

A decorative graphic on the left side of the slide consisting of two overlapping parallelograms. The front one is blue and the back one is a light green. They are positioned diagonally, with the blue one partially covering the green one.

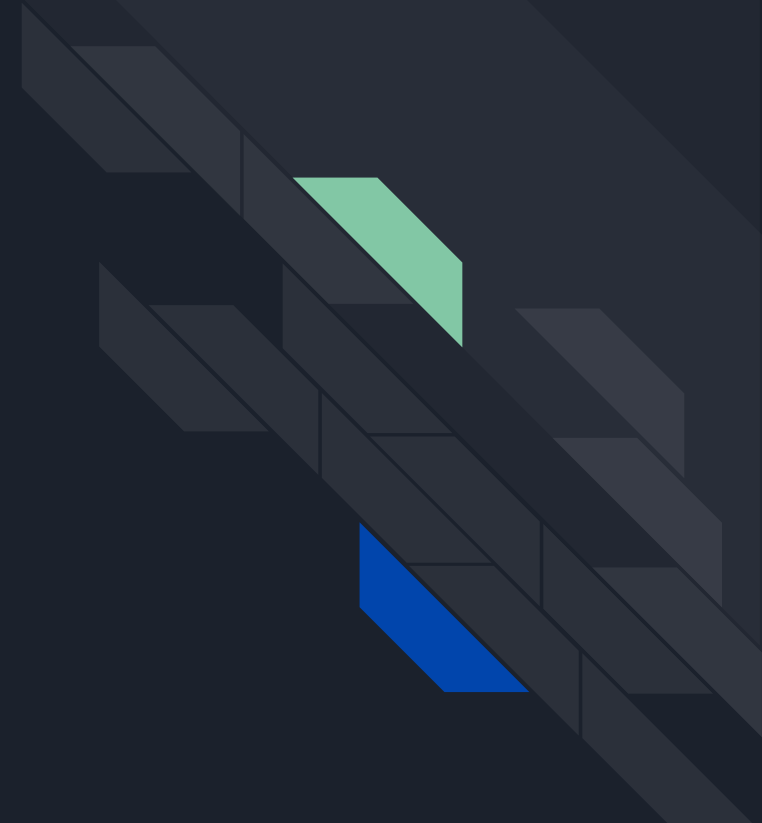
Modeling the Human Skeleton

An exercise in Hierarchical Modeling

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Introduction





Goals:

- Explore 3D Processing concepts in regards to modeling a human skeleton.
- Concepts such as:
 - 3D Shapes, textures, lighting, perspective
 - Hierarchical modeling, scene graphs, parent and child nodes
 - Kinematic modeling
 - Motion data
- To develop a final project implementing these concepts to create a human skeleton.

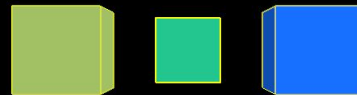
Concepts





Drawing in 3D

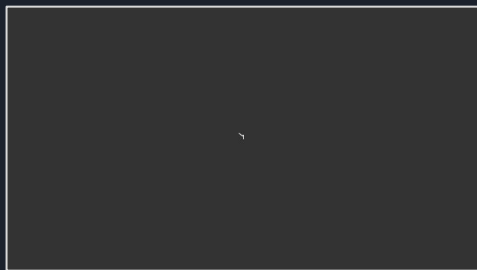
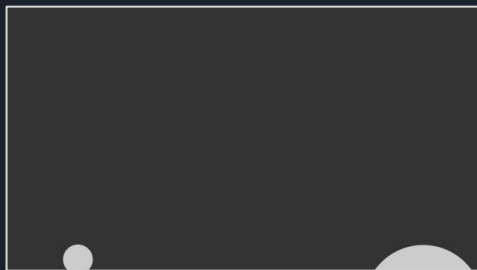
- Moving from programming in 2D to 3D
- Drawing in 3D space
- Translating in 3D space
- Rotating in 3D space
- Ray casting



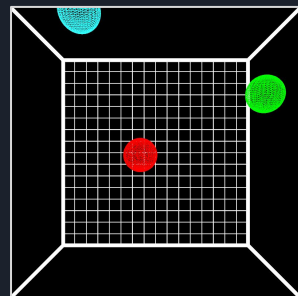
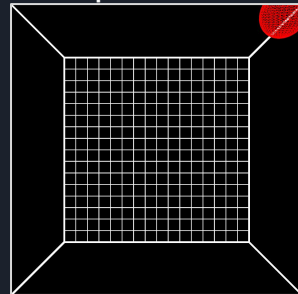
Motion Examples

