Elektrische Dokumentation Electrical Documentation

EMCO PCTurn 55

Version A6P_V01

Ref. No. ZVP675010

Typenschild aufkleben!

Elektro-Dokumentation Emco PCTurn 55 Version A6P_V01

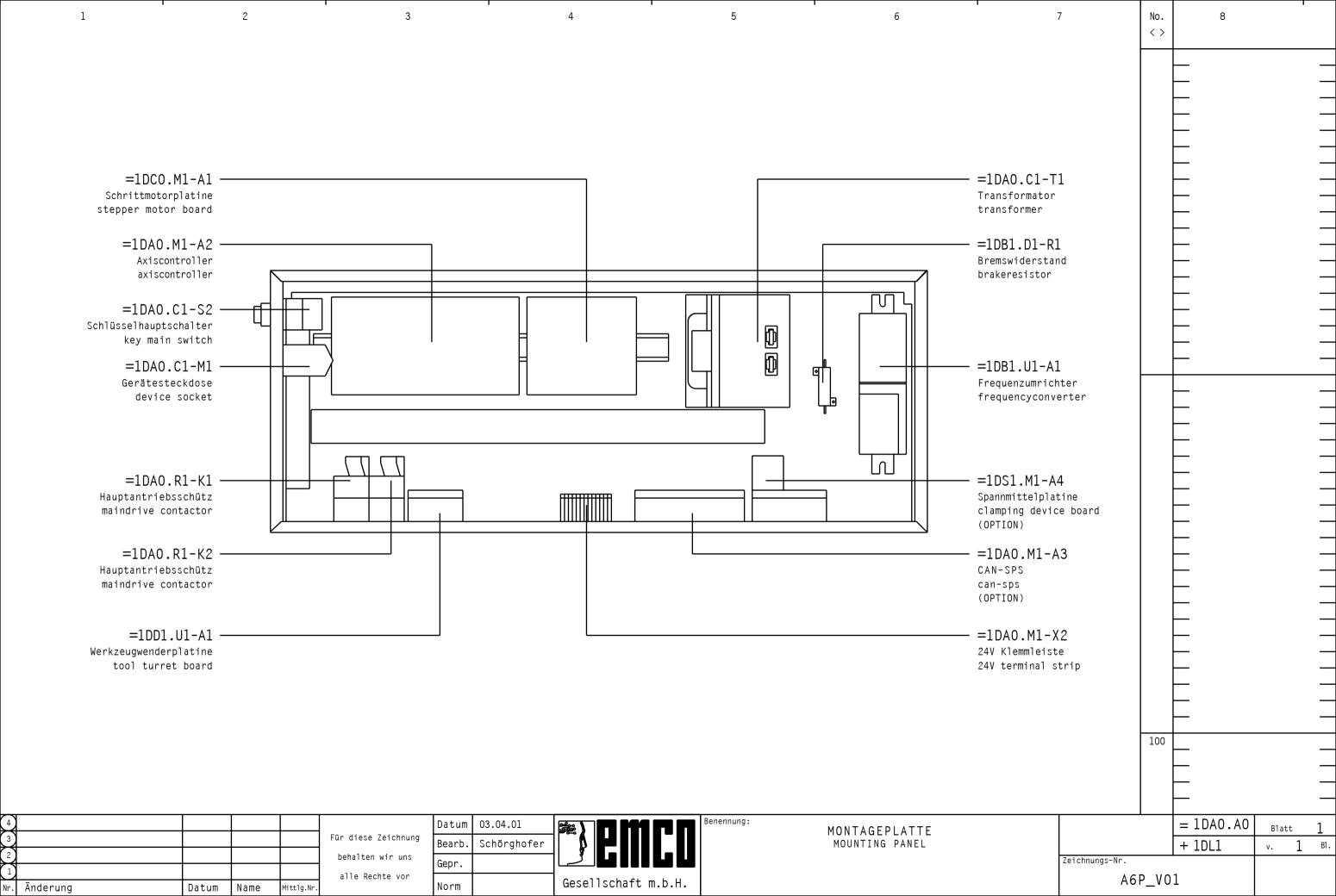


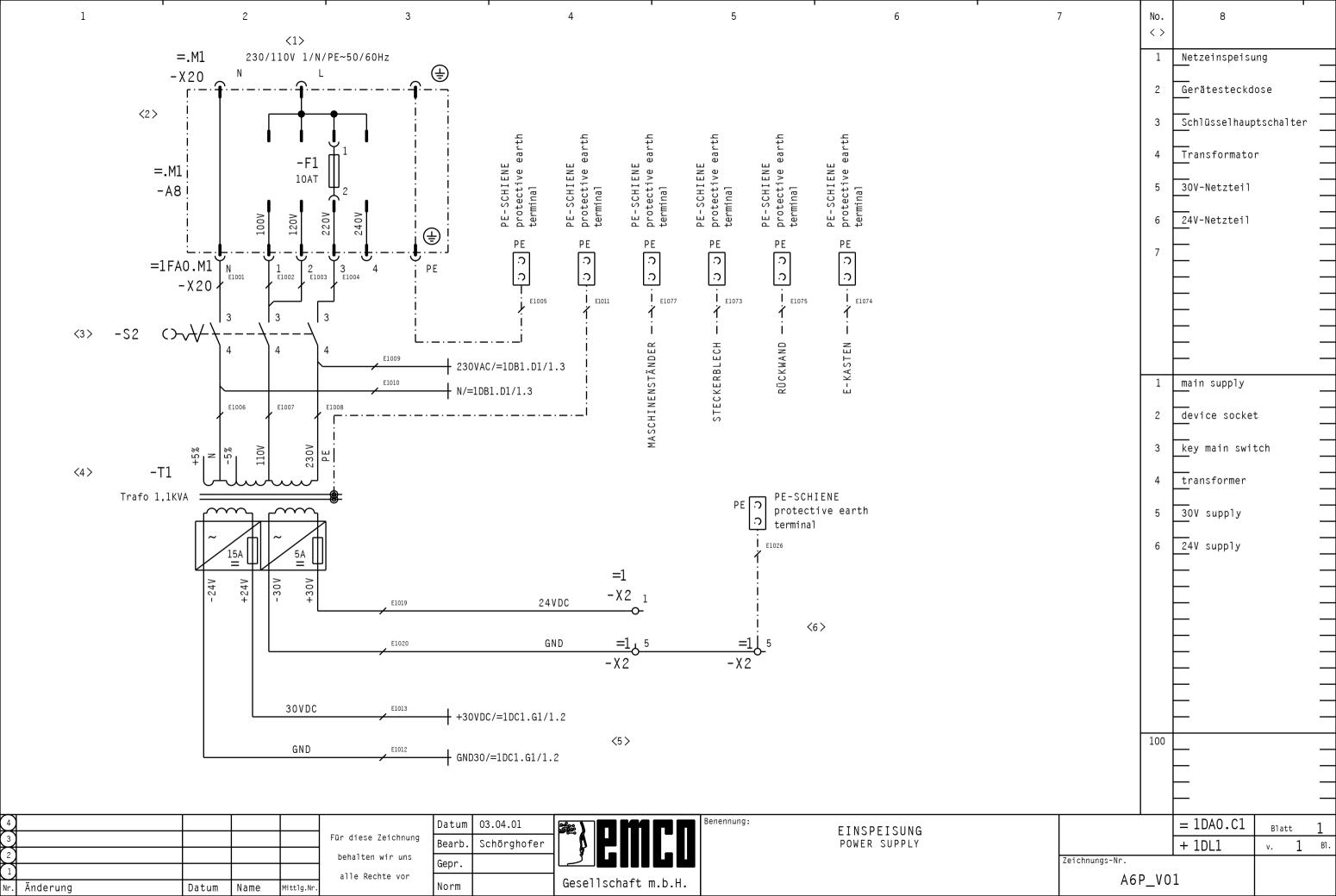
Elektrische Dokumentation EMCO PCTurn 55

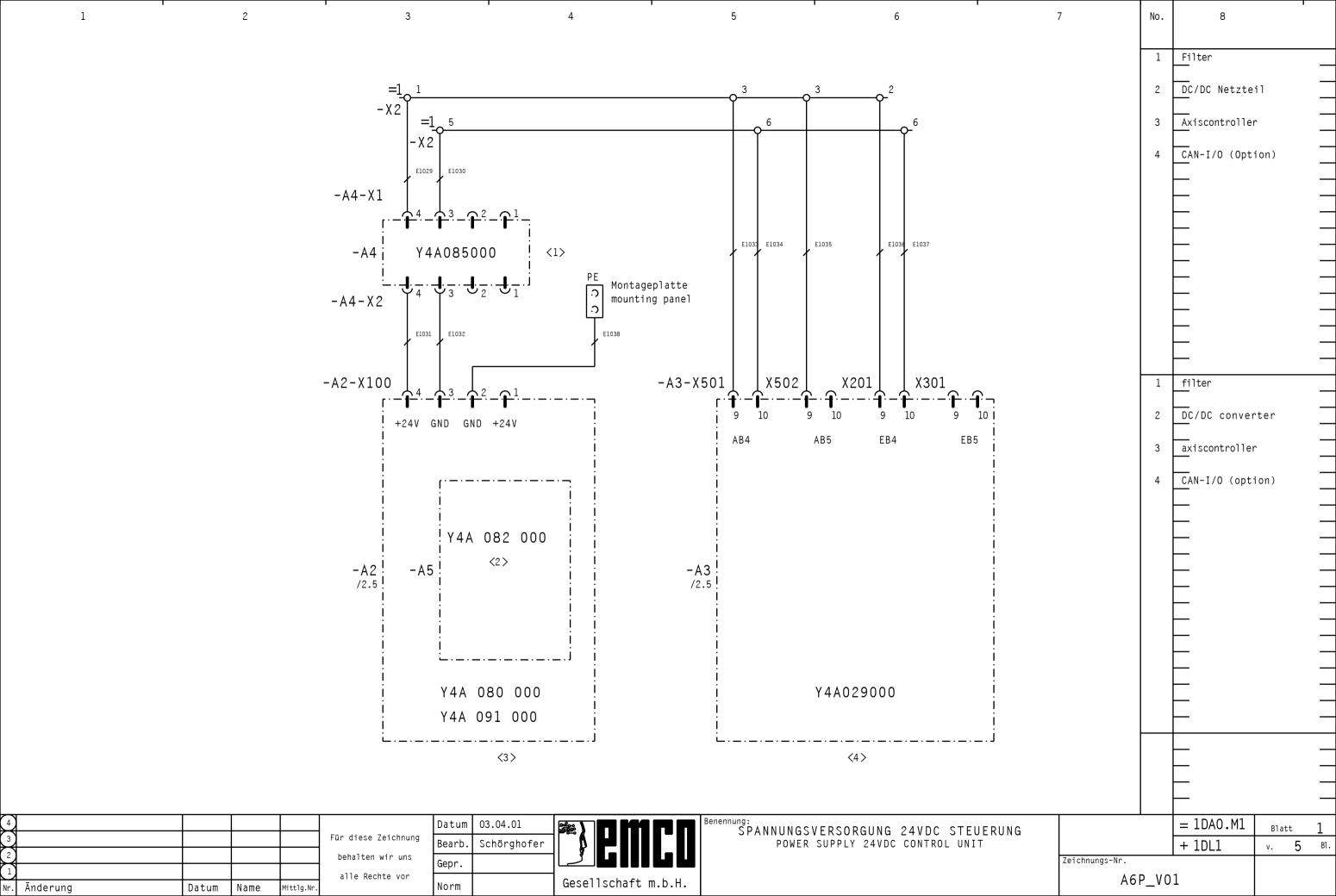
Versionen und Änderungen:

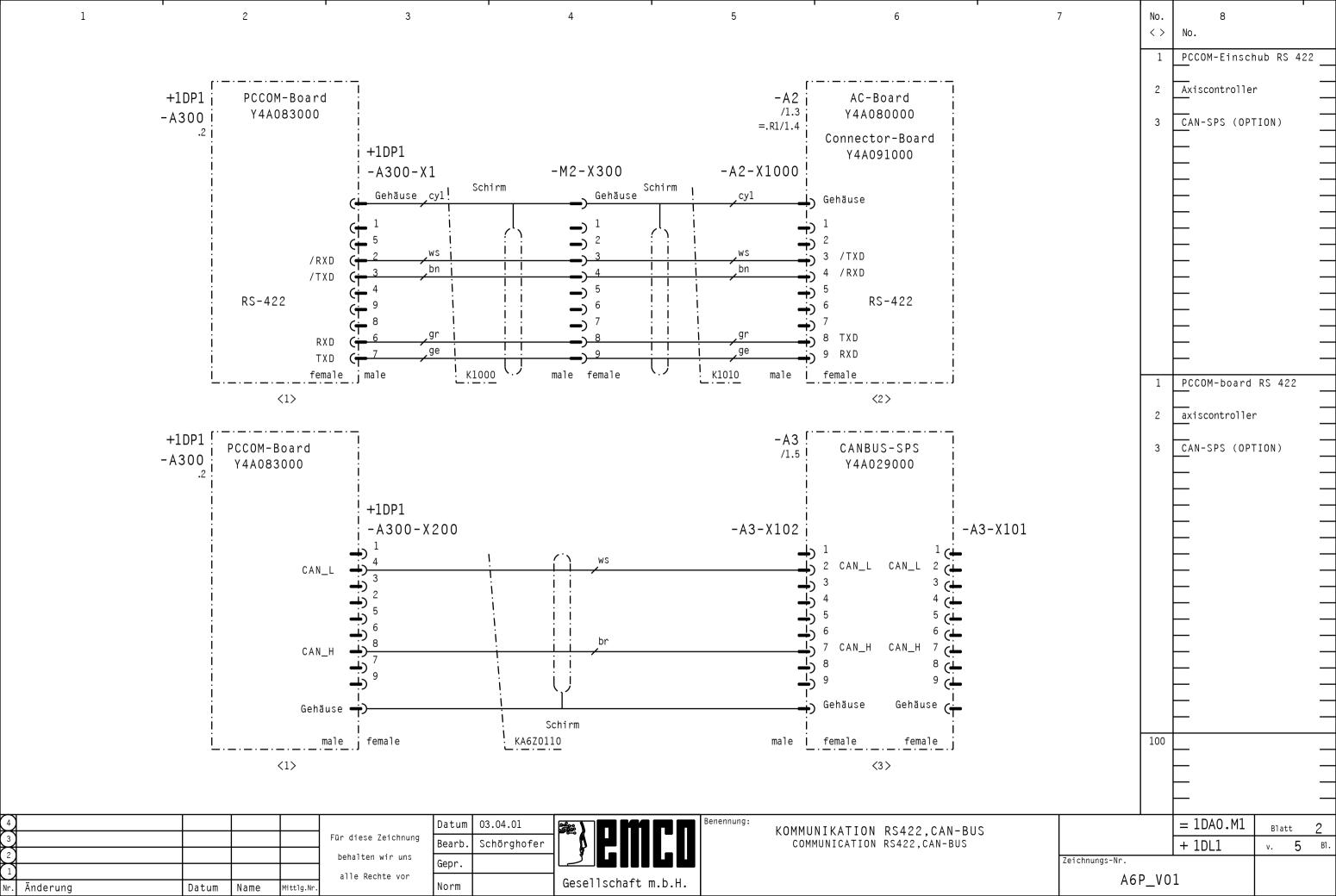
VERSION:	ÄNDERUNGEN:	KOMMENTAR:
A6P_V00		Neuausgabe (Serienstand)
A6P_V01	17.05.1999	Umstellung auf 3-Phasen-Schrittmotoren und
		Lenze Hauptantriebssteller.

	Datum:	Name:	Unterschrift:
Bearbeitet:	17.05.1999	Friedrich Schörghofer	
Geprüft:	17.05.1999	Reiter Georg	
für Serie Freigegeben:	17.05.1999	Friedrich Schörghofer	









Pin Nr.	Signal	=1DA0.M1-A2		Blatt Strompfad
		Funktionserkläru	ng	
-X100 : 1	+24V			
-X100 : 2	GND			
-X100 : 3	GND	Versorgung AC	supply AC	=1DA0.M1/1.3
-X100 : 4	+24V	Versorgung AC	supply AC	=1DA0.M1/1.3
-X101 : 1	+5V	+5V	+5V	=1DD1.H1/1.5
-X101 : 2	GND	GND	GND	=1DD1.H1/1.5
-X101 : 3	E 2.1	WZW-Strobe	tool turret-strobe	=1DD1.H1/1.5
		WZW Strobt	tool turret strope	-IDD1:N1/1:3
-X102 : 1	+5 V			
-X102 : 2	GND			
-X102 : 3	E 2.2	WZW-Sync	tool turret-sync	=1DD1.H1/1.7
-X103 : 1	+24V	+24V	+24V	=1DB1.M1/1.7
-X103 : 2	GND			
-X103 : 3	E 2.3	n=0	n=0	=1DB1.M1/1.7
-X105 : 1	+24V			
-X105 : 2	GND			
-X105 : 3	E 2.4			
-X104 : 1	SR X	Servo Ready X	servo ready X	=1DC1.M1/1.2
-X104 : 2	DIR X	Richtung X	dirction X	=1DC1.M1/1.2
-X104 : 3	DIR X/	Richtung X/	dirction X/	=1DC1.M1/1.2
-X104 : 4	CK X	Takt X	clock X	=1DC1.M1/1.3
-X104 : 5	CK X/	Takt X/	clock X/	=1DC1.M1/1.3
-X104 : 6	SR Z	Servo Ready Z	servo ready Z	=1DC2.M1/1.3
-X104 : 7	DIR Z	Richtung Z	dirction Z	=1DC2.M1/1.3
-X104 : 8	DIR Z/	Richtung Z/	dirction Z/	=1DC2.M1/1.3
-X104 : 9	CK Z	Takt Z	clock Z	=1DC2.M1/1.3
-X104 : 10	CK Z/	Takt Z/	clock Z/	=1DC2.M1/1.4
-X104 : 11	SR Y	Servo Ready Y	servo ready Y	
-X104 : 12	DIR Y	Richtung Y	dirction Y	
-X104 : 13	DIR Y/	Richtung Y/	dirction Y/	
-X104 : 14	CK Y/	Takt Y	clock Y	
-X104 : 15	CK Y/	Takt Y/	clock Y/	
-X104 : 16	DOOR	Freigabe Achsen	enable axis	=1DC2.M1/1.4
-X106 : 1	+5 V	+5V	+5 V	=1DC1.M1/1.4
-X106 : 2	GND	GND	GND	=1DC1.M1/1.4
-X106 : 3	+5 V			

Funktionserklär Drehfeldfrequenz GND Sollwert +24V Betriebsbereit Reglerfreigabe Richtung HA GND +5V	rotating frequency GND control value +24V Servo ready release controler direction MD GND	=1DB1.M1/1.2 =1DB1.M1/1.2 =1DB1.M1/1.2 =1DB1.M1/1.3 =1DB1.M1/1.3 =1DB1.M1/1.4
GND Sollwert +24V Betriebsbereit Reglerfreigabe Richtung HA GND	rotating frequency GND control value +24V Servo ready release controler direction MD	=1DB1.M1/1.2 =1DB1.M1/1.2 =1DB1.M1/1.3 =1DB1.M1/1.3 =1DB1.M1/1.4
Sollwert +24V Betriebsbereit Reglerfreigabe Richtung HA GND	control value +24V Servo ready release controler direction MD	=1DB1.M1/1.2 =1DB1.M1/1.3 =1DB1.M1/1.3 =1DB1.M1/1.4
+24V Betriebsbereit Reglerfreigabe Richtung HA GND	+24V Servo ready release controler direction MD	=1DB1.M1/1.3 =1DB1.M1/1.3 =1DB1.M1/1.4
Reglerfreigabe Richtung HA GND	Servo ready release controler direction MD	=1DB1.M1/1.3 =1DB1.M1/1.4
Reglerfreigabe Richtung HA GND	Servo ready release controler direction MD	=1DB1.M1/1.3 =1DB1.M1/1.4
Reglerfreigabe Richtung HA GND	Servo ready release controler direction MD	=1DB1.M1/1.3 =1DB1.M1/1.4
Reglerfreigabe Richtung HA GND	release controler direction MD	=1DB1.M1/1.4
Richtung HA GND	direction MD	
Richtung HA GND	direction MD	
Richtung HA GND		
GND		
GND		
GND		
	GND	=1DB1.M1/1.5
+5 V		=1DB1.M1/1.5
1 1 0 1	+5 V	=1DB1.M1/1.6
GND	GND	=1DB1.M1/1.6
		202201127200
SYNC	sync	=1DB1.M1/1.7
E STROBE	strobe	=1DB1.M1/1.6
NOT AUS	E-OFF	=1DAO.R1/1.6
112.112.112.112.112.112.112.112.112.112	2	
Freigabe Achsen	enable axis	
HA-Schütz	HA-contactor	=1DAO.R1/1.6
1111 CONTACT	1111 0011040001	15/10/11/1/110
Türendschalter	limit-switch door	=1DAO.R1/1.5
Räderdeckelschalter		=1DAO.R1/1.5
	HA-Schütz Türendschalter	HA-Schütz HA-contactor Türendschalter limit-switch door

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Datum	03.04.01
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Gepr.	
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AC-AUSGANGS/EINGANGSLISTE AC-output/input list

	= 1DA0.M1	Blatt		3
	+ 1DL1	٧.	5	В1.
eichnungs-Nr.				
A6P_V0				

Pin Nr.	Signal	=1DA0.M1-A2		Blatt Strompfad
		Funktionserklärung	J	
-X112 : 1				
-X112 : 2				
-X112 : 3				
-X112 : 4	+5 V	+5V	+5V	
-X112 : 5	UAO	Sync-Impuls HA	sync-impuls MD	
-X112 : 6	/UA2	Impulse HA	Impulse MD	
-X112 : 7	GND	GND	GND	
-X112 : 8	UA1	Impulse HA	Impulse MD	
-X112 : 9				
-X112 : 10	+5V	+5V	+5 V	
-X112 : 11				
-X112 : 12	/UAO	Sync-Impuls HA	sync-impuls MD	
-X112 : 13	GND	GND	GND	
-X112 : 14	UA2	Impulse HA	Impulse MD	
-X112 : 15	/UA1	Impulse HA	Impulse MD	
-X113 : 1	+24V	+24V	+24V	=1DC1.M1/1.5
-X113 : 1 -X113 : 2	GND	+24V	T24V	-1001.01/1.5
-X113 : 2	REF X	Referenzpunktschalter X	reference point switch X	=1DC1.M1/1.5
-X114 : 1	+24V	+24V	+24V	=1DC1.M1/1.7
-X114 : 2	GND	GND	GND	=1DC1.M1/1.7
-X114 : 3	SYNC X	Sync-Impuls X-Achse	sync-impuls X-axis	=1DC1.M1/1.6
-X115 : 1	+24V	+24V	+24V	
-X115 : 2	GND	1	1211	
-X115 : 2	REF Y	Referenzpunktschalter Y	reference point switch Y	
	NET 1	Referenzpankosenariser i	reference points surveil 1	
-X116 : 1	+24V	+24V	+24V	
-X116 : 2	GND	GND	GND	
-X116 : 3	SYNC Y	Sync-Impuls Y-Achse	sync-impuls Y-axis	
-X117 : 1	+24V	+24V	+24V	=1DC2.M1/1.5
-X117 : 2	GND			
-X117 : 3	REF Z	Referenzpunktschalter Z	reference point switch Z	=1DC2.M1/1.5
V110 · 1		·	·	
-X118 : 1 -X118 : 2	+24V	+24V	+24V	=1DC2.M1/1.6 =1DC2.M1/1.6
-X118 : 2 -X118 : 3	GND SYNC Z	GND Sync-Impuls Z-Achse	GND	=1DC2.M1/1.6 =1DC2.M1/1.6
_V110 : 2	STNC Z	Sync-Impurs Z-Achse	sync-impuls Z-axis	-IDC7.MI/1.0
			,	
			Datum 03.04.01	ofer
		Für d	iese Zeichnung Bearb. Schörgh	ofer A

