

Lecture 13

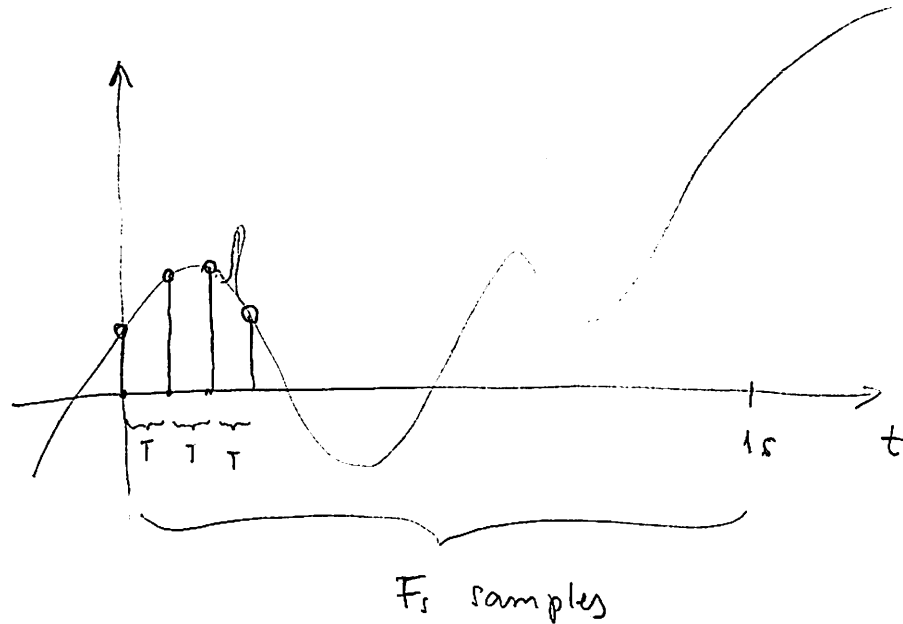
Sampling of continuous-time (CT) signals

CT signal $x_c(t)$
($t \in \mathbb{R}$)



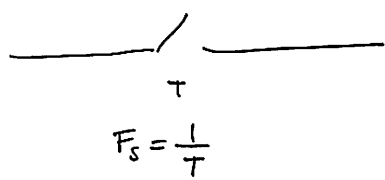
discrete-time signal

$$x[n] = x_c(nT)$$

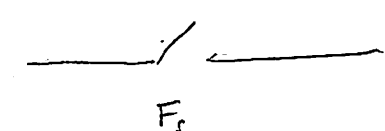


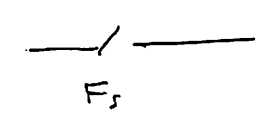
sampling frequency $F_s = \frac{1}{T}$
(samples/second)

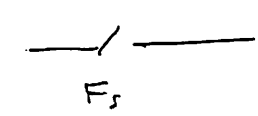
Key question: Are the samples $\{x[0], x[1], x[2], \dots\}$ sufficient
to uniquely characterize $x_c(t)$? How large does F_s have to be?

Ex: $x_c(t) = \cos(\underbrace{2\pi f_0 t}_{\omega_0 t})$  $x[n] = \cos(2\pi f_0 \cdot nT)$
 $= \cos\left(2\pi \underbrace{\frac{f_0}{F_s}}_{\omega_0} n\right)$

Consider another signal:

$y_c(t) = \cos(2\pi(f_0 + \overset{k \in \mathbb{Z}}{kF_s})t)$  $y[n] = \cos(2\pi(f_0 + kF_s)nT)$
 $= \cos\left(2\pi \frac{f_0}{F_s} n + 2\pi kn\right)$
 $= \cos\left(2\pi \frac{f_0}{F_s} n\right) = x[n]$

signal @ freq. f_0  same discrete-time signal!

