

# Schwarz methods, Schur complements, preconditioning and numerical linear algebra

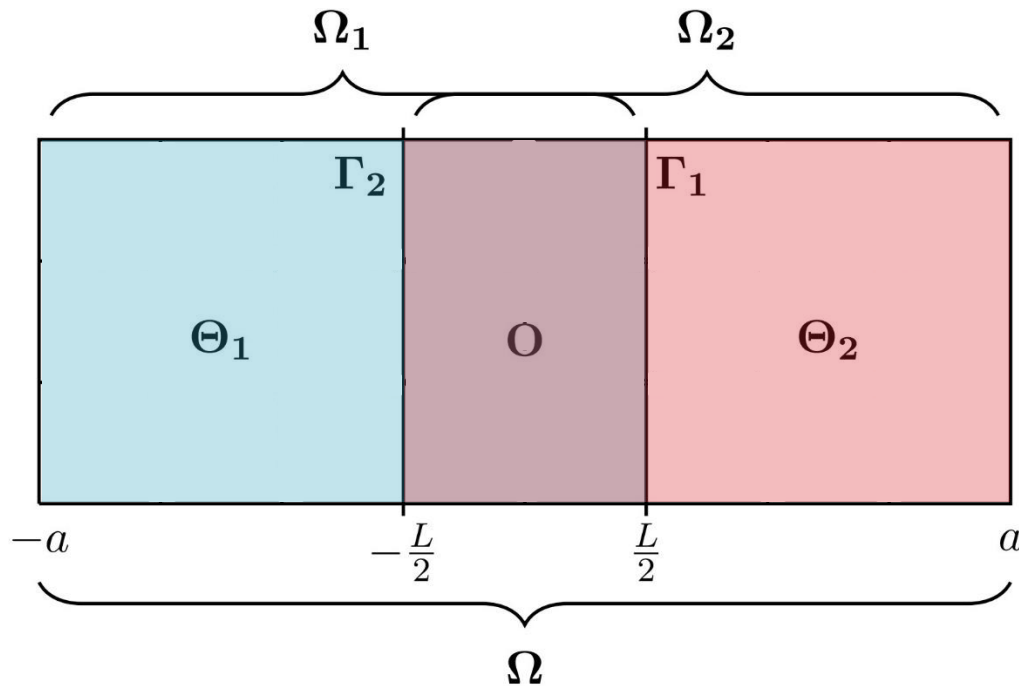
*Michal Outrata*  
supervised by Martin J. Gander

# Outline



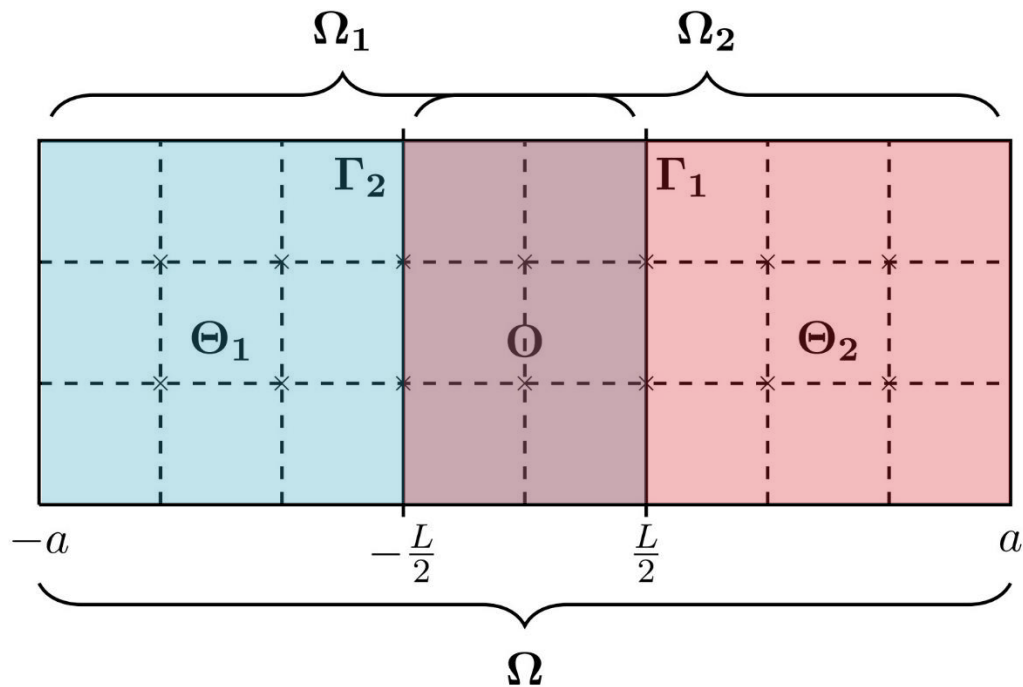
- Model problem and set-up
- Schwarz methods and DS
- Schwarz methods and ABC
- IRK preconditioners

# Model problem



$$\begin{aligned}\Delta u &= f && \text{in } \Omega, \\ u &= g && \text{on } \partial\Omega\end{aligned}$$

# Model problem



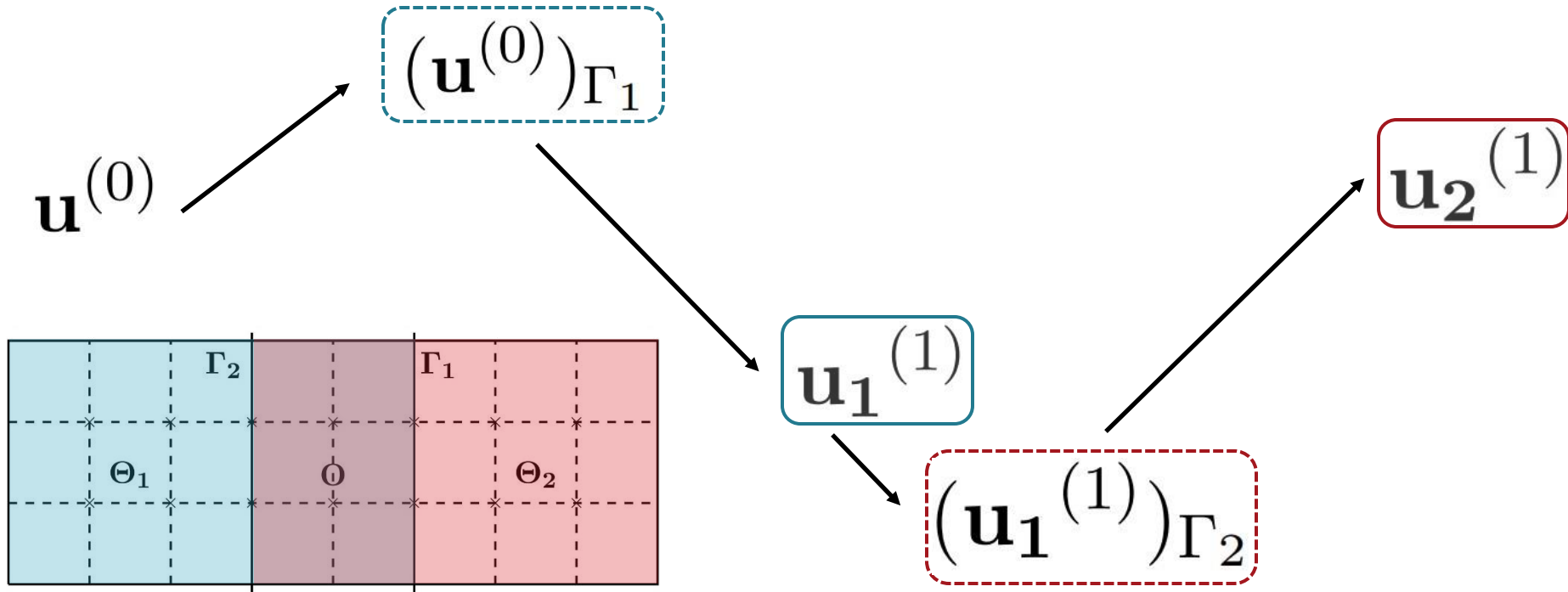
$$L\mathbf{u} = \mathbf{f}$$

blackboard (diag D)

# Schwarz methods



# Schwarz methods



# Schwarz methods

$$\frac{1}{h^2} \begin{bmatrix} D & I & & \\ I & \ddots & \ddots & \\ & \ddots & \ddots & I \\ & & I & D \end{bmatrix} \mathbf{u}_1^{(n)} = \mathbf{b}_1^{(n)}$$

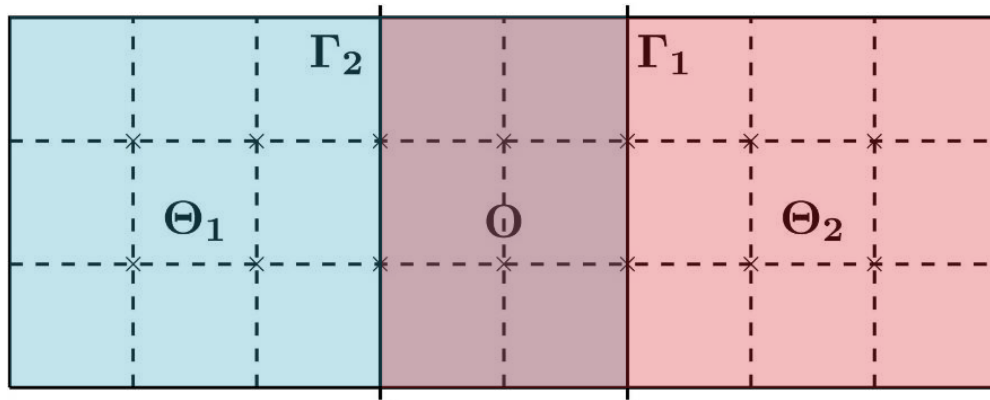
$$\frac{1}{h^2} \begin{bmatrix} D & I & & \\ I & \ddots & \ddots & \\ & \ddots & \ddots & I \\ & & I & D \end{bmatrix} \mathbf{u}_2^{(n)} = \mathbf{b}_2^{(n)}$$

# Optimal Schwarz methods





# Optimal Schwarz methods



# Optimal Schwarz methods

$$\frac{1}{h^2} \begin{bmatrix} D & I & & \\ I & \ddots & \ddots & \\ & \ddots & D & I \\ & & I & D - S_1^* \end{bmatrix} \mathbf{u}_1^{(n)} = \mathbf{b}_1^{(n)}$$

$$\frac{1}{h^2} \begin{bmatrix} D - S_2^* & I & & \\ & I & \ddots & \ddots \\ & & \ddots & D & I \\ & & & I & D \end{bmatrix} \mathbf{u}_2^{(n)} = \mathbf{b}_2^{(n)}$$

