```
[Info]
 2
    Version = 3.28
 3
    CheckChange = 13ff6a4f
 4
   PLCFileName = Mill55.awl
    //.********************************
 5
    // * *
 6
 7
    // * PLC PROGRAM FOR THE PCM55 *
8
    // * FROM VERS. 3.00 AC95 and ACC *
9
   // * *
10
    // * Designed by Friedrich Schörghofer April 19, 2002 *
11
    //.************************
12
13
   // TABLE OF CONTENTS:
   //
14
15
    // OB 1 ORGANIZATIONAL BLOCK
    // SIMULATE FC 0 TOOL TURNER
16
17
   // FC 1 INITIALIZATIONS
18
   // FC 2 ITEM COUNTER
19
    // FC 3 MAIN DRIVE FELDERER FU
20
   // FC 33 MAIN DRIVE LENZE FU
21 // FC 4 OPERATING MODES
22 // FC 5 AXES READINESS
23
   // FC 6 AXES JOG, INC
24
    // REFERENCE FC 7 AXES
25
   // FC 8 AUX_ON AC95
26
   // FC 88 AUX_ON AC95 / AC88 CONVERSION TO ACC
27
   // FC 9 AUX_ON ACC
28
    // FC 10 AT PROGRAM END RESET OR RESTART
    // FC 11 NC START AND NC STOP FROM MO OR M1
2.9
30 // FC 12 AFG / EFG
31 // FC 13 NC STARTVERR. AND CONTROL BUTTONS
32
    // FC 14 ALARM STATUS
33
    // FC 16 PLC-> SURFACE SIGNALS
34
   // FC 17 AUTOMATIC DOOR
35 // FC 18 tbsp. VICE
36 // FC 21 PARTIAL APPLIANCE
37
    // BLOW OUT FC 22
   // FC 23 SAFETY CIRCUIT ACC
38
39
   // FC 26 COOLANT (M8 / M9)
40 // FC 30 PNEUMATIC CLAMPING DEVICE
41
    // FC 32 AUTOMATICALLY SWITCH TO BA REF
42.
    // FC 34 ASSIGN THE INPUTS AC95 - ACC
43
   // FC 35 ASSIGN THE OUTPUTS AC95 - ACC
44 // FC 40 ROBOTICS INTERFACE
45
    // FC 41 RENISHAW PROBE
46
    // FC 49 ADOPT TOOL POSITIONS INTO MILL55_ACC.MSD
47
    // FC 50 TOOL TURNERS
48
   // FC 51 TOOL CLAMPING SYSTEM
49
   // SET FC 52 TOOL POSITION FROM THE SETTING DATA
50
    // FC 53 CHECK NEW T-WORD AND DETERMINE NEW TOOL DISC POSITION
51
    // RETURN FC 54 TOOL 1
52
   // Return FC 55 TOOL 0 OR NO TOOL
   // Return FC 56 TOOLS 2 TO 8
54
    // FC 57 PICK UP TOOL 1
55
    // FC 58 PICK UP TOOL 0
56
   // FC 59 PICK UP TOOLS 2 TO 8
57
   // FC 60 Z-AXIS TRAVEL TO TARGET POSITION
    // FC 61 A-AXIS TRAVEL TO TARGET POSITION
58
59
    // FC 62 LED CONTROL
60
    // FC 63 WARNING LIGHT
61 // FC 64 MO TRIP WITH TXX and CAMCONCEPT
62 // TRIGGER FC 65 MO and move up the Z-axis with TXX and Sinumeric Operate
63 // FC 66 HANDWHEEL
64
    //
```

```
// SETTING BIT'S FOR COMMISSIONING AND SERVICE:
 66
      // M 200.0 = 0 FOR SETTING THE TOOL REFERENCE POINT
     //\cdot M·200.0 = 1 TOOL AXIS TRAVELS TO 0 DEGREES AFTER REFERENCING
 68
     // SET THE TOOL POSITIONS AND APPLY TO THE MSD FILE
 69
     // ADOPT THE POSITION FOR Z-AXIS T1-T8 EXPRESSION AND RECOVERY POSITION
 70
      // PULL IN TOOL AND EXIT WITH "CTR ^"
 71
     // M 300.0 DOOR AUTOMATICALLY OPEN / CLOSE VIA PLC
 72
     //
 73
     //
 74
     // EASY CYCLE- WINNC- PC key assignment MILL / TURN55:
 75
 76
     // ALT U CTR ^ DB20.DBX 294.2 CHUCK OPEN / CLOSE
 77
     // ALT K CTR 1 DB20.DBX 294.5 WZW SWIVEL FURTHER ONE POSITION TURN55
 78
     // ALT K CTR 1 DB20.DBX 294.5 EXTRACT / PULL IN TOOL MILL55
 79
      // ALT O CTR 2 DB20.DBX 294.6 BLOW OUT ON / OFF (M71-ON, M72-OFF)
 80
     // ALT O CTR 2 DB20.DBX 294.6 MINIMUM QUANTITY COOLING ON / OFF Q 3.5 (M7-ON, M9-OFF)
 81
     // (ONLY IF THE BLOW DEVICE IS NOT ACTIVATED)
     // ALT I CTR 3 DB20.DBX 294.1 SWIVELING PART UNIT ONE DIVISION (M27)
 82
 83
     // ALT X CTR 4 DB20.DBX 295.1 FEED STOP
 84
     // ALT C CTR 5 DB20.DBX 295.2 FEED START
 85
     // ALT V CTR 6 DB20.DBX 295.3 SPINDLE STOP
     // ALT B CTR 7 DB20.DBX 295.4 SPINDLE START
     // ALT N CTR 8 DB1.DBX 1374.4 AUXILIARY DRIVES ON
 87
 88
     // ALT H CTR 9 DB20.DBX 294.4 VICE / QUILL FORE (M26)
 89
     // ALT J CTR 0 DB20.DBX 294.3 VICE / QUILL BACK (M25)
     // ALT M CTR & DB1.DBX 1374.3 AUXILIARY DRIVES OFF
 90
 91
     // ALT P CTR OB1.DBX 1374.2 MACHINE DOOR OPEN / CLOSE
 92
 93
     94
 95
     // Applies to both stepper motor modules:
 96
 97
      // A 3.7 Enable differential line driver clocks for SM
 98
     //
 99
     // 1.1 Pin assignment for 1st stepper motor module Y5A011000
100
101
     //
102
     //
103
     // (-A111)
104
105 // ·X3: ·1 · I · O · O · Servo · Ready · X · (physical · axis · O)
    // X3: 2 DIR X
106
    // X3: 3 DIR X /
107
     // X3: 4 CK X
108
111 // X3: ·7 · DIR · Z
    // X3: 8 DIR Z /
112
113 // X3: 9 CK Z
    // X3: 10 CK Z /
114
    // X3: 11 I 0.1 Servo Ready Y (physical axis 2)
115
    // X3: 12 DIR Y
116
     // X3: 13 DIR Y /
117
118 //·X3:·14·CK·Y
    // X3: 15 CK Y /
119
120 // \cdot X3 : \cdot 16 \cdot A \cdot 3.0 \cdot = \cdot M \cdot 17.0 \cdot // \cdot ENABLE \cdot AXES \cdot A
121 //
122 //·1.2·Pin·assignment·for·2nd·stepper·motor·module·Y5A011000
123 // for tool turret MILL 55
124 //
125 // (-A112)
127 // X3: 1 (I · 0.3 · Servo · SERVO · READY · HA · physical · axis · 3)
128 // X3: 2 (This line is disconnected on the stepper motor card with it)
```

```
129 //·X3:·3·(there is no short circuit with the HA setpoint module)
130 // x3: 4
131 // X3: 5
132 // X3: 6 · I · 0 · 5 · Servo · Ready · tool · turret · DRIVE · (physical · axis · 4)
133 // X3: 7 DIR Z
134 // X3: 8 DIR Z /
135 // X3: 9 CK Z
136 // X3: 10 CK Z /
137 // X3: 11 I · 0 · 4 · Servo · Ready · round · axis · DRIVE · (physical · axis · 5)
138 // X3: 12 DIR Y
139 // X3: 13 DIR Y /
140 // X3: 14 CK Y
141 // X3: 15 CK Y /
142 // X3: 16 A 3.1 ACC ONLY // AXES ENABLE B
143 //
144 //
145
      // 2nd pin assignment SET VALUE MODULE Y5A013000
146
147
      //·(-A114)
148
     //
149 // X3: 1 rotating field frequency
     // X3: 2 GND
150
     //·X3:·3·//·SET·VALUE·0-10V
151
     // X3: 4 // DIRECTION
152
     // x3: 5
153
154
     // X3: 6 + 24V
     //·X3:·7·I·0.3·=·M·15.7·//·SERVO·READY·HA·(physical·axis·3)
155
     // x3: 8
156
     // X3: 9
157
     // X3: 10
158
     //·X3:·11·Q·0.3 = M·17.1·// CONTROLLER ENABLE MAIN DRIVE
159
     // X3: 12 Q 11.5
160
     // X3: 13 A 11.6
161
    // x3: 14
162
163
     // X3: 15 GND
164
      //
165
166
     // 3. Input and output assignment on REF module Y5A017000
167
168
     // (-A131)
169
      //
170
      // X5: 1 I16.0 REF1 // REF switch X-axis
171
      // X5: 2 I16.1 REF2 // REF switch Y-axis
172
     // X5: 3 I16.2 REF3 // REF switch Z-axis
173
      // X5: 4 I16.3 REF4 // REF BERO A-ROUND AXIS
174
      // X5: 5 I16.4 REF5 // REF BERO WZW
175
     // X5: 6 I17.0 SYNC1 // SYNC BERO X-axis
176
     // X5: 7 I17.1 SYNC2 // SYNC BERO Y-axis
177
      // X5: 8 I17.2 SYNC3 // SYNC BERO Z-axis
178
      // X5: 9 I17.5 SYNC4 // SYNC BERO A-ROUND AXIS
      // X5: 10 I17.4 SYNC5 // SYNC BERO tool axis
179
180
      // X5: 11 E 2.3 = M·15.6; // only TURN !! WHEEL COVER LIMIT SWITCH (IN SERIES WITH
      EMERGENCY STOP!)
181
      // X6: 1 · I · 2 · 0 · = · M · 15 · 0 · // · 1st · door · limit · switch · MACHINE · DOOR · CLOSED · (MAIN · MOTOR ·
      CONTACTOR ON)
182
      // Monitoring whether HA contactors have dropped out (must have 0 signal
183
     // be with the door or wheel cover open or the EMERGENCY STOP pressed)
      // X6: 2 I 2.1 = M 15.1 // 1st door limit switch MACHINE DOOR OPEN
184
185
      // (0 signal when the door is closed!)
186
      // X6: 3 I 2.2 = M 15.2 // EMERGENCY OFF
187
      // X6: 4 I 2.4 = M 16.0 // n = 0 RELAY FROM LENZE-FU
188
      // X6: 5 I 2.5 ON 24V (only ACC) // 2nd door limit switch MACHINE DOOR CLOSED 2nd door
      limit switch
189
      // X6: 6 I 2.6 IN 24V
```

```
190
    // X6: 7 I 2.7 A 5V
191
     // X6: 8 I 3.0 A 5V
192
    // X6: 9 A 3.5 AUS 24V (ACC only) // ACTIVATE RENISHAW PROBE WITH 12 INTERFACE
193 // X6: 10 · A · 3.4 · AUS · 24V · (ACC · only) · // · OUTPUT · FOR · AUXILIARY · RELAY · DOOR · CLOSED
194 // X6: 11 A 3.3 OFF 24V // COOLANT (M8 = ON / M9 = OFF)
195
      //
196
     //
197
     // 4. Pin assignment on INPUT module Y5A018000
198
199
     //·(-A132)
200
     //
     // X5: 1 I 4.0 // TOOL RETRACTED
201
202
     // X5: 2 I 4.1 // TOOL EXPRESSED
203
     // X5: 3 I 4.2 // 12mm BERO TOOL EQUIPPED
204
      // X5: 4 I 4.3
205
     // X5: 5 I 4.4 // DOOR OPEN, AUTOMATIC DOOR
206
     // X5: 6 I 4.5 // PRESSURE SWITCH VICE
207
     // X5: 7 I 4.6
208
     // X5: 8 E 4.7 SCHÄFER dividing attachment finished
209
     // X5: 9 E 5.0 robotics close door
210
     // X5: 10 I 5.1 Open the robotics door
211
     // X5: 11 E 5.2 Open the robotics vice
212
     // X6: 1 I 5.3 Close the robotics vice
213
     // X6: 2 I 5.4 Handwheel clock input (in MSD file: PLCHandWheelInput0 = 5.4)
214
     // X6: 3 I 5.5 Handwheel direction input
215
     // X6: 4 I 5.6 Start the robotics program
216
     // X6: 5 I 5.7 Robotics feed stop
217
     // X6: 6 I 6.0 tool infeed above
     // X6: 7 I 6.1 Tool infeed below
218
219
     // X6: 8 I 6.2 STATUS RENISHAW PROBE MI 12 INTERFACE
220
     // X6: 9 E 6.3 \ STATUS RENISHAW PROBE MI 12 INTERFACE
     // X6: 10 I 6.4 NO ERROR RENISHAW PROBE MI 12 INTERFACE
221
222
     // X6: 11 E 6.5 LOW BATT RENISHAW PROBE MI 12 INTERFACE
223
     //
224
     //
225
     //
226
     // 5. Pin assignment on OUTPUT module Y5A019000
227
228
     //·(-A134)
229
     //
230
      // \times 5: 1 A 4.0 = M·18.0 // MINIMAL LUBRICATION (M7 = ON / M9 = OFF)
231
     // X5: 2 Q 4.1 = M 18.1
232
     // X5: 3 A 4.2 = M 18.2 // BLOW-OUT VALVE
233
     // X5: 4 A 4.3 = M 18.3 // DOOR OPEN
     // X5: 5 A 4.4 = M 18.4 // DOOR CLOSED
234
235
     // X5: 6 A 4.5 = M 18.5 // VICE FORE
     // X5: 7 A 4.6 = M 18.6 // VICE BACK
236
     // X5: 8 Q 4.7 = M 18.7 // PARTIAL APPLIANCE PART
237
     // X5: 9 Q 5.0 = M 19.0 // ROBOTIC PROGRAM STOP
238
239
      (M30, M0, M1, M2)
      // X5: 10 A 5.1 = M 19.1 // ROBOTIC AXES ARE AT REF.PKT.
240
     // X6: 1 Q 5.2 = M 19.2
241
242
     // X6: 2 A 5.3 = M 19.3 // ROBOTIC DOOR OPEN
     // X6: 3 A 5.4 = M 19.4 // ROBOTIC DOOR CLOSED
243
244
     // X6: 4 A 5.5 = M 19.5 // ROBOTIC REAR VICE
     // X6: 5 A 5.6 = M 19.6 // ROBOTIC VICE CLAMPED
245
246
     // X6: 6 A 5.7 = M 19.7 // ROBOTIC ALARM OUTPUT
     // X6: 7 A 6.0 ACC ONLY // TOOL CLAMPING MOTOR
247
      // X6: 8 A 6.1 ACC ONLY // BLOW OFF THE TOOL CONE
248
249
     // X6: 9 A 6.2
250
     // x6: 10 Q 6.3
251
     //
252
     //
253
```

```
254 // with LENZE-FU and 3-phase stepper motors
255 //
256 // lst input assignment on the AC plug-in board Y4A091000 top-hat rail external FU:
     // (Axiscontroller Y4A 080 000 for top hat rail)
     //
258
259
      // X113.1 + 24V
260
      // X113.2 GND
261
     // X113.3 I 0.0 Reference switch axis 0 (X)
262
263
     // X115.1 + 24V
264
     // X115.2 GND
265
     // X115.3 I 0.1 Reference switch axis 1 (Y)
266
267
     // X117.1 + 24V
268
      // X117.2 GND
269
      // X117.3 I 0.2 Reference switch axis 2 (Z)
270
271
     // I 0.3 Reference point axis 3 (HA)
272
273
     // X114.3 + 24V (X) Bero
274
     // X114.3 GND (X) Bero
275
     // X114.3 I 0.4 Sync axis 0 (X) Bero
276
     //
277
      // X116.3 + 24V (Y) Bero
278
      // X116.3 GND (Y) Bero
279
     // X116.3 I 0.5 Sync axis 1 (Y) Bero
280
281
     // X118.3 + 24V (Z) Bero
282
     // X118.3 GND (Z) Bero
     // X118.3 I 0.6 Sync axis 2 (Z) Bero
283
284
     //
     // X109.1 + 5V
285
286
      // X109.2 GND
287
     // X109.3 free
288
     // X109.4 I 0.7
289
     // X109.5
290
     // A 3.7 Enable differential line driver clocks for SM
291
292
     // Ribbon cable connector to the stepper motor board 16pol. :
293
     // X104.1 I 1.0 // I 0.0 = M 15.3; // SERVO READY AXIS 0 (X)
      // \cdot X104.6 \cdot I \cdot 1.1 \cdot // \cdot I \cdot 0.1 \cdot = \cdot M \cdot 15.4; \cdot // \cdot SERVO \cdot READY \cdot AXIS \cdot 0 \cdot (Y)
294
295
      // X104.14 I 1.2 // I 0.2 = M 15.5; // SERVO READY AXIS 0 (Z)
296
     // X104.16 Servo Enable (via X110.4 from X121.3 = Q 0.1)
297
     //
     //
298
299
     // X111.1 I 1.5 // I 2.0 = M 15.0 // MACHINE DOOR CLOSED (MAIN MOTOR CONTACTOR ON)
300
     // Monitoring whether HA contactors have dropped out (must have 0 signal
301
     // be with the door or wheel cover open or the EMERGENCY STOP pressed)
302
     // X111.2 GND
303
      // X111.3 I 1.6 // I 2.1 = M 15.1 // MACHINE DOOR OPEN
304
      // (0 signal when the door is closed!)
305
      // X111.4 I 1.7 // I 2.3 = M 15.6; // WHEEL COVER LIMIT SWITCH (IN SERIES WITH
      EMERGENCY STOP!)
306
      //
307
     // X110.1 I 1.4 // I 2.2 = M 15.2 // EMERGENCY OFF
308
     // X110.2 GND
309
     // X110.3 I 2.0 reserve input
      // X110.4 Servoenable (signal comes from X121.3 = Q0.1). This entrance
310
311
      // is via the 16pol. Ribbon cable connector X104 Pin16 to the
      // SM card and releases the output stages there (works
312
313
     // only with new SM card Y4A031000).
314
     //
     // X101.1 + 5V
315
316
      // X101.2 GND
```

```
317
      // X101.3 I 2.1
318
     // X102.1 + 5V
319
320
     // X102.2 GND
321
      // X102.3 I 2.2
322
      // X103.1 + 24V
323
324
     // X103.2 GND
325
      // X103.3 I · 2.3 · // I · 2.4 · = M · 16.0 · // n · = 0 · RELAY · FROM · LENZE-FU
326
327
      // X105.1 + 24V
328
     // X105.2 GND
329
     // X105.3 E 2.4 Renishaw measuring probe (special machine for USA, input only for NC)
330
331
      // E 2.5 Sync X (for monitor display for setting the reference switch)
332
      // E 2.6 Sync Y (for monitor display for setting the reference switch)
333
      // E 2.7 Sync Z (for monitor display for setting the reference switch)
334
      //
335
      // 2nd output assignment on the AC connector board Y4A081000:
336
337
     // X1070.1 rotating field frequency analog
338
     // X1070.2 GND
339
      // X1070.3 setpoint analog
340
      // x1070.6 + 24V
341
      // X1070.7 · I · 1.3 · // · I · 0.3 · = · M · 15.7 · // · SERVO · READY · HA
342
343
      // \times 107.2 \cdot Q \cdot 0.0 \cdot // \cdot Q \cdot 0.3 = M \cdot 17.1 \cdot // \cdot CONTROLLER \cdot ENABLE \cdot MAIN \cdot DRIVE
344
      // X107.6 RE / LI (0/1) Direction of rotation of the main drive
     // X107.7 GND
345
346
     //
347
     // X121.1 + 24V
      // X121.2 GND
348
349
      // X121.3 Q 0.1 // Q 3.0 = M 17.0 // ENABLE AXES
      // (AC95: is connected to X110.4 - enable
350
351
     // the stepper motor output stages)
352
      //
      // X120.1 + 24V
353
354
     // X120.2 GND
355
     // X120.3 Q 0.2 reserve output
356
      //
      // x123.1 + 24V
357
358
      // X123.2 GND
359
      // X123.3 Q 0.3 reserve output
360
     //
361
      // X122.1 + 24V
362
      // X122.2 GND
363
     // \times 122.3 \cdot A \cdot 0.4 \cdot // \cdot A \cdot 3.3 \cdot = M \cdot 17.2 \cdot // \cdot COOLANT \cdot (M8 \cdot = \cdot ON \cdot / \cdot M9 \cdot = \cdot OFF)
364
365
      // 3. Input / output assignment on the CANBUS I / O board Y4A029000:
366
367
      // input byte 4,5
368
      // X201.1 E 4.0 8 ***** ONLY AC95 EL.VICE "No part clamped"
      // X201.2 I 4.1 8 ****** ONLY AC95 EL.VICE open
369
      // X201.3 E 4.2 8 ***** ONLY ACC 12mm-BERO TOOL EQUIPPED
370
371
      // X201.4 E 4.3
372
      // X201.5 E 4.4 // DOOR OPEN, AUTOMATIC DOOR
373
      // X201.6 I 4.5 8 ***** ACC / AC95 EL.VICE PART CLAMPED (signal from clamping device
      board)
374
      // 8 ***** ACC / AC95 Pneum. VICE PRESS
     K SWITCH
375
376
     // X201.7 E 4.6
377
     // X201.8 E 4.7 SCHÄFER dividing attachment finished
378
      // X201.9 + 24V supply
379
      // X201.10 GND supply
```

```
381 //
382 // X301.1 E 5.0 robotics close door
     // X301.2 I 5.1 Open the robotics door
384 // X301.3 E 5.2 Open the robotics vice
385 // X301.4 E 5.3 Close robotics vice
386 // X301.5 E 5.4 Robotics
387 // X301.6 E 5.5 Robotics
388 // X301.7 I 5.6 Start the robotics program
389 // X301.8 E 5.7 Robotics feed stop
390 // X301.9 + 24V supply
391 // X301.10 GND supply
392 //
393 //
394 // output byte 4.5
395 - // \cdot x501.1 \cdot Q \cdot 4.0 \cdot // \cdot Q \cdot 4.0 \cdot = \cdot M \cdot 18.0 \cdot MINIMAL \cdot LUBRICATION
396 //·X501.2·Q·4.1·//·Q·4.1·=·M·18.1
397 // X501.3 A 4.2 // A 4.2 = M 18.2 BLOW-OUT VALVE
398 // X501.4 · A · 4.3 · // · A · 4.3 · = · M · 18.3 · DOOR · OPEN
      // X501.5 A 4.4 // A 4.4 = M 18.4 DOOR CLOSED
400 // X501.6 · A · 4.5 · // · A · 4.5 · = · M · 18.5 · CLAMPING · THE · VICE
401 // X501.7.0.4.6.//.0.4.6.= M.18.6.RELEASE.THE.VICE
402 // X501.8 O 4.7 // O 4.7 - M 18.7 PARTIAL APPLIANCE PART
403 // X501.9 + 24V supply
404 // X501.10 GND supply
    // X502.1 A 5.0 // A 5.0 = M 19.0 ROBOTIC PROGRAM STOP (M30, M0, M1, M2)
406 // X502.2 A · 5.1 · // · A · 5.1 · = · M · 19.1 · ROBOTIC · AXES · ARE · AT · REF. PKT.
407 / X502.3 Q 5.2 / Q 5.2 = M 19.2
408 // X502.4 A 5.3 // A 5.3 = M 19.3 ROBOTIC DOOR OPEN
409 // X502.5 A 5.4 // A 5.4 = M 19.4 ROBOTIC DOOR CLOSED
410 // X502.6 · A · 5.5 · // · A · 5.5 · = · M · 19.5 · ROBOTIC · REAR · VICE
411 // X502.7 A 5.6 // A 5.6 = M 19.6 ROBOTIC VICE CLAMPED
412 //·X502.8·Q·5.7·//·Q·5.7·=·M·19.7·ROBOTIC·ALARM·OUTPUT
413 // X502.9 + 24V supply
414 // X502.10 GND supply
415 //
416 //
417 //
418 // SET; = 1
419 // CLR; = 0
420
      //
    // TIMER:
421
    // SI = IMPULSE
422
     // ·THE · MAXIMUM · PULSE · LENGTH · CORRESPONDS · TO · THE · PROGRAMMED · TIME
423
    // ·THE·MINIMUM·PULSE·LENGTH·CORRESPONDS·TO·THE·LENGTH·OF·THE·INPUT·SIGNAL
424
     //
425
     //·SV·=·PULSE·(EXTENDED)
426
427
      // THE PULSE LENGTH CORRESPONDS TO THE PROGRAMMED TIME
     // THE DURATION OF THE INPUT SIGNAL HAS NO INFLUENCE
428
429
     // SE = SWITCH-ON DELAY
430
     // THE DELAY DURATION CORRESPONDS TO THE PROGRAMMED TIME
431
432
      // THE INPUT SIGNAL MUST BE PRESENT FOR AT LEAST
433
     // SS = SWITCH-ON DELAY (STORING)
434
     // THE DELAY DURATION CORRESPONDS TO THE PROGRAMMED TIME
435
436
      // THE DURATION OF THE INPUT SIGNAL HAS NO INFLUENCE
437
     //·SA·=·SWITCH-OFF·PULSE
438
     // THE PULSE LENGTH CORRESPONDS TO THE PROGRAMMED TIME
439
440
     // THE TIMER CHANGES FROM "0" TO "1" AND THE TIME IS STARTED
     //·IF THE INPUT SIGNAL GOES FROM "1" TO "0".
441
442
443
      // TIME BASE ASSIGNMENT OF THE TIME WORD
```

```
// 16 ..... 8 7 ..... 0
444
445
     // 0.01 S 0000 0000 0000 0000
     // 0.1 S 0001 0000 0000 0000
446
    // 1 S 0010 0000 0000 0000
447
448
    // 10 S 0011 0000 0000 0000
449
     // H Z E = TIME VALUE IN BCD FORMAT
     // 00 = BINARY CODE FOR TIME BASE
451 FUNCTION FC 64: VOID
452 NAME: MO RELEASE ON TXX AND CAMCONCEPT
453 BEGIN
454 U DB20.DBX 182.0; // NEW T-WORD
455 SPBN-M001;
456 L DB20.DBW 184; // T-WORD
457 L DB20.DBW 356; // ACTIVE TOOL IN DB20
458 <> I.
459 SPBN M001;
460 S M 12.0
461 MOO1: NOP 0;
462 U M 12.0
463 FP M 12.1
464 U M 12.1
465 SPBN M002;
466 = DB20.DBX 192.0; // MO DYNAMIC
467 S.DB3.DBX.0.2; // Message.7002 change tool
468 R M 12.0
469 M002: NOP 0;
470 O DB1.DBX 1370.3; // RESET KEY PRESSED
471 O DB1.DBX 1440.0; // RESET TRIPPED
472 O DB20.DBX 3.6; // NC START REQUEST
473 O DB20.DBX 0.2; // FC NC-START
474 R DB3.DBX 0.2; // 7002 change tool
475 END_FUNCTION
476 FUNCTION FC 65: VOID
477 NAME: TRIP MO and move up the Z-axis with TXX and Sinumeric Operate
478 BEGIN
479 U DB20.DBX 182.0; // NEW T-WORD
480 SPBN M6401;
481 L DB20.DBW 184; // T-WORD
482 L DB20.DBW 356; // ACTIVE TOOL IN DB20
483 <> I.
484 SPBN·M6401;
485 S M 12.0 // T-WORD IS VALID
486 M6401: NOP 0;
487 NETWORK
488 TITLE - T-WORD IS VALID SPINDLE ENABLE AND AFG / EFG switch off
489 U.M.12.0.// T-WORD IS VALID
490 = M 94.7; // SPINDLE ENABLE T-WORD IS VALID
     = M 90.5; // AFG / EFG T-WORD IS VALID
492 NETWORK
493 TITLE - - CALCULATE - Z-AXIS - TOOL - CHANGE - POSITION
494 U M 12.0 // T-WORD IS VALID
495 FP M 12.1 // FP T-WORD IS VALID
496 U.M. 12.1 // FP T-WORD IS VALID
497 SPBN M6402;
498 L.DB20.DBD.486.//.max..Software.limit.switch.for.channel.axis.Z
499 L + 5.0E-03;
500 - R
501 T MD 28 // Z-AXIS TARGET POSITION
502 M6402: NOP 0;
503 NETWORK
504 TITLE - MOVE Z-AXIS TO TOOL CHANGE POSITION
505 U M 12.0 // T-WORD IS VALID
506 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
507 U.M. 22.3 // Z-AXIS IS ON TARGET POSITION
```

```
S.M. 20.3. / / RETURN TOOL DONE
509 R M 22.3 // Z-AXIS IS ON TARGET POSITION
510 NETWORK
    TITLE - SPINDLE ENABLE AND AFG / EFG switch on
512 O DB3.DBX 0.2; // Message 7002 change tool
513 O DB1.DBX 1370.3; // RESET KEY PRESSED
514 O DB1.DBX 1440.0; // RESET TRIPPED
515 R M 94.7; // SPINDLE ENABLE T-WORD IS VALID
516 R M 90.5; // AFG / EFG T-WLOCATION IS VALID
517 R M 20.3 // RETURN TOOL DONE
518 R M 12.0 // T-WORD IS VALID
519 R.M.22.2.//.Z-AXIS.MOVE.TO.TARGET.POSITION.ACTIVE
520 NETWORK
521 TITLE -- Trigger MO and display message 7002 Change tool
522 U.M. 20.3 // RETURN TOOL DONE
523 SPBN M6403;
524 SET
525 = DB20.DBX 192.0; // M0 DYNAMIC
526 S DB3.DBX 0.2; // Message 7002 change tool
527 R M 20.3 // RETURN TOOL DONE
528 R M 12.0 // T-WORD IS VALID
529 M6403: NOP 0
530 NETWORK
531 TITLE - message 7002 Change tool after NC START delete
532 O DB1.DBX 1370.3; // RESET KEY PRESSED
533 O DB1.DBX 1440.0; // RESET TRIPPED
534 O DB20.DBX 3.6; // NC START REQUEST
535 O DB20.DBX 0.2; // FC NC-START
536 R DB3.DBX 0.2; // 7002 change tool
537 R M 12.0 // T-WORD IS VALID
538 END FUNCTION
539 FUNCTION FC 66: VOID
540 NAME: HANDWHEEL
541 BEGIN
542 NETWORK
543 TITLE = functions for handwheel
544 O DB20.DBX 326.5; // BA INC1 from Kern
545 O DB20.DBX 326.6; // BA INC10 from Kern
546 O DB20.DBX 326.7; // BA INC100 from Kern
547 O DB20.DBX 327.0; // BA INC1000 from Kern
548 = M 98.6; // Handwheel BA
549 U (;
550 O (;
551 U M 98.6; // Handwheel BA
552 UN M 98.7; // HM handwheel active
<del>553 );</del>
554 O.M. 98.0; // Fl. Select INC1
    O M 98.1; // Fl. Select INC10
556 O M 98.2; // Fl. Select INC100
557 O·M·98.3; // Fl. Select INC1000
559 = DB1.DBX 1440.2; // Handwheel selection
560 O DB1.DBX 1370.3; // RESET KEY PRESSED
561 O DB1.DBX 1440.0; // RESET TRIPPED
562 ON M 98.6; // Handwheel BA
563 U.M. 98.7; // HM handwheel active
564 - DB1.DBX 1440.3; // handwheel deselection
565 U DB1.DBX 1440.2; // Handwheel selection
566 S M 98.7; // HM handwheel active
567 U DB1.DBX 1440.3; // handwheel deselection
568 R M 98.7; // HM handwheel active
569 // Include INC increment when changing BA
570 U DB20.DBX 326.5; // BA INC1 from Kern
571 FP M 98.0; // Fl. Select INC1
```

```
572 IIN M 98 0:
573 SPB INC1;
574 L + 1.0E - 06;
575 T DB20.DBD 16; // INC increment
576 INC1: NOP 0;
577 U-DB20.DBX-326.6; // BA-INC10-from-Kern
578 FP M 98.1; // Fl. Select INC10
579 UN M 98.1;
580 SPB INC2;
581 L + 1.0E-05;
582 T.DB20.DBD.16; // INC increment
583 INC2: NOP 0;
584 U DB20.DBX 326.7; // BA INC100 from Kern
585 FP M 98.2; // Fl. Select INC100
586 UN M 98.2;
587 SPB INC3;
588 L + 1.0E - 04;
589 T DB20.DBD 16; // INC increment
590 INC3: NOP 0;
591 U DB20.DBX 327.0; // BA INC1000 from Kern
592 FP M 98.3; // Fl. Select INC1000
593 UN M 98.3;
594 SPB INC4;
595 L + 1.0E-03;
596 T.DB20.DBD.16; // INC increment
597 INC4: NOP 0;
598 END FUNCTION
599 FUNCTION FC 88: VOID
NAME: AUX ON AC95 / AC88 CONVERSION TO ACC
601 BEGIN
602 NETWORK 1
603 TITLE = ENABLE DIFFERENTIAL LINE DRIVER ON ACC MOTHERBOARD
604
     U M 110.3; // AUX-ON MANUAL
605 S.A.3.7; // ENABLE DIFFERENTIAL LINE DRIVER CYCLES FOR SM
606 UN M 110.3; // AUX-ON MANUAL
    L S5TIME # 1S; // 10X0.1S
607
608
     SE T 10;
609
    U T 10;
610 R A 3.7; // ENABLE DIFFERENTIAL LINE DRIVER CYCLES FOR SM
611 NETWORK 1
612
     TITLE = ALARM NOT_AUS AC95 CONVERSION TO ACC
613
     UN M 15.2; // EMERGENCY STOP SWITCH
614 S DB2.DBX 0.0; // ALARM EMERGENCY STOP
615 = DB1.DBX 1390.5; // PLC> SURF. EMERGENCY STOP SWITCH
    O DB1.DBX 1370.0; // 1st PLC LOOP
616
617
     O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
618
     O DB1.DBX 1370.3; // RESET KEY PRESSED
619
    R DB2.DBX 0.0; // ALARM EMERGENCY STOP
620
    NETWORK 2
621
     TITLE = MESSAGE MACHINE DOOR OPEN AC95 CONVERSION TO ACC
622
     U M 15.1; // MACHINE DOOR OPEN
623 UN DB3.DBX 6.2; // NO PART CLAMPED (M7050)
624 UN DB1.DBX 1370.0; // 1st PLC LOOP
    UN DB3.DBX 2.7; // MESSAGE 7023 WAITING TIME MAIN DRIVE
625
    UN DB3.DBX 0.2; // 7002 change tool
626
627
     = DB3.DBX 5.0; // MACHINE DOOR OPEN (7040)
628
    NETWORK 3
629
     TITLE = 6024 ALARM DOOR OPEN AC95 CONVERSION TO ACC
630
     O M 131.7; // AXES IN MOVEMENT
631
     O M 92.0; // ROUND AXIS IN MOVEMENT
U DB20.DBX 326.4; // AUTO OPERATING MODE
633
    = M 102.0; // HM
    U M 131.7; // AXES IN MOVEMENT
634
635
    U DB20.DBX 327.2; // REFERENCE OPERATING MODE
```

```
636
     = M 102.1; // HM
637
    U DB20.DBX 324.0; // PROGRAM RUNNING
638 UN DB20.DBX 324.1; // STOP STATE
U DB20.DBX 326.4; // AUTO OPERATING MODE
640 = M 102.2; // HM
     UN M 114.3; // ACTUAL SPEED LESS THAN 20RPM
641
642
    = M 102.3; // HM
643 O M 102.0; // HM
644 O M 102.1; // HM
645 O M 102.2; // HM
646
    O M 102.3; // HM
647
    = M 110.2; // HM DOOR ALARM
648 U M 110.2; // HM DOOR ALARM
049 U M 15.1; // MACHINE DOOR OPEN
650
    S DB2.DBX 3.0; // 6024 ALARM DOOR OPEN
651
     O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
O DB1.DBX 1370.3; // RESET KEY PRESSED
653 R DB2.DBX 3.0; // 6024 ALARM DOOR OPEN
654
    NETWORK 4
655
     TITLE = SUM ALARMS 1 AC95 CONVERSION TO ACC
656 L DB2.DBW 0; // WORD ALARMS 1
657 LW#16#0;
658
   <> I;
    = M 105.0; // SUM ALARMS1
659
660 NETWORK 5
TITLE = SUM ALARMS 2 AC95 CONVERSION TO ACC
662 L DB2.DBW 2; // WORD ALARMS 2
663
    LW#16#0;
    <> I;
664
665 = M 105.1; // SUM ALARMS 2
666 NETWORK 6
TITLE = SUM THERMAL ALARMS AC95 CONVERSION TO ACC
     L DB2.DBW 4; // BYTE / THERM. ALARMS
668
669
   LW#16#0;
670 <> I;
671 = M 105.2; // SUM THERM. ALARMS
672
    NETWORK 7
     TITLE = SELECTION AUX ON AC95 CONVERSION TO ACC
673
674 U DB1.DBX 1370.0; // 1st PLC LOOP
675 S M 110.1; // AUX_ON ON
676
    U M 110.1; // AUX_ON ON
677
     = DB1.DBX 1390.2; // PLC> SURFACE AUX-ON
678
    S M 110.0; // AUX_ON AUTO
679 S M 110.3; // AUX-ON MANUAL
680 NETWORK 8
681
     TITLE = DESELECT AUX_ON AC95 CONVERSION TO ACC
682 O M 105.0; // SUM ALARMS 1
683 O M 105.1; // SUM ALARMS 2
684 O M 105.2; // SUM THERM. ALARMS
685
     O DB1.DBX 1366.3; // ALARM ACTIVE
686
    R M 110.3; // AUX-ON MANUAL
687 UN M 110.3; // AUX-ON MANUAL
688 O M 15.1; // MACHINE DOOR OPEN
    O M 18.3; // EXIT FLAG DOOR OPEN
689
690
    O DB1.DBX 1366.3; // ALARM ACTIVE
691 R M 110.0; // AUX-ON AUTO
692 NETWORK 9
693
    TITLE = HW CHECK DOOR OPEN AC95 CONVERSION TO ACC (ALARM 6009)
694
     U M 15.1; // MACHINE DOOR OPEN
695
    L S5TIME # 1S; // 10X0.1S
696 SE T 6; // T6 SWITCH-ON DELAYED
697
    U T 6; // T6
698
    U M 15.0; // MACHINE DOOR CLOSED (MAIN MOTOR CONTACTOR ON)
699
     S DB2.DBX 1.1; // HW ERROR SAFETY CIRCUIT
```

```
700
     NETWORK 10
701
     TITLE = HW REVIEW CLOSE DOOR AC95 CONVERSION TO ACC
702 UN DB1.DBX 1370.0; // 1st PLC LOOP
703 UN M 15.1; // MACHINE DOOR OPEN
704 U M 15.2; // EMERGENCY STOP SWITCH
705
     U M 15.6; // WHEEL COVER CLOSED
706
    L S5TIME # 1S; // 10X0.1S
707 SE T 11; // T11 SWITCH-ON TV.
708 U T 11; // T11
709
    UN M 15.0; // MACHINE DOOR CLOSED (MAIN MOTOR CONTACTOR ON)
710
     S DB2.DBX 1.1; // HW ERROR SAFETY CIRCUIT
     O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
711
712
     O DB1.DBX 1370.3; // RESET KEY PRESSED
713
    R DB2.DBX 1.1; // HW ERROR SAFETY CIRCUIT
714
      END FUNCTION
715
    FUNCTION FC 41: VOID
716 NAME: RENISHAW PROBE
717
    BEGIN
718
     // X6: 9 A 3.5 // ACTIVATE RENISHAW PROBE MI 12 INTERFACE
719
     // X6: 8 E 6.2 // STATUS RENISHAW PROBE MI 12 INTERFACE
720
    // X6: 9 E 6.3 // \ STATUS RENISHAW PROBE MI 12 INTERFACE
721
     //·X6: 10·I·6.4·//·NO·ERROR·RENISHAW·PROBE·MI·12·INTERFACE·(24VDC·IF·NO·ERROR)
722
     // X6: 11 E 6.5 // LOW BATT RENISHAW PROBE MI 12 INTERFACE (24VDC IF BATTERY LOW)
723
     NETWORK
724
    TITLE = PROBE PRESENT
725 O E 6.2 // STATUS RENISHAW PROBE MI 12 INTERFACE
726 O E 6.3 // \ STATUS RENISHAW PROBE MI 12 INTERFACE
727
     = M 11.0 // RENISHAW PROBE MI 12 INTERFACE AVAILABLE
728
     NETWORK
729
     TITLE = ACTIVATE RENISHAW PROBE MI 12 INTERFACE
730 U DB20.DBX 328.4 // MEASURE REQUIREMENTS
731
     UN DB2.DBX 2.5; // (A6021) OPTICAL CONNECTION INTERRUPTED
732
     U E 6.2 // STATUS RENISHAW PROBE MI 12 INTERFACE
733
    UN E 6.3 // \ STATUS RENISHAW PROBE MI 12 INTERFACE
734 O M 11.4 // HM RENISHAW PROBE MI 12 SWITCH OFF INTERFACE
735 O M 11.5 // CANCEL FLAG RESET KEY PRESSED
736
     L S5TIME # 200MS; // 200MS
737
     SV T 16; // LONGER PULSE
738
    U T 16; // LONGER PULSE
739
    = A 3.5 // ACTIVATE RENISHAW PROBE MI 12 INTERFACE
740
     UN T 16; // LONGER PULSE
741
     ; R T 17;
742
    R M 11.4 // HM RENISHAW SWITCH OFF PROBE MI 12 INTERFACE
743 U A 3.5 // ACTIVATE RENISHAW PROBE MI 12 INTERFACE
744
    U DB20.DBX 328.4 // MEASURE REQUIREMENTS
745
     S M 11.1 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED
746
     U M 11.1 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED
747
     UN E 6.2 // STATUS RENISHAW PROBE MI 12 INTERFACE
748
     U E 6.3 // \ STATUS RENISHAW PROBE MI 12 INTERFACE
749
     U E 6.4 // NO ERROR RENISHAW PROBE MI 12 INTERFACE
     R M 11.1 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED
750
751
     S M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
752 NETWORK
753
     TITLE = ACC RELEASE MEASURE
754
     U M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
755
     S DB20.DBX 343.7 // ACC RELEASE MEASURE
756
    NETWORK
757
     TITLE = END MEASUREMENT
758
     U M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
759
     U E 6.4 // NO ERROR RENISHAW PROBE MI 12 INTERFACE
760 U·E·6.2·//·STATUS·RENISHAW·PROBE·MI·12·INTERFACE
761
     UN E 6.3 // \ STATUS RENISHAW PROBE MI 12 INTERFACE
762
    R M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
763
     R T 17;
```

```
764
      S M 11.3 // RENISHAW MEASUREMENT COMPLETED WITHOUT ERRORS
765
     UN DB20.DBX 328.4 // MEASURE REQUIREMENT
766
     U M 11.3 // RENISHAW MEASUREMENT COMPLETED WITHOUT ERRORS
767
     ON M 11.0 // RENISHAW PROBE MI 12 INTERFACE AVAILABLE
768
     R DB20.DBX 343.7 // ACC RELEASE MEASURE
769
      R M 11.3 // RENISHAW MEASUREMENT COMPLETED WITHOUT ERRORS
770
      S M 11.4 // HM RENISHAW PROBE MI 12 SWITCH OFF INTERFACE
771
     UN E 6.2 // STATUS RENISHAW PROBE MI 12 INTERFACE
772
     U E 6.3 // \ STATUS RENISHAW PROBE MI 12 INTERFACE
773
     U E 6.4 // NO ERROR RENISHAW PROBE MI 12 INTERFACE
774
     UN M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
775
     UN DB1.DBX 1370.3; // RESET KEY PRESSED
776
     FP M 11.5 // CANCEL FLAG RESET KEY PRESSED
777
     NETWORK
778
      TITLE = CANCEL MEASUREMENT
779
      O M 11.1 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED
780
     O M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
781
     O M 11.3 // RENISHAW MEASUREMENT COMPLETED WITHOUT ERRORS
782
     U DB1.DBX 1370.3; // RESET KEY PRESSED
783
     R M 11.1 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED
784
     R M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
785
     R M 11.3 // RENISHAW MEASUREMENT COMPLETED WITHOUT ERRORS
786
     R DB20.DBX 343.7 // ACC RELEASE MEASURE
787
      S M · 11.4 · // · HM · RENISHAW · PROBE · MI · 12 · SWITCH · OFF · INTERFACE
788
    R T 17;
789
    NETWORK
790 TITLE = (A6021) OPTICAL LINK LOSSED
791
      ; U M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
792
     U M 11.1 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED
793
     L S5TIME # 100S; // 200M SECONDS
794
    SS T 17;
795
     U T 17;
796
     UN E 6.4 // NO ERROR RENISHAW PROBE MI 12 INTERFACE
797
      S DB2.DBX 2.5; // (A6021) OPTICAL CONNECTION INTERRUPTED
798 R M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
799
    R T 17;
800
      O DB1.DBX 1370.3; // RESET KEY PRESSED
801
     R DB2.DBX 2.5; // (A6021) OPTICAL CONNECTION INTERRUPTED
802
    NETWORK
     TITLE = 7044 PROBE BATTERY LOW
803
804
      U M 11.2 // RENISHAW PROBE MI 12 INTERFACE ACTIVATED AND READY
805
     U E 6.5 // LOW BATT RENISHAW PROBE MI 12 INTERFACE
806
      S DB3.DBX 5.4; // 7044 PROBE BATTERY LOW
807
     U DB1.DBX 1370.3; // RESET KEY PRESSED
     R DB3.DBX 5.4; // 7044 PROBE BATTERY LOW
808
809
     END_FUNCTION
810
     FUNCTION FC 49: VOID
811
     NAME: ENTER TOOL POSITIONS IN MILL55_ACC.MSD
812
813
      // CTR 1 DB20.DBX 294.5 ACCEPT POSITION FOR TOOL 1
814
      // CTR 2 DB20.DBX 294.6 ACCEPT POSITION FOR TOOL 2
815
     // CTR 3 DB20.DBX 294.1 ACCEPT POSITION FOR TOOL 3
816
     // CTR 4 DB20.DBX 295.1 ACCEPT POSITION FOR TOOL 4
817
      // CTR 5 DB20.DBX 295.2 ACCEPT POSITION FOR TOOL 5
818
     // CTR 6 DB20.DBX 295.3 ACCEPT POSITION FOR TOOL 6
819
     // CTR 7 DB20.DBX 295.4 ACCEPT POSITION FOR TOOL 7
820
     // CTR 8 DB1.DBX 1374.4 ACCEPT POSITION FOR TOOL 8
821
     // CTR & DB1.DBX 1374.3 POSITION FOR Z-AXIS T1-T8 ADOPT EXPRESSION AND RECOVERY POSITION
822
      NETWORK
823
      TITLE = APPLY POSITION FOR TOOL 1
824
    U DB20.DBX 294.5 // "CTR 1" KEY ADOPT POSITION FOR TOOL 1
825
     SPBN M001;
826
      L 1 // SWIVELED TOOL
```

