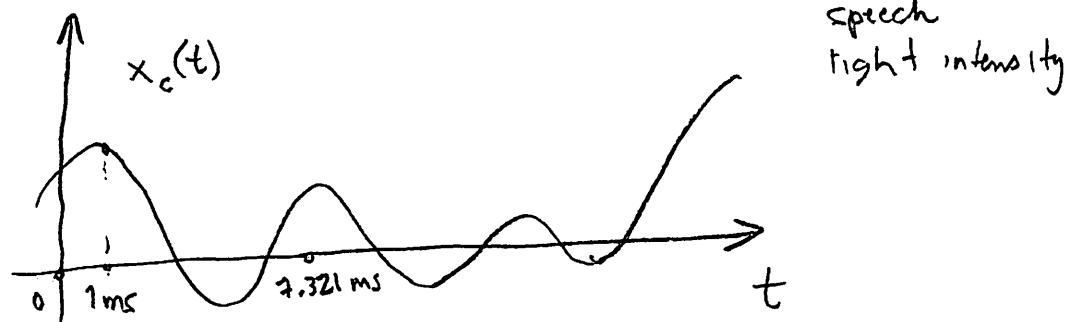


- Main characters: Signals and Systems

① Signals: physical quantity that carries information

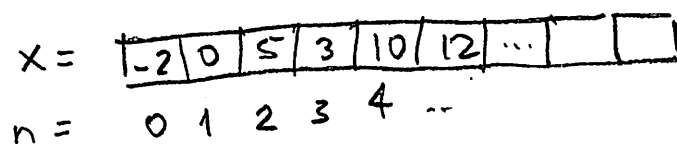
(i) continuous-time (analog, real-world)

$$x(t), t \in \mathbb{R}$$



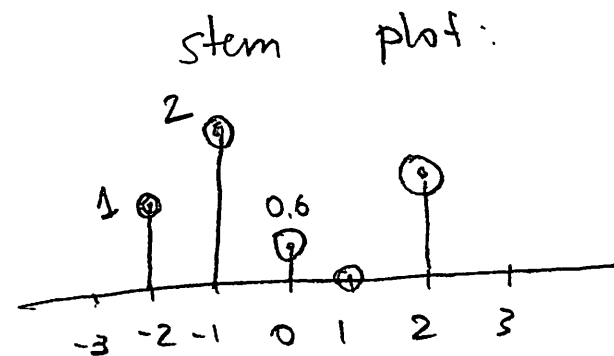
(ii) discrete-time (digital, computer)

$$\{x[n]\}_{n=-\infty}^{\infty}$$

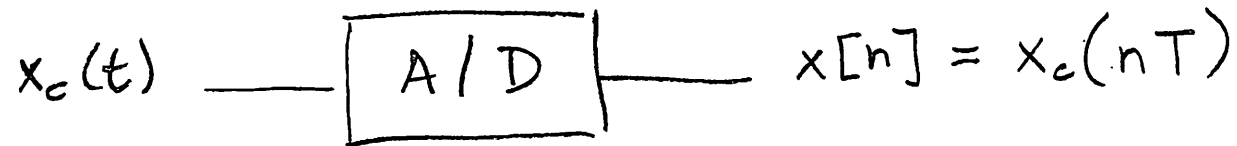


bytes stored in memory

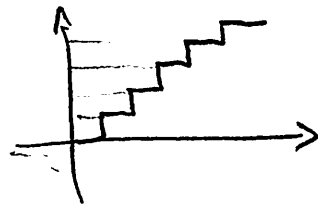
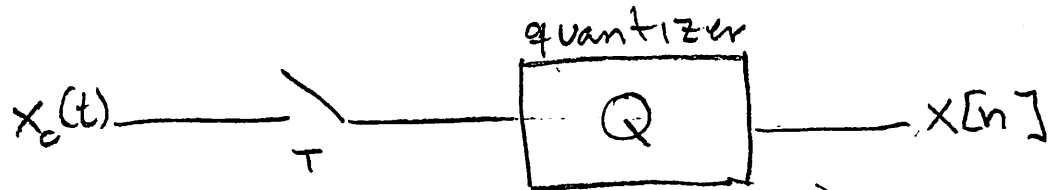
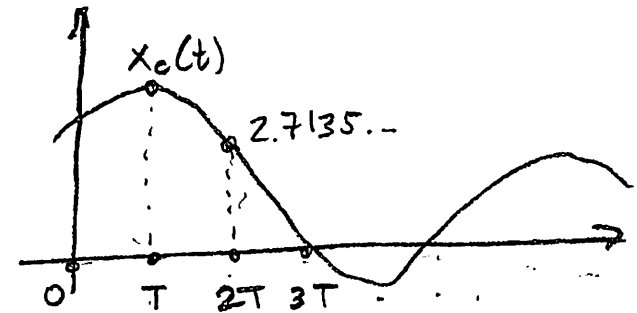
$$= \left\{ \dots, \underset{\substack{\uparrow \\ \text{samples}}}{x[-1]}, x[0], \underset{\substack{\uparrow \\ \text{sample index}}}{x[1]}, x[2], \dots \right\}$$