# Optimal Schwarz methods

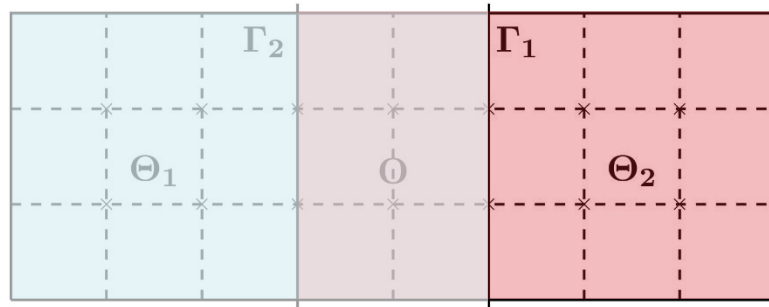
$$\frac{1}{h^2} \begin{bmatrix} D & I & & \\ I & \ddots & \ddots & \\ & \ddots & D & I \\ & & I & D - S_1^* \end{bmatrix} \mathbf{u}_1^{(n)} = \mathbf{b}_1^{(n)}$$

$$\frac{1}{h^2} \begin{bmatrix} D - S_2^* & I & & \\ & I & \ddots & \ddots \\ & & \ddots & D & I \\ & & & I & D \end{bmatrix} \mathbf{u}_2^{(n)} = \mathbf{b}_2^{(n)}$$

$$S_1^* := E_{\Gamma_1}^T L_{\Theta_2}^{-1} E_{\Gamma_1}$$

# Optimal Schwarz methods

$$S^* := E_{\Gamma_1}^T L_{\Theta_2}^{-1} E_{\Gamma_1}$$



# Optimized Schwarz methods



# Optimized Schwarz methods

$$\frac{1}{h^2} \begin{bmatrix} D & I & & \\ I & \ddots & \ddots & \\ & \ddots & D & I \\ & & I & D - S_1 \end{bmatrix} \mathbf{u}_1^{(n)} = \mathbf{b}_1^{(n)}$$

$$\frac{1}{h^2} \begin{bmatrix} D - S_2 & I & & \\ & I & \ddots & \ddots \\ & & \ddots & D & I \\ & & & I & D \end{bmatrix} \mathbf{u}_2^{(n)} = \mathbf{b}_2^{(n)}$$

$$S^* \rightarrow S$$

# Optimized Schwarz methods

$$\frac{1}{h^2} \begin{bmatrix} D & I & & \\ I & \ddots & \ddots & \\ & \ddots & D & I \\ & & I & D - S_1 \end{bmatrix} \mathbf{u}_1^{(n)} = \mathbf{b}_1^{(n)}$$

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$$S^* \rightarrow S \quad \|S - S^*\|$$

# Optimized Schwarz methods

$$\frac{1}{h^2} \begin{bmatrix} D & I & & \\ I & \ddots & \ddots & \\ & \ddots & D & I \\ & & I & D - S_1 \end{bmatrix} \mathbf{u}_1^{(n)} = \mathbf{b}_1^{(n)}$$

$$\frac{1}{h^2} \begin{bmatrix} D - S_2 & I & & \\ & I & \ddots & \ddots \\ & & \ddots & D & I \\ & & & I & D \end{bmatrix} \mathbf{u}_2^{(n)} = \mathbf{b}_2^{(n)}$$

$$S^* \rightarrow S \quad \|S - S^*\| \quad \rho^{\text{discr}}(S)$$



# Schwarz methods & DS



# Schwarz methods & DS



DS = data-sparse formats

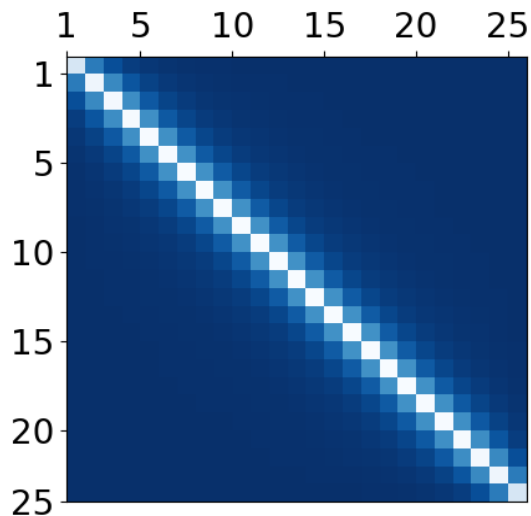
low-rank & HODLR

# Schwarz methods & DS

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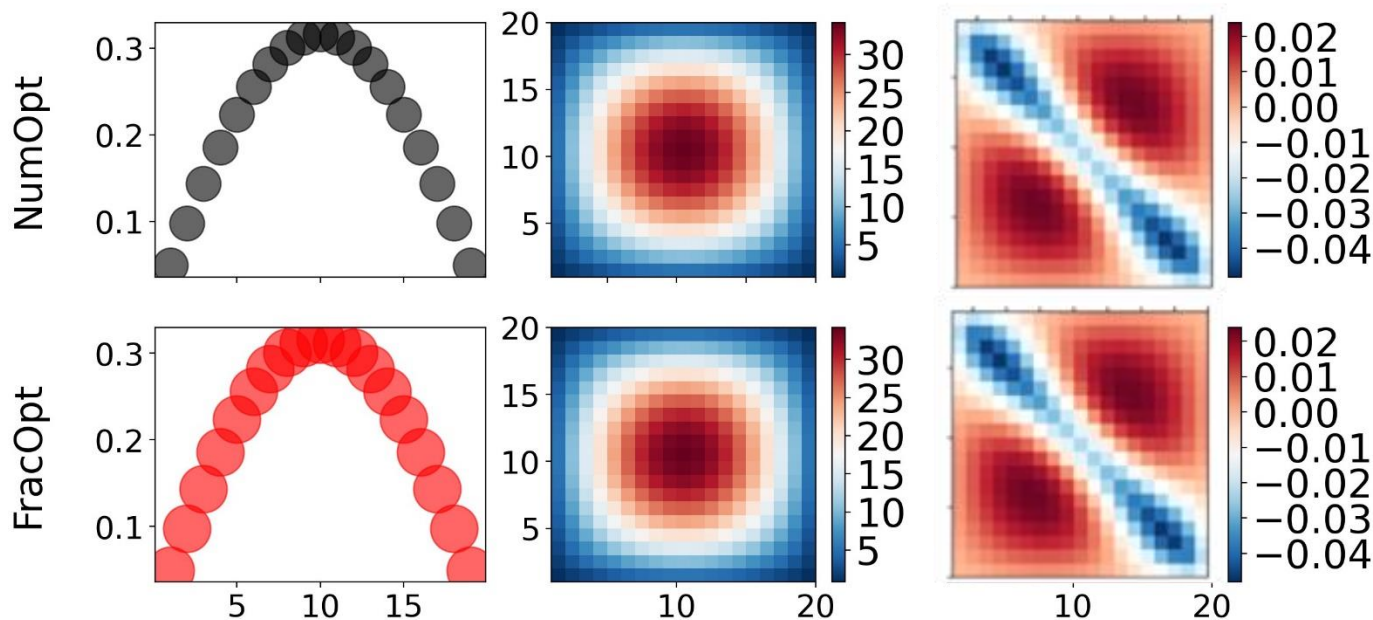
# Schwarz methods & DS



