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Chapter 2

Partition Function Computation and Improvements

2.1 Introduction

The partition function for a thermodynamic system of fixed volume, in contact with a heat reservior with absolute temperature T, is

$$Z = \sum_{s} e^{-E(s)/RT}, \qquad (2.1)$$

where s denotes a particular state of the system, E(s) is the energy of that state, and RT is the gas constant multiplied by the temperature, specified above. Each particular term in the sum is called that state's Boltzmann factor. The probability of a state is then said to be its Boltzmann factor divided by the partition function, or

$$P(s) = \frac{1}{Z}e^{-E(s)/RT}.$$
 (2.2)

In our model an RNA strand is such a thermodynamic system, its secondary structure is its state, and the rest of the cell is the reservoir of heat. We assign each secondary structure an energy according to the free energy model described in Chapter 1. According to this model, the energy of a secondary structure is the sum of the energies of its loops.

To compute the partition function we must sum up every possible secondary structure. There are many possible secondary structures, on the order of 1.8^n where n is the sequence length. However, the computation of the partition function benefits greatly from the linear nature of the energy model: it allows us to recursively define the partition function. For example, say we have computed the full partition function of a strand of n bases, define a function Q such that:

$$Q(i,j) = \text{sum of boltzmann factors for every structure contained between } i \text{ and } j.$$

$$(2.3)$$

The full partition computation can therefore be represented as the function Q acting on the bounding two bases 1 and n:

$$Q(1,n) = \sum_{s \text{ on } [1,n]} e^{-E(s)/RT}.$$
(2.4)

If we now extend the strand by attaching a small hairpin to the end, as pictured in Figure 2-1, there is no need to go back and recompute the energy of every single secondary structure, rather we can just multiply the already-computed partition function by the boltzmann factor of the hairpin turn (let E(h) be the hairpin energy) to get the new partition function:

$$Q(1, n+5) = \sum_{s \text{ on } [1,n]} e^{-(E(s)+E(h))/RT} = Q(1,n)e^{-E(h)/RT}.$$
 (2.5)

This replaces an exponential-time computation (the sum), with a constant time computation (multiplying the pre-computed Q(1, n) with the energy term). In general, this technique allows us to compute the partition function efficiently, working up from

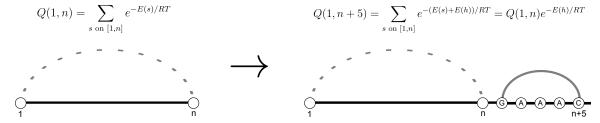


Figure 2-1: Extending the strand by adding an attached hairpin adds the energy of the hairpin to each structure. To compute the new partition function Q(1, n + 5), we do not need to sum the energies of all possible structures again, we can simply use the old value, Q(1, n), and multiply it by the Boltzmann factor of the hairpin. This is the concept behind the dynamic programming algorithm.

Q(1,2) to Q(1,n). In computer science this technique is called dynamic programming, a really fancy name for the technique of storing the results of a computation in a table for later use.

The dynamic programming algorithm for computing the partition function of an RNA strands has several versions, depending on how in depth you go with the energy model. If you ignore psuedoknots, which is standard in the field, and if you make an approximation that internal loops will never exceed a certain length, the fastest algorithm runs in $O(n^3)$. We believe that we can streamline this computation even more, taking advantage of the fact that empirically, the number of probable base pairs of a strand of length n seems to grow like n, not n^2 . This is the same result we used to speed up the stochastic traceback algorithm and potentially a partition function algorithm that includes pseudoknots. The algorithm will be presented in its simplest form, with more complicated versions available in the appendices.

2.2 Motivation

In certain situations, such as partition function clustering, the partition function is computed and recomputed several times. If the partition function takes on the order of hours or days to compute, this can make partition function clustering a bad option. However in these situations it is also true that the partition function is recomputed with almost the same properties, just certain pairs restricted. This motivates a method of computing the partition function using a known pairs heueristic to prune away unnecessary computation.

This concept has already been implemented to great success in the stochastic traceback algorithm. We've been able to show via experiment that the partition function only admits roughly O(n) pairs with probabilities above thresholds around the machine precision limit. If we have the partition function already computed, we can recompute it by only adding in pairs that have sufficient probability. We can also extend this method: if a good heuristic appears in the future, one that can eliminate a large number of pairs, while being computationally cheap, we should be able to use the results to speed up the partition function computation.

