



# INA333 Micro-Power (50µA), Zero-Drift, Rail-to-Rail Out Instrumentation Amplifier

## 1 Features

- Low Offset Voltage: 25 µV (Maximum),  $G \geq 100$
- Low Drift: 0.1 µV/°C,  $G \geq 100$
- Low Noise: 50 nV/√Hz,  $G \geq 100$
- High CMRR: 100 dB (Minimum),  $G \geq 10$
- Low Input Bias Current: 200 pA (Maximum)
- Supply Range: 1.8 V to 5.5 V
- Input Voltage: (V–) +0.1 V to (V+) –0.1 V
- Output Range: (V–) +0.05 V to (V+) –0.05 V
- Low Quiescent Current: 50 µA
- Operating Temperature: –40°C to +125°C
- RFI Filtered Inputs
- 8-Pin VSSOP and 8-Pin WSON Packages

## 2 Applications

- Bridge Amplifiers
- ECG Amplifiers
- Pressure Sensors
- Medical Instrumentation
- Portable Instrumentation
- Weigh Scales
- Thermocouple Amplifiers
- RTD Sensor Amplifiers
- Data Acquisition

## 3 Description

The INA333 device is a low-power, precision instrumentation amplifier offering excellent accuracy. The versatile 3-operational amplifier design, small size, and low power make it ideal for a wide range of portable applications.

A single external resistor sets any gain from 1 to 1000. The INA333 is designed to use an industry-standard gain equation:  $G = 1 + (100 \text{ k}\Omega / R_G)$ .

The INA333 device provides very low offset voltage (25 µV,  $G \geq 100$ ), excellent offset voltage drift (0.1 µV/°C,  $G \geq 100$ ), and high common-mode rejection (100 dB at  $G \geq 10$ ). It operates with power supplies as low as 1.8 V ( $\pm 0.9$  V) and quiescent current is only 50 µA, making it ideal for battery-operated systems. Using autocalibration techniques to ensure excellent precision over the extended industrial temperature range, the INA333 device also offers exceptionally low noise density (50 nV/√Hz) that extends down to DC.

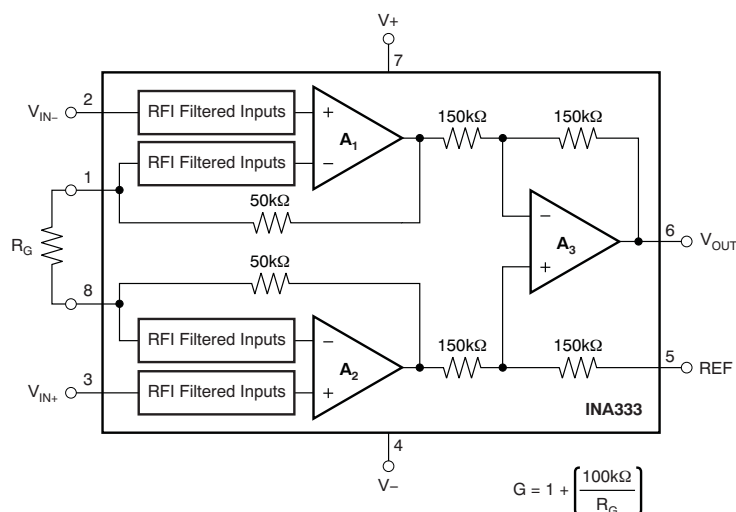
The INA333 device is available in both 8-pin VSSOP and WSON surface-mount packages and is specified over the  $T_A = -40^\circ\text{C}$  to  $+125^\circ\text{C}$  temperature range.

**Device Information<sup>(1)</sup>**

PART NUMBER	PACKAGE	BODY SIZE (NOM)
INA333	VSSOP (8)	3.00 mm x 3.00 mm
	WSON (8)	3.00 mm x 3.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

**Simplified Schematic**



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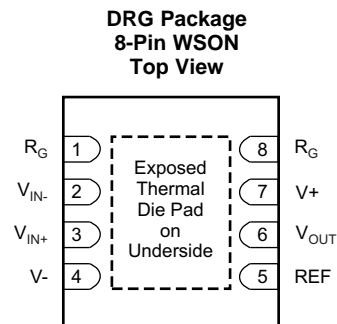
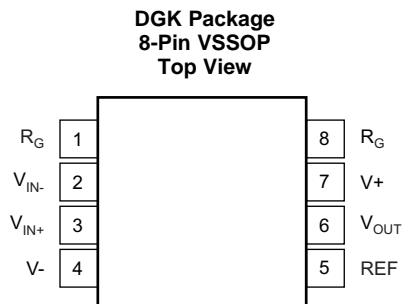
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## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision B (October 2008) to Revision C	Page
<ul style="list-style-type: none"> <li>Added <i>ESD Ratings</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i>, <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Layout</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section .....</li> </ul>	<b>1</b>

## 5 Pin Configuration and Functions



### Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
REF	5	I	Reference input. This pin must be driven by low impedance or connected to ground.
RG	1, 8	—	Gain setting pins. For gains greater than 1, place a gain resistor between pins 1 and 8.
V <sup>+</sup>	7	—	Positive supply
V <sup>-</sup>	4	—	Negative supply
VIN+	3	I	Positive input
VIN-	2	I	Negative input
VOUT	6	O	Output

## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) <sup>(1)</sup>

	MIN	MAX	UNIT
Supply voltage	7		V
Analog input voltage <sup>(2)</sup>	(V <sub>-</sub> ) – 0.3	(V <sub>+</sub> ) + 0.3	V
Output short-circuit <sup>(3)</sup>	Continuous		
Operating temperature, T <sub>A</sub>	–40	150	°C
Junction temperature, T <sub>J</sub>		150	°C
Storage temperature, T <sub>stg</sub>	–65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) Input pins are diode-clamped to the power-supply rails. Input signals that can swing more than 0.3 V beyond the supply rails should be current limited to 10 mA or less.
- (3) Short-circuit to ground.

### 6.2 ESD Ratings

		VALUE	UNIT
V <sub>(ESD)</sub> Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±4000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±1000	
	Machine model (MM)	±200	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
V <sub>S</sub> Supply voltage	1.8	5.5	V
Specified temperature	–40	125	°C

### 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		INA333		UNIT
		DGK (VSSOP)	DRG (WSON)	
		8 PINS	8 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	169.5	60	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	62.7	60	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	90.3	50	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	7.6	—	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	88.7	—	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	—	6	°C/W

- (1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

## 6.5 Electrical Characteristics

for  $V_S = 1.8 \text{ V}$  to  $5.5 \text{ V}$  at  $T_A = 25^\circ\text{C}$ ,  $R_L = 10 \text{ k}\Omega$ ,  $V_{REF} = V_S / 2$ , and  $G = 1$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
INPUT <sup>(1)</sup>						
V <sub>OSI</sub>	Offset voltage, RTI <sup>(2)</sup>			±10 ±25/G	±25 ±75/G	μV
PSR	vs temperature	T <sub>A</sub> = −40°C to +125°C			±0.1 ±0.5 / G	μV/°C
	vs power supply	1.8 V ≤ V <sub>S</sub> ≤ 5.5 V		±1 ±5/G	±5 ±15/G	μV/V
	Long-term stability			See <sup>(3)</sup>		
	Turnon time to specified V <sub>OSI</sub>	T <sub>A</sub> = −40°C to +125°C		See <i>Typical Characteristics</i>		
	Impedance					
Z <sub>IN</sub>	Differential			100    3		GΩ    pF
Z <sub>IN</sub>	Common-mode			100    3		GΩ    pF
V <sub>CM</sub>	Common-mode voltage range	V <sub>O</sub> = 0 V	(V−) + 0.1		(V+) − 0.1	V
CMR	Common-mode rejection	DC to 60 Hz				
	G = 1	V <sub>CM</sub> = (V−) + 0.1 V to (V+) − 0.1 V	80	90		dB
	G = 10	V <sub>CM</sub> = (V−) + 0.1 V to (V+) − 0.1 V	100	110		dB
	G = 100	V <sub>CM</sub> = (V−) + 0.1 V to (V+) − 0.1 V	100	115		dB
	G = 1000	V <sub>CM</sub> = (V−) + 0.1 V to (V+) − 0.1 V	100	115		dB
INPUT BIAS CURRENT						
I <sub>B</sub>	Input bias current			±70	±200	pA
	vs temperature	T <sub>A</sub> = −40°C to +125°C		See <a href="#">Figure 26</a>		pA/°C
I <sub>OS</sub>	Input offset current			±50	±200	pA
	vs temperature	T <sub>A</sub> = −40°C to +125°C		See <a href="#">Figure 28</a>		pA/°C
INPUT VOLTAGE NOISE						
e <sub>NI</sub>	Input voltage noise	G = 100, R <sub>S</sub> = 0 Ω, f = 10 Hz		50		nV/√Hz
		G = 100, R <sub>S</sub> = 0 Ω, f = 100 Hz		50		nV/√Hz
		G = 100, R <sub>S</sub> = 0 Ω, f = 1 kHz		50		nV/√Hz
		G = 100, R <sub>S</sub> = 0 Ω, f = 0.1 Hz to 10 Hz		1		μV <sub>PP</sub>
i <sub>N</sub>	Input current noise	f = 10 Hz		100		fA/√Hz
		f = 0.1 Hz to 10 Hz		2		pA <sub>PP</sub>
GAIN						
G	Gain equation			1 + (100 kΩ/R <sub>G</sub> )		V/V
	Range of gain		1		1000	V/V
	Gain error	V <sub>S</sub> = 5.5 V, (V−) + 100 mV ≤ V <sub>O</sub> ≤ (V+) − 100 mV				
		G = 1		±0.01%	±0.1%	
		G = 10		±0.05%	±0.25%	
		G = 100		±0.07%	±0.25%	
		G = 1000		±0.25%	±0.5%	
	Gain vs temperature, G = 1	T <sub>A</sub> = −40°C to +125°C		±1	±5	ppm/°C
	Gain vs temperature, G > 1 <sup>(4)</sup>	T <sub>A</sub> = −40°C to +125°C		±15	±50	ppm/°C
	Gain nonlinearity	V <sub>S</sub> = 5.5 V, (V−) + 100 mV ≤ V <sub>O</sub> ≤ (V+) − 100 mV				
	Gain nonlinearity, G = 1 to 1000	R <sub>L</sub> = 10 kΩ		10		ppm
OUTPUT						
	Output voltage swing from rail	V <sub>S</sub> = 5.5 V, R <sub>L</sub> = 10 kΩ		See <a href="#">Figure 29</a>	50	mV
	Capacitive load drive			500		pF
I <sub>SC</sub>	Short-circuit current	Continuous to common		−40, +5		mA

