Kernelized Wasserstein Natural Gradient

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Outline

- General problem and Motivation
- Wasserstein Natural Gradient
- Kernelized Wasserstein Natural Gradient
- Experiments

Given a model ρ_{θ} of the form:

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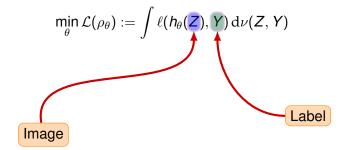
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$$\theta_{t+1} = \theta_t - \gamma \widehat{\nabla \mathcal{L}}(\rho_{\theta_t})$$

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Euclidean gradient

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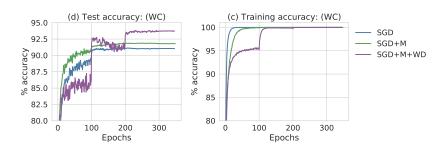
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- Fast training (using autodiff and GPUs)
- Often gives impressive results

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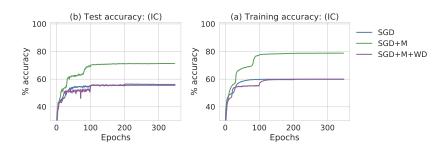


First order methods: Challenges

Large scale models \Rightarrow SGD

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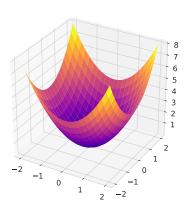
- Sensitive to parametrization
- Can fail miserably when the problem is ill-conditioned

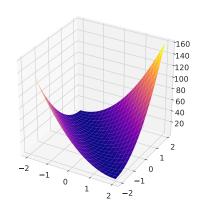


III-conditioned problem

Definition (III-conditioned problem)

A problem $\min_{\theta} \mathcal{L}(\rho_{\theta})$ is ill-conditioned if the hessian $H\mathcal{L}(\rho_{\theta})$ at a local optimum θ^* has a high condition number: $\kappa := \frac{\lambda_{max}}{\lambda_{min}}$





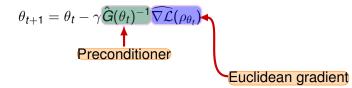
III-conditioned problem \Rightarrow Second order methods!!

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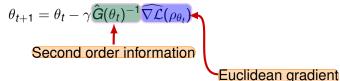
Ill-conditioned problem ⇒ Second order methods!!

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Euclidean gradient

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Second order information

▶ When the density of ρ_{θ} is available ...

Euclidean gradient

Ill-conditioned problem ⇒ Second order methods!!

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Second order information

- When the density of ρ_{θ} is available ...
- Can choose $\hat{G}(\theta_t)$ as an estimator of the fisher information matrix:

$$G_F(\theta_t) = \int \nabla \rho_{\theta_t}(x) \nabla \rho_{\theta_t}(x)^{\top} \rho_{\theta}(x) dx$$

 $\nabla^F \mathcal{L}(\rho_{\theta}) := G_F(\theta_t)^{-1} \nabla \mathcal{L}(\rho_{\theta_t})$

Euclidean gradient

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▶ $\nabla^F \mathcal{L}(\rho_\theta)$ called the *Fisher Natural gradient*.

Ill-conditioned problem ⇒ Second order methods!!

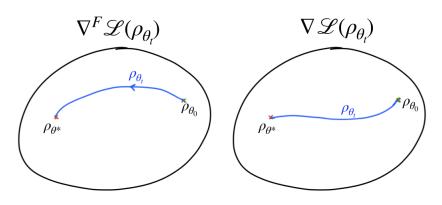
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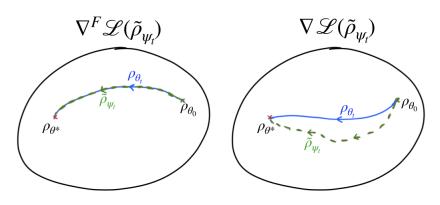
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Euclidean gradient

- ▶ $\nabla^F \mathcal{L}(\rho_\theta)$ called the *Fisher Natural gradient*.
- Robust to parametrization.