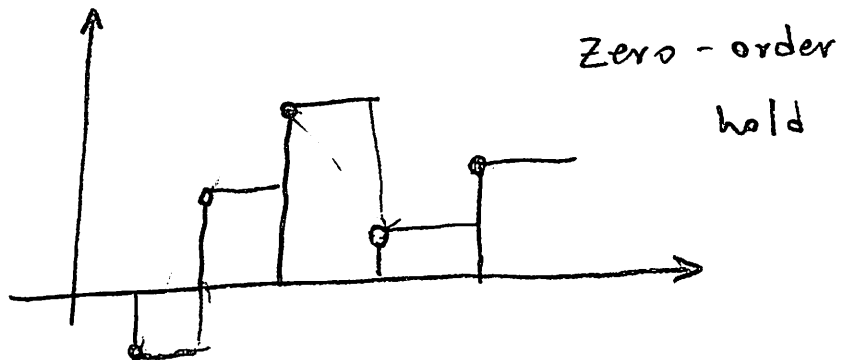
- converting between discrete and continuous



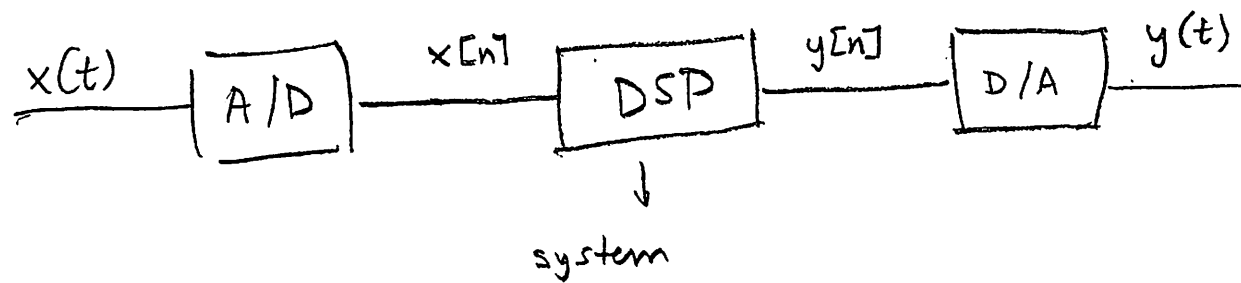
↑
 T (sampling period)



