

Midterm Exam

7:00-8:30PM, Monday, October 15, 2018

Name Key

UIN: _____

Section: 10:00 AM 3:00 PM 6:00PM Chicago

Score _____

Problem	Pts.	Score
1	5	
2	5	
3	3	
4	8	
5	6	
6	5	
7	6	
8	5	
9	5	
10	5	
11	5	
12	5	
13	5	
14	3	
15	7	
16	5	
17	5	
18	7	
19	5	
Total		

Please do not turn this page over until told to do so.

You may not use any books, electronic devices, or notes other than **one handwritten** two-sided sheet of 8.5" x 11" paper.

GOOD LUCK!

1. (5 Pts.) The output $y[n]$ and input $x[n]$ of a causal system are related by the equation below. Find the values of the impulse response $h[n]$ for the indicated values of n .

$$y[n] = -y[n-6] + 2x[n] + x[n-5]$$

↓

$$h[n] = -h[n-6] + 2s[n] + s[n-5]$$

n	0	1	5	6	11	12
$h[n]$	2	0	1	-2	-1	2
	+0.5	+0.5	+1	+1	+1	+1

$$h[0] = -h[-6] + 2s[0] + s[-5] = 2$$

$$h[1] = -h[-5] + 2s[1] + s[-4] = 0$$

$$h[5] = -h[-1] + 2s[5] + s[0] = 1$$

$$h[6] = -h[0] + 2s[6] + s[1] = -2$$

$$h[11] = -h[5] + 2s[11] + s[6] = -1$$

$$h[12] = -h[6] + 2s[12] + s[7] = 2$$

2. (5 Pts.) Let $h[n] = (n-1)^2(u[n] - u[n-3])$ for all n . Let $x_1[n] = (-3)^n u[n-1]$. Determine the signal $y[n]$ given by the convolution $y[n] = x_1[n] * h[n]$.

(a) $y[n] = (-3)^n u[n-1] + (-3)^{n-1} u[n-2] + (-3)^{n-2} u[n-3]$

(b) $y[n] = (-3)^{n-1} u[n-1] - (-3)^{n-2} u[n-3]$

$$u[n] - u[n-3]$$

(c) $y[n] = (-3)^n u[n] + (-3)^{n-2} u[n-2]$

$$= s[n] + s[n-1] + s[n-2]$$

(d) $y[n] = (-3)^{n-3}((-3)^3 u[n-1] - 3u[n-3] + 4u[n-4])$

$$(n-1)^2(u[n]-u[n-3])$$

5 (e) $y[n] = (-3)^n u[n-1] + (-3)^{n-2} u[n-3]$

$$= (n-1)^2 s[n] + (n-1)^2 s[n-1] + (n-1)^2 s[n-2]$$

$$= (0-1)^2 s[n] + (1-1)^2 s[n-1] + (2-1)^2 s[n-2]$$

$$= s[n] + s[n-2]$$

So $y[n] = x_1[n] * (s[n] + s[n-2])$

$$= x_1[n] + x_1[n-2]$$

$$= (-3)^n u[n-1] + (-3)^{n-2} u[n-3]$$

3. (3 Pts.) An LTI system has impulse response $h[n] = \cos(\pi\sqrt{n})u[n]$.

Is this system BIBO stable? Yes No +1

Why? The impulse response is not absolutely summable: $\sum_{n=0}^{\infty} |\cos(\pi\sqrt{n})| = \infty$ +2

$\cos(\pi\sqrt{n})$ is always nonzero (since n must be an integer) and oscillates; it never converges to 0

4. (8 Pts.) For each of the systems with input $x[n]$ and output $y[n]$ in the table, indicate with YES or NO whether the properties indicated apply to the system.

	Linear	Time-Invariant	Causal	Stable
$y[n] = 3y[n-1] + x[n+1]$	Yes ^{2/3}	Yes ^{2/3}	No ^{2/3}	No ^{2/3}
$y[n] = x[2] \cos(x[n])$	No ^{2/3}	No ^{2/3}	No ^{2/3}	Yes ^{2/3}
$y[n] = \frac{2}{ n +1} y[n-1] + x[n] + \cos(n+3)$	No ^{2/3}	No ^{2/3}	Yes ^{2/3}	Yes ^{2/3}