Fisher Natural gradient descent: $\theta_{t+1} = \theta_t - \gamma \nabla^F \mathcal{L}(\rho_{\theta_t})$

▶ Have a change of variables $\psi = \Psi(\theta)$ and write $\tilde{\rho}_{\psi} = \rho_{\theta}$.

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- Continuous-time limit of the Fisher natural gradient:

$$\begin{aligned} \dot{\theta}_t &= -\nabla^F \mathcal{L}(\rho_{\theta_t}), \quad \theta_0 \\ \dot{\psi}_t &= -\nabla^F \mathcal{L}(\tilde{\rho}_{\psi_t}), \quad \psi_0 &= \Psi(\theta_0) \end{aligned}$$

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- ▶ Robustness to parametrization $\Rightarrow \psi_t = \Psi(\theta_t)$
- Doesn't hold for the euclidean gradient in general!

Second order methods: Challenges

Fisher Natural gradient descent: $\theta_{t+1} = \theta_t - \gamma \hat{G}_F(\theta_t)^{-1} \widehat{\nabla \mathcal{L}}(\rho_{\theta_t})$

¹[Grosse and Martens, 2016, George et al., 2018]

Second order methods: Challenges

Fisher Natural gradient descent: $\theta_{t+1} = \theta_t - \gamma \hat{G}_F(\theta_t)^{-1} \widehat{\nabla \mathcal{L}}(\rho_{\theta_t})$

- ▶ Computational: Expensive to store and invert $\hat{G}_F(\theta)$ at every iteration .
- ▶ Prior works proposed cheap approximations of $\hat{G}_F(\theta)^{-1}$.
- ▶ Requires to know the density ρ_{θ} .

¹[Grosse and Martens, 2016, George et al., 2018]

Contributions

A second order method based on the Wasserstein natural gradient which is:

- Robust to parametrization
- Doesn't require access to the density of the model
- Trades-off between accuracy and computational cost
- Comes with convergence rates.

General recipe for natural gradients

1. Choose a distance/divergence *d* defined on the model ρ_{θ} :

$$\min_{u} \nabla \mathcal{L}(\rho_{\theta_t})^{\top} u + d(\rho_{\theta_t+u}, \rho_{\theta_t})$$

2. Second order expansion of d at ρ_{θ} :

$$d(
ho_{ heta_t+u},
ho_{ heta_t}) \simeq rac{1}{2} u^{ op} G(heta_t) u$$

3. Solve:

$$\min_{u} \nabla \mathcal{L}(\rho_{\theta_t})^{\top} u + \frac{1}{2} u^{\top} G(\theta_t) u$$

Recipe for Fisher natural gradients

1. Choose the KL as a divergence

$$\min_{u} \nabla \mathcal{L}(\rho_{\theta_t})^{\top} u + \mathit{KL}(\rho_{\theta_t + u} | \rho_{\theta_t})$$

2. Second order expansion of *KL* at ρ_{θ} :

$$\mathit{KL}(
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Wasserstein Natural Gradient: Step 1

1. Choose $d(\rho_{\theta}, \rho_{\theta+u}) = \frac{1}{2}W_2^2(\rho_{\theta}, \rho_{\theta+u})$

$$\min_{u} \nabla \mathcal{L}(\rho_{\theta_t})^{\top} u + \frac{1}{2\lambda} W_2^2(\rho_{\theta_t + u}, \rho_{\theta_t})$$

▶ Well defined even when ρ_{θ} doesn't admit a density

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$$W_2^2(\delta_{\theta_1},\delta_{\theta_2}) = \|\theta_1 - \theta_2\|^2$$