(1) Total  $V_{OS}$ , referred-to-input =  $(V_{OSI}) + (V_{OSO} / G)$

(2) RTI = Referred-to-input

(3) 300-hour life test at  $150^\circ\text{C}$  demonstrated randomly distributed variation of approximately  $1 \mu\text{V}$

(4) Does not include effects of external resistor  $R_G$

**INA333**

SBOS445C – JULY 2008 – REVISED DECEMBER 2015

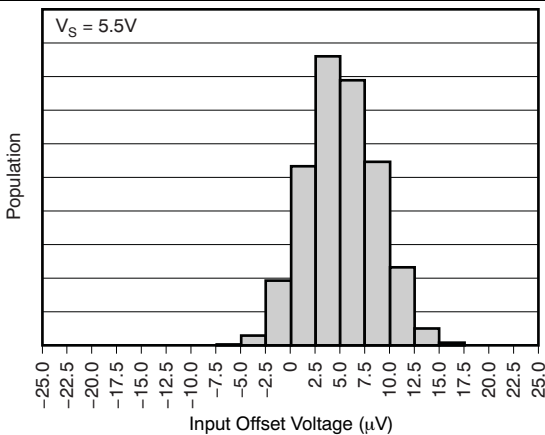
[www.ti.com](http://www.ti.com)
**Electrical Characteristics (continued)**

for  $V_S = 1.8\text{ V}$  to  $5.5\text{ V}$  at  $T_A = 25^\circ\text{C}$ ,  $R_L = 10\text{ k}\Omega$ ,  $V_{REF} = V_S / 2$ , and  $G = 1$  (unless otherwise noted)

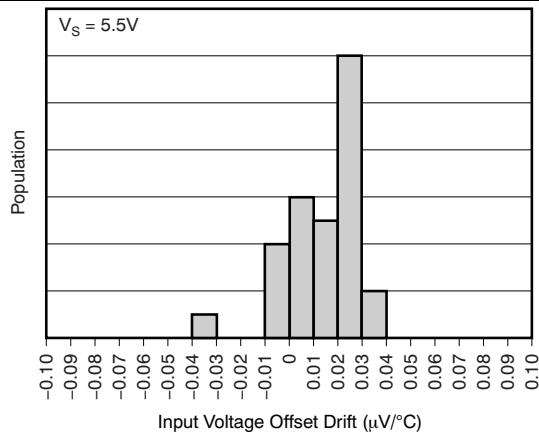
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>FREQUENCY RESPONSE</b>						
Bandwidth, –3dB		$G = 1$		150		kHz
		$G = 10$		35		kHz
		$G = 100$		3.5		kHz
		$G = 1000$		350		Hz
SR Slew rate		$V_S = 5\text{ V}$ , $V_O = 4\text{-V step}$ , $G = 1$		0.16		V/ $\mu\text{s}$
		$V_S = 5\text{ V}$ , $V_O = 4\text{-V step}$ , $G = 100$		0.05		V/ $\mu\text{s}$
$t_S$ Settling time to 0.01%		$V_{STEP} = 4\text{ V}$ , $G = 1$		50		$\mu\text{s}$
		$V_{STEP} = 4\text{ V}$ , $G = 100$		400		$\mu\text{s}$
$t_S$ Settling time to 0.001%		$V_{STEP} = 4\text{ V}$ , $G = 1$		60		$\mu\text{s}$
		$V_{STEP} = 4\text{ V}$ , $G = 100$		500		$\mu\text{s}$
Overload recovery		50% overdrive		75		$\mu\text{s}$
<b>REFERENCE INPUT</b>						
$R_{IN}$				300		k $\Omega$
Voltage range			$V_-$		$V_+$	V
<b>POWER SUPPLY</b>						
Voltage range		Single voltage range	+1.8		+5.5	V
		Dual voltage range	$\pm 0.9$		$\pm 2.75$	V
$I_Q$	Quiescent current	$V_{IN} = V_S / 2$		50	75	$\mu\text{A}$
	vs temperature	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$			80	$\mu\text{A}$
<b>TEMPERATURE RANGE</b>						
Specified temperature range			–40		125	$^\circ\text{C}$
Operating temperature range			–40		150	$^\circ\text{C}$

## 6.6 Typical Characteristics

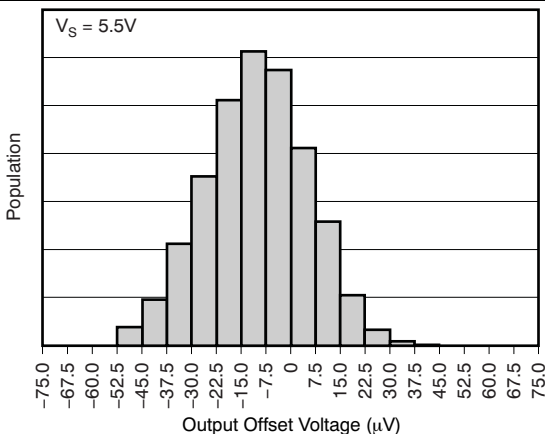
at  $T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{ V}$ ,  $R_L = 10\text{ k}\Omega$ ,  $V_{\text{REF}} = \text{midsupply}$ , and  $G = 1$  (unless otherwise noted)



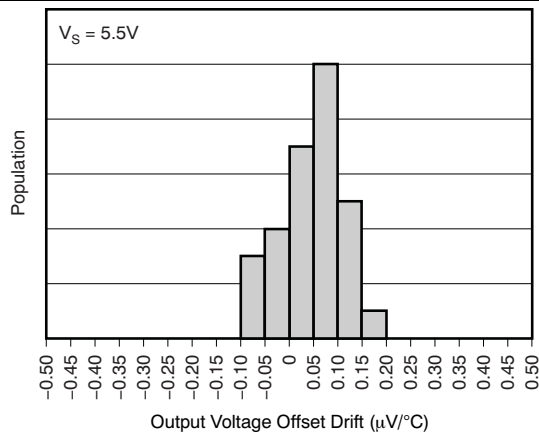
**Figure 1. Input Offset Voltage**



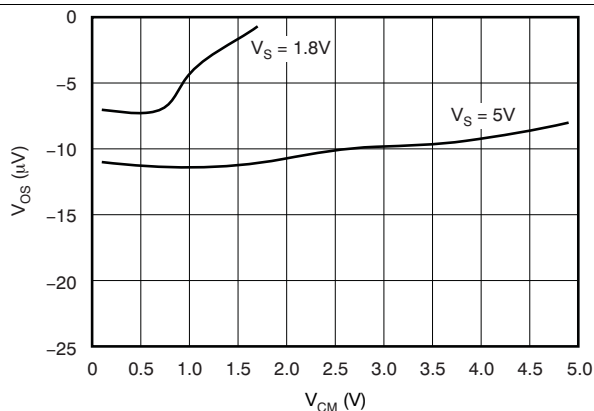
**Figure 2. Input Voltage Offset Drift ( $-40^\circ\text{C}$  to  $125^\circ\text{C}$ )**