5. (6 Pts.) Given the z-transform pair $x[n] \leftrightarrow X(z) = 1/(1 - 0.3z^{-1})^3$ with ROC: $|z| > 0.3$, determine the z-transform with ROC of $y[n] = x[n-2] * (5^n x[n-1])$

$$x[n-2] \leftrightarrow z^{-2} X(z) \quad (+1)$$

$$5^n x[n-1] = 5 \cdot 5^{n-1} x[n-1] \leftrightarrow 5 z^{-1} X(\frac{1}{5} z) \quad (+1)$$

$$\text{So } Y(z) = (z^{-2} X(z))(5 z^{-1} X(\frac{1}{5} z)) = \frac{5 z^{-3}}{(1 - 0.3 z^{-1})^3 (1 - 1.5 z^{-1})^3}, |z| > 1.5 \quad (+2)$$

$$Y(z) = \frac{5 z^{-3}}{(1 - 0.3 z^{-1})^3 (1 - 1.5 z^{-1})^3}$$

$$ROC_Y : |z| > 1.5$$

6. (5 Pts.) The one-sided z-transform of a right-sided sequence $x[n]$ is

$$X(z) = \frac{1}{z^7(z+3)^2}, \quad |z| > 3$$

Find $x[n]$ for all n .

- (a) $n 3^{n-9} u[n]$
 (b) $(n-8) 3^{n-8} u[n-8]$
 5 (c) $(n-8)(-3)^{n-9} u[n-8]$
 (d) $(n-6) 3^{n-6} u[n-6]$
 (e) $(n-6)(-3)^{n-6} u[n-6]$

$$X(z) = \frac{z^{-7}}{(z+3)^2} = -\frac{1}{3} z^{-8} \left(\frac{-3z}{(z+3)^2} \right), |z| > 3$$

$$\begin{aligned} \Rightarrow x[n] &= -\frac{1}{3} (n-8) (-3)^{n-8} u[n-8] \\ &= (n-8)(-3)^{n-9} u[n-8] \end{aligned}$$

7. (6 Pts.) The one-sided z-transform of a right-sided *real-valued* sequence $x[n]$ is

$$\frac{(1-j)}{1 + (1/4 + \sqrt{3}/4j)z^{-1}} + \frac{B}{1 + (1/4 - \sqrt{3}/4j)z^{-1}}, \quad |z| > 1/2$$

(a) Find B.

$$B = 1+j$$

Need conjugate symmetry
since $x(n)$ is real

(b) $x[n]$ has the form $x[n] = a \cos(bn + c)d^n u[n]$. Find the unknown constants.

$$\begin{aligned} X(z) &= \frac{\sqrt{2}e^{-j\pi/4}}{1 + \frac{1}{2}e^{j\pi/3}z^{-1}} + \frac{\sqrt{2}e^{j\pi/4}}{1 + \frac{1}{2}e^{-j\pi/3}z^{-1}}, |z| > 1/2 \rightarrow x(n) = \left(-\frac{1}{2}\right)^n \sqrt{2} e^{-j\pi/4} e^{j\pi/3} u(n) \\ &\quad + \left(-\frac{1}{2}\right)^n \sqrt{2} e^{j\pi/4} e^{-j\pi/3} u(n) \\ &= \sqrt{2} \left(-\frac{1}{2}\right)^n \left(e^{j(\frac{\pi}{3}n - \frac{\pi}{4})} + e^{-j(\frac{\pi}{3}n - \frac{\pi}{4})}\right) u(n) \\ &= 2\sqrt{2} \cos\left(\frac{\pi}{3}n - \frac{\pi}{4}\right) \left(-\frac{1}{2}\right)^n u(n) \end{aligned}$$

$$a = 2\sqrt{2}$$

$$b = \frac{\pi}{3}$$

$$c = -\frac{\pi}{4}$$

$$d = -\frac{1}{2}$$

8. (5 Pts.) Find the partial fraction expansion for $X(z) = \frac{8z^{-1}}{(1-4z^{-1})(0.5+z^{-1})}$.