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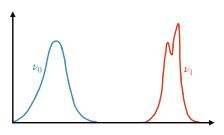
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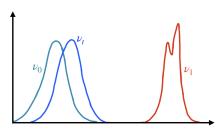
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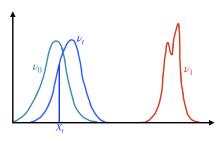
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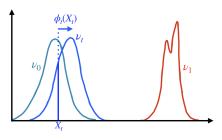
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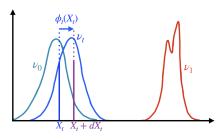
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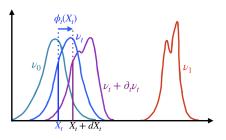
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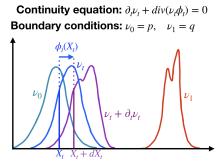
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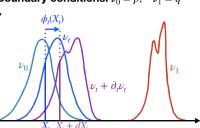
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Continuity equation:
$$\partial_t \nu_t + div(\nu_t \phi_t) = 0$$

Boundary conditions: $\nu_0 = p, \quad \nu_1 = q$



Benamou-Brenier formula²: $W_2^2(p,q) := \inf_{(\nu_t,\phi_t)} \int_0^1 \int \|\phi_t(x)\|^2 d\nu_t(x)$

²[Benamou and Brenier, 2000]

General recipe for natural gradients

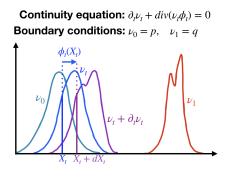
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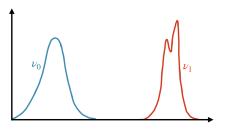
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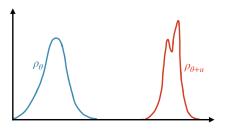
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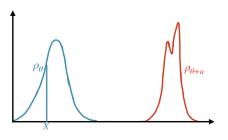
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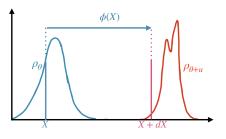
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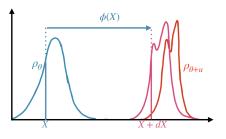


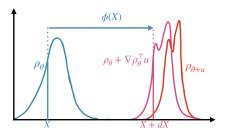




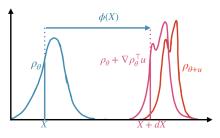




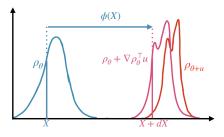




Elliptic equation:
$$\nabla \rho_{\theta}^{\mathsf{T}} u + div(\rho_{\theta} \phi) = 0$$



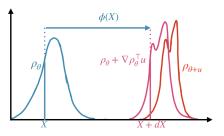
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$$\frac{1}{2}W_2^2(\rho_{\theta},\rho_{\theta+u}) \simeq \inf_{\phi} \int \|\phi(x)\|^2 \,\mathrm{d}\rho_{\theta}(x)$$

2. Taylor expansion of $\frac{1}{2}W_2^2(\rho_\theta, \rho_{\theta+u})$

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$$W_2^2(\rho_\theta, \rho_{\theta+u}) \simeq \int \|\phi(x)\|^2 d\rho_\theta(x)$$

 ϕ constrained to be 'almost' a gradient of a real valued function.

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Implicit model
$$\Rightarrow \mathbb{E}_{\rho_{\theta}}[f(x)] = \int f(h_{\theta}(z)) \, \mathrm{d}\nu(z)$$

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$$\mathbb{E}_{\rho_{\theta+u}}[f(x)] - \mathbb{E}_{\rho_{\theta}}[f(x)] \simeq \int \nabla_{x} f(h_{\theta}(z)) \nabla h_{\theta}(z)^{\top} u \, \mathrm{d}\nu(z)$$

