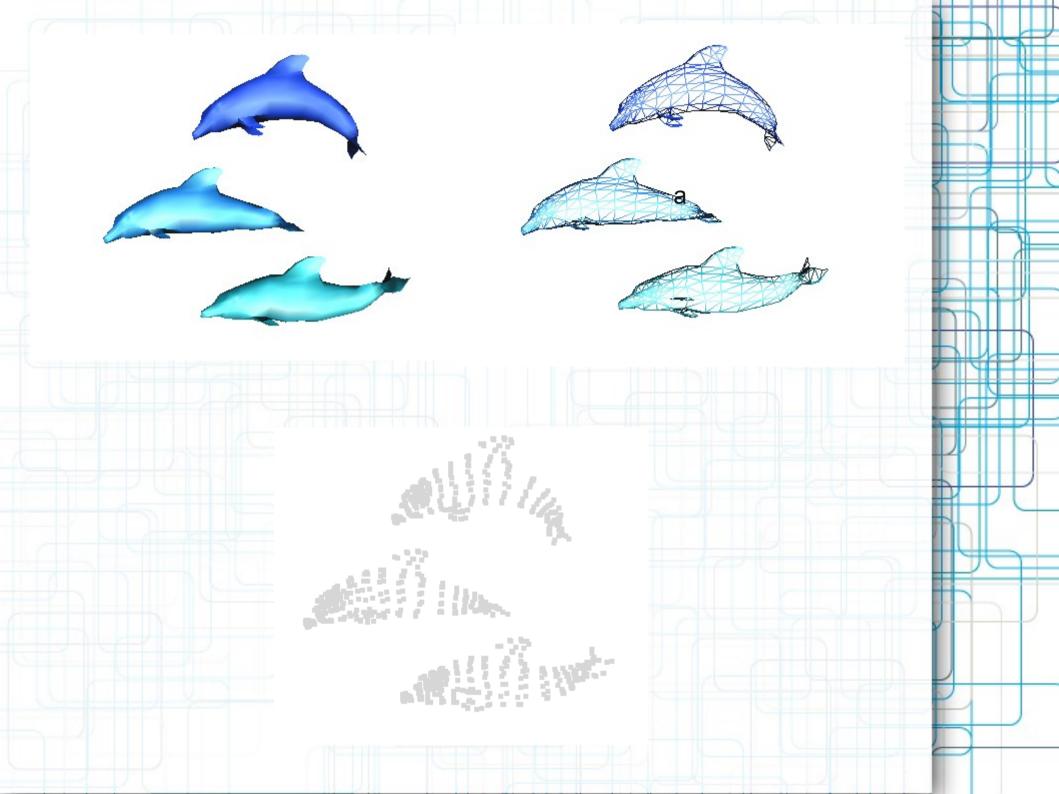


## **Objectives**

- Read in .obj file
- Display .obj file
  - Point
  - Wireframe
  - Surface
- Rotation
  - Virtual Trackball



#### **Object Structure**

- -number of vertices
- -vertices
- -number of normals
- -normals
- -number of triangles
- -triangles

#### **Parser**

- char buf[128]
- while(fscanf(file, "%s", buf) != EOF)
- fgets(buf, sizeof(buf), file)
- fscanf(file, "%f %f %f", ...)

```
v -1.000000 -1.000000 1.000000
v -1.000000 1.000000 1.000000
v 1.000000 1.000000 1.000000
v 1.000000 -1.000000 1.000000
v -1.000000 -1.000000 -1.000000
v -1.000000 1.000000 -1.000000
v 1.000000 1.000000 -1.000000
v 1.000000 -1.000000 -1.000000
```

### .obj Structure

- -number of vertices
- -vertices
- -number of normals
- -normals
- -number of triangles
- -triangles

#### Vertices - .obj file

```
v - 1.000000 - 1.000000 1.000000
```

```
v -1.000000 1.000000 1.000000
```

v 1.000000 1.000000 1.000000

v 1.000000 -1.000000 1.000000

v - 1.000000 - 1.000000 - 1.000000

v - 1.000000 1.000000 - 1.000000

v 1.000000 1.000000 -1.000000

v 1.000000 -1.000000 -1.000000

#### **Vertices - Parser**

v = -1.000000 = -1.000000 = 1.000000

```
numVertices = 0;
fscanf(file, "%f %f %f",
    &vertices[3 * numVertices + 0],
    &vertices[3 * numVertices + 1],
    &vertices[3 * numVertices + 2]);
numVertices++;
```

## .obj Structure

- -number of vertices
- -vertices
- -number of normals
- -normals
- -number of triangles
- -triangles

#### Normals - .obj File

vn 0.577350 0.577350 -0.577350 vn 0.577350 -0.577350 -0.577350 vn -0.577350 -0.577350 -0.577350  $vn = -0.577350 \ 0.577350 \ -0.577350$ vn 0.577350 0.577350 0.577350 vn 0.577350 -0.577350 0.577350 vn -0.577350 -0.577350 0.577350 vn -0.577350 0.577350 0.577350

