

Causal Inference with Continuous Multiple Time Point Interventions

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Motivation – Continuous Interventions

Data:

- ▶ CHAPAS-3 trial (📖 Mulenga et al., *Lancet Infectious Diseases*, 2016): children, ≤ 13 years, from Zambia/Uganda, randomized NRTI drug (abacavir, stavudine oder zidovudine) of HIV therapy

Pharmacological Substudy:

- ▶ 📖 Bienczak et al. (*AIDS*, 2017) evaluated concentration of NNRTI drug regimen component: Nevirapine and Efavirenz
→ higher probability of “viral failures” with lower concentrations
- ▶ what is the ideal target concentration?; causal question:

How many percent of children would have had a suppressed viral load at time t if they had had a concentration of “ x ” mg/L efavirenz at each time point?

In general: how would probability of failure vary for different hypothetical concentration trajectories? → **“causal dose-response curve” (CDRC)**

Motivation – Continuous Interventions (II)

We essentially have longitudinal observational data:

- ▶ Time-varying confounders: weight, adherence (with treatment-confounder feedback!)
- ▶ Note: *Positivity assumption may not be satisfied with continuous interventions!*
- ▶ Possible options to answer motivating question:
 - Option 1: Change question: “modified treatment policies” (e.g., Diaz et al., *JASA*, 2021)
 - Option 2: G-methods → simple application (i.e., intervene for many trajectories) **today**
 - Option 3: Find a compromise between interpretability and identifiability **today**
 - Also: for 1 time point, great DR approach developed (Kennedy, *JRSS B*, 2017)

Notation

- ▶ Follow-up time: $t = 0, 1, \dots, T$
- ▶ Outcome: Y_t
- ▶ Intervention: A_t
- ▶ Confounder, Covariate: L_t
- ▶ History: e.g. $\bar{A}_t = (A_0, \dots, A_t)$
- ▶ History up to A_t : H_t
- ▶ **Counterfactual:** e.g. $Y_t^{\bar{a}_t}$

Estimand & Estimation with Sequential G-computation

Estimand:

$$m_t : \bar{a}_t \mapsto E(Y_t^{\bar{a}_t} | \mathbf{L}_0^*), \quad t = 0, 1, \dots, T$$

Under sequential conditional exchangeability, consistency and **positivity** we have:

$$\mathbb{E}(Y_t^{\bar{a}_t}) = \mathbb{E}(\dots \mathbb{E}(\mathbb{E}(Y_t | \bar{A}_t = \bar{a}_t, \mathbf{H}_t) | \bar{A}_{t-1} = \bar{a}_{t-1}, \mathbf{H}_{t-1}) \dots | A_0 = a_0, \mathbf{L}_0)).$$

→ substitution estimation (sequential g-computation)

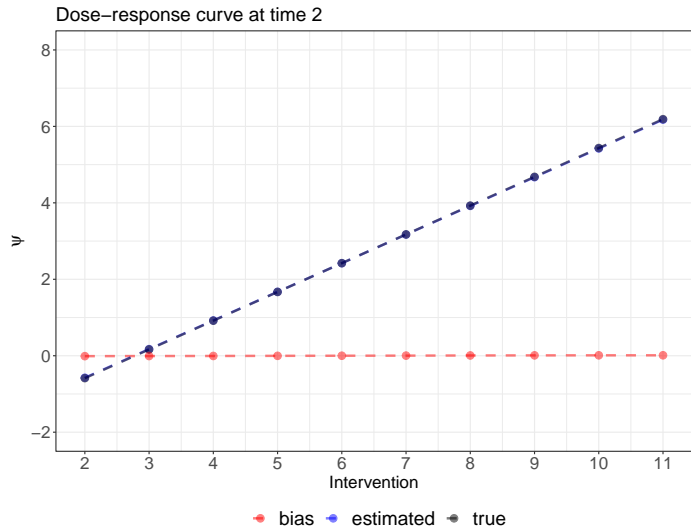
Positivity:

$$\inf_{a_t \in \bar{\mathcal{A}}_t} g(a_t | \mathbf{h}_t) > 0 \quad \text{whenever} \quad p_0(\bar{\mathbf{L}}_t = \bar{\mathbf{l}}_t, \bar{A}_{t-1} = \bar{a}_{t-1}) > 0 \quad \forall t, \bar{a}_t, \bar{\mathbf{l}}_t.$$