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$$\mathbb{E}_{\rho_{\theta+u}}[f(x)] - \mathbb{E}_{\rho_{\theta}}[f(x)] \simeq \underbrace{\int \nabla_{x} f(h_{\theta}(z)) \nabla h_{\theta}(z)^{\top} u \, d\nu(z)}_{\nabla \rho_{\theta}(f)^{\top} u}$$

$$\frac{1}{2}W_2^2(\rho_\theta,\rho_{\theta+u})\simeq \frac{1}{2}\int \|\phi(x)\|^2 d\rho_\theta(x)$$

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Variational expression for elliptic equations:

$$\begin{split} \nabla \rho_{\theta}^{\top} u + \textit{div}(\rho_{\theta} \phi) &= 0 \\ & \qquad \qquad \qquad \qquad \qquad \qquad \qquad \qquad \\ \phi \in \arg \sup_{f \in C_{c}^{\infty}(\Omega)} \nabla \rho_{\theta}(f)^{\top} u - \frac{1}{2} \mathbb{E}_{\rho_{\theta}}[\|\nabla f(x)\|^{2}] \end{split}$$

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Variational expression for elliptic equations:

General recipe for natural gradients

1. Choose a distance/divergence *d* defined on the model ρ_{θ} :

$$\min_{u} \nabla \mathcal{L}(\rho_{\theta_t})^{\top} u + d(\rho_{\theta_t + u}, \rho_{\theta_t})$$

2. Second order expansion of d at ρ_{θ} :

$$d(
ho_{ heta_t+u},
ho_{ heta_t}) \simeq rac{1}{2} u^{ op} G(heta_t) u$$

$$\min_{u} \nabla \mathcal{L}(\rho_{\theta_t})^{\top} u + \frac{1}{2} u^{\top} G(\theta_t) u$$

$$\min_{u} \nabla \mathcal{L}(\rho_{\theta})^{\top} u + \sup_{f \in C_{c}^{\infty}(\Omega)} \nabla \rho_{\theta}(f)^{\top} u - \frac{1}{2} \mathbb{E}_{\rho_{\theta}}[\|\nabla_{x} f(x)\|^{2}]$$

$$\min_{u} \sup_{f \in C_c^{\infty}(\Omega)} (\nabla \mathcal{L}(\rho_{\theta}) + \nabla \rho_{\theta}(f))^{\top} u - \frac{1}{2} \mathbb{E}_{\rho_{\theta}}[\|\nabla_x f(x)\|^2]$$

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Functional optimization: hard in general

$$\min_{u} \sup_{f \in \mathcal{H}} \mathcal{U}_{\theta}(f)^{\top} u - \frac{1}{2} \mathbb{E}_{\rho_{\theta}}[\|\nabla_{x} f(x)\|^{2}]$$

- Functional optimization: hard in general
- ▶ Replace $C_c^{\infty}(\Omega)$ by a nicer space: an RKHS \mathcal{H}^3 .

$$\min_{u} \sup_{f \in \mathcal{H}} \ \mathcal{U}_{\theta}(f)^{\top} u - \frac{1}{2} \mathbb{E}_{\rho_{\theta}}[\|\nabla_{x} f(x)\|^{2}] + \frac{1}{2} (\epsilon \|u\|^{2} - \lambda \|f\|_{\mathcal{H}}^{2})$$

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- Functional optimization: hard in general
- ▶ Replace $C_c^{\infty}(\Omega)$ by an RKHS \mathcal{H} with kernel k^4 .
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- Minimax Theorem⁵ ⇒ Exchange order of min and sup.