$$\begin{aligned} X(z) &= \frac{8z^{-1}}{(1-4z^{-1})(0.5+z^{-1})} = \frac{A}{1-4z^{-1}} + \frac{B}{0.5+z^{-1}} \quad (\text{+3}) \quad \text{OR: } X(z) = \frac{8z}{(z-4)(0.5z+1)} \\ A &= \frac{8z^{-1}}{0.5+z^{-1}} \Big|_{z=4} = \frac{8(-4)}{3/4} = \frac{8}{3} \quad (\text{+1}) \quad &= \frac{A}{z-4} + \frac{B}{0.5z+1} \quad (\text{+3}) \\ B &= \frac{8z^{-1}}{1-4z^{-1}} \Big|_{z=2} = \frac{8(-4)}{1-4(-4)} = -4 \quad (\text{+1}) \quad A = \frac{8z}{0.5z+1} \Big|_{z=4} = \frac{32}{3} \quad (\text{+1}) \\ X(z) &= \frac{8}{3} \left(\frac{1}{1-4z^{-1}} \right) - \frac{4}{3} \left(\frac{1}{0.5z+1} \right) \quad B = \frac{8z}{z-4} \Big|_{z=-2} = \frac{8}{3} \quad (\text{+1}) \end{aligned}$$

9. (5 Pts.) An LTI system has the impulse response $h[n] = (j)^n u[n-1]$. Determine a difference equation relating the input $x[n]$ and output $y[n]$ of this system.

$$\begin{aligned} h[n] &= j(j)^{n-1} u[n-1] \rightarrow H(z) = \frac{jz^{-1}}{1-jz^{-1}} = \frac{Y(z)}{X(z)} \quad (\text{+1}) \\ Y(z)(1-jz^{-1}) &= X(z)(jz^{-1}) \quad (\text{+2}) \\ y[n] &= jy[n-1] + jx[n-1] \end{aligned}$$

$$y[n] = jy[n-1] + jx[n-1]$$

10. (5 Pts.) A causal system produces the output $y[n] = \{1, 3, 0, 0, \dots\}_{n=0}^{\infty}$ when excited by the input signal $x[n] = \{1, 1/2, 0, 0, \dots\}_{n=0}^{\infty}$. Determine the impulse response of the system.

(a) $\delta[n] - n(-3)^n u[n]$

$$y[n] = s[n] + 3s[n-1]$$

(b) $(-0.5)^n u[n] + \delta[n]$

$$\hookrightarrow Y(z) = 1 + 3z^{-1}, |z| > 0$$

(c) $(-0.5)^n u[n] + (-3)^n u[n-1]$

$$x[n] = s[n] + \frac{1}{2}s[n-1]$$

(d) $5n(-3)^n u[n-1]$

$$\hookrightarrow X(z) = 1 + \frac{1}{2}z^{-1}, |z| > 0$$

5 (e) $(-0.5)^n u[n] + 3(-0.5)^{n-1} u[n-1]$

$$\hookrightarrow H(z) = \frac{Y(z)}{X(z)} = \frac{1 + 3z^{-1}}{1 + \frac{1}{2}z^{-1}} = \frac{1}{1 + \frac{1}{2}z^{-1}} + \frac{3z^{-1}}{1 + \frac{1}{2}z^{-1}}, |z| > \frac{1}{2}$$

$$\hookrightarrow h[n] = \left(-\frac{1}{2}\right)^n u[n] + 3\left(-\frac{1}{2}\right)^{n-1} u[n-1]$$

11. (5 Pts.) A system with input $x[n]$ and output $s[n]$ is described by the difference equation

$$s[n] = x[n] + cx[n-1].$$

The output $s[n]$ of the first system is the input to another causal system described by the difference equation:

$$y[n] - 2y[n-1] = s[n].$$

Find the value of c that guarantees that $y[n] = x[n]$.

$$s(z) = (1 + cz^{-1})X(z)$$

$$Y(z)(1 - 2z^{-1}) = S(z) = (1 + cz^{-1})X(z)$$

$$\frac{Y(z)}{X(z)} = \frac{1 + cz^{-1}}{1 - 2z^{-1}} = 1 \rightarrow c = -2$$

c = -2

12. (5 Pts.) The input and output of a causal system are related by the equation

$$y[n] + 1.5y[n-1] - y[n-2] = x[n]$$

Is this system BIBO stable? Yes

No +1

Why? The system is causal, and one of the poles of $H(z)$ has magnitude larger than 1, so

the ROC of $H(z)$ does not contain the unit circle. +4

13. (5 Pts.) The causal LTI system with transfer function given below is not BIBO stable. Find a *real valued* bounded input $x[n]$ that produces an unbounded output $y[n]$.

