

Chapter 06

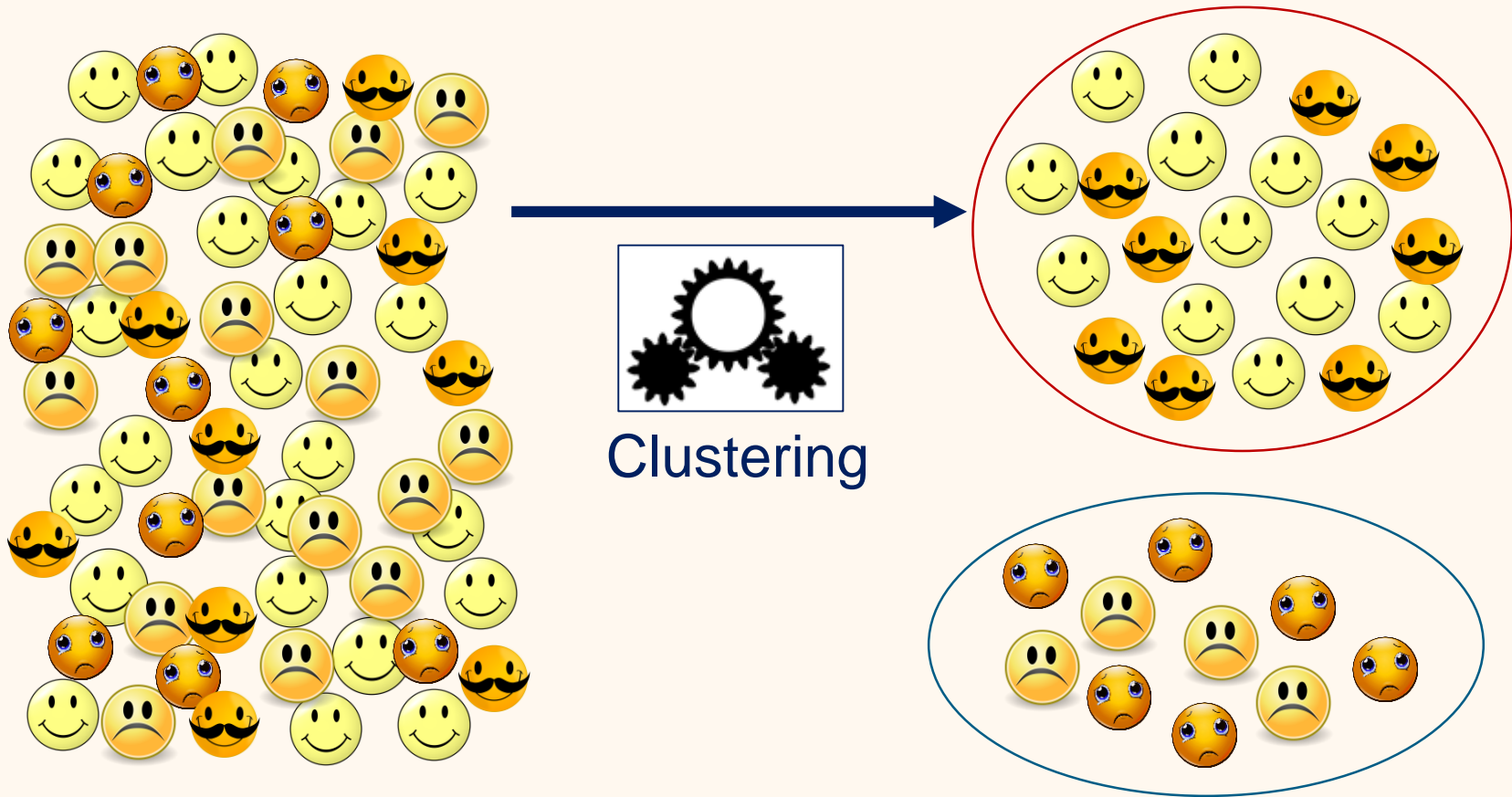
Clustering

Dr. Steffen Herbold
herbold@cs.uni-goettingen.de

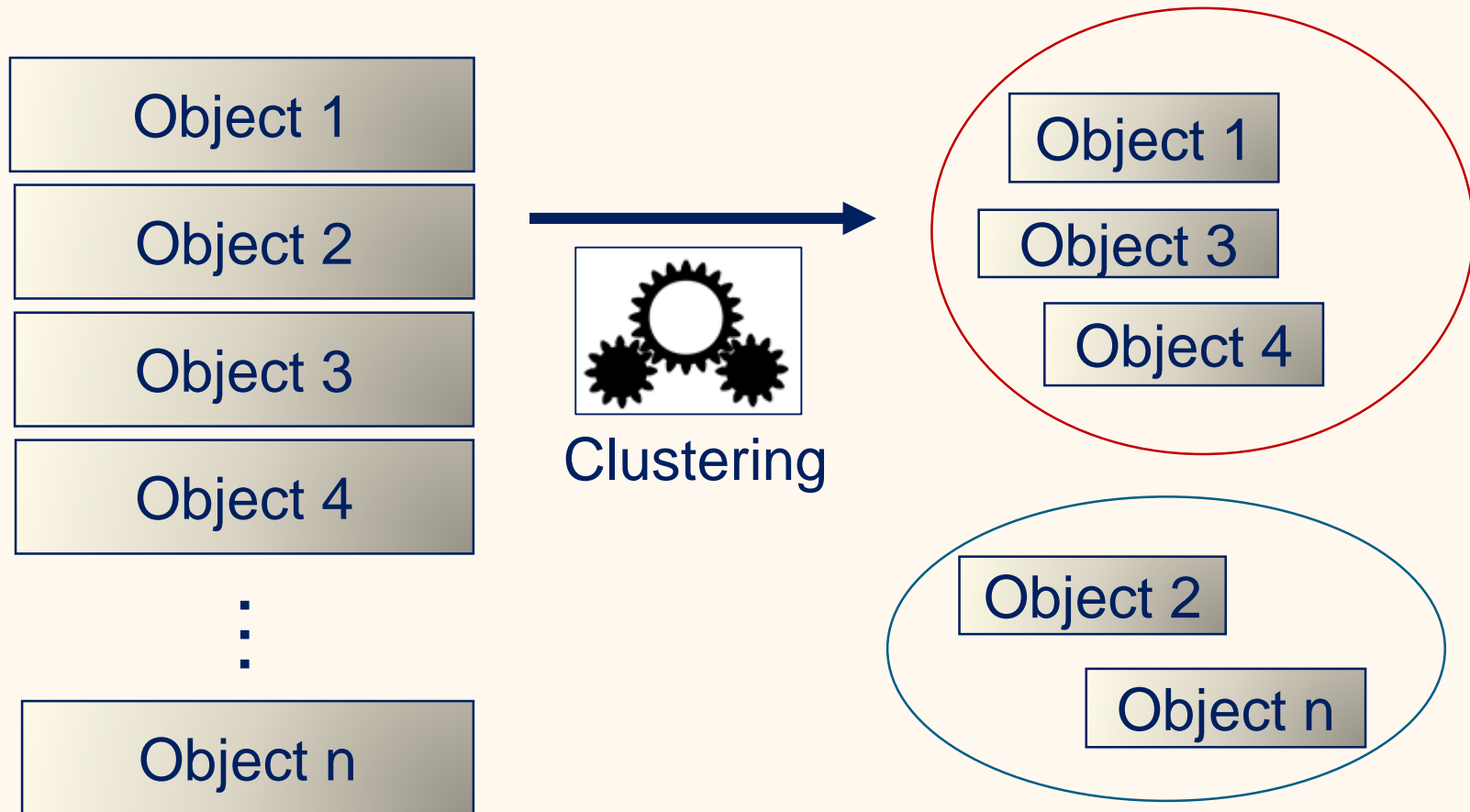
Outline

- Overview
- Clustering algorithms
 - k -means Clustering
 - EM Clustering
 - DBSCAN Clustering
 - Single Linkage Clustering
- Comparison of the Clustering Algorithms
- Summary