data-sparse formats: low-rank

# Schwarz methods & DS

data-sparse formats: low-rank



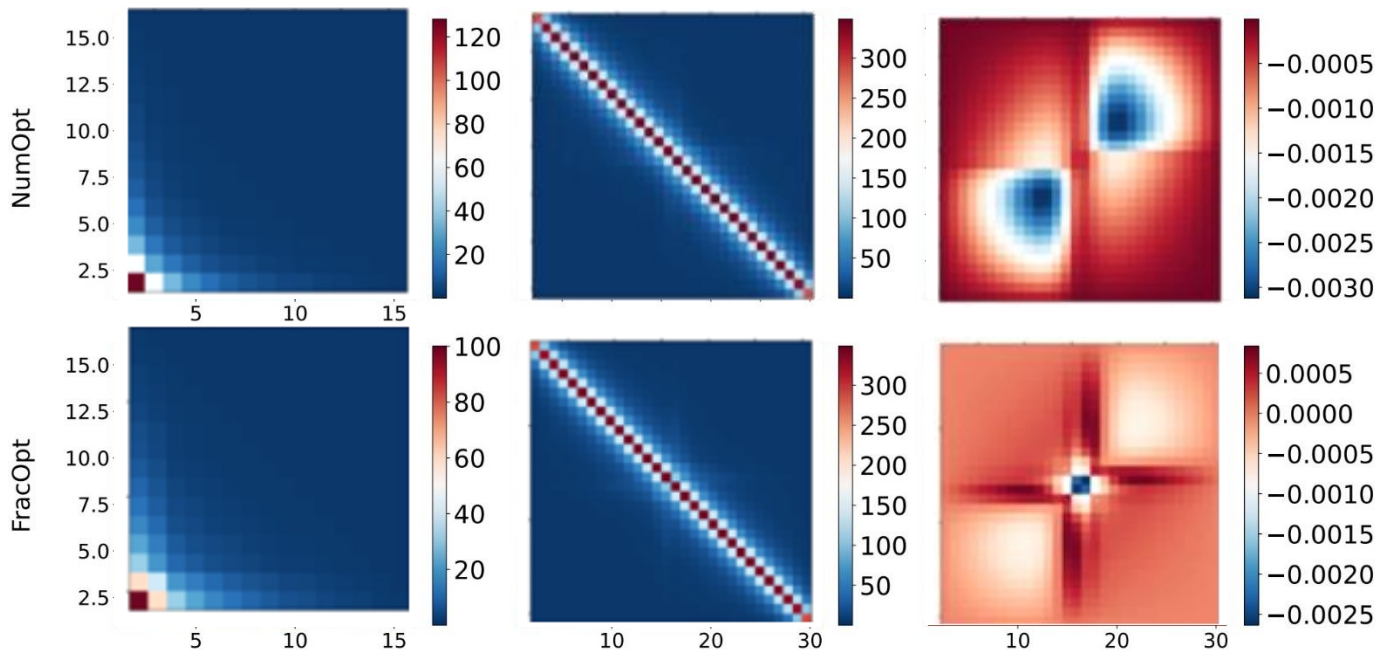
# Schwarz methods & DS



data-sparse formats: HODLR

# Schwarz methods & DS

## data-sparse formats: HODLR

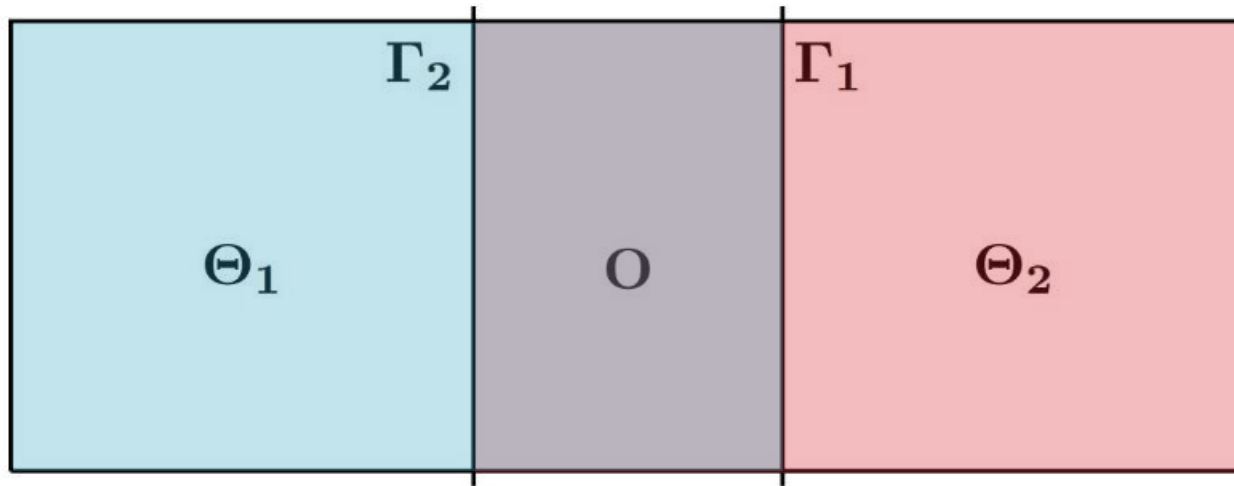




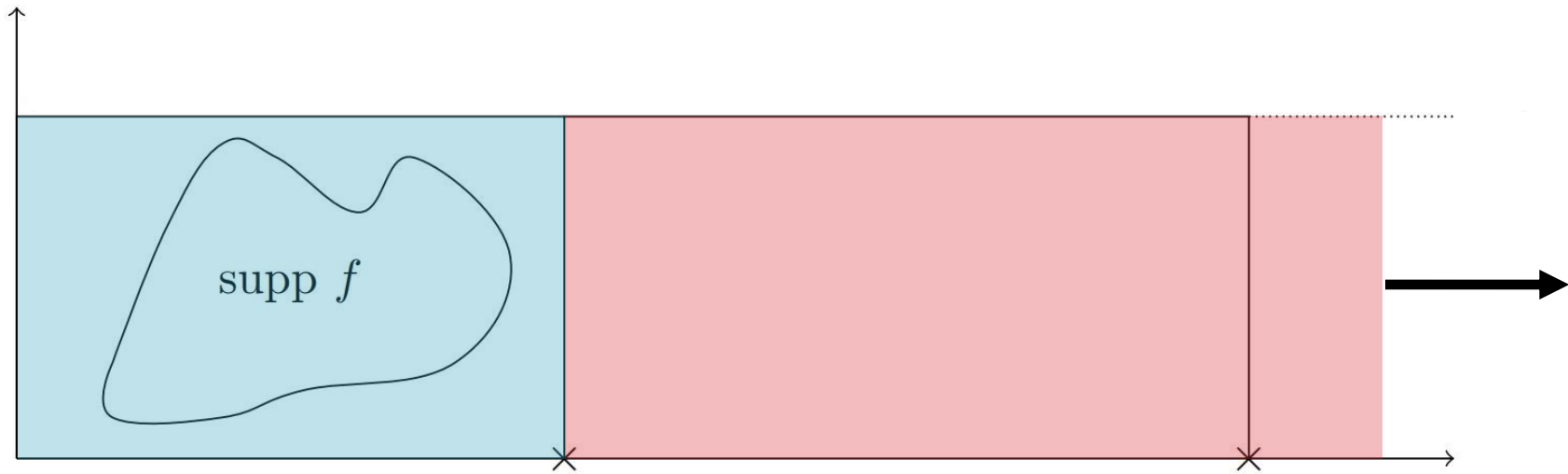
# Schwarz methods & ABC



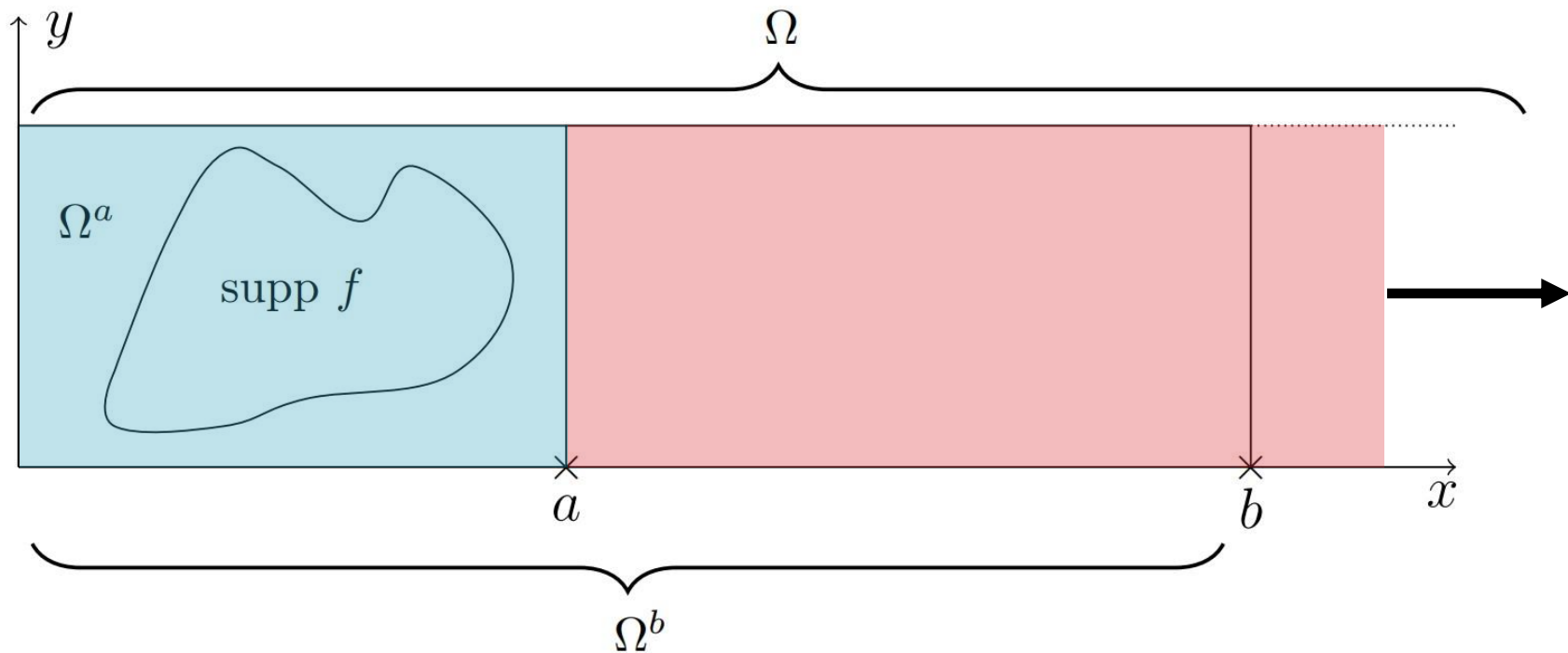
# Schwarz methods & ABC



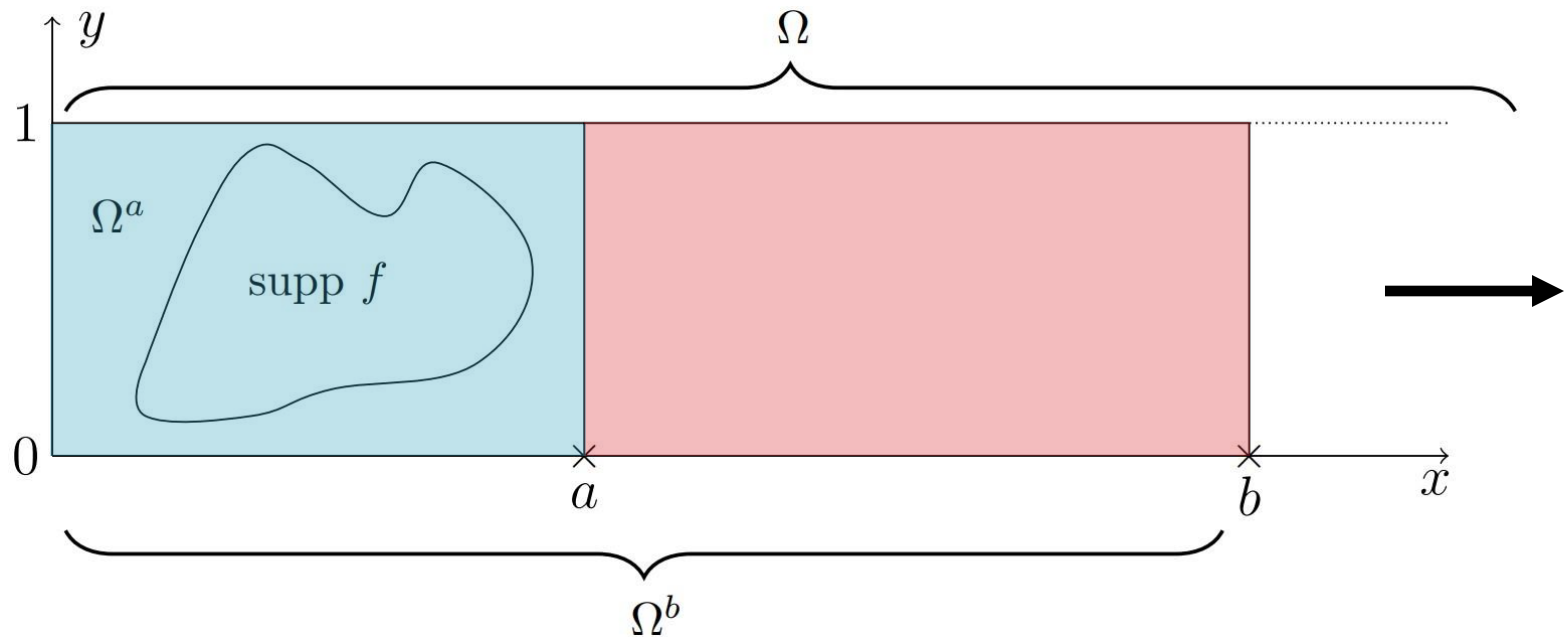
# Schwarz methods & ABC



# Schwarz methods & ABC



# Schwarz methods & ABC



$-\Delta u$  & blackboard

# Schwarz methods & ABC

$$L^a \mathbf{u}^a = \mathbf{f}^a \quad L^b \mathbf{u}^b = \mathbf{f}^b \quad L\mathbf{u} = \mathbf{f}$$

# Schwarz methods & ABC

$$L^a \mathbf{u}^a = \mathbf{f}^a \quad L^b \mathbf{u}^b = \mathbf{f}^b \quad L\mathbf{u} = \mathbf{f}$$

$$\begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & -I \\ & & -I & D_{N^a} \end{pmatrix} \begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^b-1} & -I \\ & & -I & D_{N^b} \end{pmatrix}$$

where  $D_i = D$  (blackboard)

# Schwarz methods & CF

$$L^a \mathbf{u}^a = \mathbf{f}^a \quad L^b \mathbf{u}^b = \mathbf{f}^b \quad L\mathbf{u} = \mathbf{f}$$

$$\begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & -I \\ & & -I & D_{N^a} \end{pmatrix} \begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^b-1} & -I \\ & & -I & D_{N^b} \end{pmatrix} \begin{pmatrix} h^2 L^b & & & \\ & -I & & \\ & -I & D_{N^b+1} & \ddots \\ & & \ddots & \ddots \end{pmatrix}$$

where  $D_i = D$  (blackboard)



# Schwarz methods & ABC

$$L^a \mathbf{u}^a = \mathbf{f}^a$$

$$L^b \mathbf{u}^b = \mathbf{f}^b$$

$$L\mathbf{u} = \mathbf{f}$$

$$\begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & -I \\ & & -I & D_{N^a} \end{pmatrix} \begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & I \\ & & -I & \boxed{T_{N^a}^b} \end{pmatrix} \begin{pmatrix} h^2 A^b & & & \\ & -I & & \\ & -I & D_{N^b+1} & \ddots \\ & & \ddots & \ddots \end{pmatrix}$$

$T_{N^a}^b$  (blackboard)

# Schwarz methods & ABC

$$L^a \mathbf{u}^a = \mathbf{f}^a$$

$$L^b \mathbf{u}^b = \mathbf{f}^b$$

$$L \mathbf{u} = \mathbf{f}$$

$$\begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & -I \\ & & -I & D_{N^a} \end{pmatrix} \begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & I \\ & & -I & T_{N^a}^b \end{pmatrix} \begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & I \\ & & -I & T_{N^a}^\infty \end{pmatrix}$$

$$T_{N^a}^b, T_{N^a}^\infty \text{ (blackboard)}$$

# Schwarz methods & ABC

$$L^a \mathbf{u}^a = \mathbf{f}^a \quad L^b \mathbf{u}^b = \mathbf{f}^b \quad L \mathbf{u} = \mathbf{f}$$

$$\begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & -I \\ & & -I & D_{N^a} \end{pmatrix} \begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & I \\ & & -I & T_{N^a}^b \end{pmatrix} \begin{pmatrix} D_1 & -I & & \\ -I & \ddots & \ddots & \\ & \ddots & D_{N^a-1} & -I \\ & & -I & T_{N^a}^\infty \end{pmatrix}$$

What is the effect of increasing  $b$ ?