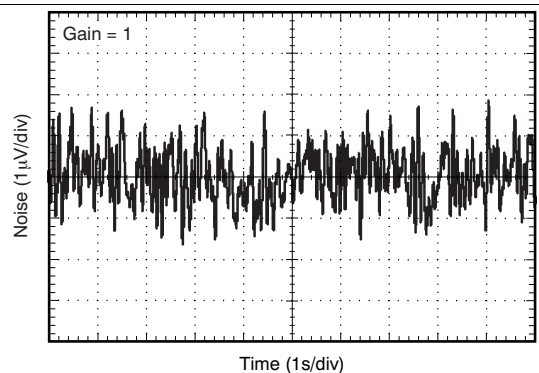
**Figure 3. Output Offset Voltage**



**Figure 4. Output Voltage Offset Drift ( $-40^\circ\text{C}$  to  $125^\circ\text{C}$ )**



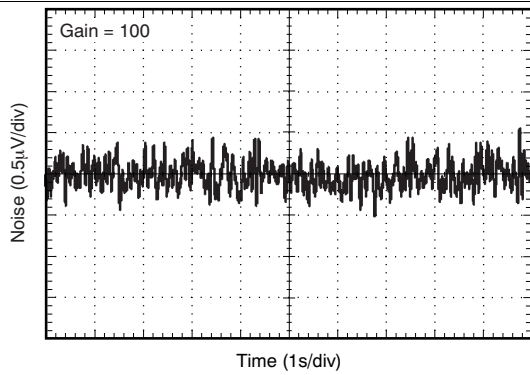
**Figure 5. Offset Voltage vs Common-Mode Voltage**



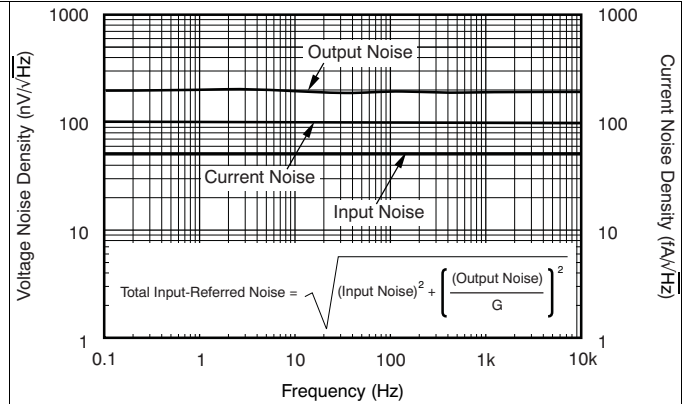
**Figure 6. 0.1-Hz to 10-Hz Noise**

## Typical Characteristics (continued)

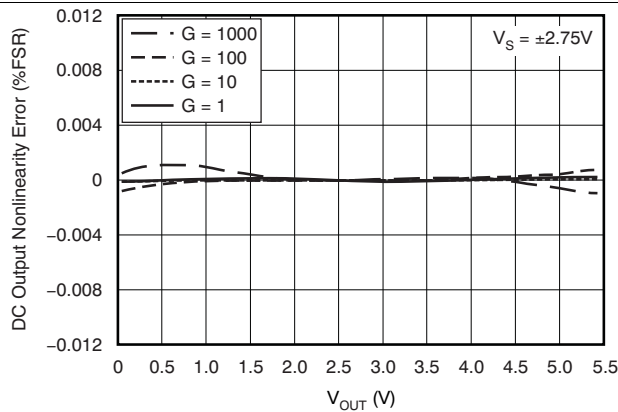
at  $T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{ V}$ ,  $R_L = 10\text{ k}\Omega$ ,  $V_{\text{REF}} = \text{midsupply}$ , and  $G = 1$  (unless otherwise noted)



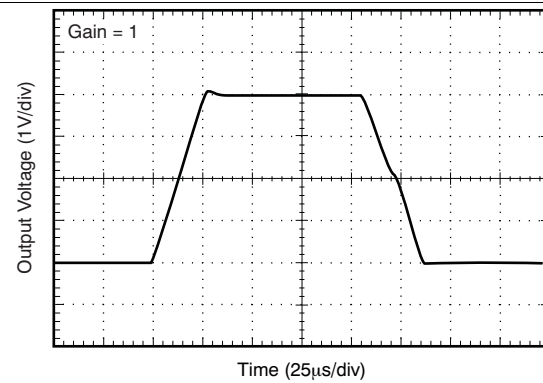
**Figure 7. 0.1-Hz to 10-Hz Noise**



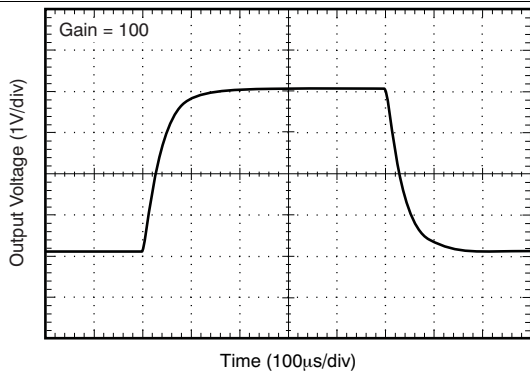
**Figure 8. Spectral Noise Density**



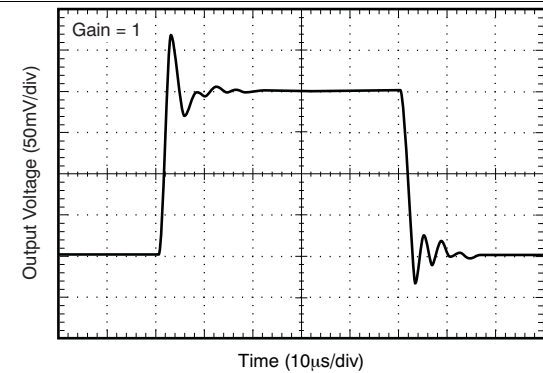
**Figure 9. Nonlinearity Error**



**Figure 10. Large Signal Response**



**Figure 11. Large-Signal Step Response**

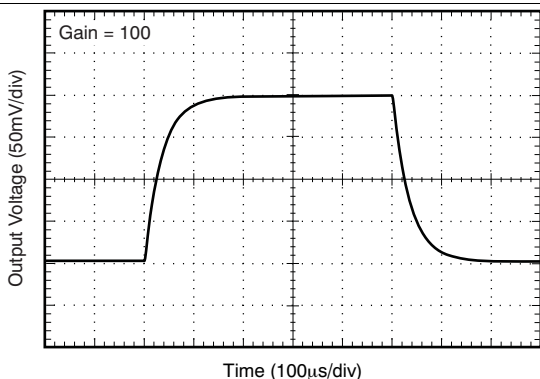


**Figure 12. Small-Signal Step Response**

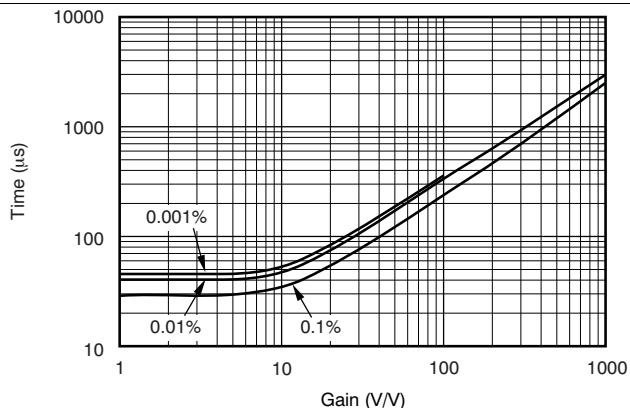


## Typical Characteristics (continued)

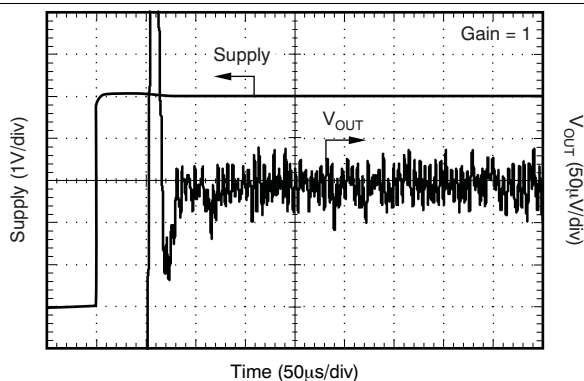
at  $T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{ V}$ ,  $R_L = 10\text{ k}\Omega$ ,  $V_{\text{REF}} = \text{midsupply}$ , and  $G = 1$  (unless otherwise noted)



