

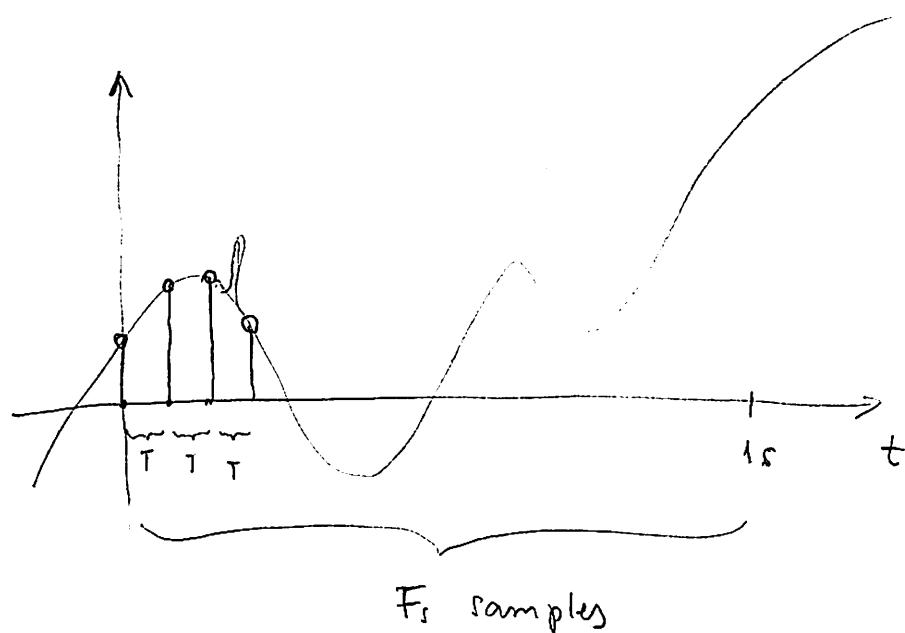
Sampling of continuous-time (CT) signals

CT signal $x_c(t)$
($t \in \mathbb{R}$)

$$x[n] = x_c(nT)$$

sampling period T

discrete-time signal



sampling frequency $F_s = \frac{1}{T}$

(samples/second)

Key question: Are the samples $\{x[0], x[1], x[2], \dots\}$ sufficient to uniquely characterize $x_c(t)$? How large does F_s have to be?

$$\text{Ex: } x_c(t) = \cos \left(2\pi f_0 \cdot \underbrace{t}_{\tau} \right) \xrightarrow{F_s = \frac{1}{\tau}} x[n] = \cos \left(2\pi f_0 \cdot n \tau \right) = \cos \left(2\pi \underbrace{\frac{f_0}{F_s}}_{\omega_0} n \right)$$

Consider another signal :

$$y_c(t) = \cos \left(2\pi (f_0 + kF_s) t \right) \xrightarrow{F_s} y[n] = \cos \left(2\pi (f_0 + kF_s) n \tau \right) = \cos \left(2\pi \frac{f_0}{F_s} n + 2\pi k n \right) = \cos \left(2\pi \frac{f_0}{F_s} n \right) = x[n]$$

signal @ freq. f_0  same discrete-time signal !
 signal @ freq. $f_0 + kF_s$ 

CT: $f_0 + kF_s$ $\xrightarrow{\text{sampled at } F_s}$ DT: $\frac{2\pi f_0}{F_s}$ (angular frequency)