827

T DB20.DBW 356 // TRANSFER CURRENT TOOL NUMBER

```
L DB1.DBD 16 // LOAD THE ACTUAL POSITION FROM ABSOLUTE AXIS 4
828
829
     L + 1.0E + 03; // MULTIPLE BY 1000
830
     * R;
    T DB10.DBD 32 // WRITE THE ACTUAL POSITION INTO THE MSD DATA
831
832 S DB20.DBX 4.2 // COMMAND-BIT 2
833
     M001: NOP 0;
834
     NETWORK
835 TITLE = APPLY POSITION FOR TOOL 2
836 U DB20.DBX 294.6 // "CTR 2" KEY ADOPT POSITION FOR TOOL 2
837
     SPBN M002;
838
     L 2 // SWIVELED TOOL
839
    T DB20.DBW 356 // TRANSFER CURRENT TOOL NUMBER
840 L DB1.DBD 16 // LOAD THE ACTUAL POSITION FROM ABSOLUTE AXIS 4
841
    L + 1.0E + 03; // MULTIPLE BY 1000
842
     * R;
     T DB10.DBD 36 // WRITE THE ACTUAL POSITION INTO THE MSD DATA
843
844
     S DB20.DBX 4.2 // COMMAND-BIT 2
845
    M002: NOP 0;
846
     NETWORK
847
     TITLE = ACCEPT POSITION FOR TOOL 3
848
    U DB20.DBX 294.1 // "CTR 3" KEY ADOPT POSITION FOR TOOL 3
849
    SPBN M003;
850 L 3 // SWIVELED TOOL
851
     T DB20.DBW 356 // TRANSFER CURRENT TOOL NUMBER
852
     L DB1.DBD 16 // LOAD THE ACTUAL POSITION FROM ABSOLUTE AXIS 4
853 L + 1.0E + 03; // MULTIPLE BY 1000
854
     * R;
855
     T DB10.DBD 40 // WRITE THE ACTUAL POSITION INTO THE MSD DATA
     S DB20.DBX 4.2 // COMMAND-BIT 2
856
857
    M003: NOP 0;
858
    NETWORK
859
    TITLE = ADOPT POSITION FOR TOOL 4
860
     U DB20.DBX 295.1 // "CTR 4" KEY ADOPT POSITION FOR TOOL 4
861 SPBN M004;
862 L 4 // SWIVELED TOOL
T DB20.DBW 356 // TRANSFER CURRENT TOOL NUMBER
     L DB1.DBD 16 // LOAD THE ACTUAL POSITION FROM ABSOLUTE AXIS 4
864
    L + 1.0E + 03; // MULTIPLE BY 1000
865
866
     * R;
```

T DB10.DBD 44 // WRITE THE ACTUAL POSITION INTO THE MSD DATA

U DB20.DBX 295.2 // "CTR 5" KEY ADOPT POSITION FOR TOOL 5

L DB1.DBD 16 // LOAD THE ACTUAL POSITION FROM ABSOLUTE AXIS 4

T DB10.DBD 48 // WRITE THE ACTUAL POSITION INTO THE MSD DATA

L DB1.DBD 16 // LOAD THE ACTUAL POSITION FROM ABSOLUTE AXIS 4

T DB20.DBW 356 // TRANSFER CURRENT TOOL NUMBER

S DB20.DBX 4.2 // COMMAND-BIT 2

TITLE = APPLY POSITION FOR TOOL 5

L + 1.0E + 03; // MULTIPLE BY 1000

S DB20.DBX 4.2 // COMMAND-BIT 2

TITLE = APPLY POSITION FOR TOOL 6

L + 1.0E + 03; // MULTIPLE BY 1000

// "CTR 6" KEY ADOPT POSITION FOR TOOL 6

888 T DB20.DBW 356 // TRANSFER CURRENT TOOL NUMBER

M004: NOP 0;

SPBN M005;

M005: NOP 0;

884 U DB20.DBX 295.3

SPBN M006;

L 6 // SWIVELED TOOL

NETWORK

\* R;

L 5 // SWIVELED TOOL

867

868 869

871

872

873

874

875

876

877

878 879

881

882

883

885 886

887

889

890

891

880

870 NETWORK

```
T DB10.DBD 52 // WRITE THE ACTUAL POSITION INTO THE MSD DATA
892
893
     S DB20.DBX 4.2 // COMMAND-BIT 2
    M006: NOP 0;
894
895
     NETWORK
896
     TITLE = APPLY POSITION FOR TOOL 7
897
     U DB20.DBX 295.4 // "CTR 7" KEY ADOPT POSITION FOR TOOL 7
898
      SPBN M007;
899 L 7 // SWIVELED TOOL
900 T DB20.DBW 356 // TRANSFER CURRENT TOOL NUMBER
      \texttt{L} \cdot \texttt{DB1.DBD} \cdot \texttt{16} \cdot \texttt{//} \cdot \texttt{LOAD} \cdot \texttt{THE} \cdot \texttt{ACTUAL} \cdot \texttt{POSITION} \cdot \texttt{FROM} \cdot \texttt{ABSOLUTE} \cdot \texttt{AXIS} \cdot \texttt{4}
901
902
      L + 1.0E + 03; // MULTIPLE BY 1000
903
      * R;
904
     T DB10.DBD 56 // WRITE THE ACTUAL POSITION INTO THE MSD DATA
905 S DB20.DBX 4.2 // COMMAND-BIT 2
906
      M007: NOP 0;
907
     NETWORK
908 TITLE = ACCEPT POSITION FOR TOOL 8
909 U DB1.DBX 1374.4 // "CTR 8" KEY ADOPT POSITION FOR TOOL 8
910 SPBN M008;
911
      L 8 // SWIVELED TOOL
912
     T DB20.DBW 356 // TRANSFER CURRENT TOOL NUMBER
913
    L DB1.DBD 16 // LOAD THE ACTUAL POSITION FROM ABSOLUTE AXIS 4
914
     L + 1.0E + 03; // MULTIPLE BY 1000
915
916
      T DB10.DBD 60 // WRITE ACTUAL POSITION INTO THE MSD DATA
917
      S DB20.DBX 4.2 // COMMAND-BIT 2
918 M008: NOP 0;
919
     NETWORK
     TITLE = POSITION FOR Z-AXIS T1-T8 EXPRESSION AND ADOPT INPUT POSITION
920
921 U DB1.DBX 1374.3 // Z-AXIS T1-T8 EXPRESSION AND INPUT POSITION
922 SPBN M009;
923
     L 14 // SWIVELED TOOL
924
      T DB20.DBW 356 // TRANSFER CURRENT TOOL NUMBER
925
      L DB1.DBD 8 // LOAD THE ACTUAL POSITION FROM ABSOLUTE AXIS 2
926 T DB10.DBD 84 // WRITE THE ACTUAL POSITION INTO THE MSD DATA
927
     S DB20.DBX 4.2 // COMMAND-BIT 2
928
     M009: NOP 0;
929
     END FUNCTION
930 FUNCTION FC 50: VOID
931 NAME: TOOL TURNERS
932
    BEGIN
933
      ; MD 28 Z-AXIS TARGET POSITION
934
    ; MD 32 A-AXIS POSITION FOR CLAMPED TOOL
935
    ; MD 36 NEW A-AXIS POSITION
936
     ; MW 40 NEW TOOL FROM VALID T-WORD
937
      ; MW 42 CLAMPED TOOL FROM THE SETTING DATA
938
     ; MW 44 RESULTS OF TOOL HOLDER INSPECTION (TOOL HOLDER FREE)
939
     ; MW · 46 · TOOL · EQUIPMENT · (RESULTS · WHEN · EXTENDING · THE · TOOL · DISC · FROM · 12mm · BERO)
940
     ; MD 64 Z-AXIS T1-T8 EXPRESSION AND INPUT POSITION
941
      ; MD 74 Z-AXIS TOOL SWIVEL POSITION NO TOOL IN THE SPINDLE
      ; MD 78 Z-AXIS 1MM UNDER SW LIMIT SWITCH
943
     ; L DB10.DBD 80; // Z-AXIS T1-T8 EXPRESSION AND INSERTION POSITION
944
    ; L DB10.DBD 88; // Z-AXIS TOOL SWIVEL POSITION NO TOOL IN THE SPINDLE
      ; L DB10.DBD 92; // Z-AXIS 1MM UNDER SW LIMIT SWITCH
945
946
     NETWORK
     TITLE - CALCULATING THE Z-AXIS T1-T8 EXPRESSION AND INSERTION POSITION
947
948
    L DB10.DBD 84; // Z-AXIS TOOL GRIPPER POSITION FOR T1
949
    L + 5.0E - 03;
950
951
      T MD 64; // Z-AXIS T1-T8 EXPRESSION AND INSERTION POSITION
952 NETWORK
953 TITLE = CALCULATING THE Z-AXIS TOOL SWIVEL POSITION NO TOOL IN THE SPINDLE
954
    L DB10.DBD 84; // Z-AXIS TOOL GRIPPER POSITION FOR T1
955
     L + 7.5E - 02; // 75 MM
```

```
956
 957
      T MD 74; // Z-AXIS TOOL SWIVEL POSITION NO TOOL IN THE SPINDLE
 958
     NETWORK
 959
     TITLE = CALCULATE THE Z-AXIS 1MM UNDER THE SW LIMIT SWITCH
 960 L DB10.DBD 84; // Z-AXIS TOOL GRIPPER POSITION FOR T1
 961
      L + 1.4E-01; // 140 MM
 962
      + \cdot R
 963 T MD 78; // Z-AXIS 1MM UNDER SW LIMIT SWITCH
 964 ; M 27.0 TOOL RETRACTED
 965
      ; M 27.1 TOOL EXPRESSED
 966
      ; M 53.0 M70 EXPRESS TOOL
 967
     ; PULL IN THE M 53.1 M72 TOOL
 968 ; DB15.DBW 25 (IN BITS FROM 0 TO 8) CLAMPED TOOL IN THE SETTING DATA
 969 NETWORK
 970
      TITLE = SET ABORT FLAG FROM THE SETTING DATA
 971 U DB1.DBX 1370.0; // 1st PLC LOOP
 972 U DB15.DBX 20.0 // SAVE TOOL ABORTED IN THE SETTING DATA
 973 S M 52.3 // TOOL CANCELED
 974
     NETWORK
 975
      TITLE = WZW AFG / EFG and NC START VERR.
 976 L DB1.DBD 16 // ABSOLUTE AXIS 4 ACTUAL POSITION
 977 L + 0.00E-00;
 978
     == · R
 979
      = M 26.0 // ABSOLUTE AXIS 4 (TOOL) 0 DEGREES REACHED
     UN M 26.0 // ABSOLUTE AXIS 4 (TOOL) 0 DEGREES REACHED
 980
 981 U DB1.DBX 134.4; // REFERENCE POINT TOOL AXIS ACTIVE
982 UN DB10.DBX 100.0 // SET TOOL MILL55 ENABLED
 983
      = M 90.2; // ABSOLUTE AXIS 4 (TOOL) 0 DEGREES REACHED AFG / EFG
     = M 96.0; // ABSOLUTE AXIS 4 (TOOL) 0 DEGREES REACHED NC START LOCK.
 984
 985
     NETWORK
 986 TITLE = TOOL ENABLE
 987
     U M 26.0 // ABSOLUTE AXIS 4 (TOOL) 0 DEGREES REACHED
 988
      U M 120.2 // TOOL AXIS 0 DEGREES REACHED
     O M 25.0 // TOOL O PICK UP DONE
 989
 990 O DB10.DBX 100.0 // SET TOOL MILL55 ACTIVATED
991 UN M 94.0; // AUX-ON SFG
 992
      U M 52.2 // REFERENCE POINT X, Y, Z AND TOOL C-AXIS ACTIVE
 993
     UN M 52.0; // TOOL TURNING ACTIVE
 994
     UN M 52.3 // TOOL ABORTED
 995 UN DB3.DBX 6.7; // MESSAGE 7055 OPEN TOOL CLAMPING SYSTEM
      UN DB3.DBX 7.0; // MESSAGE 7056 ILLEGAL TOOL NUMBER IN THE SETTING DATA
 996
 997
      UN DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
998
     UN DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
999 U DB25.DBX 340.4; // AXLE ENABLE K1
1000 U DB25.DBX 340.3; // READ RELEASE
1001
     K1
1002 = M 27.5; // TOOL ENABLE
1003 FP M 52.1 // FM TOOL ENABLE
1004 UN M 27.5; // TOOL ENABLE
1005
      = M 96.1 // NC START VERR.
1006
      U M 52.1 // FM TOOL ENABLE
1007 R M 94.7; // SPINDLE ENABLE T-WORD IS VALID
1008 R M 90.5; // AXLE RELEASE T-WORD IS VALID
1009
     NETWORK
1010
      TITLE = SET TOOL POSITION FROM THE SETTING DATA
1011
1012 U M 27.5; // TOOL ENABLE
1013
     U DB20.DBX 182.0 // NEW T-WORD (TOOL)
1014
1015
      O DB1.DBX 1370.0; // 1st PLC LOOP
1016 CC FC 52; // SET TOOL POSITION FROM THE SETTING DATA
1017
     NETWORK
1018
      CLEAR TITLE = MESSAGE "7000 WRONG T-WORD"
1019
     U DB1.DBX 1370.3; // RESET KEY PRESSED
```

```
R DB3.DBX 0.0; // 7000 WRONG T-WORD
1020
1021
     NETWORK
1022 TITLE = CHECK NEW T-WORD
1023 U M 27.5; // TOOL ENABLE
1024 U DB20.DBX 182.0 // NEW T-WORD (TOOL)
1025
      UN M 20.2 // ILLEGAL TOOL NUMBER IN THE SETTING DATA
1026 CC ·FC · 53; · // · CHECK · NEW ·T-WORD · AND · DETERMINE · NEW · TOOL · DISC · POSITION
1027 NETWORK
1028 TITLE = T-WORD IS VALID AND STOP THE MAIN SPINDLE
1029 U M 27.5; // TOOL ENABLE
1030 U DB20.DBX 182.0 // NEW T-WORD (TOOL)
1031 U M 22.6 // T-WORD DOES NOT EQUAL TOOLS
1032 UN DB3.DBX 6.7; // MESSAGE 7055 OPEN TOOL CLAMPING SYSTEM
1033 S M 94.7; // SPINDLE ENABLE T-WORD IS VALID
1034
     S M 90.5; // AFG / EFG T-WORD IS VALID
1035
     S M 20.6; // T-WORD IS VALID
1036 R M 22.7 // NEW T-WORD SAVED FOR MESSAGE 7001
1037
     NETWORK
1038
      TITLE = "7055 OPEN TOOL CLAMPING SYSTEM" AND DELETE "7057 TOOL HOLDER OCCUPIED"
1039
     U M 27.1 // TOOL EXPRESSED
1040 R DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
1041 NETWORK
1042 TITLE \cdot = \cdot START \cdot TOOL \cdot TURNING \cdot WHEN \cdot THE \cdot HS \cdot SPEED \cdot IS \cdot LESS \cdot 20 \cdot RPM
1043
     U M 20.6; // T-WORD IS VALID
1044 U M 114.3; // HA ACTUAL SPEED LESS THAN 20RPM
1045 S M 20.7; // TOOL TURNERS START FROM VALID T-WORD
1046 R M 20.6; // T-WORD IS VALID
1047
     NETWORK
     TITLE = CANCEL TURNING TOOL IF PROCESS NOT YET STARTED
1048
1049 O DB1.DBX 1370.3; // RESET KEY PRESSED
1050 O DB1.DBX 1440.0; // RESET RELEASED
1051 U M 20.6; // T-WORD IS VALID
1052
     UN M 20.7; // TOOL TURNERS START FROM VALID T-WORD
1053 R M 94.7; // SPINDLE ENABLE T-WORD IS VALID
1054 R M 90.5; // AFG / EFG T-WORD IS VALID
1055 R M 20.6; // T-WORD IS VALID
1056
      NETWORK
1057
      TITLE = CLEAR TOOL CONE CANCEL
1058 O DB1.DBX 1370.3; // RESET KEY PRESSED
1059 O DB1.DBX 1440.0; // RESET RELEASED
1060 O DB1.DBX 1366.3; // ALARM ACTIVE
1061
       O DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
1062 R A 6.1 // BLOW OFF THE TOOL CONE
1063 NETWORK
1064 TITLE = TOOL TURNING STARTED SAVE IN THE SETTING DATA
1065
     U M 20.7; // TOOL TURNERS START FROM VALID T-WORD
1066 FP M 52.4
1067 U M 52.4
1068 S DB15.DBX 20.0 // SAVE TOOL ABORTED IN THE SETTING DATA
1069 = DB20.DBX 348.3; // REQUEST FOR IMMEDIATE SETTING DATA BACKUP
1070 NETWORK
1071 TITLE = X / Y - AXIS MOVE OUT WITH ACTIVATED ROUND AXIS
1072 U M 52.7 // ROUND AXIS ACTIVATED
1073
     SPBN M111;
1074
     NETWORK
1075
     TITLE = X / Y - SAVE AXIS ACTUAL POSITION
1076 U M 20.7; // TOOL TURNERS START FROM VALID T-WORD
1077 UN M 23.7 // Y-AXIS MOVE TO TARGET POSITION ACTIVE
1078
      UN M 23.5 // HM Y-AXIS MOVE TO TARGET POSITION ACTIVE
1079
     SPBN M002;
1080 L DB1.DBD 4 // Actual position for axis 1 (Y)
1081
      T MD 56 // Actual position for axis 1 (Y)
1082
       L DB1.DBD 0 // Actual position for axis 1 (X)
```

1083

T MD 60 // Actual position for axis 1 (X)

```
1084
     M002: NOP 0;
1085
     NETWORK
1086 TITLE = X · / · Y · - MOVE · AXIS · TO · SOFTWARE · END · SWITCH
1087 U.M. 20.7; // TOOL TURNERS START FROM VALID T-WORD
1088 UN M 23.7 // Y-AXIS MOVE TO TARGET POSITION ACTIVE
1089 UN·M·23.5·// HM·Y-AXIS·MOVE·TO·TARGET·POSITION·ACTIVE
1090 SPBN M003;
1091 S M 23.7 // Y-AXIS MOVE TO TARGET POSITION ACTIVE
1092 ; S DB25.DBX 340.3; // READ-IN ENABLE K1
1093 ; S DB25.DBX 340.4; // AXLE ENABLE K1
     = DB25.DBX 1.4; // SEND NC BLOCK
1094
1095 = DB25.DBX 548.7 // GO is triggered
1096 = DB25.DBX 548.5; // SET EXACT HOLD MODE
1097 = DB25.DBX 20.0; // POSITION REQUEST FOR X-AXIS
1098 = DB25.DBX 20.1; // POSITION REQUEST FOR Y-AXIS
1099
     L DB20.DBD 482 // MAX. SW LIMIT SWITCH FOR Y-AXIS FLOAT VALUE IN M
1100 T DB25.DBD 26; // POSITION VALUE FOR Y-AXIS
1101 L.DB20.DBD.414.//MIN.SW.LIMIT.SWITCH.FOR.X-AXIS.FLOAT.VALUE.IN.M
1102
     T DB25.DBD 22; // POSITION VALUE FOR X-AXIS
1103
     M003: NOP 0;
1104 U DB25.DBX 332.0; // NC BLOCK DONE
1105 U M 20.7; // TOOL TURNERS STARTED FROM VALID T-WORD
1106 S M 23.5 // HM Y-AXIS MOVE TO TARGET POSITION ACTIVE
1107
     R M 23.7 // Y-AXIS MOVE TO TARGET POSITION ACTIVE
1108 NETWORK
1109 TITLE = X / Y - MOVE AXIS TO LISTED POSITION
1110 U·M·26.0·//·ABSOLUTE·AXIS·4·(TOOL)·0·DEGREES·REACHED
1111
      U M 21.5 // STEP 5
1112 U.M. 20.7; // TOOL TURNERS STARTED FROM VALID T-WORD
1113 UN M 21.6 // Y-AXIS MOVE TO TARGET POSITION ACTIVE
1114 SPBN M004;
1115 S M 21.6 // Y-AXIS MOVE TO TARGET POSITION ACTIVE
     ; S DB25.DBX
1116
1117 340.3; // READ-IN ENABLE K1
1118 ; S DB25.DBX 340.4; // AXLE ENABLE K1
1119 = DB25.DBX 1.4; // SEND NC BLOCK
1120 = DB25.DBX 548.7 // GO is triggered
1121 = DB25.DBX 548.5; // SET EXACT HOLD MODE
1122 = DB25.DBX 20.0; // POSITION REQUEST FOR X-AXIS
= DB25.DBX 20.1; // POSITION REQUEST FOR Y-AXIS
1124 L MD 56 // Actual position for axis 1 (Y)
1125
      T DB25.DBD 26; // POSITION VALUE FOR Y-AXIS
1126 L MD 60 // Actual position for axis 1 (X)
1127 T DB25.DBD 22; // POSITION VALUE FOR X-AXIS
1128 M004: NOP 0;
1129
     U DB25.DBX 332.0; // NC BLOCK DONE
1130 U·M·20.7; ·//·TOOL·TURNERS·STARTED·FROM·VALID·T-WORD
1131 U.M. 21.6.// Y-AXIS MOVE TO TARGET POSITION ACTIVE
1132 S M 26.2; // HM X / Y-AXIS TARGET POSITION REACHED
1133 U M 26.2; // HM X / Y-AXIS TARGET POSITION REACHED
1134 L S5TIME # 500MS;
1135 SE T 15; // T15 SWITCH-ON DELAYED
1136 U T 15; // T15 SWITCH-ON DELAYED
1137 S M 20.4 // PICK UP TOOL DONE
     R M 26.2; // HM X / Y-AXIS TARGET POSITION REACHED
1138
1139 M111: NOP 0;
1140 NETWORK
1141 TITLE = RETURN TOOL
     U M 20.7; // TOOL TURNERS STARTED FROM VALID T-WORD
1142
1143 UN M 20.3 // RETURN TOOL DONE
1144 SPBN M005;
1145 U M 42.1 // TOOL 1 CLAMPED
1146 CC FC 54 // RETURN TOOL 1
```