signal @ freq. $f_0 + kF_s$ 

CT: $f_0 + kF_s$ $\xrightarrow{\text{sampled at } F_s}$ DT: $\underbrace{2\pi \frac{f_0}{F_s}}_{\omega_s}$ (angular frequency)

$$-\frac{F_s}{2} \leq \cdot \leq \frac{F_s}{2}$$

(fundamental frequency) frames per second

Ex: Video shot at 30 fps ($F_s = 30 \text{ Hz}$)
of an airplane propeller

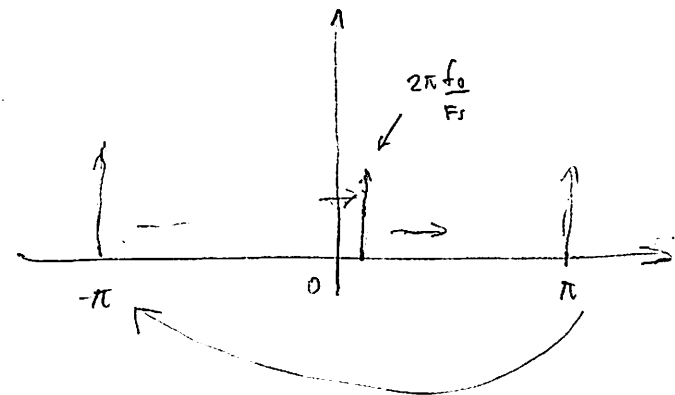
① $f_0 = 3 \text{ Hz}$: Fundamental freq: 3 Hz

② $f_0 = 27 \text{ Hz}$: Fund. freq: -3 Hz

③ $f_0 = 43 \text{ Hz}$: Fund freq: 13 Hz

④ $f_0 = 327 \text{ Hz}$: Fund freq: -3 Hz

propeller rotating
backwards



In frequency domain:

Recall: $x_c(t) = \cos(\Omega_0 t)$ $\xleftrightarrow{\text{CTFT}}$ $\pi [\delta(\Omega - \Omega_0) + \delta(\Omega + \Omega_0)]$

$$= \frac{e^{j\Omega_0 t} + e^{-j\Omega_0 t}}{2}$$

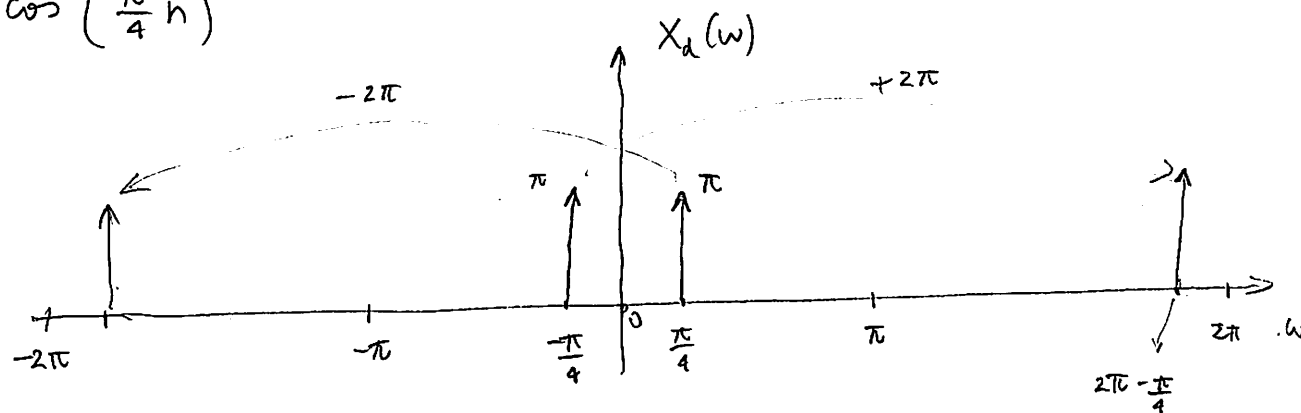
In DT: $x[n] = \cos(\omega_0 n)$ $\xleftrightarrow{\text{DTFT}}$ $\pi [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$