Example of Clustering



The General Problem



The Formal Problem

- Object space
 - $O = \{object_1, object_2, \dots\}$
 - Often infinite
- Representations of the objects in a (numeric) feature space
 - $\mathcal{F} = \{\phi(o), o \in O\}$
- Clustering
 - Grouping of the objects
 - Objects in the same group $g \in G$ should be similar
 - $c: \mathcal{F} \rightarrow G$

How do you
measure
similarity?



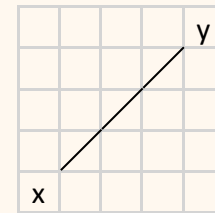
Measuring Similarity Distances

- Small distance = similar

- Euclidean Distance

- Based the eucledian norm $\|x\|_2$

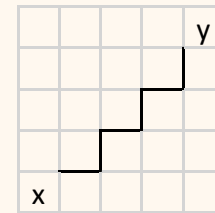
- $d(x, y) = \|y - x\|_2 = \sqrt{(y_1 - x_1)^2 + \dots + (y_n - x_n)^2}$



- Manhattan Distance

- Based on the Manhattan norm $\|x\|_1$

- $d(x, y) = \|y - x\|_1 = |y_1 - x_1| + \dots + |y_n - x_n|$



- Chebyshev Distance

- Based on the maximum norm $\|x\|_\infty$

- $d(x, y) = \|y - x\|_\infty = \max_{i=1..n} |y_i - x_i|$

2	2	2	2	2
2	1	1	1	2
2	1	0	1	2
2	1	1	1	2
2	2	2	2	2

Evaluation of Clustering Results

- No general metrics, depends on algorithms
 - Low variance for k -Means
 - High density for DBSCAN
 - Good fit in comparison to model variables for EM clustering
 - ...
- Often manual checks
 - Do the clusters make sense?
 - Can be difficult
 - Very large data
 - Many clusters
 - High dimensional data

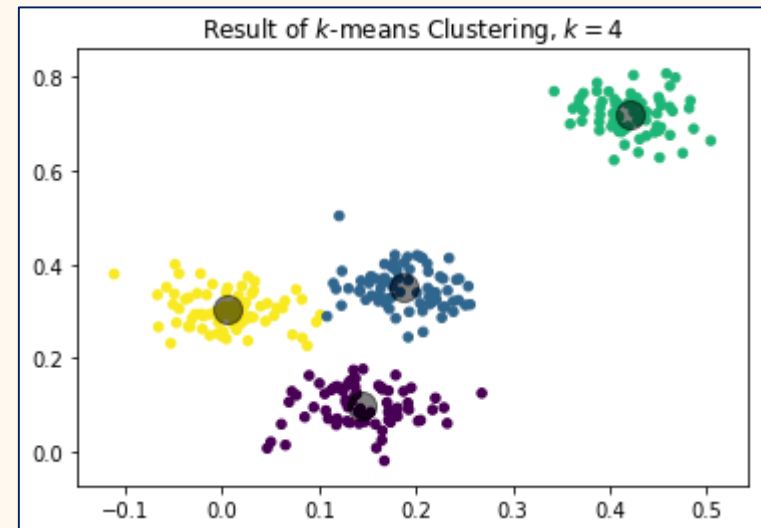
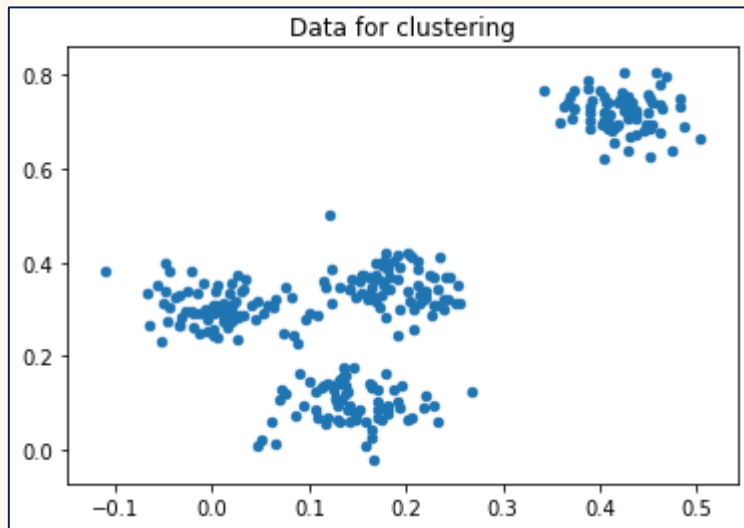
Outline

- Overview
- **Clustering algorithms**
 - ***k*-means Clustering**
 - EM Clustering
 - DBSCAN Clustering
 - Single Linkage Clustering
- Comparison of the Clustering Algorithms
- Summary

Idea Behind k -means Clustering

- Clusters are described by their center
 - The centers are called *centroid*
 - Centroid-based clustering
- Objects are assigned to the closest centroid