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Funktionserklärung -X120 : 1	n Nr.	Signal	=1DA0.M1-A2	Blatt Strompfad		
-X120 : 2 GND			Funktionserklärung	1		
-X120 : 3	20 : 1	+24V				
-X121 : 1	20 : 2	GND				
-X121 : 2 GND -X121 : 3 A 0.1 -X122 : 1 +24V -X122 : 2 GND -X122 : 3 A 0.4 -X123 : 1 +24V -X123 : 2 GND -X123 : 2 GND -X123 : 3 A 0.3 -X1000 : 1 N.CX1000 : 2 N.CX1000 : 3 /TXD RS 422 RS 422 =1DA0.M1 -X1000 : 5 N.CX1000 : 6 N.CX1000 : 7 N.CX1000 : 8 TXD RS 422 RS 422 =1DA0.M1 -X1000 : 8 TXD RS 422 RS 422 =1DA0.M1	20 : 3	A 0.2	WZW-schwenken	tool turret change	=1DD1.H1/1.4	
-X121 : 3	21 : 1	+24V				
-X122 : 1	21 : 2	GND				
-X122 : 2 GND	21 : 3	A 0.1				
-X122 : 2 GND	22 : 1	+24V				
-X122 : 3						
-X123 : 2 GND -X123 : 3 A 0.3 -X1000 : 1 N.CX1000 : 2 N.CX1000 : 3 /TXD RS 422 RS 422 =1DA0.M1 -X1000 : 4 /RXD RS 422 RS 422 =1DA0.M1 -X1000 : 5 N.CX1000 : 6 N.CX1000 : 7 N.CX1000 : 8 TXD RS 422 RS 422 =1DA0.M1						
-X123 : 2 GND -X123 : 3 A 0.3 -X1000 : 1 N.CX1000 : 2 N.CX1000 : 3 /TXD RS 422 RS 422 =1DA0.M1 -X1000 : 4 /RXD RS 422 RS 422 =1DA0.M1 -X1000 : 5 N.CX1000 : 6 N.CX1000 : 7 N.CX1000 : 8 TXD RS 422 RS 422 =1DA0.M1	23 : 1	+24V				
-X123 : 3						
-X1000 : 2 N.C. -X1000 : 3 /TXD RS 422 RS 422 =1DA0.M1 -X1000 : 4 /RXD RS 422 RS 422 =1DA0.M1 -X1000 : 5 N.C. -X1000 : 6 N.C. -X1000 : 7 N.C. -X1000 : 8 TXD RS 422 RS 422 =1DA0.M1						
-X1000 : 2 N.C. -X1000 : 3 /TXD RS 422 RS 422 =1DA0.M1 -X1000 : 4 /RXD RS 422 RS 422 =1DA0.M1 -X1000 : 5 N.C. -X1000 : 6 N.C. -X1000 : 7 N.C. -X1000 : 8 TXD RS 422 RS 422 =1DA0.M1	000 : 1	N.C.				
-X1000 : 3						
-X1000 : 4			RS 422	RS 422	=1DA0.M1/4.5	
-X1000 : 6 N.C. -X1000 : 7 N.C. -X1000 : 8 TXD RS 422 RS 422 =1DAO.M1					=1DAO.M1/4.5	
-X1000 : 7 N.C. -X1000 : 8 TXD RS 422 RS 422 =1DA0.M1	.000 : 5	N.C.				
-X1000 : 8 TXD RS 422 RS 422 =1DA0.M1	.000 : 6	N.C.				
	.000 : 7	N.C.				
-X1000:9 RXD RS 422 RS 422 =1DA0.M1	.000 : 8	TXD	RS 422	RS 422	=1DA0.M1/4.5	
	000:9	RXD	RS 422	RS 422	=1DA0.M1/4.5	

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SPS - BELEGUNG SPS - CONNECTIONS EINGÄNGE EB 0/1/2/3 INPUTS EB 0/1/2/3

5

	= 1DAO.M1	Bla	tt	4
	+ 1DL1	٧.	5	B1
ichnungs-Nr.				
A6P_V0	1			

-A3 EINGANG AUSGANG Eingänge Ausgänge Blatt Blatt Strompfad Strompfad PIN Funktionserklärung Funktionserklärung E 4.0 quill no part clamped =1DS1.M1/1.5 X201:1 A 4.0 =1DR2.M1/1.2 X501:1 chuck open =1DS1.M1/1.6 X201:2 =1DR2.M1/1.4 E 4.1 quill open A 4.1 chuck close X501:2 E 4.2 X201:3 A 4.2 =1DR1.M1/1.4 X501:3 exhaust valve E 4.3 chuck pressure switch =1DR2.M1/1.5 X201:4 A 4.3 open door =1DP1.M1/1.2 X501:4 E 4.4 =1DP1.M1/1.6 X201:5 close door =1DP1.M1/1.4 X501:5 door open A 4.4 E 4.5 A 4.5 =1DS1.M1/1.4 X201:6 =1DS1.M1/1.3 X501:6 quill clamped close quill E 4.6 X201:7 A 4.6 open quill =1DS1.M1/1.3 X501:7 E 4.7 X201:8 A 4.7 X501:8 +24VDC X201:9 +24VDC X501:9 GND X201:10 GND X501:10 E 5.0 X301:1 A 5.0 X502:1 Robotic/close door Robotic/programm stop (M0,M1,M2,M30) E 5.1 Robotic/open door X301:2 A 5.1 Robotic/chuck declamped X502:2 E 5.2 Robotic/open quill X301:3 A 5.2 Robotic/chuck clamped X502:3 X502:4 E 5.3 Robotic/close quill X301:4 A 5.3 Robotic/door open X502:5 E 5.4 Robotic/open chuck X301:5 A 5.4 Robotic/door closed E 5.5 Robotic/close chuck A 5.5 Robotic/quill declamped X502:6 X301:6 E 5.6 Robotic/programm start X301:7 A 5.6 Robotic/quill clamped X502:7 E 5.7 Robotic/feed hold X301:8 A 5.7 Alarm status X502:8 +24VDC +24VDC X201:9 X501:9 GND X201:10 GND X501:10