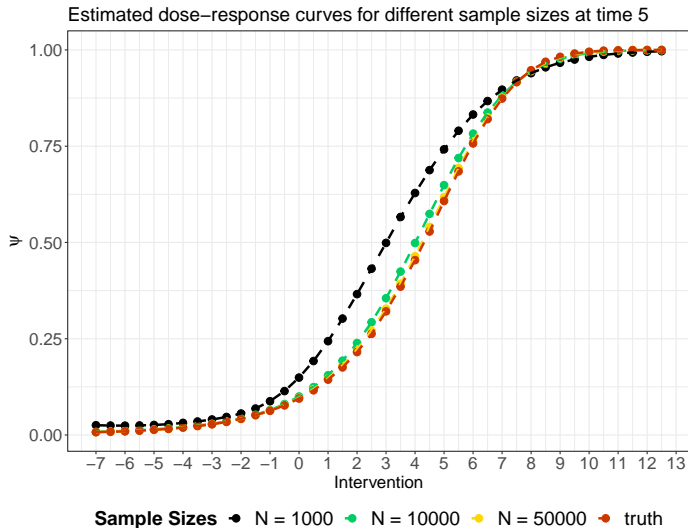
where $\bar{\mathcal{A}}_t$ denotes the set of all relevant strategies $\bar{a}_t = (a_0, \dots, a_t)$

→ What if we simply assume positivity and apply g-computation for many \bar{a}_t ?

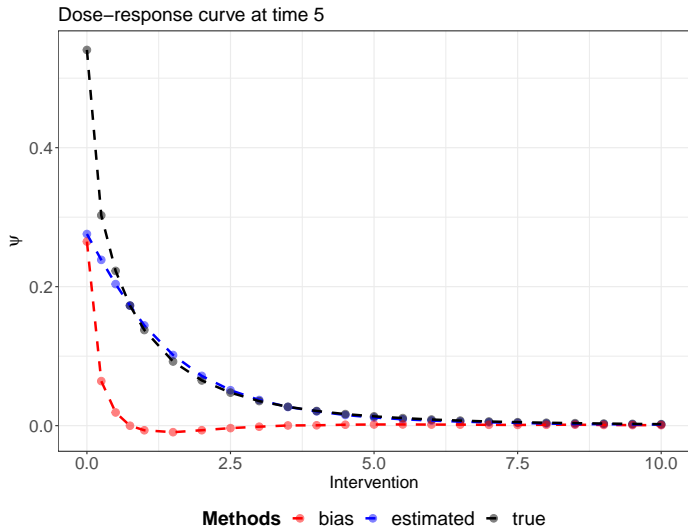
Simulation (simple)



Simulation (survival)



Simulation (complex, as in data)



Overall Consideration

The **tradeoff** to make is between

*estimating the CDRC as closely as possible, at the risk of bias due to positivity violations
because of the continuous intervention*

and

*minimizing the risk of bias due to positivity violations, at the cost of redefining the
estimand (e.g. by using modified treatment policies)*

Alternatively: compromise!

Proposal: Weighted Estimand (1 Time Point)

The general dose-response curve $m : a \mapsto E(Y^a)$ can be identified¹ with the g-formula as

$$m(a) = \int E(Y \mid A = a, \mathbf{L} = \mathbf{l}) p_0(\mathbf{l}) d\nu(\mathbf{l}),$$

Proposal: instead, rather use

$$m_w(a) = \int E(Y \mid A = a, \mathbf{L} = \mathbf{l}) w(a, \mathbf{l}) p_0(\mathbf{l}) d\nu(\mathbf{l})$$

with

$$w(a, \mathbf{l}) = \begin{cases} 1 & \text{if } g(a \mid \mathbf{l}) > c \\ \frac{g(a \mid \mathbf{l})}{g(a)} & \text{otherwise.} \end{cases}$$

