

Linear Maps

2024 年 1 月 9 日

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1 The Vector Space of Linear Maps

1.1 Definition linear map

A **linear map** from V to W is a function $T:V \Rightarrow W$ with the following properties:

- **additivity**: $T(u + v) = Tu + Tv$ for all $u, v \in V$;
- **homogeneity**: $T(\lambda v) = \lambda(Tv)$ for all $\lambda \in F$ and all $v \in V$;

1.2 Example linear maps

from R^3 to R^2
define $T \in L(R^3, R^2)$ by

$$T(x, y, z) = (2x - y + 3z, 7x + 5y - 6z)$$

from F^n to F^m

generalizing the previous example, let m and n be positive integers, let $A_{i,k} \in F$ for $j = 1, \dots, m$ and $k = 1, \dots, n$ and define $T \in l(F^n, F^m)$ by $T(x_1, \dots, x_n) = (A_{1,1}x_1 + \dots + A_{1,n}x_n, \dots, A_{m,1}x_1 + \dots + A_{m,n}x_n)$ actually every linear map from F^n to F^m is of this form.

1.3 linear maps and basis of domain

Suppose v_1, \dots, v_n is a basis of the V and $w_1, \dots, w_n \in W$. then there exists a unique linear map $T : V \rightarrow W$ such that

$$Tv_j = w_j$$

for each $j = 1, \dots, n$.