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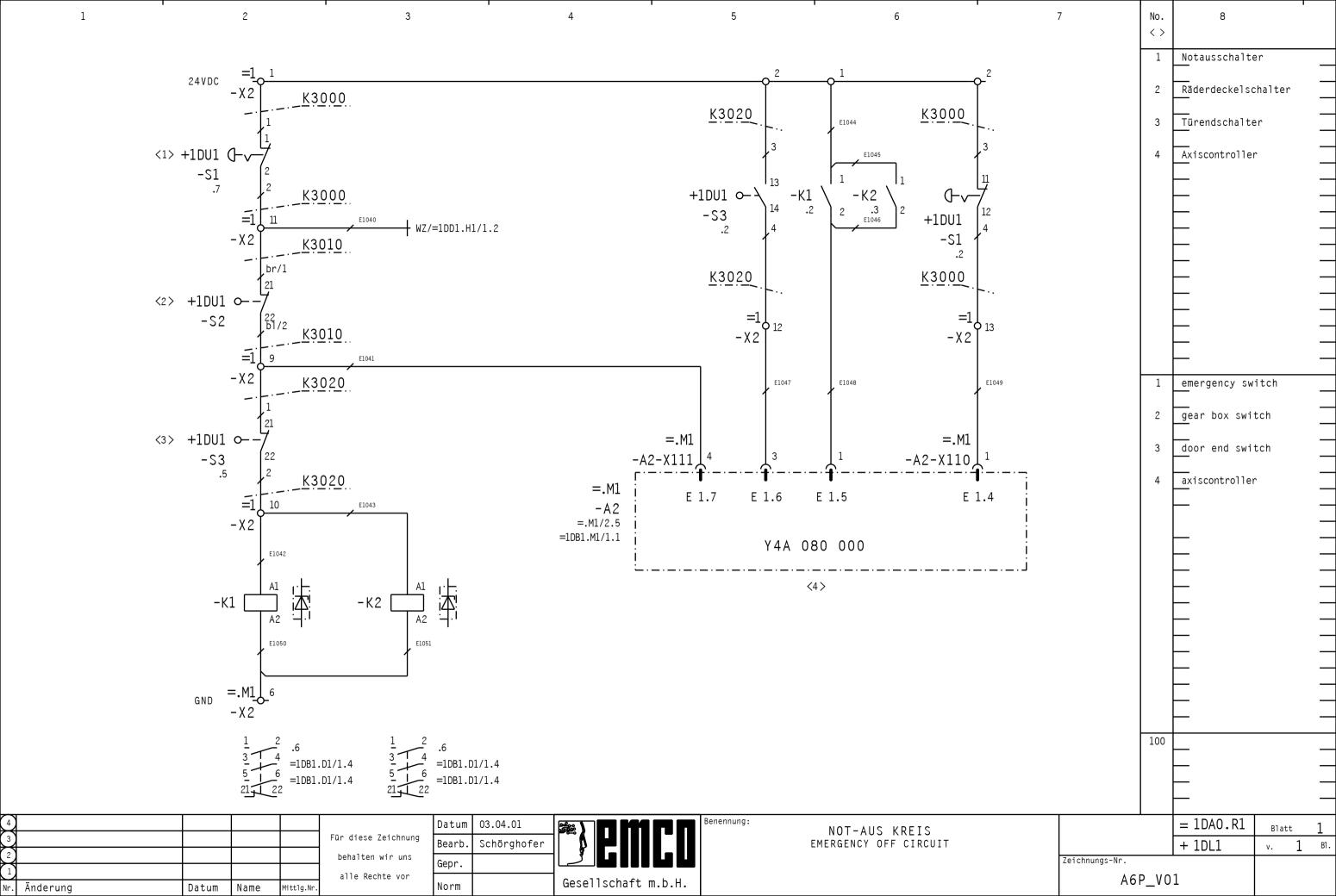
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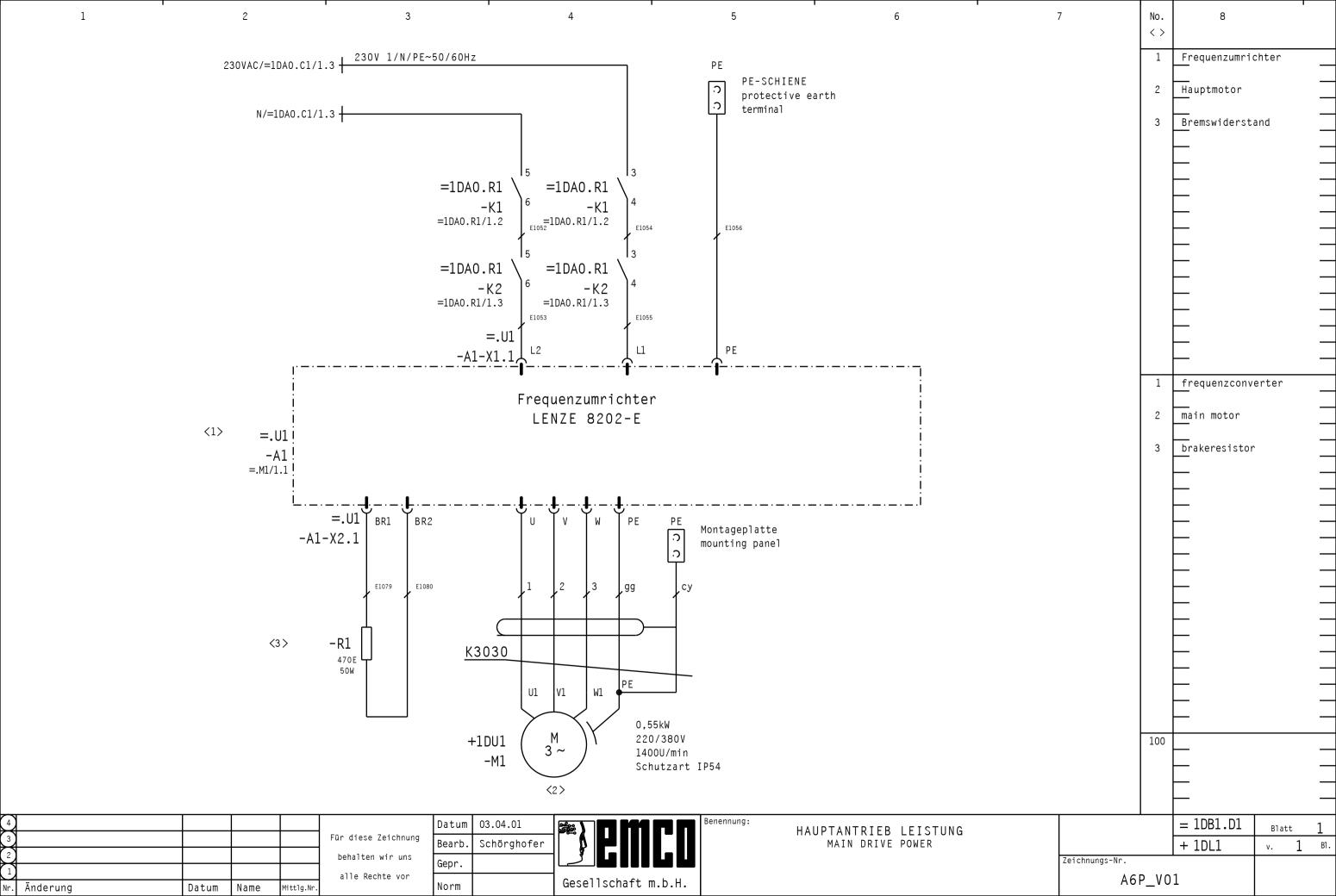
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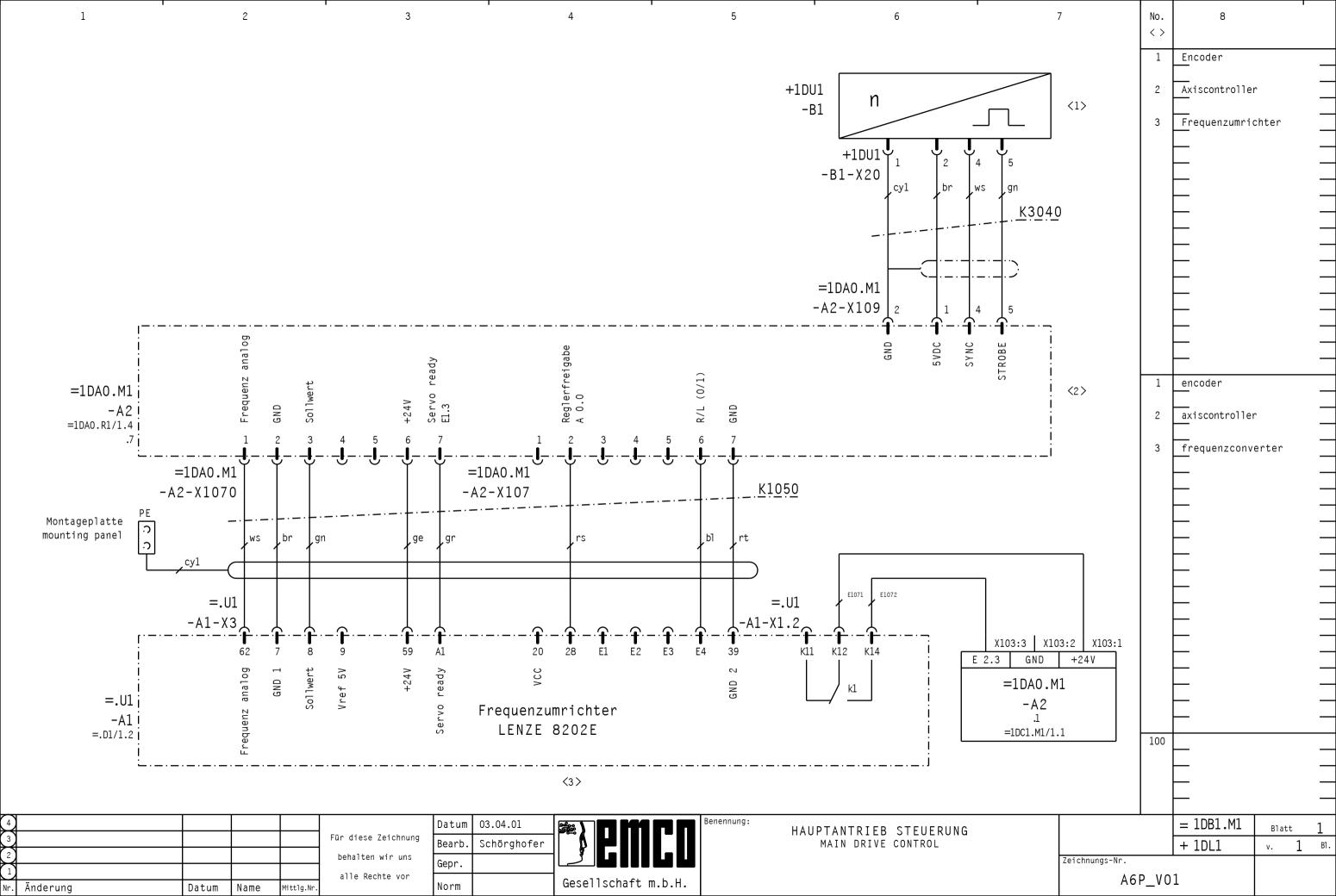
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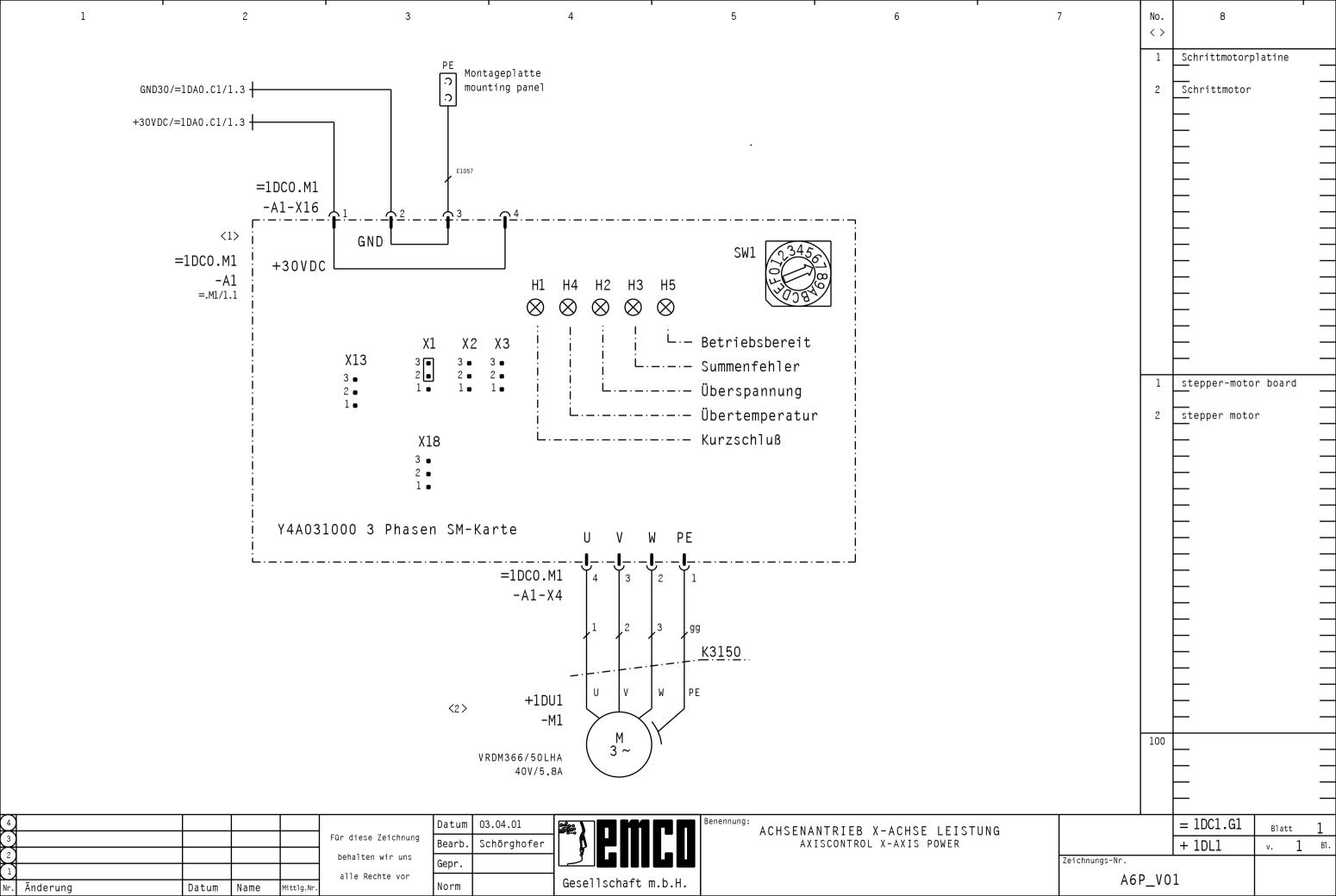
CAN-EIN/AUSGÄNGE
CAN-input/output