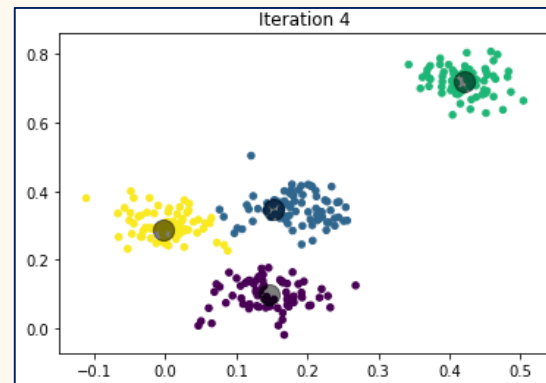
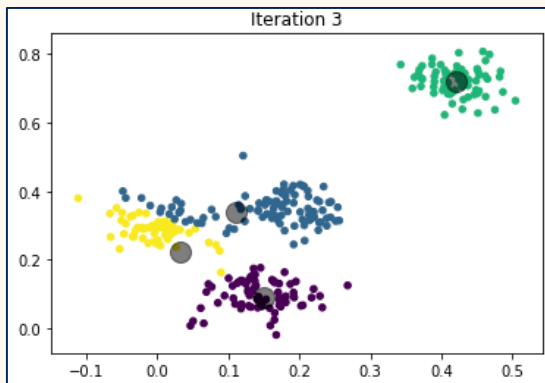
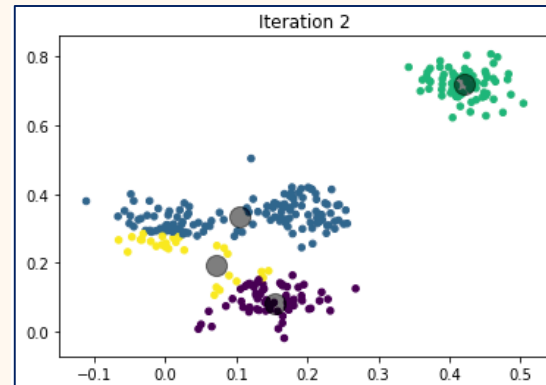
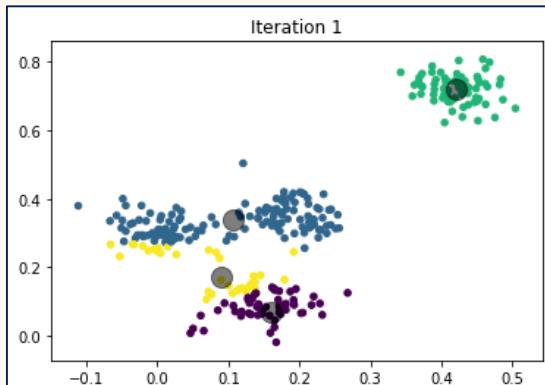
How do you
get the
centroids?



Simple Algorithm

- Select initial centroids C_1, \dots, C_k
 - Randomized
- Assign each object to closest centroid
 - $c(x) = \operatorname{argmin}_{i=1..k} d(x, C_i)$
- Update centroid
 - Arithmetic mean of assigned objects
 - $C_i = \frac{1}{|\{x:c(x)=i\}|} \sum_{x:c(x)=i} x_i$
- Repeat update and assignment
 - Until convergence, or
 - Until maximum number of iterations

Visualization of the k -means Algorithm

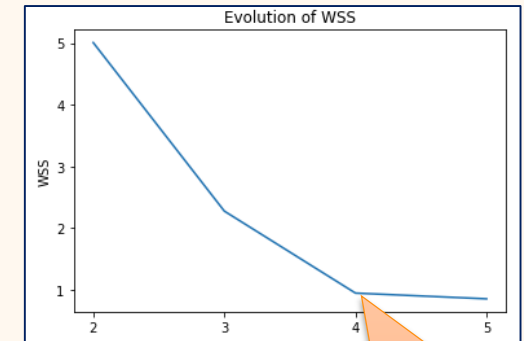
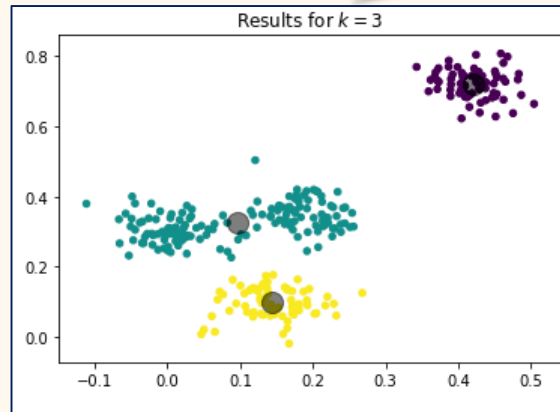
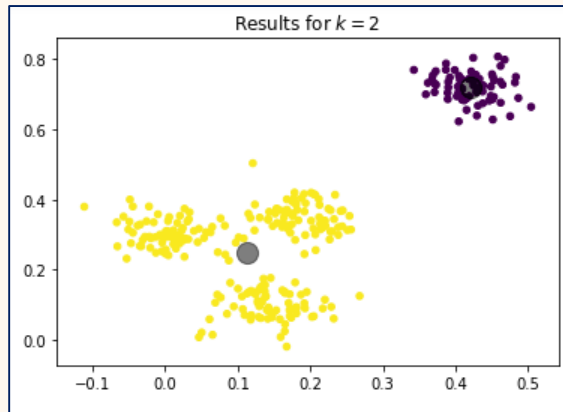


Selecting k

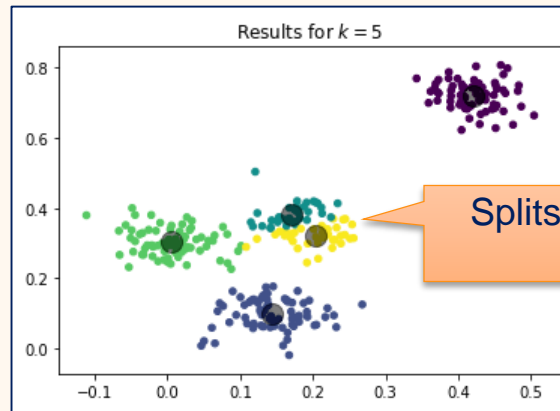
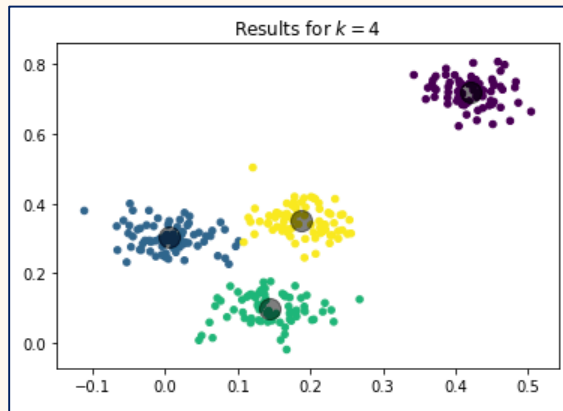
- Intuition and knowledge about data
 - Based on looking at plots
 - Based on domain knowledge
- Due to goal
 - Fixed number of groups desired
- Based on best fit
 - Within-sum-of-squares
 - $WSS = \sum_{i=1}^k \sum_{x: c(x)=i} d(x, C_i)^2$

Results for $k = 2, \dots, 5$

2, 3, and 4 all okay
→ use domain knowledge to decide



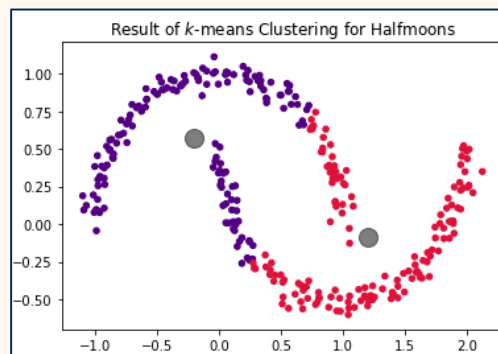
Big changes in slope
(elbows) indicate
potentially good values for
 k