$$-\frac{F_s}{2} \leq \cdot \leq \frac{F_s}{2}$$

(fundamental frequency) frames per second

Ex: Video shot at 30 fps ($F_s = 30 \text{ Hz}$)
of an airplane propeller

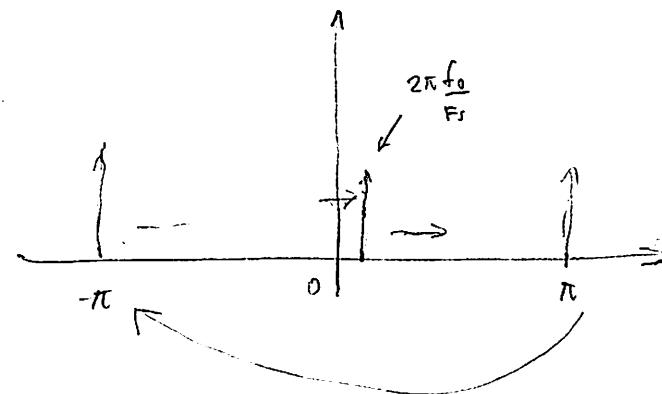
① $f_0 = 3 \text{ Hz}$: Fundamental freq: 3 Hz

② $f_0 = 27 \text{ Hz}$: Fund. freq: -3 Hz

③ $f_0 = 43 \text{ Hz}$: Fund freq: 13 Hz

④ $f_0 = 327 \text{ Hz}$: Fund freq: -3 Hz

propeller rotating
backwards



In frequency domain:

Recall : $x_c(t) = \cos(\omega_0 t)$ $\xleftrightarrow{\text{CTFT}}$ $\pi [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$

$$= \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2}$$

In DT: $x[n] = \cos(\omega_0 n)$

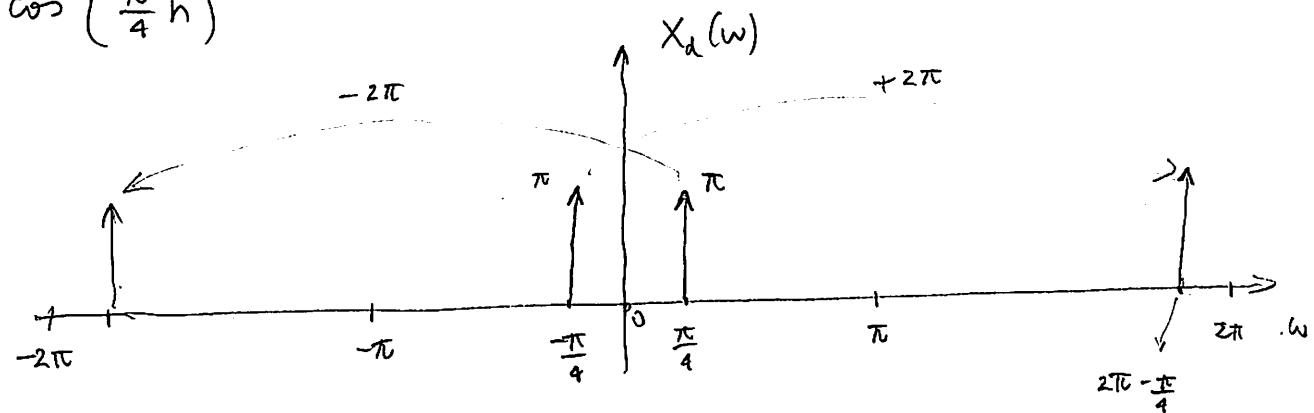
$$= \frac{e^{j\omega_0 n} + e^{-j\omega_0 n}}{2}$$

$\xleftrightarrow{\text{DTFT}}$ $\pi [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$

