

R Tutorial

Part 5

Hidden Markov Model

*Its easier to record the evidence and observations
rather than find the actual reason behind every
phenomena*

Why HMM?!

*All we do is recording observation
All we have is observations*

depmixS4

- There are different packages in R for building hidden Markov models, such as *mhsmm*, *HMM*, *depmixS4*, and so on.
- Although each of these packages has its own pros and cons, **depmixS4** package is the one we use in this tutorial.
- For more information about this package check the links below:
<https://cran.r-project.org/web/packages/depmixS4/vignettes/depmixS4.pdf>
<https://cran.r-project.org/web/packages/depmixS4/depmixS4.pdf>
- Install depmixS4 package on your R.

depmixS4

Two steps are involved in using `depmixS4` which are illustrated in the following:

1. model specification with function `depmix`.
2. model fitting with function `fit`.

Maximizing the likelihood of the train data by adjusting the model parameters and fitting the model (Problem 3).

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- The Simplest Model (model specifications):

To build a HMM we have to determine two main parameters;

- 1) The feature (or the features) which the model will be built based on it (or them).
- 2) Number of states.

```
library("depmixS4")  
data()  
set.seed(1)  
  
mod <- depmix(response =, data =, nstates = )
```

- `set.seed()`: The seed number is the starting point used in the generation of a sequence of random numbers. Using the same number insures you can reproduce the same results.
- `response`: Basically response is the feature (or the features) that the model is built for (or them).
- `data` should be a `data.frame`.
- `nstates` is the number of states.

The `depmix` function returns an object of class “`depmix`” which contains the model specification, and not a fitted model. Hence, the model needs to be fitted by calling `fit`.

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- A Simple Model (model fitting):

```
mod <- depmix(response =, data =, nstates = )  
  
fm <- fit(mod)
```

The `fit` function fit the model with the determined specifications, which means over various iterations the log-likelihood will converge at its maximum.

```
> fm <- fit(mod)  
iteration 0 logLik: -305.321  
iteration 5 logLik: -305.2833  
iteration 10 logLik: -305.1962  
iteration 15 logLik: -304.8088  
iteration 20 logLik: -297.5845  
iteration 25 logLik: -91.85991  
iteration 30 logLik: -88.73835  
iteration 35 logLik: -88.73062  
converged at iteration 39 with logLik: -88.73058  
> |
```

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After determining the model's specifications, we can fit the model based on those specifications.

There is two commands which provides more detail on our model, **print()** and **summary()**.

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(Model Specification)

```
iteration 30 logLik: -88.73835  
iteration 35 logLik: -88.73062  
converged at iteration 39 with logLik: -88.73058
```

```
>
```

```
> summary(fm)
```

```
Initial state probabilities model  
pr1 pr2  
 0    1
```

Initial State Probability

```
Transition matrix  
      toS1 toS2  
fromS1 0.884 0.116  
fromS2 0.084 0.916
```

States Transition Probabilities

```
Response parameters
```

```
Resp 1 : gaussian
```

```
      Re1.(Intercept) Re1.sd  
St1          5.510    0.192  
St2          6.385    0.244
```

Responses Distribution

```
> |
```


depmixS4

depmix

Dependent Mixture Model Specification

Description

depmix creates an object of class depmix, a dependent mixture model, otherwise known as hidden Markov model. For a short description of the package see [depmixS4](#). See the vignette for an introduction to hidden Markov models and the package.