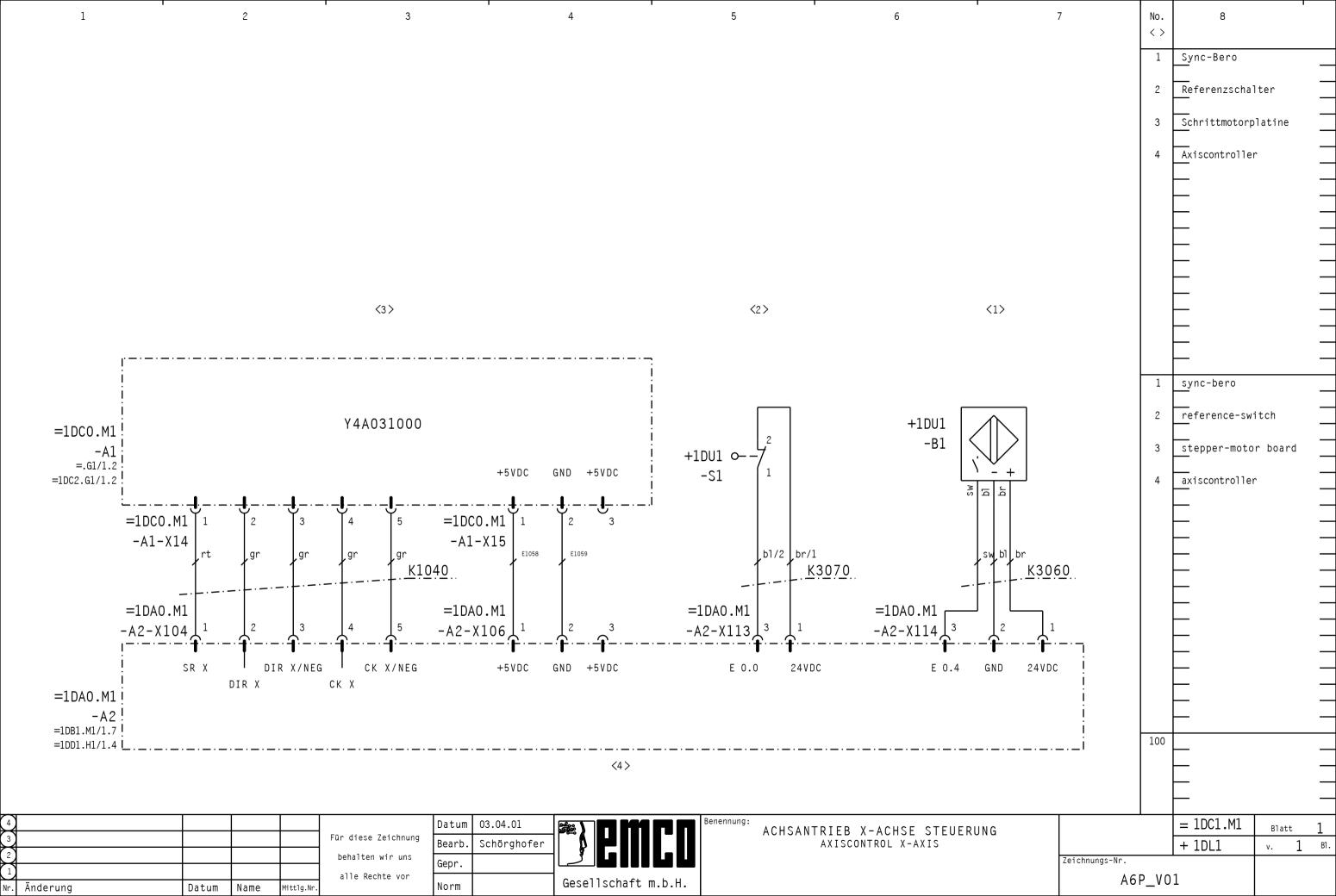
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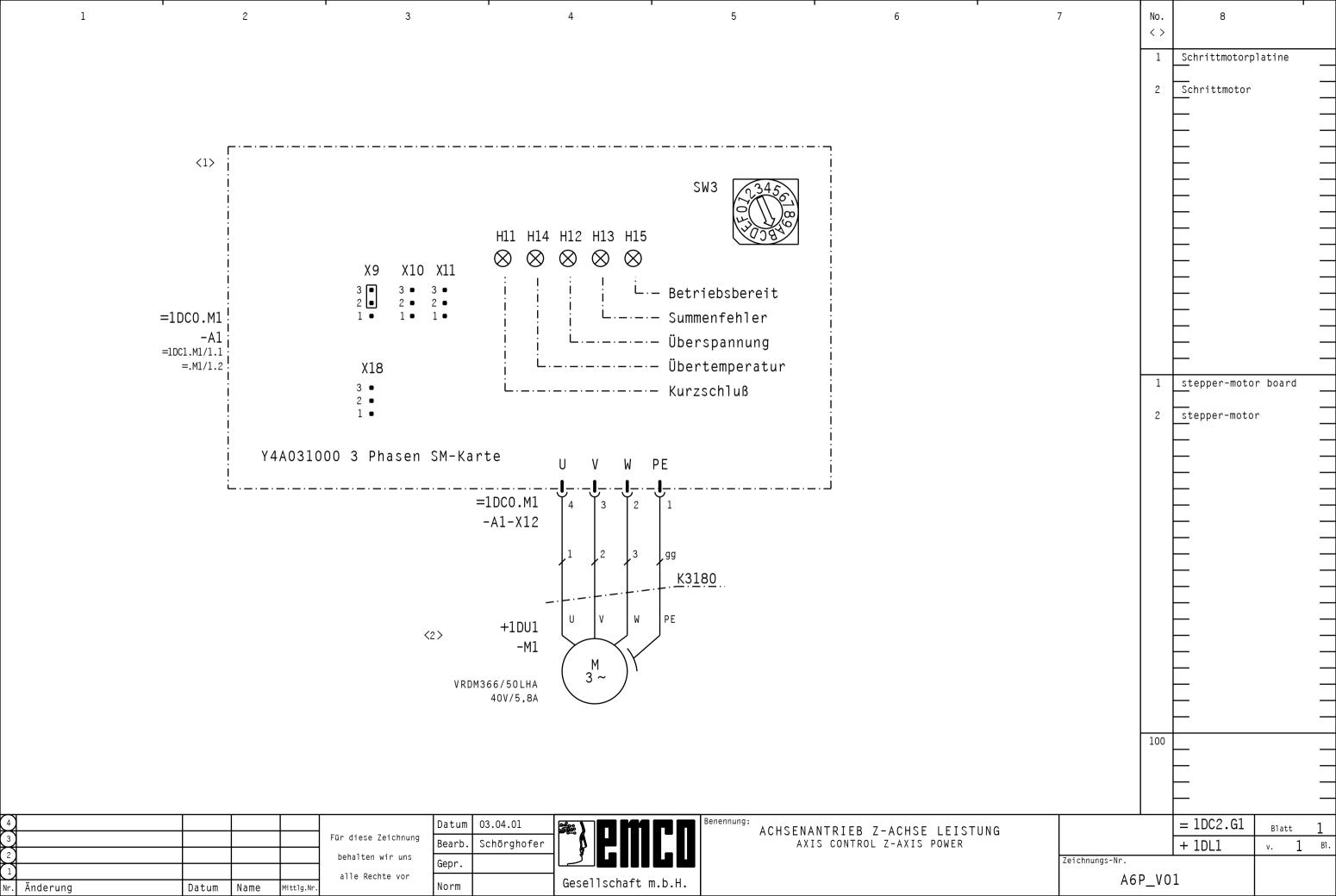