- Recreating 2D examples from Processing.org in 3D
- Focus on animating an objects and how they interact
- Bounce
- Collision
- Brownian

2D Example



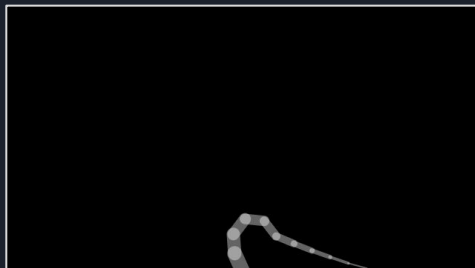
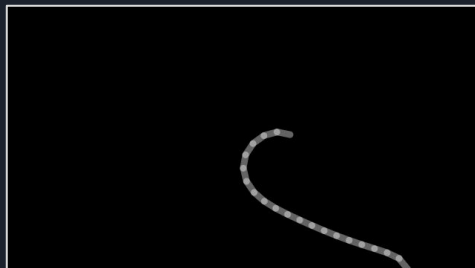
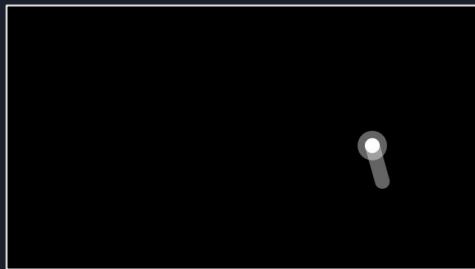
3D Implementation



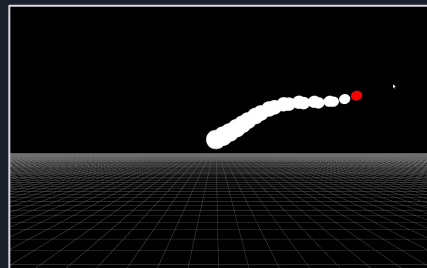
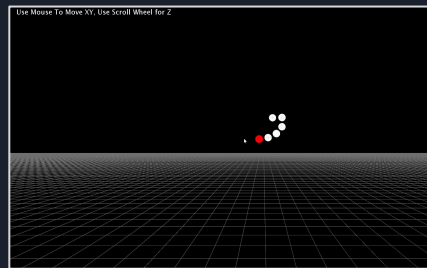
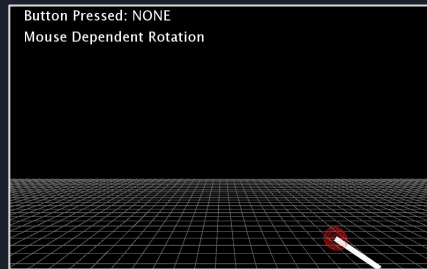
Interaction Examples

- Recreating 2D examples from Processing.org in 3D
- Focus on how the user can interact with the objects
- Follow1
- Follow3
- Reach2