⁴[Mroueh et al. 2019]

⁵[Ekeland and Téman, 1999]

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- ▶ Regularization terms ⇒ Ensure strong convexity/concavity
- Minimax Theorem⁵ ⇒ Exchange order of min and sup.
- ► Optimal descent direction *u** given by:

$$u^* = -\frac{1}{\epsilon} \mathcal{U}_{\theta}(f^*)$$
 $f^* = \arg\min_{f \in \mathcal{H}} \mathbb{E}_{\rho_{\theta}}[\|\nabla_x f(x)\|^2] + \frac{1}{\epsilon} \|\mathcal{U}_{\theta}(f)\|^2 + \lambda \|f\|_{\mathcal{H}}^2$

⁴[Mroueh et al., 2019]

⁵[Ekeland and Téman, 1999]

Have some i.i.d. samples $(Z_n)_{1 \le n \le N}$ from ν and $X_n = h_{\theta}(Z_n)$:

$$\begin{split} \hat{u}^* &= -\frac{1}{\epsilon} \widehat{\mathcal{U}}_{\theta}(\hat{f}^*), \\ \hat{f}^* &= \arg\min_{f \in \mathcal{H}} \frac{1}{N} \sum_{n=1}^N \|\nabla_x f(X_n)\|^2 + \frac{1}{\epsilon} \|\widehat{\mathcal{U}}_{\theta}(f)\|^2 + \lambda \|f\|_{\mathcal{H}}^2 \end{split}$$

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▶ Representer theorem \Rightarrow Optimal solution \hat{f}^* of the form:

$$\hat{f}^* = \sum_{n=1}^N \sum_{i=1}^d \beta_{n,i} \partial_i k(X_n,.)$$

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▶ $\beta_{n,i}$ obtained by solving a linear system of size Nd!!

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Nystrom projections ⁶ ⇒ Reduce computational cost:

$$\hat{f}_{M}^{*} = \sum_{m=1}^{M} \alpha_{m} \partial_{i_{m}} k(\widetilde{X}_{m},.)$$

⁶[Rudi et al., 2015, Sutherland et al., 2017]

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Nystrom projections ⁶ ⇒ Reduce computational cost:

$$\hat{f}_M^* = \sum_{m=1}^M \alpha_m \partial_{i_m} k(\widetilde{X}_m,.)$$
M sub-samples from $(X_i)_{1 \leq i \leq N}$

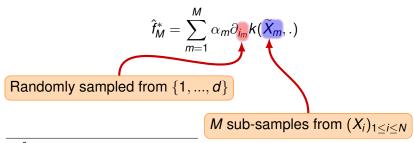
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⁶[Rudi et al., 2015, Sutherland et al., 2017]

$$\widehat{\nabla^{W}\mathcal{L}(\theta)} = \frac{1}{\epsilon} \left(I - T^{\top} (TT^{\top} + \lambda \epsilon K + \epsilon CC^{\top})^{\dagger} T \right) \widehat{\nabla \mathcal{L}(\theta)}$$

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$$C_{m,(n,i)} = \frac{1}{\sqrt{N}} \partial_{i_{m}} \partial_{i_{+}d} k(\widetilde{X}_{m}, X_{n})$$

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$$C_{m,(n,i)} = \frac{1}{\sqrt{N}} \partial_{i_m} \partial_{i_{+d}} k(\widetilde{X}_m, X_n)$$

$$T := \nabla \tau(\theta) \text{ with } \tau(\theta)_m = \frac{1}{N} \sum_{n=1}^{N} \partial_{i_m} k(\widetilde{X}_m, h_{\theta}(Z_n))$$

Theory: Consistency and convergence rates

Theorem

Let δ be such that $0 \le \delta \le 1$. Under smoothness assumptions on the model characterized by some constant $c \ge 0$, for N large enough, $M \sim (dN^{\frac{2+c}{4+c}}\log(N))$, $\lambda \sim N^{\frac{1}{2b+1}}$ and $\epsilon \lesssim N^{-\frac{1}{4+c}}$, it holds with probability at least $1-\delta$ that:

$$\|\widehat{\nabla^W\mathcal{L}(\theta)} - \nabla^W\mathcal{L}(\theta)\|^2 = \mathcal{O}\Big(N^{-\frac{2}{4+c}}\Big).$$

$$\widehat{\nabla^{W}\mathcal{L}(\theta)} = \frac{1}{\epsilon} \left(I - T^{\top} (TT^{\top} + \epsilon CC^{\top})^{\dagger} T \right) \widehat{\nabla \mathcal{L}(\theta)}$$