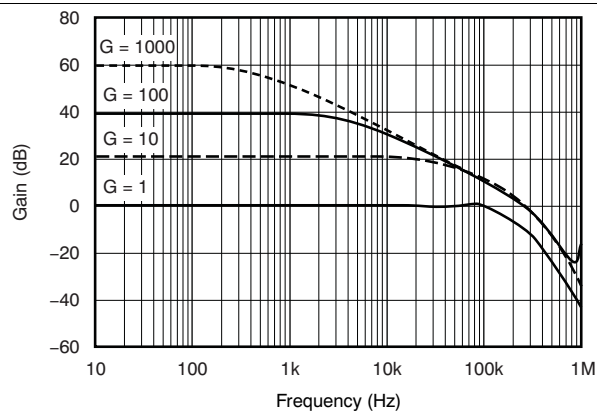
**Figure 13. Small-Signal Step Response**



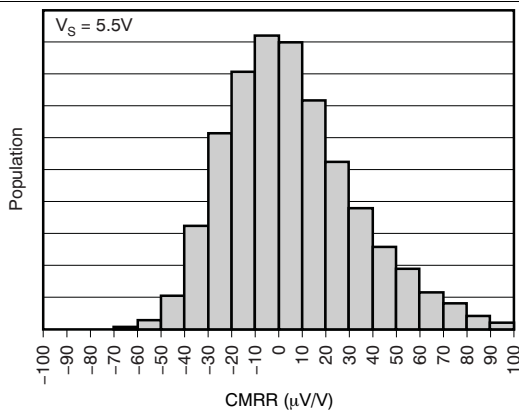
**Figure 14. Settling Time vs Gain**



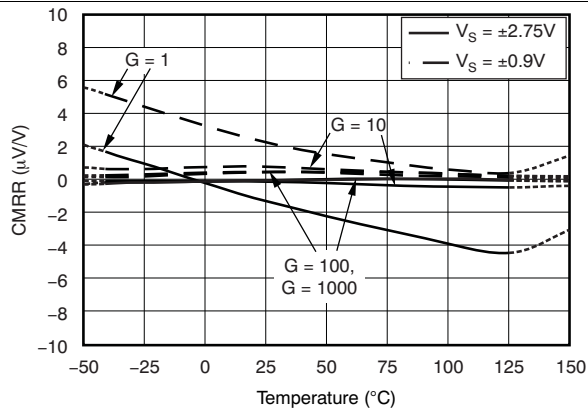
**Figure 15. Start-Up Settling Time**



**Figure 16. Gain vs Frequency**



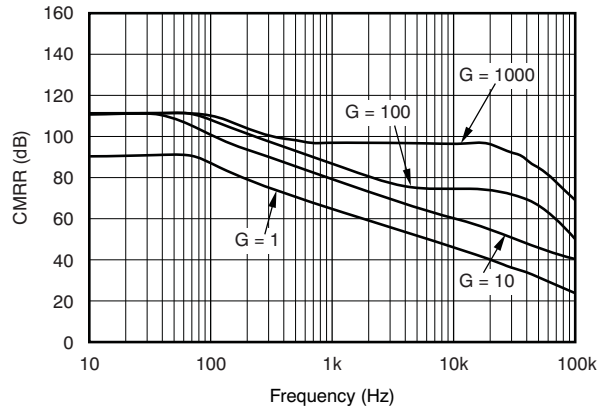
**Figure 17. Common-Mode Rejection Ratio**



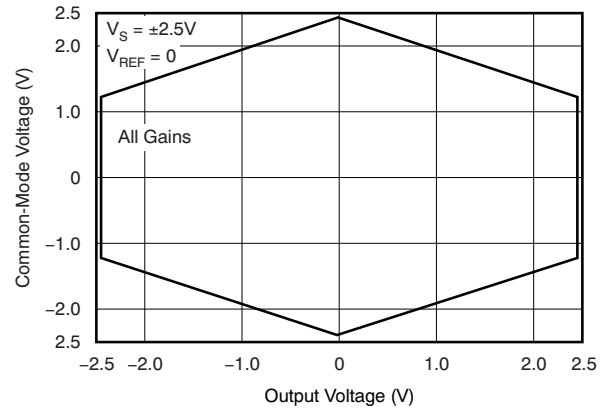
**Figure 18. Common-Mode Rejection Ratio vs Temperature**

## Typical Characteristics (continued)

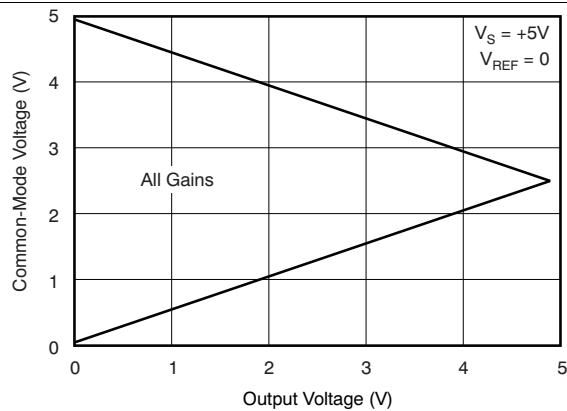
at  $T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{ V}$ ,  $R_L = 10\text{ k}\Omega$ ,  $V_{\text{REF}} = \text{midsupply}$ , and  $G = 1$  (unless otherwise noted)



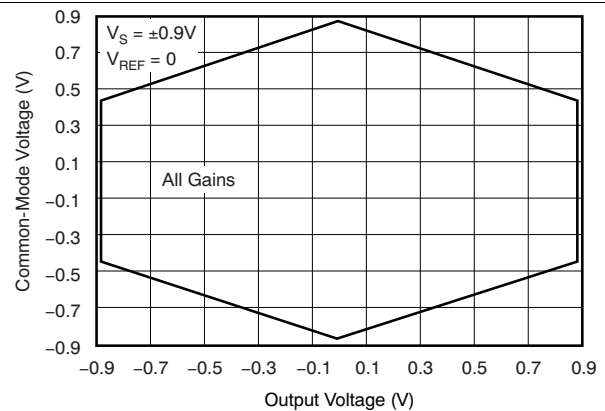
**Figure 19. Common-Mode Rejection Ratio vs Frequency**



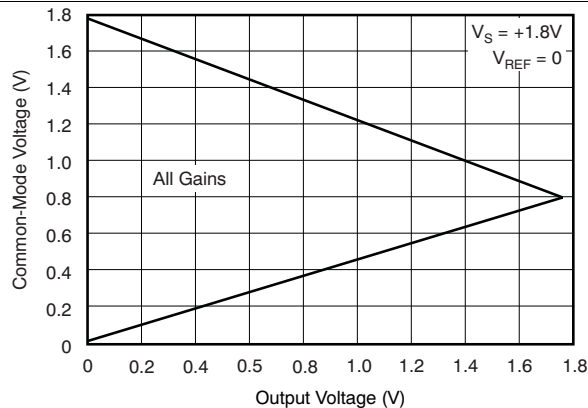
**Figure 20. Typical Common-Mode Range vs Output Voltage**



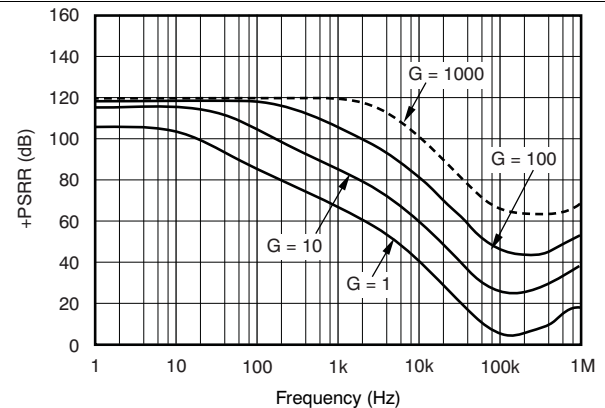
**Figure 21. Typical Common-Mode Range vs Output Voltage**