1147 SPB M005;

```
1148
      O M 20.1 // TOOL EXPRESSED AND NO TOOL NUMBER STORED
1149
     O M 42.0 // TOOL O CLAMPED
1150 CC·FC·55·// RETURN·TOOL·0·OR·NO·TOOL
1151 SPB M005;
1152 CALL FC 56 // RETURN TOOLS 2 TO 8
1153 M005: NOP 0;
1154 NETWORK
1155 TITLE = PICK UP NEW TOOL
1156 U M 20.7; // TOOL TURNERS STARTED FROM VALID T-WORD
1157 U M 20.3 // RETURN TOOL DONE
     UN M 20.4 // PICK UP TOOL DONE
1158
1159 SPBN M006;
1160 U M 40.1 // TOOL 1 SELECTED
1161 CC FC 57 // PICK UP TOOL 1
     SPB M006;
1162
1163 U M 40.0 // TOOL 0 SELECTED
1164 CC FC 58 // PICK UP TOOL 0
1165 SPB M006;
1166 CALL FC 59 // PICK UP TOOLS 2 TO 8
1167
     M006: NOP 0;
1168 NETWORK
1169 TITLE = END TOOL TURNING
1170 U M 20.4 // PICK UP TOOL DONE
1171
      O M 26.1 // NEW T-WORD IS TOOLS
1172 SPBN M007;
1173 L DB20.DBW 184; // LOAD T-WORD
1174 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1175 L 0
1176 T MD 20
1177 R DB15.DBX 20.0 // SAVE TOOL ABORTED IN THE SETTING DATA
1178 L MW 40 // MW 40
1179 T DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1180
     = DB20.DBX 348.3; // REQUEST FOR IMMEDIATE SETTING DATA BACKUP
1181 R M 90.5; // AFG / EFG T-WORD IS VALID
1182 R M 94.7; // SPINDLE ENABLE T-WORD IS VALID
1183 M007: NOP 0;
1184
     NETWORK
     TITLE = TOOL TURNING ACTIVE
1185
1186 L MB 20; // STEP CHAIN
1187 L 0;
1188
      <> I;
1189
     = M 52.0; // TOOL TURNING ACTIVE
1190 NETWORK
1191 TITLE = CANCEL TOOL TURNING
1192 U M 52.0; // TOOL TURNING ACTIVE
1193
     U · (
ON A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
1195 O DB2.DBX 0.0; // ALARM EMERGENCY STOP
1196 O DB1.DBX 1370.3; // RESET KEY PRESSED
1197
      O DB1.DBX 1440.0; // RESET TRIPPED
1198
      )
1199 0(
1200 U E 16.4 // REF BERO WZW
1201
      U DB1.DBX 1370.0; // 1st PLC LOOP
1202
      )
1203
     0(
1204 U E 16.4 // REF BERO WZW
1205 U.M. 120.5 // FM. OUTPUT FOR AUXILIARY RELAY DOOR CLOSED
1206
1207
     SPBN M001;
1208 L 0
1209 T MD 20 // TOOL STEP MARKER
1210 S M 52.3 // TOOL CANCELED
1211
     R M 94.7; // SPINDLE ENABLE T-WORD IS VALID
```

```
1212 R M 90.5; // AFG / EFG T-WORD IS VALID
1213 R M 26.2; // HM X / Y-AXIS TARGET POSITION REACHED
1214 M001: NOP 0;
1215 NETWORK
1216 TITLE = MELDUNG 7058 AXES RELEASE
1217 U E 16.4 // REF BERO WZW
     U M 120.5 // FM OUTPUT FOR AUXILIARY RELAY DOOR CLOSED
1218
1219 0(
1220 ON M 26.0 // ABSOLUTE AXIS 4 (TOOL) 0 DEGREES REACHED
      O E 16.4 // REF BERO WZW
1221
     U M 52.3 // TOOL ABORTED
1222
1223
     )
1224 O(;
1225 U M 25.0 // TOOL 0 DONE DONE
1226
      UN DB10.DBX 75.2; // RETRACT IN THE DISC AT TO TOOL
1227 );
1228 FP M 25.1
1229 U M 25.1
1230 UN DB3.DBX 6.7; // MESSAGE 7055 OPEN TOOL CLAMPING SYSTEM
1231 SPBN M008;
1232 S DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
1233 S DB15.DBX 20.0 // SAVE TOOL ABORTED IN THE SETTING DATA
1234 = DB20.DBX 348.3; // REQUEST FOR IMMEDIATE SETTING DATA BACKUP
1235 = DB1.DBX 1440.0; // TRIGGER NC RESET
1236 M008: NOP 0;
1237 NETWORK
1238 TITLE = MESSAGE 7058 DELETE AXES FREE MOVEMENT
1239
     U I 16.2 // REF Z-axis switch (0-SIGNAL IF AXIS UP !!!!)
1240 FN M 25.3
1241 U DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
1242 U M 25.3
1243 SPBN M2008;
     = DB1.DBX 1440.0; // RESET TRIPPED
1244
1245 M2008: NOP 0;
1246 UN I 16.2 // REF Z-axis switch (0-SIGNAL IF AXIS UP !!!!)
1247 U.M.120.5.//FM.OUTPUT FOR AUXILIARY RELAY DOOR CLOSED
1248
      ; ON I 16.4 // REF BERO WZW
     O DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
1249
1250 FP M 25.2
1251 U M 52.3 // TOOL ABORTED
     UN DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
1252
1253 O M 25.2
1254 O M 25.3
1255 ON I 16.4 // REF BERO WZW
1256 SPBN M009;
1257
     R M 52.3
1258 // TOOL CANCELED
1259 R DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
1260 R DB15.DBX 20.0 // SAVE TOOL ABORTED IN THE SETTING DATA
1261
      = DB20.DBX 348.3; // REQUEST FOR IMMEDIATE SETTING DATA BACKUP
1262 M009: NOP 0;
1263 END FUNCTION
1264 FUNCTION FC 54: VOID
1265 NAME: RETURN TOOL 1
1266
     BEGIN
1267 NETWORK
1268 TITLE = CHECK THAT TOOL HOLDER 1 IS FREE
1269 L DB1.DBD 16
1270 L + 0.70E-02;
1271
      <R;
1272 U E 4.2; // 12mm BERO TOOL EQUIPPED
1273 ; S M 46.1 // TOOL 1 PRESENT
1274 S DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
1275
     = DB1.DBX 1440.0; // TRIGGER NC RESET
```

```
1276 BEB
1277
     NETWORK
1278 TITLE -= STEP · O · Z-AXIS · TOOL · GRIPPER · POSITION · FOR · T1
1279 UN M 23.0 // STEP 0
1280 SPBN M001;
1281 L DB10.DBD 84; // Z-AXIS TOOL GRIPPER POSITION FOR T1
1282 T MD 28 // Z-AXIS TARGET POSITION
1283 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1284 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1285 S M 23.0 // STEP 0
1286 R M 22.3 // Z-AXIS IS ON TARGET POSITION
1287 M001: NOP 0;
1288 NETWORK
1289 TITLE = STEP 1 MOVE TOOL DISC TO RETURN POSITION
1290 U M 23.0 // STEP 0
1291 UN M 23.1 // STEP 1
1292 UN DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
1293 SPBN M002;
1294 S·M·21.7·//·HM·TOOL·TURNING·DISC·MOVE·WITH·20%·RAPID·SPEED
     S M 20.5 // CHECK THAT THE TOOL AREA IS FREE
1295
1296 L MD 32 // A-AXIS POSITION FOR CLAMPED TOOL
1297 T MD 48 // A-AXIS TARGET POSITION
1298 CC FC 61 // MOVE A AXIS TO TARGET POSITION
1299 U M 22.1 // TOOL DISC VALID POSITION REACHED
1300 R M 20.5 // CHECK THAT THE TOOL AREA IS FREE
1301 R M 22.1 // TOOL DISC VALID POSITION REACHED
1302 R·M·21.7·//·HM·TOOL·TURNER·DISC·MOVE WITH·20%·RAPID·SPEED
1303 S M 23.1 // STEP 1
1304 M002: NOP 0;
1305 NETWORK
1306 TITLE = STEP 2 PRINT TOOL
1307 U M 23.1 // STEP 1
1308
     UN M 23.2 // STEP 2
1309 UN M 27.1 // TOOL EXPRESSED
1310 S M 53.0 // M70 EXPRESS TOOL
1311 U M 23.1 // STEP 1
     UN M 23.2 // STEP 2
1312
1313 U M 27.1 // TOOL EXPRESSED
1314 S M 23.2 // STEP 2
1315 NETWORK
1316 TITLE - Z-AXIS TOOL SWIVEL POSITION NO TOOL IN THE SPINDLE
1317 U M 23.2 // STEP 2
1318 UN M 23.3 // STEP 3
1319 SPBN M004;
1320 L MD 78; // Z-AXIS 1MM UNDER SW LIMIT SWITCH
1321
      U M 40.0 // TOOL 0 SELECTED
1322 SPB M104;
1323 L MD 74; // Z-AXIS TOOL SWIVEL POSITION NO TOOL IN THE SPINDLE
1324 M104: NOP 0;
1325
      T MD 28 // Z-AXIS TARGET POSITION
1326 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1327 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1328 S M 23.3 // STEP 3
1329 S M 20.3 // RETURN TOOL DONE
1330 R M 22.3 // Z-AXIS IS ON TARGET POSITION
1331 M004: NOP 0;
1332 END FUNCTION
1333 FUNCTION FC 57: VOID
1334 NAME: PICK UP TOOL 1
     BEGIN
1335
1336 NETWORK
1337 TITLE - STEP · 0 · TOOL · DISC · ON · NEW · A-AXIS · POSITION
1338 UN M 21.0 // STEP 0
1339
     SPBN M001;
```

```
1340
     L MD 36 // NEW A-AXIS POSITION
1341
      T MD 48 // A-AXIS TARGET POSITION
1342 CC FC 61 // MOVE A AXIS TO TARGET POSITION
1343 U M 22.1 // TOOL DISC VALID POSITION REACHED
1344 R M 22.1 // TOOL DISC VALID POSITION REACHED
1345 S M 21.0 // STEP 0
1346
     M001: NOP 0;
1347 NETWORK
1348 TITLE = STEP · 2 · Z-AXIS · TO · T1-T8 · EXPRESSION · AND · MOVE · INTO · THE · INPUT · POSITION
1349 U M 21.0 // STEP 0
1350 UN M 21.1 // STEP 1
1351 SPBN M002;
1352 S A 6.1 // BLOW OFF THE TOOL CONE
1353 L MD 64; // Z-AXIS T1-T8 EXPRESSION AND INSERTION POSITION
1354
      T MD 28 // Z-AXIS TARGET POSITION
1355 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1356 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1357 S M 21.1 // STEP 1
1358
     R M 22.3 // Z-AXIS IS ON TARGET POSITION
1359
     R A 6.1 // BLOW OFF THE TOOL CONE
1360 M002: NOP 0;
1361 NETWORK
1362 TITLE = STEP 3 PULL IN TOOL
1363
     UN M 21.2 // STEP 2
1364 U M 21.1 // STEP 1
1365 UN M 27.0 // TOOL RETRACTED
1366 S M 53.1 // M72 PULL IN TOOL
1367
     UN M 21.2 // STEP 2
1368 U M 21.1 // STEP 1
1369 U M 27.0 // TOOL DRAWN IN
1370 S M 21.2 // STEP 2
1371 NETWORK
1372
     TITLE = STEP 4 Z-AXIS TOOL GRIPPER POSITION FOR T1
1373 U M 21.2 // STEP 2
1374 UN M 21.3 // STEP 3
1375 SPBN M003;
1376
      L DB10.DBD 84; // Z-AXIS TOOL GRIPPER POSITION FOR T1
1377
     T MD 28 // Z-AXIS TARGET POSITION
1378 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1379 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1380 S M 21.3 // STEP 3
1381 R M 22.3 // Z-AXIS IS ON TARGET POSITION
1382 M003: NOP 0;
1383 NETWORK
1384 TITLE = STEP 5 TOOL DISC MOVE TO 0 - POSITION
1385
     U M 21.3 // STEP 3
1386 UN M 21.4 // STEP 4
1387 SPBN M004;
1388 S M 21.7 // HM TOOL TURNING DISC MOVE WITH 20% RAPID SPEED
1389
      L 0 // A-AXIS POSITION 0 DEGREES
1390
      T MD 48 // A-AXIS TARGET POSITION
1391 CC FC 61 // MOVE A AXIS TO TARGET POSITION
1392 U.M. 22.1 // TOOL DISC VALID POSITION REACHED
1393
     R M 22.1 // TOOL DISC VALID POSITION REACHED
     R M 21.7 // HM TOOL TURNER DISC MOVE WITH 20% RAPID SPEED
1394
1395 S M 21.4 // STEP 4
1396 U M 21.4 // STEP 4
1397 UN M 52.7 // ROUND AXLE ACTIVATED
1398
      S M 20.4 // PICK UP TOOL DONE
1399
     M004: NOP 0;
1400 NETWORK
1401 TITLE - STEP 6 Z-AXIS 1MM UNDER THE SW LIMIT SWITCH
     U M 21.4 // STEP 4
1402
1403 UN M 21.5 // STEP 5
```

```
U M 52.7 // ROUND AXIS ACTIVATED
1404
1405 SPBN M005;
1406 L MD 78; // Z-AXIS 1MM UNDER SW LIMIT SWITCH
1407 T MD 28 // Z-AXIS TARGET POSITION
1408 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1409 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1410 S M 21.5 // STEP 5
1411 R M 22.3 // Z-AXIS IS ON TARGET POSITION
1412 M005: NOP 0;
1413 END_FUNCTION
1414 FUNCTION FC 59: VOID
1415 NAME: PICK UP TOOLS 2 TO 8
1416 BEGIN
1417 NETWORK
1418 TITLE = STEP 0 TOOL DISC ON NEW A-AXIS POSITION
1419 UN M 21.0 // STEP 0
1420 SPBN M001;
1421 L MD 36 // NEW A-AXIS POSITION
1422
     T MD 48 // A-AXIS TARGET POSITION
     CC FC 61 // MOVE A AXIS TO TARGET POSITION
1423
1424 U M 22.1 // TOOL DISC VALID POSITION REACHED
1425 R M 22.1 // TOOL DISC VALID POSITION REACHED
1426 S M 21.0 // STEP 0
1427 M001: NOP 0;
1428 NETWORK
1429 TITLE = STEP · 2 · Z-AXIS · TO · T1-T8 · EXPRESSION · AND · MOVE · INTO · THE · INPUT · POSITION
1430 U M 21.0 // STEP 0
1431 UN M 21.1 // STEP 1
1432 SPBN M002;
1433 S A 6.1 // BLOW OFF THE TOOL CONE
1434 L MD 64; // Z-AXIS T1-T8 EXPRESSION AND INSERTION POSITION
1435 T MD 28 // Z-AXIS TARGET POSITION
1436
     CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1437 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1438 S M 21.1 // STEP 1
1439 R M 22.3 // Z-AXIS IS ON TARGET POSITION
1440 R A 6.1 // BLOW OFF THE TOOL CONE
1441 M002: NOP 0;
1442 NETWORK
1443 TITLE = STEP 3 PULL IN TOOL
1444 UN M 21.2 // STEP 2
1445 U M 21.1 // STEP 1
1446 UN M 27.0 // TOOL RETRACTED
1447 S M 53.1 // M72 PULL IN TOOL
1448 UN M 21.2 // STEP 2
1449
     U M 21.1 // STEP 1
1450 U M 27.0 // TOOL DRAWN IN
1451 S M 21.2 // STEP 2
1452 NETWORK
1453 TITLE = STEP 4 Z-AXIS 1MM UNDER THE SW LIMIT SWITCH
1454 U M 21.2 // STEP 2
1455 UN M 21.3 // STEP 3
1456 SPBN M003;
1457 L MD 78; // Z-AXIS 1MM UNDER SW LIMIT SWITCH
     T MD 28 // Z-AXIS TARGET POSITION
1458
1459 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1460 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1461 S M 21.3 // STEP 3
     R M 22.3 // Z-AXIS IS ON TARGET POSITION
1462
1463 M003: NOP 0;
1464 NETWORK
1465 TITLE = STEP 5 TOOL DISC MOVE TO 0 - POSITION
1466 U M 21.3 // STEP 3
1467 UN M 21.5 // STEP 5
```

```
1468 SPBN M004;
1469
     L 0 // A-AXIS POSITION 0 DEGREES
1470 T MD 48 // A-AXIS TARGET POSITION
1471 CC FC 61 // MOVE A AXIS TO TARGET POSITION
1472 U M 22.1 // TOOL DISC VALID POSITION REACHED
1473 R M 22.1 // TOOL DISC VALID POSITION REACHED
     S M 21.5 // STEP 5
1474
1475 U M 21.5 // STEP 5
1476 UN M 52.7 // ROUND AXLE ACTIVATED
1477 S M 20.4 // PICK UP TOOL DONE
     M004: NOP 0;
1478
1479 END_FUNCTION
1480 FUNCTION FC 55: VOID
1481 NAME: TOOL 0 OR NO TOOL RETURNED
     BEGIN
1482
1483 NETWORK
1484 TITLE = OPEN TOOL CLAMPING DEVICE TO PICK UP A TOOL
1485 UN M 23.0 // STEP 0
1486 UN M 27.1 // TOOL EXPRESSED
1487
     S M 53.0 // M70 EXPRESS TOOL
1488 UN M 23.0 // STEP 0
1489 U M 27.1 // TOOL EXPRESSED
1490 S M 23.0 // STEP 0
1491
      NETWORK
1492 TITLE = MOVE Z-AXIS TO TARGET POSITION
1493 UN M 23.1 // STEP 1
1494 SPBN M001;
1495 L MD 78; // Z-AXIS 1MM UNDER SW LIMIT SWITCH
1496 ;; L DB10.DBD 88; // Z-AXIS TOOL SWIVEL POSITION NO TOOL IN THE SPINDLE
1497 T MD 28 // Z-AXIS TARGET POSITION
1498 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1499 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1500
     S M 23.1 // STEP 1
1501 R M 22.3 // Z-AXIS IS ON TARGET POSITION
1502 M001: NOP 0;
1503 U M 23.0 // STEP 0
1504
     U M 23.1 // STEP 1
1505 S M 20.3 // RETURN TOOL DONE
1506 END FUNCTION
1507 FUNCTION FC 56: VOID
1508 NAME: RETURN TOOLS 2 THROUGH 8
1509
     BEGIN
1510 NETWORK
1511 TITLE = STEP 0 Z-AXIS 1MM UNDER THE SW LIMIT SWITCH
1512 UN M 23.0 // STEP 0
1513
     SPBN M001;
1514 L MD 78; // Z-AXIS 1MM UNDER SW LIMIT SWITCH
1515 T MD 28 // Z-AXIS TARGET POSITION
1516 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1517 U M 22.3 // Z-AXIS IS ON TARGET POSITION
     S M 23.0 // STEP 0
1518
1519 M001: NOP 0;
1520 NETWORK
1521
      TITLE = STEP 1 MOVE TOOL DISC TO RETURN POSITION
1522 U M 23.0 // STEP 0
1523 UN M 23.1 // STEP 1
1524 UN DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
1525 SPBN M002;
1526 S M 20.5 // CHECK THAT THE TOOL AREA IS FREE
1527
     L MD 32
1528 // A-AXIS POSITION FOR CLAMPED TOOL
1529 T MD 48 // A-AXIS TARGET POSITION
1530 CC FC 61 // MOVE A AXIS TO TARGET POSITION
1531
     U M 22.1 // TOOL DISC VALID POSITION REACHED
```

```
1532
     R M 20.5 // CHECK THAT THE TOOL AREA IS FREE
1533 R M 22.1 // TOOL DISC VALID POSITION REACHED
1534 S M 23.1 // STEP 1
1535 M002: NOP 0;
1536 NETWORK
1537 TITLE = STEP · 2 · Z-AXIS · TO · T1-T8 · EXPRESSION · AND · MOVE · INTO · THE · INPUT · POSITION
     U M 23.1 // STEP 1
1538
1539 UN M 23.2 // STEP 2
1540 SPBN M003;
1541 L MD 64; // Z-AXIS T1-T8 EXPRESSION AND INSERTION POSITION
1542 T MD 28 // Z-AXIS TARGET POSITION
1543 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1544 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1545 S M 23.2 // STEP 2
1546 R M 22.3 // Z-AXIS IS ON TARGET POSITION
1547 M003: NOP 0;
1548 NETWORK
1549 TITLE = STEP 3 PRINT TOOL
1550 U M 23.2 // STEP 2
1551 UN M 23.3 // STEP 3
1552 UN M 27.1 // TOOL EXPRESSED
1553 S M 53.0 // M70 EXPRESS TOOL
1554 U M 23.2 // STEP 2
1555 UN M 23.3 // STEP 3
1556 U M 27.1 // TOOL EXPRESSED
1557 S M 23.3 // STEP 3
1558 NETWORK
1559
     TITLE = MOVE Z-AXIS TO TARGET POSITION
1560 U M 23.3 // STEP 3
1561 UN M 23.4 // STEP 4
1562 SPBN M004;
1563 L MD 78; // Z-AXIS 1MM UNDER SW LIMIT SWITCH
1564
     U M 40.0 // TOOL 0 SELECTED
1565 SPB M104;
1566 L MD 74; // Z-AXIS TOOL SWIVEL POSITION NO TOOL IN THE SPINDLE
1567 M104: NOP 0;
1568 T MD 28 // Z-AXIS TARGET POSITION
1569 CC FC 60 // Z-AXIS TRAVEL TO TARGET POSITION
1570 U M 22.3 // Z-AXIS IS ON TARGET POSITION
1571 S M 23.4 // STEP 4
     S M 20.3 // RETURN TOOL DONE
1572
1573
     R M 22.3 // Z-AXIS IS ON TARGET POSITION
1574 M004: NOP 0;
1575 END FUNCTION
1576 FUNCTION FC 58: VOID
1577
     NAME: PICK UP TOOL 0
1578 BEGIN
1579 NETWORK
1580 TITLE = STEP 1 MOVE TOOL DISC TO POSITION 8
UN DB10.DBX 75.2; // RETRACT IN THE DISC AT TO TOOL
1582 SPBN M003;
1583 UN M 21.0 // STEP 0
1584 SPBN M002;
1585
      ; L 0 // A-AXIS POSITION 0 DEGREES
1586
     L DB10.DBD 60 // Position for tool 8 in degrees
1587
     T MD 48 // A-AXIS TARGET POSITION
1588 CC FC 61 // MOVE A AXIS TO TARGET POSITION
1589 U M 22.1 // TOOL DISC VALID POSITION REACHED
1590 R M 22.1 // TOOL DISC VALID POSITION REACHED
1591 S M 21.0 // STEP 0
1592 S M 21.1 // STEP 1
1593 M002: NOP 0;
1594 M003: NOP 0;
1595
     NETWORK
```

```
TITLE = STEP 1 MOVE TOOL DISC TO POSITION 0
1596
1597
      U DB10.DBX 75.2; // RETRACT IN THE DISC AT TO TOOL
1598 SPBN M010;
1599 UN M 21.0 // STEP 0
1600 SPBN M011;
1601
      L 0 // A-AXIS POSITION 0 DEGREES
      T MD 48 // A-AXIS TARGET POSITION
1602
1603 CC FC 61 // MOVE A AXIS TO TARGET POSITION
1604 U M 22.1 // TOOL DISC VALID POSITION REACHED
R M 22.1 // TOOL DISC VALID POSITION REACHED
1606 S M 21.0 // STEP 0
1607 S M 21.1 // STEP 1
1608 M011: NOP 0;
1609 M010: NOP 0;
1610 NETWORK
1611 TITLE = STEP 2
1612 U M 21.1 // STEP 1
1613 U M 40.0 // TOOL 0 SELECTED
1614 S M 20.4 // PICK UP TOOL DONE
1615
     S M 25.0 // TOOL 0 PICK UP DONE
1616 END_FUNCTION
1617 FUNCTION FC 61: VOID
1618 NAME: MOVE A-AXIS TO TARGET POSITION
1619
      BEGIN
1620 NETWORK
1621 TITLE = STEP 2 MOVE TOOL DISC TO VALID POSITION
1622 UN M 22.0 // PIVOTING ACTIVE
1623 UN M 22.1 // TOOL DISC VALID POSITION REACHED
1624 SPBN M001;
1625 S M 22.0 // PIVOTING ACTIVE
1626 = DB25.DBX 1.4; // SEND NC BLOCK
1627 = DB25.DBX 548.5; // SET EXACT HOLD MODE
1628
      = DB25.DBX 549.0; // G1 IS TRIGGERED
1629 = DB25.DBX 549.4; // FEED RATE IN DEGREES / S VALUE IN DBD556
1630 L DB10.DBD 28; // FEED VALUE IN DEGREES / SECONDS
1631 T DB25.DBD 556; // F-VALUE IN M / S OR M / U
1632
     S DB25.DBX 21.4; // POSITION REQUEST FOR CHANNEL AXIS C
1633 L MD 48 // A-AXIS TARGET POSITION
1634 T DB25.DBD 70; // POSITION VALUE FOR CHANNEL AXIS C
1635 L 0 // DELETE MW 46
1636
      T MW 46 // DELETE MW 46
1637
      U E 4.2; // 12mm BERO TOOL EQUIPPED
1638 S M 46.1 // TOOL 1 PRESENT
1639 U.M. 21.7 // HM TOOL TURNER DISC MOVE WITH 20% RAPID SPEED
1640 SPBN M001;
1641
      L DB10.DBD 24; // T-1 ACCEPTANCE FEED VALUE IN DEGREES / SECONDS FOR TOOL DISC
1642 T DB25.DBD 556; // F-VALUE IN M / S OR M / U
1643 M001: NOP 0;
1644 NETWORK
1645
      TITLE = CHECK WHETHER TOOL SPACE IS FREE
1646 U DB25.DBX 332.0; // NC BLOCK DONE
1647 U M 22.0 // PIVOTING ACTIVE
1648 R DB25.DBX 332.0; // NC BLOCK DONE
1649
     S M 22.1 // TOOL DISC VALID POSITION REACHED
1650 R M 22.0 // PIVOTING ACTIVE
1651 U M 22.1 // TOOL DISC VALID POSITION REACHED
1652 U M 20.5 // CHECK THAT THE TOOL AREA IS FREE
1653 SPBN M002;
1654
      L MW 46 // TOOL EQUIPMENT
     L MW 42 // CLAMPED TOOL FROM THE SETTING DATA
1655
1656 UW
1657
      T MW 44 // RESULTS OF TOOL HOLDER INSPECTION
     L MW 44 // RESULTS OF TOOL HOLDER INSPECTION
1658
1659
     \mathbf{L} \cdot \mathbf{0}
```

```
1660 <> I.
1661 S DB3.DBX 7.1; // MELDUN
1662 G 7057 TOOL HOLDER OCCUPIED
1663 = DB1.DBX 1440.0; // TRIGGER NC RESET
1664 R M 22.1 // TOOL DISC VALID POSITION REACHED
1665 M002: NOP 0;
1666 NETWORK
1667 TITLE = CHECK TOOLS IN DISC
1668 U E 4.2; // 12mm BERO TOOL EQUIPPED
1669 FP M 27.4
1670 U M 27.4
1671 U M 22.0 // PIVOTING ACTIVE
1672 U M 20.5 // CHECK THAT THE TOOL AREA IS FREE
1673 SPBN M003;
1674 ; Filter tool 1 Bero
1675 L DB1.DBD 16
1676 L + 0.70E-02;
1677 <R;
1678 BEB
    ; Tool 2
1679
1680 L DB1.DBD 16
1681 L + 2.10E-02;
1682 <R;
1683 S M 46.2 // TOOL 2 PRESENT
1684 BEB
1685 ; Tool 3
1686 L DB1.DBD 16
1687
     L + 3.20E-02;
1688 <R;
1689 S M 46.3 // TOOL 3 PRESENT
1690 BEB
1691
      ; Tool 4
1692
      L DB1.DBD 16
1693 L + 4.90E-02; -
1694 <R;
1695 S M 46.4 // TOOL 4 PRESENT
1696 BEB
1697 ; Tool 5
1698 L DB1.DBD 16
1699 L + 6.30E-02;
1700
1701 S M 46.5 // TOOL 5 PRESENT
1702 BEB
1703 ; Tool 6
1704 L DB1.DBD 16
1705 L + 7.70E-02;
1706 <R;
1707 S M 46.6 // TOOL 6 PRESENT
1708 BEB
1709 ; Tool 7
1710 L DB1.DBD 16
1711 L + 9.10E-02;
1712 <R;
1713 S M 46.7 // TOOL 7 PRESENT
    BEB
1714
1715 ; Tool 8
1716 L DB1.DBD 16
1717 L + 1.05E-01;
1718
      S M 47.0 // TOOL 8 PRESENT
1719
1720 BEB
1721 M003: NOP 0;
1722 END_FUNCTION
1723
    FUNCTION FC 51: VOID
```

```
1724
     NAME: TOOL CLAMPING SYSTEM
1725
     BEGIN
1726 UN E 4.1 // TOOL EXPRESSED
1727 U DB10.DBX 2.0; // ACTIVATE AC 2000
1728 = M 94.3; // SFG TOOL EXPRESSED
1729
      NETWORK
      TITLE = EXPRESS THE TOOL WITH THE "CTRL + 1" OR "CTRL + ^" KEYS
1730
1731 // ALT U CTR ^ DB20.DBX 294.2 CHUCK OPEN / CLOSE
1732 // ALT K CTR · 1 · DB20 . DBX · 294 . 5 · SWIVEL · TOOL · ONE · POSITION · FURTHER
U DB20.DBX 294.5 // (CTRL 1 or Alt K) Express / retract tool
1734
     FP·M·26.6·// FP-M·(STRG·1·or Alt·K) Push out·/ pull·in·tool
     U DB20.DBX 294.2 // (CTRL ^ or ALT U) CHUCK OPEN / CLOSE
1735
1736
     U M 200.0 // SET TOOL POSITIONS
1737
1738
      U M 26.6 // FP-M (STRG 1 or Alt K) Express / retract tool
1739
     UN M 200.0 // SET TOOL POSITIONS
1740 )
1741 U.E.2.1; // S1.DOOR.SWITCH.(0.SIGNAL.WHEN.THE.DOOR.IS.CLOSED)
1742
     U E 2.5; // S2 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
1743
     UN M 52.0; // TOOL TURNING ACTIVE
1744 U M 27.2 // EXPRESS RELEASE TOOL
1745 FP M 27.3
1746 U M 27.3
1747
     SPBN M101
1748 L 0
1749 T MW 40 // MW 40
1750 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1751
      M101: NOP 0
1752
     NETWORK
1753 TITLE = EXPRESS RELEASE TOOL
1754 U M 15.2; // EMERGENCY STOP SWITCH
U M 114.3; // ACTUAL SPEED LESS THAN 20RPM
1756
      = M 27.2 // EXPRESS RELEASE TOOL
1757
     NETWORK
1758 TITLE = EXPRESS TOOL
1759 O M 27.3
1760 O M 53.0; // EXPRESS M70 TOOL
1761 UN M 27.1 // TOOL EXPRESSED
1762 U M 27.2 // EXPRESS RELEASE TOOL
1763 S A 6.0 // TOOL CLAMPING MOTOR
1764 S M 27.6 // HM TOOL CLAMPING MOTOR EXPRESS
1765
     S M 94.1; // SFG TOOL EXPRESSED
1766 R M 27.0 // TOOL RETRACTED
1767 O M 27.6 // HM TOOL CLAMPING MOTOR EXPRESS
1768 O DB1.DBX 1370.0; // 1st PLC LOOP
1769
     UN E 4.1 // TOOL EXPRESSED
1770 U E 4.0 // TOOL DRAWN IN
1771 O M 70.0; // FM EMERGENCY OFF PRESSED
1772 R A 6.0 // TOOL CLAMPING MOTOR
1773 R M 27.6 // HM TOOL CLAMPING MOTOR EXPRESS
1774 R M 53.0; // EXPRESS M70 TOOL
1775 S M 27.1 // TOOL EXPRESSED
1776 SPBN M102
1777
     L \cdot 0
     T DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1778
1779 = DB20.DBX 348.3; // REQUEST FOR IMMEDIATE SETTING DATA BACKUP
1780 U DB3.DBX 6.7; // MESSAGE 7055 OPEN TOOL CLAMPING SYSTEM
1781 R M 52.3 // TOOL CANCELED
1782
      R DB3.DBX 6.7; // MESSAGE 7055 OPEN TOOL CLAMPING SYSTEM
1783 M102: NOP 0
1784 NETWORK
1785 TITLE = PULL IN TOOL
1786
1787 U M 27.3
```

```
U M 200.0 // SET TOOL POSITIONS
1788
1789
1790 O M 53.1; // PULL IN M72 TOOL
1791 UN M 27.0 // TOOL RETRACTED
1792 UN M 27.6 // HM TOOL CLAMPING MOTOR EXPRESS
1793 U M 27.2 // EXPRESS RELEASE TOOL
1794
     S A 6.0 // TOOL CLAMPING MOTOR
1795 S M 27.7 // PULL IN HM TOOL CLAMPING MOTOR
1796 O M 27.7 // PULL IN HM TOOL CLAMPING MOTOR
1797
     O DB1.DBX 1370.0; // 1st PLC LOOP
     UN E 4.0 // TOOL RETRACTED
1798
1799 U E 4.1 // TOOL EXPRESSED
1800 O M 70.0; // FM EMERGENCY OFF PRESSED
1801 R A 6.0 // TOOL CLAMPING MOTOR
     R M 27.7 // HM PULL IN TOOL CLAMPING MOTOR
1802
1803 R M 53.1; // PULL IN M72 TOOL
1804 S M 27.0 // TOOL RETRACTED
1805 R M 27.1 // TOOL EXPRESSED
      U M 27.0 // TOOL DRAWN IN
1806
1807
     FP M 53.2; // PULL IN THE HM M72 TOOL
1808 U M 53.2; // PULL IN THE HM M72 TOOL
1809 UN DB1.DBX 1370.0; // 1st PLC LOOP
1810 SPBN M103
1811 L MW 40 // MW 40
1812 T DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1813 = DB20.DBX 348.3; // REQUEST FOR IMMEDIATE SETTING DATA BACKUP
1814 M103: NOP 0
1815 U M 27.1 // TOOL EXPRESSED
1816 S M 94.1; // SFG TOOL EXPRESSED
1817 U M 27.0 // TOOL ON
1818 DRAWN
1819 R M 94.1; // SFG TOOL EXPRESSED
1820 END FUNCTION
1821 FUNCTION FC 52: VOID
1822 NAME: SET TOOL POSITION FROM THE SETTING DATA
1823 BEGIN
1824 NETWORK
1825 TITLE = SET TOOL POSITION FROM THE SETTING DATA
1826 ; Determine the return position for the clamped tool
1827 L 0;
1828
     T MW 42
1829
     L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1830 L.O;
1831 == I;
1832 = M 20.0 // NO TOOL NUMBER STORED
1833
     SPB M001
1834 L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1835 L 1
1836 == I.
1837 = M \cdot 42.0 // TOOL \cdot 0 \cdot CLAMPED
1838
     SPB M001
1839 L DB10.DBD 32 // Position for tool 1 in degrees
1840 T MD 32 // A-AXIS POSITION FOR CLAMPED TOOL
1841 L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1842
     L \cdot 2
1843 == I.
1844 = M \ 42.1 \ // \ TOOL \ 1 \ CLAMPED
1845 SPB M001
1846
      L DB10.DBD 36 // Position for tool 2 in degrees
1847
      T MD 32 // A-AXIS POSITION FOR CLAMPED TOOL
1848 L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1849 L·4
1850 == I.
1851
      = M 42.2 // TOOL 2 CLAMPED
```

```
1852 SPB M001
1853 L DB10.DBD 40 // Position for tool 3 in degrees
1854 T \cdot MD \cdot 32 \cdot / / \cdot A-AXIS \cdot POSITION \cdot FOR \cdot CLAMPED \cdot TOOL
1855 L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1856 L 8
1857
     == I.
     = M 42.3 // TOOL 3 CLAMPED
1858
1859 SPB M001
1860 L DB10.DBD 44 // Position for tool 4 in degrees
1861
      T MD 32 // A-AXIS POSITION FOR CLAMPED TOOL
     L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1862
1863 L 16
1864 == I.
1865 = M 42.4 // TOOL 4 CLAMPED
1866 SPB M001
1867 L DB10.DBD 48 // Position for tool 5 in degrees
1868 T MD 32 // A-AXIS POSITION FOR CLAMPED TOOL
1869 L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1870 L 32
1871
     == I.
1872 = M 42.5 // TOOL 5 CLAMPED
1873 SPB M001
1874 L DB10.DBD 52 // Position for tool 6 in degrees
1875
      T MD 32 // A-AXIS POSITION FOR CLAMPED TOOL
1876 L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1877 L 64
1878 == I.
1879
     = M 42.6 // TOOL 6 CLAMPED
1880 SPB M001
1881 L DB10.DBD 56 // Position for tool 7 in degrees
1882 T MD 32 // A-AXIS POSITION FOR CLAMPED TOOL
1883 L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1884
     L 128
1885 == I.
1886 = M \ 42.7 \ // \ TOOL \ 7 \ CLAMPED
1887 SPB M001
1888 L DB10.DBD 60 // Position for tool 8 in degrees
1889 T MD 32 // A-AXIS POSITION FOR CLAMPED TOOL
1890 L DB15.DBW 25; // CLAMPED TOOL IN THE SETTING DATA
1891 L 256
     == I.
1892
1893
     = M 43.0 // TOOL 8 CLAMPED
1894 SPB M001
1895 L 0
1896 T MD 32 // A-AXIS POSITION FOR CLAMPED TOOL
1897
     S M 20.2 // ILLEGAL TOOL NUMBER IN THE SETTING DATA
1898 = DB3.DBX · 7.0; · // MESSAGE · 7056 · ILLEGAL · TOOL · NUMBER · IN · THE · SETTING · DATA
1899 = DB1.DBX 1440.0; // TRIGGER NC RESET
1900 M001: NOP 0
1901 NETWORK
1902 TITLE = TOOL DRAWN IN AND NO TOOL NUMBER STORED (BIG PROBLEM)
1903 U M 20.0 // NO TOOL NUMBER STORED
1904 U M 27.0 // TOOL DRAWN IN
1905 SPBN M111
     S DB3.DBX 6.7; // MESSAGE 7055 OPEN TOOL CLAMPING SYSTEM
1906
1907 = DB1.DBX 1440.0; // TRIGGER NC RESET
1908 M111: NOP 0
1909 NETWORK
1910
      TITLE = TOOL EXPRESSED AND NO TOOL NUMBER STORED (NO PROBLEM)
1911 U M 20.0 // NO TOOL NUMBER STORED
1912 U M 27.1 // TOOL EXPRESSED
1913 S M 20.1 // TOOL EXPRESSED AND NO TOOL NUMBER STORED
1914
     NETWORK
1915
      TITLE = SET TOOL WHEN STARTING UP
```

```
1916 U DB1.DBX 1370.0; // 1st PLC LOOP
1917
     SPBN M110;
1918 UN M 42.1;
1919 SPB M113
1920 L 1;
1921 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1922 M113: NOP 0
1923 UN M 42.2;
1924 SPB M114
1925 L 2;
1926 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1927 M114: NOP 0
1928 UN M 42.3;
1929 SPB M115
1930 L-3;
1931 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1932 M115: NOP 0
1933 UN M 42.4;
1934 SPB M116
1935
     L 4;
1936 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1937 M116: NOP 0
1938 UN M 42.5;
1939 SPB M117
1940 L 5;
1941 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1942 M117: NOP 0
1943 UN M 42.6;
1944 SPB M118
1945 L 6;
1946 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1947 M118: NOP 0
1948
     UN M 42.7;
1949 SPB M119
1950 L 7;
1951 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1952 M119: NOP 0
1953 UN M 43.0;
1954 SPB M110
1955 L 8;
1956 T DB20.DBW 356; // ACTIVE TOOL IN DB20
1957 M110: NOP 0
1958 END_FUNCTION
1959 FUNCTION FC 53: VOID
1960 NAME: CHECK NEW T-WORD AND DETERMINE A NEW TOOL DISC POSITION
1961 BEGIN
1962 NETWORK
1963 TITLE = 7000 INCORRECT T-WORD PROGRAMMED
1964 L DB20.DBW 184; // LOAD T-WORD
1965 L 8; // CHARGE CONSTANT DEC 8
1966 > I; // COMPARISON TO LARGER
1967 = M 22.4 // T-WORD GREATER 10
1968 L DB20.DBW 184; // LOAD T-WORD
1969 L 0; // LOAD CONSTANT DEC 0
1970 <I; // COMPARISON TO SMALLER
1971 = M 22.5 // T-WORD LOWER 0
1972 O M 22.4 // T-WORD LARGER 8
1973 O M 22.5 // T-WORD LOWER 0
1974 U DB20.DBX 182.0 // NEW T-WORD (TOOL)
     SPBN M222
1975
1976 S DB3.DBX 0.0; // 7000 WRONG T-WORD
1977 = DB1.DBX 1
1978 440.0; // TRIGGER NC RESET
1979
     M222: NOP 0
```

```
1980 NETWORK
1981
      TITLE = T-WORD IS VALID
1982 UN DB3.DBX 0.0; // 7000 WRONG T-WORD
1983 SPBN M002
1984 L 0 // DELETE MW 40
1985 T MW 40 // DELETE MW 40
1986 L DB20.DBW 184; // T-WORD
1987 L 0
1988 == I.
1989 = M·40.0·// TOOL·0·SELECTED (RETURN CLAMPED TOOL
1990 ; OR PULL IN TOOL CHIPPING SYSTEM)
1991 SPB M002
1992 L DB10.DBD 32 // Position for tool 1 in degrees
1993 T MD 36 // NEW A-AXIS POSITION
1994 L DB20.DBW 184; // T-WORD
     L \cdot 1
1995
1996 == I.
1997 = M 40.1
1998 SPB M002
1999
     L DB10.DBD 36 // Position for tool 2 in degrees
2000 T MD 36 // NEW A-AXIS POSITION
2001 L DB20.DBW 184; // T-WORD
2002 L·2
2003
     == I.
2004 = M 40.2
2005 SPB M002
2006 L DB10.DBD 40 // Position for tool 3 in degrees
2007
     T MD 36 // NEW A-AXIS POSITION
2008 L DB20.DBW 184; // T-WORD
2009 L 3
2010 == I.
2011 = M 40.3
2012
     SPB M002
2013 L DB10.DBD 44 // Position for tool 4 in degrees
2014 T MD 36 // NEW A-AXIS POSITION
2015 L DB20.DBW 184; // T-WORD
2016 L 4
     == I.
2017
2018 = M 40.4
2019 SPB M002
2020 L DB10.DBD 48 // Position for tool 5 in degrees
2021
      T MD 36 // NEW A-AXIS POSITION
2022 L DB20.DBW 184; // T-WORD
2023 L·5
2024 == I.
2025 = M 40.5
2026 SPB M002
2027 L DB10.DBD 52 // Position for tool 6 in degrees
2028 T MD 36 // NEW A-AXIS POSITION
2029 L DB20.DBW 184; // T-WORD
2030 L 6
2031 == I.
2032 = M 40.6
2033 SPB M002
2034 L DB10.DBD 56 // Position for tool 7 in degrees
2035 T MD 36 // NEW A-AXIS POSITION
2036 L DB20.DBW 184; // T-WORD
2037 L 7
2038
     == I.
2039
     = M 40.7
2040 SPB M002
2041 L DB10.DBD 60 // Position for tool 8 in degrees
2042
     T MD 36 // NEW A-AXIS POSITION
2043 L DB20.DBW 184; // T-WORD
```

```
2044
     L 8
2045 == I.
2046 = M 41.0
2047 M002: NOP 0
2048 L MW 40 // NEW TOOL FROM VALID T-WORD
2049 L MW 42 // CLAMPED TOOL FROM THE SETTING DATA
2050
     <> I; // COMPARE TO INEQUAL
2051 = M \cdot 22.6 // T-WORD NOT EQUAL TO TOOL
2052 L MW 40 // NEW TOOL FROM VALID T-WORD
2053 L · MW · 42 \cdot / / · CLAMPED · TOOL · FROM · THE · SETTING · DATA
2054
     == I; // COMPARE TO INEQUAL
2055
     = M 26.1 // NEW T-WORD EQUALS TOOLS
2056 END FUNCTION
2057 FUNCTION FC 60: VOID
2058
      NAME: MOVE Z-AXIS TO TARGET POSITION
     BEGIN
2059
2060 UN M 22.2 // Z-AXIS MOVE TO TARGET POSITION ACTIVE
2061 SPBN M001;
2062
      S M 22.2 // Z-AXIS MOVE TO TARGET POSITION ACTIVE
2063 R M 22.3 // Z-AXIS IS ON TARGET POSITION
2064 = DB25.DBX 1.4; // SEND NC BLOCK
2065 = DB25.DBX 548.7 // GO is triggered
2066 = DB25.DBX 20.2; // POSITION REQUEST FOR Z-AXIS
2067
      L MD 28 // Z-AXIS TARGET POSITION
2068
      T DB25.DBD 30; // POSITION VALUE FOR Z-AXIS
2069 M001: NOP 0;
2070 U DB25.DBX 332.0; // NC BLOCK DONE
2071
      U M 22.2 // Z-AXIS MOVE TO TARGET POSITION ACTIVE
2072
     R M 22.2 // Z-AXIS MOVE TO TARGET POSITION ACTIVE
2073
     S M 22.3 // Z-AXIS IS ON TARGET POSITION
2074 R DB25.DBX 332.0; // NC BLOCK DONE
2075
      END_FUNCTION
2076
      FUNCTION FC 23: VOID
2077
      NAME: SAFETY CIRCUIT ACC
2078 BEGIN
2079
      // X6: 1 I 2.0 = M 15.0 // 1st door limit switch MACHINE DOOR CLOSED (MAIN MOTOR
      CONTACTOR ON)
2080
     // Monitoring whether HA contactors have dropped out (must have 0 signal
2081
     // be with the door or wheel cover open or the EMERGENCY STOP pressed)
2082
     // X6: 2 I 2.1 = M 15.1 // 1st door limit switch MACHINE DOOR OPEN
2083
      // (0 signal when the door is closed!)
2084
      // X6: 5 · I · 2.5 · // only MILL55 · ACC · 2nd · door · limit · switch · MACHINE · DOOR · CLOSED · 2nd · door
      limit switch
2085
     // (0 signal when the door is closed!)
2086
      // X6: 10 A 3.4 // only MILL55 ACC safety output for relay (category 3)
2087
      NETWORK
2088 TITLE = SAFETY CIRCUIT DEFECTIVE K1, K2 OR K3 STUCK
2089 UN A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2090
     ; U E 2.1; // S1 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
2091
      ; U E 2.5; // S2 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
2092
      U E 2.0; // K1, K2, or K3 ON (1 SIGNAL WHEN THE DOOR IS CLOSED)
2093
      0 (
      U A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2094
2095
      UN E 2.0; // K1, K2, or K3 ON (1 SIGNAL WHEN THE DOOR IS CLOSED)
2096
      )
     L S5TIME # 1S;
2097
2098 SE T 6; // T6 SWITCH-ON DELAYED
2099 U T 6; // T6
2100
      S DB2.DBX 1.1; // HW ERROR SAFETY CIRCUIT
2101
      O DB1.DBX 1370.3; // RESET KEY PRESSED
2102 R DB2.DBX 1.1; // HW ERROR SAFETY CIRCUIT
2103 NETWORK
2104
      TITLE = MACHINE DOOR CLOSED
2105
     U·(
```

```
2106
      O DB1.DBX 1370.0; // 1st PLC LOOP
2107
      O M 1.0 // HM MACHINE DOOR OPEN
2108
2109 UN E 2.1; // S1 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
2110 UN E 2.5; // S2 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
2111
      UN E 2.0; // K1, K2, or K3 ON (1 SIGNAL WHEN THE DOOR IS CLOSED)
2112
      S A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2113 NETWORK
2114 TITLE = MACHINE DOOR OPEN
2115 O.E.2.1; // S1 DOOR SWITCH (O.SIGNAL WHEN THE DOOR IS CLOSED)
2116
     O E 2.5; // S2 DOOR SWITCH (0 SIGNAL WHEN CLOSED
2117
     NER DOOR)
2118 R A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2119 NETWORK
2120
      SET TITLE = HM WITH THE MACHINE DOOR OPEN
2121 UN A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2122 U E 2.1; // S1 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
2123 U.E.2.5; // S2 DOOR SWITCH (0.SIGNAL WHEN THE DOOR IS CLOSED)
2124
     UN E 2.0; // K1, K2, or K3 ON (1 SIGNAL WHEN THE DOOR IS CLOSED)
2125
     UN M 1.0 // HM MACHINE DOOR OPEN
2126 S M 1.1 // HM MACHINE DOOR OPEN
2127 NETWORK
2128 TITLE = 10S RECOVERY TIME FOR LENDER
2129
     U M 1.1 // HM MACHINE DOOR OPEN
2130 L S5TIME # 10S; // 10S
2131 SE T 12; // SWITCH-ON DELAY
2132 U DB1.DBX 1370.0; // 1st PLC LOOP
2133
     U M 1.1 // HM MACHINE DOOR OPEN
2134
     O T 12; // SWITCH-ON DELAY
2135 S M 1.0 // HM MACHINE DOOR OPEN
2136 R M 1.1 // HM MACHINE DOOR OPEN
2137 NETWORK
2138
      TITLE = MESSAGE 7023 WAITING TIME MAIN DRIVE
2139 UN M 1.0 // HM MACHINE DOOR OPEN
2140 UN E 2.1; // S1 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
2141 UN E 2.5; // S2 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
2142
     UN E 2.0; // K1, K2, or K3 ON (1 SIGNAL WHEN THE DOOR IS CLOSED)
2143 UN A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2144 = DB3.DBX 2.7; // MESSAGE 7023 WAITING TIME MAIN DRIVE
2145 = M 90.0; // WAITING TIME MAIN DRIVE AFG / EFG
2146
      = M 96.2; // WAITING TIME MAIN DRIVE NC_START VERR.
2147
      U A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2148
     R M 1.0 // HM MACHINE DOOR OPEN
2149 U A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2150 FP M 120.5 // FM OUTPUT FOR AUXILIARY RELAY DOOR CLOSED
2151
      U A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2152 FN M 120.6 // NEGATIVE-FM DOOR OPEN
2153 UN A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2154 = M·96.3; // OUTPUT FOR AUXILIARY RELAY DOOR CLOSED NC_START LOCK.
2155
      END FUNCTION
2156
     FUNCTION FC 34: VOID
2157 NAME: ASSIGN INPUTS AC95 - ACC
2158 BEGIN
2159
     NETWORK
2160
      TITLE = DOOR SWITCH ASSIGNMENT
2161 U DB10.DBX 2.0; // ACTIVATE AC 2000
2162 U E 2.0; // MACHINE DOOR CLOSED (MAIN MOTOR CONTACTOR ON)
2163
2164
      UN DB10.DBX 2.0; // ACTIVATE AC 2000
     U E 1.5; // MACHINE DOOR CLOSED (MAIN MOTOR CONTACTOR ON)
2165
2166 = M 15.0; // MACHINE DOOR CLOSED (MAIN MOTOR CONTACTOR ON)
2167
     NETWORK
2168
      TITLE = DOOR SWITCH ASSIGNMENT
2169
     U DB10.DBX 2.0; // ACTIVATE AC 2000
```

```
UN M 2.0\ //\ \text{IDENTIFICATION} AC95 CONVERSION TO ACC
2170
2171
      UN A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2172
     U M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
2173
2174
      U E 2.1; // DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
2175
2176
      0(
2177
      UN DB10.DBX 2.0; // ACTIVATE AC 2000
2178
      U E 1.6; // DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
2179
2180
     UN DB1.DBX 1370.0; // 1st PLC LOOP
2181
      = M 15.1; // MACHINE DOOR OPEN
2182 NETWORK
2183 TITLE = EMERGENCY OFF ASSIGNMENT
2184
      U DB10.DBX 2.0; // ACTIVATE AC 2000
2185
     U E 2.2; // EMERGENCY STOP AC 2000
2186
     UN DB10.DBX 2.0; // ACTIVATE AC 2000
2187
2188
     U E 1.4; // EMERGENCY STOP AC 95
2189
      = M 15.2; // EMERGENCY STOP SWITCH
2190
     U M 15.2; // EMERGENCY STOP SWITCH
2191 FN M 70.0; // FM EMERGENCY OFF PRESSED
2192
     NETWORK
2193
      TITLE = WHEEL COVER LIMIT SWITCH ASSIGNMENT
2194
      U DB10.DBX 2.0; // ACTIVATE AC 2000
2195 U.E.2.3; // WHEEL COVER LIMIT SWITCH (IN SERIES WITH EMERGENCY STOP!)
2196 O
2197
      UN DB10.DBX 2.0; // ACTIVATE AC 2000
     U E 1.7; // WHEEL COVER LIMIT SWITCH (IN SERIES WITH EMERGENCY STOP!)
2198
     = M·15.6; // WHEEL COVER LIMIT SWITCH (IN SERIES WITH EMERGENCY STOP!)
2199
2200 NETWORK
      TITLE = SERVO READY ASSIGNMENT
2201
2202
      U DB10.DBX 2.0; // ACTIVATE AC 2000
2203
     U E 0.0; // SERVO READY AXIS 0 (X)
2204
2205 UN DB10.DBX 2.0; // ACTIVATE AC 2000 6
2206
      U E 1.0; // SERVO READY AXIS 0 (X)
2207
      = M = 15.3; // SERVO READY AXIS 0 (X)
2208
     U DB10.DBX 2.0; // ACTIVATE AC 2000
2209 U E 0.1; // SERVO READY AXIS 1 (Y)
2210
      0
2211
     UN DB10.DBX 2.0; // ACTIVATE AC 2000
2212 U E 1.1; // SERVO READY AXIS 1 (Y)
2213 = M 15.4; // SERVO READY AXIS 1 (Y)
2214 U DB10.DBX 2.0; // ACTIVATE AC 2000
2215
      U E 0.2; // SERVO READY AXIS 2 (Z)
2216
     UN DB10.DBX 2.0; // ACTIVATE AC 2000
2217
2218 U E 1.2; // SERVO READY AXIS 2 (Z)
2219
      = M 15.5; // SERVO READY AXIS 2 (Z)
      U DB10.DBX 2.0; // ACTIVATE AC 2000
2220
2221 U E 0.3; // SERVO READY HA
2222
2223
     UN DB10.DBX 2.0; // ACTIVATE AC 2000
2224
     U E 1.3; // SERVO READY HA
2225
     = M 15.7; // SERVO READY HA
2226 NETWORK
2227
     TITLE = N = 0 FROM LENZE INVERTER ASSIGNMENT
2228
      U DB10.DBX 2.0; // ACTIVATE AC 2000
2229
      U E 2.4; // n = 0 RELAY FROM LENZE-FU
2230
      UN DB10.DBX 2.0; // ACTIVATE AC 2000
2231
2232
     U E 2.3; // n = 0 RELAY FROM LENZE-FU
2233
      = M 16.0; // n = 0 RELAY FROM LENZE-FU
```

```
2234
     END_FUNCTION
2235 FUNCTION FC 35: VOID
2236 NAME: ASSIGN THE OUTPUTS AC95 - ACC
2237 BEGIN
2238 U DB10.DBX 2.0; // ACTIVATE AC 2000
2239 SPBN M001;
2240
      // ASSIGN ACC KEY TO OPEN DOOR (MSTT)
2241 U DB1.DBX 1403.7; // Concept CAM
2242 U DB1.DBX 1374.0; // MACHINE KEYBOARD DOOR OPEN
2243 O(
     UN DB1.DBX 1403.7; // Concept CAM
2244
2245
     U DB1.DBX 13
2246 74.1; // MACHINE KEYBOARD DOOR CLOSED
2247
2248
      = M 138.1; // HM MACHINE KEYBOARD DOOR OPEN
2249
      // ASSIGN ACC KEY DOOR CLOSED (MSTT)
2250 U DB1.DBX 1403.7; // Concept CAM
U DB1.DBX 1374.1; // MACHINE KEYBOARD DOOR CLOSED
2252
2253
     UN DB1.DBX 1403.7; // Concept CAM
2254 U DB1.DBX 1374.0; // MACHINE KEYBOARD DOOR OPEN
2255
2256
     = M 138.2; // HM MACHINE KEYBOARD DOOR CLOSED
2257
      // ACC BUTTON ASSIGN VICE ACC
     U DB20.DBX 294.3; // VICE CLOSE BUTTON (PC)
2258
2259 UN DB20.DBX 294.4; // VICE OPEN BUTTON (PC)
2260 FP M 138.7; // FM BUTTON VICE CLOSED ACC
2261
      // ACC BUTTON ASSIGN VICE TO ACC
2262 U DB20.DBX 294.4; // VICE OPEN BUTTON (PC)
2263 UN DB20.DBX 294.3; // VICE CLOSE BUTTON (PC)
2264 FP M 137.1; // FM BUTTON VICE ON ACC
2265 // ASSIGN ACC ENABLE AXES
2266
      U M 17.0; // EXIT FLAG ENABLE AXES
2267 = A 3.0; // ENABLE SM MODULE A
2268 UN M 2.0; // IDENTIFICATION CONVERSION TO ACC
2269 SPBN M3501;
2270 U M 17.0; // EXIT FLAG ENABLE AXES
2271 U.A.3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
2272 L S5TIME # 1500MS; // 1.5 S
2273 SE T 13; // SWITCH-ON DELAY
2274 U T 13; // SWITCH-ON DELAY
2275
     = A 3.1; // ENABLE SM MODULE B
2276 ON A 3.1; // ENABLE SM MODULE B
2277 O E 0.5; // Servo Ready tool turret drive (physical axis 4)
2278 U M 52.5 // TOOL TURNER ACTIVATED
2279
2280 ON A 3.1; // ENABLE SM MODULE B
2281
      O E 0.4; // Servo Ready round axis drive (physical axis 5)
2282
     U M 52.7 // ROUND AXIS ACTIVATED
2283
2284
     = M 90.3; // ENABLE SM MODUL B AFG / EFG
= M 96.4; // ENABLE SM MODUL B NC START VERR.
2286 M3501: NOP 0;
2287
      // ASSIGN ACC CONTROLLER ENABLE MAIN DRIVE
     U M 17.1; // INITIAL FLAG CONTROLLER ENABLE MAIN DRIVE
2288
2289
     = A 0.3; // CONTROLLER ENABLE MAIN DRIVE
2290 // ASSIGN ACC COOLANT (M8 = ON / M9 = OFF)
2291 U·M·17.2; \cdot// EXIT·FLAG·COOLANT·(M8·=·ON·/·M9·=·OFF)
2292
     = A 3.3; // COOLANT (M8 = ON / M9 = OFF)
2293
      // ASSIGN ACC MINIMUM LUBRICATION
2294 U M 18.0; // INITIAL FLAG MINIMAL LUBRICATION
2295 = A 4.0; // MINIMAL LUBRICATION
2296
      // ASSIGN ACC BLOW-OUT VALVE
2297
     U M 18.2; // EXIT FLAG BLOW-OUT VALVE
```

```
= A 4.2; // EXHAUST VALVE
2298
2299
      // ASSIGN ACC DOOR OPEN
2300 U M 18.3; // EXIT FLAG DOOR OPEN
2301 = A 4.3; // OPEN THE DOOR
2302 // ASSIGN ACC DOOR
2303 U M 18.4; // EXIT FLAG DOOR CLOSED
     = A 4.4; // CLOSE THE DOOR
2304
2305 // ASSIGN ACC VICE TO CLAMP
2306 U M 18.5; // EXIT FLAG CLAMP VICE
2307
     = A 4.5; // CLAMPING THE VICE
2308
      // ASSIGN ACC TO RELEASE VICE
2309
     U M 18.6; // RELEASE THE EXIT FLAG VICE
= A 4.6; // RELEASE THE VICE
2311
      // ASSIGN ACC TO SHARE PARTS
2312
     U M 18.7; // SHARE EXIT FLAG SUB-APPARATUS
2313
     = A 4.7; // SHARE PARTIAL APPLIANCE
2314 // ASSIGN ACC ROBOTICS PROGRAM STOP (M30, M0, M1, M2)
2315 U.M.19.0; // EXIT FLAG ROBOTICS PROGRAM STOP (M30, M0, M1, M2)
2316
      = A 5.0; // ROBOTIC PROGRAM STOP (M30, M0, M1, M2)
2317
      // ACC ROBOTICS AXES ARE AT REF. POINT.
2318 U M 19.1; // ROBOTICS AXES ARE AT REF. POINT.
2319 = A 5.1; // ROBOTICS AXES ARE AT REF. POINT.
2320 // ACC ROBOTICS ASSIGN THE DOOR OPEN
2321
      U M 19.3; // EXIT FLAG ROBOTICS DOOR OPEN
2322 = A 5.3; // ROBOTICS DOOR OPEN
2323 // ASSIGN ACC ROBOTICS CLOSED DOOR
2324 U M 19.4; // EXIT FLAG ROBOTICS DOOR CLOSED
2325
      = A 5.4; // ROBOTIC DOOR CLOSED
     // ASSIGN ACC ROBOTICS REAR VICE
2326
2327 U M 19.5; // INITIAL FLAG ROBOTICS REAR VICE
2328 = A 5.5; // REAR ROBOTIC VICE
2329
      // ASSIGN ACC ROBOTICS CLAMPED VICE
2330
      U M 19.6; // EXIT FLAG ROBOTICS VICE CLAMPED
2331 = A 5.6; // ROBOTIC VICE CLAMPED
2332 // ASSIGN ACC ROBOTICS ALARM OUTPUT
2333 U M 19.7; // EXIT FLAG ROBOTICS ALARM OUTPUT
2334
      = A 5.7; // ROBOTIC ALARM OUTPUT
2335
     M001: NOP 0;
2336 UN DB10.DBX 2.0; // ACTIVATE AC 2000
2337 SPBN M002;
2338
      // AC95 ASSIGN THE OPEN DOOR KEY (MSTT)
2339
      U DB1.DBX 1374.0; // MACHINE KEYBOARD DOOR ON AC95
2340 = M 138.1; // HM MACHINE KEYBOARD DOOR OPEN
2341
      // AC95 ASSIGN DOOR CLOSED KEY (MSTT)
2342
     U DB1.DBX 1374.1; // MACHINE KEYBOARD DOOR TO AC95
2343
     = M 138.2; // HM MACHINE KEYBOARD DOOR CLOSED
2344
      // AC95 BUTTON ASSIGN VICE AC95
2345 U DB20.DBX 294.4; // VICE CLOSE BUTTON (PC)
2346
     UN DB20.DBX 294.3; // VICE OPEN BUTTON (PC)
2347
      FP M 138.7; // FM KEY VICE TO AC95
2348
      // AC95 BUTTON ASSIGN VICE TO AC95
2349
     U DB20.DBX 294.3; // VICE OPEN BUTTON (PC)
2350 UN DB20.DBX 294.4; // VICE CLOSE BUTTON (PC)
2351
      FP M 137.1; // FM BUTTON VICE ON AC95
2352
      // AC95 RELEASE ASSIGN AXES
2353
     U M 17.0; // EXIT FLAG ENABLE AXES
2354 = A 0.1; // AXES ENABLE
      // ASSIGN AC95 CONTROLLER ENABLE MAIN DRIVE
2355
2356
      U M 17.1; // INITIAL FLAG CONTROLLER ENABLE MAIN DRIVE
2357
      = A 0.0; // CONTROLLER ENABLE MAIN DRIVE
2358
2359
      // AC95 COOLANT ASSIGN (M8 = ON / M9 = OFF)
2360
     U M 17.2; // EXIT FLAG COOLANT (M8 = ON / M9 = OFF)
2361
      = A 0.4; // COOLANT (M8 = ON / M9 = OFF)
```

```
2362
     // ASSIGN AC95 BLOW-OUT VALVE
2363
     U M 18.2; // EXIT FLAG BLOW-OUT VALVE
2364 = A 4.2; // EXHAUST VALVE
2365 // AC95 ASSIGN THE DOOR OPEN
2366 U M 18.3; // EXIT FLAG DOOR OPEN
2367
     = A 4.3; // OPEN THE DOOR
2368
      // ASSIGN AC95 DOOR
2369 U M 18.4; // EXIT FLAG DOOR CLOSED
= A 4.4; // CLOSE THE DOOR
2371
      // AC95 ASSIGN VICE TO CLAMP
2372
     U M 18.5; // EXIT FLAG CLAMP VICE
2373 = A 4.5; // CLAMPING THE VICE
2374 // AC95 RELEASE VICE ASSIGN
2375 U M 18.6; // RELEASE THE EXIT FLAG VICE
2376
      = A 4.6; // RELEASE THE VICE
2377
      // AC95 ASSIGN SHARED UNIT
2378 U M 18.7; // SHARE EXIT FLAG SUB-APPARATUS
2379 = A 4.7; // SHARE PARTIAL APPLIANCE
2380
      // AC95 ASSIGN ROBOTICS PROGRAM STOP (M30, M0, M1, M2)
2381
      U M 19.0; // EXIT FLAG ROBOTICS PROGRAM STOP (M30, M0, M1, M2)
= A \cdot 5.0; // ROBOTIC PROGRAM STOP (M30, M0, M1, M2)
2383 // AC95 ROBOTIC AXES ARE AT REF.PKT.
2384 U M 19.1; // ROBOTICS AXES ARE AT REF. POINT.
2385
      = A 5.1; // ROBOTICS AXES ARE AT REF. POINT.
2386
      // AC95 ASSIGN ROBOTIC DOOR OPEN
2387 U M 19.3; // EXIT FLAG ROBOTICS DOOR OPEN
2388 = A 5.3; // ROBOTICS DOOR OPEN
2389
      // AC95 ASSIGN ROBOTICS CLOSED DOOR
2390 U M 19.4; // EXIT FLAG ROBOTICS DOOR CLOSED
2391 = A 5.4; // ROBOTIC DOOR CLOSED
2392 // AC95 ASSIGN ROBOTICS REAR VICE
2393 U \cdot M \cdot 19.5; \cdot / / \cdot INITIAL \cdot FLAG \cdot ROBOTICS \cdot REAR \cdot VICE
2394
     = A 5.5; // REAR ROBOTIC VICE
2395
      // AC95 ASSIGN ROBOTIC VICE CLAMPED
2396 U M 19.6; // EXIT FLAG ROBOTICS VICE CLAMPED
2397 = A 5.6; // ROBOTIC VICE CLAMPED
2398
      // AC95 ASSIGN ROBOTICS ALARM OUTPUT
     U M 19.7; // EXIT FLAG ROBOTICS ALARM OUTPUT
2399
2400 = A 5.7; // ROBOTIC ALARM OUTPUT
2401 M002: NOP 0;
     END_FUNCTION
2402
2403
     FUNCTION FC 0: VOID
2404 NAME: TOOL TURNERS
2405 BEGIN
2406 NETWORK 1
2407
      UN DB20.DBX 182.0; // NEW T-WORD
2408 SPB M001;
2409 L DB20.DBW 184; // T-WORD
2410 T DB20.DBW 356; // ACTIVE TOOL IN DB20
2411 M001: NOP 0;
2412 NETWORK 2
2413 L DB20.DBW 184; // T-WORD
2414 L W # 16 # 1; // HEX 1
2415
      <!; // COMPARISON TO SMALLER
     U DB20.DBX 182.0; // NEW T-WORD
2416
2417 = M 125.1; // T-WORD LOWER 1
2418 NETWORK 3
2419 L DB20.DBW 184; // T-WORD
2420 L W # 16 # 63; // TOOL NO. 99
2421 > I; // COMPARISON TO LARGER
2422 U DB20.DBX 182.0; // NEW T-WORD
2423 = M 125.2; // T-WORD GREATER 99
2424
     NETWORK 4
2425
     O M 125.1; // T-WORD LOWER 1
```

```
O M 125.2; // T-WORD GREATER 99
2426
2427
     S DB3.DBX 0.0; // T-WORD INVALID
2428 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
2429 O DB1.DBX 1370.3; // RESET KEY PRESSED
2430 R DB3.DBX 0.0;
2431 END_FUNCTION
2432 FUNCTION FC 1: VOID
2433 NAME: INITIALIZATIONS
2434 BEGIN
2435 NETWORK 1
2436 TITLE = MO, M1 TRIP
2437 U DB20.DBX 224.1; // M1 ACTIVE
2438 U DB20.DBX 324.5; // CONDITIONAL STOP ACTIVE
2439 O DB20.DBX 224.0 // M0 ACTIVE
2440 = M 0.0; // M0 / M1 ACTIVE
2441 U DB20.DBX 192.1; // M1 DYNAMIC
2442 U DB20.DBX 324.5; // CONDITIONAL STOP ACTIVE
2443 O DB20.DBX 192.0; // MO DYNAMIC
2444 = M 0.1; // HM M0 / M1 DYNAMIC
     O DB20.DBX 192.0; // M0 DYNAMIC
2445
2446 = DB20.DBX 256.0; // REPORT M0
2447 U DB20.DBX 192.1; // M1 DYNAMIC
2448 U DB20.DBX 324.5; // CONDITIONAL STOP ACTIVE
2449
     = DB20.DBX 256.1; // REPORT M1
2450 NETWORK 2
2451 TITLE = DOOR FEEDBACKS
2452 UN DB10.DBX 75.0; // ACTIVATE THE AUTOMATIC DOOR
2453 UN M 15.1; // MACHINE DOOR OPEN
2454 = DB1.DBX 1390.1; // PLC> SURF. DOOR CLOSED
2455 UN DB10.DBX 75.0; // ACTIVATE THE AUTOMATIC DOOR
2456 UN DB1.DBX 1390.1; // PLC> SURF. DOOR CLOSED
2457 = DB1.DBX 1390.0; // PLC> SURF. DOOR OPEN
2458
      NETWORK 3
2459 TITLE = PLC / OB -> SINGLE ITEM ACTIVE
2460 UN DB10.DBX 1.0; // PLC-MSD CONTINUOUS RUN ACTIVE
2461 = DB1.DBX 1390.3; // PLC / RM -> SINGLE ITEM ACTIVE
     NETWORK $ 4
2462
2463 TITLE = FEED SWITCH ON 0%
2464 L DB20.DBW 358; // FEED OVERRIDE ACTUAL VALUE
2465 L W # 16 # 0000; // LOAD 0
2466 == I; // COMPARISON TO EQUAL
2467
      = M 100.2; // FEED SWITCH ON 0%
2468
     NETWORK 5
2469 TITLE = 6008 MISSING CAN PART.
2470 O DB10.DBX 75.0; // ACTIVATE THE AUTOMATIC DOOR
2471
      O DB10.DBX 75.1; // tbsp. ACTIVATE VICE
2472 O DB10.DBX 75.3; // ACTIVATE THE BLOW DEVICE
2473 O DB10.DBX 75.6; // ACTIVATE SCHÄFER PARTIAL APPLIANCE
2474 O DB10.DBX 75.7; // ACTIVATE ROBOTICS INTERFACE
2475
      U · (;
      ON DB1.DBX 1414.0; // 1st CAN INPUT PORT (CAN ADDRESS 0)
2476
2477
      ON DB1.DBX 1415.0; // 1st CAN OUTPUT PORT (CAN ADDRESS 7)
2478 );
     UN DB10.DBX 2.0; // ACTIVATE AC 2000
2479
2480
      = DB2.DBX 1.0; // 6008 MISSING CAN PART.
2481 NETWORK 6
2482 TITLE = SELECTION OF THE FREQUENCY INVERTER
2483 L DB10.DBB 20; // HARWARE COMPONENTS
2484
     == I; // COMPARISON TO EQUAL
2485
2486 = M 115.0; // FELDERER FU
2487 L DB10.DBB 20; // HARWARE COMPONENTS
2488
2489
     == I; // COMPARISON TO EQUAL
```

```
= M 115.1; // LENZE FU
2490
2491 END FUNCTION
2492 FUNCTION FC 2: VOID
2493 NAME: ITEM COUNTER
2494 BEGIN
2495 NETWORK 1
2496 TITLE = PIECE COUNTER
2497 UN DB20.DBX 192.2; // M2 dyn
2498 UN DB20.DBX 195.6; // M30 dyn
2499 O DB20.DBX 324.2; // DRYRUN ACTIVE
2500 SPB M214;
2501 SET;
2502 L DB15.DBD 4; // Counter
2503 L DW # 16 # 000F 423F; // 999999 PIECES
2504 <> D;
    SPB M211;
2505
2506 SET;
2507 L DW # 16 # 0000_0000;
2508 T DB15.DBD 4;
    M211: NOP 0;
2509
2510 L DB15.DBD 4;
2511 L DW # 16 # 0000 0001;
2512 + D; // Piece counter +1 low
    T DB15.DBD 4;
2513
2514 L DB15.DBD 8; // BATCH COUNTER
2515 L DW # 16 # 000F_423F; // 999999 PIECES
2516 <> D;
2517
    SPB M213;
2518 SET;
2519 L DW # 16 # 0000 0000;
2520 T DB15.DBD 8;
2521 M213: NOP 0;
2522 L DB15.DBD 8;
2523 L DW # 16 # 0000_0001;
2524 + D; // Piece counter +1 low
2525 T DB15.DBD 8;
2526 M214: L DB15.DBD 0; // target number
2527 L DW # 16 # 0000_0000;
2528 <> D;
2529 SPB M202;
2530 SPA M201;
2531 M202: NOP 0;
2532 L DB15.DBD 4; // Qty.
2533 L DB15.DBD 0; // target number
2534 <D;
2535 SPB M201;
2536 SET;
2537 S DB3.DBX 5.3; // 7043 TARGET QUANTITY REACHED
2538 L DW # 16 # 0;
2539 T DB15.DBD 4;
2540 M201: NOP 0;
2541 NETWORK 2
2542 TITLE = NC START LOCKING
U DB3.DBX 5.3; // Message target quantity reached
= M 96.6; // Message target quantity reached NC_START VERR.
O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
2546 O DB1.DBX 1370.3; // RESET KEY PRESSED
2547 R DB3.DBX 5.3; // Message target quantity reached
2548 END FUNCTION
2549 FUNCTION FC 3: VOID
2550 NAME: MAIN DRIVE FELDERER FU
2551 BEGIN
2552 // OUTPUTS:
2553
```

```
U DB10.DBX 2.0; // ACTIVATE ACC
2554
2555
     SPBN M001;
2556 NETWORK
2557 TITLE = CONTROLLER ENABLE FOR MAIN DRIVE
2558 O DB20.DBX 340.0; // SPINDLE ON IN THE CLOCKWISE
O DB20.DBX 340.1; // SPINDLE ONE COUNTERCLOCKWISE
2560
     S M 145.2;
2561 U M 145.2;
2562 U M 104.2; // SUM SFG
2563
2564
     UN M 114.3; // ACTUAL SPEED LESS THAN 20RPM
2565
     U M 145.7 // HM CONTROLLER ENABLE FOR MAIN DRIVE
2566 = A·3.1·//·AXES·ENABLE·B·=·CONTROLLER·ENABLE·FOR·MAIN·DRIVE
2567 S M 145.7 // HM CONTROLLER ENABLE FOR MAIN DRIVE
2568
      NETWORK
2569
     TITLE = SET OUTPUT FOR PUL UP
2570 UN A 3.4
2571 S A 3.4
2572
     M001: NOP 0;
2573
     NETWORK 1
2574 TITLE = FELDERER MAIN DRIVE READY TO OPERATE
2575 UN M 15.7; // HA READY TO OPERATE
2576 = M 94.2; // SFG
     NETWORK 2
2577
2578 TITLE = FIELDS MONITORING HA SHARP
2579 U M 110.0; // AUX-ON
2580 L S5TIME # 2S; // 2S
2581
      SE T 2; // SWITCH-ON DELAY
2582 NETWORK 3
2583 TITLE = FELDERER 6013 MAIN DRIVE NOT READY
2584 UN DB10.DBX 2.0; // ACTIVATE AC 2000
2585 UN M 15.7; // HA SERVO-READY
2586
     L S5TIME # 200MS; // 0.2S
2587 SE T 3; // SWITCH-ON DELAY
2588 UT 2;
2589 U T 3;
2590 S DB2.DBX 1.5; // MAIN DRIVE NOT READY 6013
2591 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
2592 O DB1.DBX 1370.3; // RESET KEY PRESSED
2593 R DB2.DBX 1.5;
2594
     NETWORK 4
2595
      TITLE = FELDERER FM BUTTON SPINDLE START (MSST)
2596 O DB20.DBX 295.4; // SPINDLE START BUTTON
2597 UN M 200.0 // SET TOOL POSITIONS
2598 FP M 132.5; // FM BUTTON SPINDLE START
2599
     NETWORK 5
2600 TITLE = FELDERER FM KEY SPINDLE STOP (MSST)
2601 O DB20.DBX 295.3; // KEY SPINDLE HOLD
2602 UN M 200.0 // SET TOOL POSITIONS
2603 FP M 132.7; // FM KEY SPINDLE STOP
     NETWORK 6
2604
2605 TITLE = FIELDS CHANGE DIRECTION OF ROTATION WITH THE START BUTTON
2606 U M 106.7; // M3 / M4 SPINDLE START ENABLE
     UN DB20.DBX 324.0; // PROGRAM RUNNING
2607
2608
     U M 132.5; // FM BUTTON SPINDLE START
     S M 108.3; // HM SPINDLE SWITCHED ON
2609
2610 L S5TIME # 1S; // 1 SECOND
2611 SV T 44; // LONGER PULSE
2612
     O DB1.DBX 1370.3; // RESET KEY PRESSED
2613
     O DB1.DBX 1440.0; // RESET TRIPPED
2614 R M 108.3; // HM SPINDLE SWITCHED ON
2615 NETWORK 7
2616
      TITLE = FELDERER NEGATIVE FLANKENMERKER
2617 U T 44; // EXTENDED PULSE M3 / M4
```

```
2618 FN M 108.2; // FM / SPINDLE START BUTTON
2619 NETWORK 8
2620 TITLE = FELDERER
2621 U M 104.2; // SUM SFG
2622 UN M 131.7; // AXES IN MOVEMENT
2623 UN M 114.3; // ACTUAL SPEED LESS THAN 20RPM
2624 U M 132.7; // FM KEY SPINDLE STOP
2625 S M 132.1; // SPINDLE STOP ACTIVE
2626 S M 95.7; // SFG
2627 S M 91.7; // AFG, EFG
     U M 106.7; // OPERATION MANUAL AND INC1 UP TO 10000
2628
2629 R M 91.7; // AFG, EFG
2630 U M 110.0; // AUX ON
2631 U M 132.5; // FM BUTTON SPINDLE START
2632
     O DB1.DBX 1370.3; // RESET KEY PRESSED
2633 O DB1.DBX 1440.0; // RESET TRIPPED
2634 R M 132.1; // SPINDLE STOP ACTIVE
2635 R M 95.7; // SFG
2636 R M 91.7; // AFG, EFG
2637
     NETWORK 9
2638 TITLE = FELDERER
2639 UN M 110.0; // AUX-ON
2640 = M 95.0; // SPINDLE ENABLE
2641 NETWORK 10
2642 TITLE = FIELDS SUM SFG
2643 L MW 94; // WORD SFG (SPINDLE ENABLE)
2644 L W # 16 # 0; // H 0
2645 == I; // COMPARISON TO EQUAL
2646 = M 104.2; // SUM SFG
2647 NETWORK 11
2648 TITLE = FELDERER MAIN DRIVE ENABLE
2649 U M 104.2; // SUM SFG
2650
     UN DB1.DBX 1440.0; // RESET TRIPPED
2651 = M 114.0; // MAIN DRIVE ENABLE
2652 NETWORK 12
2653 TITLE = FIELDS SELECTION MAIN DRIVE M3
2654
     U M 114.0; // HA RELEASE
     U (;
2655
2656 UN DB10.DBX 1.6; // SPINDLE START AFTER MO
2657 U M 104.3; // SUM NC-STARTVERR.
     U M 101.0; // NC START MEMORY
2658
2659
     U M 100.6; // M3 MEMORY
2660 O;
2661 U DB20.
2662 DBX 192.3; // M3 DYN.
2663
2664 U T 44; // EXTENDED PULSE M3 / M4
2665 UN DB20.DBX 295.4; // SPINDLE START BUTTON
2666 );
2667
     = DB20.DBX 256.3; // RELEASE M3
      S DB20.DBX 340.0; // SPINDLE ON IN THE CLOCKWISE
2668
2669 R DB20.DBX 340.1; // SPINDLE ONE COUNTERCLOCKWISE
2670 R M 100.6; // M3 MEMORY
2671
      NETWORK 13
2672
      TITLE = FIELDS SELECTION MAIN DRIVE M4
2673 U M 114.0; // HA RELEASE
2674 U (;
2675 UN DB10.DBX 1.6; // SPINDLE START AFTER MO
2676
      U M 104.3; // SUM NC-STARTVERR.
2677
      U M 101.0; // NC START MEMORY
2678 U M 100.7; // M4 MEMORY
2679
2680 U DB20.DBX 192.4; // M4 DYN.
2681
      0;
```

```
U M 108.2; // FM / T44 M3 / M4
2682
2683
     U DB20.DBX 295.4; // SPINDLE START BUTTON
2684 );
2685 = DB20.DBX 256.4; // TRIGGER M4
2686 S DB20.DBX 340.1; // SPINDLE ONE COUNTERCLOCKWISE
2687
      R DB20.DBX 340.0; // SPINDLE ON IN THE CLOCKWISE
     R M 100.7; // M4 MEMORY
2688
     NETWORK 14
2689
2690 TITLE = FIELDS SELECTION MAIN DRIVE M5
2691
      U M 108.3; // HM SPINDLE SWITCHED ON
2692
     O M 132.7; // FM KEY SPINDLE STOP
2693
ON M 106.7; // M3 / M4 SPINDLE START ENABLE
2695
2696
      O DB1.DBX 1370.0; // 1st PLC LOOP
2697
      O DB20.DBX 192.5; // M5 DYNAMIC
2698 O DB1.DBX 1440.0; // RESET TRIPPED
2699 O DB1.DBX 1370.3; // RESET KEY PRESSED
2700
      O DB20.DBX 324.2; // DRYRUN ACTIVE
2701
      = M 114.5; // M5 HM
2702 NETWORK 15
2703 TITLE = FIELDS M3, M4 SAVE AT M0, M1
2704 U M 0.1; // HM MO / M1 STATIC
2705
      UN DB10.DBX 1.6; // SPINDLE START AFTER MO
2706 U DB20.DBX 224.3; // M3 STATIC
2707 S M 100.6; // M3 MEMORY
2708 U M 0.1; // HM M0 / M1 STATIC
2709
     UN DB10.DBX 1.6; // SPINDLE START AFTER MO
2710 U DB20.DBX 224.4; // M4 STATIC
2711 S M 100.7; // M4 MEMORY
2712 O DB1.DBX 1440.0; // RESET TRIPPED
2713 O DB1.DBX 1370.3; // RESET KEY PRESSED
2714
     R M 100.6; // M3 MEMORY
2715 R M 100.7; // M4 MEMORY
2716 NETWORK 16
2717 TITLE = FIELDS M5 OF M0, M1 AND M5 HM
2718
     U M 0.1; // HM M0 / M1 STATIC
     U·(;
2719
2720 O DB20.DBX 224.3; // M3 STATIC
2721 O DB20.DBX 224.4; // M4 STATIC
2722
      );
2723
     O M 114.5; // M5 HM
2724 UN M 101.0; // NC START MEMORY
2725 O DB20.DBX 195.6; // M30 DYN.
2726 O DB20.DBX 192.2; // M2 DYN.
2727
      = DB20.DBX 256.5; // TRIP M5
2728 R DB20.DBX 340.0; // SPINDLE ON IN THE CLOCKWISE
2729 R DB20.DBX 340.1; // SPINDLE ONE COUNTERCLOCKWISE
2730 R M 108.3; // HM SPINDLE SWITCHED ON
2731
      R M 145.2
2732
     NETWORK 17
2733 TITLE = FELDERER SPINDLE ENABLE
2734 U M 114.0; // HA RELEASE
2735 = DB20.DBX 340.5; // SPINDLE ENABLE
2736
      // END OF THE BUILDING
     NETWORK 18
2737
2738 TITLE = FELDERER MAIN DRIVE IS ON
2739 O DB20.DBX 224.5; // M5 STATIC
2740
      ON M 114.0; // HA RELEASE
2741
      = M 114.3; // ACTUAL SPEED LESS THAN 20RPM
2742 END FUNCTION
2743 FUNCTION FC 33: VOID
2744
     NAME: MAIN DRIVE LENZE FU
2745
     BEGIN
```

```
2746 NETWORK 1
2747
     TITLE = LENZE MAIN DRIVE READY TO OPERATE
2748 UN M 15.7; // SERVO READY HA
2749 = M 94.2; // SFG
2750 = M 96.7; // SERVO READY MAIN DRIVE NC START VERR.
2751 NETWORK 2
2752 TITLE = LENZE MONITORING HA SHARP
2753 U M 110.0; // AUX-ON
2754 L S5TIME # 4S; // 4S
2755 SE T 2; // SWITCH-ON DELAY
2756
     NETWORK 3
2757 TITLE -= LENZE 6013 MAIN DRIVE NOT READY
2758 ; UN DB10.DBX 2.0; // ACTIVATE AC 2000
2759 UN M 15.7; // SERVO READY HA
2760 L S5TIME # 200MS; // 0.2S
2761 SE T 3; // INPUT FILTER
2762 U T 2;
2763 U T 3;
2764 S DB2.DBX 1.5; // MAIN DRIVE NOT READY 6013
     O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
2765
2766 O DB1.DBX 1370.3; // RESET KEY PRESSED
2767 R DB2.DBX 1.5;
2768 NETWORK 4
2769
      TITLE = LENZE FM BUTTON SPINDLE START (MSST)
2770
      O DB20.DBX 295.4; // SPINDLE START BUTTON
2771 UN M 200.0 // SET TOOL POSITIONS
2772 FP M 132.5; // FM BUTTON SPINDLE START
2773 NETWORK 5
2774 TITLE = LENZE FM BUTTON SPINDLE HOLD (MSST)
2775 O DB20.DBX 295.3; // KEY SPINDLE HOLD
2776 UN M 200.0 // SET TOOL POSITIONS
2777 FP M 132.7; // FM KEY SPINDLE STOP
2778
     NETWORK 6
2779 TITLE = LENZE
2780 U M 106.7; // M3 / M4 SPINDLE START ENABLE
2781 UN DB20.DBX 324.0; // PROGRAM RUNNING
2782
     U M 132.5; // FM BUTTON SPINDLE START
2783 S M 108.3; // HM SPINDLE SWITCHED ON
2784 L S5TIME # 1S; // 1 SECOND
2785 SV T 44; // LONGER PULSE
2786
      O DB1.DBX 1370.3; // RESET KEY PRESSED
2787
      O DB1.DBX 1440.0; // RESET TRIPPED
2788 R M 108.3; // HM SPINDLE SWITCHED ON
2789 NETWORK 7
2790 TITLE = LENZE NEGATIVE FLANKENMERKER
2791
      U T 44; // EXTENDED PULSE M3 / M4
2792 FN M 108.2; // FM / SPINDLE START BUTTON
2793 NETWORK 8
2794 TITLE = LENZE
2795 U M 104.2; // SUM SFG
2796 UN M 131.7; // AXES IN MOVEMENT
2797 UN M 114.3; // ACTUAL SPEED LESS THAN 20RPM
2798 U M 132.7; // FM KEY SPINDLE STOP
2799 S M 132.1; // SPINDLE STOP ACTIVE
2800 S M 95.7; // SFG
2801 S M 91.7; // AFG, EFG KEY SPINDLE HOLD
2802 U M 106.7; // OPERATION MANUAL AND INC1 UP TO 10000
2803 R M 91.7; // AFG, EFG
     U M 110.0; // AUX ON
2804
     U M 132.5; // FM BUTTON SPINDLE START
2805
2806 O DB1.DBX 1370.3; // RESET KEY PRESSED
2807 O DB1.DBX 1440.0; // RESET TRIPPED
2808 R M 132.1; // SPINDLE STOP ACTIVE
2809
     R M 95.7; // SFG
```

```
2810 R M 91.7; // AFG, EFG
2811 NETWORK 9
2812 TITLE = LENZE
2813 UN M110.0; // AUX-ON
2814 = M 95.0; // SPINDLE ENABLE
2815 NETWORK 10
2816 TITLE = LENZE SUM SFG
2817 ; U M 95.0; // AUX-ON
2818 ; U M 95.1; // SPN IN MOTION (SFG)
; U M 95.2; // SFG MELDUNG 7050 NO PART CLOSED
2820 ; U M 94.1; // SFG TOOL EXPRESSED
2821 ; U M 94.3; // SFG TOOL EXPRESSED
2822 L MW 94; // WORD SFG (SPINDLE ENABLE)
2823 L W # 16 # 0; // H 0
2824 == I; // COMPARISON TO EQUAL
2825 = M 104.2; // SUM SFG
2826 NETWORK 11
2827 TITLE = LENZE MAIN DRIVE ENABLE
2828 U M 104.2; // SUM SFG
     UN DB1.DBX 1440.0; // RESET TRIPPED
2829
2830 = M 114.0; // MAIN DRIVE ENABLE
2831 NETWORK 12
2832 TITLE = LENZE SELECT MAIN DRIVE M3
2833
     U M 114.0; // HA RELEASE
2834 U (;
2835 UN DB10.DBX 1.6; // SPINDLE START AFTER MO
2836 U M 104.3; // SUM NC-STARTVERR.
2837
     U M 101.0; // NC START MEMORY
     U M 100.6; // M3 MEMORY
2838
2839
2840 U DB20.DBX 192.3; // M3 DYN.
2841
2842
     U T 44; // EXTENDED PULSE M3 / M4
UN DB20.DBX 295.4; // SPINDLE START BUTTON
2844 );
2845 S M 114.1
2846 U M 114.1
     L S5T # 0S300MS;
2847
2848 SE T 0;
2849 U M 114.1
2850 U T 1;
2851 O T 0;
2852 = DB20.DBX 256.3; // RELEASE M3
2853 S DB20.DBX 340.0; // SPINDLE ON IN THE CLOCKWISE
2854 R DB20.DBX 340.1; // SPINDLE ONE COUNTERCLOCKWISE
2855 R M 100.6; // M3 MEMORY
2856 R M 114.1
2857 NETWORK 13
2858 TITLE = LENZE SELECTION MAIN DRIVE M4
2859 U M 114.0; // HA RELEASE
2860 U (;
2861 UN DB10.DBX 1.6; // SPINDLE START AFTER MO
2862 U M 104.3; // SUM NC-STARTVERR.
2863 U M 101.0; // NC START MEMORY
     U M 100.7; // M4 MEMORY
2864
2865
     0;
2866 U DB20.DBX 192.4; // M4 DYN.
2867 O;
2868
      U M 108.2; // FM / T44 M3 / M4
     U DB20.DBX 295.4; // SPINDLE START BUTTON
2869
2870 );
2871 S M 114.2
2872
     U M 114.2
2873
     L S5T # 0S300MS;
```

```
2874
     SE T 1;
2875 U M 114.2
2876 U T 0;
2877 O T 1;
2878 = DB20.DBX 256.4; // TRIGGER M4
2879 S DB20.DBX 340.1; // SPINDLE ONE COUNTERCLOCKWISE
2880 R DB20.DBX 340.0; // SPINDLE ON IN THE CLOCKWISE
2881 R M 100.7; // M4 MEMORY
2882 R M 114.2
2883 NETWORK 14
2884
      TITLE = LENZE SELECTION MAIN DRIVE M5
2885 U M 108.3; // HM SPINDLE SWITCHED ON
2886 U (;
      O M 132.7; // FM KEY SPINDLE STOP
2887
2888
      ON M 106.7; // M3 / M4 SPINDLE START ENABLE
2889
     );
2890 O DB1.DBX 1370.0; // 1st PLC LOOP
2891 O DB20.DBX 192.5; // M5 DYNAMIC
2892
     O DB1.DBX 1440.0; // RESET TRIPPED
2893
     O DB1.DBX 1370.3; // RESET KEY PRESSED
2894 O DB20.DBX 324.2; // DRYRUN ACTIVE
2895 = M 114.5; // M5 HM
2896 NETWORK 15
2897
      TITLE = LENZE M3, M4 SAVE AT M0, M1
2898 U M 0.1; // HM M0 / M1 DYNAMIC
2899 UN DB10.DBX 1.6; // SPINDLE START AFTER MO
2900 U DB20.DBX 224.3; // M3 STATIC
2901
      S M 100.6; // M3 MEMORY
2902 U M 0.1; // HM M0 / M1 DYNAMIC
2903 UN DB10.DBX 1.6; // SPINDLE START AFTER MO
2904 U DB20.DBX 224.4; // M4 STATIC
2905 S M 100.7; // M4 MEMORY
2906
      O DB1.DBX 1440.0; // RESET TRIPPED
2907 O DB1.DBX 1370.3; // RESET KEY PRESSED
2908 R M 100.6; // M3 MEMORY
2909 R M 100.7; // M4 MEMORY
2910 NETWORK 16
      TITLE = LENZE M5 FROM M0, M1, M2, M30 AND M5 HM
2911
2912 U M 0.1; // HM M0 / M1 DYNAMIC
2913 U (;
2914
      O DB20.DBX 224.3; // M3 STATIC
2915
     O DB20.DBX 224.4; // M4 STATIC
2916 );
2917 O M 114.5; // M5 HM
2918 UN M 101.0; // NC START MEMORY
2919
     O DB20.DBX 195.6; // M30 DYN.
2920 O DB20.DBX 192.2; // M2 DYN.
2921 = DB20.DBX 256.5; // REPORT M5
2922 R DB20.DBX 340.0; // SPINDLE ON IN THE CLOCKWISE
2923 R DB20.DBX 340.1; // SPINDLE ONE COUNTERCLOCKWISE
     R M 108.3; // HM SPINDLE SWITCHED ON
2924
2925 R M 114.1
2926 R M 114.2
2927
     R M 114.4
2928
     NETWORK 17
2929
     TITLE = LENZE SPINDLE ENABLE
2930 U M 114.0; // HA RELEASE
= DB20.DBX 340.5; // SPINDLE ENABLE
     NETWORK 18
2932
2933
      TITLE = LENZE MAIN DRIVE IS ON
2934 U M 16.0; // n = 0 RELAY FROM LENZE-FU
2935 ON M 15.7; // HA SERVO-READY
2936
      = M 114.3; // ACTUAL SPEED LESS THAN 20RPM
2937
     R M 114.6 // HM CONTROLLER ENABLE FOR MAIN DRIVE
```

```
2938
     NETWORK 19
2939 TITLE = LENZE CONTROLLER ENABLE FOR MAIN DRIVE
2940 O M 114.1; // REQUIREMENT M3
2941 O M 114.2; // REQUIREMENT M4
2942 = M 90.7; // TAKE AWAY AFG AND EFG
2943 S M 114.4; // HM
     U M 114.4; // HM
2944
2945 U M 104.2; // SUM SFG
2946 O
2947
     UN M 114.3; // ACTUAL SPEED LESS THAN 20RPM
2948
     U M 114.6; // HM CONTROLLER ENABLE FOR MAIN DRIVE
     = ·M·17.1; ·//·INITIAL·FLAG·CONTROLLER·ENABLE·MAIN·DRIVE
2949
2950 S.M.114.6; // HM.CONTROLLER ENABLE FOR MAIN DRIVE
2951 END_FUNCTION
2952
      FUNCTION FC 4: VOID
2953
     NAME: OPERATING MODES
2954 BEGIN
2955 NETWORK 1
2956 TITLE = SUM SPINDLE ON / OFF
2957
     UN DB20.DBX 327.2; // REFERENCE OPERATING MODE
2958 UN DB20.DBX 326.4; // AUTOMATIC MODE
2959 UN DB20.DBX 326.2; // OPERATING MODE MDI
2960 UN DB20.DBX 326.1; // EDIT MODE
2961
      UN DB20.DBX 326.3; // OPERATING MODE REPOS
2962 UN DB20.DBX 327.4; // PRESET OPERATING MODE
2963 = M \cdot 106.7; // M3 / M4 SPINDLE ENABLE IN THE -
2964 // OPERATING MODE JOG AND INC
2965
      END FUNCTION
     FUNCTION FC 5: VOID
2966
2967
     NAME: AXES READINESS
2968 BEGIN
2969 NETWORK 0
2970
     TITLE = RELEASE AXES
2971 U DB1.DBX 1370.0; // 1st PLC LOOP
2972 L S5TIME # 100MS; // 1S
2973 SS T 4; // SWITCH-ON DELAY (STORING)
2974
      U M 115.1; // LENZE FU
     U \cdot T
2975
2976 4; // SWITCH-ON DELAY (STORING)
2977 = M 17.0; // EXIT FLAG ENABLE AXES
2978
      NETWORK 1
2979
      TITLE = AXES READY FOR OPERATION
2980 UN M 15.3; // X-AXIS SERVO-READY
2981 UN M 15.4; // Y-AXIS SERVO-READY
2982 UN M 15.5; // Z-AXIS SERVO-READY
2983
      = M 111.0; // AXES READINESS
2984 NETWORK 2
2985 TITLE = AXES READY FOR OPERATION AFG / EFG
2986 UN M 111.0; // AXES READY TO OPERATE
2987
     = M 90.1; // AXES READY FOR OPERATION AFG / EFG
     NETWORK 3 8 *******
2988
2989 TITLE = SURVEILLANCE AXES SHARP
2990 U M 110.0; // AUX ON
2991
      L S5TIME # 1S500MS; // 15X0.1S
2992
     SE T 5; // START T5 AS SWITCH-ON DELAY.
2993
     NETWORK 4
2994 TITLE = ALARM DRIVE X-AXIS DEFECTIVE
2995 U M 15.3; // X-AXIS SERVO-READY
2996
      U T 5; // MONITORING AXES SHARP
2997
      S DB2.DBX 1.2; // ALARM DRIVE X-AXIS DEFECTIVE
2998 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
2999
      O DB1.DBX 1370.3; // RESET KEY PRESSED
3000 R DB2.DBX 1.2; // ALARM DRIVE X-AXIS DEFECTIVE
3001
     NETWORK 5
```

