partial: An R Package for Creating Partial Dependence Plots

by Brandon M. Greenwell

Abstract Complex nonparametric models (e.g., neural networks, random forests, and support vector machines) are often used in predictive analytics, especially when dealing with large observational databases that don't adhere to the strict assumptions imposed by traditional statistical techniques (e.g. multiple linear regression). Unfortunately, it can be challenging for the uninitiated to understand the results of such models and explain them to management. Partial dependence plots offer a simple solution. Partial dependence plots are low-dimensional graphical renderings of the prediction function $\widehat{f}(x)$ so that the relationship between the outcome and predictors of interest can be easily understood. These plots are especially useful in explaining the output from complex black box models like support vector machines or neural networks or constructing simpler parsimonious models on newly obtained data.

Introduction

Predictor importance is an important task in any supervised learning problem. However, ranking variables is only part of the story and once a subset of "important" features is identified it is often necessary to assess the relationship between them (or subset thereof) and the response. This can be done in many ways, but in machine learning it is often accomplished by constructing *partial dependence plots* (PDPs); see Friedman (2000) for details. PDPs help visualize the relationship between a subset (typically 1-3) of the predictors and the response while accounting for the average effect of the other independent variables in the model. They are particularly effective with black box models like random forest and support vector machines.

Let $x = \{x_1, x_2, ..., x_n\}$ represent the predictors in a model whose prediction function is $\hat{f}(x)$. If we partition x into an interest set, z_s , and its compliment, $z_c = x \setminus z_s$, then the partial dependence of the response on z_s is defined as

$$\bar{f}_s(z_s) = \frac{1}{n} \sum_{i=1}^n \hat{f}\left(z_s, z_{i,c}\right),\tag{1}$$

where $z_{i,c}$ (i = 1, 2, ..., n) are the values of z_c that occur in the training sample; that is, weaverage out the effects of all the other predictors in the model. Let x_1 be the predictor variable of interest with unique values $\{x_{11}, x_{12}, ..., x_{1k}\}$. The partial dependence of the response on x_1 can be constructed as follows:

- 1. For $i \in \{1, 2, ..., k\}$:
 - (a) Create a copy of the training data and replace the original values of x_1 with the constant x_{1i} .
 - (b) Compute the vector of predicted values from the modified copy of the training data.
 - (c) Compute the average prediction to obtain $\bar{f}_1(x_{1i})$.
- 2. Plot the pairs $[x_{1i}, \bar{f}_1(x_{1i})]$ for i = 1, 2, ..., k.

This can be quite computationally intensive since the algorithm involves k passes over the training records. Fortunately, this can be parallelized quite easily. This algorithm can also be easily extended to larger subsets of 2 or more features as well.

Limited implementations of Friedman's PDPs are available in packages randomForest (Liaw and Wiener, 2002) and gbm, among others; these are limited in the sense that they only apply to the models fit using these packages. For example, the partialPlot function in randomForest only applies to objects of class "randomForest". While the randomForest implementation will only allow for a single predictor, the gbm implementation can deal with any subset of the predictor space; however, these implementations only apply to models fit using the respective package. Partial dependence functions are not restricted to tree-based models; they can be applied to any supervised learning algorithm (e.g., neural networks). However, to our knowledge, there is no general package for constructing PDPs in R (e.g., PDPs for a conditional random forest as implemented by the cforest function in the party and partykit packages; see Torsten Hothorn and Zeileis (2015) and Hothorn and Zeileis (2016), respectively). The partial (Greenwell, 2016) package tries to close this gap by offering a general framework for PDPs that can be applied to several types of fitted models.

The **plotmo** package (Milborrow, 2015) is one alternative to **partial**. According to the author, **plotmo** constructs "a poor man's partial dependence plot." In particular, it plots a model's response when varying one or two predictors while holding the other predictors in the model constant (continuous features are fixed at their median value, while factors are held at their first level). These plots allow for up to two variables at a time and are less accurate than PDPs, but are faster to construct. For additive models (i.e., no interactions), these plots are identical in shape to partial dependence plots.