2.3 Computation

The standard way of computing the partition function involves filling out a table where the (i, j) member represents the partition function for the substrand from base i to base j. Because the energy model for RNA is (mostly) linear, the partition function from i to j can be expressed as a function of nearby members of this table. This function is the recurrence relation for the partition function of RNA. Because the free energy model is so complicated and has gone through many iterations, differenct RNA folding software packages implement different versions of the recurrence relation, and they vary widely in complexity.

The definitive representation of the recurrence relation for RNA was formulated in 1990 by J.S. McCaskill in his landmark paper *The Equilibrium Partition Function* and Base Pair Binding Probabilities for RNA Secondary Structure [TODO: cite?]. The formula is also presented better and explained well by a later paper by Dirks and

Pierce in 2003 (Dirks & Peirce 2003). Starting at the outermost layer of this relation, the formula for the partition function of the strand from base i to base j is:

$$Q(i,j) = 1 + \sum_{i \le d < e \le j} Q(i,d-1)Q^b(d,e)$$
(2.6)

The theory behind this formula is that the partition function is a sum of the empty state (the first term, 1) and the state with at least 1 pair, the furthest pair to the right being pair (d, e). The term $Q^b(d, e)$ is the partition function assuming that base d and base e are paired. This function has the following recursion relation:

$$Q^{b}(i,j) = e^{-\frac{\text{Hairpin}(i,j)}{RT}} + \sum_{i \le d < e \le j} e^{\frac{\text{Interior}(i,d,e,j)}{RT}} Q^{b}(d,e) + \sum_{i \le d < e \le j} Q^{m}(i+1,d-1)Q^{b}(d,e)e^{-\frac{\alpha_{1}+2\alpha_{2}+\alpha_{3}(j-e-1)}{RT}} Q^{b}(d,e)$$
(2.7)

The theory behind this formula is that the partition function for a strand assuming i and j are paired includes 3 cases:

- 1. There are no bases paired between i and j, the loop is a hairpin and uses the energy function for a hairpin loop, we call $\operatorname{Hairpin}(i,j)$, which consists of data table lookups.
- 2. There is an internal loop between i and j and a second pair d and e. This uses a different energy model, we call Internal(i,j) and also consists of data table lookups.
- 3. There is a multiloop formed by the pair i and j, which must be carefully accounted for using a special model for multiloops.

The multiloop partition function, $Q^m(i,j)$ is the last piece of the puzzle. The formula is:

$$Q^{m}(i,j) = \sum_{i \le d < e \le j} e^{-\frac{\alpha_2 + \alpha_3(d-i) + \alpha_3(j-e)}{RT}} Q^{b}(d,e) + Q^{m}(i,d-1)Q^{b}(d,e)e^{-\frac{\alpha_2 + \alpha_3(j-e)}{RT}}$$
(2.8)

In english, this just means we sum up all the ways to just have 1 pair, and then all the ways to have more than one pair. The case with no pairs is not included, as in the original recursion in Q^b , $Q^m(i+1,d-1)Q^b(d,e)$ must yield at least 2 pairs. Since Q^b makes one, then Q^m must make at least 1.

For example, the UNAFold software package implements a particularly hairy recurrence relation. Define Q(i,j) as the partition function from i to j, Q'(i,j) to be the partition function from i to j, assuming i and j are paired, and define $Q^1(i,j)$ to be the partition function from i to j, assuming exactly 1 pair happens on that interval, and that pair happens with base i. The recurrence relation is therefore

[recurrence relation]

Note the terms Z_{ND} , $Z_{3'D}$, $Z_{5'D}$, and Z_{DD} are extra free energy terms corresponding to 'dangle energies' which are the results of an experiment later implemented in the model to improve it from the standard energy model. In addition there are AU penalty terms appended to where pairs are made, as AU and GU pairs have penalties associated with forming. These additional energy terms improve the model's predictive ability and bring the model closer to the "truth", however it unfortunately makes the partition function seem very threatening.

