Scheduler elevatorAndTheirPorts: Map<Integer, Integer> Elevator thisProjectSucks: boolean direction: String receivePacket69: DatagramPacket elevatorNum: int queueInUse: boolean requestDownButton: boolean data: byte[] noMoreRequests: boolean directionLamp: String sendPacket: DatagramPacket numOfCars: int receivePacket: DatagramPacket floorButtons: Map<Integer, Boolean> receivePacket23: DatagramPacket elevatorQueue: ArrayList<InputData> currentFloor: int sendPacket: DatagramPacket requestUpButtonLamp: boolean floorQueues: Map<Integer, ArrayList<InputData>> requestQueue: ArrayList<InputData> sendReceiveSocket: DatagramSocket numOfPeopleServiced: int requestQueue requestQueue sendAndReceiveSocket: DatagramSocket sendPacket: DatagramPacket receivePacket: DatagramPacket receiveSocket69: DatagramSocket · requestUpButton: boolean InputData «create» floorButtonsLamps: Map<Integer, Boolean> elevatorsInfo: Map<Integer, ArrayList<Integer>> · requestDownButtonLamp: boolean firstRequest: boolean carRequest: int data: byte[] numOfPeople: int + Floor(): timeOfRequest: long currentFloor: int motorMoving: Boolean + getReceivePacket(): DatagramPacket receiveSocket23: DatagramSocket floor: int doorOpen: Boolean + getRequestDownButtonLamp(): Boolean isDirectionUp: Boolean requestQueue: ArrayList<InputData> + getRequestUpButton(): Boolean Scheduler(int): + InputData(long, int, Boolean, int): · isNoMoreRequests(): boolean sendAndReceiveSocket: DatagramSocket getDirectionLamp(): String + getCarRequest(): int getReceivePacket69(): DatagramPacket elevatorQueue: ArrayList<InputData> + getRequestUpButtonLamp(): Boolean + getFloor(): int initiateFloor(): void · setQueueInUse(boolean): void Elevator(int, int, String): - getNumOfCars(): int + toString(): String + setDirectionLamp(String): void - moveElevator(): int getIsDirectionUp(): Boolean + setRequestDownButtonLamp(Boolean): void receiveElevatorRequest(): int - main(String[]): void getTimeOfRequest(): long getElevatorToSendRequest(): int + printInputData(ArrayList<InputData>): void receiveInstruction(): void · isQueueInUse(): boolean - isDirectionUp(): boolean + receiveAcknowledgement(): void getMotorMoving(): Boolean compareTo(InputData): int receiveFloorRequest(): void handleInputErrors(int, int, String): boolean getSizeOfRequestQueue(): int «create» + setRequestUpButtonLamp(Boolean): void receiveInstructionFromFloor(): void saveReceivedMessage(String): void elevatorQueue 1...n + main(String[]): void - getCurrentFloor(): int sleep(int): void · main(String[]): void + setRequestUpButton(Boolean): void setDoorOpen(Boolean): void + getRequestDownButton(): Boolean sendFloorAcknowledgement(): void getReceivePacket(): DatagramPacket translateStringInstruction(String): void + sendHasElevatorArrived(): void sendRequest(): void - sendElevatorAcknowledgement(): void + getSendPacket(): DatagramPacket getRequestQueue(): ArrayList<InputData> + setRequestDownButton(Boolean): void getReceivePacket23(): DatagramPacket closeSocket(): void - getRequestQueue(): ArrayList<InputData> + getElevatorQueue(): ArrayList<InputData> setFloorButton(Integer, Boolean): void - sendToElevators(): void + receiveStatus(): void setMotorMoving(Boolean): void + readData(String): void receiveFromElevator(): void getDoorOpen(): Boolean saveElevatorStatus(String): void + sendInstruction(InputData, Boolean): void stopElevator(): void elevatorAndTheirPortsPut(int, int): void + closeSocket(): void - setFloorButtonLamps(Integer, Boolean): void closeSockets(): void + isGoingUp(String): boolean

Floor