**Figure 22. Typical Common-Mode Range vs Output Voltage**



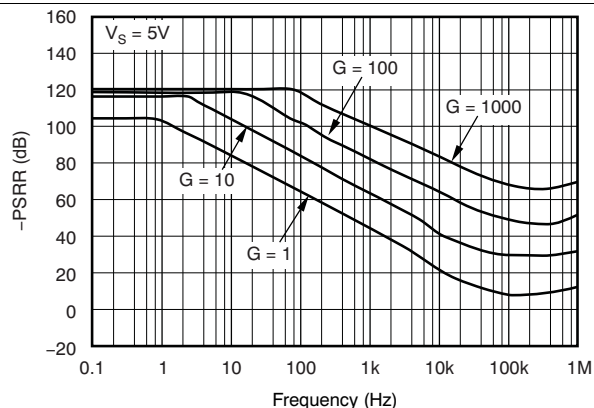
**Figure 23. Typical Common-Mode Range vs Output Voltage**



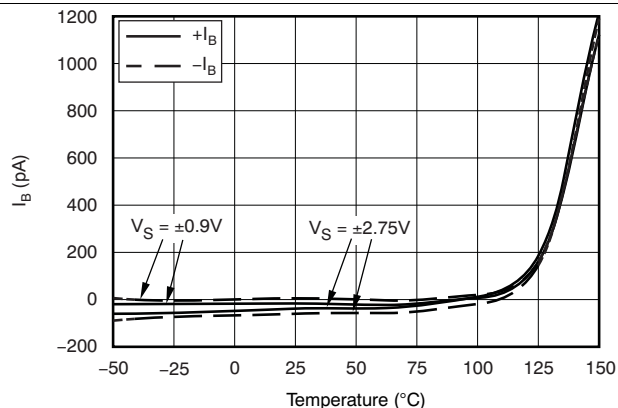
**Figure 24. Positive Power-Supply Rejection Ratio**

## Typical Characteristics (continued)

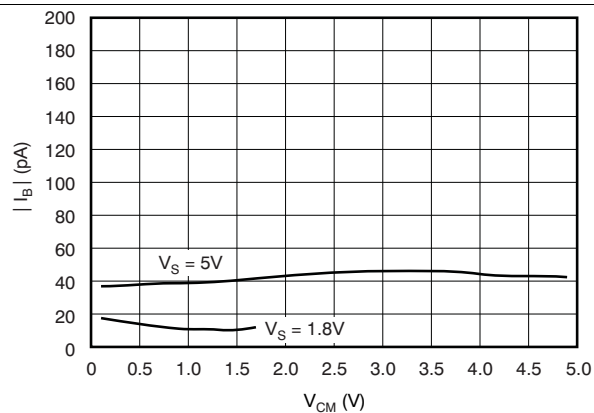
at  $T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{ V}$ ,  $R_L = 10\text{ k}\Omega$ ,  $V_{\text{REF}} = \text{mid supply}$ , and  $G = 1$  (unless otherwise noted)



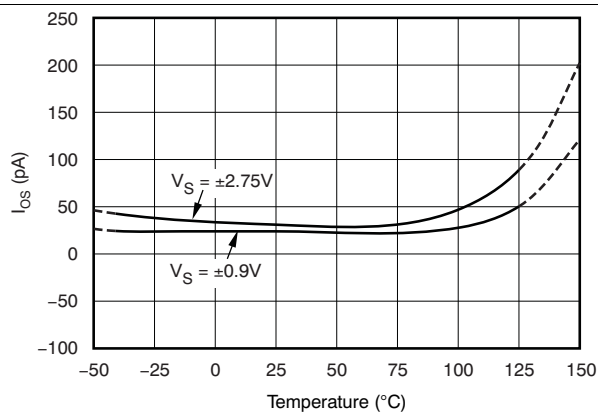
**Figure 25. Negative Power-Supply Rejection Ratio**



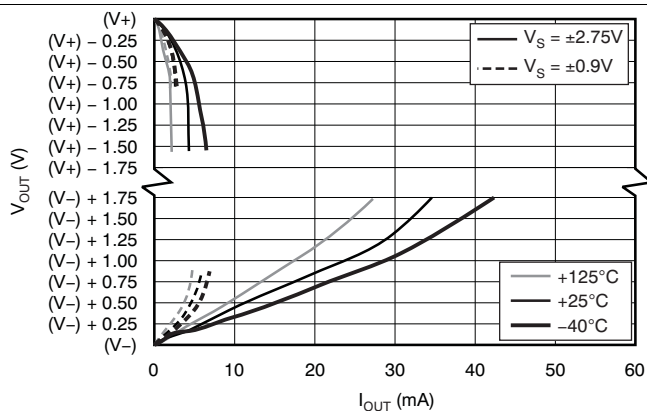
**Figure 26. Input Bias Current vs Temperature**



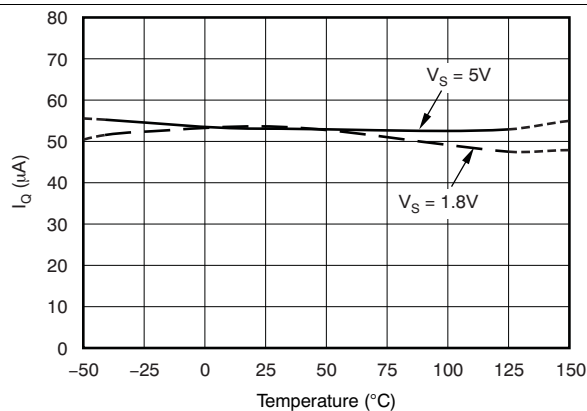
**Figure 27. Input Bias Current vs Common-Mode Voltage**



**Figure 28. Input Offset Current vs Temperature**



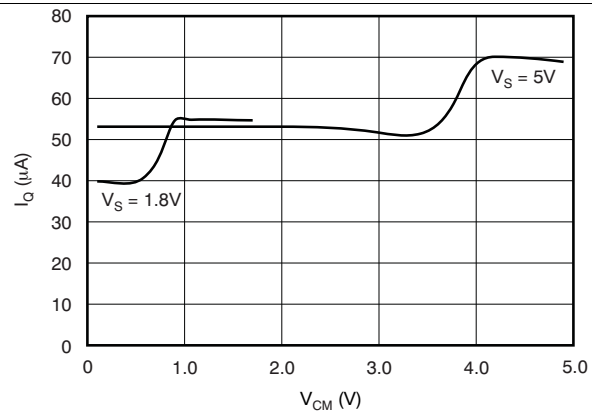
**Figure 29. Output Voltage Swing vs Output Current**



**Figure 30. Quiescent Current vs Temperature**

## Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{ V}$ ,  $R_L = 10\text{ k}\Omega$ ,  $V_{\text{REF}} = \text{midsupply}$ , and  $G = 1$  (unless otherwise noted)



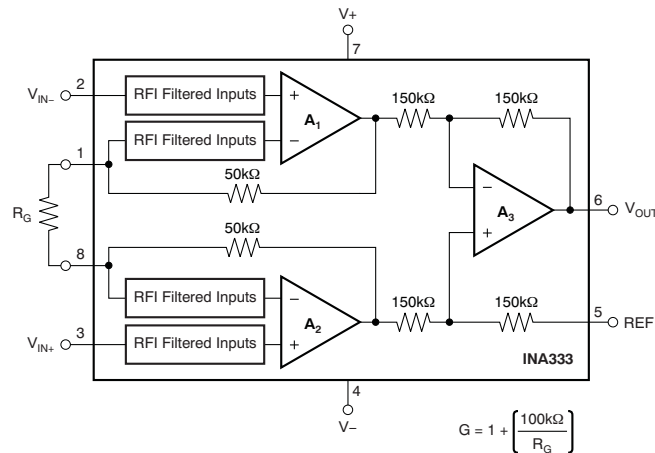
**Figure 31. Quiescent Current vs Common-Mode Voltage**

## 7 Detailed Description

### 7.1 Overview

The INA333 is a monolithic instrumentation amplifier (INA) based on the precision zero-drift OPA333 (operational amplifier) core. The INA333 also integrates laser-trimmed resistors to ensure excellent common-mode rejection and low gain error. The combination of the zero-drift amplifier core and the precision resistors allows this device to achieve outstanding DC precision and makes the INA333 ideal for many 3.3-V and 5-V industrial applications.

### 7.2 Functional Block Diagram



### 7.3 Feature Description

The INA333 is a low-power, zero-drift instrumentation amplifier offering excellent accuracy. The versatile three-operational-amplifier design and small size make the amplifiers ideal for a wide range of applications. Zero-drift chopper circuitry provides excellent DC specifications. A single external resistor sets any gain from 1 to 10,000. The INA333 is laser trimmed for very high common-mode rejection (100 dB at  $G \geq 100$ ). This device operates with power supplies as low as 1.8 V, and quiescent current of 50  $\mu$ A, typically.

