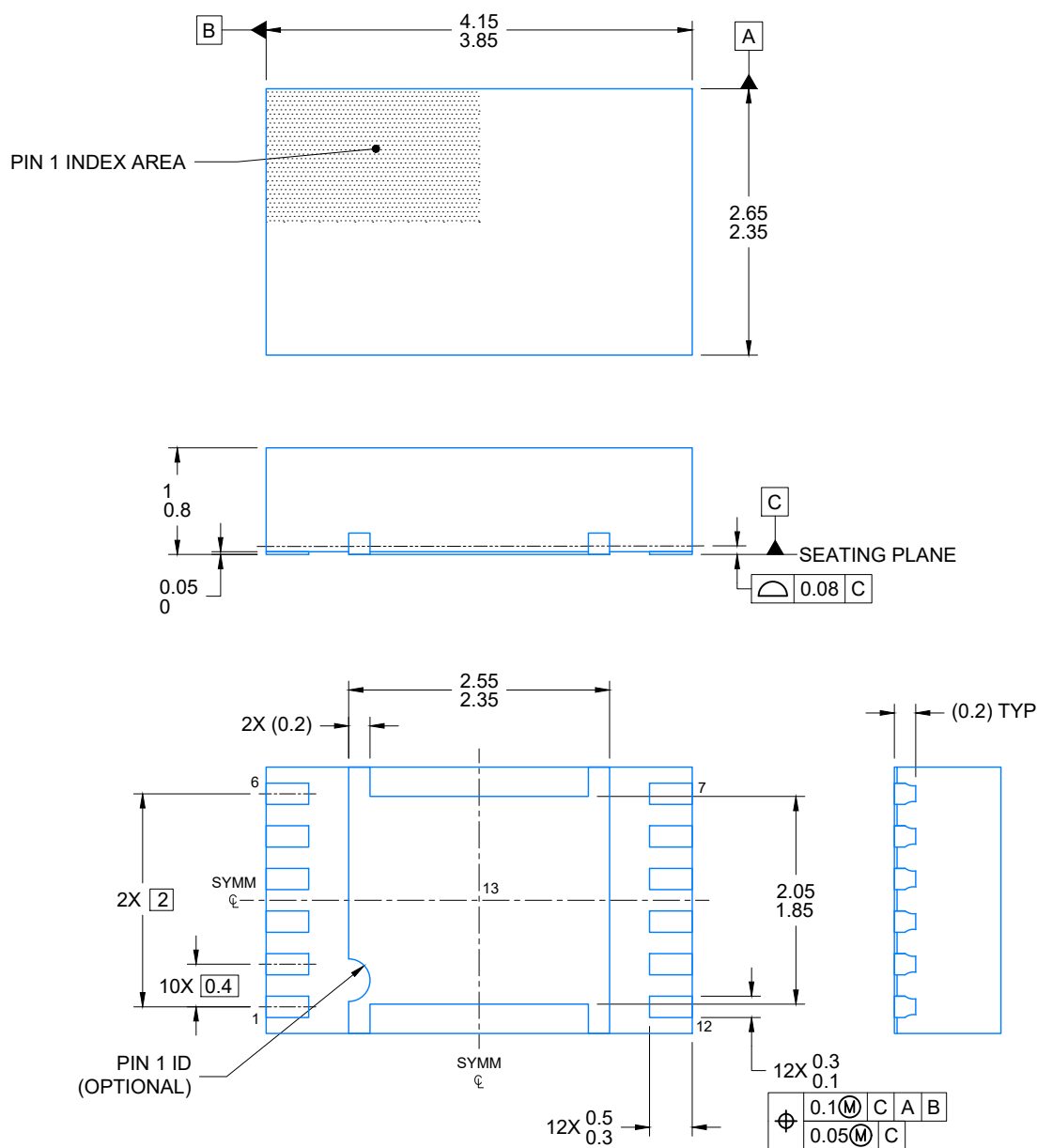
## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ27441DRZR-G1A	SON	DRZ	12	3000	346.0	346.0	33.0
BQ27441DRZR-G1B	SON	DRZ	12	3000	346.0	346.0	33.0
BQ27441DRZT-G1A	SON	DRZ	12	250	210.0	185.0	35.0
BQ27441DRZT-G1B	SON	DRZ	12	250	210.0	185.0	35.0