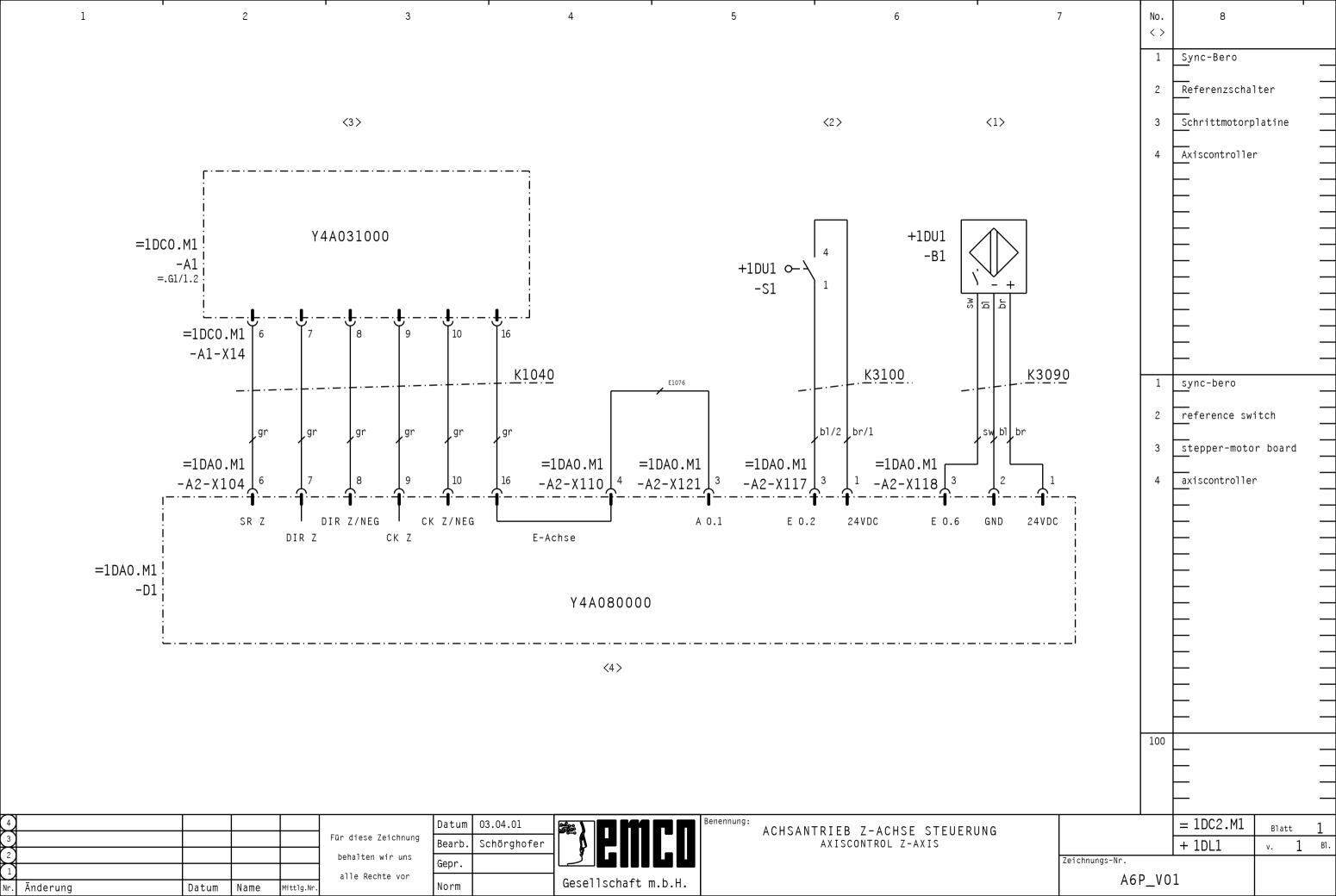


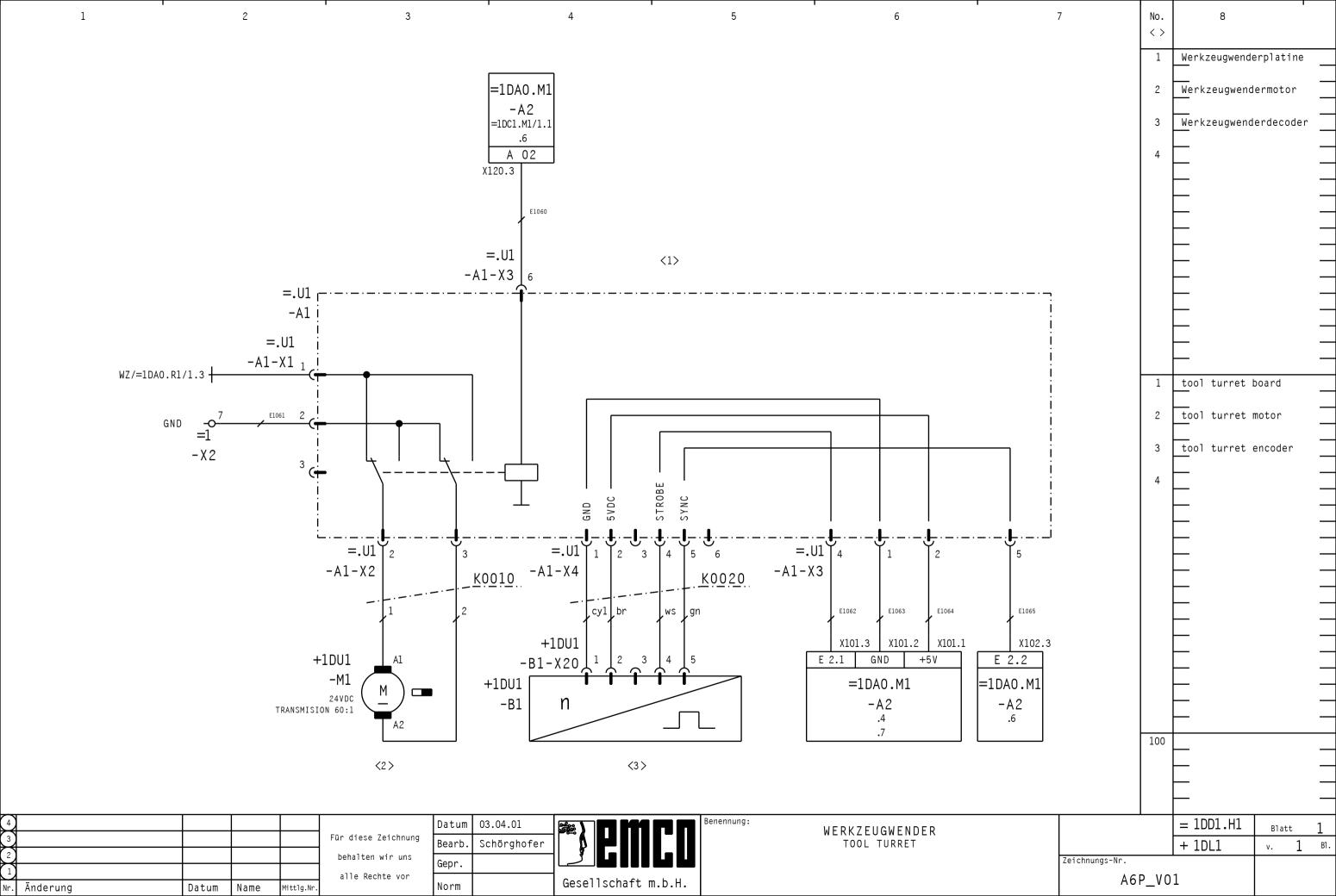


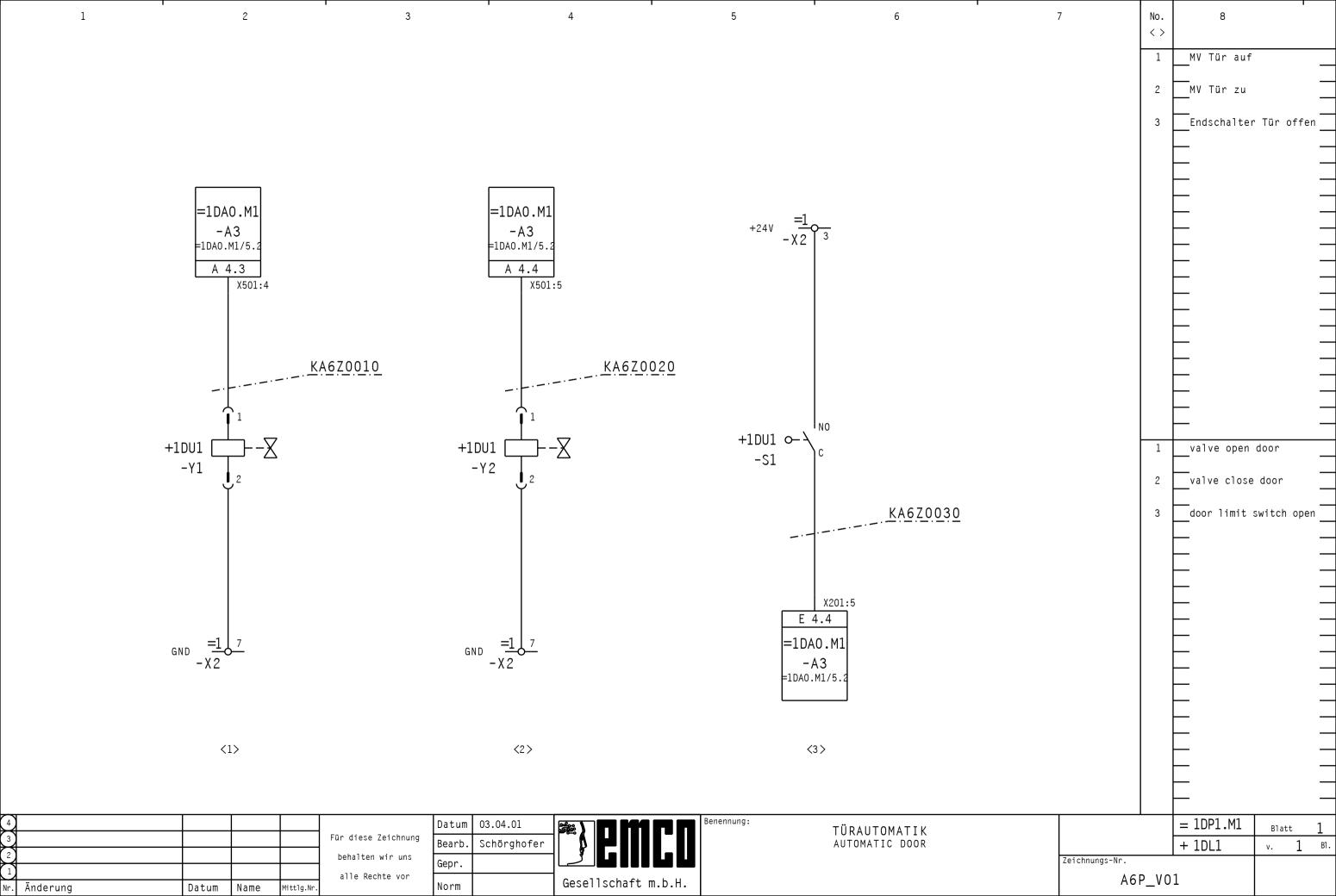


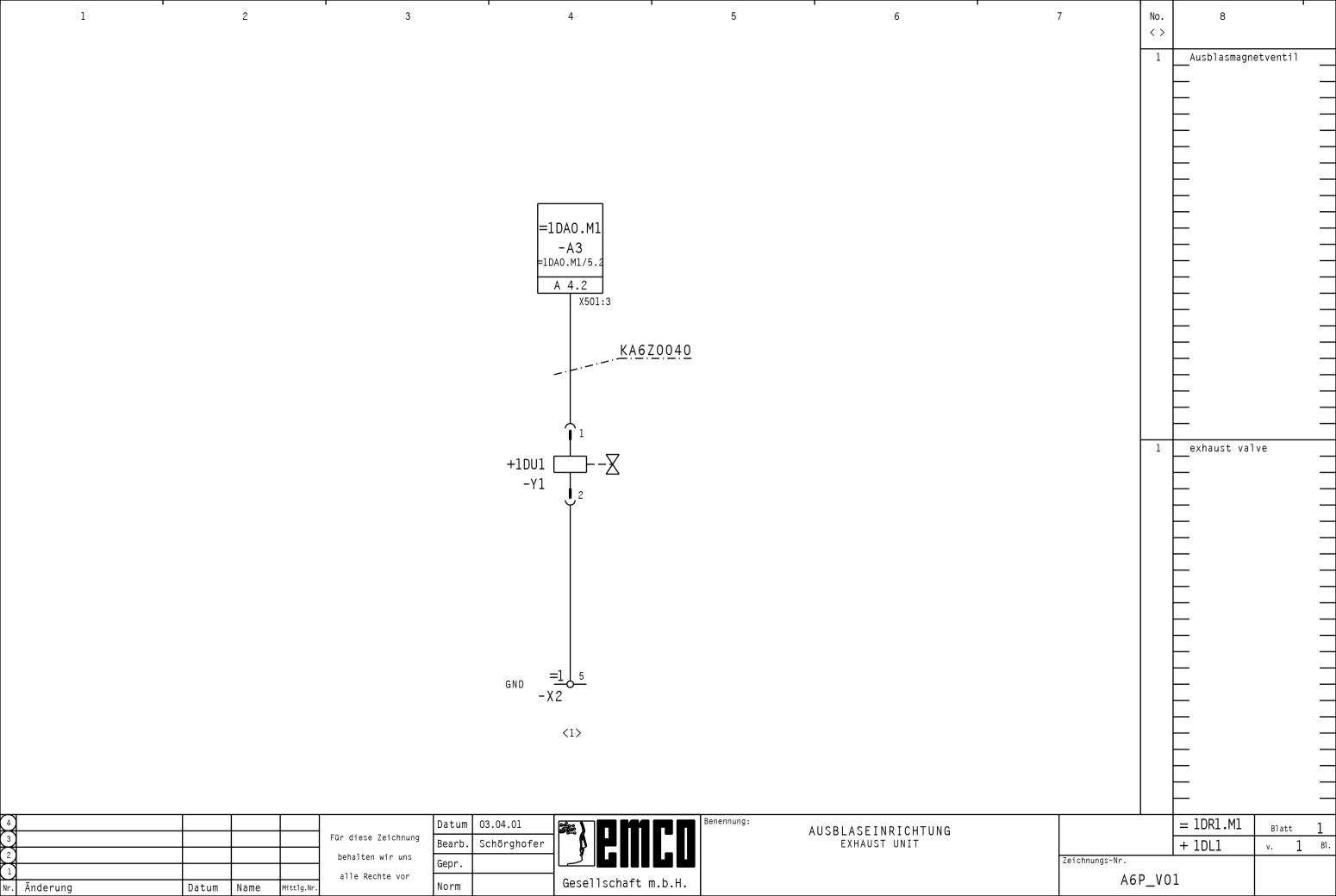


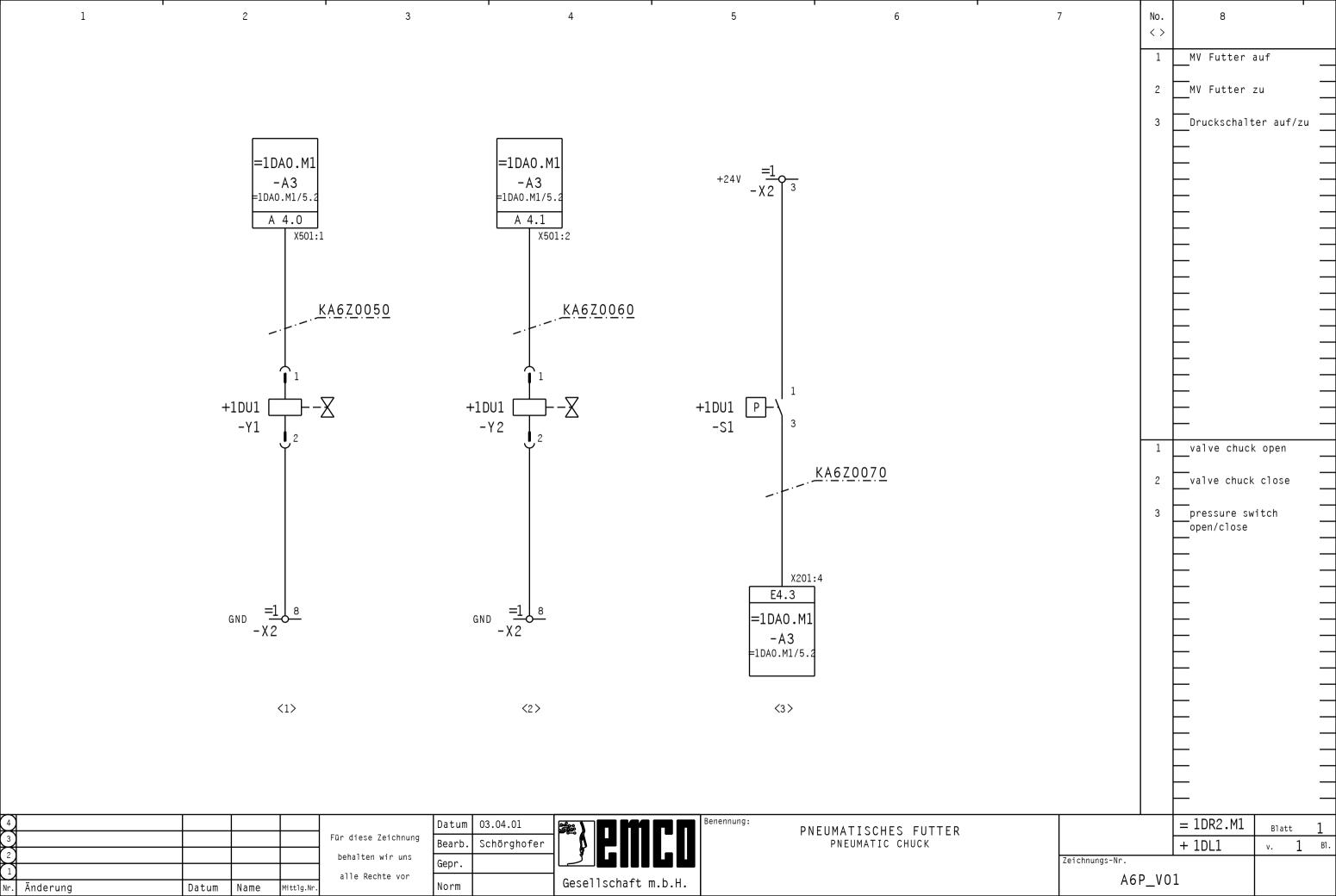


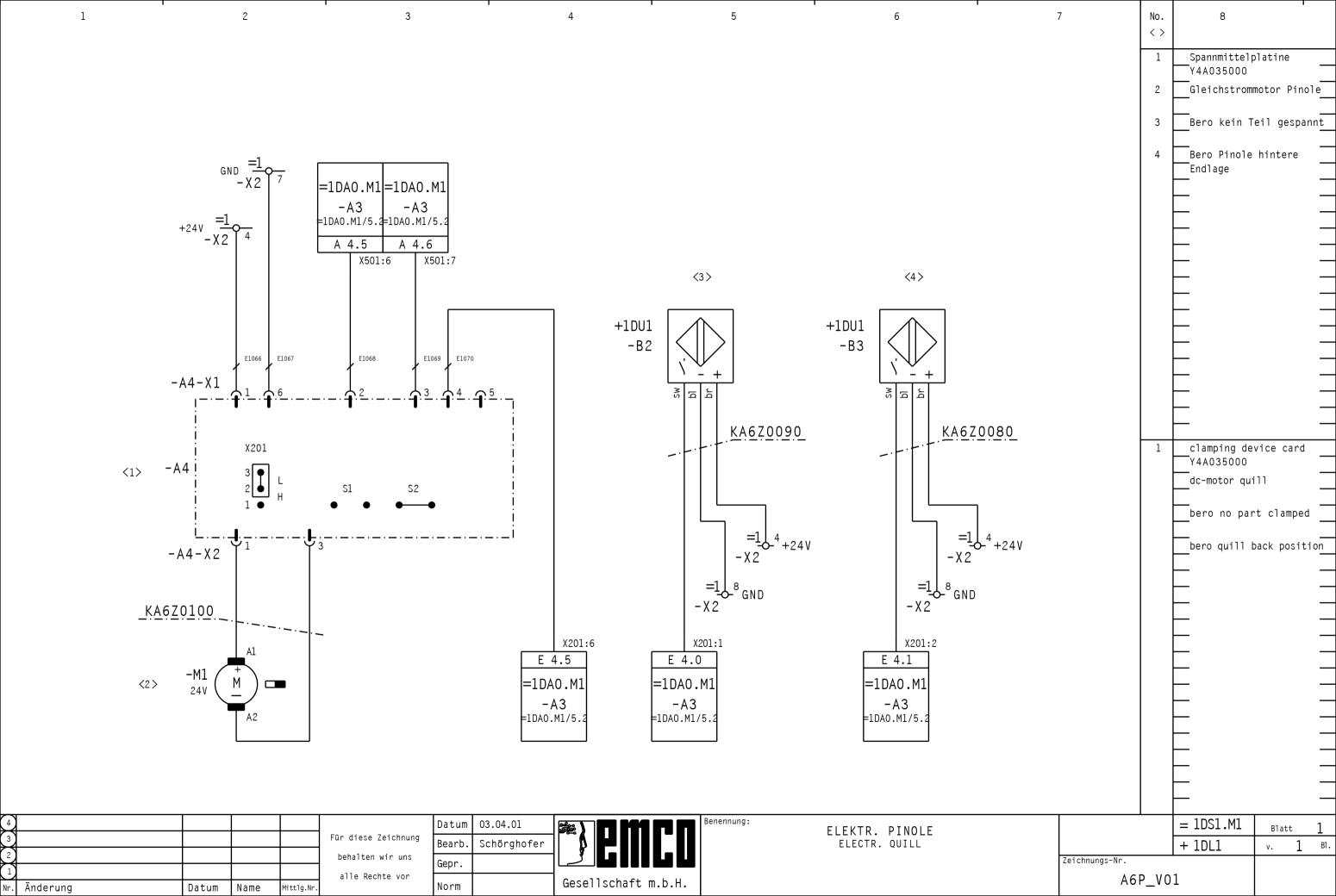


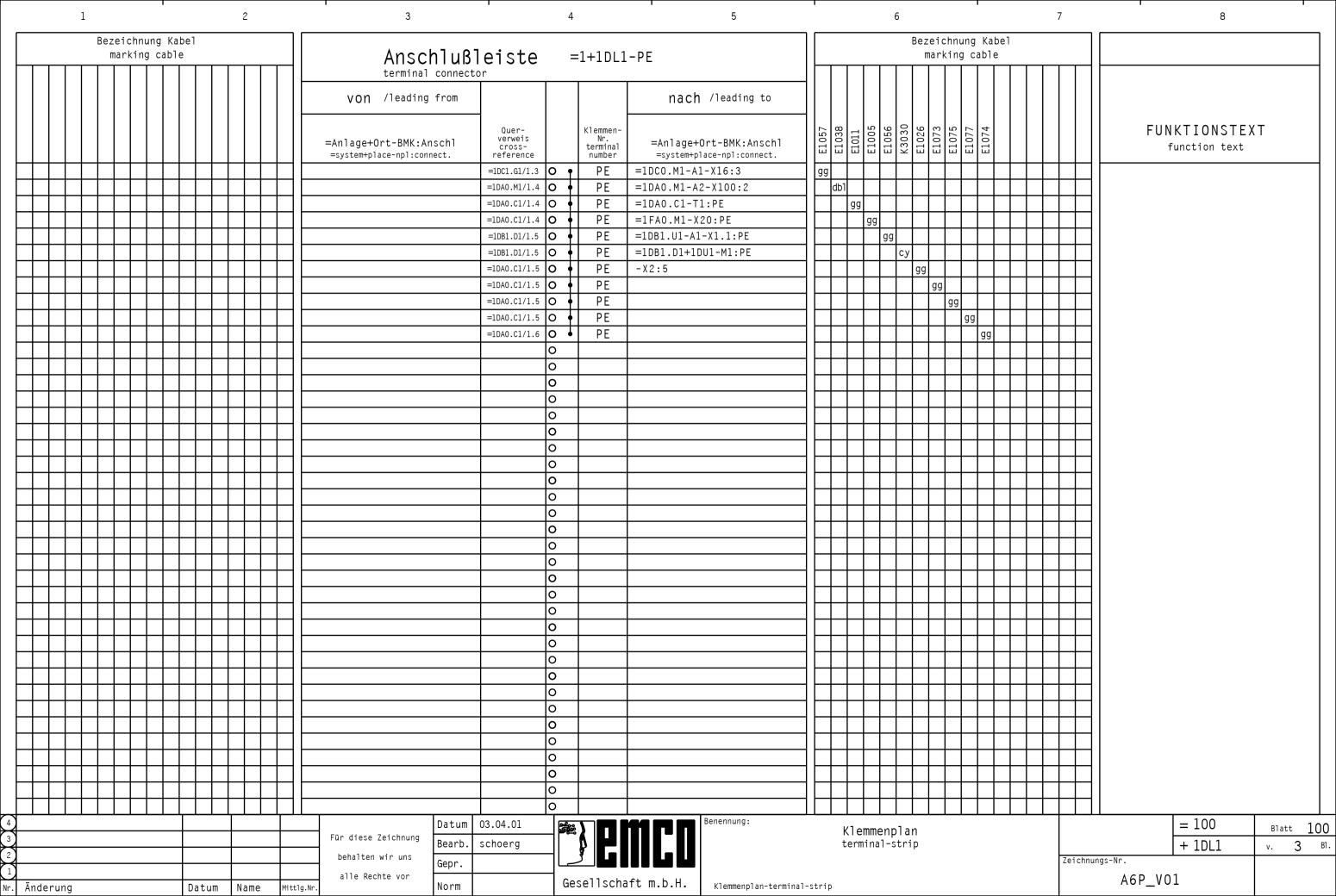




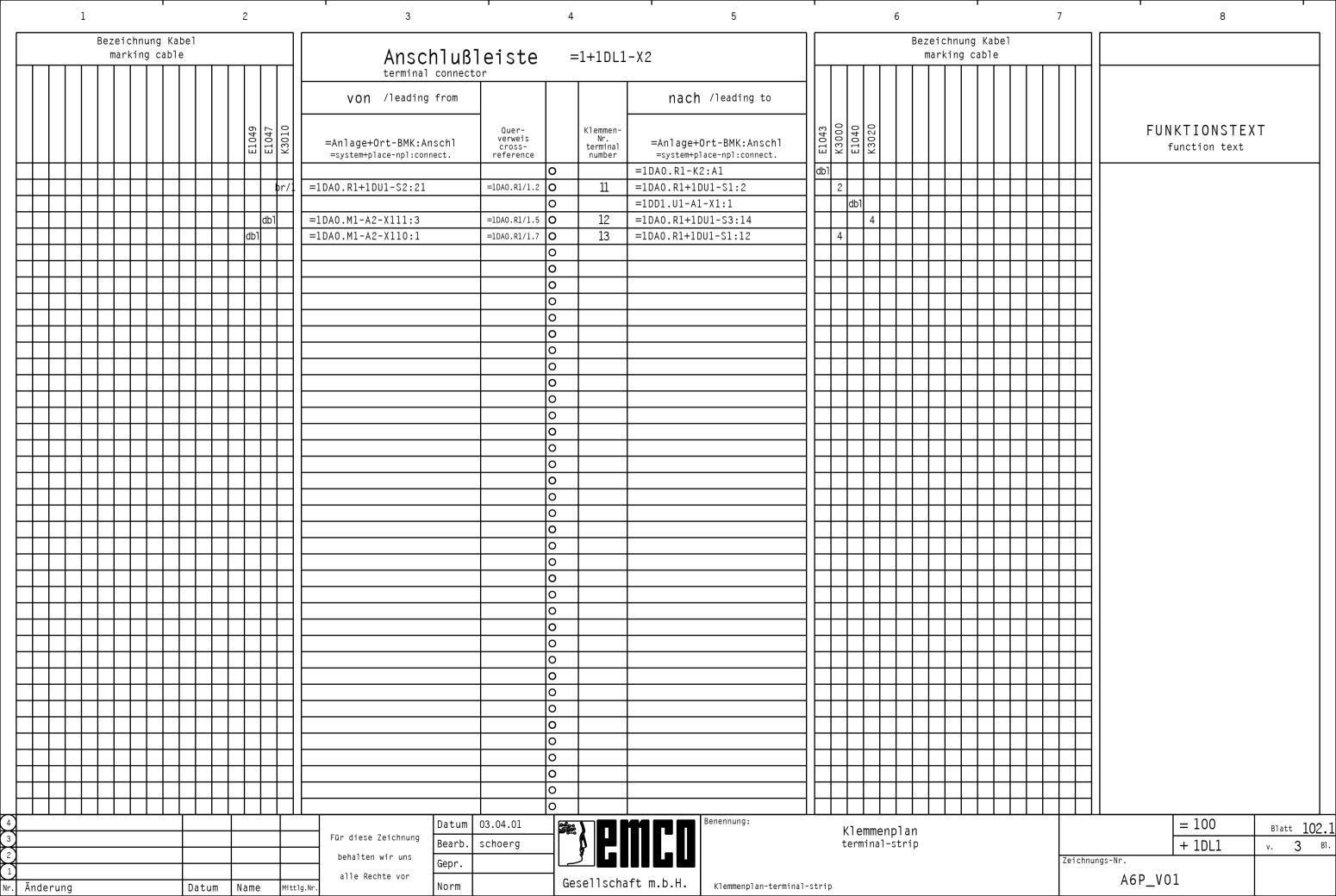








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											terminal connec	tor		_		_													
											von /leading from				nach /leading to														
									E1042	K3U2U E1026	=Anlage+Ort-BMK:Anschl	Quer- verweis cross-		Klemmen- Nr. terminal	=Anlage+Ort-BMK:Anschl	73000	E1029	E1019	K3020 E1036	E1033 E1035	E1066	E1030	E1034	E105/	E1067	E1041		FUNKTIONST function te	
	+	₩	_	\vdash	+	Н	+	++	+	+	=system+place-npl:connect.	reference =1DAO.R1/1.2	0 •	number 1	=system+place-npl:connect. =1DAO.R1+1DU1-S1:1	$\dashv \vdash$	++	+	+	$\vdash\vdash$	++	+	₩	+	\vdash	+			
		\vdash		\vdash	+	Н	+	++	+	+		_	0	1 1	=1DAO.M1-A4-X1:4	$\dashv\vdash$	Idb]		+		++		\vdash		\vdash	+			
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	-	\vdash		++	+	\vdash	+	++	-	+		=1DAO.C1/1.4	0	1 1	=1DAO.C1-T1:+30V	$\dashv \vdash$	+ + + + + + + + + + + + + + + + + + + +	bī	+	\vdash	++	+	\vdash	+	\vdash	+			
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		\vdash		\vdash		\vdash	+	++	\dashv	+		=1DAO.M1/1.6	0	2	=1DA0.M1-A3-X201:9	$\dashv\vdash$	++		db1		++	+	\vdash		\vdash	+			
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		\vdash		\vdash	+	\vdash		++	-	+		=1DAO.M1/1.5	0	3	=1DAO.M1-A3-X501:9	$\dashv\vdash$	++	+		db]	++		\vdash	+		+			
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l 	+	++		+	+	\vdash	+	++	\dashv	+			0	3	=1DP1.M1+1DU1-S1:N0	$\dashv\vdash$	++	++	+	H	++	+	\vdash	+		+			
l 	+	+			+	H	+	++	+	+		_	0 •	4	=1DS1.M1-A4-X1:1	$\dashv \vdash$	++	+	+		db1	+	\vdash	+					
					+	\vdash	+	+	\dashv	+		_	0	4	=1DS1.M1+1DU1-B2:br	$\dashv \vdash$	+				100		\vdash						
	+	+		\vdash	+	\vdash		++	+	+		_	0	4	=1DS1.M1+1DU1-B3:br	$\dashv \vdash$	++				++		\vdash	+					
	-	\vdash		++	+	Н	+	++	+	+		=1DR1.M1/1.4	0 •	5	=1DR1.M1+1DU1-Y1:2	$\dashv \vdash$	++	++	+	\vdash	++	+	\vdash	+	\vdash	+			
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A-5400 HALLEIN-TAXACH	<pre> Zeichn.Nr.: A6P_V01</pre>	*	1	*
*Tel.: 06245/891-0	*	*		*
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Anlage Ort BM			======================================	Hersteller/manufact
	ı. path	parts no	technische beschiefbung technical description Funktionstext/description	Bestellnr./ordernumbe