Splits like these indicate too
many clusters

Problems of k -Means

- Depends on initial clusters
 - Results may be unstable
- Wrong k can lead to bad results
- All features must have a similar scale
 - Differences in scale introduce artificial weights between features
 - Large scales dominate small scales
- Only works well for “round” clusters



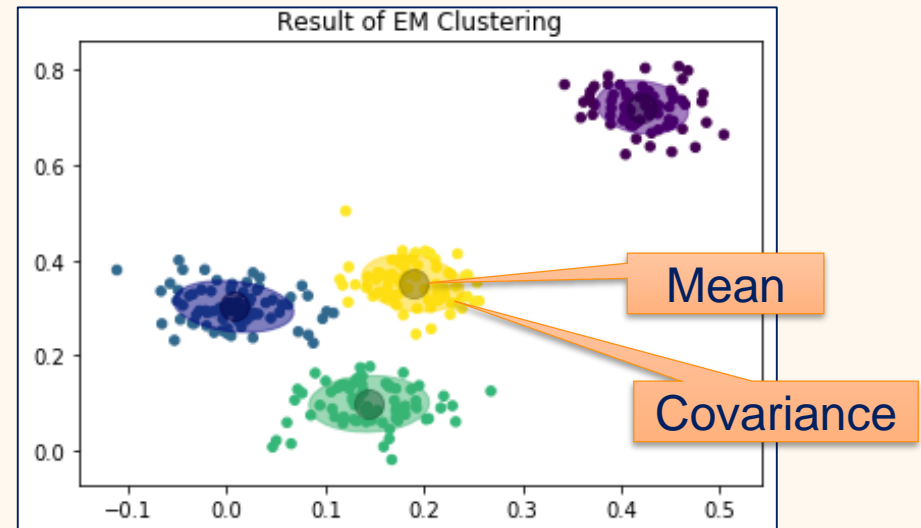
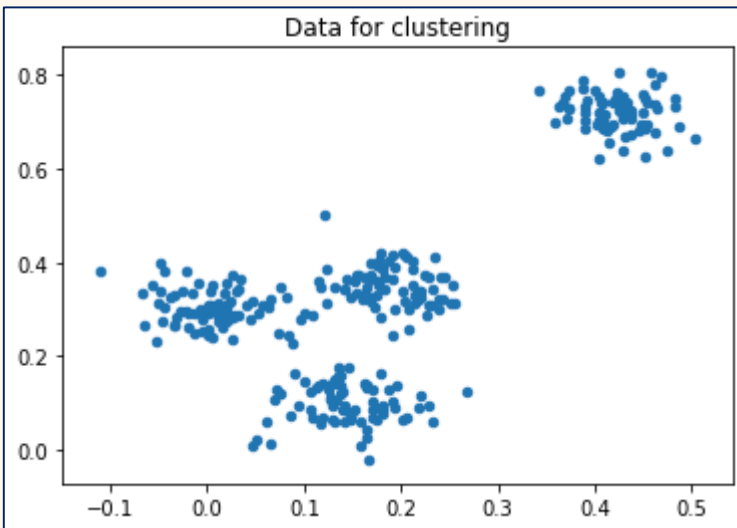
Outline

- Overview
- **Clustering algorithms**
 - k -means Clustering
 - **EM Clustering**
 - DBSCAN Clustering
 - Single Linkage Clustering
- Comparison of the Clustering Algorithms
- Summary

Idea Behind EM Clustering

How do you
get the
distributions?

- Clusters are described by probability distributions
 - Usually normal distribution (“Gaussian Mixture Model”)
 - Distribution-based clustering
- Objects are assigned to the “most likely” cluster



(Simplified!) EM Algorithm

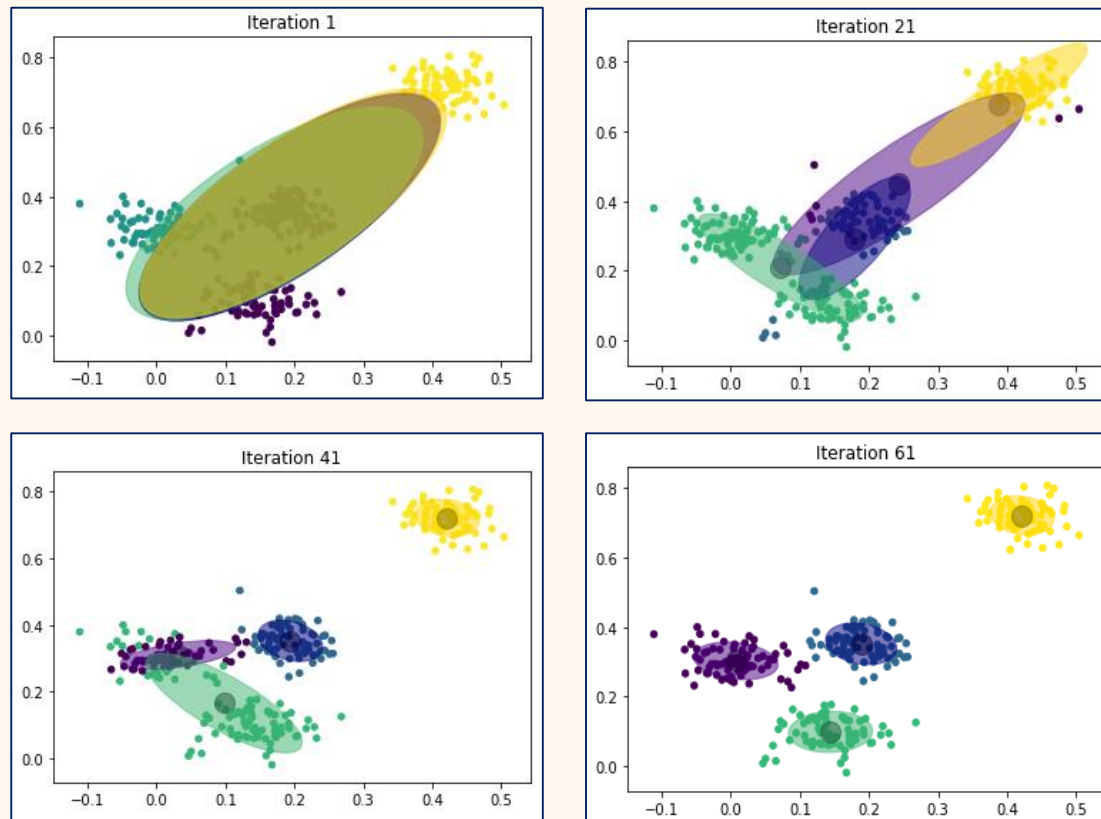
- Task: Determine k normal distributions that “fit” the data well
 - $C_1 \sim (\mu_1, \sigma_1), \dots, C_k \sim (\mu_k, \sigma_k)$,
 - Estimate start values similar to k -means
- **Expectation step**
 - Calculate weights of objects
 - Weights define the likelihood that an object belongs to a cluster
 - $w_j(x) = \frac{p(x|\mu_j, \sigma_k)}{\sum_{i=1}^k p(x|\mu_i, \sigma_i)}$ for all objects $x \in X$
- **Maximization step**
 - Update mean values
 - $\mu_j = \frac{1}{|X|} \sum_{x \in X} w_j(x) \cdot x$



WARNING:

This is a correct, but simplified version of the algorithm that ignores the update of the (co)variance.