PDPs can be misleading in the presence of substantial interactions (Goldstein et al., 2015). To overcome this issue Goldstein, Kapelner, Bleich, and Pitkin developed the concept of *individual* conditional expectation (ICE) plots – available in the ICEbox package. ICEbox only allows for one variable at a time (i.e., no multivariate displays), though color can be used effectively to display information about an additional predictor. The ability to construct derivative plots is also available.

Many other techniques exist for visualizing relationships between the predictors and the response based on a fitted model. For example, the car package (Fox and Weisberg, 2011) contains many functions for constructing partial-residual and marginal-model plots. The effects package (Fox, 2003) is also of interest. However, these methods are orientated towards simpler parametric models (e.g., linear and generalized linear models), whereas plotmo, ICEbox, and partial are mainly for nonparametric and black box models (though they can be used for simple parametric models as well).

Constructing PDPs in R

As described in the introduction, the **partial** package is useful for constructing PDPs for many types of fitted models in R. These are especially useful for visualizing the relationships discovered by complex machine learning algorithms such as a random forest. The latest stable release is available from CRAN:

```
install.packages("partial")
```

The development version is located on GitHub: https://github.com/bgreenwell/partial. Bug reports and usggestions are appreciated and should be sumbitted to https://github.com/bgreenwell/partial/issues.

Currently, only two functions are exported by partial:

- partial
- plotPartial

The partial function evaluates the partial dependence (1) from a fitted model over a grid of predictor values. If plot = FALSE (the default), partial returns a data frame with an additional class: "partial". The columns are labeled in the same order as the features supplied to pred. var, and the last column is always labeled y and contains the partial dependence function values $\bar{f}_s(z_s)$. If plot = TRUE, then partial returns a lattice plot (Sarkar, 2008). For more advanced plotting, the plotPartial function will take a "partial" object and display a more customizable lattice plot.

Currently supported models are described in Table 1. While more models will be added, the partial.default method should be able to handle many others not listed in Table 1; for example, neural networks from the nnet package (Venables and Ripley, 2002) or projection pursuit regression (Friedman and Stuetzle, 1981) using the ppr function in the stats package.

For illustration, we will use the (corrected) Boston housing data which are available from the **mlbench** package (Dimitriadou, 2010). These data contain the median value of owner-occupied homes in 506 U.S. census tracts in the Boston area, along with 13 independent variables such as the per capita crime rate by town. We begin by loading the data and omitting unimportant columns.

```
data(BostonHousing2, package = "mlbench") # mlbench must be installed!
boston <- BostonHousing2[, -c(1, 2, 5)]</pre>
```

Next, we fit a random forest to the entire data set with default tuning parameters and 500 trees:

```
library(randomForest)
set.seed(101) # for reproducibility
boston.rf <- randomForest(cmedv ~ ., data = boston, importance = TRUE)
varImpPlot(boston.rf) # variable importance plot</pre>
```

The model fit is reasonable, with an *out-of-bag* (pseudo) \mathbb{R}^2 of 0.89. The variable importance scores are displayed in Figure 1. Both plots indicate that the percentage of lower status of the population (1stat) and the average number of rooms per dwelling (rm) are highly associated with the median value of owner-occupied homes (cmedv). The question then arises, "What is the nature of these associations?" To help answer this, we can look at the partial dependence of cmedv on 1stat and rm, both individually and together.

Type of model	R package	Object class
Decision trees	rpart (Therneau et al., 2015) party partykit	<pre>"rpart" "BinaryTree" "constparty"/"party"</pre>
Bagged decision trees	ipred (Peters and Hothorn, 2015) adabag (Alfaro et al., 2013)	"classbagg", "regbagg" "bagging"
Boosted decision trees	gbm adabag (Alfaro et al., 2013)	"gbm" "boosting"
Random forest Conditional random forest	randomForest party	"randomForest" "RandomForest"
Linear model Generalized linear model Multivariate adaptive re- gression splines (MARS)	partykit stats stats earth (Milborrow, 2016)	<pre>"cforest" "lm" "glm","lm" "earth"</pre>
Support vector machines	e1071 (Meyer et al., 2015) kernlab (Karatzoglou et al., 2004)	"svm" "ksvm"