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3002
     TITLE = ALARM DRIVE Y-AXIS DEFECTIVE
3003 U M 15.4; // Y-AXIS SERVO READY
3004 U T 5; // MONITORING AXES SHARP
3005 S DB2.DBX 1.3; // ALARM DRIVE Y-AXIS DEFECTIVE
3006 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
3007
      O DB1.DBX 1370.3; // RESET KEY PRESSED
     R DB2.DBX 1.3; // ALARM DRIVE Y-AXIS DEFECTIVE
3008
3009 NETWORK 6
3010 TITLE = ALARM DRIVE Z-AXIS DEFECTIVE
3011
      U M 15.5; // Z-AXIS SERVO-READY
3012
     U T 5; // MONITORING AXES SHARP
3013 L S5TIME # 500MS;
3014 SE T 31;
3015 U T 31;
3016 S DB2.DBX 1.4; // ALARM DRIVE Z-AXIS DEFECTIVE
3017 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
3018 O DB1.DBX 1370.3; // RESET KEY PRESSED
3019 R DB2.DBX 1.4; // ALARM DRIVE Z-AXIS DEFECTIVE
3020 NETWORK 6
     TITLE = ALARM DRIVE TOOL AXIS DEFECTIVE 8 **********
3021
3022 ; U M 15.xxx; // TOOL-AXIS SERVO-READY
3023 ; U T 5; // MONITORING AXES SHARP
     ; S DB2.DBX 1.xxx; // ALARM DRIVE Z-AXIS DEFECTIVE
3024
3025
3026
     ; O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
3027 ; O DB1.DBX 1370.3; // RESET KEY PRESSED
3028 ; R DB2.DBX 1.4; // ALARM DRIVE Z-AXIS DEFECTIVE
3029
     END FUNCTION
3030 FUNCTION FC 6: VOID
3031 NAME: AXES JOG
3032 BEGIN
3033 NETWORK 1
3034 TITLE = ACHSEN_JOG ENABLE
3035 U DB20.DBX 340.4; // AXLE ENABLE
3036 = M 112.0; // ACHSEN JOG ENABLE
3037 NETWORK 2
3038 TITLE = ACHSEN_JOG / STARTVERR.
3039 U DB20.DBX 1.2; // FC JOG_REQUIREMENT
3040 UN M 112.0; // ACHSEN_JOG ENABLE
3041 R DB20.DBX 1.2; // FC JOG_REQUIREMENT
3042
     NETWORK
3043
      TITLE = JOG A-AXIS / STARTVERL.
3044 U DB20.DBX 1.2; // FC JOG AXES
3045 U·(
3046 O DB20.DBX 11.2; // JOG CHANNEL AXIS A IN POS. DIRECTION
3047
      O DB20.DBX 13.2; // JOG CHANNEL AXIS A IN NEGATIVE DIRECTION
3048 UN A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
3049 )
3050 R DB20.DBX 1.2; // FC JOG AXES
3051
      NETWORK
3052 TITLE = AXES INC / STARTVERR.
3053 ON M 112.0; // ACHSEN JOG ENABLE
3054 O M 100.2; // FEED SWITCH ON 0%
3055 U DB20.DBX 1.3; // FC INC REQUEST
3056
     R DB20.DBX 1.3; // FC INC REQUEST
3057
     END_FUNCTION
3058 FUNCTION FC 32: VOID
3059 NAME: AUTOMATICALLY SWITCH TO BA REF
3060
      BEGIN
3061 NETWORK
3062 TITLE = PREVENT AUTOMATICALLY SWITCHING TO BAREF WITH THE AUX-ON BUTTON (TO DRIVE FREE
      !!)
3063 UN M 121.0
3064
     UN M 121.2
```