$$= \frac{e^{j\omega_0 n} + e^{-j\omega_0 n}}{2}$$

always
 2π -periodic

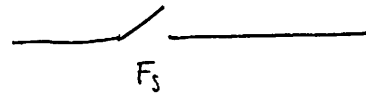
repeated at every
interval of length 2π

Ex: $x[n] = \cos\left(\frac{\pi}{4} n\right)$



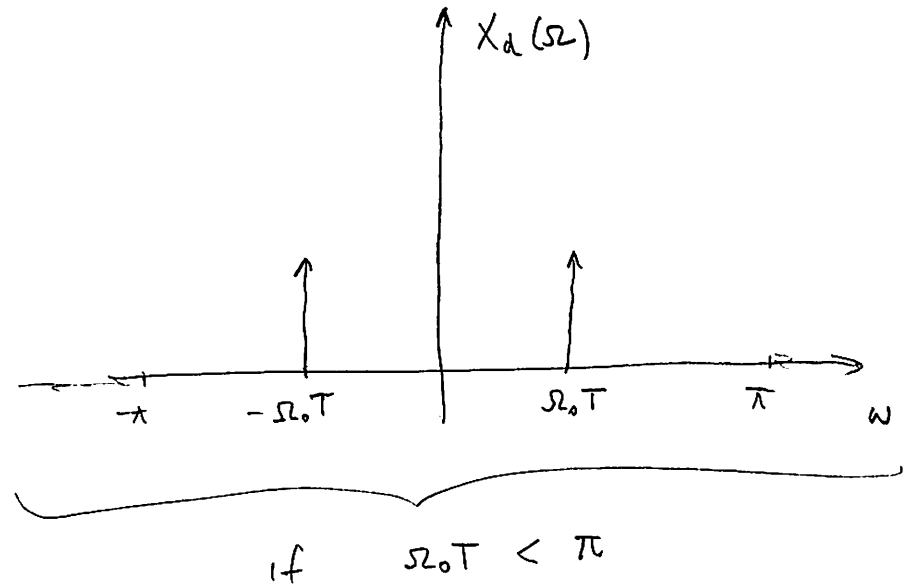
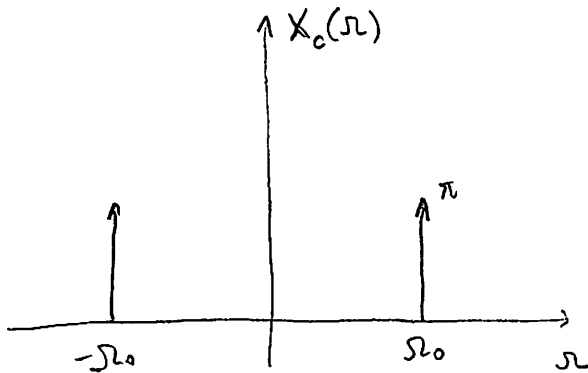
Sampling at $F_s = \frac{1}{T}$

$$x_c(t) = \cos(\Omega_0 t)$$

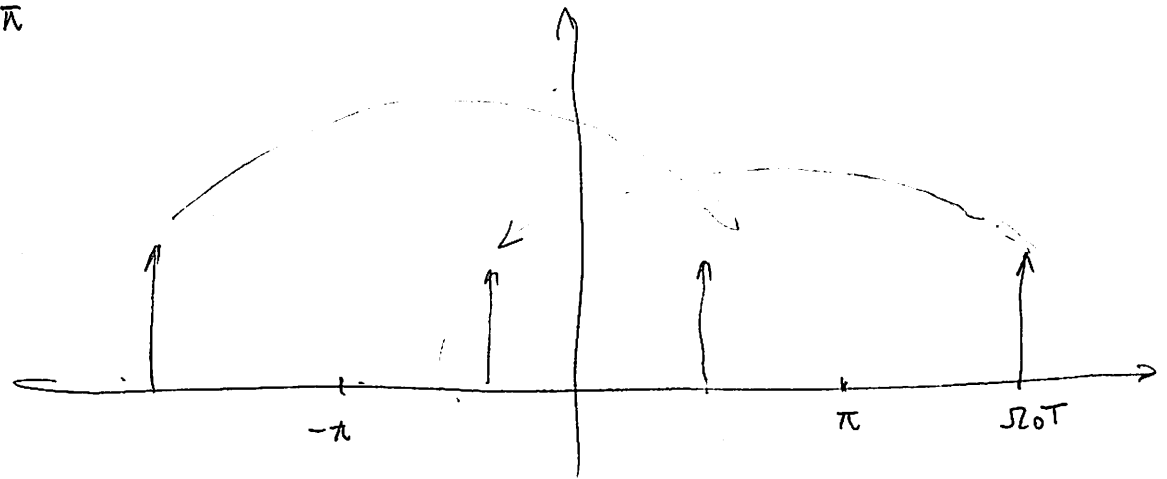


$$x[n] = \cos(\Omega_0 nT) = \cos(\overbrace{\Omega_0 T}^{\omega_0} \cdot n)$$

In freq. domain:



If $\pi < \Omega_0 T < 2\pi$



$$f_0 = 0.9$$

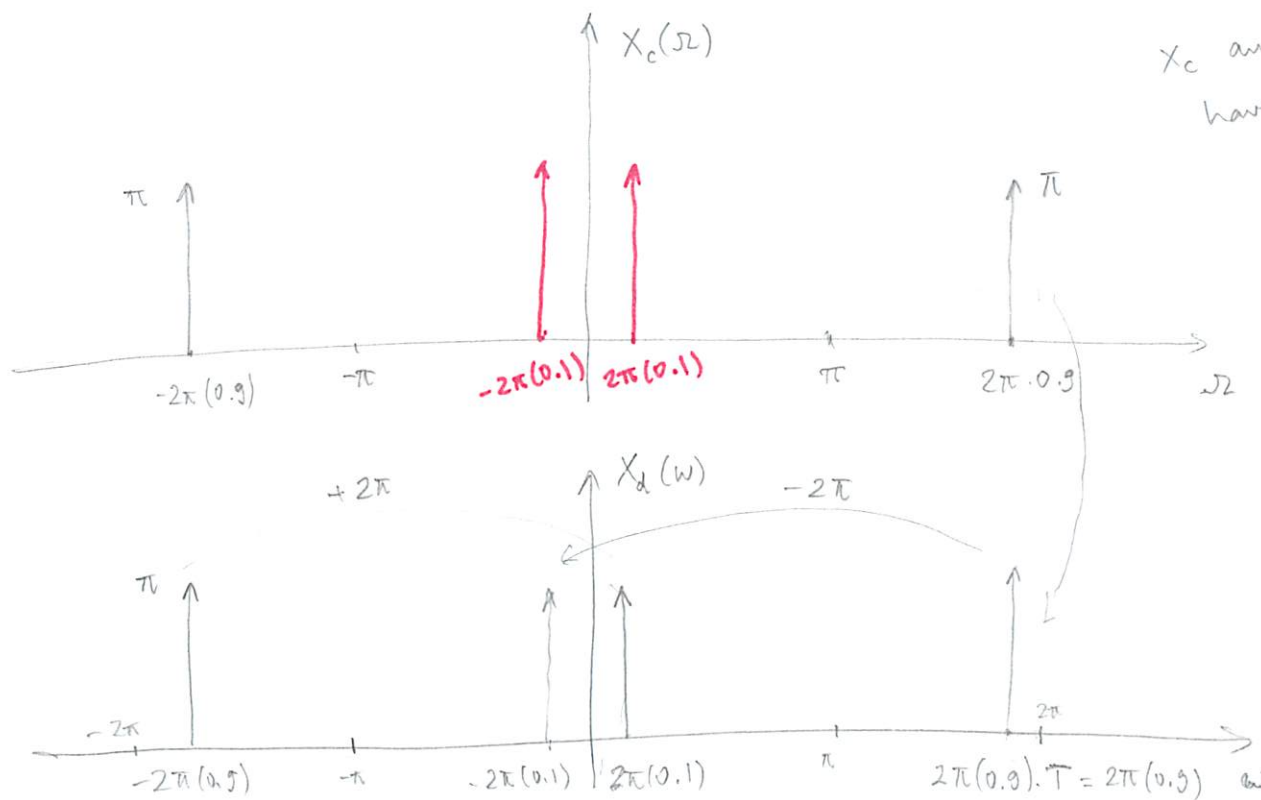
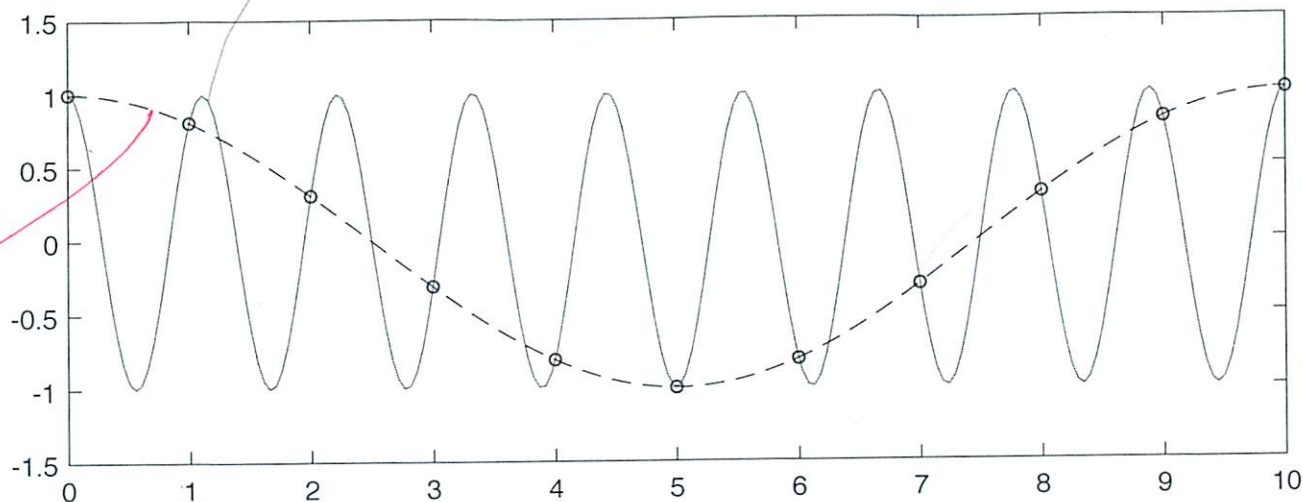
$$x_c(t) = \cos(\underbrace{2\pi(0.9)}_{\Omega_0} t)$$