Usage

```
depmix(response, data=NULL, nstates, transition=~1, family=gaussian(),
prior=~1, initdata=NULL, respstart=NULL, trstart=NULL, instart=NULL,
ntimes=NULL,...)
```

Arguments

- | | |
|------------|--|
| response | The response to be modeled; either a formula or a list of formulae (in the multi-variate case); this interfaces to the glm and other distributions. See 'Details'. |
| data | An optional data.frame to interpret the variables in the response and transition arguments. |
| nstates | The number of states of the model. |
| transition | A one-sided formula specifying the model for the transitions. See 'Details'. |
| family | A family argument for the response. This must be a list of family's if the response is multivariate. |
| prior | A one-sided formula specifying the density for the prior or initial state probabilities. |

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<code>initdata</code>	An optional <code>data.frame</code> to interpret the variables occurring in prior. The number of rows of this <code>data.frame</code> must be equal to the number of cases being modeled, <code>length(ntimes)</code> . See 'Details'.
<code>respstart</code>	Starting values for the parameters of the response models.
<code>trstart</code>	Starting values for the parameters of the transition models.
<code>instart</code>	Starting values for the parameters of the prior or initial state probability model.
<code>ntimes</code>	A vector specifying the lengths of individual, i.e. independent, time series. If not specified, the responses are assumed to form a single time series, i.e. <code>ntimes=nrow(data)</code> . If the data argument has an attribute <code>ntimes</code> , then this is used. The first example in fit uses this argument.

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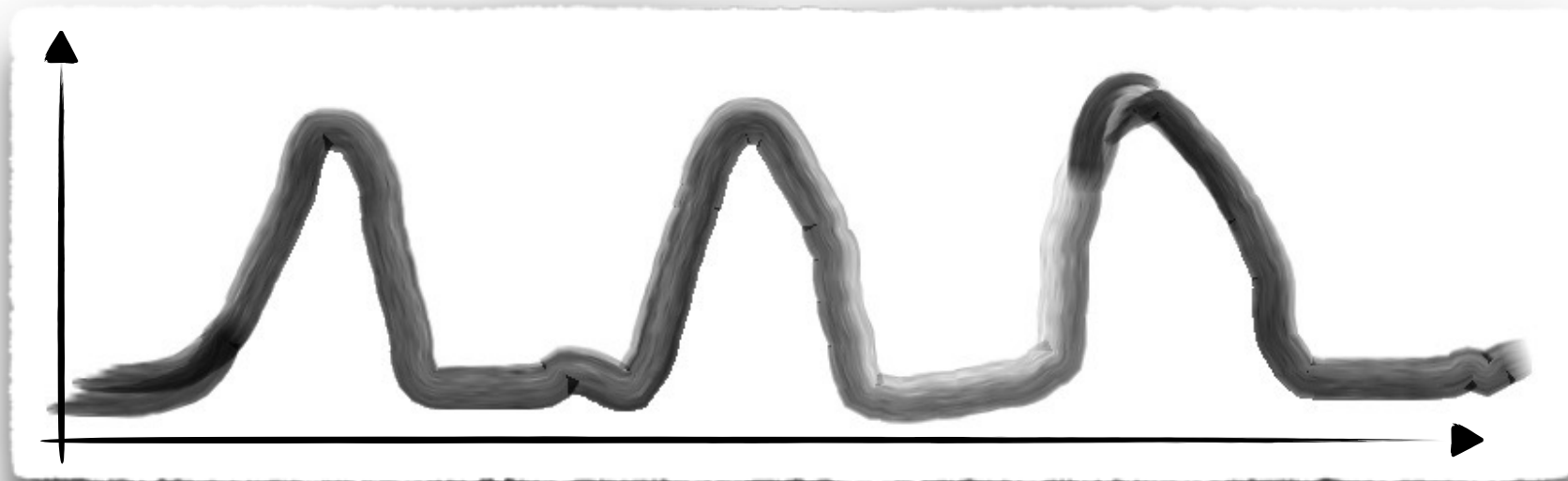
Before going into more details of **depmixS4** package, a few concepts and techniques need to be discussed in order to build a better model which represents the training data:

- Determining the number of states (AIC and BIC)
- Overfitting and underfitting
- Feature selection

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(Number of States)

Getting a sense of states in the hidden Markov models by visualizing the observations;



How many states this observation sequence can have?