2D Example

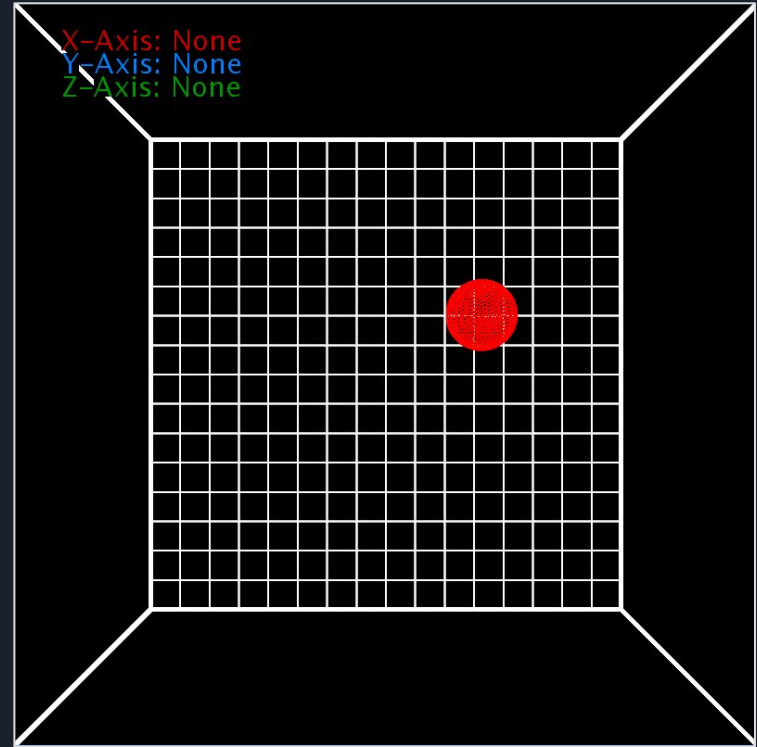


3D Implementation



External Forces

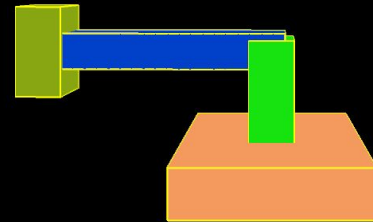
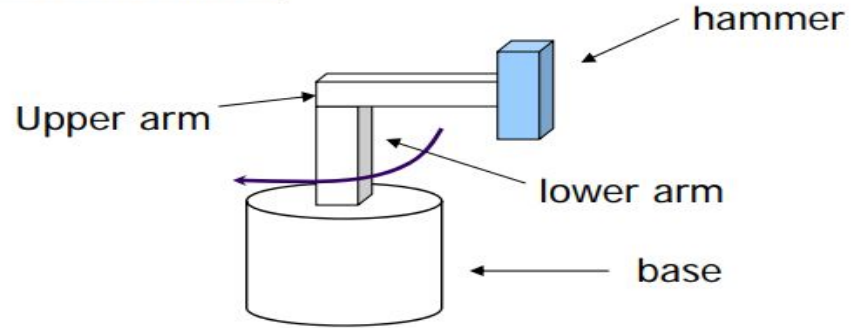
- How do objects react when external forces are applied
- Apply an external force on one or more axis
- Ex. changing the direction of gravity acting on a ball



Hierarchical Modeling

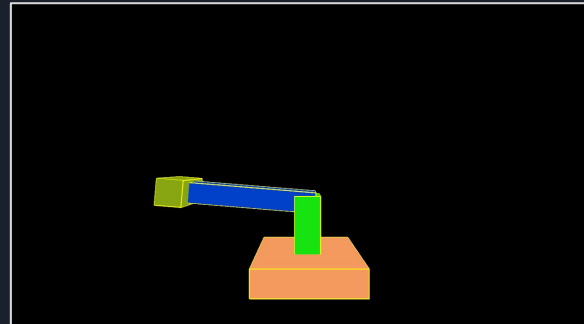
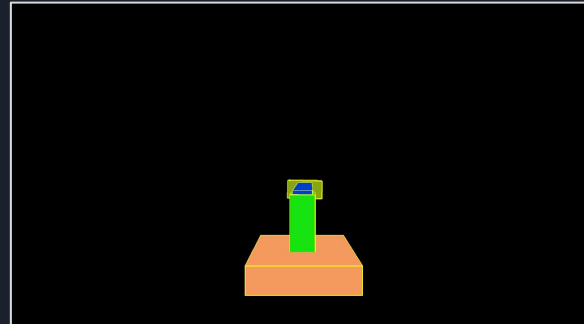
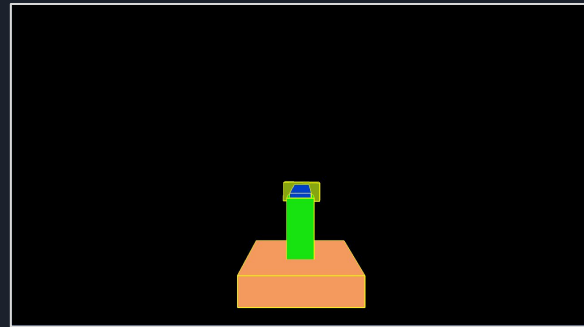
- Scene graphs
- Matrix stack
- PushMatrix()
- PopMatrix()
- Absolute and Relative transformations
- Child shapes/nodes dependent on movement with parent nodes

A ROBOT HAMMER!