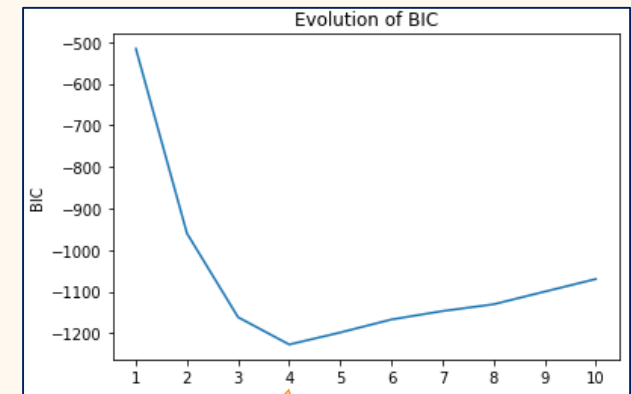
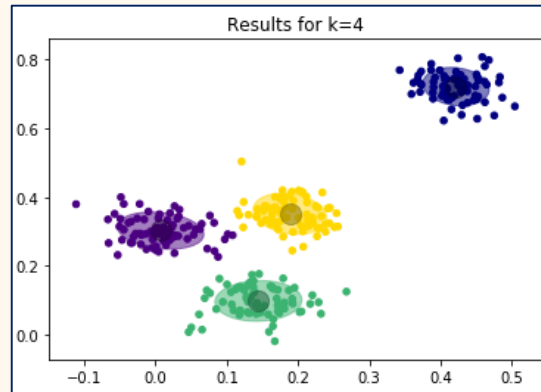
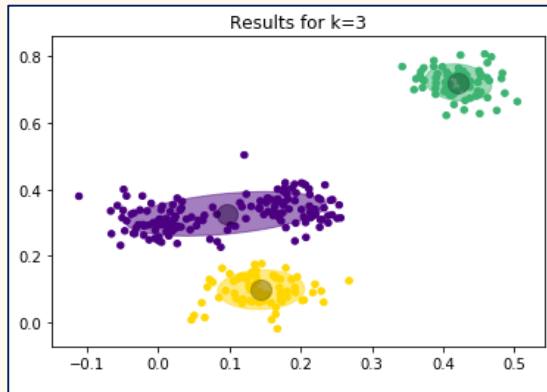
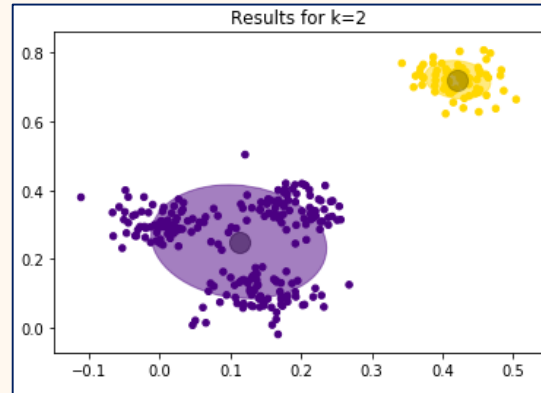
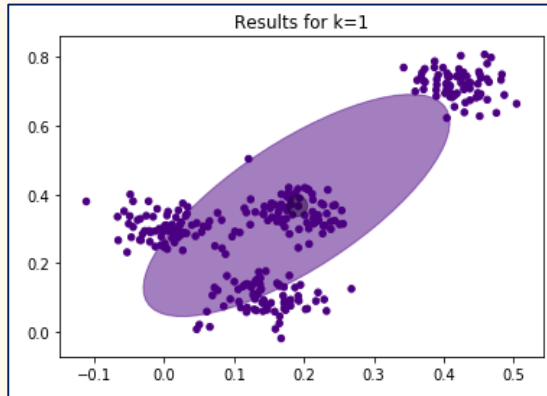
Visualization of the EM Algorithm



Selecting k

- Same as k -means: Intuition, knowledge, goal
- Bayesian Information Criterion (BIC)
 - Difference between the model complexity and the likelihood of the clusters
 - $BIC = \ln(|X|)k' - \hat{L}(C_1, \dots, C_k; X)$
 - k' is the number of model parameters (i.e., mean values, covariances)
 - $\hat{L}(C_1, \dots, C_k; X) = p(C_1, \dots, C_k|X)$ is the likelihood function
 - The lower the better
 - Decreases with less complex models
 - Decreases with better likelihood

Results for $k = 1, \dots, 4$



Minimum = optimal ratio
between model complexity
and goodness of fit

Problems of EM Clustering

- Depends on initial clusters
 - Results may be unstable
- Wrong k can lead to bad results
- May not converge
- Only works well with normally distributed clusters

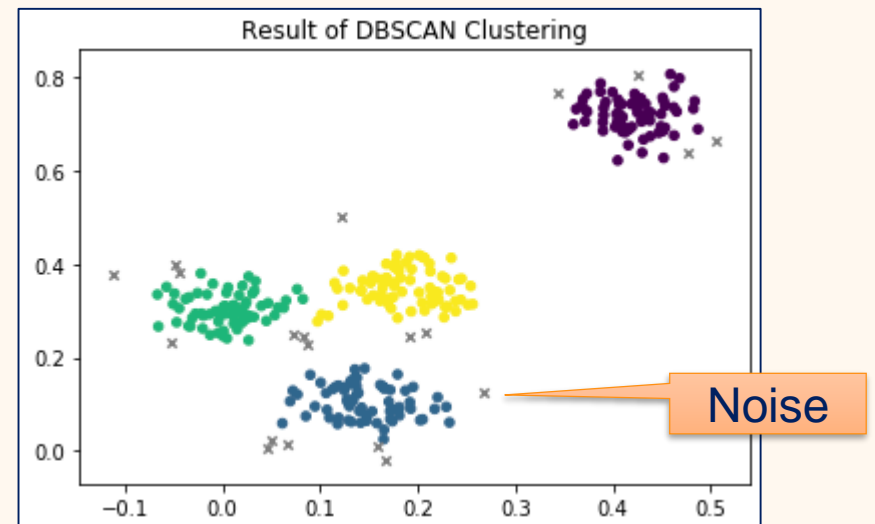
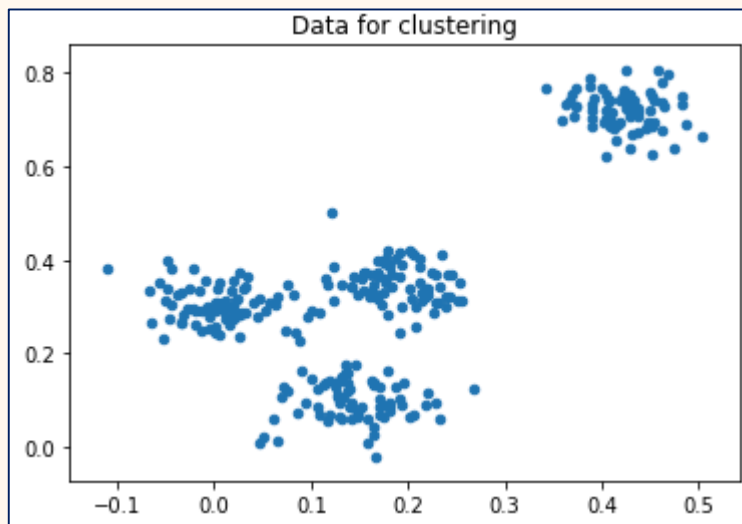