$$F_s = 1$$

$$T = 1$$

$$x[n] = \cos(2\pi(0.9)n)$$

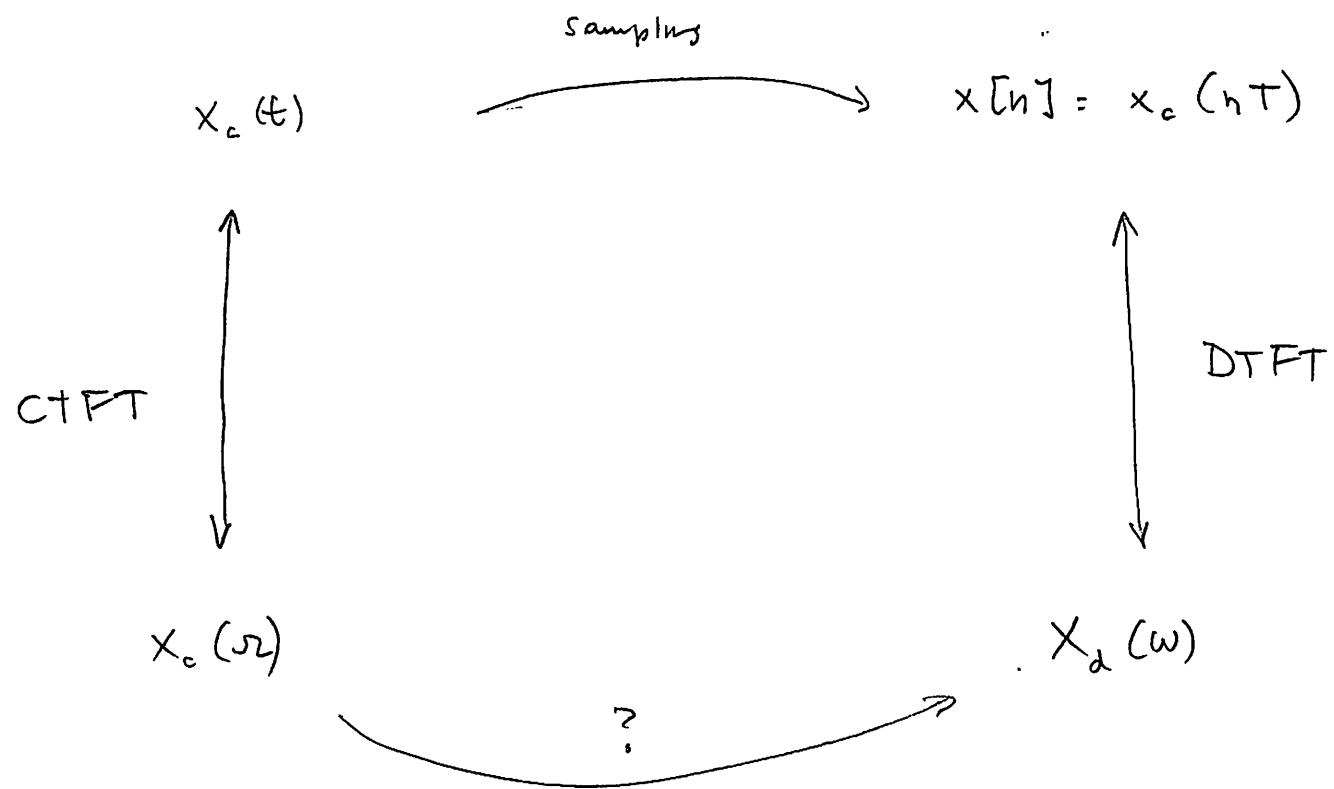
$$y_c(t) = \cos(2\pi(0.1)t)$$



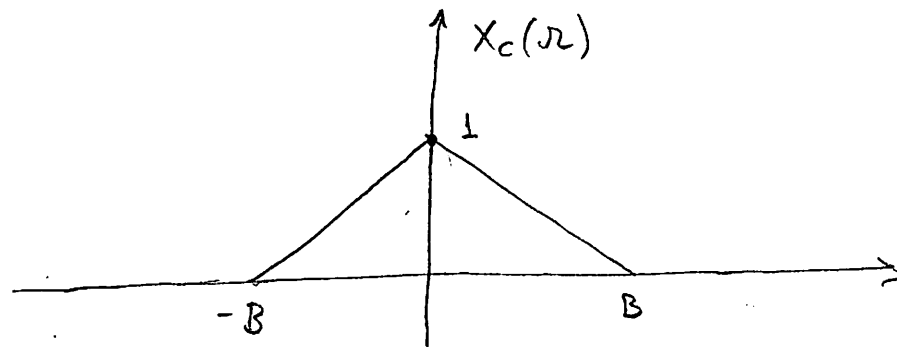