### 7.4 Device Functional Modes

#### 7.4.1 Internal Offset Correction

INA333 internal operational amplifiers use an auto-calibration technique with a time-continuous 350-kHz operational amplifier in the signal path. The amplifier is zero-corrected every 8  $\mu$ s using a proprietary technique. Upon power up, the amplifier requires approximately 100  $\mu$ s to achieve specified VOS accuracy. This design has no aliasing or flicker noise.

#### 7.4.2 Input Common-Mode Range

The linear input voltage range of the input circuitry of the INA333 is from approximately 0.1 V below the positive supply voltage to 0.1 V above the negative supply. As a differential input voltage causes the output voltage to increase, however, the linear input range is limited by the output voltage swing of amplifiers A1 and A2. Thus, the linear common-mode input range is related to the output voltage of the complete amplifier. This behavior also depends on supply voltage—see [Figure 20](#).

Input overload conditions can produce an output voltage that appears normal. For example, if an input overload condition drives both input amplifiers to the respective positive output swing limit, the difference voltage measured by the output amplifier is near zero. The output of the INA333 is near 0 V even though both inputs are overloaded.

## 8 Application and Implementation

### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

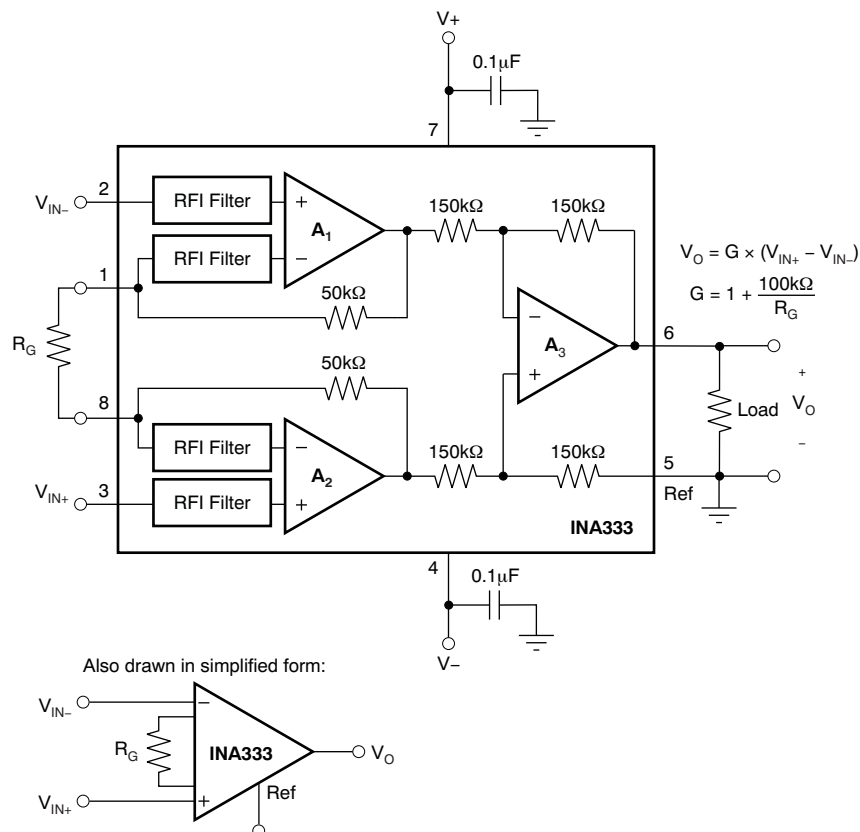
### 8.1 Application Information

The INA333 measures small differential voltage with high common-mode voltage developed between the noninverting and inverting input. The high input impedance makes the INA333 suitable for a wide range of applications. The ability to set the reference pin to adjust the functionality of the output signal offers additional flexibility that is practical for multiple configurations.

### 8.2 Typical Application

Figure 32 shows the basic connections required for operation of the INA333 device. Good layout practice mandates the use of bypass capacitors placed close to the device pins as shown.

The output of the INA333 device is referred to the output reference (REF) pin, which is normally grounded. This connection must be low-impedance to assure good common-mode rejection. Although 15  $\Omega$  or less of stray resistance can be tolerated while maintaining specified CMRR, small stray resistances of tens of  $\Omega$ s in series with the REF pin can cause noticeable degradation in CMRR.



**Figure 32. Basic Connections**

## Typical Application (continued)

### 8.2.1 Design Requirements

The device can be configured to monitor the input differential voltage when the gain of the input signal is set by the external resistor  $R_G$ . The output signal references to the Ref pin. The most common application is where the output is referenced to ground when no input signal is present by connecting the Ref pin to ground. When the input signal increases, the output voltage at the OUT pin increases, too.

### 8.2.2 Detailed Design Procedure

#### 8.2.2.1 Setting the Gain

Gain of the INA333 device is set by a single external resistor,  $R_G$ , connected between pins 1 and 8. The value of  $R_G$  is selected according to [Equation 1](#):

$$G = 1 + (100 \text{ k}\Omega / R_G) \quad (1)$$

[Table 1](#) lists several commonly-used gains and resistor values. The 100 k $\Omega$  in [Equation 1](#) comes from the sum of the two internal feedback resistors of  $A_1$  and  $A_2$ . These on-chip resistors are laser trimmed to accurate absolute values. The accuracy and temperature coefficient of these resistors are included in the gain accuracy and drift specifications of the INA333 device.

The stability and temperature drift of the external gain setting resistor,  $R_G$ , also affects gain. The contribution of  $R_G$  to gain accuracy and drift can be directly inferred from the gain [Equation 1](#). Low resistor values required for high gain can make wiring resistance important. Sockets add to the wiring resistance and contribute additional gain error (possibly an unstable gain error) in gains of approximately 100 or greater. To ensure stability, avoid parasitic capacitance of more than a few picofarads at the  $R_G$  connections. Careful matching of any parasitics on both  $R_G$  pins maintains optimal CMRR over frequency.

**Table 1. Commonly-Used Gains and Resistor Values**

DESIRED GAIN	$R_G$ ( $\Omega$ )	NEAREST 1% $R_G$ ( $\Omega$ )
1	NC <sup>(1)</sup>	NC
2	100k	100k
5	25k	24.9k
10	11.1k	11k
20	5.26k	5.23k
50	2.04k	2.05
100	1.01k	1k
200	502.5	499
500	200.4	200
1000	100.1	100

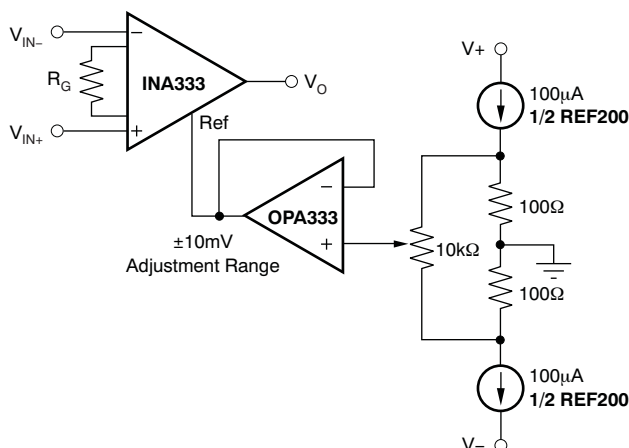
(1) NC denotes no connection. When using the SPICE model, the simulation will not converge unless a resistor is connected to the  $R_G$  pins; use a very large resistor value.

#### 8.2.2.2 Internal Offset Correction

The INA333 device internal operational amplifiers use an auto-calibration technique with a time-continuous 350-kHz operational amplifier in the signal path. The amplifier is zero-corrected every 8  $\mu$ s using a proprietary technique. Upon power-up, the amplifier requires approximately 100  $\mu$ s to achieve specified  $V_{OS}$  accuracy. This design has no aliasing or flicker noise.

#### 8.2.2.3 Offset Trimming

Most applications require no external offset adjustment; however, if necessary, adjustments can be made by applying a voltage to the REF pin. [Figure 33](#) shows an optional circuit for trimming the output offset voltage. The voltage applied to REF pin is summed at the output. The operational amplifier buffer provides low impedance at the REF pin to preserve good common-mode rejection.