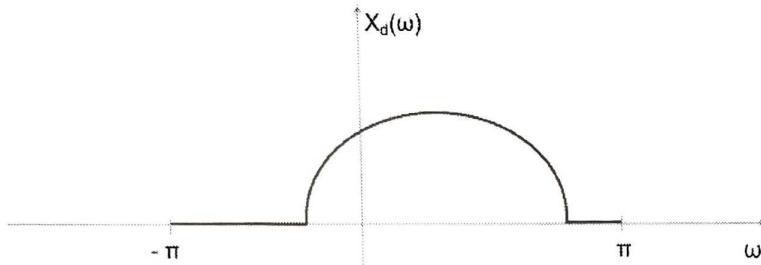
$$H(z) = \frac{1 - 3z^{-3}}{1 - e^{j\pi/3}z^{-1}}$$

- (a) $e^{j\pi n/3}u[n] - e^{-j\pi n/3}u[n]$
 (b) $n \cos(\pi n/3)u[n]$
 5 (c) $\textcircled{e}^{j\pi n/3}u[n] + e^{-j\pi n/3}u[n]$
 (d) $ne^{j\pi n/3}u[n]$
 (e) $\sin(\pi n/6 + \pi/3)$

$H(z)$ has a pole at $e^{j\pi/3}$, so $X(z)$ needs a pole at $e^{j\pi/3}$

- (a) $e^{j\pi n/3}u[n] - e^{-j\pi n/3}u[n] = 2j\sin(\frac{n\pi}{3})u[n]$; not real
 (b) Not bounded
 (c) $e^{j\pi n/3}u[n] + e^{-j\pi n/3}u[n] = 2\cos(\frac{n\pi}{3})u[n]$; this works
 (d) Not bounded
 (e) Wrong pole locations

14. (3 Pts.) Let $x[n]$ have the real-valued DTFT given in the plot below. Is $x[n]$ a real-valued sequence?



Yes

No ①

Why? The magnitude does not exhibit even symmetry ②

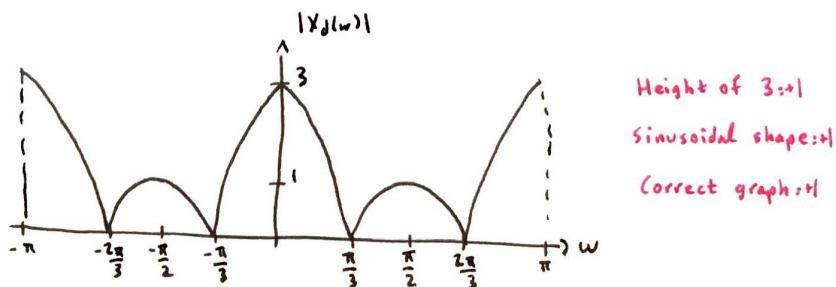
15. (7 Pts.) Let $x[n] = \delta[n] + \delta[n - 2] + \delta[n - 4]$.

- (a) What is the DTFT $X_d(\omega)$ of $x[n]$?

- (a) $X_d(\omega) = 1 + e^{-j2\omega} + e^{j2\omega}$
 (b) $X_d(\omega) = \sin^2(4\omega)$
 4 (c) $\textcircled{X}_d(\omega) = e^{-j2\omega}(1 + 2\cos(2\omega))$
 (d) $X_d(\omega) = \frac{\sin(3\omega)}{\omega}$
 (e) $X_d(\omega) = e^{-j2\omega}\sin(4\omega)$

$$\begin{aligned} X_d(\omega) &= 1 + e^{-j2\omega} + e^{-j4\omega} \\ &= e^{-j2\omega}(e^{j2\omega} + 1 + e^{-j2\omega}) \\ &= e^{-j2\omega}(1 + 2\cos(2\omega)) \end{aligned}$$

- (b) Sketch the magnitude of $X_d(\omega)$, labeling the axes and “important points” on your sketch.



16. (5 Pts.) Determine the signal $x[n]$ whose DTFT is $X_d(\omega) = -1 + 3e^{-j(\omega+\pi/2)} + j \sin(4\omega)$. Note: The arrow indicates $n = 0$.