¹under consistency, positivity and conditional exchangeability

Weighted Estimand – Implications

- ▶ yields the desired dose-response curve under enough support (i.e., $g(a | \mathbf{I}) > c$)
- ▶ otherwise the estimand is $E(Y|A = a)$
 - not a causal quantity but does not require positivity assumption

Weighted Estimand – Multiple Time Points

$$w_t(a_{t+1}, \mathbf{h}_{t+1}, c) = \begin{cases} 1 & \text{if } g_t(a_{t+1} \mid \mathbf{h}_{t+1}) > c, \\ \frac{g_t(a_{t+1} \mid \mathbf{h}_{t+1})}{g_t(a_{t+1} \mid a_t, \mathbf{h}_t)} & \text{if } g_t(a_{t+1} \mid \mathbf{h}_{t+1}) \leq c \text{ and } g_t(a_{t+1} \mid a_t, \mathbf{h}_t) > c, \\ \frac{g_t(a_{t+1} \mid \mathbf{h}_{t+1})}{g_t(a_{t+1} \mid a_{t-1}, \mathbf{h}_{t-1})} & \text{if } g_t(a_{t+1} \mid \mathbf{h}_{t+1}) \leq c \text{ and } g_t(a_{t+1} \mid a_t, \mathbf{h}_t) \leq c \\ & \text{and } g_t(a_{t+1} \mid a_{t-1}, \mathbf{h}_{t-1}) > c, \\ \vdots & \vdots \\ \frac{g_t(a_{t+1} \mid \mathbf{h}_{t+1})}{g_t(a_{t+1})} & \text{otherwise .} \end{cases}$$

Weighted Estimand – Implications

- ▶ returns the CDRC if there is enough conditional support in terms of $g_t(a_t | \mathbf{h}_t) > c$
- ▶ if there is not enough conditional support (and the weight denominator is $> c$)
we can show that the estimand equates to $E(Y_t | A_t = a_t, \dots, A_0 = a_0)$
→ not a causal quantity but does not require positivity assumption
- ▶ if there is not enough conditional support and the weight denominator is too small the estimand entails a compromise

Weighted Estimand – Estimation (I)

For example, substitution estimator based on the following expression:

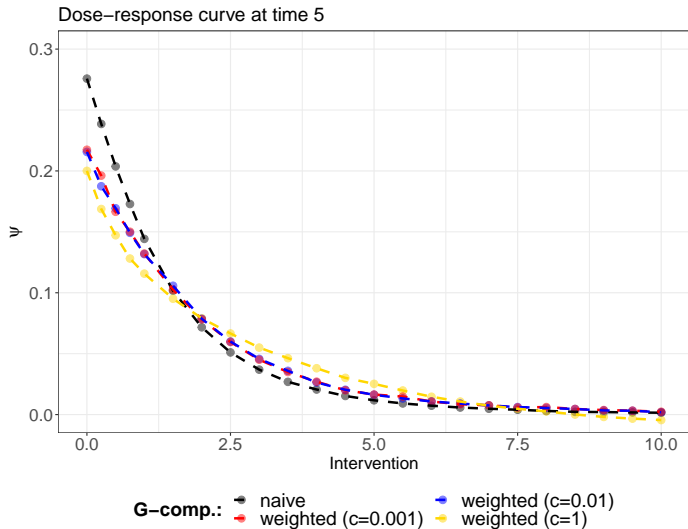
$$\mathbb{E}_{w_0}(\dots \mathbb{E}_{w_{t-1}}(\mathbb{E}_{w_t}(Y_t|\bar{A}_t = \bar{a}_t, \mathbf{H}_t)|\bar{A}_{t-1} = \bar{a}_{t-1}, \mathbf{H}_{t-1}) \dots |A_0 = a_0, \mathbf{L}_0)),$$

where we define $\mathbb{E}_{w_t}(Y_t|\bar{A}_t = \bar{a}_t, \mathbf{H}_t) = \mathbb{E}(w_t Y_t|\bar{A}_t = \bar{a}_t, \mathbf{H}_t)$.