# Schwarz methods & ABC

$$T_{N^a}^b :$$

# Schwarz methods & ABC

$$\hat{T}_i^b = Q \frac{D}{h^2} Q^T - Q \frac{(T_{i+1}^b)^{-1}}{h^4} Q^T = \frac{\Lambda}{h^2} - \frac{(\hat{T}_{i+1}^b)^{-1}}{h^4}$$

$$T_{Na}^b :$$

# Schwarz methods & ABC

$$\hat{T}_i^b = Q \frac{D}{h^2} Q^T - Q \frac{(T_{i+1}^b)^{-1}}{h^4} Q^T = \frac{\Lambda}{h^2} - \frac{(\hat{T}_{i+1}^b)^{-1}}{h^4}$$

$$T_{Na}^b :$$

$$\hat{t}_i^b(\lambda) = \frac{1}{h^2} \left( \lambda - \frac{1}{h^2 \hat{t}_{i+1}^b(\lambda)} \right)$$

# Schwarz methods & ABC

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$$\hat{t}_i^b(\lambda) = \frac{1}{h^2} \left( \lambda - \frac{1}{h^2 \hat{t}_{i+1}^b(\lambda)} \right)$$

$$\hat{t}_i^b(\lambda) = \frac{1}{h^2} \left( \lambda - \frac{1}{\lambda - \frac{1}{h^2 \hat{t}_{i+2}^b}} \right)$$

# Schwarz methods & ABC

$T_{N^a}^b :$

$$\hat{t}_{N^a}^b(\lambda) = \frac{1}{h^2} \begin{pmatrix} \lambda - \frac{1}{\lambda - \frac{1}{\lambda - \frac{1}{\ddots}}} \end{pmatrix}$$

$N^b - N^a$  levels; blackboard



# Schwarz methods & ABC

$$T_{N^a}^\infty :$$

# Schwarz methods & ABC

$$\hat{T}_{N^a}^\infty(\lambda) = \lim_{b \rightarrow +\infty} \hat{T}_{N^a}^b(\lambda)$$

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# Schwarz methods & ABC

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# Schwarz methods & ABC

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$T_{N^a}^\infty :$

$$\hat{t}_i^b(\lambda) = \frac{1}{h^2} \left( \lambda - \frac{1}{h^2 \hat{t}_{i+1}^b(\lambda)} \right)$$

# Schwarz methods & ABC

$$\hat{T}_{Na}^{\infty}(\lambda) = \lim_{b \rightarrow +\infty} \hat{T}_{Na}^b(\lambda) \quad \hat{t}_{Na}^{\infty}(\lambda) = \lim_{b \rightarrow +\infty} \hat{t}_{Na}^b(\lambda)$$

$T_{Na}^{\infty} :$

$$\hat{t}_i^b(\lambda) = \frac{1}{h^2} \left( \lambda - \frac{1}{h^2 \hat{t}_{i+1}^b(\lambda)} \right)$$

$$\hat{t}_{Na}^{\infty}(\lambda) = \frac{1}{h^2} \left( \lambda - \frac{1}{h^2 \hat{t}_{Na}^{\infty}(\lambda)} \right)$$

# Schwarz methods & ABC

$$\hat{T}_{Na}^{\infty}(\lambda) = \lim_{b \rightarrow +\infty} \hat{T}_{Na}^b(\lambda) \quad \hat{t}_{Na}^{\infty}(\lambda) = \lim_{b \rightarrow +\infty} \hat{t}_{Na}^b(\lambda)$$

$T_{Na}^{\infty} :$

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# Schwarz methods & ABC

$T_{Na}^\infty :$

$$\hat{t}_{Na}^\infty(\lambda) = \frac{1}{h^2} \begin{pmatrix} \lambda - \frac{1}{\lambda - \frac{1}{\lambda - \frac{1}{\ddots \ddots \ddots}}} \end{pmatrix}$$

blackboard

# Schwarz methods & ABC

$$\hat{t}_{Na}^{\infty}(\lambda) = \frac{1}{h^2} \left( \lambda - \frac{1}{h^2 \hat{t}_{Na}^{\infty}(\lambda)} \right)$$

$$T_{Na}^{\infty} :$$



# Schwarz methods & ABC

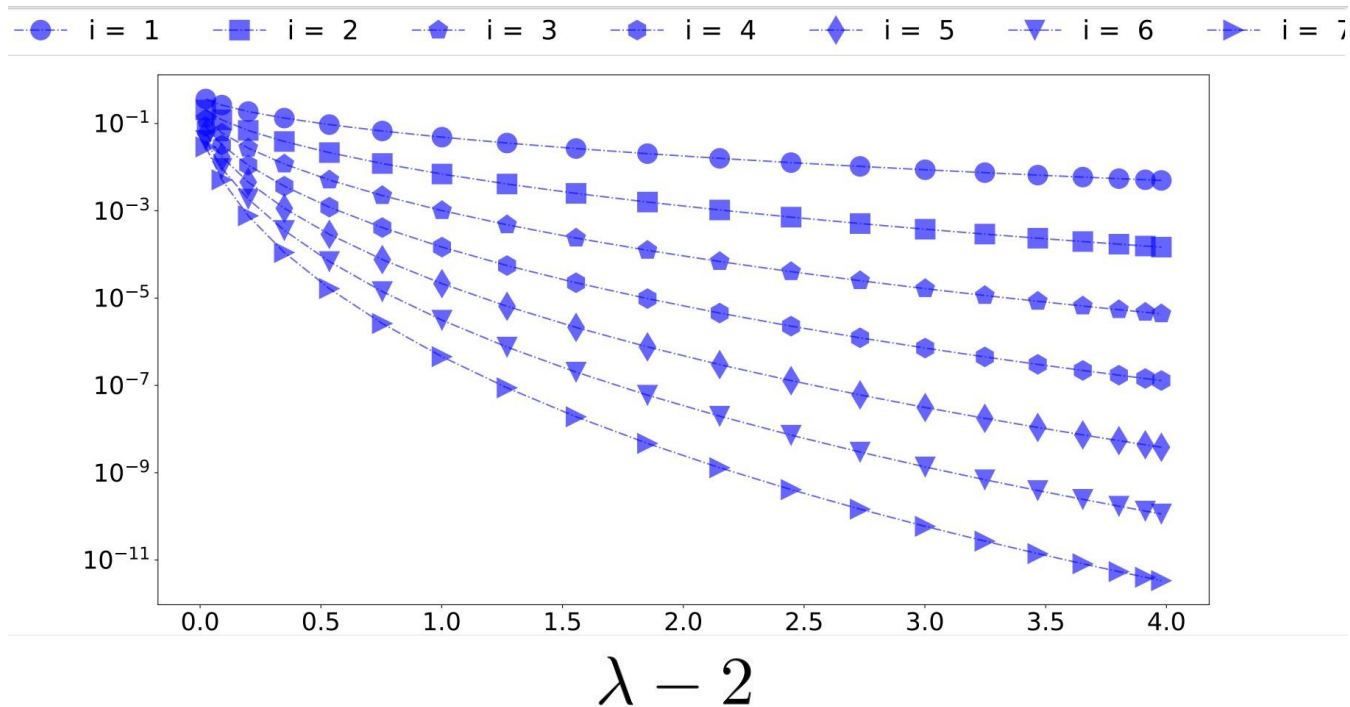
$$\hat{t}_{Na}^{\infty}(\lambda) = \frac{1}{h^2} \left( \lambda - \frac{1}{h^2 \hat{t}_{Na}^{\infty}(\lambda)} \right)$$

$T_{Na}^{\infty} :$

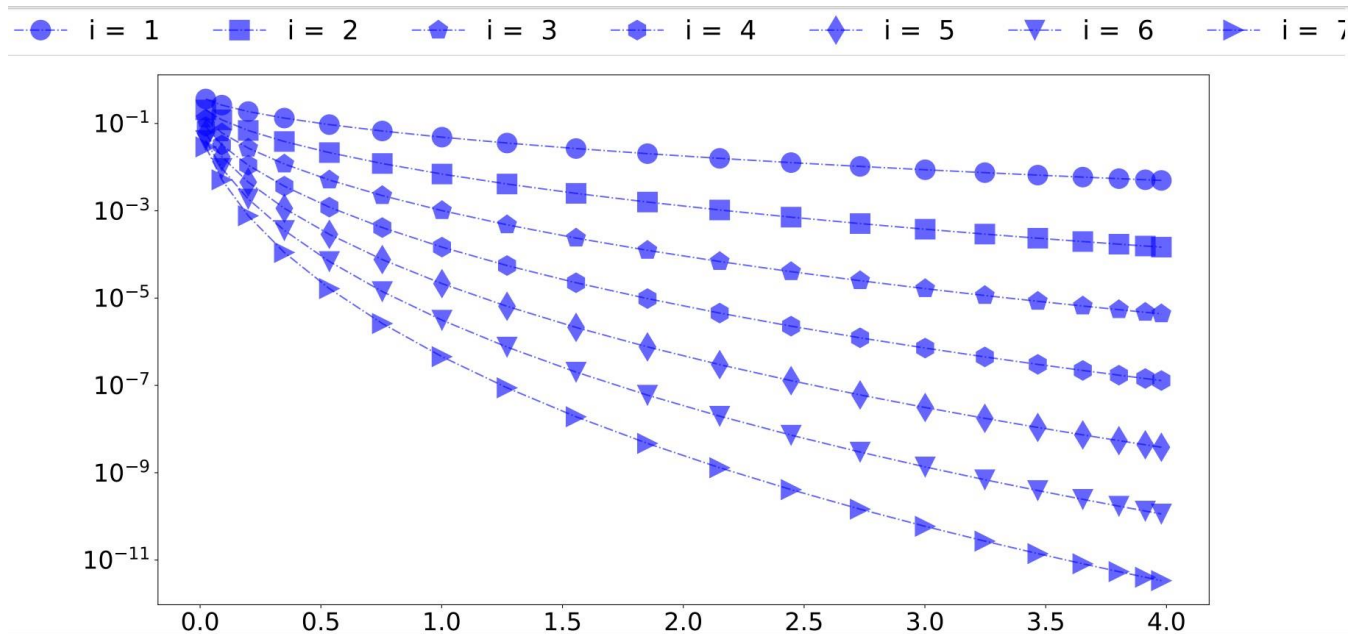
$$\hat{t}_{Na}^{\infty}(\lambda) = \frac{\lambda + \sqrt{\lambda^2 - 4}}{2h^2}$$

blackboard

# Schwarz methods & ABC

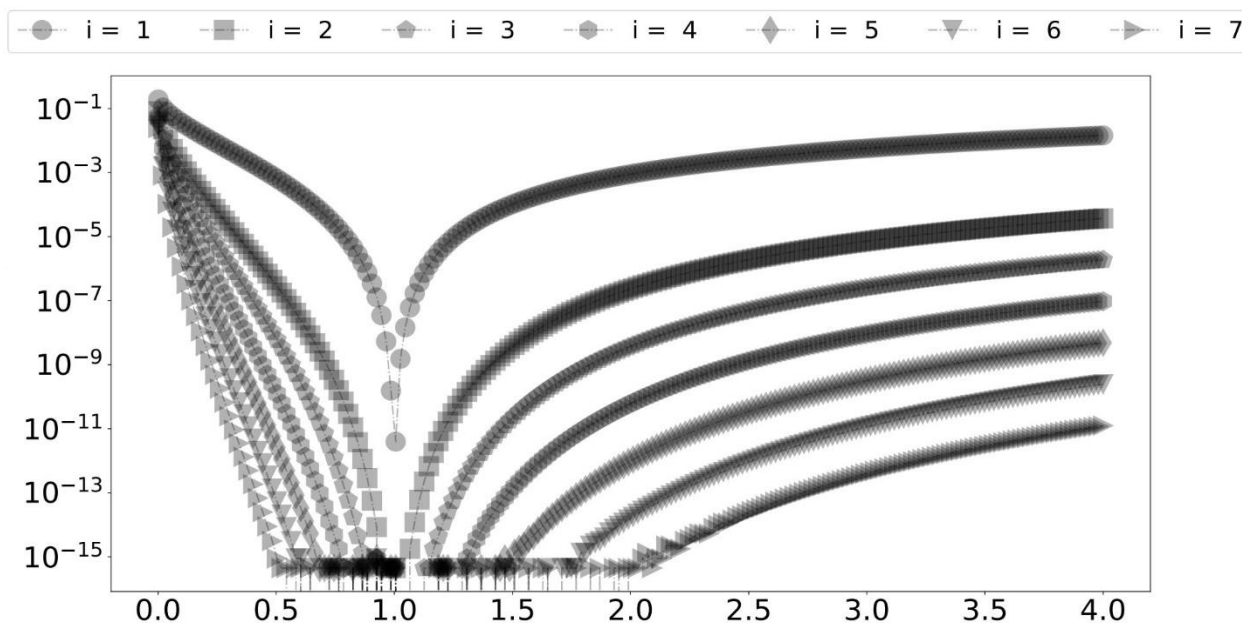


# Schwarz methods & ABC



Padé approximation about endpoint

# Schwarz methods & ABC



Shifted Padé approximation

# IRK preconditioners



# IRK preconditioners

$$\frac{\partial}{\partial t}u = \Delta u \quad \text{in } \Omega \times (0, T)$$

