Michaël Ramamonjisoa

PHD STUDENT IN COMPUTER VISION AND DEEP LEARNING

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Education

Ecole Normale Supérieure Paris-Saclay

Paris area, France

MASTER'S DEGREE - MATHÉMATIQUES VISION APPRENTISSAGE (MVA)

2017 - 2018

- 3D Computer Vision (R. Marlet, P. Monasse, M. Aubry); Audio signal Analysis, Indexing and Transformations (R. Badeau, G. Richard); Introduction to Digital Imaging (J. Delon, Y. Gousseau); Object Recognition and Computer Vision (I. Laptev, J. Ponce, C. Schmid, J. Sivic); Speech and Language Processing (E. Dupoux, B. Sagot, N. Zeghidour);
- High Dimension Statistical Learning (S. Mallat); Convex Optimization (A. D'Aspremont); Deep Learning (V. Lepetit); Kernel Methods for machine learning (J. Mairal, J-P. Vert); Probabilistic Graphical Models (F. Bach, G. Obozinski); Unsupervised Learning (R. Vidal)

Unsupervised Learning: Low Rank Matrix Completion, Face Clustering (Matlab)

Projects: Object Recognition and Computer Vision: Training CNNs using synthetic images of people (Torch, Python, Blender)

Introduction to Digital Imaging: Texture Synthesis using CNNs (Caffe, Python)

Imperial College London

London, United Kingdom

2013 - 2014

MSc Optics and Photonics

Double degree in engineering with IOGS
Optics, Photonics, Information theory, Biophotonics

Institut d'Optique Graduate School Paristech (IOGS)

Paris area, France

GRANDE ECOLE - 3RD YEAR ABROAD

2011 - 2014

- · Engineering Diploma
- · Optics, Signal and image processing, Electronics, Physics

Professional experience

IMAGINE team- Ecole des Ponts/LIGM

Paris area, France

PHD STUDENT Oct. 2018 – present

Disentangling for Scene Understanding from Images – Supervisor: Prof. Vincent Lepetit

• 3D Geometry Estimation, Scene Understanding, 3D Pose Estimation

Prophesee (formerly Chronocam)

Paris, France

INTERN Apr. – Sept. 2018

Double Frequency Tracking Using Event-Based Cameras

HGH Systèmes Infrarouges

Paris area, France

PROJECT ENGINEER

Jan. 2015 – Sept. 2017

· Manager of the infrared testing software (Infratest) of HGH: designed signal and image processing algorithms for optronics systems

Thalès Research & Technology

Paris area, France

INTERN June – Nov. 2014

Optical Design of a Lidar; signal processing for imaging on Matlab

ONERA (The French Aerospace Lab)

Paris area, France

INTERN May – July 2013

Designed a 3D-model of an urban area using Cinema 4D, then tested ONERA's Radar imaging algorithms on the 3D model

Publications

- M. Ramamonjisoa, V. Lepetit, **SharpNet: Fast and Accurate Recovery of Occluding Contours in Monocular Depth Estimation**, *The IEEE International Conference on Computer Vision (ICCV) Workshops*, 2019
- G. Pitteri[†], M. Ramamonjisoa[†], V. Lepetit, On Object Symmetries and 6D Pose Estimation from Images, 2019 International Conference on 3D Vision (3DV), 2019
 † denotes equal contribution
- C. Barrat, T. Lepot, M. Ramamonjisoa, S. Fradcourt, Extension to NIR and visible ranges of high-resolution relative spectral response measurement using Fourier Transform Infrared Spectrometer (FTIR) of CMOS FPAs, *Proc. SPIE 10433*, Electro-Optical and Infrared Systems: Technology and Applications XIV, 1043316 (6 October 2017); doi: 10.1117/12.2278301
- C. Barrat, T. Lepot, M. Ramamonjisoa, S. Fradcourt, **A practical implementation of high resolution relative spectral response measurement of CMOS IRFPAs using Fourier Transform Infrared Spectrometer (FTIR)**, *Proc. SPIE 9987*, Electro-Optical and Infrared Systems: Technology and Applications XIII, 99870V (21 October 2016); doi: 10.1117/12.2242014

Teaching

- Numerical Methods, 1st year of Master practical sessions, Institut d'Optique Graduate School
- Artificial Intelligence, 1st year of Master practical sessions, Université de Bordeaux
- Deep Learning, 1st year of Master practical sessions, Bordeaux INP

Relevant skills

- Computer skills: Python, C++, Matlab, Pytorch, Keras, Tensorflow, Unix shell, Cinema 4D, Blender, SolidWorks, LaTeX
- Languages: French (native); English (fluent, TOEFL 108/120); Spanish (conversational); Malagasy (basic skills); Mandarin (basic skills)