Outline

- Overview
- **Clustering algorithms**
 - k -means Clustering
 - EM Clustering
 - **DBSCAN Clustering**
 - Single Linkage Clustering
- Comparison of the Clustering Algorithms
- Summary

Idea behind DBSCAN

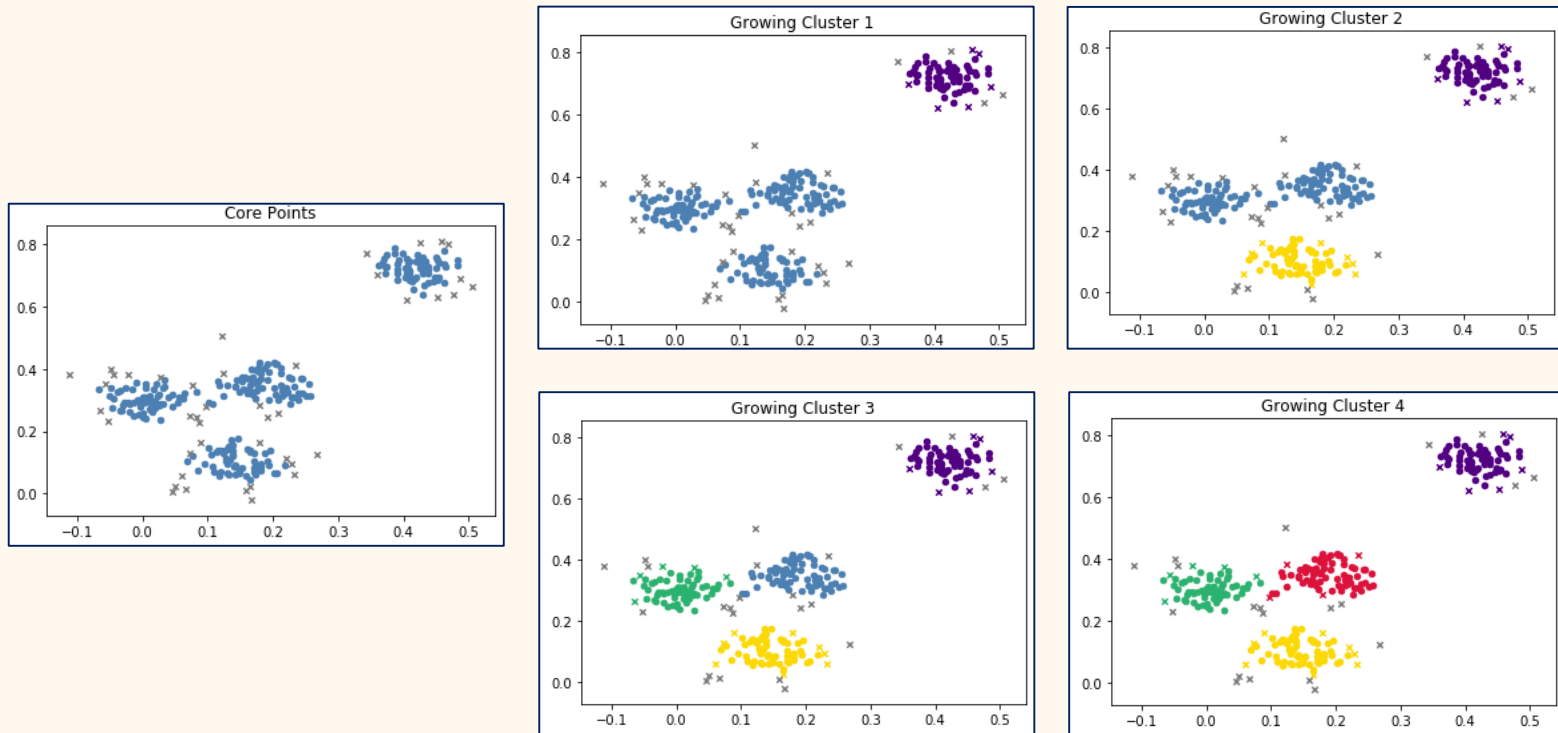
- Clusters are described by other objects close by
 - Density-based clustering
- Scan area around an object for other objects
 - If objects are found, they probably belong to the same group
 - If no objects are found, the object is probably noise



(Relatively) Simple Algorithm

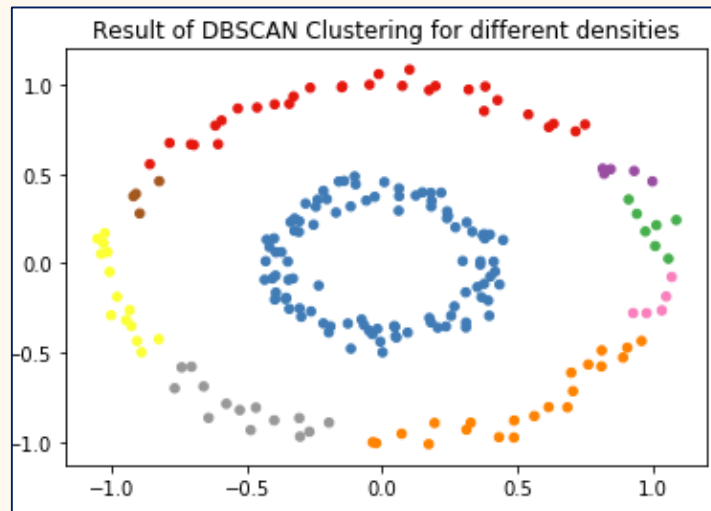
- Two parameters
 - Neighborhood size ϵ
 - Minimal number of points to be considered dense *minPts*
- Determine all objects with dense neighborhoods (core points)
 - $x \in X$ such that $|\{x' \in X: d(x, x') \leq \epsilon\}| \geq minPts$
- Grow clusters by assigning all points that share a neighborhood to the same cluster
- All points that are neither core points nor in the neighborhood of a core point are noise

Visualization of the DBSCAN Algorithm



Problems of DBSCAN

- All features must be in the same range
- What if different clusters have different densities?
→ Main problem of DBSCAN!