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(Number of States)

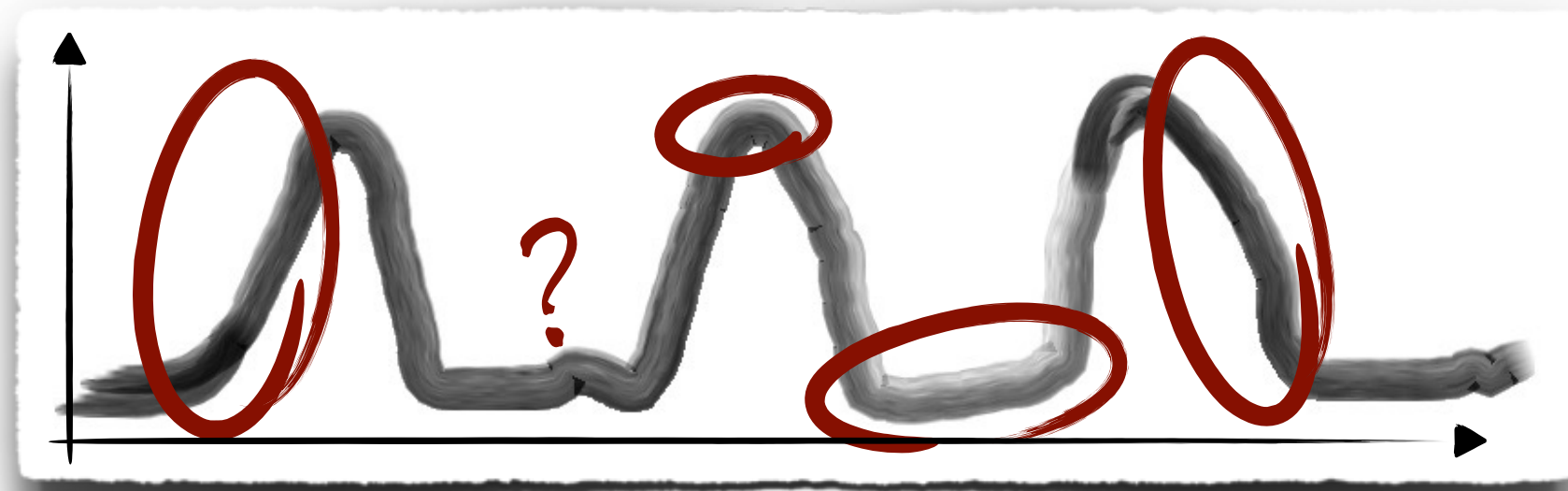
Getting a sense of states in the hidden Markov models by visualizing the observations;



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(Number of States)

Getting a sense of states in the hidden Markov models by visualizing the observations;



By choosing a greater number for states, redundant detail is adding to the model and it may overfit the model.

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(Number of States)

How many states are not too much nor too less? What would be the best number of states?

Sometimes by visualizing the training data we can get a rough feeling about the number of states. But this cannot be anything more than a guess for a starting point.

There are few measures which help to avoid overfitting or underfitting when we are adjusting a model's parameters.

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(AIC and BIC)

When fitting models, it is possible to increase the likelihood by adding parameters, but doing so may result in overfitting. Both AIC and BIC attempt to resolve this problem.⁽¹⁾

The model with the lowest BIC is preferred.

Definition [\[edit\]](#)

The BIC is formally defined as^[2]

$$\text{BIC} = \ln(n)k - 2 \ln(\hat{L}).$$

where

- \hat{L} = the maximized value of the [likelihood function](#) of the model M , i.e. $\hat{L} = p(x|\hat{\theta}, M)$, where $\hat{\theta}$ are the parameter values that maximize the likelihood function;
- x = the observed data;
- n = the number of data points in x , the number of [observations](#), or equivalently, the sample size;
- k = the number of [parameters](#) estimated by the model. For example, in [multiple linear regression](#), the estimated parameters are the intercept, the q slope parameters, and the constant variance of the errors; thus, $k = q + 2$.

