

## ECE310: Quiz#6 (6pm Section CSS) Fall 2018 Solutions

1. (5 pts) The frequency response of an LTI system is

$$H_d(\omega) = (\omega^2 + 2 \cos(2\omega))e^{j\omega \cos(4\omega)}, \quad \frac{\pi}{8} \leq |\omega| \leq \frac{6\pi}{7}$$

- (a) Is the system real?  
(b) Determine the output  $y[n]$  for input  $x[n] = 1 + \cos(\frac{\pi n}{4}) + \cos(\frac{\pi}{5}) \sin(\frac{9\pi n}{10})$ .

### Solution

(a) Since the support is symmetric, to verify whether or not the system is real, we need to see if  $X_d(\omega) = X_d^*(-\omega)$ . Plug in:

$$\begin{aligned} X_d(\omega) &= (\omega^2 + 2 \cos(2\omega))e^{j\omega \cos(4\omega)} \\ X_d^*(\omega) &= (\omega^2 + 2 \cos(2\omega))e^{-j\omega \cos(4\omega)} \\ X_d^*(-\omega) &= ((-\omega)^2 + 2 \cos(-2\omega))e^{-j(-\omega) \cos(-4\omega)} \\ &= (\omega^2 + 2 \cos(\omega))e^{j\omega \cos(4\omega)} \\ &= X_d(\omega) \end{aligned}$$

using the fact that cosine is an even function. Since  $X_d(\omega) = X_d^*(-\omega)$ , **the system is real**.

(b) Since the system is real, we know that

$$x[n] = \cos(\omega_0 n + \phi) \rightarrow \boxed{H_d(\omega)} \rightarrow y[n] = |H_d(\omega_0)| \cos(\omega_0 n + \phi + \angle H_d(\omega_0))$$

Therefore, we can write the output as

$$y[n] = H_d(0) + \left| H_d\left(\frac{\pi}{4}\right) \right| \cos\left(\frac{\pi n}{4} + \angle H_d\left(\frac{\pi}{4}\right)\right) + \cos\left(\frac{\pi}{5}\right) \left| H_d\left(\frac{9\pi}{10}\right) \right| \sin\left(\frac{9\pi n}{10} + \angle H_d\left(\frac{9\pi}{10}\right)\right)$$

Calculating  $H_d(\omega)$  at the desired values gives

$$\begin{aligned} H_d(0) &= 0 \text{ (outside the bounds)} \\ H_d\left(\frac{\pi}{4}\right) &= \left(\frac{\pi^2}{16} + 2 \cos\left(\frac{\pi}{2}\right)\right) e^{j\frac{\pi}{4} \cos(\pi)} = \frac{\pi^2}{16} e^{-j\frac{\pi}{4}} \\ H_d\left(\frac{9\pi}{10}\right) &= 0 \text{ (outside the bounds)} \end{aligned}$$

Therefore, the output is given as

$$\boxed{y[n] = \frac{\pi^2}{16} \cos\left(\frac{\pi n}{4} - \frac{\pi}{4}\right)}$$

**Grading:**

- 2 points for (a).
- 1 point for application of the eigensequence property.
- 1 point for calculating  $H_d(0)$ ,  $H_d(\frac{\pi}{4})$ , and  $H_d(\frac{9\pi}{10})$ .
- 1 point for the final answer.

2. (5 pts) Consider the discrete-time signal  $x[n] = 2 \tan(\frac{\pi}{5}) \cos(\frac{10\pi n}{13})$ . Find two continuous-time signals  $x_c(t)$  that will produce  $x[n]$  when sampled at a rate of 260 samples per second.

### Solution

Since cosine is a  $2\pi$ -periodic even function, we can write

$$x[n] = 2 \tan\left(\frac{\pi}{5}\right) \cos\left(\left(\frac{10\pi}{13} \pm 2\pi k\right)n\right), \quad k \in \mathbb{Z}$$

Therefore, since  $x[n] = x_c(nT)$ , and using the relationship  $\omega = \Omega T$  with  $T = \frac{1}{260}$  s, we find that

$$x_c(t) = 2 \tan\left(\frac{\pi}{5}\right) \cos((200\pi \pm 520\pi k)t), \quad k \in \mathbb{Z}$$

We get infinitely many possible continuous-time signals, depending on the value of  $k$  chosen. For example, when  $k = 0$ , we get

$$x_c(t) = 2 \tan\left(\frac{\pi}{5}\right) \cos(200\pi t)$$

and when  $k = 1$ , we get

$$x_c(t) = 2 \tan\left(\frac{\pi}{5}\right) \cos(720\pi t)$$

### Grading:

- 3 points for correct reasoning.
- 1 point for each continuous-time signal.