=1DA0.C1+1DL1-F1	1.3	17FF750028	GLASROHRSICHERUNG 10 AT 5x20 glas tube fuse 10 AT time-lag 5x20	WICKMANN
=1DAO.C1+1DL1-S2	1.2	ZEL440022 	SCHLOSSTASTE ZB2 BG2 2 Stellungen rastend, links abziehbar key-switched-button ZB2 BG2 two positions grided, strippable left	TELEMECANIQUE ZB2 BG2
=1DA0.C1+1DL1-S2	1.2		KONTAKTELEMENT ZB2 BZ103 2 Schließer 	TELEMECANIQUE ZB2 BZ103
=1DA0.C1+1DL1-S2	1.2		KONTAKTBLOCK	TELEMECANIQUE
=1DAO.C1+1DL1-T1	1.2	ZET000386		HABERMANN
=1DA0.M1+1DL1-A2	1.3		G.AXISCONTROLLER AC95 MONTAGEPLATTE g.axiscontroller AC95 mounting panel	EMCO
=1DA0.M1+1DL1-A2	1.3		G.STECKERPL. AC95 MONTAGEPLATTE FREMD FU g.plug-board AC95 mounting panel buy FC	EMCO
=1DA0.M1+1DL1-A3	1.5	Y4A029000	G.SPS-ERWEITERUNG g.sps-extension board	EMCO
=1DA0.M1+1DL1-A4			G.FILTERPLATINE g.filter-board	EMCO
=1DA0.M1+1DL1-A8	1.2		GERÄTESTECKER 1-POLIG 10A/250V TYP:KEC MIT STECKKONTAKTEN 4,8x0,8 single-pole plug 10A/250V type:KEC with male contacts 4,8x0,8	SCHURTER 4303.0091
=1DA0.M1+1DP1-A30	00 2.2		G.PC-EINSCHUB RS422/RS485/CAN-SPS 	EMC0 Y4A083000
	<u> </u>	. <u> </u>	g.PC insert-card RS422/RS485/CAN-SPS	
=1DAO.R1+1DL1-K1	1.2		WECHSELSTROMSCHÜTZ alternating current contactor	SIEMENS 3TJ5001-0BB4
=1DAO.R1+1DL1-K1	1.2	· -	ENTSTÖRDIODE 3TX4490-4A FÜR HILFSSCHÜTZ 3TH2 supression diode for relay type 3TH2	SIEMENS 3TX4490-4A

Fortsetzung auf Seite 2

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======= Anlage (SachNr.	Technische Beschreibung	Hersteller/manufact
inståll 1 ======		·	i '	j ' i	technical description Funktionstext/description	Bestellnr./ordernumbe
					WECHSELSTROMSCHÜTZ	SIEMENS 3TJ5001-0BB4
	<u> </u>	alternating current contactor				
=1DAO.R1+1	1DL1-	К2	1.3		ENTSTÖRDIODE 3TX4490-4A FÜR HILFSSCHÜTZ 3TH2 supression diode for relay type 3TH2	SIEMENS 3TX4490-4A
=1DAO.R1+1	1DU1-	\$1	1.2	ZEL401010		RAFI 1.30043.551/030
			 	 	mushroom button 	
=1DAO.R1+1	1DU1-	·S1	1.2	į i	KONTAKTELEMENT Aufschnappkontakt 1ÖFFNER	RAFI 5.00100.054
			 		contact-element snapp-on-contact one NC-contact	
=1DAO.R1+1DU1-S1 1.2	ZEE710701	KUPPLUNG 45294/0	ABB GHV 8706602P2			
		İ i	coupling 452940	4111 07000011		
=1DAO.R1+1	1 D U 1 -	S2	1.2	ZEL212040 	TÜRENDSCHALTER MIT ROLLENSCHWENKHEBEL Kontakte zwangsgeführt lt. VDE 660 Teil 206 door limit switch with roller-joystick contacts positive-operated for VDE 660 part 206	