```
3065
     UN M 52.2 // REFERENCE POINT X, Y, Z AND TOOL C-AXIS ACTIVE
3066 U DB1.DBX 1374.4 // AUX ON BUTTON
3067 UN M 200.0 // SET TOOL POSITIONS
3068 S M 121.1
3069 S M 121.0
3070 U DB1.DBX 1374.4 // AUX ON BUTTON
3071 UN M 200.0 // SET TOOL POSITIONS
3072 UN M 121.1
3073 = M 121.2
3074 R M 121.0
3075
     UN DB1.DBX 1374.4 // AUX ON BUTTON
3076 R M 121.1
3077 NETWORK
3078 TITLE = AUTOMATICALLY SWITCH TO BA REF
3079 U DB1.DBX 1370.0; // 1st PLC LOOP
3080 S DB100.DBX500.0; // BIT FOR BA JOG
3081 L DB20.DBW 288 // BA SELECTION
3082 L 0
3083
     == I.
3084
     SPB M0011
3085 L DB20.DBW 288 // BA SELECTION
3086 T DB100.DBW 500
3087 M0011: NOP 0
3088
      UN M 52.3 // TOOL ABORTED
3089 UN DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
3090 UN DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
3091 UN·M·52.2·// REFERENCE POINT·X, Y, Z·AND·TOOL·C-AXIS·ACTIVE
3092
     UN M 121.0
     ; U M 110.0; // AUX-ON
3093
3094 SPBN M0012
3095 L W # 16 # 0400 // SET BIT BA REF
3096 T DB20.DBW 288 // BA SELECTION
3097
      SPA M0013
3098 M0012: NOP 0
3099 L DB100.DBW 500
3100 T DB20.DBW 288 // BA SELECTION
3101
      M0013: NOP 0
3102 L DB20.DBW 326
3103 L DB20.DBW 288
3104 <> I.
3105 = DB20.DBX 0.0 // BA CHANGE REQUEST
3106
     END FUNCTION
3107 FUNCTION FC 7: VOID
3108 NAME: AXES REFERENCING
3109 BEGIN
3110 NETWORK 1
3111 TITLE = REFERENCE RELEASE
3112 U M 104.0; // SUM AFG
3113 U M 110.0; // AUX_ON AUTO
3114 UN M 100.2; // FEED SWITCH ON 0%
     UN M 52.3 // TOOL ABORTED
3115
3116 UN DB3.DBX 6.7; // MESSAGE 7055 OPEN TOOL CLAMPING SYSTEM
3117 UN DB3.DBX 7.0; // MESSAGE 7056 ILLEGAL TOOL NUMBER IN THE SETTING DATA
3118 UN DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
     UN DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
3119
3120 = M 120.0; // REFERENCE RELEASE
3121 NETWORK 2
3122 TITLE = APPROACH REFERENCE POINT CANCEL (TRIGGER RESET)
3123
      U DB20.DBX 327.2; // REFERENCE OPERATING MODE
3124 U M 15.1; // MACHINE DOOR OPEN
3125 U M 131.7;
3126 // AXES IN MOVEMENT
3127
     SPBN M001;
3128
     = DB1.DBX 1440.0; // TRIGGER NC RESET
```

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M001: NOP 0
3129
3130 NETWORK
3131 TITLE = REFPKT.X, Y, Z, APPROACH FROM MST AT THE SAME TIME
3132 U DB20.DBX 830.4; // REFERENCE ALL AXES FROM MST
3133 U DB20.DBX 327.2; // REFERENCE OPERATING MODE
3134 U M 120.0; // REFERENCE RELEASE
3135
     UN M 121.3; // REFPKT.X, Z, APPROACH AT THE SAME TIME
3136 FP M 121.4 // FM REFPKT.X, Z, APPROACH FROM MST AT THE SAME TIME
3137 U.M. 121.4 // FM REFPKT.X, Z, AT THE SAME TIME APPROACH FROM MST
3138 SPBN M331;
3139
      = DB20.DBX 8.0; // REFERENCE X-AXIS
3140 = DB20.DBX 8.1; // REFERENCE Y-AXIS
3141 = DB20.DBX 8.2; // REFERENCING Z-AXIS
3142 = DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3143 M331: NOP 0
3144 NETWORK 4
3145 TITLE = REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3146 U M 120.0; // REFERENCE RELEASE
3147
     UN M 121.3; // REFPKT.X, Z, APPROACH AT THE SAME TIME
3148
     U DB20.DBX 8.0; // REFERENCE X-AXIS
3149
     U DB20.DBX 8.1; // REFERENCE Y-AXIS
3150 U DB20.DBX 8.2; // REFERENCING Z-AXIS
3151 S M 121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3152
     FP M 121.5; // FM REFPKT.X, Z, APPROACH AT THE SAME TIME
3153 O DB1.DBX 1370.3; // RESET KEY PRESSED
3154 O DB1.DBX 1440.0 // TRIGGER NC RESET
3155 O M 122.5; // FM REFERENCE POINT ACTIVE
3156
      O M 52.6 // FM REFERENCE POINT X, Y, Z AND TOOL C-AXIS ACTIVE
3157
     R M 121.3; // REFPKT.X, Z, APPROACH AT THE SAME TIME
3158 ; 8 (((((U M 120.4; // REFERENCE POINT X & Y & Z-AXIS ACTIVE
3159 ; U.M. 121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3160
     ; R DB20.DBX 8.0; // REFERENCE X-AXIS
3161
      ; R DB20.DBX 8.1; // REFERENCE Y-AXIS
3162
     ; R DB20.DBX 8.2; // REFERENCING Z-AXIS
3163 ; R M 121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3164 NETWORK 5
3165
      TITLE = DISABLE REFERENCE POINT
3166 U DB1.DBX 134.0; // REFERENCE POINT X-AXIS ACTIVE
3167 U DB1.DBX 134.1; // REFERENCE POINT Y-AXIS ACTIVE
3168 U DB1.DBX 134.2; // REFERENCE POINT Z-AXIS ACTIVE
3169
      = M·120.4; // REFERENCE POINT X & Y & Z AXIS ACTIVE
      O M 120.6 // NEGATIVE FM DOOR OPEN
3170
3171 O M 120.5 // FM EXIT FOR AUXILIARY RELAY DOOR CLOSED
3172 O DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
3173
      O DB1.DBX 1370.3; // RESET KEY PRESSED
3174
      O DB1.DBX 1440.0 // TRIGGER NC RESET
3175
3176
      ON M 26.0 // ABSOLUTE AXIS 4 (TOOL) 0 DEGREES REACHED
3177
      O E 16.4 // REF BERO WZW
3178
      )
3179
      0 (
3180 U DB20.DBX 9.2; // REFERENCING CHANNEL AXIS A
3181 U DB10.DBX 100.0 // SET TOOL TURNERS ACTIVATED
3182
      O M 121.5; // APPROACH FM REFPKT XYZ AT THE SAME TIME
3183
      U M 120.0; // REFERENCE RELEASE
     U M 23.6; // Z-AXIS IN THE SAFE AREA
3184
3185
      O DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
3186
3187
      U M 52.5 // TOOL TURNER ACTIVATED
3188
     FP M 121.6
3189 U M 121.6
3190 SPBN M111;
3191
      = DB20.DBX 348.4; // DISABLE CHANNELO REFERENCE POINT OF THE ROUND AXES
3192
     = DB25.DBX 348.4; // DISABLE CHANNEL1 REFERENCE POINT OF THE ROUND AXES
```

```
R M 120.2 // TOOL AXIS 0 DEGREES REACHED
3193
3194
     R M 120.3 // HM TOOL AXIS 0 DEGREES REACHED
3195
     R M 25.0 // TOOL 0 PICK UP DONE
3196 M111: NOP 0
3197 U·M·121.5; ·// APPROACH·FM REFPKT·XYZ·AT·THE·SAME·TIME
3198
      ; 8 (((((UN M 52.5 // TOOL TURNER ACTIVATED
3199
     ; UN M 52.7 // ROUND AXLE ACTIVATED
3200 O DB2.DBX 1.2; // ALARM X-AXIS DEFECTIVE
3201
     O DB2.DBX 1.3; // ALARM Y-AXIS DEFECTIVE
3202
     O DB2.DBX 1.4; // ALARM Z-AXIS DEFECTIVE
3203
     O DB2.DBX 1.5; // ALARM TOOL AXIS DEFECTIVE 8 *********
3204 O DB2.DBX 0.0; // ALARM EMERGENCY STOP
3205 FP M 121.7
3206 U M 121.7
3207
     SPBN M221;
3208
     = DB20.DBX 348.0; // DISABLE CHANNELO REFERENCE POINT
3209 = DB25.DBX 348.0; // DISABLE CHANNEL1 REFERENCE POINT
3210 = DB20.DBX 348.4; // DISABLE CHANNELO REFERENCE POINT OF THE ROUND AXES
3211
      = DB25.DBX 348.4; // DISABLE CHANNEL1 REFERENCE POINT OF THE ROUND AXES
3212
     U M 121.5; // APPROACH FM REFPKT XYZ AT THE SAME TIME
3213 S M 121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3214 R M 120.4; // REFERENCE POINT X & Y & Z AXIS ACTIVE
3215 = DB20.DBX 348.4; // DISABLE CHANNELO REFERENCE POINT OF THE ROUND AXES
3216
      = DB25.DBX 348.4; // DISABLE CHANNEL1 REFERENCE POINT OF THE ROUND AXES
     R M 120.2 // TOOL AXIS O DEGREES REACHED
3217
3218 R M 120.3 // HM TOOL AXIS 0 DEGREES REACHED
3219 R M 25.0 // TOOL 0 PICK UP DONE
3220 M221: NOP 0
3221
     NETWORK 6
3222 TITLE = DISABLE APPROACH TO REFERENCE
3223 U DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3224 UN M 120.0; // REFERENCE RELEASE
3225
      R DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3226 S DB20.DBX 318.7; // NEG. ACKNOWLEDGMENT DNC
3227 NETWORK 7
3228 TITLE = REFERENCE Z-AXIS (FC-CODE)
3229
     U M 121.5; // FM REFPKT.X, Z, APPROACH AT THE SAME TIME
3230 U DB20.DBX 8.2; // REFERENCING Z-AXIS
3231 UN·M·120.4; // REFERENCE POINT X & Y & Z AXIS ACTIVE
3232
3233
     U M 120.0; // REFERENCE RELEASE
3234
      UN M 121.3; // REFPKT.X, Z, APPROACH AT THE SAME TIME
3235
     U DB20.DBX 8.2; // REFERENCING Z-AXIS
3236
     );
3237
     0(
3238
      U M 121.5; // FM REFPKT.X, Z, APPROACH AT THE SAME TIME
     UN M 52.5 // TOOL TURNER ACTIVATED
3239
3240 UN M 52.7 // ROUND AXLE ACTIVATED
3241
3242
      = DB20.DBX 8.2; // REFERENCING Z-AXIS
3243
      NETWORK 8
3244 TITLE = FM REFERENZPOINT Z-AXIS ACTIVE
3245 U DB1.DBX 134.2; // REFERENCE POINT Z-AXIS ACTIVE
3246 FP M 120.7; // FM REFERENCE POINT Z-AXIS ACTIVE
3247
      NETWORK 9
3248
     TITLE = REFERENCE X-AXIS (FC-CODE)
3249 U M 121.3; // REFPKT.X, Z, APPROACH AT THE SAME TIME
3250 U M 120.7; // FM REFERENCE POINT Z-AXIS ACTIVE
3251
      0(;
3252 U M 120.0; // REFERENCE RELEASE
3253 UN M 121.3; // REFPKT.X, Z, APPROACH AT THE SAME TIME
3254 U DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
      U DB20.DBX 8.0; // REFERENCE X-AXIS
3255
3256
      );
```

```
= DB20.DBX 8.0; // REFERENCE X-AXIS
3257
3258
     R DB20.DBX 8.2; // REFERENCING Z-AXIS
3259
     SPBN M002;
3260 = DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3261 M002: NOP 0;
     NETWORK 10
3262
3263
      TITLE = REFERENCE Y-AXIS (FC-CODE)
3264 U.M.121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3265 U M 120.7; // FM REFERENCE POINT Z-AXIS ACTIVE
3266 0(;
3267
      U M 120.0; // REFERENCE RELEASE
3268
     UN M 121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3269
     U DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3270 U DB20.DBX 8.1; // REFERENCE Y-AXIS
3271
3272
     = DB20.DBX 8.1; // REFERENCE Y-AXIS
3273 NETWORK 8
3274 TITLE = FM X, Y, Z REFERENCE POINT ACTIVE
3275
      U M 120.4; // REFERENCE POINT X & Y & Z AXIS ACTIVE
3276
     FP M 120.1; // FM REFERENCE POINT X, Y and Z-AXIS ACTIVE
3277
     R M 121.0
3278 U DB1.DBX 134.0; // REFERENCE POINT X-AXIS ACTIVE
3279 U DB1.DBX 134.1; // REFERENCE POINT Y-AXIS ACTIVE
3280
      U DB1.DBX 134.2; // REFERENCE POINT Z-AXIS ACTIVE
3281 U (
3282 O DB1.DBX 134.4; // REFERENCE POINT TOOL AXIS ACTIVE
3283
     ON M 52.5 // TOOL TURNER ACTIVATED
3284
3285
     U·(
3286
     O DB1.DBX 134.5; // REFERENCE POINT A-AXIS ACTIVE
3287
     ON M 52.7 // ROUND AXIS ACTIVATED
3288
3289
      = M·52.2 // REFERENCE POINT X, Y, Z AND TOOL C-AXIS ACTIVE
     FP M 52.6 // FM REFERENCE POINT X, Y, Z AND TOOL C-AXIS ACTIVE
3290
3291 NETWORK 8
3292 TITLE = REFERENCE TOOL
3293
     U M 52.5 // TOOL TURNER ACTIVATED
     SPBN M003;
3294
3295 NETWORK 10
3296 TITLE = Z-AXIS IN THE SAFE AREA
3297 L DB1.DBD 8; // Z-AXIS IS POSITION
3298
     L MD 74; // Z-AXIS TOOL SWIVEL POSITION NO TOOL IN THE SPINDLE
3299
     > = R
3300 = M \ 23.6; // Z-AXIS IN THE SAFE AREA
3301 NETWORK 10
3302
      TITLE = REFERENCE TOOL AXIS (FC CODE)
3303 U.M.121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3304 U M 120.7; // FM REFERENCE POINT Z-AXIS ACTIVE
3305
     ; 8 ((((0 (
3306
      ; U M 120.4; // REFERENCE POINT X & Y & Z AXIS ACTIVE
3307
      ; U M 121.5; // APPROACH FM REFPKT XYZ AT THE SAME TIME
3308
     ; )
3309
     0(
3310 UN M 121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
      U DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3311
3312
     U DB20.DBX 9.2; // REFERENCING CHANNEL AXIS A
3313
     U DB10.DBX 100.0 // SET TOOL TURNERS ACTIVATED
3314
      )
3315
      U · (
3316
      O DB10.DBX 100.0 // SET TOOL TURNERS ENABLED
3317
     O M 23.6; // Z-AXIS IN THE SAFE AREA
3318
3319
     U M 120.0; // REFERENCE RELEASE
3320
      SPBN M004;
```