Joints and Constraints

- Translation constraints limit range of movement
- Joint constraints limit the angles of the joints
- Hinge Joints seen here
- Ball and Socket Joints seen later

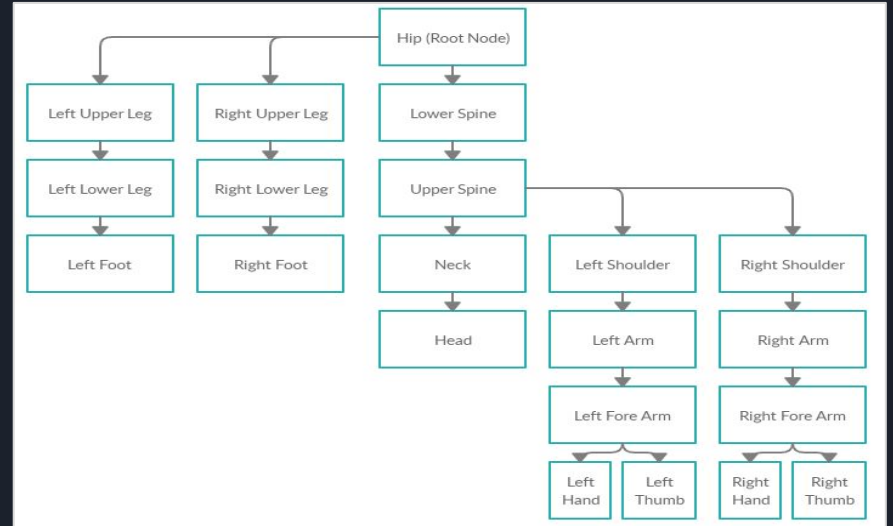
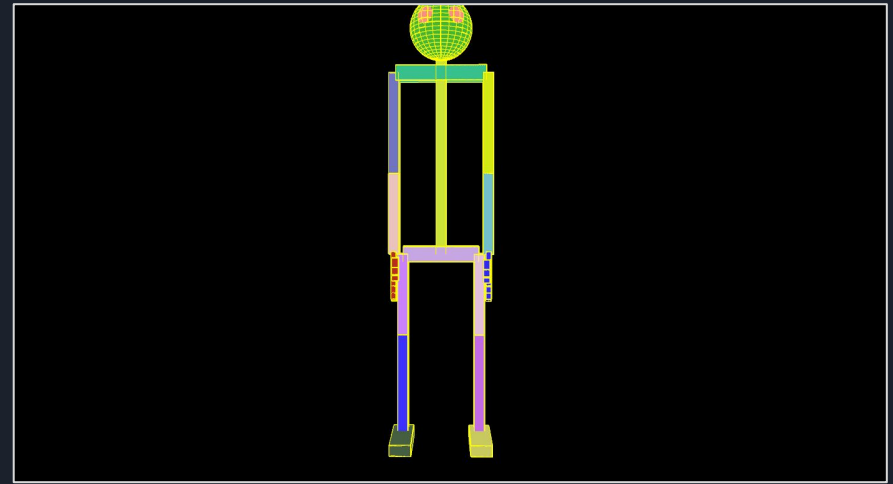


Human Modeling



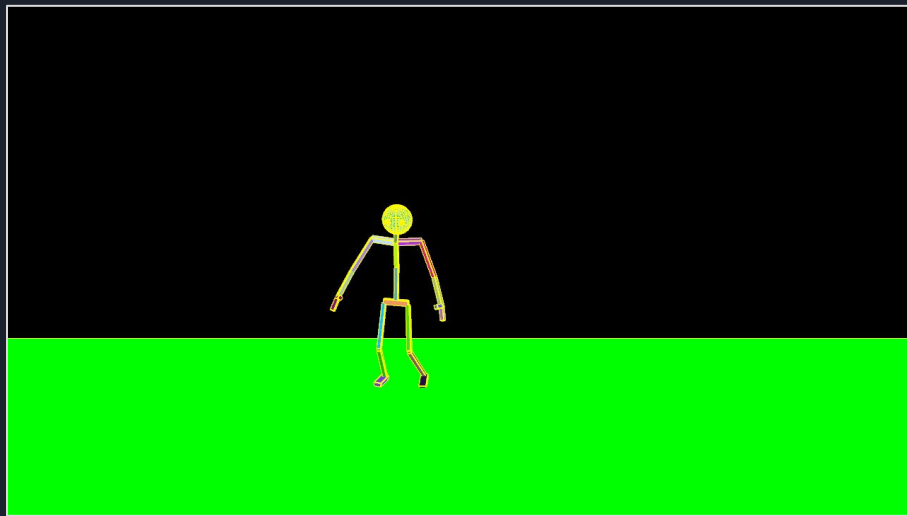
Modeling a Human Skeleton

- Applied all concepts talked about previously
- Raycasting allows the user to select the bone to move
- Motion and Interaction concepts allow for manipulation
- Child nodes(hands) dependent on parents(arms)
- Hinge, Ball and Socket and similar joints