=1DAO.R1+1	1 D U 1 -	\$3	1.2	ZEL212040 	TÜRENDSCHALTER MIT ROLLENSCHWENKHEBEL Kontakte zwangsgeführt lt. VDE 660 Teil 206 door limit switch with roller-joystick contacts positive-operated for VDE 660 part 206	SIEMENS 3SE 3200-1E
=1DB1.D1+1	1 D U 1 -	M1	1.4 	ZM0473381 	DREHSTROMMOTOR 0.55KW 1400U/MIN 220/380V BAUGRÖSSE 71,BAUFORM B14 KL.FLANSCH three-phase-motor 0,55KW 1400upm 220/380V size 71, design B14 small flange	ELIN
=1DB1.M1+1	1 D U 1 -	В1	1.6 		G.DREHGEBERPLATINE HAUPTANTRIEB g.encoder board main drive	EMCO
=1DB1.U1+1	 1DL1-	A1	1.2		FREQUENZUMRICHTER 230V 0,75KW TYP:E82EV751 VECTOR Frequency converter 230V 0,75kW typ:E82EV751 VECTOR	LENZE
=1DC0.M1+1	1DL1-	A1	1.2	Y4A031000	3-PHASEN SCHRITTMOTORPLATINE FÜR 2 ACHSEN 3-phase steppermotorboard for 2 axis	EMCO
=1DC1.G1+1	 1DU1-	M1	1 . 4 	ZM0780031 	SCHRITTMOTOR VRDM366/50LHA 3-PHASIG 40V 5,8A 0,9NM Steppermotor VRDM366/50LHA 3-phase 40V 5,8A 0,9NM	BERGERLAHR

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Anlage Ort BMK install loc equ.	Pfad path	SachNr.	Technische Beschreibung technical description funktionstext/description	Hersteller/manufact Bestellnr./ordernumbe
======================================		ZEL212023	INDUKTIVER NÄHERUNGSSCHALTER PNP-Schließer M8x1 7m Kabel inductance proximity switch PNP-closer M8x1 7m cable	BALLUF BES 516-324-EOL
=1DC1.M1+1DU1-S1	1.5	ZEL239002	BASISSCHALTER V-10FL2-1C2 V3L-E9001M-D18 microswitch V-10FL2-1C2 V3L-E9001M-D18	OMRON
=1DC2.G1+1DU1-M1	1.4	ZM0780031	SCHRITTMOTOR VRDM366/50LHA 3-PHASIG 40V 5.8A 0.9NM Steppermotor VRDM366/50LHA 3-phase 40V 5.8A 0.9NM	BERGERLAHR
=1DC2.M1+1DU1-B1	1.7	ZEL212023	INDUKTIVER NÄHERUNGSSCHALTER PNP-Schließer M8x1 7m Kabel inductance proximity switch PNP-closer M8x1 7m cable	BALLUF BES 516-324-EOL
=1DC2.M1+1DU1-S1	1.6		BASISSCHALTER V-10FL2-1C2 V3L-E9001M-D18 microswitch V-10FL2-1C2 V3L-E9001M-D18	OMRON
=1DD1.H1+1DU1-B1	1.4		G.DREHGEBERPLATINE WZW g.encoder board	EMCO
=1DD1.H1+1DU1-M1	1.3		DC-MOTOR 12V MIT GETRIEBE 60 : 1 DC-motor 12V with transmission 60 : 1	MAXON
=1DD1.U1+1DL1-A1	1.2		G.WERKZEUGWENDERPLATINE g.tool turret board	EMCO
=1DS1.M1+1DL1-A4	1.2		G.SPANNMITTELPLATINE g.clamping device board	EMCO
=1DS1.M1+1DL1-M1	1.2		GLEICHSTROMMOTOR MIT GETRIEBE 12V direct-current motor with transmission 12v	MAXON
=1DS1.M1+1DU1-B2	1.5	ZEL212023	INDUKTIVER NÄHERUNGSSCHALTER PNP-Schließer M8x1 7m Kabel inductance proximity switch PNP-closer M8x1 7m cable	BALLUF BES 516-324-EOL
=1DS1.M1+1DU1-B3	1.6	ZEL212023	INDUKTIVER NÄHERUNGSSCHALTER PNP-Schließer M8x1 7m Kabel inductance proximity switch PNP-closer M8x1 7m cable	BALLUF BES 516-324-EOL