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$$T_m = \frac{1}{N} \sum_{n=1}^{N} \nabla_{\theta} \partial_{i_m} k(Y_m, h_{\theta}(Z_n))$$

$$\widehat{\nabla^{W}\mathcal{L}(\theta)} = \frac{1}{\epsilon} \left(I - T^{\top} (TT^{\top} + \epsilon CC^{\top})^{\dagger} T \right) \widehat{\nabla \mathcal{L}(\theta)}$$

$$T = CB$$
, $B_n = \nabla_\theta h_\theta(Z_n)$

$$\widehat{\nabla^{W}\mathcal{L}(\theta)} = \frac{1}{\epsilon} \left(I - B^{\top}C^{\top}(CBB^{\top}C^{\top} + \epsilon CC^{\top})^{\dagger}CB \right) \widehat{\nabla \mathcal{L}(\theta)}$$

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Additional structure when $\lambda = 0$:

$$\widehat{\nabla^{W}\mathcal{L}(\theta)} = \frac{1}{\epsilon} \left(I - B^{\top}C^{\top}(CBB^{\top}C^{\top} + \epsilon CC^{\top})^{\dagger}CB \right) \widehat{\nabla \mathcal{L}(\theta)}$$

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'Simplify' C:

$$\widetilde{T} = S^{\dagger}U^{\top}T, \qquad P = S^{\dagger}S$$

where $CC^{\top} = USU^{\top}$

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$$T = CB$$
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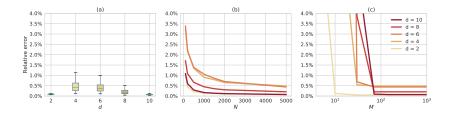
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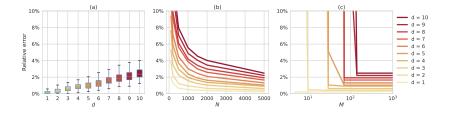
Experimental evaluation: Synthetic models

Hyper-spheres: X = a + rZ, $Z \sim \mathbb{S}_d$



Experimental evaluation: Synthetic models

Gaussians: X = a + rZ, $Z \sim \mathcal{N}(0, I)$

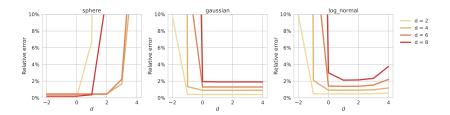


Experimental evaluation: Sensitivity to the choice of the kernel

• Gaussian kernel $k(x, y) = \exp(-\frac{\|x - y\|^2}{\sigma})$

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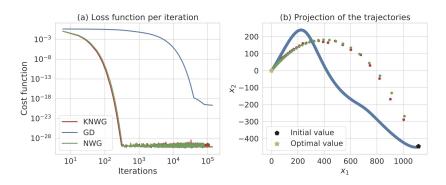


Experimental evaluation: Optimization trajectory

- Gaussian model for ρ_{θ}
- ▶ Loss functional $\mathcal{L}(\rho_{\theta}) = W_2^2(\rho_{\theta}, \rho_{\theta^*})$.

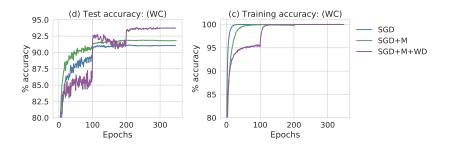
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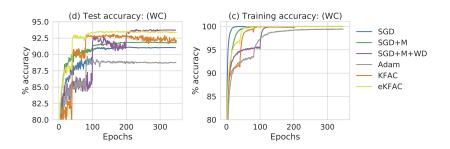


$$\min_{\theta} \mathcal{L}(\rho_{\theta}) := \int \ell(h_{\theta}(Z), Y) \, \mathrm{d}\nu(Z, Y)$$