$$u = g \quad \text{on } \partial\Omega \times (0, T)$$

$$u = u_0 \quad \text{at } \partial\Omega \times \{0\}$$

# IRK preconditioners

$$\mathbf{u}^m = \mathbf{u}^{m-1} + \tau \sum_{i=1}^s b_i \mathbf{k}_i^m$$

$$\left( I_s \otimes I_n - \frac{\tau}{h^2} (A \otimes L) \right) \mathbf{k}^m = \frac{1}{h^2} (I_s \otimes L) \mathbf{u}^{m-1}$$

$$M$$

# IRK preconditioners



M. M. Rana, V. E. Howle, K. Long, A. Meek, and W. Milestone. A New Block Preconditioner for Implicit Runge-Kutta Methods for Parabolic PDE Problems, 2021.



# IRK preconditioners

$$\text{factor} \left( I_s \otimes I_n - \frac{\tau}{h^2} A \otimes L \right)$$

# IRK preconditioners

$$\text{factor} \left( I_s \otimes I_n - \frac{\tau}{h^2} A \otimes L \right) \approx I_s \otimes I_n - \frac{\tau}{h^2} \text{factor}(A) \otimes L$$

# IRK preconditioners

$$\text{factor} \left( I_s \otimes I_n - \frac{\tau}{h^2} A \otimes L \right) \approx I_s \otimes I_n - \frac{\tau}{h^2} \text{factor}(A) \otimes L$$

$$I_s \otimes I_n - \frac{\tau}{h^2} D_A \otimes L =: P^{\text{diag}}$$

# IRK preconditioners

$$I_s \otimes I_n - \frac{\tau}{h^2} U_A \otimes L =: P^{\text{diag}}$$

$$M \left( P^{\text{diag}} \right)^{-1}$$

$$\text{sp.linalg.gmres} (M, \text{rhs}, P^{\text{diag}})$$

# IRK preconditioners

sp.linalg.gmres

$$\frac{\|r_k\|}{\|r_0\|} \leq \min_{\substack{\varphi(0)=1 \\ \deg(\varphi) \leq k}} \|\varphi(M (P^{\text{diag}})^{-1})\|$$

$$\frac{\|r_k\|}{\|r_0\|} \leq \kappa(S) \min_{\substack{\varphi(0)=1 \\ \deg(\varphi) \leq k}} \max_{\zeta_i \in \text{sp}(M(P^{\text{triang}})^{-1})} |\varphi(\zeta_i)|$$

$$\frac{\|r_k\|}{\|r_0\|} \leq \kappa(S) \min_{\substack{\varphi(0)=1 \\ \deg(\varphi) \leq k}} \max_{\zeta \in \text{co}(\text{sp}(\dots))} |\varphi(\zeta)|$$

# IRK preconditioners

$$s = 2$$

# IRK preconditioners

**Proposition.** Let  $s = 2$  and  $a_{ij} \neq 0$ . Adopting the above notation and setting  $\text{sp}(L) = \{\lambda_k\}_k$  and  $\theta_k = \frac{\tau}{h^2} \lambda_k$  we have  $\text{sp}(M (P^{\text{diag}})^{-1}) = \zeta_{1,2}^{(k)}$  with

$$\zeta_{1,2}^{(k)} = 1 \pm \sqrt{\frac{a_{12}a_{21}}{(|\theta_k^{-1}| + a_{11})(|\theta_k^{-1}| + a_{22})}},$$

and the condition number of the eigenbasis is given by

$$\kappa(S) = \max_{k=1,\dots,n} \sqrt{\frac{1 + \left| \frac{a_{21}(1+a_{22}|\theta_k|)}{a_{12}(1+a_{11}|\theta_k|)} \right| + \left| 1 - \left| \frac{a_{21}(1+a_{22}|\theta_k|)}{a_{12}(1+a_{11}|\theta_k|)} \right| \right|}{1 + \left| \frac{a_{21}(1+a_{22}|\theta_k|)}{a_{12}(1+a_{11}|\theta_k|)} \right| - \left| 1 - \left| \frac{a_{21}(1+a_{22}|\theta_k|)}{a_{12}(1+a_{11}|\theta_k|)} \right| \right|}}.$$

# IRK preconditioners

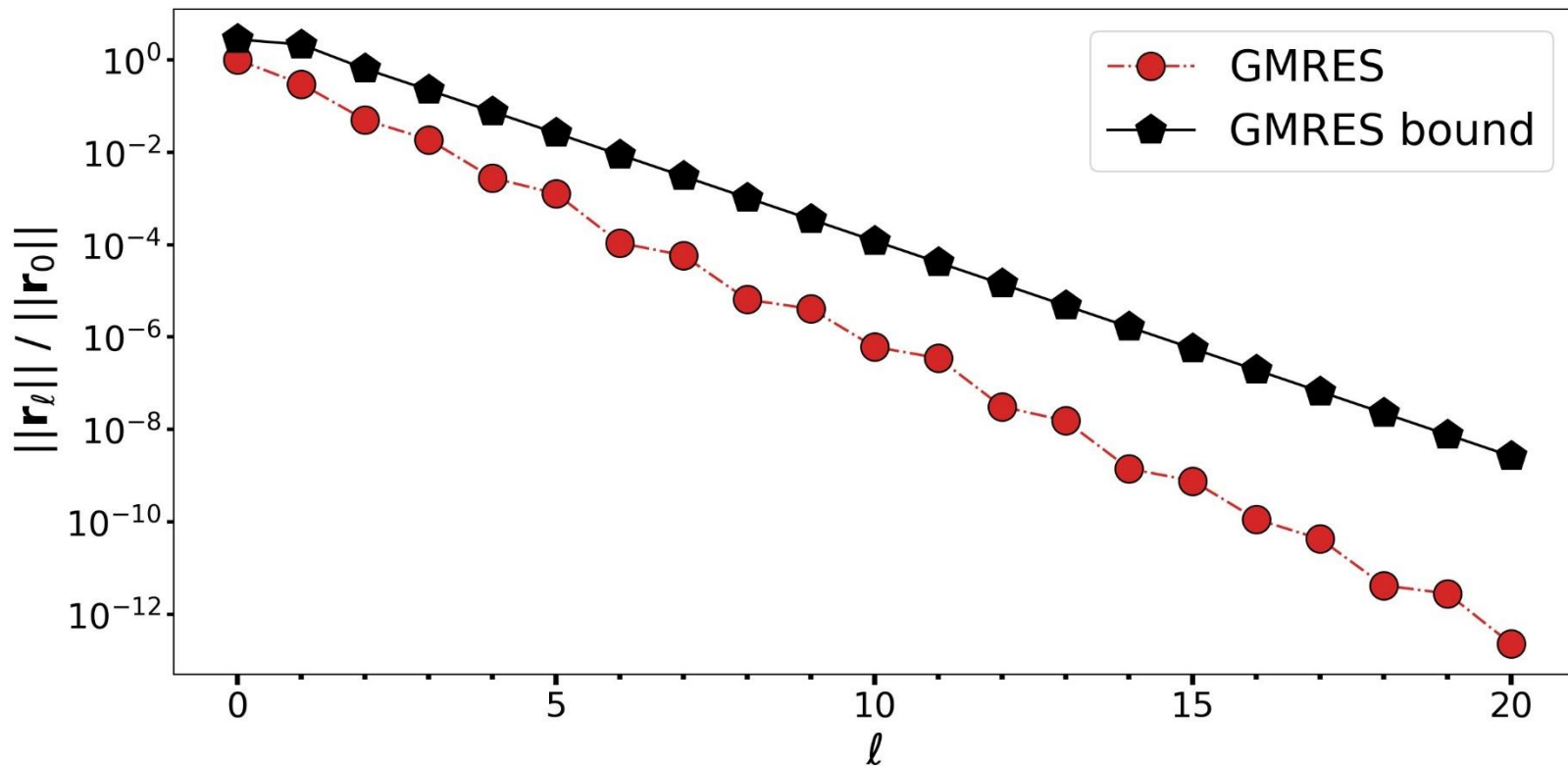
preconditioned GMRES

What can we predict ?