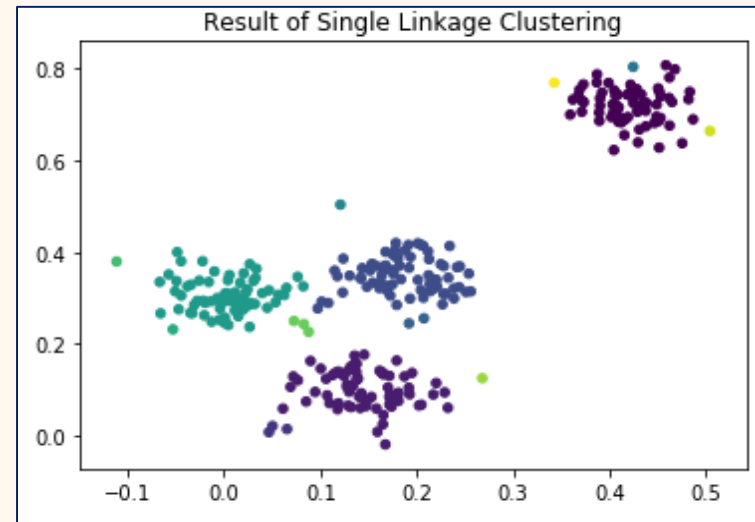
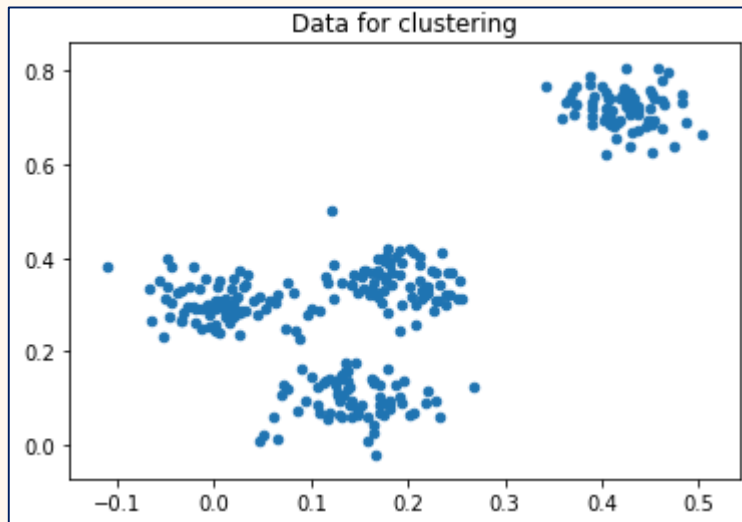
- This is also related to the size of the data
→ DBSCAN is very sensitive to sampling

Outline

- Overview
- **Clustering algorithms**
 - k -means Clustering
 - EM Clustering
 - DBSCAN Clustering
 - **Single Linkage Clustering**
- Comparison of the Clustering Algorithms
- Summary

Idea behind Hierarchical Clustering

- Clusters are described by hierarchies of similarity
 - Hierarchical clustering (also called connectivity-based clustering)
- Find most similar pair of objects and establish link
 - “Nearest Neighbor Clustering”

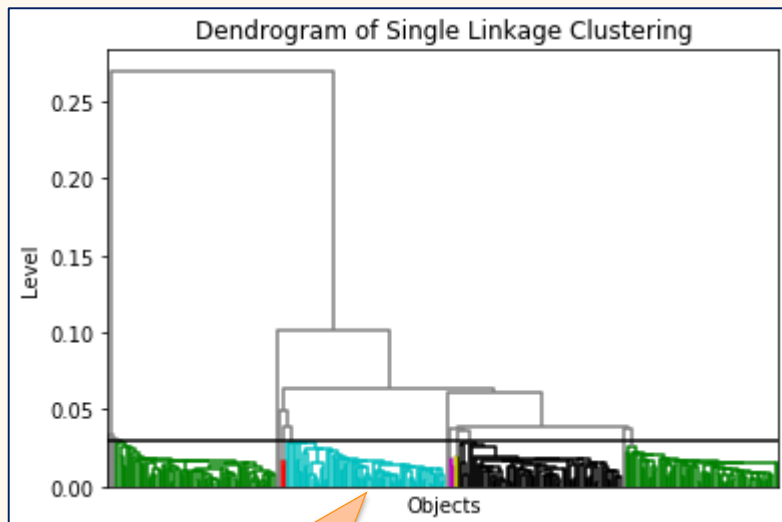


Simple Single Linkage Algorithm (SLINK)

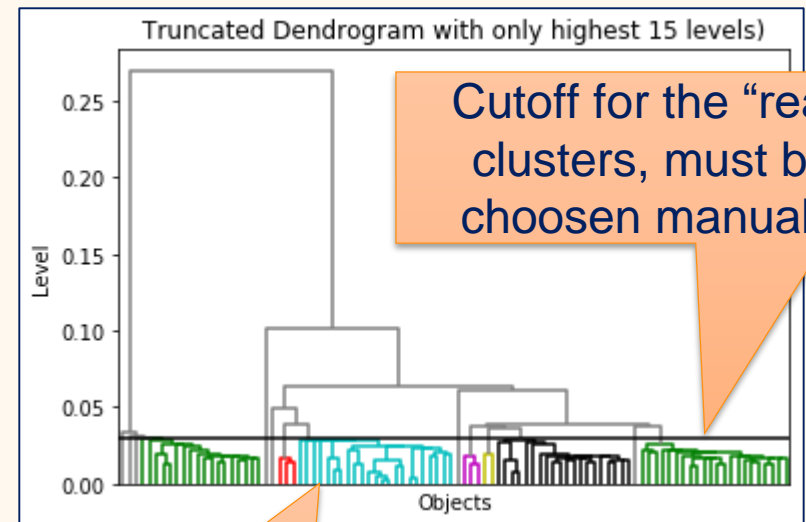
- Every object has its own cluster at the beginning
- The *level* of all these basic clusters is 0
 - $L(C) = 0$ for all $C = \{x\}$ with $x \in X$
- Find two closest clusters
 - $C, C' = \operatorname{argmin}_{C, C' \in \text{clusters}} d(C, C')$
 - $d(C, C') = \min_{x \in C, x' \in C'} d(x, x')$
- Merge C, C' into a new cluster $C_{\text{new}} = C \cup C'$
- The level is the distance between the initial clusters
 - $L(C_{\text{new}}) = d(C, C')$

Dendrograms of Clustering

- Visualizes clustering as a tree
 - Horizontal line: Merging of two clusters
 - Vertical line: Increase of the level due to merge