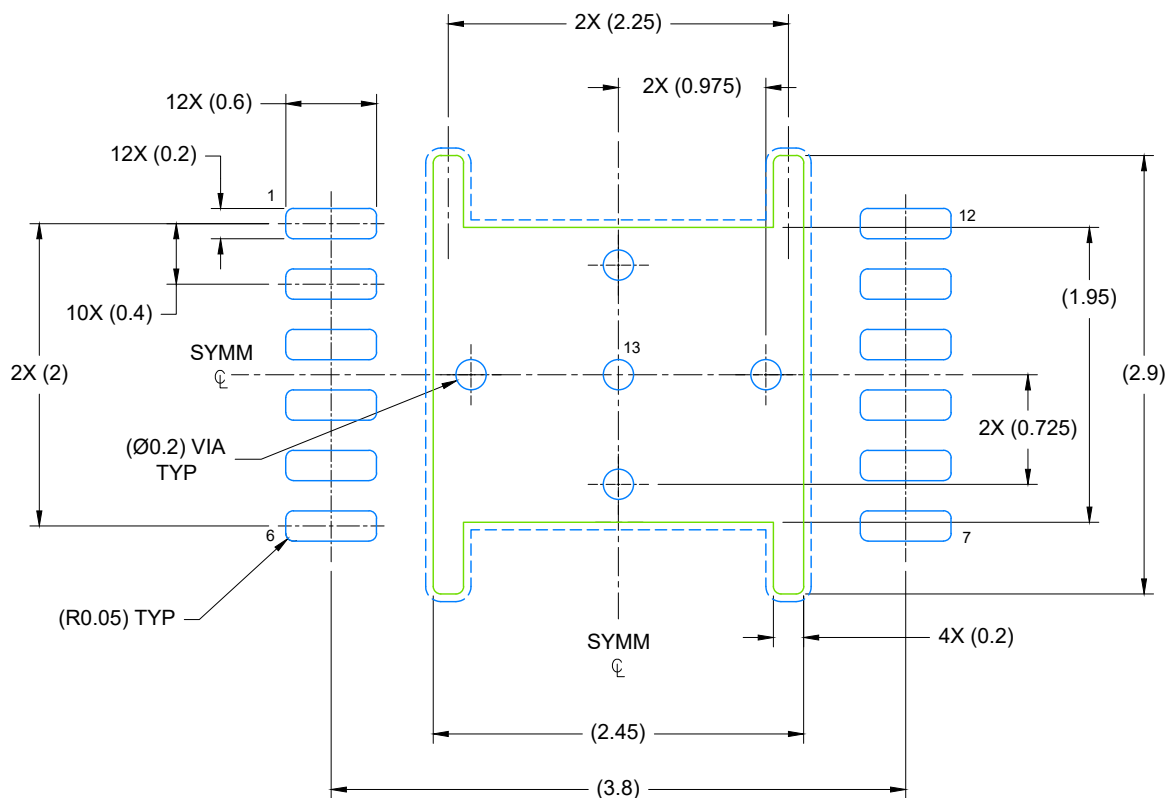




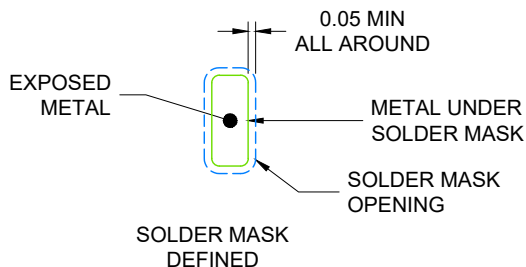
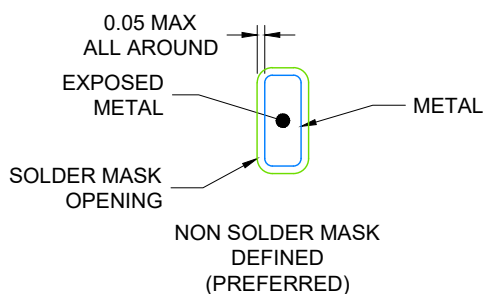
4218895/B 03/2022

## NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE: 20X



SOLDER MASK DETAILS

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NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/sluea271](http://www.ti.com/lit/sluea271)).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

**VSON - 1 mm max height**

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