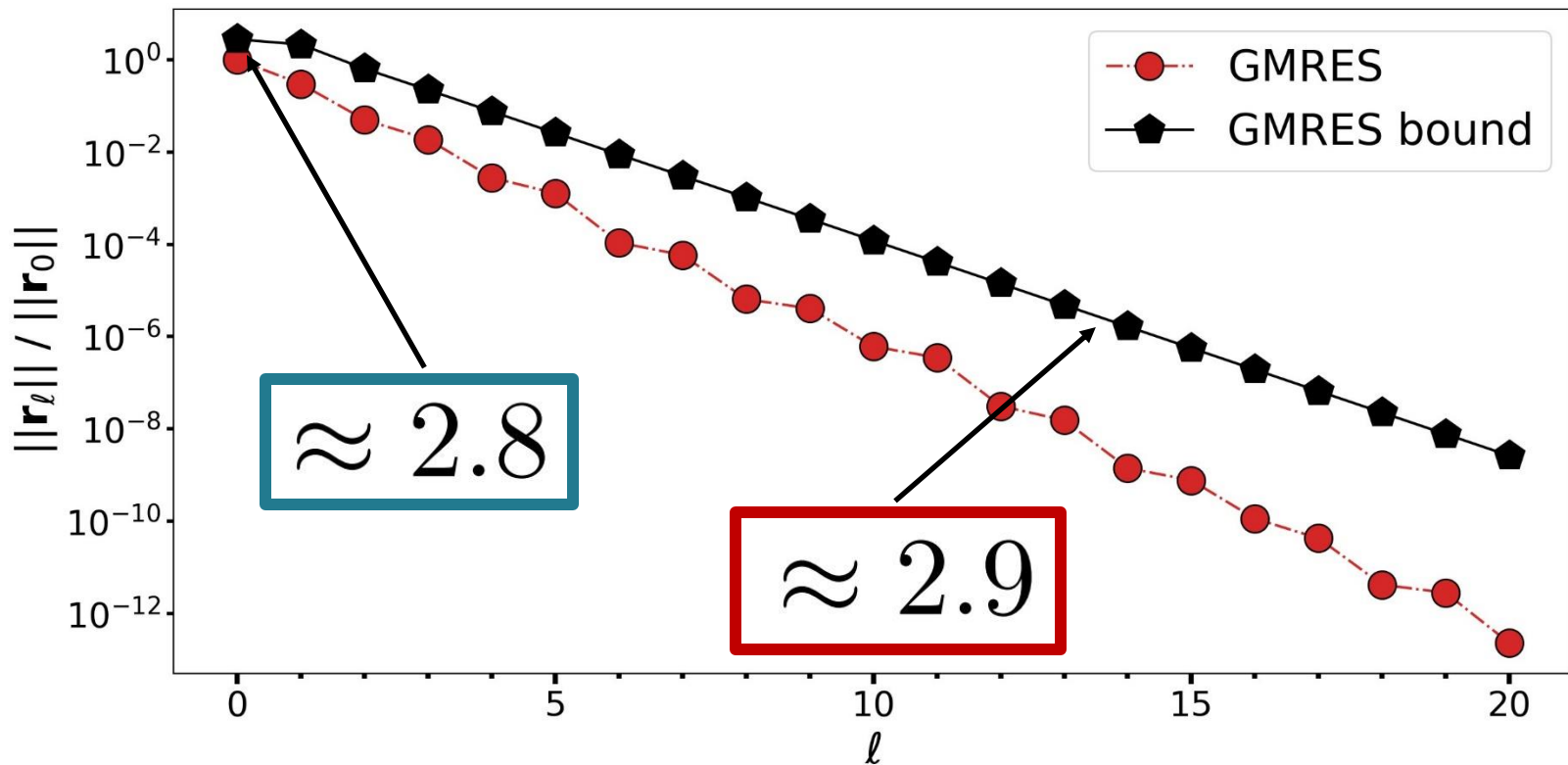
$$s = 2$$



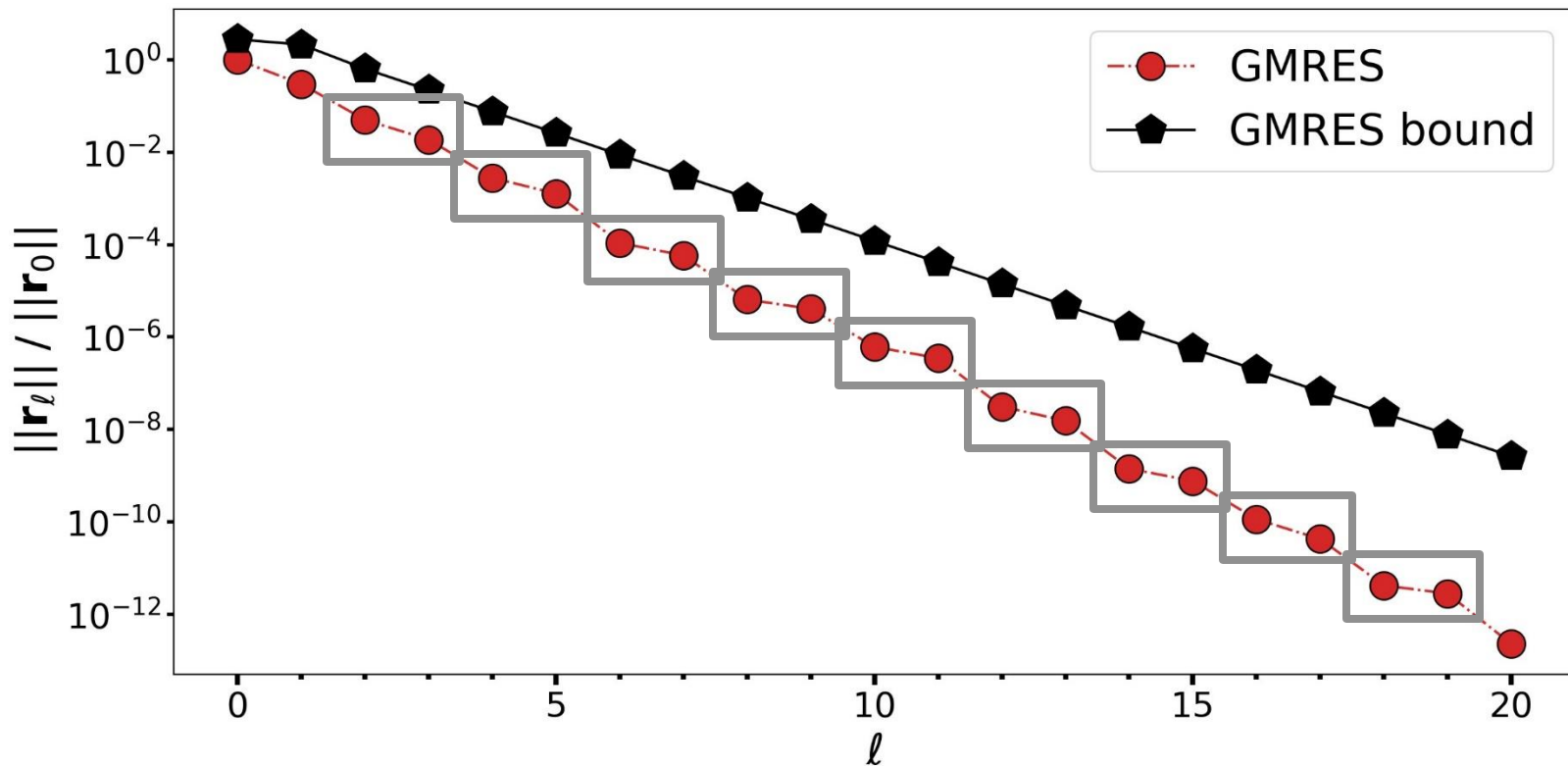
# IRK preconditioners



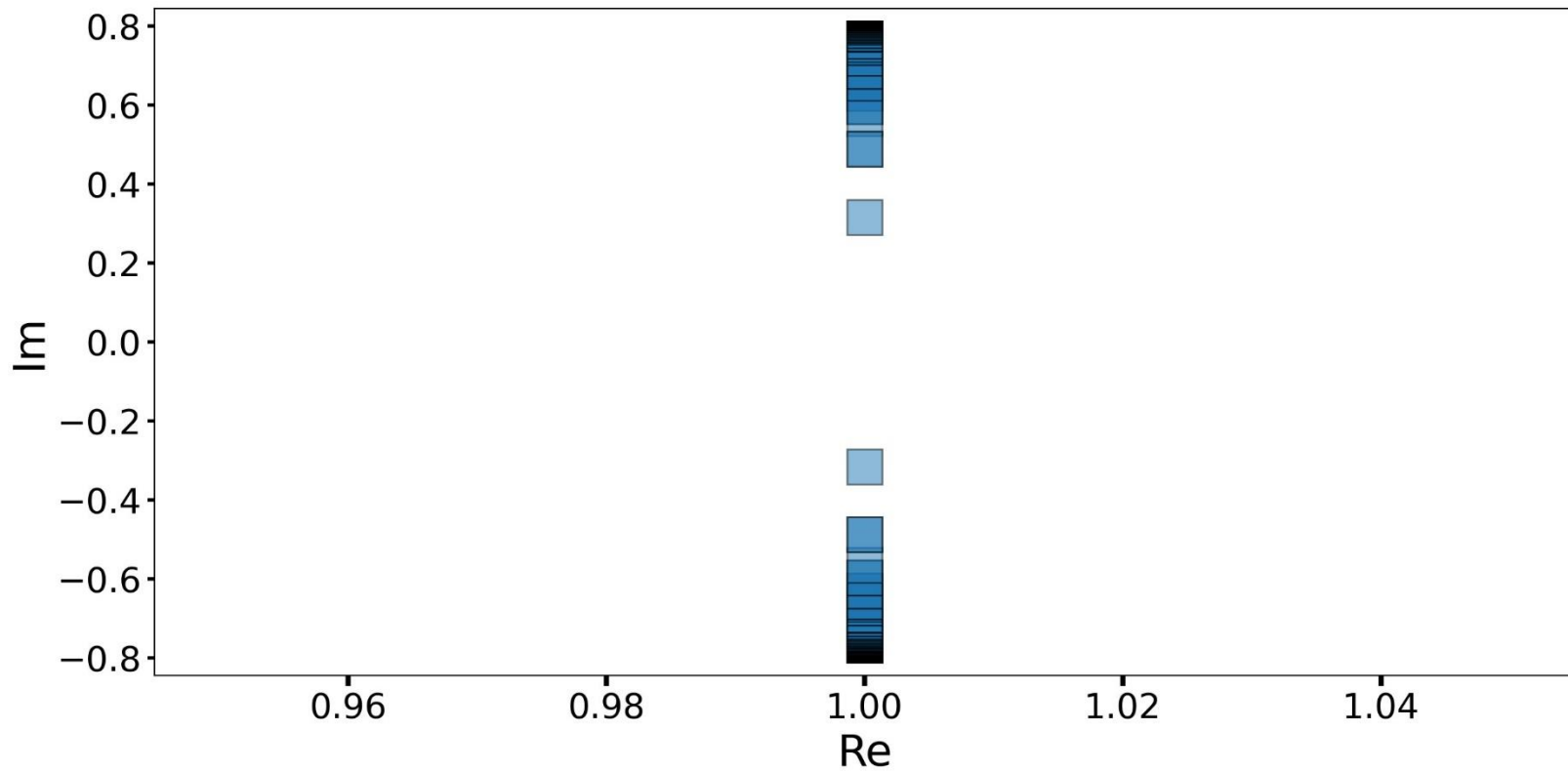
# IRK preconditioners



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# IRK preconditioners

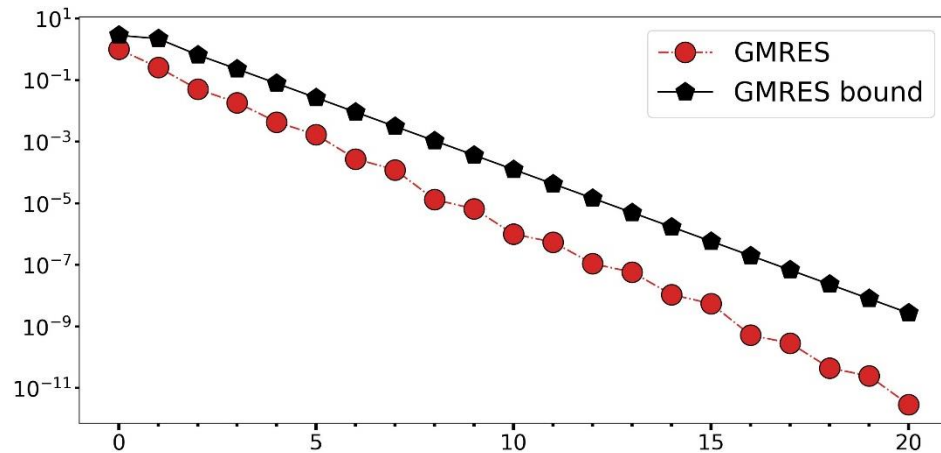
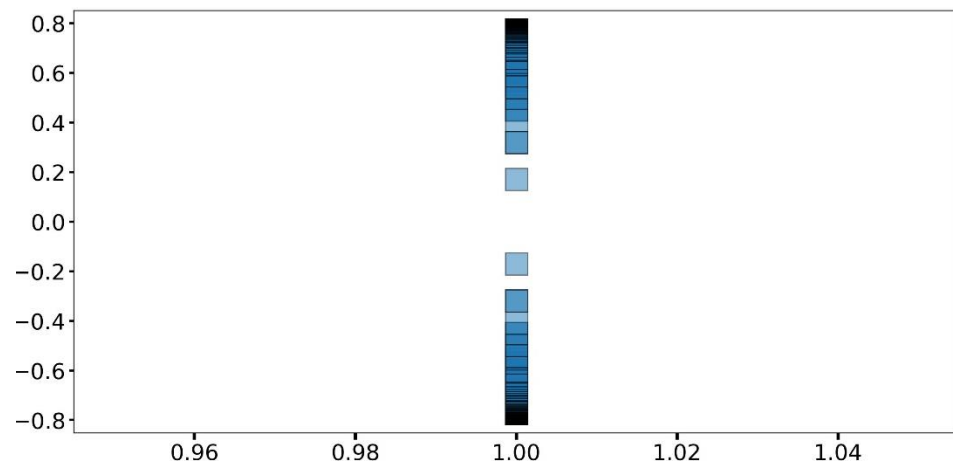
sp.linalg.gmres

$$\frac{\|r_k\|}{\|r_0\|} \leq \min_{\substack{\varphi(0)=1 \\ \deg(\varphi) \leq k}} \|\varphi(M (P^{\text{diag}})^{-1})\|$$

$$\frac{\|r_k\|}{\|r_0\|} \leq \kappa(S) \min_{\substack{\varphi(0)=1 \\ \deg(\varphi) \leq k}} \max_{\zeta_i \in \text{sp}(M(P^{\text{triang}})^{-1})} |\varphi(\zeta_i)|$$

$$\frac{\|r_k\|}{\|r_0\|} \leq \kappa(S) \min_{\substack{\varphi(0)=1 \\ \deg(\varphi) \leq k}} \max_{\zeta \in \text{co}(\text{sp}(\dots))} |\varphi(\zeta)|$$