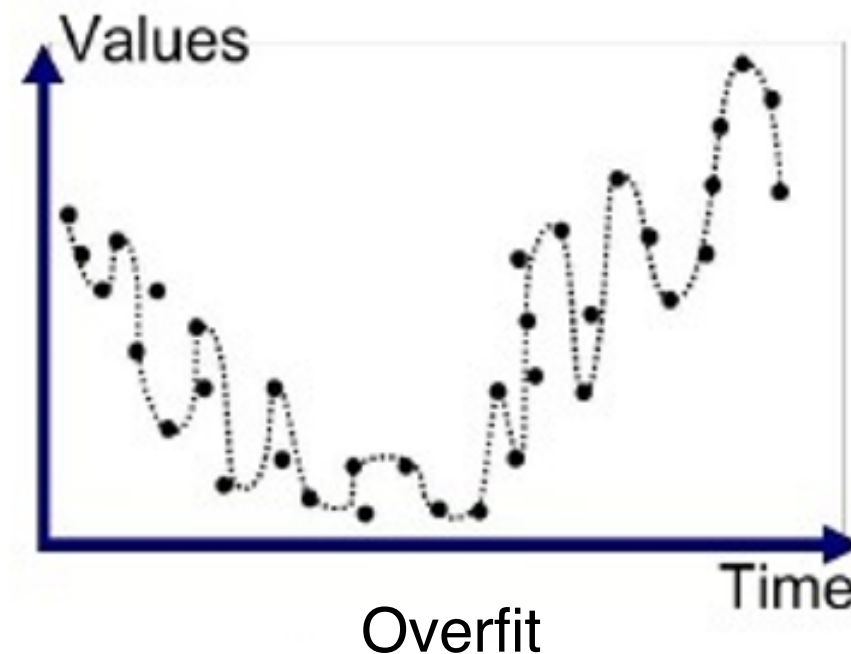
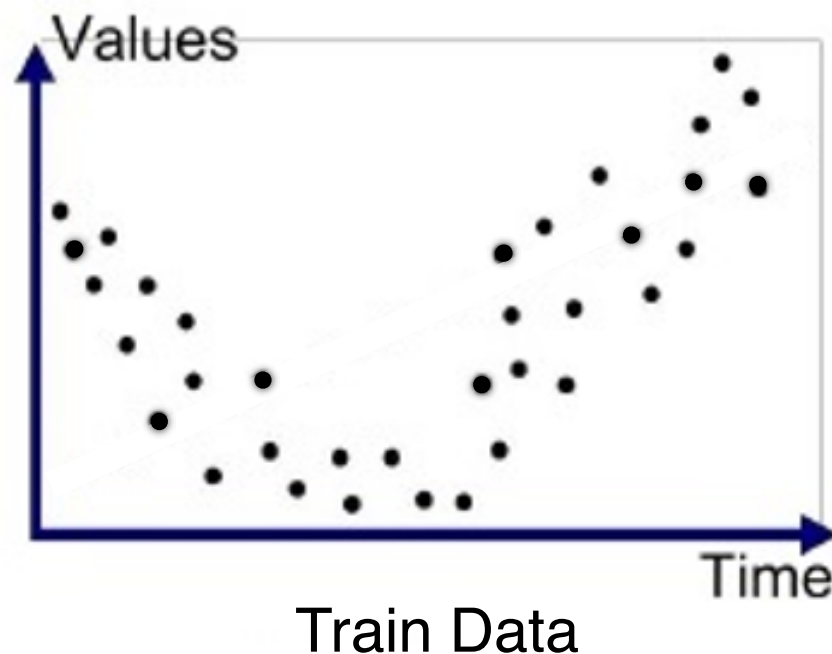
(1) https://en.wikipedia.org/wiki/Bayesian_information_criterion

Modeling

(Overfitting and Underfitting)

Overfitting occurs when the model fits the details in the training data to the extent that it negatively impacts the model on test data. This means the normal fluctuations in the training data is picked up by the model.

Overfitting may happen because the parameter of the model is not determine properly.