Each object is a leaf node



Cutoff for the “real” clusters, must be chosen manually

Nodes that are subsequently merged 15 times are suppressed

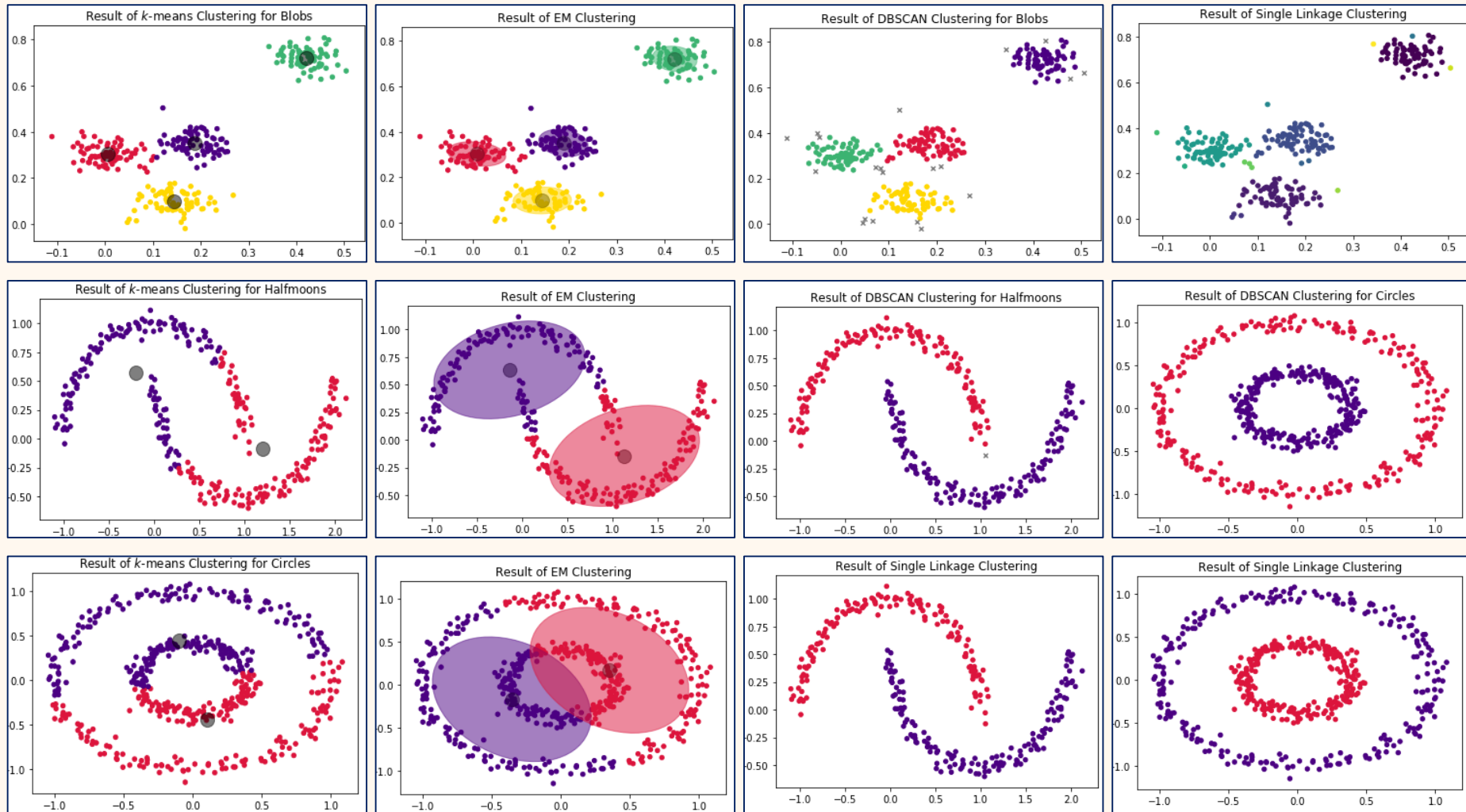
Problems with Hierarchical Clustering

- Often scales badly in terms of memory consumption
 - Standard algorithm requires square matrix of distances between all objects
- All features must be in the same range
- Different densities in different clusters may be problematic
 - Hard to find single cut-off
 - Can be solved by visual analysis of of the dendrogram

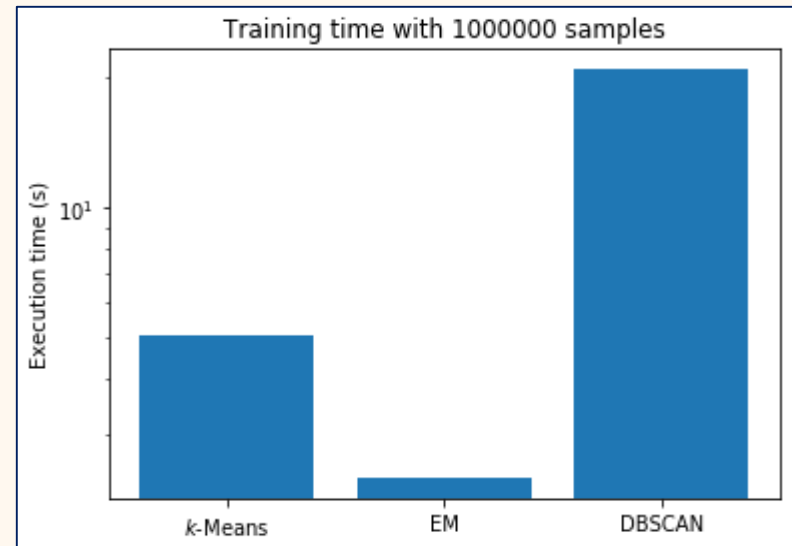
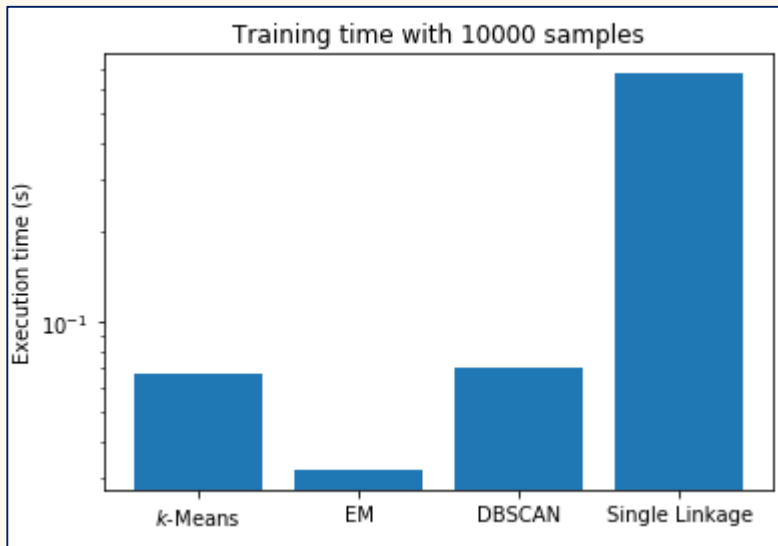
Outline

- Overview
- k -means Clustering
- DBSCAN Clustering
- **Comparison of the Clustering Algorithms**
- Summary

Comparison of Clusters



Comparison of Execution Times



- Single linkage requires too much memory for larger clusters

Strengths and Weaknesses

	Cluster number	Explanatory value	Consis representation	Categorical features	Missing features	Correlated features
<i>k</i> -means	-	+	+	-	-	0
EM	0	+	+	-	-	0
DBSCAN	+	-	-	-	-	0
SLINK	0	+	-	-	-	0



There are clustering algorithms for categorical data, e.g., *k*-modes

Summary

- Clustering is concerned with the inference of groups for objects
- Works well for numeric data but is often not well suited for categorical data
 - Scales are very important for most clustering algorithms
- Different types of clustering algorithms
 - Centroid-based
 - Distribution-based
 - Density-based
 - Hierarchical / connectivity-based
- Evaluation often difficult and requires manual intervention