always
2 π -periodic

repeated at every
interval of length 2 π

Ex: $x[n] = \cos\left(\frac{\pi}{4}n\right)$



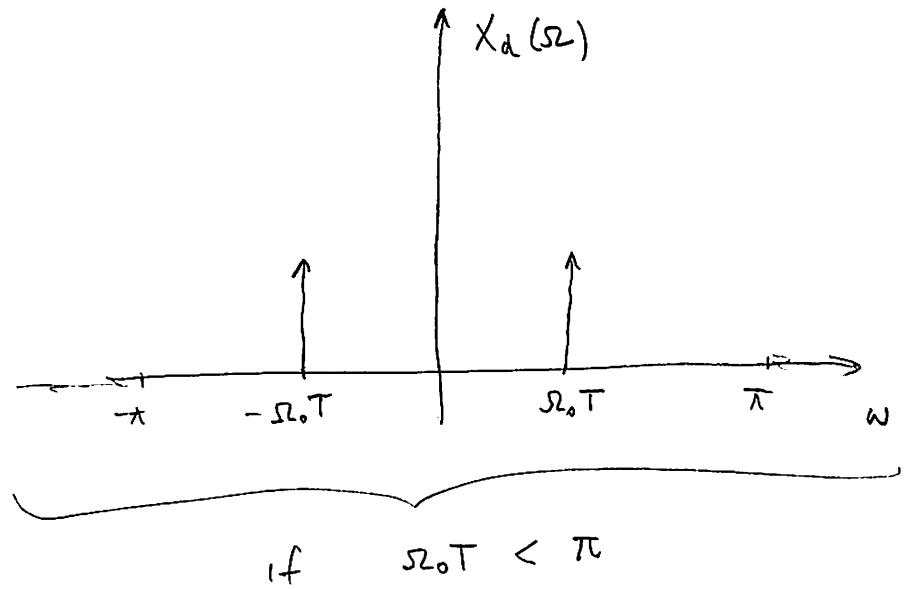
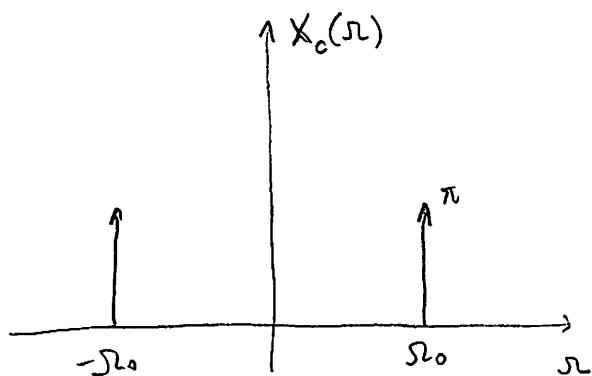
Sampling at $F_s = \frac{1}{T}$

$$x_c(t) = \cos(\Omega_0 t)$$

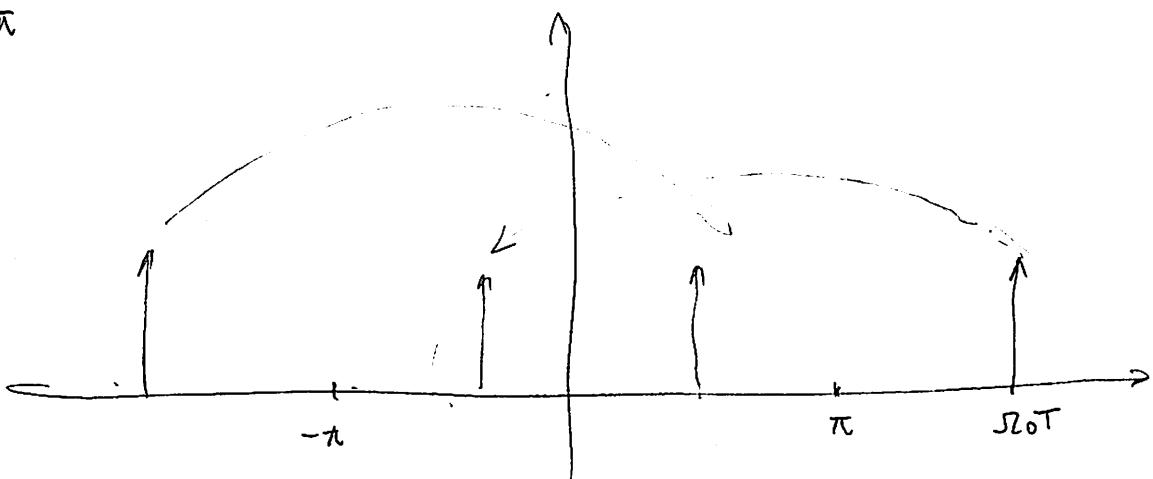
$$\xrightarrow{F_s}$$

$$x[n] = \cos(\Omega_0 nT) = \cos(\overbrace{\Omega_0 T}^{w_0} \cdot n)$$

In freq. domain:



If $\pi < \Omega_0 T < 2\pi$



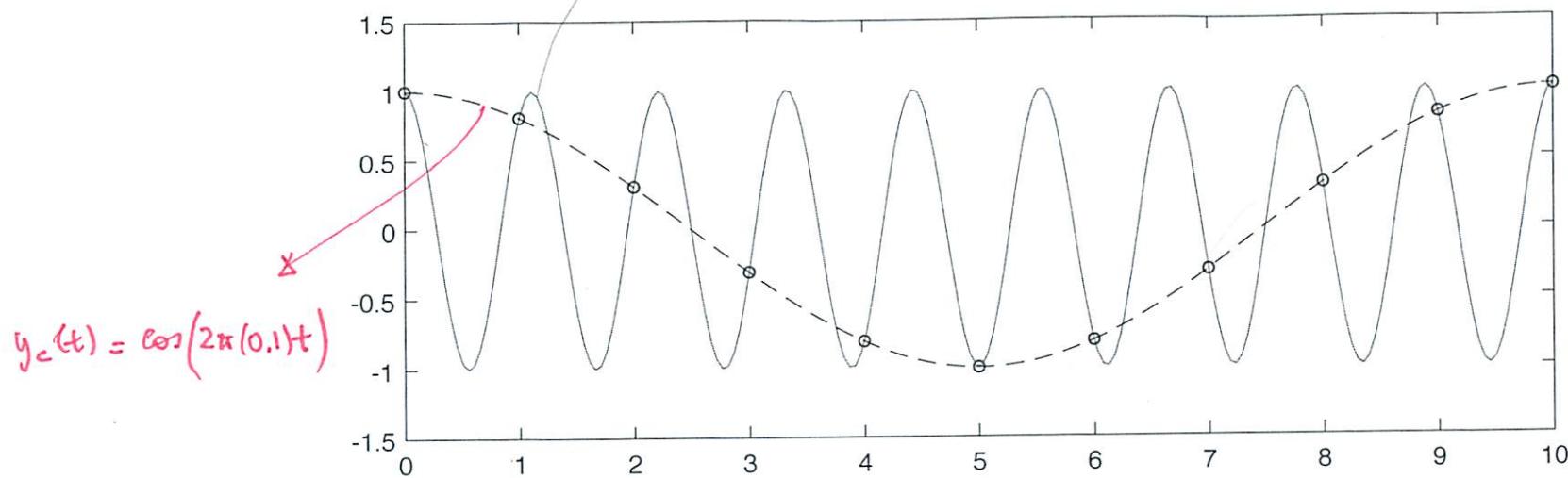
$$f_0 = 0.9$$

$$x_c(t) = \cos(2\pi(0.9)t)$$

$$F_s = 1$$

$$T = 1$$

$$x[n] = \cos(2\pi(0.9)n)$$

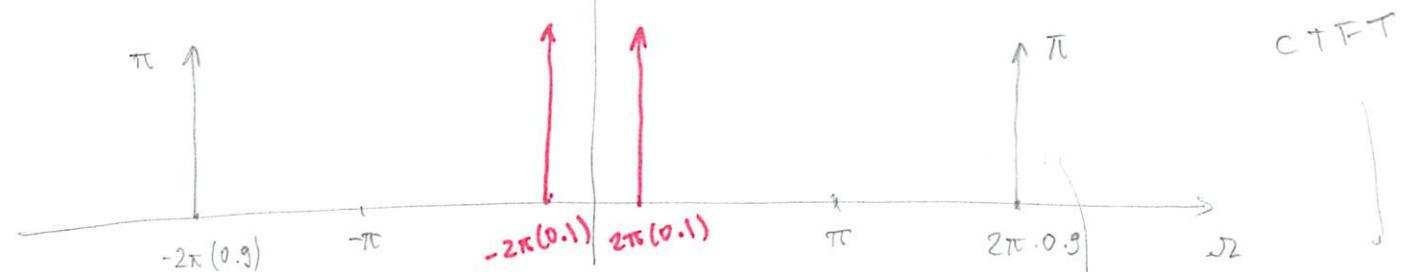