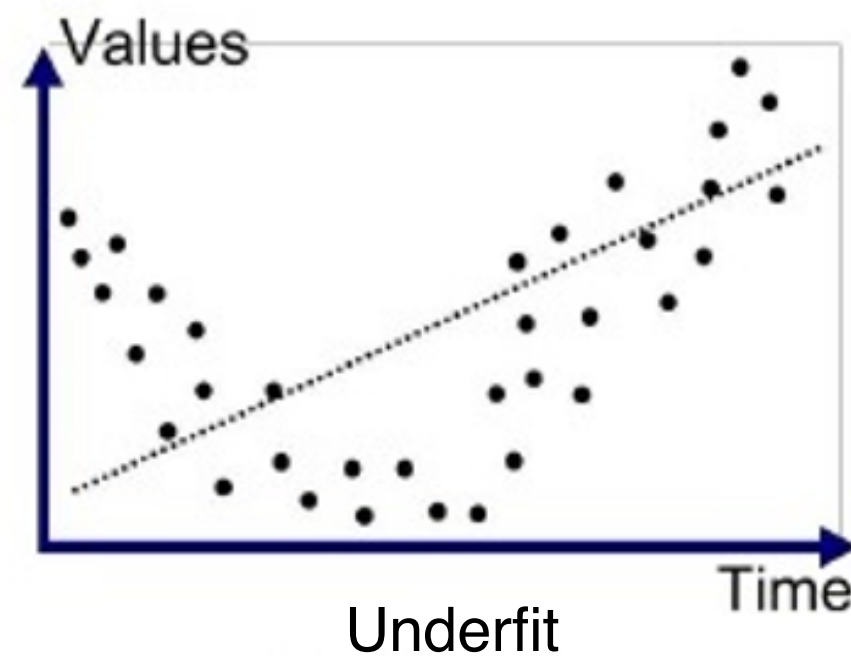
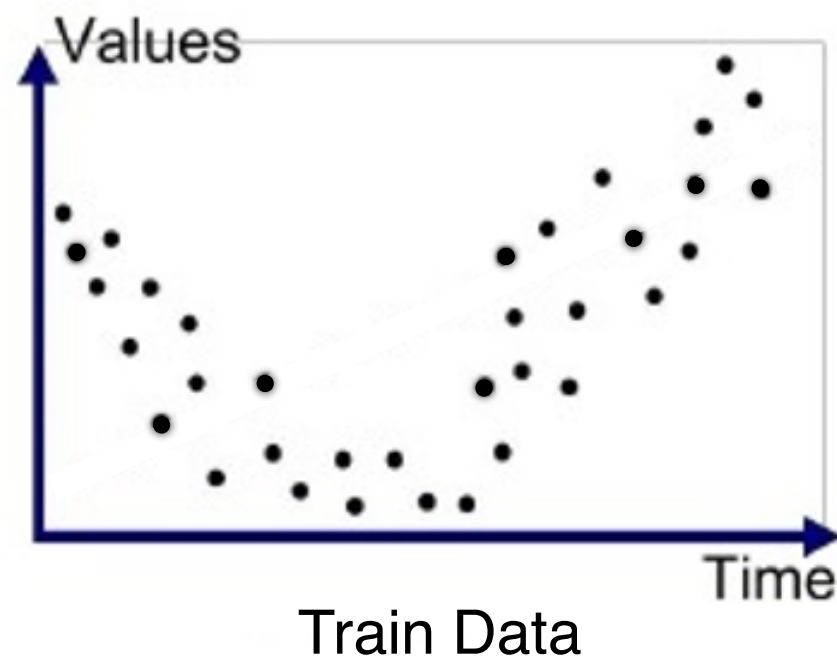


Modeling

(Overfitting and Underfitting)

Underfitting refers to a model that neither fits the training data, nor captures the underlying trend of the training data.

Underfitting may happen because, there was not enough training data, the training data was too general, or the parameter of the model is not determine properly.