x_c and y_c
have different
CTFT

but the
same DTFT

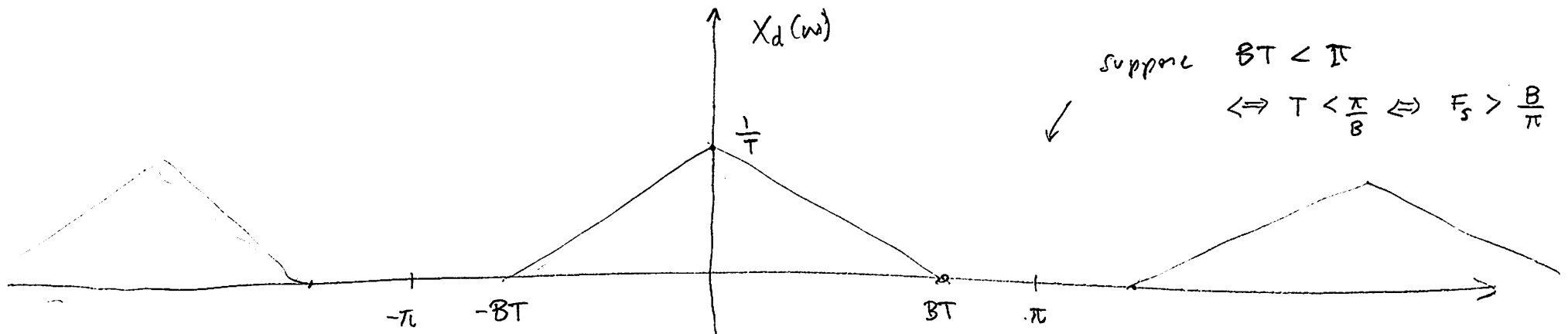
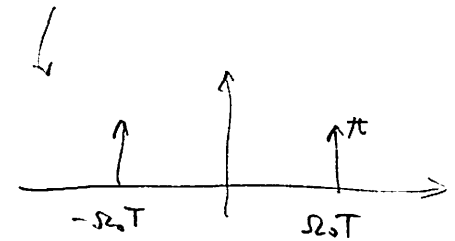
Connecting continuous and discrete