Table 1: Models specifically supported by the **package**.

boston.rf

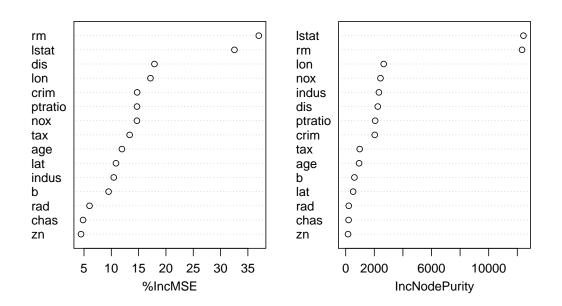


Figure 1: Dotchart of variable importance scores for the Boston housing data based on a random forest with 500 trees.

Single predictor PDPs

As previously mentioned, the randomForest package has its own partialPlot function for visualizing the partial dependence of the response on a single predictor. For example, the following snippet of code plots the partial dependence of cmedv on lstat:

```
partialPlot(boston.rf, pred.data = boston, x.var = "lstat")
```

The same plot can be achieved using the partial function and setting plot = TRUE (see the left side of Figure 2):

```
library(partial)
partial(boston.rf, pred.var = "lstat", plot = TRUE)
```

The only difference is that partial uses the lattice graphics package to produce all of its displays.

For a more customizable plot, call partial with plot = FALSE and use the plotPartial function. **Note:** the *pipe* operator %>% provided by the magrittr package (Bache and Wickham, 2014) is exported for writing more convenient code, as illustrated in snippet of code below which increases the line width, adds a LOESS smoother, and customizes the *y*-axis label.

```
boston.rf %>%
  partial(pred.var = "lstat") %>%
  plotPartial(smooth = TRUE, lwd = 2, ylab = expression(f(lstat)))
```

The result is displayed in the right side of Figure 2 below.

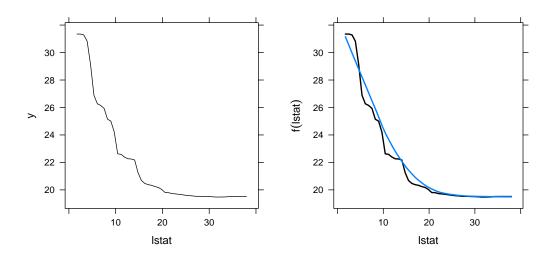


Figure 2: Partial dependence of cmedv on 1stat based on a random forest. *Left*: Default plot. *Right*: Customized plot obtained using the plotPartial function.

Multi-predictor PDPs

The benefit of using partial is threefold: (1) it is a generic function that can be used for various types of model fits (not just random forests), (2) it will allow for any number of predictors to be used, and (3) it can utilize any of the parallel backends supported by the **foreach** package (Analytics and Weston, 2015c); we discuss parallel execution in a later section. For example, the following code chunk uses a multivariate adaptive regression splines (MARS) model (Friedman, 1991) to assess the joint effect of 1stat and rm on cmedv. The results, which make use of various plotPartial options, are displayed in Figure 3.

Note that the default color map for contour plots is the Matplotlib "viridis" color map provided through the viridis package (Garnier, 2016).

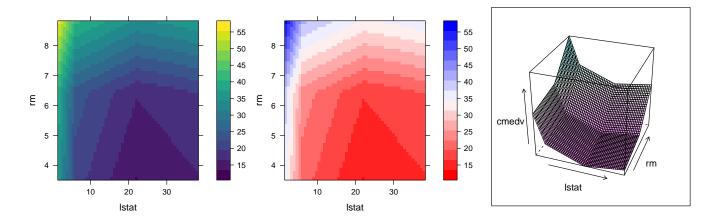


Figure 3: Partial dependence of cmedv on 1stat and rm based on a third degree MARS model. *Left*: Default plot. *Middle*: Using a different color palette. *Right*: Using a 3-D surface.