$$y_c(t) = \cos(2\pi(0.1)t)$$

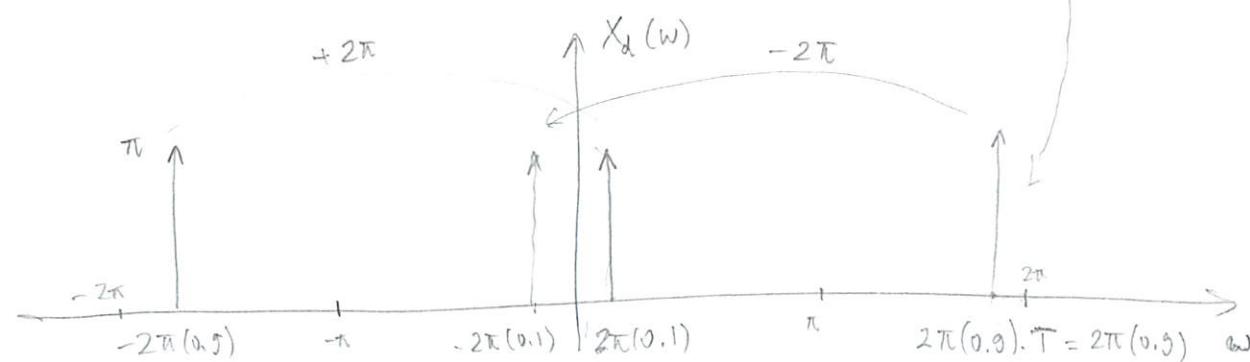


x_c and y_c
have different

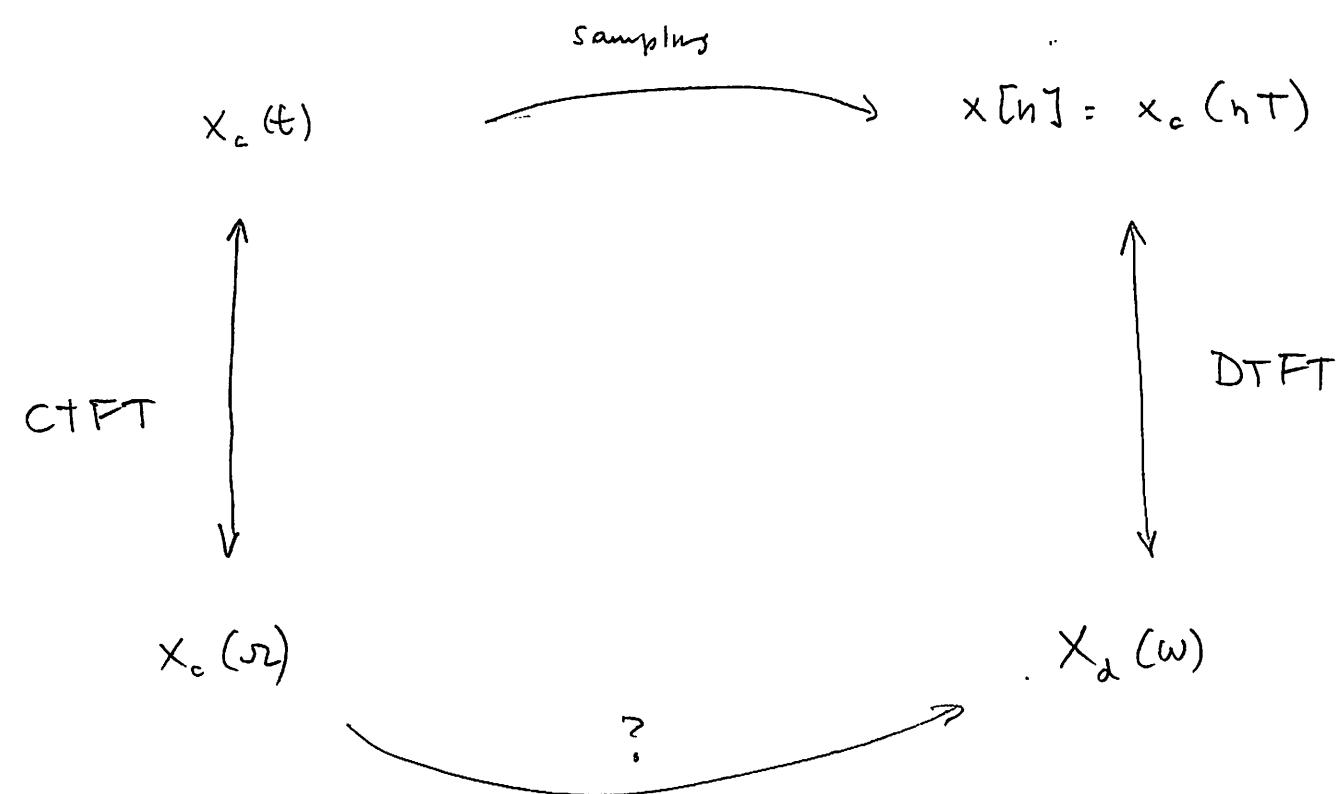
c+FFT



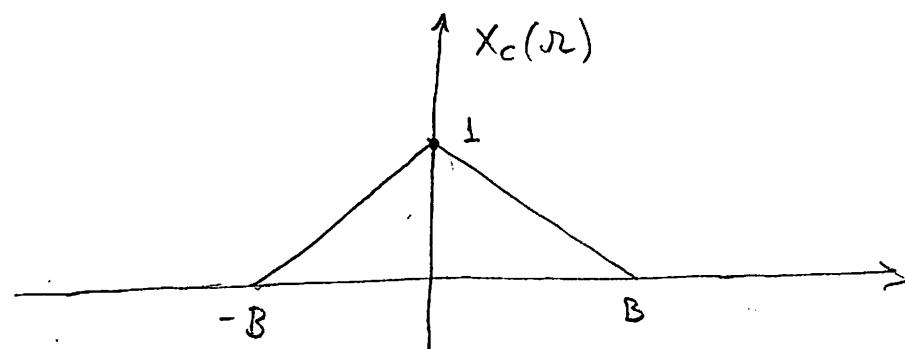