→ can also re-expressed into parametric g-formula-type expression, but then requires estimation of conditional *densities*, not only expectations

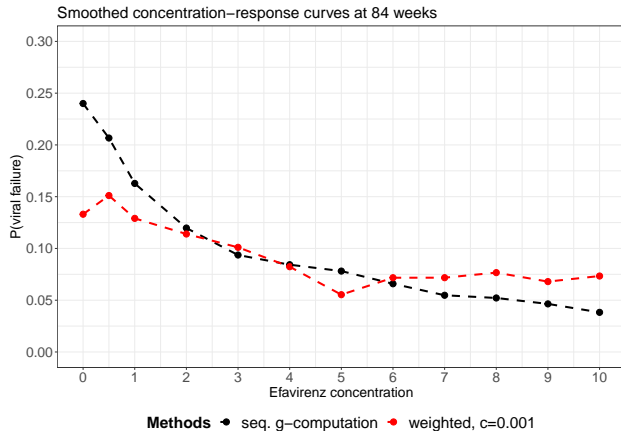
Note: even if Y_t is normal, $w_t Y_t$ may not be normal; so we may need a data-adaptive approach

Simulation (complex, as in data)



Data Analysis

Based on a complete case analysis of $n = 58$ kids



Weighted curve deviates from estimated CDRC in areas of low support

Interpretation

The weighted curve shows the probability of failure

- ▶ if patients whose covariate trajectory that makes the intervention value of interest at t not unlikely to occur (under the desired intervention before t), receive the intervention at t
- ▶ all other patients get different interventions that produce, on average, outcomes as we would expect among those who actually follow the trajectory of interest.

The weighted curve acts like a magnifying glass and sensitivity tool if we don't want to rely on parametric extrapolation in regions of low support, where fixing the concentration to a specific level seems unrealistic.

Summary

- ▶ Standard g-computation can be used for continuous interventions
 - ▶ + targets the CDRC of interest
 - ▶ - relies on positivity assumption
- ▶ Simulations show that strategy may work, but can be problematic in regions of low support or with limited sample size
- ▶ Weighted curves offer a compromise and do not require the positivity assumption
- ▶ The toolkit for causal effect estimation with longitudinal continuous interventions should ideally be broad

Literature

- [1] Andrzej Bienczak, Paolo Denti, Adrian Cook, Lubbe Wiesner, Veronica Mulenga, Cissy Kityo, Addy Kekitiinwa, Diana M. Gibb, David Burger, Ann S. Walker, and Helen McIlleron.
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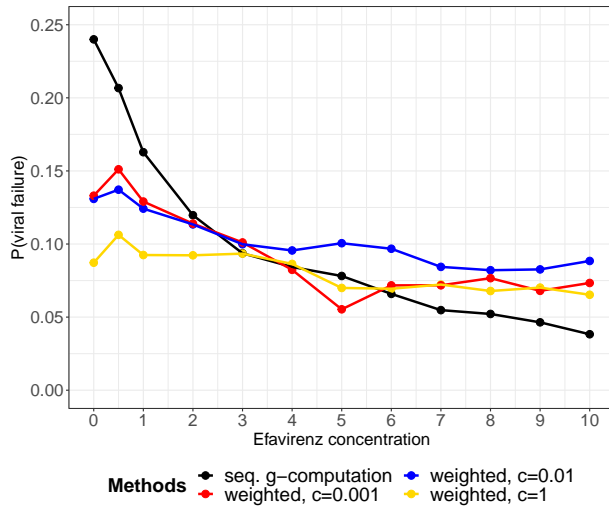
- [2] Iván Díaz, Nicholas Williams, Katherine L. Hoffman, and Edward J. Schenck.
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- [3] Edward H. Kennedy, Zongming Ma, Matthew McHugh, and Dylan S. Small.
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- [4] Veronica Mulenga, Victor Musiime, Adeodata Kekitiinwa, Adrian D. Cook, George Abongomera, Julia Kenny, Chisala Chabala, Grace Mirembe, Alice Asimwe, Ellen Owen-Powell, David Burger, Helen McIlleron, Nigel Klein, Chifumbe Chintu, Margaret J. Thomason, Cissy Kityo, A. Sarah Walker, and Diana Gibb.
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APPENDIX

Concentration–response curves at 84 weeks



Treatment-Confounder Feedback