# IRK preconditioners



# Conclusion



**Thank you for  
your attention**



# Schwarz methods



Karl Hermann Amandus  
Schwarz

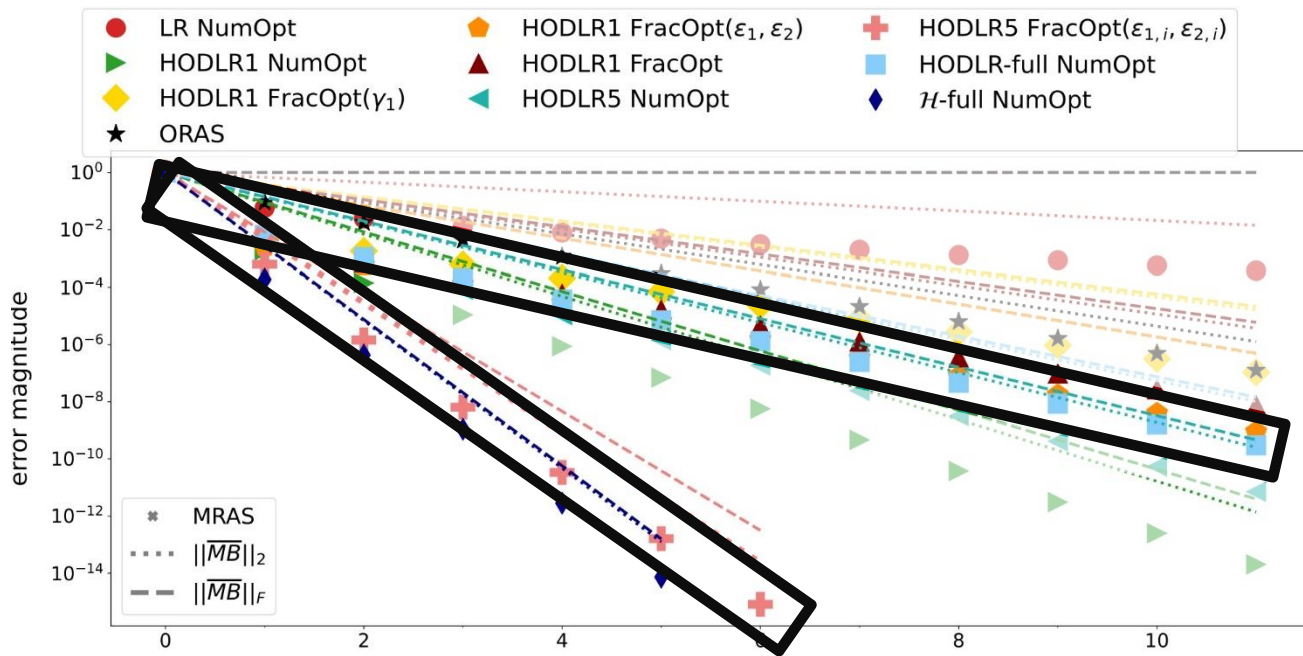
# Schwarz methods & DS



data-sparse formats: convergence

# Schwarz methods & DS

## data-sparse formats: convergence



# Schwarz methods & ABC



Henri Eugène Padé

# References



# Continued fractions and Padé

**Theorem.** *For any  $\alpha \in (-1, +\infty)$  we have*

$$\sqrt{1+\alpha} = 1 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{2 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{\ddots}}}}$$

*Moreover, for any  $n$  the  $[n+1, n]$ -Padé approximant of  $\sqrt{1+\alpha}$  expanded about  $\alpha = 0$  is the  $(2n+1)$ -st truncation of the continued fraction above.*

# Continued fractions and Padé

To combine

$$\sqrt{1+\alpha} = 1 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{2 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{\ddots}}}}$$

# Continued fractions and Padé

To combine

$$\sqrt{1+\alpha} = 1 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{2 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{\ddots}}}}$$

and

$$\hat{t}_{Na}^{\infty}(\lambda) = \frac{\lambda + \sqrt{\lambda^2 - 4}}{2h^2}$$



# Continued fractions and Padé

To combine

$$\boxed{\sqrt{1+\alpha}} = 1 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{2 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{\ddots}}}}$$

and

$$\hat{t}_{Na}^{\infty}(\lambda) = \frac{\lambda + \boxed{\sqrt{\lambda^2 - 4}}}{2h^2}$$

things get a little *calculaty*

# Continued fractions and Padé

Having  $\lambda = 2 + z$  we get

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$$\hat{t}_{Na}^b(z) = \frac{1}{h^2} \left( 2 + z - \frac{1}{2 + z - \frac{1}{2 + z - \frac{\ddots}{2 + z - \frac{1}{2 + z}}}} \right)$$

# Continued fractions and Padé

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$$\hat{t}_{Na}^\infty(z) = \frac{1}{h^2} \left( 2 + z - \frac{1}{2 + z - \frac{1}{2 + z - \frac{1}{2 + z - \frac{1}{\dots}}}} \right) = \frac{1}{h^2} \left( 1 + \frac{z}{2} + \frac{z}{2} \sqrt{1 + \frac{4}{z}} \right)$$

# Continued fractions and Padé

Combining

$$\sqrt{1+\alpha} = 1 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{2 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{\ddots}}}}$$

# Continued fractions and Padé

Combining

$$\sqrt{1+\alpha} = 1 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{2 + \frac{\frac{\alpha}{2}}{1 + \frac{\frac{\alpha}{2}}{\ddots}}}}$$

and

$$\hat{t}_{N^a}^\infty(z) = \frac{1}{h^2} \left( 1 + \frac{z}{2} + \frac{z}{2} \sqrt{1 + \frac{4}{z}} \right)$$

# Continued fractions and Padé

Combining

$$\boxed{\sqrt{1+\alpha}} = 1 + \cfrac{\cfrac{\alpha}{2}}{1 + \cfrac{\cfrac{\alpha}{2}}{2 + \cfrac{\cfrac{\alpha}{2}}{1 + \cfrac{\cfrac{\alpha}{2}}{\ddots}}}}$$

and

$$\hat{t}_{N^a}^\infty(z) = \frac{1}{h^2} \left( 1 + \frac{z}{2} + \frac{z}{2} \boxed{\sqrt{1 + \frac{4}{z}}} \right)$$

becomes a little easier

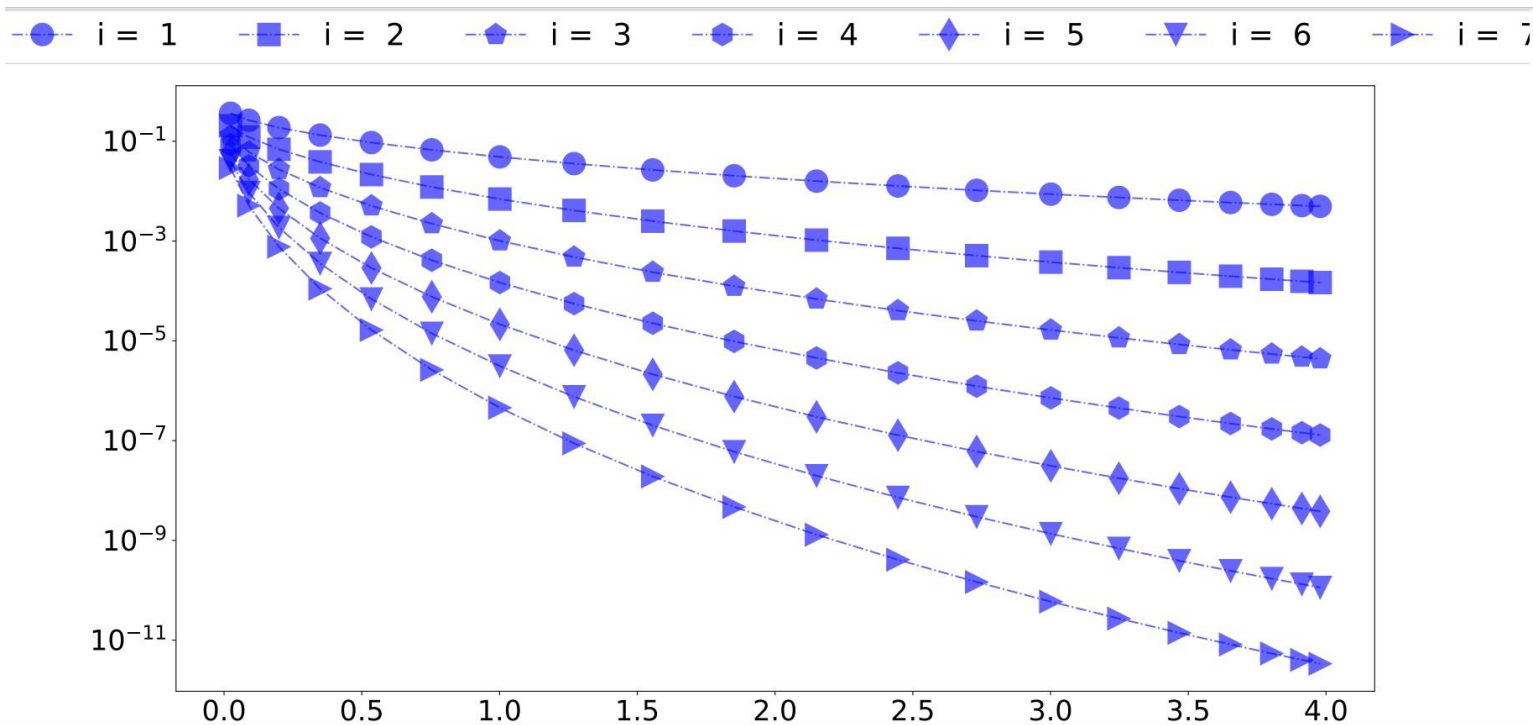
# Continued fractions and Padé

Having  $\lambda = 2 + z$  we get

**Theorem.** *The function  $\hat{t}_{N^a}^b(z)$  is the  $[n, n]$ -Padé approximation about the expansion point  $z = +\infty$  of  $\hat{t}_{N^a}^\infty(z)$ , where  $n = N^b - N^a$ .*