but the
same DTFT



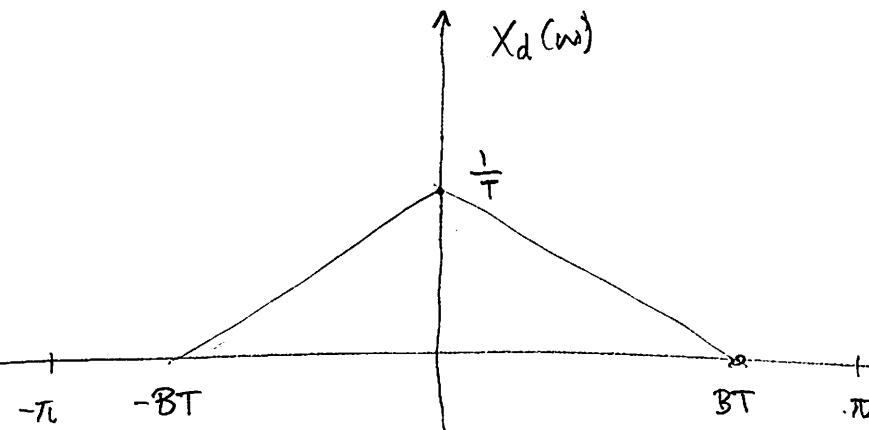
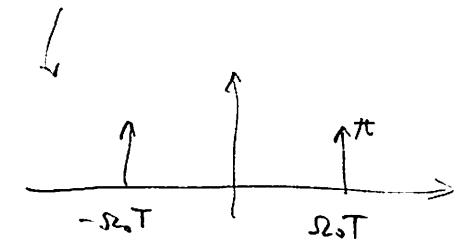
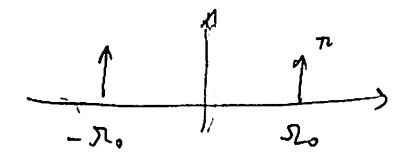
Connecting continuous and discrete