Repeat vertex parsing process

## .obj Structure

- -number of vertices
- -vertices
- -number of normals
- -normals
- -number of triangles
- -triangles

## Triangles - .obj File

```
f 1 2 3

f 3 4 1

f 6 5 7

f 5 8 7

(Or)

f 4//4 3//3 2//2 1//1
```

#### **Triangle - Parser**

- F 1//1 2//2 3//3
- numTriangle = 1

```
T(numTriangles).vindices[0] = v;
T(numTriangles).nindices[0] = n;
```

```
T(numTriangles).vindices[1] = v;
T(numTriangles).nindices[1] = n;
```

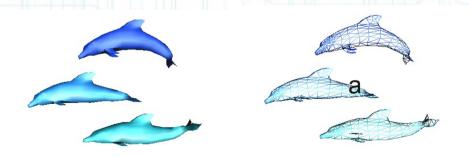
```
T(numTriangles).vindices[2] = v;
T(numTriangles).nindices[2] = n;
```

#### Display .obj File

- Traverse each triangle
  - Get 3 vertex indices
  - Draw 3 vertices of triangle
    - Access three indices in vertex list
  - If applicable:
    - Same for vertex normals

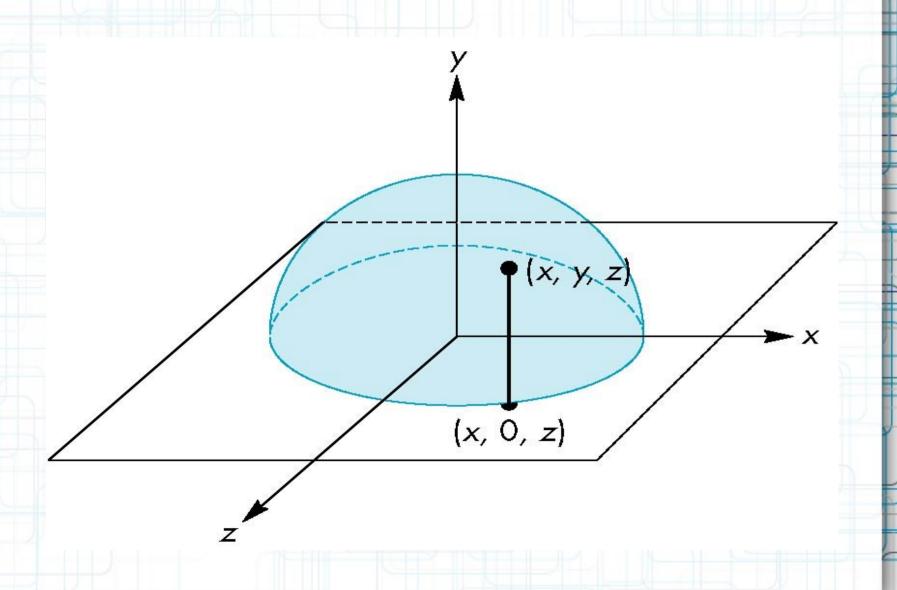
# Display .obj File

- Representation:
  - Point: glBegin(GL POINTS)
  - Wireframe: glBegin(GL\_LINE\_STRIP)
  - Surface: glBegin(GL TRIANGLES)

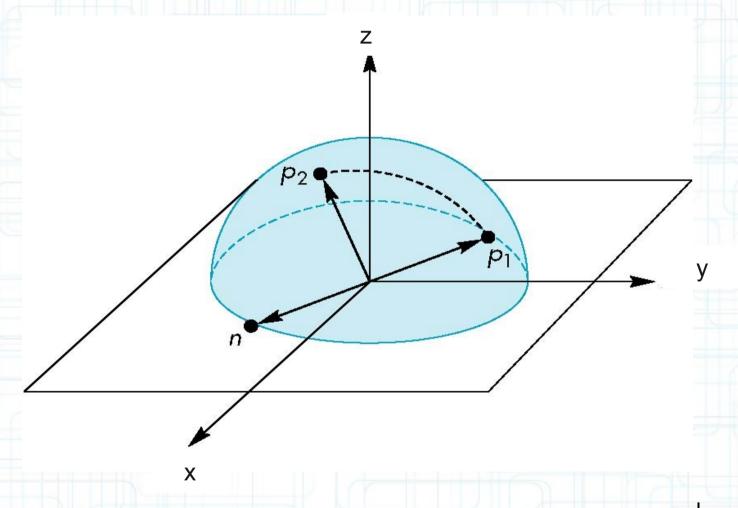




# Projection



#### **Plane of Rotation**



$$|\sin \theta| = \frac{|\mathbf{n}|}{|\mathbf{p}_1||\mathbf{p}_2|}$$