

I. Personal and study details

Student's name: **Kamler Michal**

Personal ID number: **516070**

Faculty / Institute: **Faculty of Electrical Engineering**

Department / Institute: **Department of Cybernetics**

Study program: **Cybernetics and Robotics**

II. Bachelor's thesis details

Bachelor's thesis title in English:

Development of a Safe Flocking Algorithm for UAVs Using 3D Lidar and Collaborative Multi-Robot Coordination

Bachelor's thesis title in Czech:

Vývoj bezpečného algoritmu pro koordinaci UAV pomocí 3D lidar a koordinace více robotů

Guidelines:

- (1) Develop a safe flocking algorithm for UAVs in C++ within the MRS system framework. The algorithm must ensure collision-free and efficient movement of UAV.
- (2) Compare your solution to some of the most promising algorithms in the literature within the MRS simulator, in particular [1],[2],[3].
- (3) The novel contributions of the thesis will include
 - i) Extend existing multi-robot algorithm from 2d to 3d.
 - ii) Use 3d lidar to localize, sense, process, and react to environments such as a forest.
 - iii) Research on possible enhancements of the algorithm for example using neural networks or learning-based techniques.
- (4) Conduct an experimental campaign to validate the theoretical findings. Include different real-world scenarios, such as navigating through forests or crowded spaces.

Bibliography / sources:

- [1] Boldrer, M., Serra-Gomez, A., Lyons, L., Alonso-Mora, J., & Ferranti, L. (2024). Rule-Based Lloyd Algorithm for Multi-Robot Motion Planning and Control with Safety and Convergence Guarantees. arXiv preprint arXiv:2310.19511v2 (2023).
- [2] Mezey, D., Bastien, R., Zheng, Y., McKee, N., Stoll, D., Hamann, H., & Romanczuk, P. (2024). Purely vision-based collective movement of robots. arXiv preprint arXiv:2406.17106.
- [3] Ahmad, A., Licea, D. B., Silano, G., Báča, T., & Saska, M. (2022). PACNav: a collective navigation approach for UAV swarms deprived of communication and external localization. Bioinspiration & Biomimetics, 17(6), 066019

Name and workplace of bachelor's thesis supervisor:

Manuel Boldrer, Ph.D. Multi-robot Systems FEE

Name and workplace of second bachelor's thesis supervisor or consultant:

Date of bachelor's thesis assignment: **30.01.2025** Deadline for bachelor thesis submission: _____

Assignment valid until: **20.09.2026**

prof. Dr. Ing. Jan Kybic
Head of department's signature

prof. Mgr. Petr Páta, Ph.D.
Vice-dean's signature on behalf of the Dean

III. Assignment receipt

The student acknowledges that the bachelor's thesis is an individual work. The student must produce his thesis without the assistance of others, with the exception of provided consultations. Within the bachelor's thesis, the author must state the names of consultants and include a list of references.

Date of assignment receipt

Student's signature