Suppose $X_c(\Omega)$ is given below



For $x(t) = \cos(\Omega_0 t)$



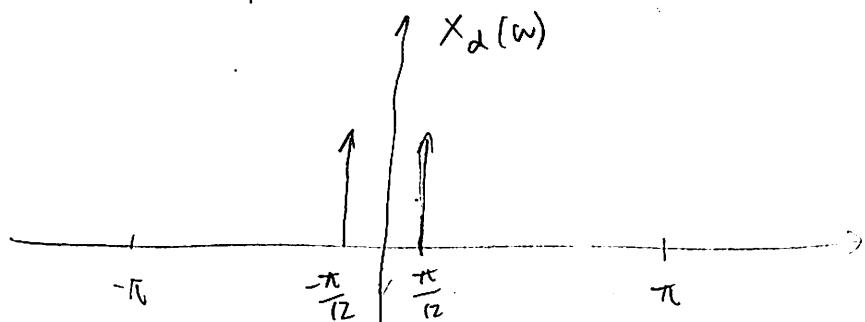
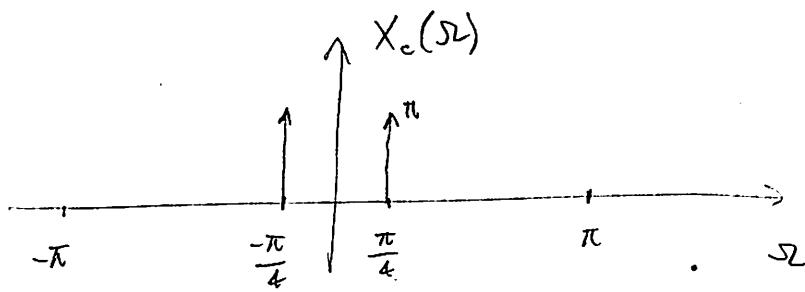
Suppose $BT < \pi$

$$\Leftrightarrow T < \frac{\pi}{B} \Leftrightarrow f_s > \frac{B}{\pi}$$

In general:

$$X_d(\omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c\left(\frac{\omega + 2k\pi}{T}\right)$$

Ex: $x(t) = \cos\left(\frac{\pi}{4}t\right)$ sampled at $F_s = 3, T = \frac{1}{3}$ $\rightarrow \cos\left(\frac{\pi}{4} \cdot nT\right) = \cos\left(\frac{\pi}{12}n\right)$



$$X_c(jw) = \pi \left[\delta\left(jw - \frac{\pi}{4}\right) + \delta\left(jw + \frac{\pi}{4}\right) \right]$$

$$X_d(jw) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c\left(\frac{w+2k\pi}{T}\right) = \frac{1}{T} \sum_{k=-\infty}^{\infty} \pi \left[\delta\left(\frac{w+2k\pi}{T} - \frac{\pi}{4}\right) + \delta\left(\frac{w+2k\pi}{T} + \frac{\pi}{4}\right) \right]$$

$$= \frac{\pi}{T} \sum_{k=-\infty}^{\infty} \left[\delta\left(\frac{w+2k\pi - T\frac{\pi}{4}}{T}\right) + \delta\left(\frac{w+2k\pi + T\frac{\pi}{4}}{T}\right) \right] \quad \text{Recall that} \\ \delta(\alpha w) = \frac{1}{\alpha} \delta(w)$$

$$= \pi \sum_{k=-\infty}^{\infty} \left[\delta\left(w + 2k\pi - \frac{\pi}{12}\right) + \delta\left(w + 2k\pi + \frac{\pi}{12}\right) \right]$$