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3321
      = DB25.DBX 9.4; // REFERENCING CHANNEL AXIS C
3322
      = DB25.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3323 R M \cdot 120.2 \cdot // \cdot TOOL \cdot AXIS \cdot 0 \cdot DEGREES \cdot REACHED
3324 R M 120.3 // HM TOOL AXIS 0 DEGREES REACHED
3325 M004: NOP 0;
3326
      NETWORK 10
3327
      TITLE = TOOL AXIS REFERENCE FROM AXIS KEY (THE KEY IS ONLY EFFECTIVE IN SETTING MODE !!)
3328 U DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3329 U DB20.DBX 9.2; // REFERENCING CHANNEL AXIS A
3330 U DB10.DBX 100.0 // SET TOOL TURNERS ACTIVATED
3331
      R DB20.DBX 9.2; // REFERENCING CHANNEL AXIS A
     R DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3332
3333 NETWORK
3334 TITLE = MOVE TOOL AXIS TO 0 °
3335
      U DB1.DBX 134.4; // REFERENCE POINT TOOL AXIS ACTIVE
3336 FP M 122.0 // FM REFERENCE POINT TOOL AXIS ACTIVE
3337 UN DB10.DBX 100.0 // SET TOOL MILL55 ENABLED
3338
     0(
3339
       U DB10.DBX 100.0 // SET TOOL MILL55 ACTIVATED
3340
     U M 200.0 // SET TOOL POSITIONS
3341
3342
     U M 122.0 // FM REFERENCE POINT TOOL AXIS ACTIVE
3343
      UN M 120.2 // TOOL AXIS 0 DEGREES REACHED
3344
      UN M 120.3 // HM TOOL AXIS 0 DEGREES REACHED
     U M 120.0; // REFERENCE RELEASE
3345
3346 U (
3347
       O DB10.DBX 100.0 // SET TOOL TURNERS ENABLED
3348
      O M 23.6; // Z-AXIS IN THE SAFE AREA
3349
3350 SPBN M006;
3351 S M 120.3 // HM TOOL AXIS 0 DEGREES REACHED
3352
     = DB25.DBX 1.4; // SEND NC BLOCK
3353
       = DB25.DBX 548.5; // SET EXACT HOLD MODE
3354 = DB25.DBX 549.0; // G1 IS TRIGGERED
3355 = DB25.DBX 549.4; // FEED RATE IN DEGREES / S VALUE IN DBD556
3356 L DB10.DBD 28; // FEED VALUE IN DEGREES / SECONDS
3357
      T DB25.DBD 556; // F-VALUE IN M / S OR M / U
3358
     S DB25.DBX 21.4; // POSITION REQUEST FOR CHANNEL AXIS C
3359
     L + 0.00E0;
3360 T DB25.DBD 70; // POSITION VALUE FOR CHANNEL AXIS C
3361
      \mathbf{L} \cdot \mathbf{0}
3362
      T MW 46
3363 M006: NOP 0;
3364 U.M. 120.3 // HM. TOOL AXIS 0 DEGREES REACHED
     U DB25.DBX 332.0; // NC BLOCK DONE
3365
3366
      SPBN M007;
3367
      S M 120.2 // TOOL AXIS 0 DEGREES REACHED
3368 R M 120.3 // HM TOOL AXIS 0 DEGREES REACHED
3369 R DB25.DBX 332.0; // NC BLOCK DONE
3370
      U E 4.2; // 12mm BERO TOOL EQUIPPED
      S M 46.1 // TOOL 1 PRESENT
3371
3372 M007: NOP 0;
3373 M003: NOP 0;
3374
     U M 52.7 // ROUND AXIS ACTIVATED
3375
      SPBN M008;
3376 NETWORK 10
3377
     TITLE = ROUND AXIS A REFERENCE (FC CODE)
     U M 121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3378
      U M 120.7; // FM REFERENCE POINT Z-AXIS ACTIVE
3379
3380
      0(;
3381
      UN M 121.3; // REFPKT.X, Y, Z, APPROACH AT THE SAME TIME
3382
      U DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
      U DB20.DBX 9.2; // REFERENCING CHANNEL AXIS A
3383
3384
       );
```

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3385
3386
      U M 120.4; // REFERENCE POINT X & Y & Z AXIS ACTIVE
3387
     U M 121.5; // APPROACH FM REFPKT XYZ AT THE SAME TIME
3388 )
3389 ; 0(
3390
      ; U M 120.5 // FM OUTPUT FOR AUXILIARY RELAY DOOR CLOSED
3391
      ; U DB1.DBX 134.2; // REFERENCE POINT Z-AXIS ACTIVE
3392 ; U M 120.0; // REFERENCE RELEASE
3393 ; )
3394
     U M 120.0; // REFERENCE RELEASE
3395
     SPBN M005;
3396 = DB20.DBX 9.2; // REFERENCING CHANNEL AXIS A
3397 = DB20.DBX 1.1; // APPROACH REFERENCE POINT (DEFLECTION)
3398 M005: NOP 0;
3399 M008: NOP 0;
3400 NETWORK 11
3401 TITLE = FM REFERENCE POINT ACTIVE
3402 U.M.52.2.//.REFERENCE.POINT.X.,Y.,Z.AND.TOOL.C-AXIS.ACTIVE
3403
     FP M 122.5; // FM REFERENCE POINT ACTIVE
     UN M 52.2 // REFERENCE POINT X, Y, Z AND TOOL C-AXIS ACTIVE
3404
3405
     = M 96.5; // REFERENCE POINT INACTIVE NC_START LOCK.
3406 NETWORK 13
3407 TITLE = MELDUNG 7017 REFERENZP. APPROACH
3408
      UN DB3.DBX 6.2; // MESSAGE NO PART TENSIONED
3409 UN DB3.DBX 5.0; // MESSAGE MACHINE DOOR OPEN
3410 UN DB3.DBX 6.7; // MESSAGE 7055 OPEN TOOL CLAMPING SYSTEM
3411 UN DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
3412
     UN DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
3413 UN M 52.2 // REFERENCE POINT X, Y, Z AND TOOL C-AXIS ACTIVE
3414 UN DB3.DBX 2.7; // MESSAGE 7023 WAITING TIME MAIN DRIVE
3415 = DB3.DBX 2.1; // 7017 APPROACH REFERENCE POINT
3416 END_FUNCTION
3417
     FUNCTION FC 8: VOID
3418 NAME: AUX_ON AC95
3419 BEGIN
3420 NETWORK 1
3421
      TITLE = ALARM NOT_AUS AC95
3422 UN M 15.2; // EMERGENCY STOP SWITCH
3423 S DB2.DBX 0.0; // ALARM EMERGENCY STOP
3424 = DB1.DBX 1390.5; // PLC> SURF. EMERGENCY STOP SWITCH
      O DB1.DBX 1370.0; // 1st PLC LOOP
3425
3426
      O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
3427 O DB1.DBX 1370.3; // RESET KEY PRESSED
3428 R DB2.DBX 0.0; // ALARM EMERGENCY STOP
3429
     NETWORK 2
3430
      TITLE = MESSAGE MACHINE DOOR OPEN AC95
3431 U M 15.1; // MACHINE DOOR OPEN
3432 UN DB3.DBX 6.2; // NO PART CLAMPED (M7050)
3433 UN DB1.DBX 1370.0; // 1st PLC LOOP
3434 UN DB3.DBX 2.7; // MESSAGE 7023 WAITING TIME MAIN DRIVE
     UN DB3.DBX 0.2; // 7002 change tool
3435
3436 = DB3.DBX 5.0; // MACHINE DOOR OPEN (7040)
3437 NETWORK 3
3438 TITLE = 6024 DOOR OPEN ALARM AC95
3439
     O M 131.7; // AXES IN MOVEMENT
3440 O M 92.0; // ROUND AXIS IN MOVEMENT
3441 U DB20.DBX 326.4; // AUTO OPERATING MODE
3442 = M 102.0; // HM
3443
     U M 131.7; // AXES IN MOVEMENT
3444 U DB20.DBX 327.2; // REFERENCE OPERATING MODE
3445 = M 102.1; // HM
3446 U DB20.DBX 324.0; // PROGRAM RUNNING
3447
     UN DB20.DBX 324.1; // STOP STATE
     U DB20.DBX 326.4; // AUTO OPERATING MODE
3448
```

```
= M 102.2; // HM
3449
3450 UN M 114.3; // ACTUAL SPEED LESS THAN 20RPM
3451 = M 102.3; // HM
3452 O M 102.0; // HM
3453 O M 102.1; // HM
3454 O M 102.2; // HM
     O M 102.3; // HM
3455
3456 = M \ 110.2; // HM \ DOOR \ ALARM
3457 U M 110.2; // HM DOOR ALARM
3458 U M 15.1; // MACHINE DOOR OPEN
3459
     S DB2.DBX 3.0; // 6024 ALARM DOOR OPEN
3460 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
3461 O DB1.DBX 1370.3; // RESET KEY PRESSED
3462 R DB2.DBX 3.0; // 6024 ALARM DOOR OPEN
3463
     NETWORK 4
3464 TITLE = SUM ALARMS 1 AC95
3465 L DB2.DBW 0; // WORD ALARMS 1
3466 LW#16#0;
3467
      <> I;
3468
     = M 105.0; // SUM ALARMS1
3469 NETWORK 5
3470 TITLE = SUM ALARMS 2 AC95
3471 L DB2.DBW 2; // WORD ALARMS 2
     L W # 16 # 0;
3472
3473 <> I;
3474 = M 105.1; // SUM ALARMS 2
3475 NETWORK 6
3476
      TITLE = SUM THERMAL ALARMS AC95
3477 L DB2.DBW 4; // BYTE / THERM. ALARMS
3478 L W # 16 # 0;
3479 <> I;
3480 = M 105.2; // SUM THERM. ALARMS
3481
      NETWORK 7
3482 TITLE = SELECTION AUX_ON AC95
3483 U DB1.DBX 1370.0; // 1st PLC LOOP
3484 S M 110.1; // AUX ON ON
3485 U M 110.1; // AUX_ON ON
3486 = DB1.DBX 1390.2; // PLC> SURFACE AUX-ON
3487 S M 110.0; // AUX ON AUTO
3488 S M 110.3; // AUX-ON MANUAL
     NETWORK 8
3489
3490
      TITLE = DESELECT AUX ON AC95
3491 O M 105.0; // SUM ALARMS 1
3492 O M 105.1; // SUM ALARMS 2
3493 O M 105.2; // SUM THERM. ALARMS
3494
     O DB1.DBX 1366.3; // ALARM ACTIVE
3495 R M 110.3; // AUX-ON MANUAL
3496 UN M 110.3; // AUX-ON MANUAL
3497 O M 15.1; // MACHINE DOOR OPEN
3498
      O M 18.3; // EXIT FLAG DOOR OPEN
3499
     O DB1.DBX 1366.3; // ALARM ACTIVE
3500 R M 110.0; // AUX-ON AUTO
3501 NETWORK 9
3502
     TITLE = HW CHECK DOOR OPEN AC95 (ALARM 6009)
3503 U M 15.1; // MACHINE DOOR OPEN
3504 L S5TIME # 1S; // 10X0.1S
3505 SE T 6; // T6 SWITCH-ON DELAYED
3506 UT 6; // T6
3507
      U M 15.0; // MACHINE DOOR CLOSED (MAIN MOTOR CONTACTOR ON)
3508
      S DB2.DBX 1.1; // HW ERROR SAFETY CIRCUIT
3509 NETWORK 10
3510 TITLE = HW CHECK CLOSE DOOR AC95
3511
      UN DB1.DBX 1370.0; // 1st PLC LOOP
3512 UN M 15.1; // MACHINE DOOR OPEN
```

```
U M 15.2; // EMERGENCY STOP SWITCH
3513
3514 U M 15.6; // WHEEL COVER CLOSED
3515 L S5TIME # 1S; // 10X0.1S
3516 SE T 11; // T11 SWITCH-ON TV.
3517 U T 11; // T11
3518
     UN M 15.0; // MACHINE DOOR CLOSED (MAIN MOTOR CONTACTOR ON)
3519
      S DB2.DBX 1.1; // HW ERROR SAFETY CIRCUIT
3520 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
3521 O DB1.DBX 1370.3; // RESET KEY PRESSED
3522
     R DB2.DBX 1.1; // HW ERROR SAFETY CIRCUIT
3523
     END_FUNCTION
3524 FUNCTION FC 9: VOID
3525 NAME: AUX_ON ACC
3526 BEGIN
     NETWORK 1
3527
3528 TITLE = ENABLE DIFFERENTIAL LINE DRIVER ON ACC MOTHERBOARD
3529 U M 110.3; // AUX-ON MANUAL
3530 S A 3.7; // ENABLE DIFFERENTIAL LINE DRIVER CYCLES FOR SM
3531
      UN M 110.3; // AUX-ON MANUAL
3532
     L S5TIME # 1S; // 10X0.1S
3533 SE T 10;
3534 U T 10;
3535 R A 3.7; // ENABLE DIFFERENTIAL LINE DRIVER CYCLES FOR SM
3536
     NETWORK 1
3537 TITLE = ALARM NOT_AUS ACC
3538 UN M 15.2; // EMERGENCY STOP SWITCH
3539 S DB2.DBX 0.0; // ALARM EMERGENCY STOP
3540
      = DB1.DBX 1390.5; // PLC> SURF. EMERGENCY STOP SWITCH
3541 O DB1.DBX 1370.0; // 1st PLC LOOP
3542 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
3543 O DB1.DBX 1370.3; // RESET KEY PRESSED
3544 R DB2.DBX 0.0; // ALARM EMERGENCY STOP
3545
     NETWORK 2
3546 TITLE = MESSAGE MACHINE DOOR OPEN ACC
3547 U M 15.1; // MACHINE DOOR OPEN
3548 UN DB3.DBX 6.2; // NO PART CLAMPED (M7050)
3549
      UN DB1.DBX 1370.0; // 1st PLC LOOP
3550 UN DB3.DBX 6.7; // MESSAGE 7055 OPEN TOOL CLAMPING SYSTEM
3551 UN DB3.DBX 7.0; // MESSAGE 7056 ILLEGAL TOOL NUMBER IN THE SETTING DATA
3552 UN DB3.DBX 7.1; // MESSAGE 7057 TOOL HOLDER OCCUPIED
3553 UN DB3.DBX 7.2; // MESSAGE 7058 AXES RELEASE
3554 UN DB3.DBX 2.7; // MESSAGE 7023 WAITING TIME MAIN DRIVE
3555 UN DB3.DBX 0.2; // 7002 change tool
3556 = DB3.DBX 5.0; // MACHINE DOOR OPEN (7040)
3557
     NETWORK
3558
     TITLE = AXES IN MOTION
3559 L DB1.DBB 1358; // AXES IN MOVEMENT
3560 L B # 16 # 0; // LOAD CONSTANT HEX 0
3561 <> I; // COMPARE TO INEQUAL
     = M 131.7; // AXES IN MOVEMENT
3562
3563
     NETWORK 3
3564 TITLE = 6024 ALARM DOOR OPEN ACC
3565 O M 131.7; // AXES IN MOVEMENT
3566 O M 92.0; // ROUND AXIS IN MOVEMENT
3567
     U DB20.DBX 326.4; // AUTO OPERATING MODE
3568 = M 102.0; // HM
3569 U M 131.7; // AXES IN MOVEMENT
3570 U DB20.DBX 327.2; // REFERENCE OPERATING MODE
3571
      = M 102.1; // HM
     U DB20.DBX 324.0; // PROGRAM RUNNING
3572
3573 UN DB20.DBX 324.1; // STOP STATE
3574
     U · (
3575
      O DB20.DBX 326.4; // AUTO OPERATING MODE
3576
      O DB20.DBX 326.2; // OPERATING MODE MDI
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3577 )
3578 = M 102.2; // HM
3579 UN M 114.3; // ACTUAL SPEED LESS THAN 20RPM
3580 = M 102.3; // HM
3581 O M 102.0; // HM
3582 O M 102.1; // HM
3583 O M 102.2; // HM
3584 O M 102.3; // HM
3585 = M \ 110.2; // HM \ DOOR \ ALARM
3586 U M 110.2; // HM DOOR ALARM
3587 U M 15.1; // MACHINE DOOR OPEN
3588 S DB2.DBX 3.0; // 6024 ALARM DOOR OPEN
3589 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
3590 O DB1.DBX 1370.3; // RESET KEY PRESSED
3591 R DB2.DBX 3.0; // 6024 ALARM DOOR OPEN
3592 NETWORK 4
3593 TITLE = SUM ALARMS 1 ACC
3594 L DB2.DBW 0; // WORD ALARMS 1
3595 L W # 16 # 0;
3596 <> I;
3597 = M 105.0; // SUM ALARMS1
3598 NETWORK 5
3599 TITLE = SUM ALARMS 2 ACC
3600 L DB2.DBW 2; // WORD ALARMS 2
3601 L W # 16 # 0;
3602 <> I;
3603 = M 105.1; // SUM ALARMS 2
3604 NETWORK 5
3605 TITLE = SUM ALARMS 3 ACC
3606 L DB2.DBW 3; // WORD ALARMS 3
3607 L W # 16 # 0;
3608 <> I;
3609
     = M 105.3; // SUM ALARMS 3
3610 NETWORK 6
3611 TITLE = SUM THERMAL ALARMS ACC
3612 L DB2.DBW 4; // BYTE / THERM. ALARMS
3613 L W # 16 # 0;
3614 <> I;
3615 = M 105.2; // SUM THERM. ALARMS
3616 NETWORK 7
3617 TITLE = SELECTION AUX_ON ACC
3618 U DB1.DBX 1370.0; // 1st PLC LOOP
3619 S M 110.1; // AUX_ON ON
3620 U M 110.1; // AUX ON ON
3621
      = DB1.DBX 1390.2; // PLC> SURFACE AUX-ON
     S M 110.0; // AUX_ON AUTO
3622
3623 S M 110.3; // AUX-ON MANUAL
3624 NETWORK 8
3625 TITLE = DESELECT AUX_ON ACC
3626
      O M 105.0; // SUM ALARMS 1
3627 O M 105.1; // SUM ALARMS 2
3628 O M 105.3; // SUM ALARMS 3
3629 O M 105.2; // SUM THERM. ALARMS
3630 O DB1.DBX 1366.3; // ALARM ACTIVE
3631 R M 110.3; // AUX-ON MANUAL
3632 UN M 110.3; // AUX-ON MANUAL
3633 ON A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
3634 O M 18.3; // EXIT FLAG DOOR OPEN
3635
      O DB1.DBX 1366.3; // ALARM ACTIVE
3636 R M 110.0; // AUX-ON AUTO
3637 END FUNCTION
3638 FUNCTION FC 13: VOID
     NAME: NC-STARTVERR. AND CONTROL BUTTONS
3639
3640
     BEGIN
```

```
3641
      NETWORK
3642
      TITLE = FM CYCLE START BUTTON FROM CONTROL PANEL AND RAFITAS BUTTON
3643 O DB20.DBX 831.5 // CYCLE START KEY FROM CONTROL PANEL
3644 FP M 105.5; // FM CYCLE START BUTTON FROM CONTROL PANEL
3645 U.M.105.5; // FM.CYCLE.START.BUTTON.FROM.CONTROL.PANEL
3646
      = DB20.DBX 3.6; // NC START REQUEST
3647
       NETWORK
3648 TITLE = FM NC STOP BUTTON FROM CONTROL PANEL or HM MO / M1 DYNAMIC
3649
       O DB20.DBX 831.4 // NC STOP KEY FROM CONTROL PANEL
3650 FP M 105.6; // FM NC STOP BUTTON FROM THE CONTROL PANEL
3651
       O M 105.6; // FM NC STOP BUTTON FROM THE CONTROL PANEL
       O M 0.1; // HM M0 / M1 DYNAMIC
3652
3653
     O DB20.DBX 0.1; // NC STOP REQUEST
3654
       = DB20.DBX 0.1; // NC STOP REQUEST
3655
       NETWORK
       \texttt{TITLE} \cdot = \cdot \texttt{FM} \cdot \texttt{RESET} \cdot \texttt{BUTTON} \cdot \texttt{FROM} \cdot \texttt{THE} \cdot \texttt{CONTROL} \cdot \texttt{PANEL}
3656
       O DB20.DBX 828.6 // RESET BUTTON FROM CONTROL PANEL
3657
3658
     FP M 105.7; // FM RESET BUTTON FROM CONTROL PANEL
3659
       O M 105.7; // FM RESET BUTTON FROM THE CONTROL PANEL
3660
     O DB20.DBX 4.0; // RESET REQUEST
3661
      = DB20.DBX 4.0; // RESET REQUIREMENT
3662
     NETWORK 1
      TITLE = AUX_ON / WORT NC_START VERR.
3663
3664
       UN M 96.2; // WAITING TIME MAIN DRIVE NC_START VERR.
3665
       UN M 96.3; // OUTPUT FOR AUXILIARY RELAY DOOR CLOSED NC_START LOCK.
3666 UN M 96.4; // ENABLE SM MODUL B NC START VERR.
3667
     UN M 96.6; // Message target quantity reached NC_START VERR.
3668
       UN M 96.7; // SERVO READY MAIN DRIVE NC_START VERR.
       UN M 97.2; // MESSAGE 7050 NO PART CLAMPED NC_START LOCK.
3669
     UN M 97.3; // SPN IN MOVEMENT NC START LOCK.
3670
3671
      UN M 97.4; // PART.IN MOVEMENT NC START LOCK.
3672
       = M · 104.4; · // · SUM · NC_START · LOCKED · WITHOUT · REFERENCE · POINT · INACTIVE
3673
       UN M 96.5; // REFERENCE POINT INACTIVE NC START LOCK.
3674
       UN M 96.0; // ABSOLUTE AXIS 4 (TOOL) 0 DEGREES REACHED NC_START LOCK.
3675 UN M 96.1; // TOOL ENABLE NC START VERR.
3676 U M 104.4; // SUM NC START LOCKED WITHOUT REFERENCE POINT INACTIVE
      = M 104.3; // SUM NC_START VERR.
3677
     NETWORK 3
3678
3679 O M 100.6; // M3 MEMORY
3680 O M 100.7; // M4 MEMORY
3681
      UN DB10.DBX 1.6; // SPINDLE START AFTER MO
3682
       U DB20.DBX 0.2; // FC NC-START
3683 U M 104.3; // SUM NC_STARTVERR.
3684 S M 101.0; // NC START MEMORY
3685
     NETWORK
3686
      TITLE = AUTOMATIC AND MDI OPERATING MODE
3687
     ; UN DB20.DBX 326.2; // OPERATING MODE MDI
3688
     ; UN DB20.DBX 326.4; // AUTOMATIC MODE
3689
     UN DB20.DBX 326.0; // JOG MODE
3690
       UN DB20.DBX 326.1; // EDIT MODE
       UN DB20.DBX 326.3; // OPERATING MODE REPOS
3691
3692 UN DB20.DBX 326.5; // OPERATING MODE INC 1
3693
     UN DB20.DBX 326.6; // OPERATING MODE INC 10
       UN DB20.DBX 326.7; // OPERATING MODE INC 100
3694
3695
       UN DB20.DBX 327.0; // OPERATING MODE INC 1000
       UN DB20.DBX 327.1; // OPERATING MODE INC 10000
3696
3697
       UN DB20.DBX 327.2; // REFERENCE OPERATING MODE
       UN DB20.DBX 327.3; // OPERATING MODE INC VAR
3698
       UN DB20.DBX 327.4; // PRESET OPERATING MODE
3699
       O DB1.DBX 1402.5; // HEIDENHAIN TNC355 ACTIVE
3700
       = M 103.0; // AUTOMATIC AND MDI OPERATING MODE
3701
3702
     NETWORK 4
       TITLE = NC_START / STARTVERR.
3703
3704
       ON M 103.0; // AUTOMATIC AND MDI OPERATING MODE
```

```
3705
     ON M 104.3; // SUM NC START VERR.
3706 O M 101.0; // NC START MEMORY
3707 O DB1.DBX 1366.3; // ALARM ACTIVE
3708 U DB20.DBX 0.2; // FC NC_START
3709 R DB20.DBX 0.2; // FC NC_START
3710 = DB20.DBX 319.0; // NEG. ACKNOWLEDGMENT DNC
3711 END FUNCTION
3712 FUNCTION FC 10: VOID
3713 NAME: AT_PROGRAM_ENDE_RESET_ODER_NEUSTART
3714 BEGIN
3715
     NETWORK 1
3716 TITLE = PROGRAM END TO NC
3717 O M 10.1; // HM
3718 UN DB10.DBX 1.0; // SPS-MSD (CONTINUOUS RUN)
3719
     R M 10.1; // HM
3720 = DB20.DBX 348.1; // PROGRAM RUNNING WILL BE RESET
3721 NETWORK 2
3722 TITLE = PROGRAM END AND RESTART (CONTINUOUS RUN) ON NC
3723
      O M 10.1; // HM
3724 U DB10.DBX 1.0; // SPS-MSD (CONTINUOUS RUN)
3725 R M 10.1; // HM
3726 = DB20.DBX 348.2; // PROGRAM RUNNING WILL BE RESET AND STARTED
     NETWORK 3
3727
3728
      TITLE = ACTUAL SPEED LESS THAN 20RPM
3729 O DB20.DBX 192.2; // M2 DYN.
3730 O DB20.DBX 195.6; // M30 DYN.
3731 S M 10.0; // HM
3732
     U M 10.0; // HM
3733 U M 114.3; // ACTUAL SPEED LESS THAN 20RPM
3734 S M 10.1; // HM
3735 R M 10.0; // HM
3736 NETWORK 3
3737
      TITLE = M2 and M30 FEEDBACK FROM M2, M30 AND RESET
3738 O DB20.DBX 348.1; // PROGRAM RUNNING WILL BE RESET
3739 O DB20.DBX 348.2; // PROGRAM RUNNING WILL BE RESET AND STARTED
3740 O DB1.DBX 1370.3; // RESET KEY PRESSED
3741
      O DB1.DBX 1440.0; // RESET TRIPPED
3742 R M 10.0; // HM
3743 R M 10.1; // HM
3744 = DB20.DBX 259.6; // REPORT M30
3745
      = DB20.DBX 256.2; // REPORT M2
3746
     END FUNCTION
3747 FUNCTION FC 11: VOID
3748 NAME: NC_START_UND_NC_STOP_VON_MO_ODER_M1
3749 BEGIN
3750 NETWORK 2
3751 TITLE = FC NC START
3752 UN DB10.DBX 1.6; // Start of the spindle after M0
3753 U M 101.0; // NC start memory
3754
      U (;
      O DB20.DBX 224.3; // M3 Static
3755
3756 O DB20.DBX 224.4; // M4 Static
3757
     );
      ; O E 2.4 // External CYCLE Start 8 **** foot switch for Andi's PCM50
3758
3759
      O M 150.1; // FM ROBOTICS INTERFACE NC START
3760 S DB20.DBX 0.2; // FC NC-START
3761 U DB20.DBX 0.2; // FC NC-START
3762 R M 101.0; // NC start memory
3763
     END_FUNCTION
3764 FUNCTION FC 12: VOID
3765 NAME: AFG EFG
3766 BEGIN
3767
     NETWORK 1
3768
      TITLE = FM KEY FEED START
```

```
U DB20.DBX 295.2; // FEED START BUTTON
3769
3770
      UN DB20.DBX 295.1; // FEED HOLD KEY
3771 UN M 200.0 // SET TOOL POSITIONS
3772 FP M 133.5; // FM KEY FEED START
3773 NETWORK 2
3774
      TITLE = FM KEY FEED HOLD
3775
      U DB20.DBX 295.1; // FEED HOLD KEY
3776 UN DB20.DBX 295.2; // FEED START BUTTON
3777 UN M 200.0 // SET TOOL POSITIONS
3778 FP M 133.7; // FM KEY FEED STOP
3779
     NETWORK
3780 TITLE = FEED STOP / START ENABLE
3781 U M 104.0; // SUM AFG
3782 = M 133.0; // FEED STOP / START ENABLE
3783
      NETWORK 3
      TITLE = FEED STOP ACTIVE
3784
3785
      O DB20.DBX 326.4; // AUTOMATIC MODE
3786
      O DB20.DBX 326.2; // OPERATING MODE MDI
3787
      O DB20.DBX 327.2; // REFERENCE OPERATING MODE
3788
      U · (
3789
     U M 133.0; // FEED STOP / START ENABLE
3790 U M 133.7; // FM KEY FEED STOP
3791
      UN M 15.1; // MACHINE DOOR OPEN
3792
      U M 131.7; // AXES IN MOVEMENT
3793
     )
3794 S M 91.6; // AFG, EFG FEED STOP ACTIVE
3795 U M 133.5; // FM BUTTON PREVIEW
3796
      B START
3797
      UN M 132.1; // SPINDLE STOP ACTIVE
3798 UN M 15.1; // MACHINE DOOR OPEN
3799 O DB1.DBX 1440.0; // RESET TRIPPED
3800 O DB1.DBX 1370.3; // RESET KEY PRESSED
3801
      R M 91.6; // AFG, EFG
3802 NETWORK 4
3803 TITLE = SUM MELDUNGEN AFG / EFG
3804 L DB3.DBW 0; // WORD / MESSAGES AFG / EFG
     L W # 16 # 0; // LOAD CONSTANT HEX 0
3805
3806
     <> I; // COMPARE TO INEQUAL
3807 = M 91.0; // SUM MESSAGES AFG / EFG
3808 NETWORK 5
3809 TITLE = SUM AFG KO
3810
      UN M 90.1; // AXES READY FOR OPERATION AFG / EFG
3811 UN M 90.4; // SPM ON THE MOVE
3812 UN M 90.5; // AFG / EFG T-WORD IS VALID
3813 UN M 90.7; // TAKE AWAY AFG AND EFG
3814
     UN M 91.0; // SUM MESSAGES AFG / EFG
3815
     UN M 91.2; // AFG MELDUNG 7050 NO PART CLAMPED
3816 UN M 91.5; // VICE MOV. ACTIVE AFG / EFG
3817 UN M 91.6; // AFG, EFG FEED STOP ACTIVE
3818
      UN M 91.7; // AFG, EFG KEY SPINDLE HOLD
3819
      = M 104.0; // SUM AFG
3820 NETWORK 5
3821 TITLE = SUM EFG KO
3822
     UN M 90.1; // AXES READY FOR OPERATION AFG / EFG
3823
      UN M 90.2; // ABSOLUTE AXIS 4 (TOOL) 0 DEGREES REACHED AFG / EFG
     UN M 90.4; // SPM ON THE MOVE
3824
3825 UN M 90.5; // AFG / EFG T-WORD IS VALID
     UN M 90.7; // TAKE AWAY AFG AND EFG
3826
      UN M 91.0; // SUM MESSAGES AFG / EFG
3827
      UN M 91.2; // AFG MELDUNG 7050 NO PART CLAMPED
3828
3829 UN M 91.5; // VICE MOV. ACTIVE AFG / EFG
3830 UN M 91.6; // AFG, EFG FEED STOP ACTIVE
3831
      UN M 91.7; // AFG, EFG KEY SPINDLE HOLD
3832
      = M 104.1; // SUM EFG
```

```
3833
     NETWORK 6
3834
     TITLE = AFG / EFG
3835 UN DB20.DBX 327.2; // REFERENCE OPERATING MODE
3836 UN DB20.DBX 326.4; // AUTOMATIC MODE
3837 UN DB20.DBX 326.2; // OPERATING MODE MDI
3838
      UN DB20.DBX 326.1; // EDIT MODE
3839
      UN DB20.DBX 326.3; // OPERATING MODE REPOS
3840 UN DB20.DBX 327.4; // PRESET OPERATING MODE
3841
      U M 110.3; // AUX-ON MANUAL
3842
3843
     UN DB20.DBX 326.0; // JOG MODE
3844 UN DB20.DBX 326.1; // EDIT MODE
3845 UN DB20.DBX 326.3; // OPERATING MODE REPOS
3846 UN DB20.DBX 327.4; // PRESET OPERATING MODE
3847
     U M 110.0; // AUX-ON AUTO
3848
     = M 110.7; // HM OPERATING MODES
3849 U M 110.7; // HM OPERATING MODES
3850 U M 104.0; // SUM AFG
3851
      = DB20.DBX 340.4; // AXIS ENABLE KO
3852
     U M 110.7; // HM OPERATING MODES
3853 U M 104.1; // SUM EFG
3854 = DB20.DBX 340.3; // READ-IN ENABLE KO
3855 NETWORK 5
3856
      TITLE = AFG K1
3857 UN M 90.1; // AXES READY FOR OPERATION AFG / EFG
3858 UN M 90.3; // ENABLE SM MODUL B AFG / EFG
3859 UN M 90.4; // SPM ON THE MOVE
3860 UN M 90.7; // TAKE AWAY AFG AND EFG
3861 UN M 91.0; // SUM MESSAGES AFG / EFG
3862 UN M 91.2; // AFG MELDUNG 7050 NO PART CLAMPED
3863 UN M 91.5; // VICE MOV. ACTIVE AFG / EFG
3864 UN M 91.6; // AFG, EFG FEED STOP ACTIVE
3865
      UN M 91.7; // AFG, EFG KEY SPINDLE HOLD
3866 U M 110.7; // HM OPERATING MODES
3867 = DB25.DBX 340.4; // AXLE ENABLE K1
3868 NETWORK 6
3869
      TITLE = EFG K1
3870 UN M 90.1; // AXES READY FOR OPERATION AFG / EFG
3871 UN M 90.3; // ENABLE SM MODUL B AFG / EFG
3872 UN M 90.4; // SPM ON THE MOVE
3873 UN M 90.7; // TAKE AWAY AFG AND EFG
3874
      UN M 91.0; // SUM MESSAGES AFG / EFG
3875 UN M 91.2; // AFG MELDUNG 7050 NO PART CLAMPED
3876 UN M 91.5; // VICE MOV. ACTIVE AFG / EFG
3877
     UN M 91.6; // AFG, EFG FEED STOP ACTIVE
3878
      UN M 91.7; // AFG, EFG KEY SPINDLE HOLD
3879
     U M 110.7; // HM OPERATING MODES
3880 = DB25.DBX 340.3; // READ-IN ENABLE K1
3881 NETWORK
3882
      TITLE = enables for Repos operating mode
3883
      U DB20.DBX 324.0; // PROGRAM RUNNING
3884 U DB20.DBX 324.1; // PROGRAM STOPPED
3885 U DB20.DBX 326.3; // OPERATING MODE REPOS
3886 SPBN M1302;
3887
      = DB25.DBX 340.3; // READ-IN ENABLE K1
3888 = DB25.DBX 340.4; // AXLE ENABLE K1
3889 M1302: NOP 0;
3890 END FUNCTION
3891
      FUNCTION FC 14: VOID
3892
     NAME: ALARM STATUS
3893 BEGIN
3894 NETWORK 1
3895
      TITLE =
3896
     U DB1.DBX 1366.3; // ALARM ACTIVE
```

```
3897
      = M 19.7; // EXIT FLAG ROBOTICS ALARM OUTPUT
3898
     END FUNCTION
3899 FUNCTION FC 16: VOID
3900 NAME: PLC_OBERFLAECHEN_SIGNALE
3901 BEGIN
3902
     NETWORK 1
3903 U DB10.DBX 75.0; // ACTIVATE THE AUTOMATIC DOOR
3904 = DB1.DBX 1418.0; // AUT. DOOR
3905 O DB10.DBX 75.4; // Activate pneumatic vice
3906 O DB10.DBX 75.1; // Activate the electric vice
3907
      = DB20.DBX 382.1; // Clamping device available
3908 U DB10.DBX 75.3;
3909 = DB20.DBX 382.4; // BLOW DEVICE
3910 U DB10.DBX 75.6;
3911
      = DB20.DBX 382.5; // PARTIAL APPARATUS
3912 END_FUNCTION
3913 FUNCTION FC 17: VOID
3914 NAME: AUTOMATIC DOOR
3915 BEGIN
3916
     NETWORK 1
3917 TITLE = RELEASE OPEN THE DOOR
3918 ; UN M 110.2; // HM DOOR ALARM
3919 NETWORK 1
3920 TITLE = FM PC KEY DOOR
3921 U DB1.DBX 1374.2; // DOOR BUTTON
3922 U·M·139.6·// HM·DOOR·OPEN FROM EXIT FLAG DOOR OPEN
3923 UN M 139.5; // HM OPEN THE DOOR
3924
     UN M 110.2; // HM DOOR ALARM
     S M 139.2; // HM CLOSE THE DOOR BY PC KEY
3925
3926 R M 139.6 // HM DOOR OPEN FROM EXIT FLAG DOOR OPEN
3927 UN DB1.DBX 1374.2; // DOOR BUTTON
3928 R M 139.2; // HM CLOSE THE DOOR BY PC KEY
3929
      NETWORK 4
3930 TITLE = REQUEST DOOR OPEN
3931 U DB1.DBX 1374.2; // DOOR BUTTON
3932 UN M 139.2; // HM CLOSE THE DOOR BY PC KEY
3933
3934 U DB1.DBX 1370.0; // 1st PLC LOOP
3935 UN M 18.3; // EXIT FLAG DOOR OPEN
3936 UN M 18.4; // EXIT FLAG DOOR CLOSED
3937
     U M 15.1; // MACHINE DOOR OPEN
3938
     U E 4.4; // DOOR OPEN, AUTOMATIC DOOR
3939 ; O DB1.DBX 1382.0; // DNC REQUIREMENT DOOR OPEN
3940 O M 138.1; // HM MACHINE KEYBOARD DOOR OPEN
3941
      O M 149.1; // HM ROBOT INTERFACE
3942
     = M 139.5; // HM OPEN THE DOOR
3943 O M 0.1; // HM M0 / M1 DYNAMIC
3944 O DB20.DBX 195.6; // M30 DYNAMIC
3945 O DB20.DBX 192.2; // M2 DYNAMIC
3946
      O DB1.DBX 1382.0; // DNC REQUIREMENT DOOR OPEN
      UN DB10.DBX 1.0; // PLC-MSD CONTINUOUS RUN ACTIVE
3947
3948 S M 139.3; // OPEN MARKER DOOR
3949 NETWORK 5
3950 TITLE = REQUEST DOOR CLOSED
3951
      U DB1.DBX 1382.1; // DNC REQUIREMENT DOOR CLOSED
3952 S M 136.1 // HM DNC REQUIREMENT DOOR CLOSED
3953 UN M 15.1; // MACHINE DOOR OPEN
      O DB1.DBX 1382.0; // DNC REQUIREMENT DOOR OPEN
3954
      O DB1.DBX 1382.2; // DNC REQUEST DOOR STOP
3955
3956
      O DB1.DBX 1370.3; // RESET KEY PRESSED
3957
      O DB1.DBX 1440.0; // RESET TRIPPED
3958 R M 136.1 // HM DNC REQUIREMENT DOOR CLOSED
3959
      U M 138.2; // HM MACHINE KEYBOARD DOOR CLOSED
3960
      U M 139.6 // HM DOOR OPEN FROM EXIT FLAG DOOR OPEN
```

```
3961
    S M 139.7
3962
     R M 139.6 // HM DOOR OPEN FROM EXIT FLAG DOOR OPEN
3963 UN M 138.2; // HM MACHINE KEYBOARD DOOR CLOSED
3964 R M 139.7
3965 O M 139.2; // HM CLOSE THE DOOR BY PC KEY
3966
      O M 136.1 // HM DNC REQUIREMENT DOOR CLOSED
3967
      O M 139.7
3968 O M 149.0; // HM ROBOT INTERFACE
3969 ; 0(;
3970 ; U DB1.DBX 1370.0; // 1st PLC LOOP
3971
     ; UN M 18.3; // EXIT FLAG DOOR OPEN
3972 ; UN M 18.4; // EXIT FLAG DOOR CLOSED
3973 ; UN M 15.1; // MACHINE DOOR OPEN
3974 ;; U M 15.0; // MACHINE DOOR CLOSED (MAIN MOTOR CONTACTOR ON)
3975
      ; UN E 4.4; // DOOR OPEN, AUTOMATIC DOOR
     ; · );
3976
3977
     = M 139.4; // FLAG CLOSE THE DOOR
3978
     NETWORK 6
3979
      TITLE = ABORT CONDITION
3980
3981
     U M 139.6 // HM DOOR OPEN FROM EXIT FLAG DOOR OPEN
3982
     UN E 4.4; // DOOR OPEN, AUTOMATIC DOOR
3983
      )
3984
      0(
3985
      UN M 15.1; // MACHINE DOOR OPEN
3986 U E 4.4; // DOOR OPEN, AUTOMATIC DOOR
3987
3988
     L S5TIME # 1S; // 1 p
3989
     SE T 27; // SWITCH ON DELAY
3990 UT 27;
3991 S DB2.DBX 3.3; // DOOR SWITCH DEF. (ALARM 6027)
3992 ; R M 139.6 // HM DOOR OPEN FROM EXIT FLAG DOOR OPEN
3993
      R M 110.1; // AUX-ON ON
3994 R M 110.0; // AUX-ON AUTO
3995 R M 110.3; // AUX-ON MANUAL
3996 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
3997
      O DB1.DBX 1370.3; // RESET KEY PRESSED
     R DB2.DBX 3.3; // DOOR SWITCH DEF.
3998
3999 O DB1.DBX 1382.2; // DNC REQUEST DOOR STOP
4000 O DB2.DBX 3.4; // DOOR MONITORING PERIOD.
4001
      ON M 110.1; // AUX-ON ON
4002
     ON M 15.2; // EMERGENCY STOP SWITCH
4003 R M 136.1 // HM DNC REQUIREMENT DOOR CLOSED
4004 R M 18.3; // EXIT FLAG DOOR OPEN
     R M 18.4; // EXIT FLAG DOOR CLOSED
4005
4006
      R M 139.2; // HM CLOSE THE DOOR BY PC KEY
4007
     R M 139.3; // OPEN MARKER DOOR
4008 NETWORK 7
4009 TITLE = OPEN THE DOOR
4010
      O M 139.3; // OPEN MARKER DOOR
      O M 139.5; // OPEN MARKER DOOR
4011
4012 O M 400.0 // OPEN MARKER DOOR
4013 UN M 110.2; // HM DOOR ALARM
4014
4015
      ON E 2.1; // S1 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
4016
      ON E 2.5; // S2 DOOR SWITCH (0 SIGNAL WHEN THE DOOR IS CLOSED)
4017
     U M 18.3; // EXIT FLAG DOOR OPEN
4018
4019
      S M 18.3; // EXIT FLAG DOOR OPEN
4020
     R M 18.4; // EXIT FLAG DOOR CLOSED
4021 R M 139.1; // EXIT FLAG DOOR CLOSED
4022 O M 18.3; // EXIT FLAG DOOR OPEN
      O DB1.DBX 1370.0; // 1st PLC LOOP
4023
4024
     U E 4.4; // DOOR OPEN, AUTOMATIC DOOR
```

```
4025
     S M 139.6 // HM DOOR OPEN FROM EXIT FLAG DOOR OPEN
4026
      U M 139.6 // HM DOOR OPEN FROM EXIT FLAG DOOR OPEN
4027 S M 18.3; // EXIT FLAG DOOR OPEN
4028 R M 139.3; // OPEN MARKER DOOR
4029 U M 18.3; // EXIT FLAG DOOR OPEN
4030 UN E 4.4; // DOOR OPEN, AUTOMATIC DOOR
4031 = M 139.0; // DOOR IN MOVEMENT
4032 L S5TIME # 10S; // 10 SECONDS
4033 SE T 20; // START T20 SWITCH-ON DELAY.
4034 NETWORK 8
4035
      TITLE = CLOSE THE DOOR
4036 U M 139.4; // FLAG CLOSE THE DOOR
4037 UN M 90.4; // SPM ON THE MOVE
4038 O M 400.1 // KEEPER CLOSE THE DOOR
4039 = M 18.4; // EXIT FLAG DOOR CLOSED
4040 R M 18.3; // EXIT FLAG DOOR OPEN
4041 R M 139.4; // FLAG CLOSE THE DOOR
4042 R M 139.6 // HM DOOR OPEN FROM EXIT FLAG DOOR OPEN
4043
     U M 18.4; // EXIT FLAG DOOR CLOSED
     U M 15.1; // MACHINE DOOR OPEN
4044
4045 = M 139.0; // DOOR IN MOVEMENT
4046 L S5TIME # 10S; // 10 SECONDS
4047 SE T 21; // START T21 SWITCH-ON DELAY.
4048
     U M 18.4; // EXIT FLAG DOOR CLOSED
4049 UN M 15.1; // MACHINE DOOR OPEN
4050 O.M.120.5.//.FM.EXIT.FOR.AUXILIARY.RELAY.DOOR.CLOSED
4051 S M 139.1; // EXIT FLAG DOOR CLOSED
4052
     U M 139.1; // EXIT FLAG DOOR CLOSED
     S M 18.4; // EXIT FLAG DOOR CLOSED
4053
4054 NETWORK 9
4055 O T 20; // T20
4056 O T 21; // T21
4057
     UN DB2.DBX 3.3; // DOOR SHEET
4058 OLD DEF. (ALARM 6027)
4059 S DB2.DBX 3.4; // DOOR TIME ABGEL. (ALARM 6028)
4060 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
4061
      O DB1.DBX 1370.3; // RESET KEY PRESSED
4062 R DB2.DBX 3.4;
4063 NETWORK 10
4064 TITLE = DNC STATUS REPORTING DOOR
4065 UN M 15.1; // MACHINE DOOR OPEN
4066 UN E 4.4; // DOOR OPEN, AUTOMATIC DOOR
4067 U.M.104.4; // SUM.NC_START LOCKED WITHOUT REFERENCE POINT INACTIVE
4068 = M 148.0; // HM ROBOT INTERFACE
     = DB1.DBX 1390.1; // PLC> SURF. DOOR CLOSED
4069
4070 U M 15.1; // MACHINE DOOR OPEN
4071 U E 4.4; // DOOR OPEN, AUTOMATIC DOOR
4072 = M 148.1; // HM ROBOT INTERFACE
4073 = DB1.DBX 1390.0; // PLC> SURF. DOOR OPEN
4074
      U DB1.DBX 1382.0; // DNC DOOR OPEN
4075
     UN M 18.3; // EXIT FLAG DOOR OPEN
4076
      S DB1.DBX 1398.0; // NEG. ACKNOWLEDGMENT DNC
4077 U DB1.DBX 1382.1; // DNC DOOR CLOSED
4078
     UN M 18.4; // EXIT FLAG DOOR CLOSED
4079
      S DB1.DBX 1398.0; // NEG. ACKNOWLEDGMENT DNC
4080 END_FUNCTION
4081 FUNCTION FC 18: VOID
4082 NAME: EL VICE
4083
      BEGIN
     NETWORK 1
4084
4085 TITLE = SPN SPANNEN
4086 U (;
      ON DB20.DBX 324.0; // PROGRAM RUNNING
4087
4088
      O DB20.DBX 324.1; // STATE STOP
```

```
4089
4090 U DB20.DBX 294.4; // PC KEY PINOL FORWARD
4091 O DB20.DBX 195.2; // CLAMP M26 SPM (DYN.)
4092 O M 149.3; // ROBOTICS / FM VICE CLOSED
4093 O DB20.DBX 302.2; // CLAMP DNC INTRFACE SPM
4094 U M 140.2; // SPN ENABLE
     S M 140.0; // CLAMPING
4095
4096 = DB20.DBX 259.2; // TRIP M26
4097
     R M 140.1; // RELAX IN SPN
4098 NETWORK 2
4099
      TITLE = SPN RELAX
4100 U (;
4101 ON DB20.DBX 324.0; // PROGRAM RUNNING
4102 O DB20.DBX 324.1; // STATE STOP
4103
4104
     U DB20.DBX 294.3; // PC BUTTON QUILL BACK
4105 O DB20.DBX 195.1; // M25 SPM RELAX (DYN.)
4106 O M 149.2; // ROBOTICS / FM VICE ON
4107
      O DB20.DBX 302.1; // RELAX DNC INTERFACE SPM
4108
     U M 140.2; // SPN ENABLE
4109 S M 140.1; // RELAX IN SPN
4110 = DB20.DBX 259.1; // TRIP M25
4111 R M 140.0; // CLAMPING
     NETWORK · 3
4112
4113 TITLE = RELEASE SPN
4114 U M 110.3; // AUX-ON MANUAL
4115 U M 114.3; // ACTUAL SPEED LESS THAN 20RPM
4116 UN M 131.7; // AXES IN MOVEMENT
4117
     UN M 106.6; // EDIT MODE OPERATING MODE
4118 = M 140.2; // SPN ENABLE
4119 NETWORK 4
4120 TITLE = SPN ON THE MOVE
4121
      U M 140.0; // CLAMPING
4122 UN E 4.5; // TENSIONED
4123 0;
4124 U M 140.1; // RELAX IN SPN
4125 UN E 4.1; // REAR SPN
4126 = M 90.4; // SPN IN MOTION (AFG, EFG)
4127 = M 95.1; // SPN IN MOTION (SFG)
4128 = M 97.3; // SPN IN MOVEMENT (NC START LOCK)
4129 L S5TIME # 30S; // 30S
4130
     SE T 24;
4131 UN DB2.DBX 3.6; // NO PART CLAMPED (ALARM 6030)
4132 U T 24;
4133 S DB2.DBX 2.3; // SPN TIME MONITOR. (ALARM 6019)
4134
     O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
4135 O DB1.DBX 1370.3; // RESET KEY PRESSED
4136 R DB2.DBX 2.3; // SPN TIME MONITOR. (ALARM 6019)
4137 NETWORK 5
4138
      TITLE = MELDUNG 7050 NO PART CLOSED
     UN DB1.DBX 1370.0; // 1st PLC LOOP
4139
4140 UN E 4.5; // TENSIONED
4141 UN E 4.1; // REAR SPN
4142 O E 4.0; // BERO FRONT
     = M 91.2; // AFG MELDUNG 7050 NO PART CLAMPED
4143
4144 = M 95.2; // SFG MELDUNG 7050 NO PART CLOSED
4145 = M 97.2; // NC START INTERLOCK MESSAGE 7050 NO PART CLAMPED
4146 = DB3.DBX 6.2; // NO PART CLAMPED (7050)
     U E 4.0; // BERO FRONT
4147
4148
     U M 18.5; // EXIT FLAG CLAMP VICE
4149 S DB2.DBX 3.6; // NO PART CLAMPED (ALARM 6030)
4150 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
4151
      O DB1.DBX 1370.3; // RESET KEY PRESSED
4152
     R DB2.DBX 3.6; // NO PART CLAMPED (ALARM 6030)
```

```
4153
     NETWORK 6
4154 TITLE = SPN SPANNEN
4155 U M 140.0; // CLAMPING
4156 L S5TIME # 700MS; // 0.1 S
4157 SE T 22;
4158
     R M 18.6; // RELEASE THE EXIT FLAG VICE
4159
     U M 140.0; // CLAMPING
4160 U T 22;
4161 S M 18.5; // EXIT FLAG CLAMP VICE
     NETWORK 7
4162
4163
     TITLE = SPN RELAX
4164 U M 140.1; // RELAX IN SPN
4165 L S5TIME # 700MS; // 0.1 S
4166 SE T 23; // T23
     R M 18.5; // EXIT FLAG CLAMP VICE
4167
4168 U M 140.1; // RELAX IN SPN
4169 U T 23; // T23
4170 S M 18.6; // RELEASE THE EXIT FLAG VICE
4171
      NETWORK 8
4172
      TITLE = ABORT CONDITION
4173 U M 90.4; // SPN ON THE MOVE
4174 U (;
4175 ON M 15.2; // EMERGENCY STOP SWITCH
4176
      O DB1.DBX 1440.0; // RESET TRIPPED
4177
     O DB1.DBX 1370.3; // RESET KEY PRESSED
4178 );
4179 O DB2.DBX 2.4; // VICE FAILED (A6020)
4180 O DB2.DBX 2.6; // SPN BOARD DEFECTIVE (ALARM 6022)
4181
      O DB2.DBX 2.3; // VICE TIME OVER (A6019)
4182 O DB2.DBX 3.6; // NO PART CLAMPED (A6030)
4183 R M 18.5; // EXIT FLAG CLAMP VICE
4184 R M 18.6; // RELEASE THE EXIT FLAG VICE
4185
     R M 140.0; // CLAMPING
4186 R M 140.1; // RELAX IN SPN
4187 O E 4.1; // REAR SPN
4188 R M 18.6; // RELEASE THE EXIT FLAG VICE