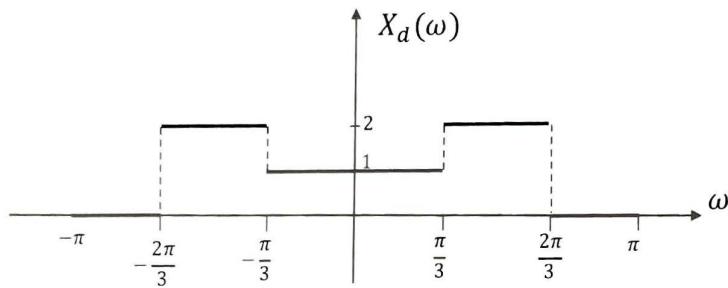
- (a) $x[n] = \{0.5\pi, 0, 0, 0, -1, 3, 0, 0, -0.5\pi\}$
- 5** (b) $x[n] = \{0.5, 0, 0, 0, -1, -3j, 0, 0, -0.5\}$
- (c) $x[n] = \{0.5j, 0, 0, 0, 1, -3j, 0, 0, 0.5j\}$
- (d) $x[n] = \{-2\pi, 0, 0, 0, -1, 3e^{-j\pi/2}, 0, 0, 2\pi\}$
- (e) $x[n] = \{0.5\pi j, 0, 0, 0, -1, 3j, 0, 0, 0.5\pi j\}$

$$X_d(\omega) = -1 + 3e^{-j\frac{\pi}{2}} e^{-j\omega} + j \left(\frac{e^{j4\omega} - e^{-j4\omega}}{2j} \right)$$

$$= -1 - 3j e^{-j\omega} + 0.5 e^{j4\omega} - 0.5 e^{-j4\omega}$$

$$\rightarrow x[n] = \{0.5, 0, 0, 0, -1, \underset{\uparrow}{-3j}, 0, 0, -0.5\}$$

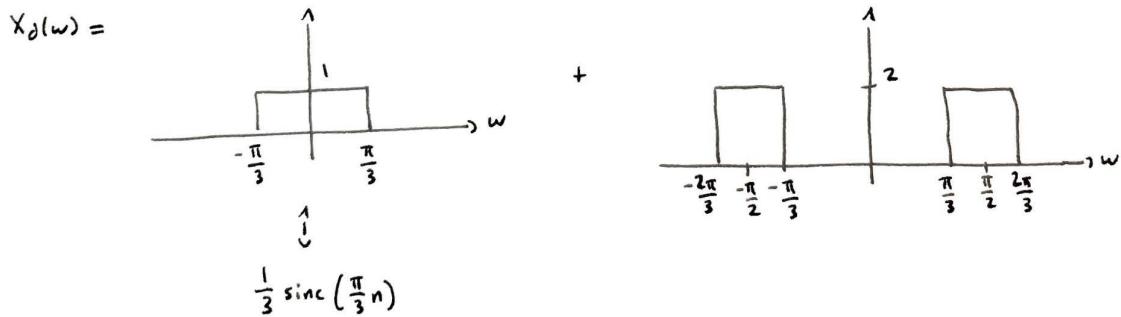
17. (5 Pts.) The DTFT of $x[n]$ is as shown below. Determine $x[n]$.



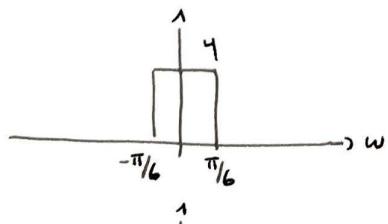
Note: None of the given options were correct due to a typo. So everyone received 5/5, and those closest to the correct solution (i.e., those that chose (b)) received 8/5.

- 5 (a) $x[n] = \text{sinc}(\pi n) \cos(\pi n/2) + \text{sinc}(2\pi n/3)$
- 8 (b) $x[n] = \frac{1}{3} \text{sinc}(\pi n/3) + \frac{2}{3} \text{sinc}(\pi n/6) \cos(\pi n/2)$
- 5 (c) $x[n] = 2\text{sinc}(\pi n/3) + \text{sinc}(2\pi n/3)$
- 5 (d) $x[n] = \frac{1}{3} \text{sinc}(\pi n/3) \cos(\pi n/3) + 3\text{sinc}(2\pi n/3)$
- 5 (e) $x[n] = \frac{1}{3} \text{sinc}(\pi n/3) + \frac{1}{3} \text{sinc}(\pi n/6) \cos(\pi n/5)$

Note: The problem must be attempted to receive the points.