Our new partition function relation has the following theory behind it: Assume we have the functions $I: B \to \{B\}$ and $J: B \to \{B\}$ that return the set of all probably pairs for a base i or a base j, respectively. The recurrence relation can be reformulated in the following way:

2.4 Derivation of new Q(i, j) formula

In UNAfold, we have that the old recurrence relations were as follows:

$$Q(i,j) = \sum_{k=i}^{j} \left(Q(i,k-1) + e^{-\frac{b(k-i)}{RT}} \right) Q^{1}(k,j)$$
 (2.9)

where

$$Q^{1}(i,j) = Q^{1}(i,j-1)e^{-\frac{b}{RT}}$$

$$+ e^{-\frac{c}{RT}}Z_{ND}(i,j)Q'(i,j)$$

$$+ e^{-\frac{b+c}{RT}}Z_{5'D}(i+1,j)Q'(i+1,j)$$

$$+ e^{-\frac{b+c}{RT}}Z_{3'D}(i,j-1)Q'(i,j-1)$$

$$+ e^{-\frac{2b+c}{RT}}Z_{DD}(i+1,j-1)Q'(i+1,j-1)$$
(2.10)

We can expand the recursive definition of $Q^1(i, j)$:

$$Q^{1}(i,j) = \sum_{k'=i+1}^{j} e^{-\frac{b(j-k')}{RT}} \left[e^{-\frac{c}{RT}} Z_{ND}(i,k') Q'(i,k') + e^{-\frac{b+c}{RT}} Z_{5'D}(i+1,k') Q'(i+1,k') + e^{-\frac{b+c}{RT}} Z_{3'D}(i,k'-1) Q'(i,k'-1) + e^{-\frac{2b+c}{RT}} Z_{DD}(i+1,k'-1) Q'(i+1,k'-1) \right]$$
(2.11)

Plugging this into Q(i, j) we get:

$$Q(i,j) = \sum_{k=i}^{j} \sum_{k'=k+1}^{j} \left(Q(i,k-1) + e^{-\frac{b(k-i)}{RT}} \right) e^{-\frac{b(j-k')}{RT}} \left[e^{-\frac{c}{RT}} Z_{ND}(k,k') Q'(k,k') + e^{-\frac{b+c}{RT}} Z_{5'D}(k+1,k') Q'(k+1,k') + e^{-\frac{b+c}{RT}} Z_{3'D}(k,k'-1) Q'(k,k'-1) + e^{-\frac{2b+c}{RT}} Z_{DD}(k+1,k'-1) Q'(k+1,k'-1) \right]$$

$$(2.12)$$

Now we'll take the jth element of the second sum and split it out (note that the jth part of the 1st sum has no elements to sum now, so we can decrement that too):

$$Q(i,j) = \sum_{k=i}^{j-1} \sum_{k'=k+1}^{j-1} \left(Q(i,k-1) + e^{-\frac{b(k-i)}{RT}} \right) e^{-\frac{b(j-k')}{RT}} \left[e^{-\frac{c}{RT}} Z_{ND}(k,k') Q'(k,k') + e^{-\frac{b+c}{RT}} Z_{5'D}(k+1,k') Q'(k+1,k') + e^{-\frac{b+c}{RT}} Z_{3'D}(k,k'-1) Q'(k,k'-1) + e^{-\frac{b+c}{RT}} Z_{DD}(k+1,k'-1) Q'(k+1,k'-1) \right] + \sum_{k=i}^{j} \left(Q(i,k-1) + e^{-\frac{b(k-i)}{RT}} \right) \left[e^{-\frac{c}{RT}} Z_{ND}(k,j) Q'(k,j) + e^{-\frac{b+c}{RT}} Z_{5'D}(k+1,j) Q'(k+1,j) + e^{-\frac{b+c}{RT}} Z_{3'D}(k,j-1) Q'(k,j-1) + e^{-\frac{2b+c}{RT}} Z_{DD}(k+1,j-1) Q'(k+1,j-1) \right]$$

$$(2.13)$$

Notice that the double sum is simply $Q(i, j-1)e^{-b/RT}$ and the terms of the second, single sum are over the pairs with j or j-1. Therefore, we can use our heuristic for the pairs of j and j-1 to produce the following computation for Q(i,j) which is

much more efficient than the previous ones:

$$Q(i,j) = Q(i,j-1)e^{-b/RT} + \sum_{k(j)} \left[\left(Q(i,k-1) + e^{-\frac{b(k-i)}{RT}} \right) e^{-\frac{c}{RT}} Z_{ND}(k,j) Q'(k,j) \right.$$