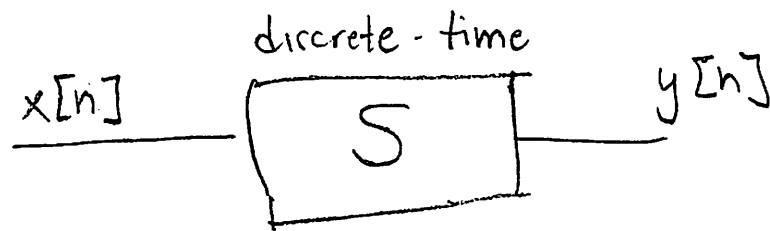
ignored in this course



In this course

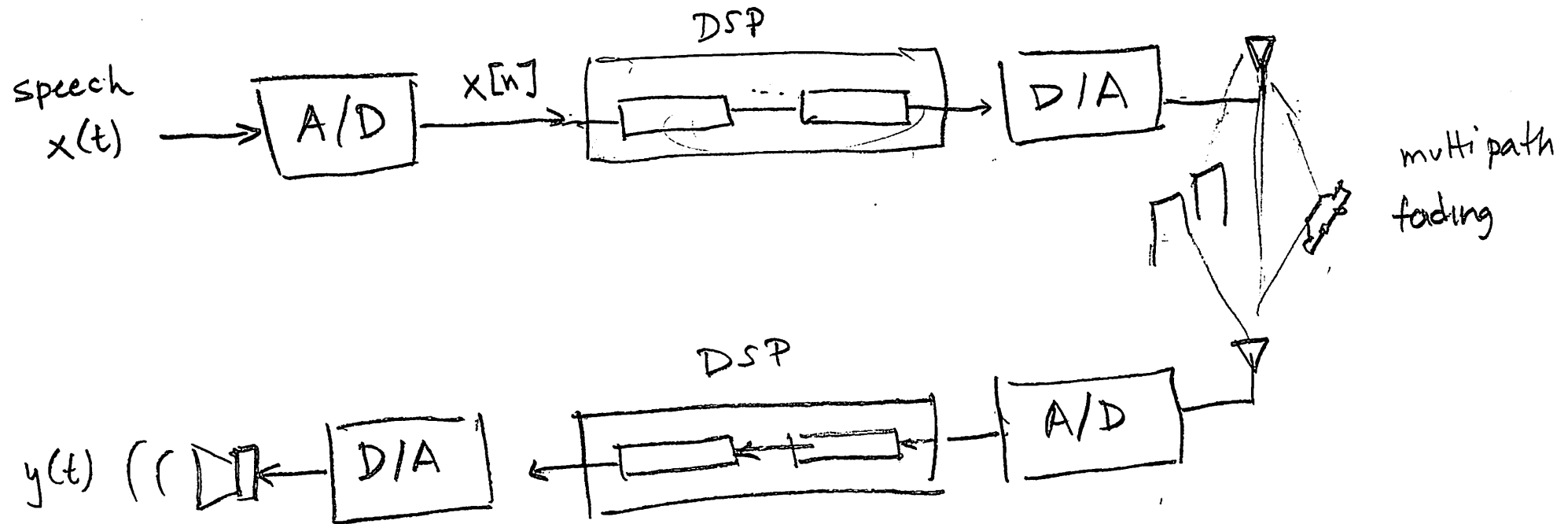


② System : maps an input signal to an output signal



$$\left\{ y[n] \right\}_{n=-\infty}^{\infty} = S \left(\left\{ x[n] \right\}_{n=-\infty}^{\infty} \right)$$

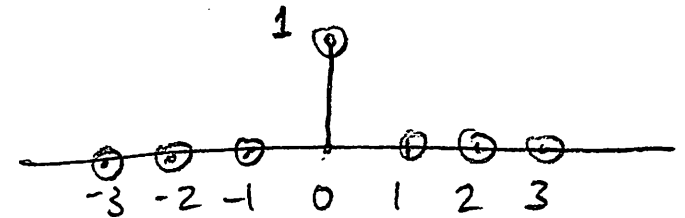
- Example DSP application (Cell phone)



Basic discrete-time signals and systems

① Impulse signal

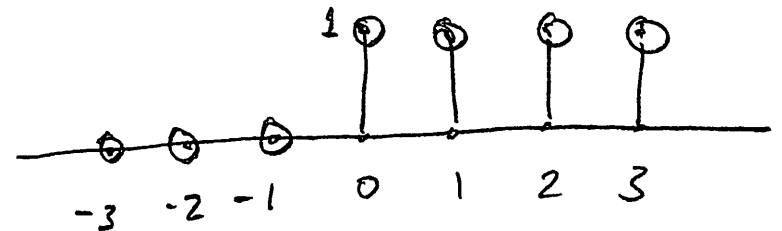
$$\delta[n] = \begin{cases} 1 & \text{if } n=0 \\ 0 & \text{otherwise} \end{cases}$$



$$\{\delta[n]\}_{n=-\infty}^{\infty} = \{\dots, 0, 0, \underset{\uparrow}{1}, 0, 0, \dots\}$$