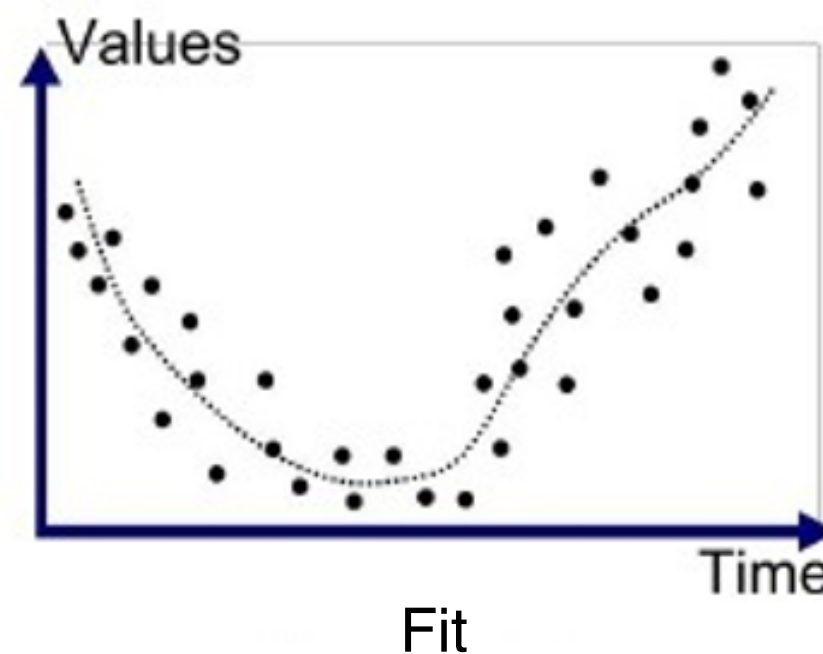
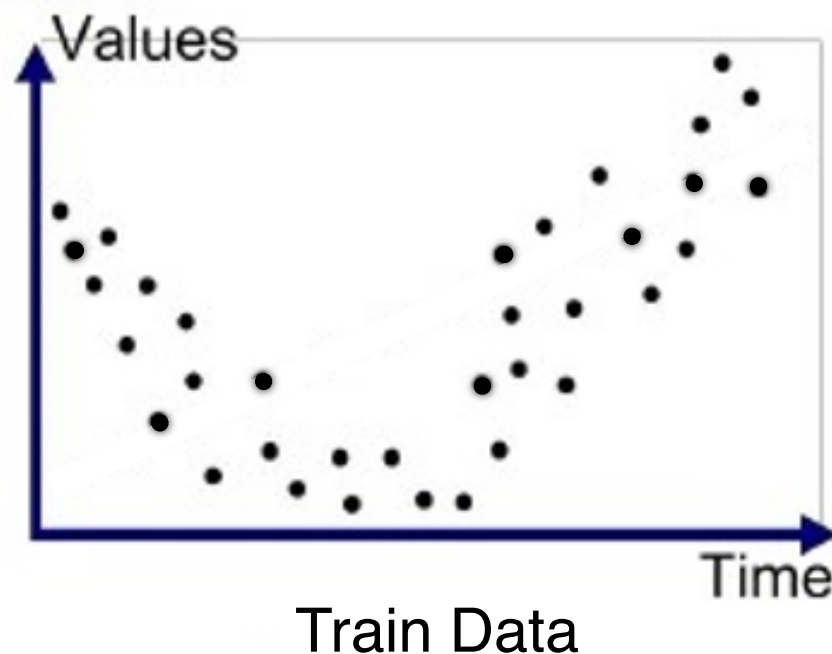


Modeling

(Overfitting and Underfitting)

Ideally, a good model is at the sweet spot between underfitting and overfitting. The goal is to capture the accurate underlying behaviour and characteristics of the train data, however, it is very difficult to do in practice.

Training Assumption: The test data has the similar underlying trend as the training data.



Modeling

(Overfitting and Underfitting)

If we want to evaluate our model based on accuracy;

- Overfit model has high accuracy on training data but low accuracy on test data.
- Underfit model has low accuracy on both train and test data.
- Fit model has high accuracy on training and also reasonably high accuracy on test data.