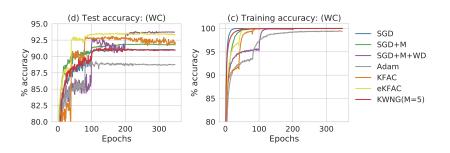
$$\min_{ heta} \mathcal{L}(
ho_{ heta}) := \int \ell(h_{ heta}(Z), Y) \, \mathrm{d}
u(Z, Y)$$



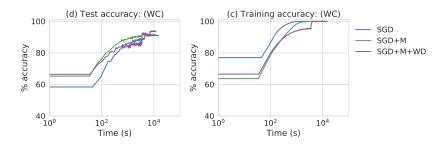
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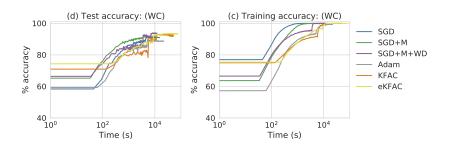
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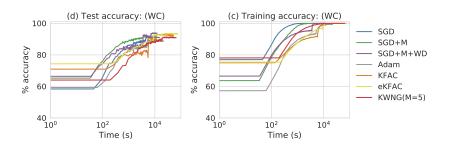
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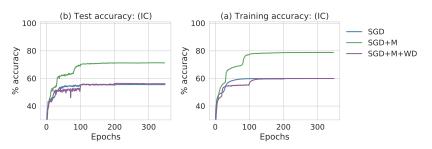


Ill-conditioned problem:

$$\min_{ heta} \mathcal{L}(
ho_{ heta}) := \int \ell(\textit{Uh}_{ heta}(\textit{Z}), \textit{Y}) \, \mathrm{d} \nu(\textit{Z}, \textit{Y})$$

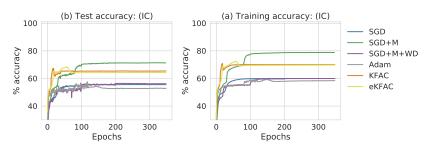
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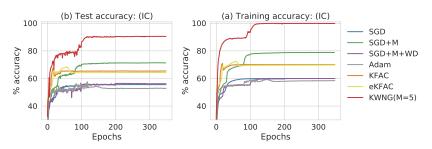
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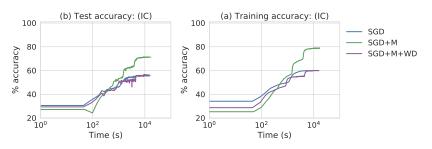
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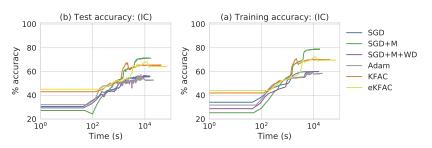
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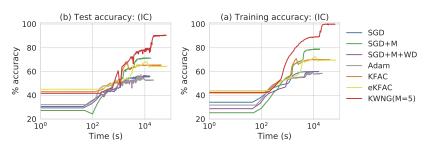
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Conclusion

Summary of contributions

- Proposed to use the Wasserstein natural gradient for ill-conditioned problems
- A new algorithm to estimate the Wasserstein natural gradient
- Convergence rate: trade-off between computational complexity and statistical accuracy

Future work:

- Consistency result for the ridgeless version ⁷
- Potential application in RL (implicit policy for RL⁸)

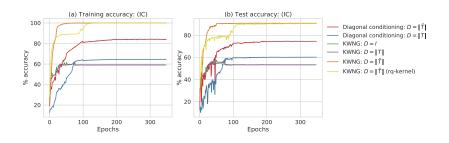
⁷[Liang et al., 2017]

⁸[Tang and Agrawal, 2019]

Thank you!

Ablation study

- ▶ Choice of the damping matrix $D(\theta)$
- Choice of the kernel (gaussian vs rational quadratic)



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