4189
     R M 140.1; // RELAX IN SPN
4190 NETWORK 9
4191 TITLE = MONITORING SPN BOARD
4192 U E 4.5; // TENSIONED
4193 UN M 18.5; // EXIT FLAG CLAMP VICE
4194
     UN M 18.6; // RELEASE THE EXIT FLAG VICE
4195 L S5TIME
4196 # 2S; // 200 * 0.01 = 2 SECONDS
     SE T 30; // SWITCH ON DELAY
4197
4198
     U T 30;
4199
     S DB2.DBX 2.6; // SPN BOARD DEFECTIVE (ALARM 6022)
4200 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
4201 O DB1.DBX 1370.3; // RESET KEY PRESSED
4202
     R DB2.DBX 2.6; // SPN BOARD DEFECTIVE (ALARM 6022)
4203 NETWORK 10
4204 TITLE = MONITORING SPM
4205 U M 140.4; // SPM CLOSED
4206 S M 140.7; // HM SPM
4207
     UN M 18.5; // EXIT FLAG CLAMP VICE
4208 R M 140.7; // HM SPM
4209 U M 140.7; // HM SPM
4210 UN E 4.5; // SPM CLOSED
4211
      S DB2.DBX 2.4; // SPM FAILED (ALARM 6020)
4212 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
4213 O DB1.DBX 1370.3; // RESET KEY PRESSED
4214 R DB2.DBX 2.4; // SPM FAILED (ALARM 6020)
4215
     NETWORK 11
4216
      TITLE = ROBOTIC INTERFACE
```

```
U M 18.5; // EXIT FLAG CLAMP VICE
4217
4218 U E 4.5; // SPM CLOSED
4219 = M 140.4; // SPM CLOSED
4220 = M 138.5; // VICE CLAMPED
4221 = DB20.DBX 310.2; // PLC> SURFACE VICE CLAMPED
    U E 4.1; // REAR SPM
4222
4223
     = M 138.4; // VICE RELEASED
4224 = DB20.DBX 310.1; // PLC> REAR SURFACE VICE
4225 NETWORK 12
4226 TITLE = NEG.Acknowledgment DNC
4227
     U DB20.DBX 302.2; // CLAMPING THE DNC VICE
4228 UN M 140.0; // CLAMPING THE SPM
4229 S DB20.DBX 318.1; // NEG. ACKNOWLEDGMENT DNC
4230 U DB20.DBX 302.1; // RELEASE DNC VICE
4231
      UN M 140.1; // RELAX SPM
4232 S DB20.DBX 318.1; // NEG. ACKNOWLEDGMENT DNC
4233 END FUNCTION
4234 ****************
4235 FUNCTION FC 30: VOID
4236
     NAME: PNEUM_VICE
4237
     BEGIN
4238 NETWORK
4239 TITLE = VICE CLOSED / OPEN ENABLE
4240 U M 110.3; // AUX-ON MANUAL
4241 U M 114.3; // ACTUAL SPEED LESS THAN 20RPM
4242 UN M 131.7; // AXES IN MOVEMENT
4243 UN M 106.6; // EDIT MODE OPERATING MODE
4244
     O DB1.DBX 1370.0; // PLC-1st LOOP
     = M 138.0; // ENABLE VICE CLOSED / OPEN
4245
4246 NETWORK
4247 TITLE = HM VICE CLOSED (M26)
4248 U DB20.DBX 324.0; // PROGRAM RUNNING
4249
      U DB20.DBX 195.2; // M26 DYN.
4250 O(
4251 U DB15.DBX 20.2 // VICE CLAMPED SAVE IN THE SETTING DATA
4252 U DB1.DBX 1370.0; // PLC-1st LOOP
4253
     S M 137.5; // HM VICE CLOSED (M26)
4254
4255 NETWORK
4256 TITLE = PERFORMANCE VICE CLOSED
4257
     U M 138.0; // ENABLE VICE CLOSED / OPEN
4258
4259
     U M 138.7; // FM BUTTON, VICE CLOSED
4260 UN M 137.1; // FM BUTTON, VICE OPEN
4261
      O DB20.DBX 195.2; // M26 DYN.
4262
4263
     O M 149.3; // ROBOTICS / FM VICE CLOSED
4264
     O DB20.DBX 302.2; // DNC / VICE CLOSED
4265
     );
4266
     U (;
      ON DB20.DBX 324.0; // PROGRAM RUNNING
4267
      O DB20.DBX 324.1; // CORE / STOP
4268
4269 );
4270 O(;
4271
      U M 137.5; // HM VICE CLOSED (M26)
4272
     UN M 131.7; // AXES IN MOVEMENT
4273
     );
4274
4275
      S M 18.5; // EXIT FLAG CLAMP VICE
4276
     R M 18.6; // RELEASE THE EXIT FLAG VICE
4277 = DB20.DBX 259.2; // TRIP M26
4278
      S M 137.7; // HM M26 STATIC
     R M 137.6; // HM M25 STATIC
4279
4280
     NETWORK
```

```
4281
     TITLE = BACK. HM VICE CLOSED (M26)
4282
     U M 137.5; // HM VICE CLOSED (M26)
4283 UN M 131.7; // AXES IN MOVEMENT
4284 R M 137.5; // HM VICE CLOSED (M26)
4285 NETWORK
4286 TITLE = HM VICE OPEN (M25)
4287
     U DB20.DBX 324.0; // PROGRAM RUNNING
4288 U DB20.DBX 195.1; // M25 DYN.
4289 O(
4290 U DB15.DBX 20.1 // VICE RELEASED SAVE IN THE SETTING DATA
4291
      U DB1.DBX 1370.0; // PLC-1st LOOP
4292
4293 S M 137.4; // HM VICE ON (M26)
4294 NETWORK
4295
      TITLE = PERFORMANCE VICE ON
4296 U M 137.1; // FM BUTTON, VICE OPEN
4297 UN M 138.7; // FM BUTTON, VICE CLOSED
4298 O DB20.DBX 195.1; // M25 DYN.
4299
      0(;
4300
     O M 149.2; // ROBOTICS / FM VICE ON
4301 O DB20.DBX 302.1; // DNC / VICE ON
4302
     );
     U · (;
4303
4304
      ON DB20.DBX 324.0; // PROGRAM RUNNING
4305
      O DB20.DBX 324.1; // CORE / STOP
4306 );
4307
     0(;
4308
     U M 137.4; // HM VICE ON (M25)
     UN M 131.7; // AXES IN MOVEMENT
4309
4310 );
4311 U M 138.0; // ENABLE VICE CLOSED / OPEN
4312
     S M 18.6; // RELEASE THE EXIT FLAG VICE
4313
     R M 18.5; // EXIT FLAG CLAMP VICE
4314 = DB20.DBX 259.1; // TRIP M25
4315 S M 137.6; // HM M25 STATIC
4316 R M 137.7; // HM M26 STATIC
4317
     NETWORK
4318 TITLE = BACK. HM VICE OPEN (M26)
4319 U M 137.4; // HM VICE ON (M26)
4320 UN M 131.7; // AXES IN MOVEMENT
4321 R M 137.4; // HM VICE ON (M26)
4322
     NETWORK
4323 TITLE = VICE CLAMPED
4324 U M 18.5; // EXIT FLAG CLAMP VICE
4325 U E 4.5; // PRESSURE SWITCH VICE
4326
      = M 138.5; // VICE CLAMPED
4327
     FP M 26.3
4328 NETWORK
4329 TITLE = VICE RELEASED
4330 U M 18.6; // RELEASE THE EXIT FLAG VICE
4331 UN E 4.5; // PRESSURE SWITCH VICE
4332 = M 138.4; // VICE RELEASED
4333 FP M 26.4
4334 NETWORK
4335
      SAVE TITLE = VICE IN SETTING DATA
4336 O M 26.3
4337 O M 26.4
4338 SPBN M001;
4339
     U M 138.4; // VICE RELEASED
4340 = DB15.DBX 20.1 // VICE RELEASED SAVE IN THE SETTING DATA
4341 U M 138.5; // VICE CLAMPED
4342 = DB15.DBX 20.2 // VICE CLAMPED IN THE SETTINGDA
     SAVE TEN
4343
4344
      = DB20.DBX 348.3; // REQUEST FOR IMMEDIATE SETTING DATA BACKUP
```

```
4345
     M001: NOP 0;
4346 NETWORK
4347 TITLE = VICE MOV. ACTIVE AFG / EFG
4348 U M 18.5; // EXIT FLAG CLAMP VICE
4349 UN E 4.5; // PRESSURE SWITCH VICE
4350
     U M 18.6; // RELEASE THE EXIT FLAG VICE
4351
4352 U E 4.5; // PRESSURE SWITCH VICE
4353 O M 137.5; // HM VICE CLOSED (M26)
4354 O M 137.4; // HM VICE ON (M25)
4355
      = M 91.5; // VICE MOV. ACTIVE AFG / EFG
4356 NETWORK
4357 TITLE = 6072 VICE NOT READY
4358 U M 18.5; // EXIT FLAG CLAMP VICE
4359 L S5TIME # 1S; // 10X0.1S
4360 SE T 32; // START T32 AS SWITCH-ON DELAY.
4361 UN E 4.5; // PRESSURE SWITCH VICE
4362 L S5TIME # 200MS; // 2X0.1S
4363 SE T 33; // START T33 AS SWITCH-ON DELAY.
     U M 18.6; // RELEASE THE EXIT FLAG VICE
4364
4365 L S5TIME # 1S; // 10X0.1S
4366 SE T 34; // START T34 AS SWITCH-ON DELAY.
4367 U E 4.5; // PRESSURE SWITCH VICE
4368
      L S5TIME # 200MS; // 2X0.1S
4369
      SE T 35; // START T35 AS SWITCH-ON DELAY.
4370 U T 32; // SCREW TO / SUPERV. SHARP
4371
      U T 33; // PRESSURE SWITCH SCREW (0.2S)
4372
     U T 34; // SCREW ON / MONITOR SHARP
4373
4374
     U T 35; // PRESSURE SWITCH SCREW (0.2S)
4375
4376 UN M 138.5; // VICE CLAMPED
4377
4378
      O DB20.DBX 224.3; // M3 STATIC
4379 O DB20.DBX 224.4; // M4 STATIC
4380 );
      S DB2.DBX 9.0; // 6072 VICE NOT READY
4381
4382
     U DB2.DBX 9.0; // 6072 VICE NOT READY
4383 U M 114.3; // ACTUAL SPEED LESS THAN 20RPM
4384 R M 18.5; // EXIT FLAG CLAMP VICE
4385
      R M 18.6; // RELEASE THE EXIT FLAG VICE
4386
      UN M 18.5; // EXIT FLAG CLAMP VICE
4387
     UN M 18.6; // RELEASE THE EXIT FLAG VICE
4388
4389
      O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
4390
      O DB1.DBX 1370.3; // RESET KEY PRESSED
4391
4392
     R DB2.DBX 9.0; // 6072 VICE NOT READY
4393 NETWORK
4394
      TITLE = 6050 \text{ M}25 / \text{M}26 \text{ WHILE HA}
4395
     UN M 114.3; // ACTUAL SPEED LESS THAN 20RPM
4396 U DB20.DBX 195.1; // M25 DYN.
4397 S DB2.DBX 6.2; // 6050 M25 WHILE HA
      O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
4398
4399
      O DB1.DBX 1370.3; // RESET KEY PRESSED
4400 R DB2.DBX 6.2; // 6050 M25 WHILE HA
4401 NETWORK
4402 TITLE = 7054 CLOSE VICE
4403
     UN M 138.5; // VICE CLAMPED
4404 UN DB3.DBX 5.2; // 7042 MACHINE DOOR INIT.
4405 UN DB3.DBX 2.4; // 7020 SPECIAL OPERATION ACTIVE
4406 UN DB3.DBX 5.0; // 7040 MACHINE DOOR OPEN
     UN DB3.DBX 2.0; // 7016 SWITCH ON AUXILIARY DRIVES
4407
4408
      UN DB3.DBX 2.1; // 7017 APPROACH REFERENCE POINT
```

```
UN DB3.DBX 2.6; // 7022 INITIALIZE TOOL TURNER
4409
4410 = DB3.DBX 6.6; // 7054 CLOSE THE VICE
4411 NETWORK
4412 TITLE = PLC / OB -> VICE CLAMPED
4413 U M 138.5; // VICE CLAMPED
4414 = DB20.DBX 310.2; // PLC / OB -> VICE CLAMPED
4415
     NETWORK
4416 TITLE = PLC / OB -> VICE RELEASED
4417 U M 138.4; // VICE RELEASED
4418 = DB20.DBX 310.1; // PLC / OB -> VICE RELEASED
4419
     NETWORK
4420 TITLE = VICE / FC DNC ACKNOWLEDGMENT
4421 U DB1.DBX 1366.0; // DNC OPERATION ACTIVE
4422 U (;
4423
     U DB20.DBX 302.2; // DNC / VICE CLOSED
4424
     UN M 137.7; // HM M26 STATIC
4425 O;
4426 U DB20.DBX 302.1; // DNC / VICE ON
4427
     UN M 137.6; // HM M25 STATIC
4428
4429
     S DB20.DBX 318.1; // VICE / FC DNC ACKNOWLEDGMENT
4430 END FUNCTION
4431 FUNCTION FC 21: VOID
4432
     NAME: PARTIAL APPLIANCE
4433 BEGIN
4434 NETWORK 1
4435 TITLE = PARTIAL APPLIANCE SWITCH-ON CONDITION
4436 UN E 4.7; // DONE TO SHARE
     UN DB1.DBX 1370.0; // PLC-1st LOOP
4437
4438 UN M 144.0; // PARTIAL APPLIANCE SHARE ACTIVE
4439 = DB3.DBX 6.3; // PARTIAL APPARATUS NOT LOCKED (M7051)
4440 U E 4.7; // DONE TO SHARE
4441
      U DB1.DBX 1370.0; // PLC-1st LOOP
4442 S M 144.4; // READY TO SHARE AND LOCKED
4443 NETWORK 2
4444 TITLE = SHARE PARTIAL APPLIANCE
4445
     O DB20.DBX 294.1; // PARTIAL APPLIANCE SHARE KEYBOARD
4446 O DB20.DBX 303.3; // DNC-INTRF.TEILAPPARAT SHARE
4447 UN DB20.DBX 324.0; // PROGRAM RUNNING
4448 O DB20.DBX 195.3; // M27 PARTIAL APPLIANCE SHARE (DYN)
4449 U M 144.7; // PARTIAL APPARATUS RELEASE
     UN M 200.0 // SET TOOL POSITIONS
4450
4451 = M 143.0; // SHARE PARTIAL APPLIANCE
4452 = DB20.DBX 259.3; // TRIP M27
4453 NETWORK 3
4454
      TITLE = RELEASE PARTIAL APPLIANCE
4455
    U M 110.3; // AUX-ON MANUAL
4456 UN M 106.6; // EDIT MODE OPERATING MODE
4457 = M 144.7; // SHARE PARTIAL APPLIANCE RELEASE
4458
     NETWORK 4
4459
      TITLE = STARTING EDGE FLAG
4460 U M 143.0; // SHARE PARTIAL APPLIANCE
4461 UN M 144.5; // HM START
4462
    = M 144.6; // FM START
4463
     U M 143.0; // SHARE PARTIAL APPLIANCE
4464 = M 144.5; // HM START
4465 NETWORK 5
4466 TITLE = PARTIAL APPLIANCE STEP 1
4467
     U M 144.6; // FM START
4468
     UN M 144.0; // PARTIAL APPLIANCE SHARE ACTIVE
4469 S M 144.0; // PARTIAL APPLIANCE SHARE ACTIVE
4470 S M 144.1; // PARTIAL APPARATUS STEP1
4471
      S M 18.7; // SHARE EXIT FLAG SUB-APPARATUS
4472
     R M 144.4; // READY TO SHARE AND LOCKED
```

```
L DB10.DBW 4; // UNLOAD TIME
4473
4474 SPS-MSD
4475 ITB; // CONVERTING AN INTEGER INTO A BCD VALUE
4476 T MW 160; // TRANSFER IN MW160
4477 SET;
4478 = M 161.4; // SET TIME GRID 0.1S
     U M 144.0; // PARTIAL APPLIANCE SHARE ACTIVE
4479
4480 L MW 160;
4481 SE T 7; // SHARE MONITORING TIME
4482 U T 7; // SHARE MONITORING TIME
4483
     S DB2.DBX 6.0; // DIVISION TIME EXPIRED (A 6048)
4484 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
4485 O DB1.DBX 1370.3; // RESET KEY PRESSED
4486 R DB2.DBX 6.0;
     NETWORK 6
4487
4488 TITLE = PARTIAL APPARATUS STEP 2
4489 U M 144.1; // PARTIAL EQUIPMENT STEP 1
4490 UN E 4.7; // PARTIAL APPLIANCE DONE
4491
      S M 144.2; // PARTIAL EQUIPMENT STEP 2
4492
     R M 144.1; // PARTIAL EQUIPMENT STEP 1
4493 L DB10.DBW 6; // DIVISION TIME FROM SPS-MSD
4494 ITB; // CONVERTING AN INTEGER INTO A BCD VALUE
4495 T MW 162;
4496
      SET;
4497 = M 163.4; // SET TIME GRID 0.1S
4498 U M 144.2; // PARTIAL EQUIPMENT STEP 2
4499 L MW 162;
4500 SE T 8; // TIME FOR DIVISION
4501 NETWORK 7
4502 TITLE = PARTIAL APPLIANCE STEP 3
4503 UT8;
4504 U M 144.2; // PARTIAL EQUIPMENT STEP 2
4505
     R M 18.7; // SHARE EXIT FLAG SUB-APPARATUS
4506 S M 144.3; // PARTIAL EQUIPMENT STEP 3
4507 R M 144.2; // PARTIAL EQUIPMENT STEP 2
4508 L DB10.DBW 8; // LOCKING TIME FROM SPS-MSD
4509
     ITB; // CONVERTING AN INTEGER INTO A BCD VALUE
4510 T MW 164;
4511 SET;
4512 = M \ 165.4; // SET TIME GRID 0.1S
4513 U M 144.3; // PARTIAL EQUIPMENT STEP 3
4514
     L MW 164;
4515 SE T 9;
4516 UT9;
4517 S DB2.DBX 6.1; // LOCKING TIME ENDED (A 6049)
4518 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
4519 O DB1.DBX 1370.3; // RESET KEY PRESSED
4520 R DB2.DBX 6.1; // LOCKING TIME ENDED (A 6049)
4521 NETWORK 8
4522
     TITLE = PARTIAL APPLIANCE DONE DONE
4523 U M 144.3; // PARTIAL EQUIPMENT STEP 3
4524 U E 4.7; // DONE TO SHARE
4525 S M 144.4; // READY TO SHARE AND LOCKED
4526 R M 144.3; // PARTIAL EQUIPMENT STEP 3
4527
      R M 144.0; // PARTIAL APPLIANCE PARTS ACTIVE
4528 NETWORK 9
4529 TITLE = PARTIAL APPARATUS ON THE MOVE
4530 O M 144.0; // PARTIAL APPLIANCE SHARE ACTIVE
      ON E 4.7; // DONE TO SHARE
4531
4532
     = M 92.0; // PART APPARATUS IN MOVEMENT (EFG)
4533 = M 97.4; // PART IN MOTION (NC START LOCK)
4534 NETWORK 10
      TITLE = ABORT CONDITION
4535
4536
     O DB2.DBX 6.0; // DIVISION TIME EXPIRED (A 6048)
```

```
O DB2.DBX 6.1; // LOCKING TIME ENDED (A 6049)
4537
4538 O DB2.DBX 6.2; // PARTIAL UNIT FAILED (A 6050)
4539 R M 18.7; // SHARE EXIT FLAG SUB-APPARATUS
4540 R M 144.0; // PARTIAL APPLIANCE SHARE ACTIVE
4541 R M 144.1; // PARTIAL EQUIPMENT STEP 1
4542
     R M 144.2; // PARTIAL EQUIPMENT STEP 2
     R M 144.3; // PARTIAL EQUIPMENT STEP 3
4543
4544 R M 144.4; // READY TO SHARE AND LOCKED
4545 NETWORK 11
4546 TITLE = MONITORING PART UNIT
4547
     U M 144.4; // READY TO SHARE AND LOCKED
4548 UN E 4.7; // DONE TO SHARE
4549 S DB2.DBX 6.2; // PARTIAL APPLIANCE FAILED (A 6050)
4550 O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
      O DB1.DBX 1370.3; // RESET KEY PRESSED
4551
4552 R DB2.DBX 6.2; // PARTIAL APPLIANCE FAILED (A 6050)
4553 NETWORK 12
4554 TITLE = NEG.Acknowledgment DNC
4555 U DB20.DBX 303.3; // DNC-INTRF.TEILAPPARAT SHARE
     UN M 144.0; // PARTIAL APPLIANCE SHARE ACTIVE
4556
4557 S DB20.DBX 318.5; // NEG. ACKNOWLEDGMENT DNC
4558 U M 144.4; // READY TO SHARE AND LOCKED
4559 = DB20.DBX 311.0; // SPLIT PLC SURFACE FINISHED AND LOCKED
4560
      END_FUNCTION
4561 FUNCTION FC 22: VOID
4562 NAME: BLOW OUT
4563 BEGIN
4564 NETWORK 1
4565 TITLE = BLOW OUT FM KEY
4566 O DB20.DBX 294.6; // BLOW OUT PC KEY
4567 UN M 200.0 // SET TOOL POSITIONS
4568 FP M 142.7; // BLOW OUT FM BUTTON
4569
     NETWORK 2
4570 TITLE = BLOW OUT ON
4571 U M 142.7; // BLOW OUT FM
4572 UN M 142.2; // BLOW OUT
4573
     = M 142.1; // HM
4574 S M 142.2; // BLOW OUT
4575 NETWORK 3
4576 TITLE = BLOW OUT
4577 U M 142.7; // BLOW OUT FM
4578
     U M 142.2; // BLOW OUT
4579 UN M 142.1; // HM
4580 R M 142.2; // BLOW OUT
4581 NETWORK 4
4582
     TITLE = EXHAUST VALVE ON
4583 U·(;
4584 U M 142.7; // BLOW OUT FM
4585 U M 142.2; // BLOW OUT
4586
      O DB20.DBX 200.7; // M71 BLOW OUT ON
     O DB20.DBX 303.0; // BLOW-OUT DNC
4587
4588 );
4589 U M 110.3; // AUX ON MANUAL
4590 S M 18.2; // EXIT FLAG BLOW-OUT VALVE
4591
      S M 142.2; // BLOW OUT
4592 = DB20.DBX 264.7; // TRIP M71
4593 S DB20.DBX 310.7; // PLC> BLOW OUT SURFACE ACTIVE
4594 NETWORK 5
4595
      TITLE = EXHAUST VALVE OFF
4596 U M 142.7; // BLOW OUT FM
4597 UN M 142.2; // BLOW OUT
4598 O DB20.DBX 201.0; // BLOW OUT M72
4599
     O DB1.DBX 1370.3; // RESET KEY PRESSED
4600
     O DB1.DBX 1440.0; // RESET TRIPPED
```

```
O DB20.DBX 302.7; // BLOW OUT DNC
4601
4602
     ON M 110.3; // AUX ON MANUAL
4603 R M 18.2; // EXIT FLAG BLOW-OUT VALVE
4604 R M 142.2; // BLOW OUT
4605 R DB20.DBX 310.7; // PLC> BLOW OUT SURFACE ACTIVE
4606 = DB20.DBX 265.0; // TRIP M72
4607
     NETWORK 6
4608 TITLE = DNC COMMANDS AND FEEDBACK
4609 U DB20.DBX 303.0; // BLOW-OUT DNC
4610 UN DB20.DBX 264.7; // TRIP M71
4611
      S DB20.DBX 318.4; // NEG. ACKNOWLEDGMENT DNC
4612 U DB20.DBX 302.7; // BLOW OUT DNC
4613 AND
4614 B20.DBX 265.0; // TRIP M72
4615 S DB20.DBX 318.4; // NEG. ACKNOWLEDGMENT DNC
4616 END_FUNCTION
4617 FUNCTION FC 26: VOID
4618 NAME: COOLANT
4619
    BEGIN
4620 NETWORK
4621 TITLE = FM KEY COOLANT (MSTT / PC)
4622 UN DB10.DBX 75.3; // BLOW DEVICE ACTIVATED
4623 UN M 15.1; // MACHINE DOOR OPEN
4624
     UN M 200.0 // SET TOOL POSITIONS
4625
     U · (
4626
      O DB20.DBX 294.6; // COOLANT BUTTON (PC)
4627
      O DB20.DBX 831.1 // COOLANT KEY (MSTT)
4628
     FP M 107.7; // FM BUTTON COOLANT
4629
4630 NETWORK
4631 TITLE = COOLANT SELECTION ON
4632 UN M 107.1; // COOLANT ON
4633
     U M 107.7; // FM BUTTON COOLANT
4634 O;
4635 U DB20.DBX 225.1; // M9 STATIC
4636 U DB20.DBX 193.0; // M8 DYN.
4637
     UN DB20.DBX 192.7; // M7 DYN.
4638 O DB20.DBX 302.6; // DNC / COOLANT ON
4639 S M 107.1; // COOLANT ON
4640 S M 117.1; // M7 MINIMAL LUBRICATION ON
4641
      = M 107.2; // HM COOLANT ON
4642
      = DB20.DBX 257.0; // TRIP M8
4643 NETWORK
4644 TITLE = SELECT MINIMAL LUBRICATION ON
4645 U DB20.DBX 225.1; // M9 STATIC
4646 U DB20.DBX 192.7; // M7 DYN.
4647 UN DB20.DBX 193.0; // M8 DYN.
4648 S M 117.1; // M7 MINIMAL LUBRICATION ON
4649 = DB20.DBX 256.7; // TRIP M7
4650 NETWORK
4651
      TITLE = COOLANT PROGRAMMED
4652 U DB20.DBX 326.4; // KERN / BA AUTO
4653 U DB20.DBX 257.0; // TRIP M8
4654 U DB20.DBX 193.0; // M8 DYN.
     S M 107.3; // COOLANT PROGRAMMED
4655
4656 NETWORK
4657 TITLE = COOLANT SELECTION ON
4658 U M 107.1; // COOLANT ON
4659
      UN M 107.2; // HM COOLANT ON
4660 U M 107.7; // FM BUTTON COOLANT
4661 UN M 107.3; // COOLANT PROGRAMMED
4662
     0;
4663
     U DB20.DBX 193.1; // M9 DYN.
4664
      O DB20.DBX 302.5; // DNC / COOLANT OFF
```

```
4665
4666 U M 107.4; // COOLANT INTERRUPTION
4667 UN DB20.DBX 326.4; // KERN / BA AUTO
4668 O DB1.DBX 1370.0; // 1st PLC LOOP
4669 O DB1.DBX 1440.0; // RESET TRIPPED
      O DB1.DBX 1370.3; // RESET KEY PRESSED
4670
4671 ON M 110.3; // AUX-ON MANUAL
4672 R M 107.1; // COOLANT ON
4673 R M 117.1; // M7 MINIMAL LUBRICATION ON
4674 R M 107.3; // COOLANT PROGRAMMED
4675
      = DB20.DBX 257.1; // TRIP M9
4676 NETWORK
4677 TITLE = INTERRUPT COOLANT WITH KEY
4678 U M 107.3; // COOLANT PROGRAMMED
4679 UN M 107.4; // COOLANT INTERRUPTION
4680 U M 107.7; // FM BUTTON COOLANT
4681 S M 107.4; // COOLANT INTERRUPTION
4682 = M 107.5; // HM COOLANT INTERRUPTION
4683
     U M 107.4; // COOLANT INTERRUPTION
4684
     UN M 107.5; // HM COOLANT INTERRUPTION
4685 U M 107.7; // FM BUTTON COOLANT
4686 ON M 107.1; // COOLANT ON
4687 R M 107.4; // COOLANT INTERRUPTION
4688
      NETWORK
4689
      TITLE = COOLANT RELEASE
4690 U (;
      ON M 15.1; // MACHINE DOOR OPEN
4691
4692
      O DB20.DBX 294.6; // COOLANT BUTTON (PC)
4693
4694 UN M 107.4; // COOLANT INTERRUPTED
4695 UN M 0.0; // M0 / M1 ACTIVE
4696 UN DB20.DBX 324.2; // DRYRUN
4697
      UN M 200.0 // SET TOOL POSITIONS
4698
     UN M 52.0; // TOOL TURNING ACTIVE
4699 = M 107.0; // COOLANT RELEASE
4700 NETWORK
4701
      TITLE = COOLANT PERFORMANCE
4702 U M 107.1; // COOLANT ON
4703 U M 107.0; // COOLANT RELEASE
4704 = M \cdot 17.2; \cdot // \cdot EXIT \cdot FLAG \cdot COOLANT \cdot (M8 \cdot = ON \cdot / \cdot M9 \cdot = OFF)
4705
      NETWORK
4706
      TITLE = MINIMAL LUBRICATION PERFORMANCE
4707 U M 117.1; // M7 MINIMAL LUBRICATION ON
4708 U M 107.0; // COOLANT RELEASE
     = M 18.0; // INITIAL FLAG MINIMAL LUBRICATION
4709
4710 NETWORK
4711 TITLE = PLC / OB -> COOLANT ON
4712 U M 107.1; // COOLANT ON
4713 = DB20.DBX 310.5; // PLC / OB -> COOLANT ON
4714
      NETWORK
4715
      TITLE = PLC / OB -> COOLANT INJECT
4716 U M 17.2; // EXIT FLAG COOLANT (M8 = ON / M9 = OFF)
4717 = DB20.DBX 310.6; // PLC / OB -> COOLANT INJECT
4718
     NETWORK
4719
      TITLE = COOLANT / FC DNC ACKNOWLEDGMENT
4720 U DB1.DBX 1366.0; // DNC OPERATION ACTIVE
4721 U (;
4722
      U DB20.DBX 302.6; // DNC / COOLANT ON
4723
      UN DB20.DBX 225.0; // M8 STATIC
4724
4725
      U DB20.DBX 302.5; // DNC / COOLANT OFF
4726
      UN DB20.DBX 225.1; // M9 STATIC
4727
4728
      S DB20.DBX 318.3; // COOLANT / FC DNC ACKNOWLEDGMENT
```

```
4729
     END_FUNCTION
4730 FUNCTION FC 40: VOID
4731 NAME: ROBOTICS_INTERFACE
4732 BEGIN
4733 NETWORK
4734 TITLE = robotics axes are at the reference point
4735 L DB1.DBD 70; // REF-POSITION X
4736 L -0.5E-03; // 0.5MM
4737 + R;
4738 L DB1.DBD 0; // IS POSITION X
4739
4740 = M 168.0
4741 L DB1.DBD 74; // REF-POSITION Y
4742 L -0.5E-03; // 0.5MM
4743
4744 L DB1.DBD 4; // IS POSITION Y
4745 <R;
4746 = M 168.1
4747
     L DB1.DBD 78; // REF-POSITION Z
4748
     L -0.5E-03; // 0.5MM
4749
     + R;
4750 L DB1.DBD 8; // IS POSITION Z
4751
      <R;
     = M 168.2
4752
4753 U M 168.0
4754 U M 168.1
4755 U M 168.2
4756 U DB1.DBX 134.0; // REFERENCE POINT X-AXIS ACTIVE
4757 U DB1.DBX 134.1; // REFERENCE POINT Y-AXIS ACTIVE
4758 U DB1.DBX 134.2; // REFERENCE POINT Z-AXIS ACTIVE
4759 = M 19.1; // ROBOTICS AXES ARE AT REF. POINT.
4760 NETWORK 1
4761
      TITLE = DOOR OPEN / CLOSE
4762 ; U E 5.0; // ORDER THE DOOR TO CLOSE
4763 ; FP M 152.0; // FM DOOR CLOSED
4764 ; U E 5.1; // ORDER DOOR OPEN
4765
     ; FP M 152.1; // FM DOOR OPEN
4766 ; U M 152.0; // FM DOOR CLOSED
4767 U E 5.0; // ORDER THE DOOR TO CLOSE
4768 UN E 5.1; // OPEN THE DOOR
4769 = M 149.0; // HAND-OVER MARKER DOOR CLOSED
4770
     ; U M 152.1;
4771 // FM DOOR OPEN
4772 U E 5.1; // ORDER DOOR OPEN
4773 UN E 5.0; // CLOSE THE DOOR
4774
     = M 149.1; // HANDOVER MARK DOOR OPEN
4775 NETWORK 2
4776 TITLE = SPM FORWARD / BACK
4777 U E 5.2; // COMMAND SPM BACK
4778 FP M 152.2; // FM SPM BACK
4779 U E 5.3; // COMMAND SPM FORWARD
4780 FP M 152.3; // FM SPM BEFORE
4781 U M 152.2; // FM SPM BACK
4782 UN E 5.3; // SPM BEFORE
4783
     = M 149.2; // ROBOTICS / FM VICE ON
4784 U M 152.3; // FM SPM BEFORE
4785 UN E 5.2; // SPM BACK
4786 = M 149.3; // ROBOTICS / FM VICE CLOSED
4787
      NETWORK 3
4788
      TITLE = CYCLE START
4789 U E 5.6; // COMMAND CYCLE START
4790 FP M 150.1; // FM CYCLE START
4791
     NETWORK 4
4792
      TITLE = FEEDHOLD ROBOTICS INTERFACE
```

```
U E 5.7; // COMMAND FEEDHOLD
4793
4794
     = DB3.DBX 0.7; // AFG, EFG FEEDHOLD (MESSAGE 7007)
4795 NETWORK 5
4796 TITLE = OUTPUTS ROBOTICS INTERFACE
4797 U M 148.1;
4798
     = M 19.3; // EXIT FLAG ROBOTICS DOOR OPEN
4799
     U M 148.0;
4800 = M 19.4; // EXIT FLAG ROBOTICS DOOR CLOSED
4801 U M 138.4; // VICE RELEASED
     = M·19.5; // INITIAL FLAG ROBOTICS REAR VICE
4802
4803
     U M 138.5; // VICE CLAMPED
4804 = M 19.6; // EXIT FLAG ROBOTICS VICE CLAMPED
4805 NETWORK 6
4806 TITLE = PROGRAM STANDING
     O M 0.0; // M0 / M1 ACTIVE
4807
4808 O DB20.DBX 224.2; // M2 STATIC
4809 O DB20.DBX 227.6; // M30 STATIC
4810 = M·19.0; // EXIT FLAG ROBOTICS PROGRAM STOP (M30, M0, M1, M2)
4811
      END_FUNCTION
4812
     FUNCTION FC 63: VOID
4813
     NAME: WARNING LIGHT
4814 BEGIN
4815 NETWORK
4816
      TITLE = FLASHING LIGHT PULSE DURATION
4817 U DB1.DBX 1370.0; // 1st PLC LOOP
4818 SPBN M001
4819 L DB10.DBW 10; // LOADING TIME FROM SPS-MSD
4820 ITB; // CONVERTING AN INTEGER INTO A BCD VALUE
4821
      T MW 70; // TRANSFER IN MW30
4822 SET;
4823 R M 71.4; // SET TIME GRID 0.01S
4824 R M 71.5; // SET TIME GRID 0.01S
4825
     M001: NOP 0
4826 UN T 48; // PAUSE DURATION
4827 L MW 70; // LOAD MW30
4828 SV T 47; // START AS AN EXTENDED PULSE
4829
     NETWORK
4830 TITLE = FLASHING LIGHT PAUSE DURATION
4831 U DB1.DBX 1370.0; // 1st PLC LOOP
4832 SPBN M002
4833 L DB10.DBW 12; // LOADING TIME FROM SPS-MSD
4834
      ITB; // CONVERTING AN INTEGER INTO A BCD VALUE
4835 T MW 72; // TRANSFER IN MW32 (TIME GRID IS 0.01S)
4836 SET;
     R M 73.4; // SET TIME GRID 0.01S
4837
4838
     R M 73.5; // SET TIME GRID 0.01S
     M002: NOP 0
4839
4840 UN T 47; // PULSE DURATION
4841 L MW 72; // LOAD MW30
     SV T 48; // START AS AN EXTENDED PULSE
4842
4843
     END FUNCTION
4844 FUNCTION FC 62: VOID
4845 NAME: LED CONTROL
4846 BEGIN
4847
     NETWORK
4848 TITLE = LAMP TEST
4849 ; U DB20.DBX 294.7 // 8 *********
4850 ; S DB20.DBX 846.0 // SKIP
4851
      ; S DB20.DBX 846.1 // DRYRUN
4852
     ; S DB20.DBX 847.0 // CLOSE THE DOOR
4853 ; S DB20.DBX 847.1 // OPEN THE DOOR
4854 ; S DB20.DBX 847.3 // 1X KEY
4855 ; S DB20.DBX 847.4 // OPT.STOP (M1)
4856
     ; S DB20.DBX 848.4 // CHUCK
```

```
4857
     ; S DB20.DBX 848.6 // RESET
4858 ; S DB20.DBX 848.7 // SINGLE BLOCK
4859 ; S DB20.DBX 849.6 // QUILL BACK
4860 ; S DB20.DBX 849.7 // QUILL FORE
4861 ; S DB20.DBX 850.0 // TOOL TURNING
     ; S DB20.DBX 850.4 // APPROACH REFERENCE POINT
4862
4863
     ; S DB20.DBX 851.1 // COOLANT
4864 ; S DB20.DBX 851.4 // PROGRAM STOP
4865 ; S DB20.DBX 851.5 // PROGRAM START
4866 ; S DB20.DBX 851.6 // FEED RATE STOP
4867
      ; S DB20.DBX 852.0 // FEED RATE START
4868 ; S DB20.DBX 852.1 // SPINDLE STOP
4869 ; S DB20.DBX 852.3 // SPINDLE START
4870 ; S DB20.DBX 852.4 // AUX OFF
4871
      ; S DB20.DBX 852.6 // AUX ON
4872
     ; ROBOTICS TEST
4873
4874 ; R DB20.DBX 846.0 // SKIP
4875
      ; R DB20.DBX 846.1 // DRYRUN
     ; R DB20.DBX 847.0 // CLOSE THE DOOR
4876
4877 ; R DB20.DBX 847.1 // OPEN THE DOOR
4878 ; R DB20.DBX 847.3 // 1X KEY
4879 ; R DB20.DBX 847.4 // OPT.STOP (M1)
4880
      ; R DB20.DBX 848.4 // CHUCK
4881 ; R DB20.DBX 848.6 // RESET
4882 ; R DB20.DBX 848.7 // SINGLE BLOCK
4883 ; R DB20.DBX 849.6 // QUILL BACK
     ; R DB20.DBX 849.7 // QUILL FORE
4884
     ; R DB20.DBX 850.0 // TOOL TURNING
4885
4886 ; R DB20.DBX 850.4 // APPROACH REFERENCE POINT
4887 ; R DB20.DBX 851.1 // COOLANT
4888 ; R DB20.DBX 851.4 // PROGRAM STOP
4889
     ; R DB20.DBX 851.5 // PROGRAM START
4890 ; R DB20.DBX 851.6 // FEED RATE STOP
4891 ; R DB20.DBX 852.0 // FEED RATE START
4892 ; R DB20.DBX 852.1 // SPINDLE STOP
4893
     ; R DB20.DBX 852.3 // SPINDLE START
     ; R DB20.DBX 852.4 // AUX OFF
4894
4895 ; R DB20.DBX 852.6 // AUX ON
4896
     ; U T 47; // BLINK PULSE
4897
      ; = DB20.DBX 851.0
4898
4899
4900 ; U T 48; // START AS AN EXTENDED PULSE
4901
      ; = DB20.DBX 850.6
4902
     NETWORK
4903
     TITLE =
4904 ;
4905
4906
      NETWORK
4907
      TITLE = COOLANT
4908 U M 18.0; // INITIAL FLAG MINIMAL LUBRICATION
4909 = DB20.DBX 851.1 // LED COOLANT
4910 NETWORK
4911
      TITLE = DRYRUN ACTIVE
4912 U DB20.DBX 324.2 // DRYRUN active
4913 ; U M 94.x; // DRYRUN SFG
4914 = DB20.DBX 846.1 // LED DRYRUN
4915
      NETWORK
4916
      TITLE = FADE-OUT SET SKIP
4917 U DB20.DBX 324.6 // Skip block (SKIP) active
4918 = DB20.DBX 846.0 // LED SKIP
4919
     NETWORK
4920
      TITLE = optional stop M1 active
```

```
U DB20.DBX 324.5 // Optional stop M1 active
4921
4922 = DB20.DBX 847.4 // LED OPT.STOP (M1)
4923 NETWORK
4924 TITLE = SINGLE SENTENCE
4925 U DB20.DBX 324.7 // Single block (SINGLE) active
4926 = DB20.DBX 848.7 // LED SINGLE BLOCK
4927
     NETWORK
4928 TITLE = AUX ON LIGHT, AUX OFF FLASHING
4929 ; U T 47; // START AS AN EXTENDED PULSE
4930 O M 110.0; // AUX-ON
4931
      = DB20.DBX 852.6 // LED AUX ON
4932 NETWORK
4933 TITLE = APPROACH REFERENCE POINT
4934 U T 47; // START AS AN EXTENDED PULSE
4935
      U M 110.0; // AUX-ON
4936 O.M.121.3; // REFPKT.X, Z, APPROACH AT THE SAME TIME
4937 UN M 52.2 // REFERENCE POINT X, Y, Z AND TOOL C-AXIS ACTIVE
4938 ; UN DB20.DBX 324.4; // REFERENCE POINT ACTIVE
4939
     ; UN DB3.DBX 2.6; // 7022 INITIALIZE TOOL TURNER
4940 = DB20.DBX 850.4 // LED APPROACH REFERENCE POINT
4941 ; NETWORK
4942 ; TITLE = TOOL TURNING ACTIVE
4943
4944
      ; U DB3.DBX 2.6; // 7022 INITIALIZE TOOL TURNER
4945
     ; U T 47; // START AS AN EXTENDED PULSE
4946 ; O M 152.0; // TOOL TURNING ACTIVE
4947 ; = DB20.DBX 850.0 // LED TOOL TURNING
4948
     NETWORK
4949
     TITLE = SPINDLE STOP ACTIVE
4950 U M 132.1; // SPINDLE STOP ACTIVE
4951 U T 47; // START AS AN EXTENDED PULSE
4952 = DB20.DBX 852.3 // LED SPINDLE START
4953
     NETWORK
4954 TITLE -= FEED STOP ACTIVE
4955 ; U M 133.1; // FEED STOP ACTIVE
4956 U M 91.6; // AFG, EFG FEED STOP ACTIVE
4957
     U T 47; // START AS AN EXTENDED PULSE
4958 = DB20.DBX 852.0 // LED FEED START
4959 NETWORK
4960 TITLE = LED PROGRAM STOP ACTIVE
4961 U DB20.DBX 324.0; // program is running
4962 U DB20.DBX 324.1; // STOP STATE
4963 U T 47; // START AS AN EXTENDED PULSE
4964 = DB20.DBX 851.5 // PROGRAM START
4965 NETWORK
4966
      TITLE = VICE CLAMPED
4967 O M 138.5; // VICE CLAMPED
4968 O T 47; // START AS AN EXTENDED PULSE
4969 U DB10.DBX 75.4; // ACTIVATE PNEUMATIC CLAMPING DEVICE
4970 = DB20.DBX 849.6 // LED VICE CLAMPED
4971
      NETWORK
4972 TITLE = DOOR CLOSED AUTOMATIC DOOR
4973 O T 47; // START AS AN EXTENDED PULSE
4974 O A 3.4; // EXIT FOR AUXILIARY RELAY DOOR CLOSED
     U DB10.DBX 75.0; // ACTIVATE THE AUTOMATIC DOOR
4975
4976 = DB20.DBX 847.0 // CLOSE THE DOOR
4977 NETWORK
4978 TITLE = END PROGRAM AND CLEAR LED
4979
      ; U DB1.DBX 1440.1; // EXIT PROGRAM
     ; U M 110.0; // AUX-ON
4980
4981 ; R DB1.DBX 1440.1; // EXIT PROGRAM
4982 U DB1.DBX 1440.1; // EXIT PROGRAM
4983 UN M 110.0; // AUX-ON
4984
     SPBN M001
```

```
L W # 16 # 0; // LOAD CONSTANT HEX 0
4985
4986
      T DB20.DBW 846 // CLEAR LED IN CONTROL PANEL
4987
     T DB20.DBW 848 // CLEAR LED IN CONTROL PANEL
     T DB20.DBW 850 // CLEAR LED IN CONTROL PANEL
4988
4989
      T DB20.DBW 852 // CLEAR LED IN CONTROL PANEL
4990
      M001: NOP 0
4991
      END FUNCTION
4992 FUNCTION FC 75: VOID
4993 SURNAME:
4994 BEGIN
     U A 3.4; // MACHINE DOOR CLOSED
4995
4996 L S5TIME # 5S; // 2S
4997 SE T 14; // SWITCH-ON DELAY
4998 U T 14; // SWITCH-ON DELAY
4999
     S M 400.0 // OPEN FLAG DOOR
5000 R M 400.1 // FLAG CLOSE THE DOOR
5001 FP M 400.2
5002 U M 400.2
5003
     SPBN M001;
5004
     L MD 410
5005 L·1.
5006 + R
5007 T MD 410
5008
      M001: NOP 0;
5009 U E 4.4; // DOOR OPEN, AUTOMATIC DOOR
5010 S M 400.1 // MARKER CLOSE THE DOOR
5011 R M 400.0 // OPEN FLAG DOOR
5012
     END FUNCTION
5013
     ORGANIZATION BLOCK OB 1
5014 NAME: ORGANIZATIONAL BLOCK
5015 BEGIN
5016 U DB10.DBX 2.0; // ACTIVATE AC 2000
5017
      U E 3.0 // INPUT IDENTIFICATION AC95 CONVERSION TO ACC
5018
     = M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
5019
      O DB10.DBX 100.1 // STANDARD MACHINE ACTIVATED
5020
      O DB10.DBX 100.2 // STANDARD MACHINE WITH ROUND AXIS ACTIVATED
5021
      O M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
     ON DB10.DBX 2.0; // ACTIVATE AC 2000
5022
5023
     U·(
5024
      O DB1.DBX 1403.7 // CAM Concept surface
      O DB1.DBX 1406.0 // EASY CYCLE surface
5025
5026
      )
5027
      CC FC 64 // MO RELEASE WITH TXX AND CAMCONCEPT
5028
      O DB10.DBX 100.1 // STANDARD MACHINE ACTIVATED
5029
      O DB10.DBX 100.2 // STANDARD MACHINE WITH ROUND AXIS ACTIVATED
5030
      O M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
5031
      U DB1.DBX 1406.1 // WinNc for Sinumeric Operate
5032
      CC FC 65 // TRIP MO and move up the Z-axis with TXX and Sinumeric Operate
5033
      CALL FC 34; // ASSIGN THE INPUTS AC 95 - ACC
5034
      U DB10.DBX 2.0; // ACTIVATE AC 2000
5035
      UN M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
5036
      CC FC 23 // SAFETY CIRCUIT ACC
5037
      CALL FC 1; // INITIALIZATIONS
5038
      O DB10.DBX 100.1 // STANDARD MACHINE ACTIVATED
5039
      O DB10.DBX 100.2 // STANDARD MACHINE WITH ROUND AXIS ACTIVATED
5040
     UN DB10.DBX 100.0 // SET TOOL TURNERS ENABLED
5041
      UN DB10.DBX 100.3 // TOOL TURNER ACTIVATED
5042
      UN DB10.DBX 100.4 // TOOL TURNER AND ROUND AXLE ACTIVATED
5043
      ON DB10.DBX 2.0; // ACTIVATE AC 2000
5044
      O M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
5045
      CC FC 0; // SIMULATE TOOL TURNERS
5046 U DB1.DBX 1426.1; // ROBOTICS INTERFACE ACTIVATED WITH DISKETTE
5047
      U DB10.DBX 75.7; // ROBOTICS INTERFACE ACTIVATED WITH WINCONFIG
5048
      CC FC 40; // ROBOTICS INTERFACE
```

```
CALL FC 10; // AT PROGRAM END, RESET OR RESTART
5049
5050 CALL FC 11; // NC START AND NC STOP FROM MO OR M1
5051 CALL FC 5; // AXES READINESS
5052 O M 115.0; // FELDERER FU
5053 CC FC 3; // MAIN DRIVE FELDERER FU
5054
      O M 115.1; // LENZE FU
      CC FC 33; // MAIN DRIVE LENZE FU
5055
5056 CALL FC 4; // OPERATING MODES
5057
     UN DB10.DBX 2.0; // ACTIVATE AC 2000
5058
      CC FC 8; // AUX_ON AC95
5059
      U DB10.DBX 2.0; // ACTIVATE AC 2000
5060
     UN · M · 2.0 · / / · IDENTIFICATION · AC95 · CONVERSION · TO · ACC
5061
      CC FC 9; // AUX_ON ACC
5062
     U M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
5063
      CC FC 88 // AUX_ON AC95 CONVERSION TO ACC
5064
      CALL FC 6; // AXES_JOG
5065 CALL FC 32; // AUTOMATICALLY SWITCH TO BA REF
5066
      CALL FC 7; // REFERENCE AXES
5067
      CALL FC 16; // PLC-> OBEFL.SIGNALE
5068
      CALL FC 14; // ALARM STATUS
5069
     U DB10.DBX 75.0; // ACTIVATE THE AUTOMATIC DOOR
5070
     CC FC 17; // AUTOMATIC DOOR
5071
      U DB10.DBX 75.1; // tbsp. ACTIVATE VICE
5072
      UN DB10.DBX 75.4; // ACTIVATE PNEUMATIC CLAMPING DEVICE
5073
      U·(
      ON DB10.DBX 2.0; // ACTIVATE AC 2000
5074
5075
      O M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
5076
      CC FC 18; // tbsp. VICE
5077
5078
     U DB10.DBX 75.4; // ACTIVATE PNEUMATIC CLAMPING DEVICE
5079
     UN DB10.DBX 75.1; // ACTIVATE EL.VICE
5080
      CC FC 30; // PNEUM.CLAMPING DEVICE
5081
      UN DB10.DBX 75.4; // ACTIVATE PNEUMATIC CLAMPING DEVICE
5082 UN DB10.DBX 75.1; // ACTIVATE EL.VICE
5083 S M 18.6; // RELEASE THE EXIT FLAG VICE
5084 R M 18.5; // EXIT FLAG CLAMP VICE
5085
      FP M 26.5
     U M 26.5
5086
5087 SPBN M001;
5088 R DB15.DBX 20.2 // VICE CLAMPED SAVE IN THE SETTING DATA
      = DB15.DBX 20.1 // VICE RELEASED SAVE IN THE SETTING DATA
5089
     = DB20.DBX 348.3; // REQUEST FOR IMMEDIATE SETTING DATA BACKUP
5090
5091 M001: NOP 0;
5092 U DB10.DBX 75.6; // ACTIVATE SCHÄFER PARTIAL APPLIANCE
5093
      CC FC 21; // PARTIAL APPARATUS
5094
      U DB10.DBX 75.3; // ACTIVATE THE BLOW DEVICE
5095
     CC FC 22; // BLOW OUT
5096
     CALL FC 26; // COOLANT (M8 / M9)
5097
      CALL FC 2; // ITEM COUNTER
5098
      O DB10.DBX 100.4 // TOOL TURNER AND ROUND AXIS ACTIVATED
5099
      O DB10.DBX 100.2 // STANDARD MACHINE WITH ROUND AXIS ACTIVATED
5100 U DB10.DBX 2.0; // ACTIVATE AC 2000
5101
     UN M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
      = M 52.7 // ROUND AXIS ACTIVATED
5102
5103
      O DB10.DBX 100.0 // SET TOOL TURNERS ENABLED
      O DB10.DBX 100.3 // TOOL TURNER ACTIVATED
5104
5105
      O DB10.DBX 100.4 // TOOL TURNER AND ROUND AXIS ACTIVATED
      UN DB10.DBX 100.1 // STANDARD MACHINE ACTIVATED
5106
5107
      UN DB10.DBX 100.2 // STANDARD MACHINE WITH ROUND AXLE ACTIVATED
5108
      U DB10.DBX 2.0; // ACTIVATE AC 2000
5109 UN M 2.0 // IDENTIFICATION AC95 CONVERSION TO ACC
5110 = M 52.5 // TOOL TURNER ACTIVATED
5111
      U M 52.5 // TOOL TURNER ACTIVATED
5112
      CC FC 51; // TOOL CLAMPING SYSTEM
```