Avoiding extrapolation

There are a couple ways to mitigate the risk of extrapolation in PDPs: rug displays and convex hulls. Rug displays are one-dimensional plots added to the axes. Both partial and plotPartial have a rug option that, when set to TRUE, will display the deciles of the distribution (as well as the minimum and maximum values) for the predictors on the horizontal and vertical axes. The following snippet of code produces the left display in Figure 4.

In two or more dimensions, plotting the convex hull is more informative; it outlines the region of the predictor space that the model was trained on. When chull = TRUE, the convex hull of the first two dimensions of z_s (i.e., the first two variables supplied to pred.var) is added to the plot; alternatively, you can set chull = TRUE in the call to partial, in which case only the region within the convex hull of the first two variables is plotted. Over interpreting the partial dependence plot outside of this region can be dangerous. The right display in Figure 4 was produced using:

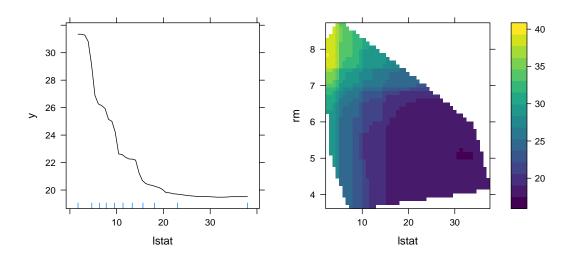


Figure 4: Examples of partial dependence plots with the addition of a rug display (left) and a convex hull (right).

Addressing computational concerns

Constructing PDPs can be quite computationally expensive. Several strategies are available to ease the computational burden for large problems. For example, there is no need to compute partial dependence of median home value using each unique value of rm in the training data (which would require k=446 passes over the data!). We could get very reasonable results using a reduced number of points. Current options are to use a grid of equally spaced values in the range of the variable of interest; the number of points ban be controlled using the grid.resolution. Alternatively, a specific set of values (e.g., quantiles of interest) can be supplied through the pred.grid argument. To illustrate, the following snippet of code computes the partial dependence of median home value on rm using each option; the results are displayed in Figure 5.

```
partial(boston.rf, plot = TRUE)
partial(boston.rf, "rm", grid.resolution = 30, plot = TRUE)
partial(boston.rf, "rm", pred.grid = data.frame(rm = 3:9), plot = TRUE)
```

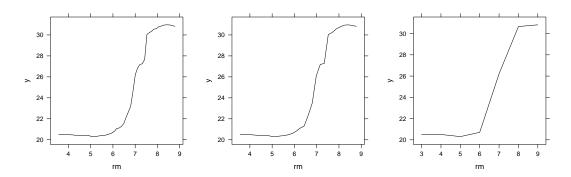


Figure 5: Partial dependence of cmedv on rm. *Left*: Default plot. *Middle*: Using a reduced grid size. *Right*: Using a user-specified grid.

The partial function relies on the plyr package (Wickham, 2011), rather than for loops. This makes it possible to request progress bars (e.g., .progress = "text") or run partial in parallel. In fact, partial can use any of the parallel backends supported by the foreach package. To use this functionality, we must load and register a supported parallel backend [e.g., doMC (Analytics and Weston, 2015a) or doParallel (Analytics and Weston, 2015b)].

To illustrate, we will use the Los Angeles ozone pollution data described in ????. The data are available from http://statweb.stanford.edu/~tibs/ElemStatLearn/datasets/LAozone.data. The following code chunk loads the data into R:

Next, we use MARS to to study the relationship between atmospheric ozone (ozone) concentration and meteorology in the Los Angeles basin in 1976, allowing for up to three-way interactions.

```
ozone.earth <- earth(ozone ~ ., data = ozone, degree = 3)
summary(ozone.earth)</pre>
```

A single three-way interaction term between wind, temp, and dpg was selected by the MARS algorithm. To understand this interaction, we can use partial. However, since the partial dependece between three continuous variables can be computationally expensive, we will run partial in parallel.