# Continued fractions and Padé



# IRK preconditioners

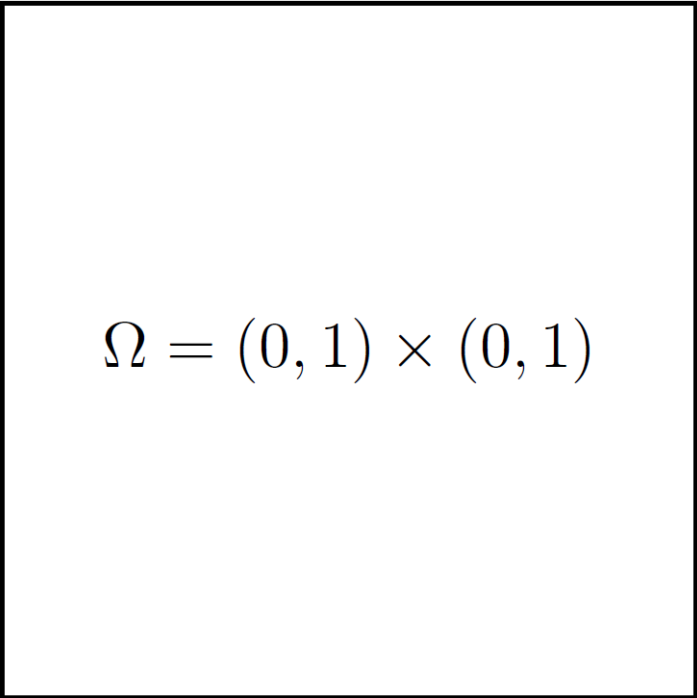


# IRK preconditioners

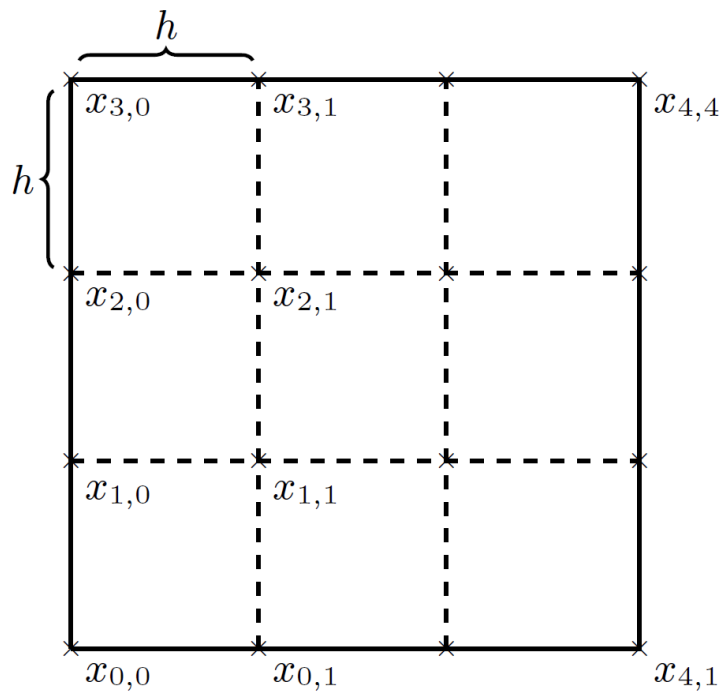


Step I :

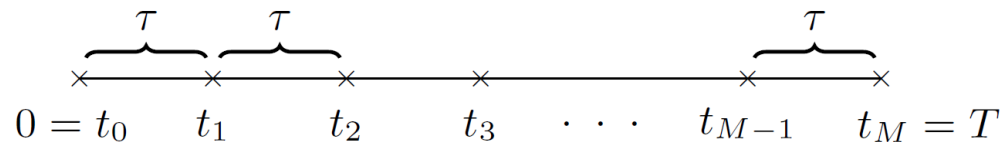
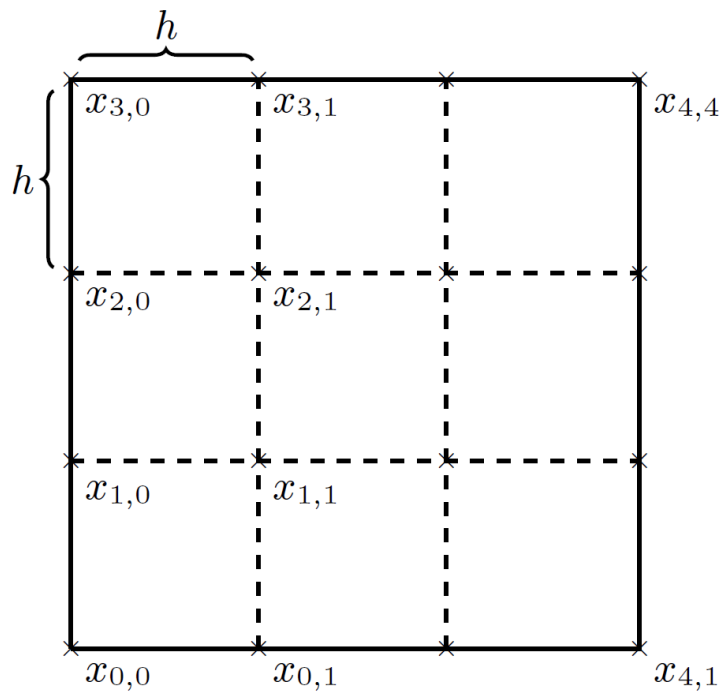
# IRK preconditioners


$$\Omega = (0, 1) \times (0, 1)$$

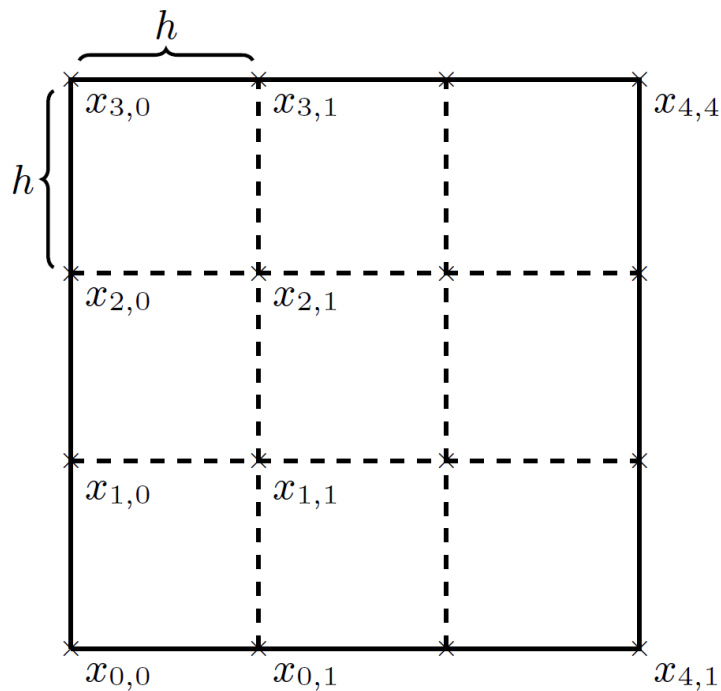
# IRK preconditioners



# IRK preconditioners



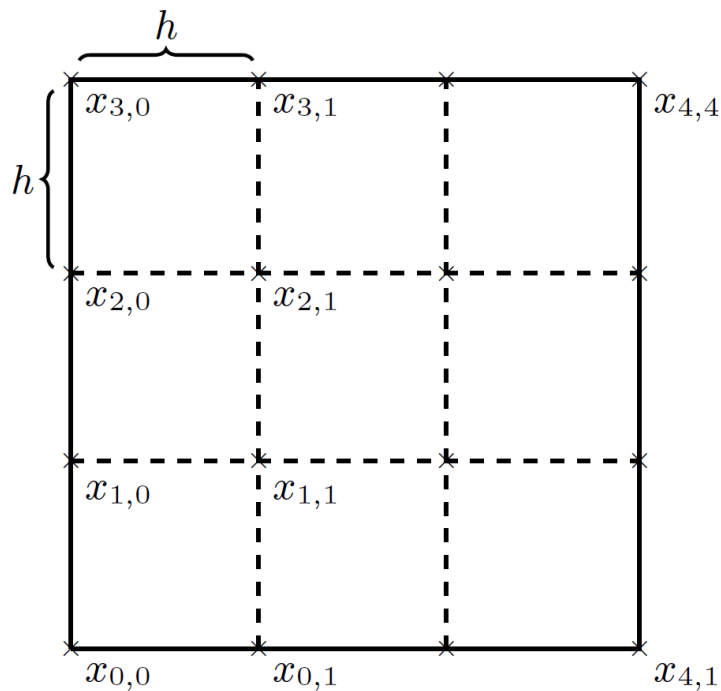
# IRK preconditioners



A diagram illustrating a time interval  $[0, T]$  divided into sub-intervals of length  $\tau$ . The timeline is marked with points  $0 = t_0$ ,  $t_1$ ,  $t_2$ ,  $t_3$ ,  $\dots$ ,  $t_{M-1}$ , and  $t_M = T$ . Braces above the timeline indicate that the intervals  $[t_0, t_1]$ ,  $[t_1, t_2]$ , and  $[t_{M-1}, t_M]$  each have a length of  $\tau$ .

$$\mathbf{u}^m \approx u(t_m, x_{ij})$$

# IRK preconditioners



$$\begin{array}{c}
 \tau \quad \tau \quad \tau \\
 \times \quad \times \quad \times \quad \times \quad \cdots \quad \times \quad \times \\
 0 = t_0 \quad t_1 \quad t_2 \quad t_3 \quad \cdots \quad t_{M-1} \quad t_M = T
 \end{array}$$

$$\mathbf{u}^m \approx u(t_m, x_{ij})$$

$$\Delta \approx L$$



# IRK preconditioners



# IRK preconditioners

$$\mathbf{u}^m = \mathbf{u}^{m-1} + \tau \sum_{i=1}^s b_i \mathbf{k}_i^m$$

# IRK preconditioners

Step I :

$$M \left( P^{\text{diag}} \right)^{-1} \sim \begin{bmatrix} X_{11} & \dots & X_{1s} \\ \vdots & \ddots & \vdots \\ X_{s1} & \dots & X_{ss} \end{bmatrix}$$

# IRK preconditioners

Step I :

$$M \left( P^{\text{diag}} \right)^{-1} \sim \begin{bmatrix} X_{11} & \dots & X_{1s} \\ \vdots & \ddots & \vdots \\ X_{s1} & \dots & X_{ss} \end{bmatrix}$$

$$\text{with } X_{ij} = \text{diag} \left( \xi_1^{(ij)}, \dots, \xi_n^{(ij)} \right) \quad \forall ij$$

# Preconditioner analysis



Step II :

# IRK preconditioners

Step II :

$$X = \begin{bmatrix} X_{11} & \dots & X_{1s} \\ \vdots & \ddots & \vdots \\ X_{s1} & \dots & X_{ss} \end{bmatrix} \sim$$

with  $X_{ij} = \text{diag} \left( \xi_1^{(ij)}, \dots, \xi_n^{(ij)} \right)$

$$X \in \mathbb{R}^{ns \times ns}$$

# IRK preconditioners

Step II :

$$X = \begin{bmatrix} X_{11} & \dots & X_{1s} \\ \vdots & \ddots & \vdots \\ X_{s1} & \dots & X_{ss} \end{bmatrix} \sim X_k = \begin{bmatrix} \xi_k^{(11)} & \dots & \xi_k^{(1s)} \\ \vdots & \ddots & \vdots \\ \xi_k^{(s1)} & \dots & \xi_k^{(ss)} \end{bmatrix}$$

with  $X_{ij} = \text{diag} \left( \xi_1^{(ij)}, \dots, \xi_n^{(ij)} \right)$

$$X \in \mathbb{R}^{ns \times ns}$$

$$X_k \in \mathbb{R}^{s \times s}$$

# IRK preconditioners

**Lemma.** *Let  $X \in \mathbb{R}^{ns \times ns}$  and  $X_k \in \mathbb{R}^{s \times s}$  be as above and set*

$$\text{eigenpair}(X_k) = \left( \mu_\ell^{(k)}, \mathbf{s}_\ell^{(k)} \right).$$

*Then the eigenpairs of  $X$  are equal to  $\left( \mu_\ell^{(k)}, \mathbf{s}_\ell^{(k)} \otimes \mathbf{e}_k \right)$ .*