**Figure 33. Optional Trimming of Output Offset Voltage**

#### 8.2.2.4 Noise Performance

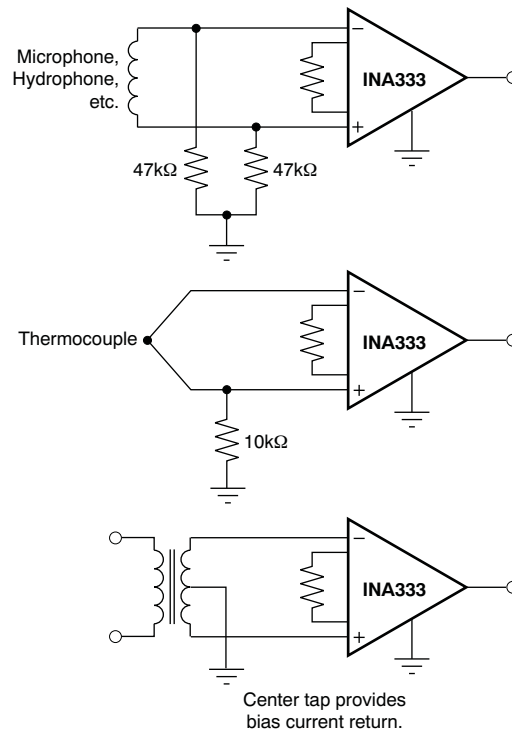
The auto-calibration technique used by the INA333 device results in reduced low frequency noise, typically only 50 nV/ $\sqrt{\text{Hz}}$ , ( $G = 100$ ). The spectral noise density can be seen in detail in [Figure 8](#). Low frequency noise of the INA333 device is approximately 1  $\mu\text{V}_{\text{PP}}$  measured from 0.1 Hz to 10 Hz, ( $G = 100$ ).

#### 8.2.2.5 Input Bias Current Return Path

The input impedance of the INA333 device is extremely high—approximately 100 G $\Omega$ . However, a path must be provided for the input bias current of both inputs. This input bias current is typically  $\pm 70$  pA. High input impedance means that this input bias current changes very little with varying input voltage.

Input circuitry must provide a path for this input bias current for proper operation. [Figure 34](#) shows various provisions for an input bias current path. Without a bias current path, the inputs float to a potential that exceeds the common-mode range of the INA333 device, and the input amplifiers will saturate. If the differential source resistance is low, the bias current return path can be connected to one input (see the thermocouple example in [Figure 34](#)). With higher source impedance, using two equal resistors provides a balanced input with possible advantages of lower input offset voltage as a result of bias current and better high-frequency common-mode rejection.





**Figure 34. Providing an Input Common-Mode Current Path**

#### 8.2.2.6 Input Common-Mode Range

The linear input voltage range of the input circuitry of the INA333 device is from approximately 0.1 V below the positive supply voltage to 0.1 V above the negative supply. As a differential input voltage causes the output voltage to increase, however, the linear input range is limited by the output voltage swing of amplifiers A<sub>1</sub> and A<sub>2</sub>. Thus, the linear common-mode input range is related to the output voltage of the complete amplifier. This behavior also depends on supply voltage—see Figure 20 to Figure 23 in the [Typical Characteristics](#) section.

Input overload conditions can produce an output voltage that appears normal. For example, if an input overload condition drives both input amplifiers to the respective positive output swing limit, the difference voltage measured by the output amplifier is near zero. The output of the INA333 is near 0 V even though both inputs are overloaded.

#### 8.2.2.7 Operating Voltage

The INA333 operates over a power-supply range of 1.8 V to 5.5 V (±0.9 V to ±2.75 V). Supply voltages higher than 7 V (absolute maximum) can permanently damage the device. Parameters that vary over supply voltage or temperature are shown in the [Typical Characteristics](#) section of this data sheet.

#### 8.2.2.8 Low Voltage Operation

The INA333 device can be operated on power supplies as low as ±0.9 V. Most parameters vary only slightly throughout this supply voltage range—see the [Typical Characteristics](#) section. Operation at very low supply voltage requires careful attention to assure that the input voltages remain within the linear range. Voltage swing requirements of internal nodes limit the input common-mode range with low power-supply voltage. [Figure 20](#) to [Figure 23](#) show the range of linear operation for various supply voltages and gains.

#### 8.2.2.9 Single-Supply Operation

The INA333 device can be used on single power supplies of 1.8 V to 5.5 V. [Figure 35](#) shows a basic single-supply circuit. The output REF pin is connected to mid-supply. Zero differential input voltage demands an output voltage of mid-supply. Actual output voltage swing is limited to approximately 50 mV more than ground, when the load is referred to ground as shown. [Figure 29](#) shows how the output voltage swing varies with output current.

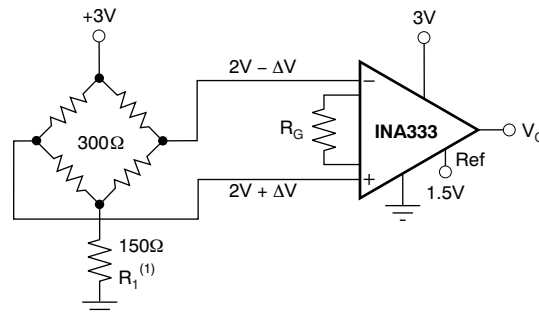
## INA333

SBOS445C – JULY 2008 – REVISED DECEMBER 2015

[www.ti.com](http://www.ti.com)

With single-supply operation,  $V_{IN+}$  and  $V_{IN-}$  must both be 0.1 V more than ground for linear operation. For instance, the inverting input cannot be connected to ground to measure a voltage connected to the noninverting input.

To show the issues affecting low voltage operation, consider the circuit in [Figure 35](#). It shows the INA333 device operating from a single 3-V supply. A resistor in series with the low side of the bridge assures that the bridge output voltage is within the common-mode range of the amplifier inputs.



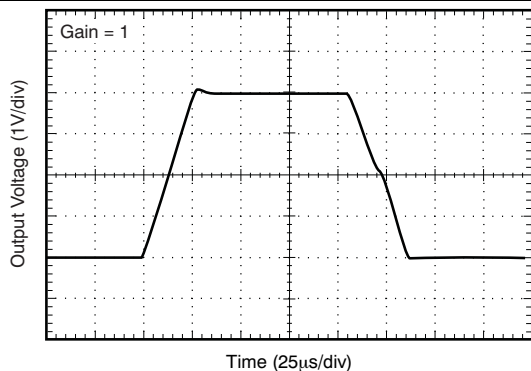
- (1)  $R_1$  creates proper common-mode voltage, only for low-voltage operation—see [Single-Supply Operation](#).

**Figure 35. Single-Supply Bridge Amplifier**

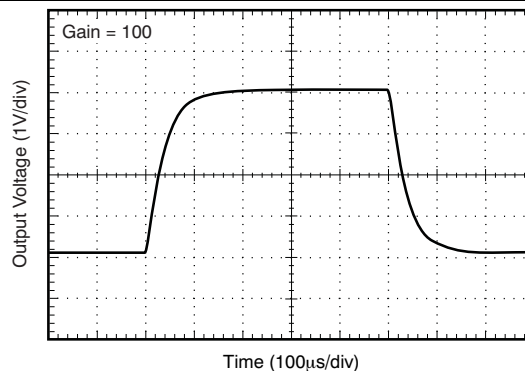
### 8.2.2.10 Input Protection

The input pins of the INA333 device are protected with internal diodes connected to the power-supply rails. These diodes clamp the applied signal to prevent it from damaging the input circuitry. If the input signal voltage can exceed the power supplies by more than 0.3 V, the input signal current should be limited to less than 10 mA to protect the internal clamp diodes. This current limiting can generally be done with a series input resistor. Some signal sources are inherently current-limited and do not require limiting resistors.

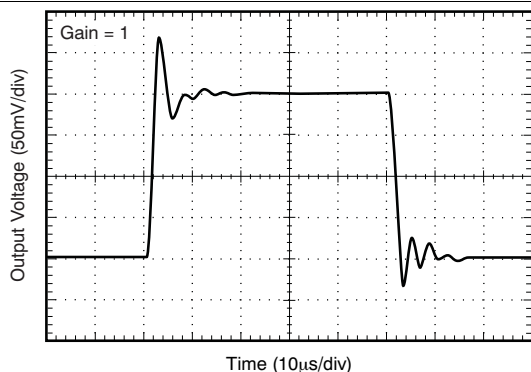
## 8.2.3 Application Curves



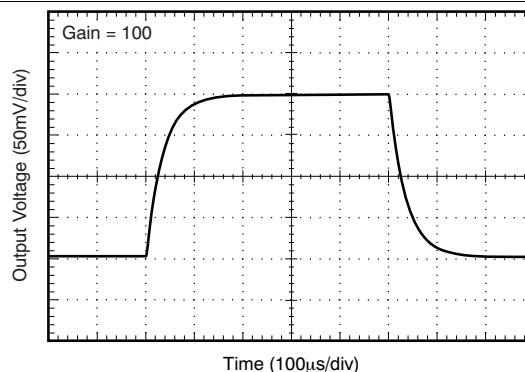
**Figure 36. Large Signal Response**



**Figure 37. Large-Signal Step Response**



**Figure 38. Small-Signal Step Response**



**Figure 39. Small-Signal Step Response**

## 9 Power Supply Recommendations

The minimum power supply voltage for INA333 is 1.8 V and the maximum power supply voltage is 5.5 V. For optimum performance, 3.3 V to 5 V is recommended. TI recommends adding a bypass capacitor at the input to compensate for the layout and power supply source impedance.