$$+ \left(Q(i,k-2) + e^{-\frac{b(k-i-1)}{RT}} \right) e^{-\frac{b+c}{RT}} Z_{5'D}(k,j) Q'(k,j) \left. \right]$$

$$+ \sum_{l(j-1)} \left[\left(Q(i,l-1) + e^{-\frac{b(l-i)}{RT}} \right) e^{-\frac{c}{RT}} Z_{ND}(l,j-1) Q'(l,j-1) \right.$$

$$+ \left. \left(Q(i,l-2) + e^{-\frac{b(l-i-1)}{RT}} \right) e^{-\frac{2b+c}{RT}} Z_{DD}(l,j-1) Q'(l,j-1) \right]$$

$$(2.14)$$

2.5 Derivation of new Q'(i, j) formula

For Q'(i, j) we start with the recursion:

$$Q'(i,j) = Z_{H}(i,j) + Z_{S}(i,j)Q'(i+1,j-1) + QBI(i,j)$$

$$+ e^{-\frac{a+c}{RT}}Z_{ND}(j,i) \sum_{k=i+3}^{j-5} Q(i+1,k-1)Q^{1}(k,j-1)$$

$$+ e^{-\frac{a+b+c}{RT}}Z_{3'D}(j,i) \sum_{k=i+4}^{j-5} Q(i+2,k-1)Q^{1}(k,j-1)$$

$$+ e^{-\frac{a+b+c}{RT}}Z_{5'D}(j,i) \sum_{k=i+3}^{j-6} Q(i+1,k-1)Q^{1}(k,j-2)$$

$$+ e^{-\frac{a+2b+c}{RT}}Z_{DD}(j,i) \sum_{k=i+4}^{j-6} Q(i+2,k-1)Q^{1}(k,j-2)$$

$$+ e^{-\frac{a+2b+c}{RT}}Z_{DD}(j,i) \sum_{k=i+4}^{j-6} Q(i+2,k-1)Q^{1}(k,j-2)$$

The 4 for loops in this make this an expensive computation as the number of bases gets very high. However, these for loops are very similar to the partition function in structure. Indeed, we could perhaps replace each of them with a function of the form $Q^m(i,j)$ defined as

$$Q^{m}(i,j) = \sum_{k=i+3}^{j-5} Q(i+1,k-1)Q^{1}(k,j-1)$$
(2.16)

Which would simplify the previous sum to a constant time computation, provided we have memoized Q^m :

$$Q'(i,j) = Z_{H}(i,j) + Z_{S}(i,j)Q'(i+1,j-1) + QBI(i,j)$$

$$+ e^{-\frac{a+c}{RT}}Z_{ND}(j,i)Q^{m}(i,j)$$

$$+ e^{-\frac{a+b+c}{RT}}Z_{3'D}(j,i)Q^{m}(i+1,j)$$

$$+ e^{-\frac{a+b+c}{RT}}Z_{5'D}(j,i)Q^{m}(i,j-1)$$

$$+ e^{-\frac{a+2b+c}{RT}}Z_{DD}(j,i)Q^{m}(i+1,j-1)$$
(2.17)

Now there just needs to be a way to efficiently compute Q^m . First we substitute in the expanded version of Q^1 :

$$Q^{m}(i,j) = \sum_{k=i+3}^{j-5} \sum_{k'=k+1}^{j-1} Q(i+1,k-1)e^{-\frac{b(j-k')}{RT}} \left[e^{-\frac{c}{RT}} Z_{ND}(k,k')Q'(k,k') + e^{-\frac{b+c}{RT}} Z_{5'D}(k+1,k')Q'(k+1,k') + e^{-\frac{b+c}{RT}} Z_{3'D}(k,k'-1)Q'(k,k'-1) + e^{-\frac{2b+c}{RT}} Z_{DD}(k+1,k'-1)Q'(k+1,k'-1) \right]$$

$$(2.18)$$

Then we do as before and seperate out the jth term of the second sum. Note that there seems to be an additional sum needed to account that I've decreased the first sum's endpoint to j-6, but the sum ends up being from k'=j-4 to k'=j-2 and since Q' for bases less than 4 apart is 0 due to hairpin loop rules, this sum is equal

to zero.