Suppose $X_c(\Omega)$ is given below



For $x(t) = \cos(\Omega_0 t)$



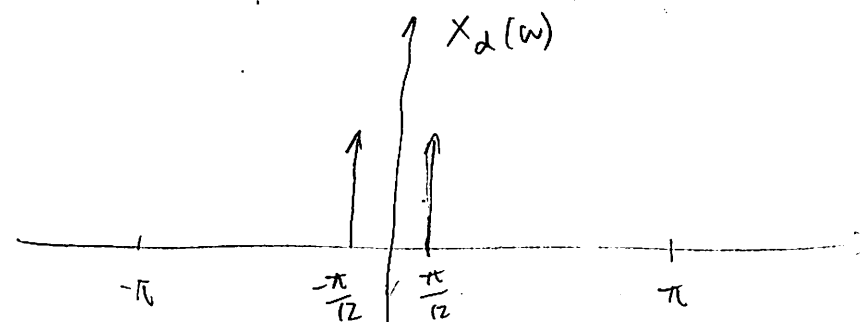
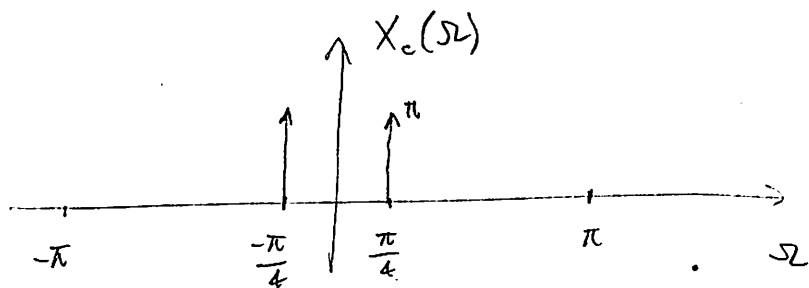
suppose $BT < \pi$

$$\Leftrightarrow T < \frac{\pi}{B} \Leftrightarrow F_s > \frac{B}{\pi}$$

In general:

$$X_d(\omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c\left(\frac{\omega + 2k\pi}{T}\right)$$

Ex: $x(t) = \cos\left(\frac{\pi}{4}t\right)$ $\xrightarrow{\text{sampled at } F_s = 3, T = 1/3}$ $\cos\left(\frac{\pi}{4} \cdot nT\right) = \cos\left(\frac{\pi}{12}n\right)$



$$X_c(\Omega) = \pi \left[\delta\left(\Omega - \frac{\pi}{4}\right) + \delta\left(\Omega + \frac{\pi}{4}\right) \right]$$

$$X_d(\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c\left(\frac{\omega + 2k\pi}{T}\right) = \frac{1}{T} \sum_{k=-\infty}^{\infty} \pi \left[\delta\left(\frac{\omega + 2k\pi}{T} - \frac{\pi}{4}\right) + \delta\left(\frac{\omega + 2k\pi}{T} + \frac{\pi}{4}\right) \right]$$

$$= \frac{\pi}{T} \sum_{k=-\infty}^{\infty} \left[\delta\left(\frac{\omega + 2k\pi - T\frac{\pi}{4}}{T}\right) + \delta\left(\frac{\omega + 2k\pi + T\frac{\pi}{4}}{T}\right) \right]$$

Recall that
 $\delta(a\omega) = \frac{1}{a} \delta(\omega)$

$$= \pi \sum_{k=-\infty}^{\infty} \left[\delta\left(\omega + 2k\pi - \frac{\pi}{12}\right) + \delta\left(\omega + 2k\pi + \frac{\pi}{12}\right) \right]$$