Applying Motion Capture Data

- Parsing Biovision Hierarchy (BVH) files
- Contains information on how to translate/rotate each joint
- Apply the parsed data to a compatible skeleton
- Data obtained from the NUS Motion Capture Database



Tools and Libraries



Processing Java

A flexible software sketchbook



shapes3D

A library to aid modeling in 3D



Information Technology

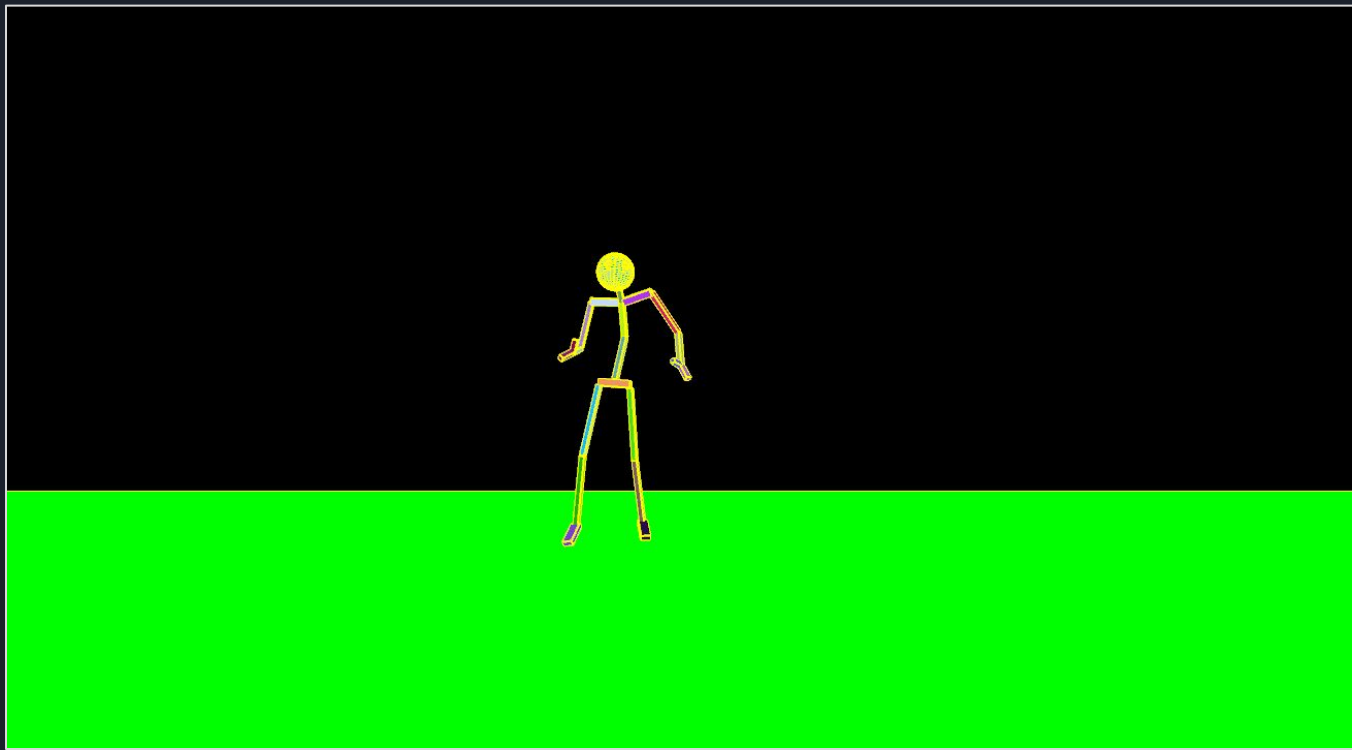
NUS Motion Capture Database

A database of .bvh mocap files

Conclusion



Final Product





References

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