$$Q^{m}(i,j) = \sum_{k=i+3}^{j-6} \sum_{k'=k+1}^{j-2} Q(i+1,k-1)e^{-\frac{b(j-k'-1)}{RT}} \left[e^{-\frac{c}{RT}} Z_{ND}(k,k') Q'(k,k') + e^{-\frac{b+c}{RT}} Z_{5'D}(k+1,k') Q'(k+1,k') + e^{-\frac{b+c}{RT}} Z_{3'D}(k,k'-1) Q'(k,k'-1) + e^{-\frac{b+c}{RT}} Z_{DD}(k+1,k'-1) Q'(k+1,k'-1) \right] + \sum_{k=i+3}^{j-5} Q(i+1,k-1) \left[e^{-\frac{c}{RT}} Z_{ND}(k,j-1) Q'(k,j-1) + e^{-\frac{b+c}{RT}} Z_{5'D}(k+1,j-1) Q'(k+1,j-1) + e^{-\frac{b+c}{RT}} Z_{3'D}(k,j-2) Q'(k,j-2) + e^{-\frac{2b+c}{RT}} Z_{DD}(k+1,j-2) Q'(k+1,j-2) \right]$$

$$(2.19)$$

The double sum is again going to be equal to $Q^m(i, j-1)e^{-b/RT}$, and the second sum can be made much more efficient by our heuristic.

$$Q^{m}(i,j) = Q^{m}(i,j-1)e^{-b/RT} + \sum_{k(j-1)} \left[Q(i+1,k-1)e^{-\frac{c}{RT}} Z_{ND}(k,j-1)Q'(k,j-1) + Q(i+1,k-2)e^{-\frac{b+c}{RT}} Z_{5'D}(k,j-1)Q'(k,j-1) \right] + \sum_{k(j-2)} \left[Q(i+1,k-1)e^{-\frac{c}{RT}} Z_{3'D}(k,j-2)Q'(k,j-2) + Q(i+1,k-2)e^{-\frac{b+c}{RT}} Z_{DD}(k,j-2)Q'(k,j-2) \right]$$

$$(2.20)$$

Since the ks for any individual j are found to be quite limited, the final form should be much more efficient at computing the Q'(i,j).

Note that for Q and in many places for Q', instead of a sum over the known k that

could possibly begin a leftmost pair, we see a double sum. One of them over k that could end a leftmost pair, and this sum is limited to a certain length below j. This is just making the same assumption that the internal loop computation makes: there are not arbitrarily long strands without base pairs, after a certain number of bases it becomes overwhelmingly more likely to make a base pair that we can virtually ignore the energy of the the cases of length beyond a certain L.

As for the second sum, since the number of probable pairs for a base i has been shown empirically to be roughly constant, regardless of length, the second sum is essentially constant. What this all means is that all $O(n^2)$ computations of Q(i,j)'s are roughly constant time. This means that the overall algorithm is $O(n^2)$, an improvement over the previous algorithms asymptotic bound by and order of n!

2.6 Results

[TODO: include timing plots for new partition function]

Calculating the partition function is still difficult, but it can be improved in the asymptotic case. The results show that the new computation has a large constant factor in the beginning of the algorithm. This could be related to the way the internal loop partition function is calculated, where we still have an $O(n^3)$ algorithm until the number of nucleotides is greater than 30. This effect is relatively diminished as we get into the 1000s in term of base count, but it still is a large constant factor. As we increase the probability barrier, we get further reductions in runtime.

[TODO: include plot with different times for different probability thresholds]

A large part of the verification of an improved algorithm is showing that it produces acceptable results compared to the old algorithm, as you can see in the plot, our algorithm gives the same results up to 1 part in 1 million [TODO: check this]. Increasing the probability threshold changes the results by [TODO: find out].

2.7 Conclusion

The partition function computation is hard and is a limiting factor in RNA structure prediction. However, given a heuristic to predict the base pairs, we can make the algorithm run faster. These improvements can be used in applications such as clustering based on our nestedness measure, using the partition function. These improvements also open up several possible branches for further investigation. Can a heuristic be generated before the partition function is computed, so that the pairs can be restricted and the computation done in much faster time than the $O(n^3)$ algorithm? Could this concept be applied to the pseudoknot algorithm to possibly speedup the computation for that as well? Applications of this sort could have tremendous impact on RNA secondary structure prediction, opening up incredible avenues of potential.