↳ Modulation:



$$\frac{2}{3} \text{sinc} \left(\frac{\pi}{6} n \right)$$

$$* \left(\delta\left(\omega - \frac{\pi}{2}\right) + \delta\left(\omega + \frac{\pi}{2}\right) \right) \frac{1}{2} =$$

$$\downarrow$$

$$\cos\left(\frac{\pi}{2}n\right) \rightarrow x[n] = \frac{1}{3} \text{sinc} \left(\frac{\pi}{3} n \right) + \frac{2}{3} \text{sinc} \left(\frac{\pi}{6} n \right) \cos \left(\frac{\pi}{2} n \right)$$

18. (7 Pts.) Consider the connection of LTI systems given by Fig. ??, where the impulse response of the first system is $h_1[n] = 2\delta[n] - \delta[n-2]$, and the frequency response of the second system for $|\omega| \leq \pi$ is given by

$$H_2(e^{j\omega}) = \begin{cases} 1 & \text{for } |\omega| \leq \frac{3\pi}{4} \\ 0 & \text{for } \frac{3\pi}{4} < |\omega| \leq \pi \end{cases}$$

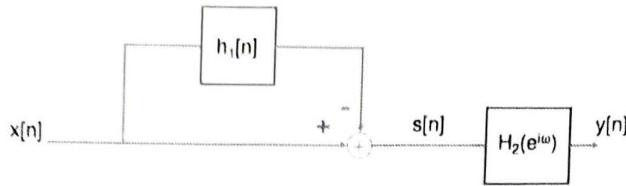


Figure 1: Interconnection of LTI Systems

- (a) Find the impulse response of the interconnected system with input $x[n]$ and output $y[n]$

$$\begin{aligned} x[n] * h_1[n] &= 2x[n] - x[n-2], \text{ so } s[n] = x[n] - (2x[n] - x[n-2]) \\ &= -x[n] + x[n-2] \quad \text{+1} \end{aligned}$$

$$\rightarrow y[n] = x[n] * (-s[n] + s[n-2]) * h_2[n]$$

$$h[n] = -\frac{3}{4} \operatorname{sinc}\left(\frac{3\pi}{4}n\right) + \frac{3}{4} \operatorname{sinc}\left(\frac{3\pi}{4}(n-2)\right)$$

$$\begin{aligned} h[n] &= (-s[n] + s[n-2]) * h_2[n] \\ &= -h_2[n] + h_2[n-2] \quad \text{+1} \\ \rightarrow h_2[n] &= \frac{3}{4} \operatorname{sinc}\left(\frac{3\pi}{4}n\right) \quad \text{+2} \end{aligned}$$

- (b) Find the frequency response of the interconnected system

$$h[n] = -h_2[n] + h_2[n-2]$$

$$H(e^{j\omega}) = -H_2(e^{j\omega}) + e^{-j\omega 2} H_2(e^{j\omega}) = H_2(e^{j\omega})(-1 + e^{-j\omega 2})$$

$$H(e^{j\omega}) = \begin{cases} -1 + e^{-j\omega 2}, & |\omega| \leq \frac{3\pi}{4} \\ 0, & \frac{3\pi}{4} < |\omega| \leq \pi \end{cases} \quad \text{+3}$$

19. (5 Pts.) A causal system is described by the difference equation

$$y[n] + \frac{\sqrt{3}}{3}y[n-1] = x[n].$$

Determine the response of the system to the input $x[n] = 2 \cos(\frac{\pi}{2}n), -\infty < n < \infty$.

$$Y(z)(1 + \frac{\sqrt{3}}{3}z^{-1}) = X(z) \Rightarrow H(z) = \frac{1}{1 + \frac{\sqrt{3}}{3}z^{-1}}, |z| > \frac{\sqrt{3}}{3} \quad \text{+1}$$

$$y[n] = \sqrt{3} \cos\left(\frac{\pi}{2}n + \frac{\pi}{6}\right) \quad \text{+5}$$

$$\rightarrow H(j\omega) = \frac{1}{1 + \frac{\sqrt{3}}{3}e^{-j\omega}}$$

$$\begin{aligned} \hookrightarrow H_d\left(\frac{\pi}{2}\right) &= \frac{1}{1 - j\frac{\sqrt{3}}{3}} \left(\frac{1 + j\frac{\sqrt{3}}{3}}{1 + j\frac{\sqrt{3}}{3}} \right) = \frac{3}{4} + j\frac{\sqrt{3}}{4} = \frac{\sqrt{3}}{2} e^{j\frac{\pi}{6}} \\ &= \frac{1}{\frac{\sqrt{3}}{3}} e^{-j\frac{\pi}{6}} \quad \text{+1} \quad \text{+1} \\ &\quad \text{+3 both} \end{aligned}$$