Setting up a parallel backend is rather straightforward. To illustrate, the following snippet of sets up the partial function to run in parallel on Unix-like systems¹ using the **doParallel** package.

```
library(doParallel) # load parallel backend
registerDoParallel(cores = 4) # use 4 cores
```

Now, to run partial in parallel, all we have to do is invoke the .parallel = TRUE option and the rest is taken care of by the internal call to **plyr** and the parallel backend we loaded. This is illustrated in following snippet of code which obtains the partial dependence of ozone on wind, temp, and dpg in parallel. The result is displayed in Figure 6.

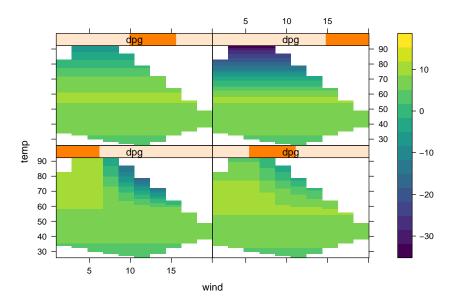


Figure 6: Partial dependence of ozone on wind, temp, and dpg. Since dpg is contiuous, it is first converted to a shingle; in this case, four groups with 10% overlap.

It is important to note that when using more than two variables, plotPartial produces a trellis display. The first two variables given to pred.var are used for the horizontal and vertical axes; additional variables define the panels. If the panel variables are continuous, then shingles² are produced first using the equal count algorithm. Hence, it is probably better to use categorical variables to define the panels in higher dimensional displays when possible, as was done in the previous example.

Classification problems

For classification problems, partial dependence functions are on a scale similar to the logit; see, for example, Hastie et al. (2009, pp. 369–370). Suppose the response is categorical with *K* levels, then for each class we compute

$$f_k(x) = \log[p_k(x)] - \frac{1}{K} \sum_{i=1}^{K} \log[p_k(x)], \quad k = 1, 2, \dots, K,$$
 (2)

where $p_k(x)$ is the predicted probability for the k-th class. Plotting $f_k(x)$ helps us understand how the log-odds for the k-th class depends on different subsets of the predictor variables.

To illustrate, consider Edgar Anderson's iris data from the **datasets** package. The iris data frame contains the sepal length, sepal width, petal length, and petal width (in centimeters) for 50 flowers from each of three species of iris: setosa, versicolor, and virginica. We fit a support vector machine with a radial basis function kernel to the data using the svm function in the **e1071** (the model parameters were determined using 5-fold cross-validation).

The partial function has to be able to extract the predicted probabilities for each class, so it is necessary to set the probability = TRUE option in the call to svm.

Next, we plot the partial dependence of Species on both Petal.Width and Petal.Length for each of the three classes. The result is displayed in Figure 7. Note that we had to supply the original training data to partial through the train option. This is necessary for fitted model objects that don't store a copy of the training data (e.g., model fitting functions that don't rely on a formula method).

¹This example will not run on Windows.

 $^{^2}$ A shingle is a special Trellis data structure that consists of a numeric vector along with intervals that define the "levels" of the shingle. The intervals may be allowed to overlap.

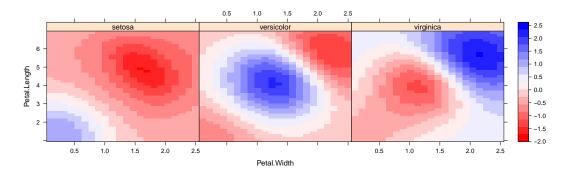


Figure 7: Partial dependence of species on petal width and petal length for the iris data.

Summary

In this paper, we showed how to construct PDPs for various types of black box models in R using the **partial** package. We briefly discussed related approaches in other packages as well. Ways to avoid extrpolation and high excecution times were demonstrated via examples. There is a bright future for **partial** in terms of growth. For example, we would like to include the ability to construct PDPs for various types of survival models (e.g. conditional random forests with censored response).

Acknowledgments

TBD.

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