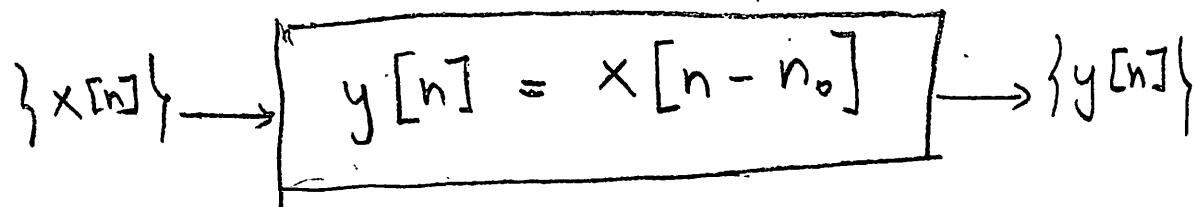
② Unit step signal

$$u[n] = \begin{cases} 1 & \text{if } n \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

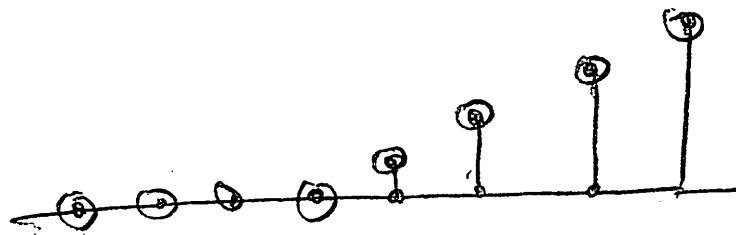
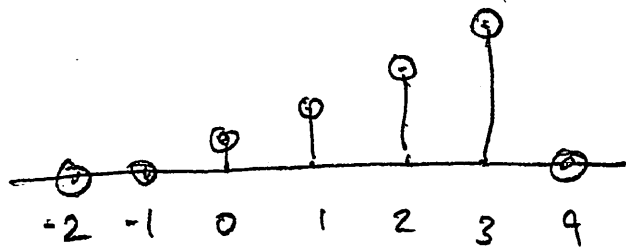


$$\{u[n]\} = \{\dots, 0, 0, \underset{\uparrow}{1}, 1, 1, \dots\}$$

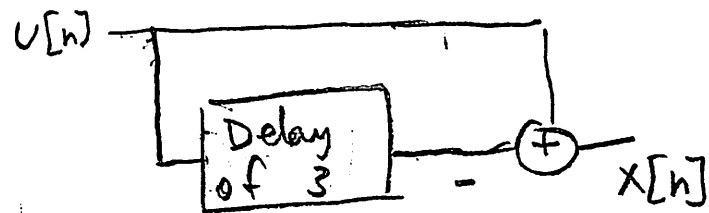
③ Delay by n_0 (system) → constant



Ex₁: $\{x[n]\}_{n=0}^3 = \{1, 2, 3, 4\}$, delay by $n_0 = 2$



Ex₂: $x[n] = u[n] - u[n-3]$



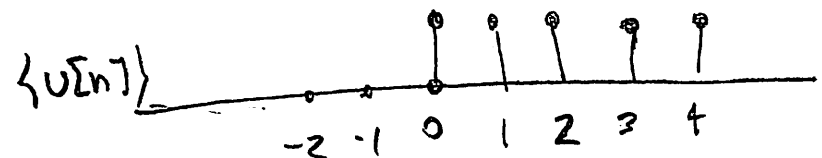
$$y[-1] = x[-1-2] = x[-3] = 0$$

$$y[0] = x[-2] = 0$$

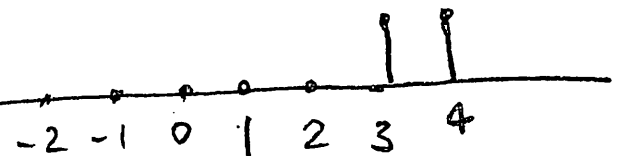
$$y[1] = x[-1] = 0$$

$$y[2] = x[0] = 1$$

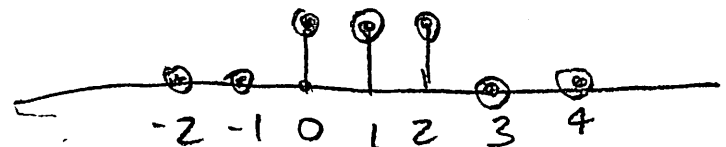
$$y[5] = x[3] = 4$$



$\{u[n-3]\}$



rectang vlar
window
signal



Ex₃: $\delta[n] \rightarrow \boxed{\text{Delay by } n_0} \rightarrow \underline{\delta[n - n_0]}$