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5113
     U M 52.5 // TOOL TURNER ACTIVATED
5114
     CC FC 50; // TOOL TURNERS
5115
     U M 200.0 // SET TOOL POSITIONS
5116 U DB10.DBX 100.0 // SET TOOL TURNERS ACTIVATED
5117
      CC FC 49 // ENTER TOOL POSITIONS IN MILL55 ACC.MSD
5118
      CALL FC 12; // AFG / EFG
5119
      CALL FC 13; // NC START VERR. AND CONTROL BUTTONS
5120 U M 300.0 //
5121
      CC FC 75; //
5122
      O DB1.DBX 1370.2; // ACKNOWLEDGMENT KEY PRESSED
5123
      O DB1.DBX 1370.3; // RESET KEY PRESSED
5124
     O DB2.DBX 1.1; // HW ERROR SAFETY CIRCUIT
5125 R M 300.0 //
5126 R M 400.0 // OPEN FLAG DOOR
5127
      R M 400.1 // FLAG CLOSE THE DOOR
5128
      CALL FC 62; // LED CONTROL
5129
     CALL FC 63; // WARNING LIGHT
5130
      CALL FC 41; // RENISHAW PROBE
5131
      U DB10.DBX 2.0; // ACTIVATE ACC
5132
      CC FC 66; // HANDWHEEL
5133
     CALL FC 35; // ASSIGN THE OUTPUTS AC95 - ACC
5134
     ; DB10.DBX B100 =; Bit 0.1 (MILL55 .MSD) SET TOOL TURNING ACTIVATED
5135
      ; DB10.DBX B100 =; Bit 1 2 (MILL55A.MSD) STANDARD MACHINE ACTIVATED
5136
      ; DB10.DBX B100 =; Bit 2 4 (MILL55B.MSD) STANDARD MACHINE WITH ROUND AXIS ACTIVATED
5137
      ; DB10.DBX B100 =; Bit 3.8 (MILL55C.MSD) TOOL TURNER ACTIVATED
5138
     ; DB10.DBX B100 =; Bit 4 16 (MILL55D.MSD) TOOL TURNER AND ROUND AXIS ACTIVATED
     ; U DB10.DBX 100.0 // SET TOOL TURNERS ACTIVATED
5139
5140
      ; U DB10.DBX 100.1 // STANDARD MACHINE ACTIVATED
     ; U DB10.DBX 100.2 // STANDARD MACHINE WITH ROUND AXIS ACTIVATED
5141
     ; U DB10.DBX 100.3 // TOOL TURNER ACTIVATED
5142
     ; U DB10.DBX 100.4 // TOOL TURNERS AND ROUND AXES ACTIVATED
5143
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5144

5145

5146

U DB25.DBX 332.0; // NC BLOCK DONE

END\_ORGANIZATION\_BLOCK

R DB25.DBX 332.0; // NC BLOCK DONE