## 11 Device and Documentation Support

## 11.1 Device Support

### 11.1.1 Development Support

#### 11.1.1.1 TINA-TI (Free Download Software)

## Using TINA-TI SPICE-Based Analog Simulation Program with the INA333

TINA is a simple, powerful, and easy-to-use circuit simulation program based on a SPICE engine. TINA-TI is a free, fully functional version of the TINA software, preloaded with a library of macromodels in addition to a range of both passive and active models. It provides all the conventional DC, transient, and frequency domain analysis of SPICE as well as additional design capabilities.

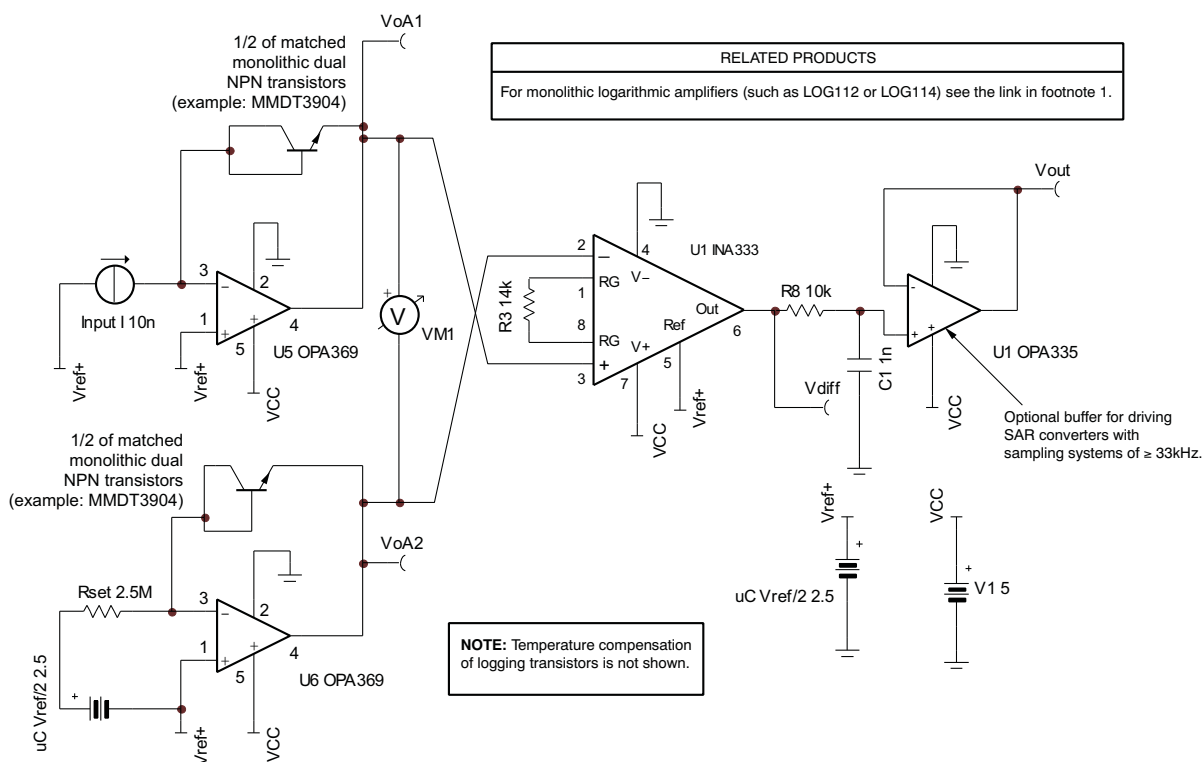
Available as a free download from the [Analog eLab Design Center](#), TINA-TI offers extensive post-processing capability that allows users to format results in a variety of ways.

Virtual instruments offer users the ability to select input waveforms and probe circuit nodes, voltages, and waveforms, creating a dynamic quick-start tool.

[Figure 41](#) and [Figure 42](#) show example TINA-TI circuits for the INA333 device that can be used to develop, modify, and assess the circuit design for specific applications. Links to download these simulation files are given below.

## NOTE

These files require that either the TINA software (from DesignSoft) or TINA-TI software be installed. Download the free TINA-TI software from the TINA-TI folder.



(1) The following link launches the TI logarithmic amplifiers web page: [Logarithmic Amplifier Products Home Page](#)

**Figure 41. Low-Power Log Function Circuit for Portable Battery-Powered Systems  
(Example Glucose Meter)**



## 11.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">INA333AIDGKR</a>	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU   NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	I333
INA333AIDGKR.A	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333
INA333AIDGKRG4	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333
<a href="#">INA333AIDGKT</a>	Active	Production	VSSOP (DGK)   8	250   SMALL T&R	Yes	NIPDAU   NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	I333
INA333AIDGKT.A	Active	Production	VSSOP (DGK)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333
INA333AIDGKTG4	Active	Production	VSSOP (DGK)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333
<a href="#">INA333AIDRGR</a>	Active	Production	SON (DRG)   8	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333A
INA333AIDRGR.A	Active	Production	SON (DRG)   8	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333A
INA333AIDRGRG4	Active	Production	SON (DRG)   8	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333A
INA333AIDRGRG4.A	Active	Production	SON (DRG)   8	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333A
<a href="#">INA333AIDRGT</a>	Active	Production	SON (DRG)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333A
INA333AIDRGT.A	Active	Production	SON (DRG)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	I333A

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.



**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**OTHER QUALIFIED VERSIONS OF INA333 :**

- Automotive : [INA333-Q1](#)

NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

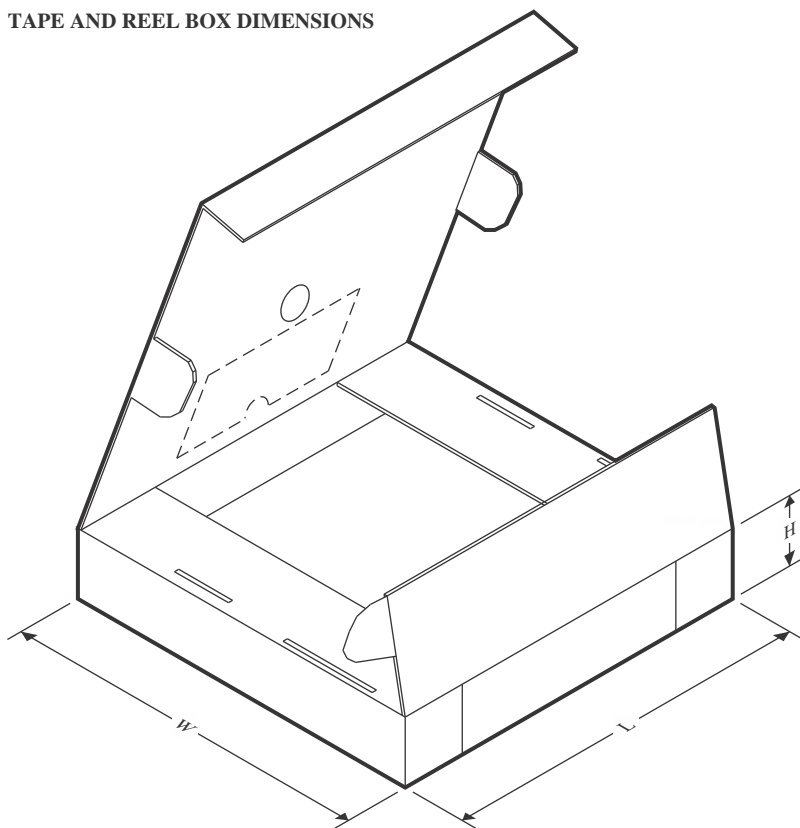
## TAPE AND REEL INFORMATION



\*All dimensions are nominal

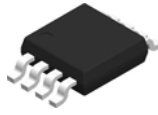
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
INA333AIDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA333AIDGKT	VSSOP	DGK	8	250	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA333AIDRGRG4	SON	DRG	8	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
INA333AIDRGT	SON	DRG	8	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2

## TAPE AND REEL BOX DIMENSIONS

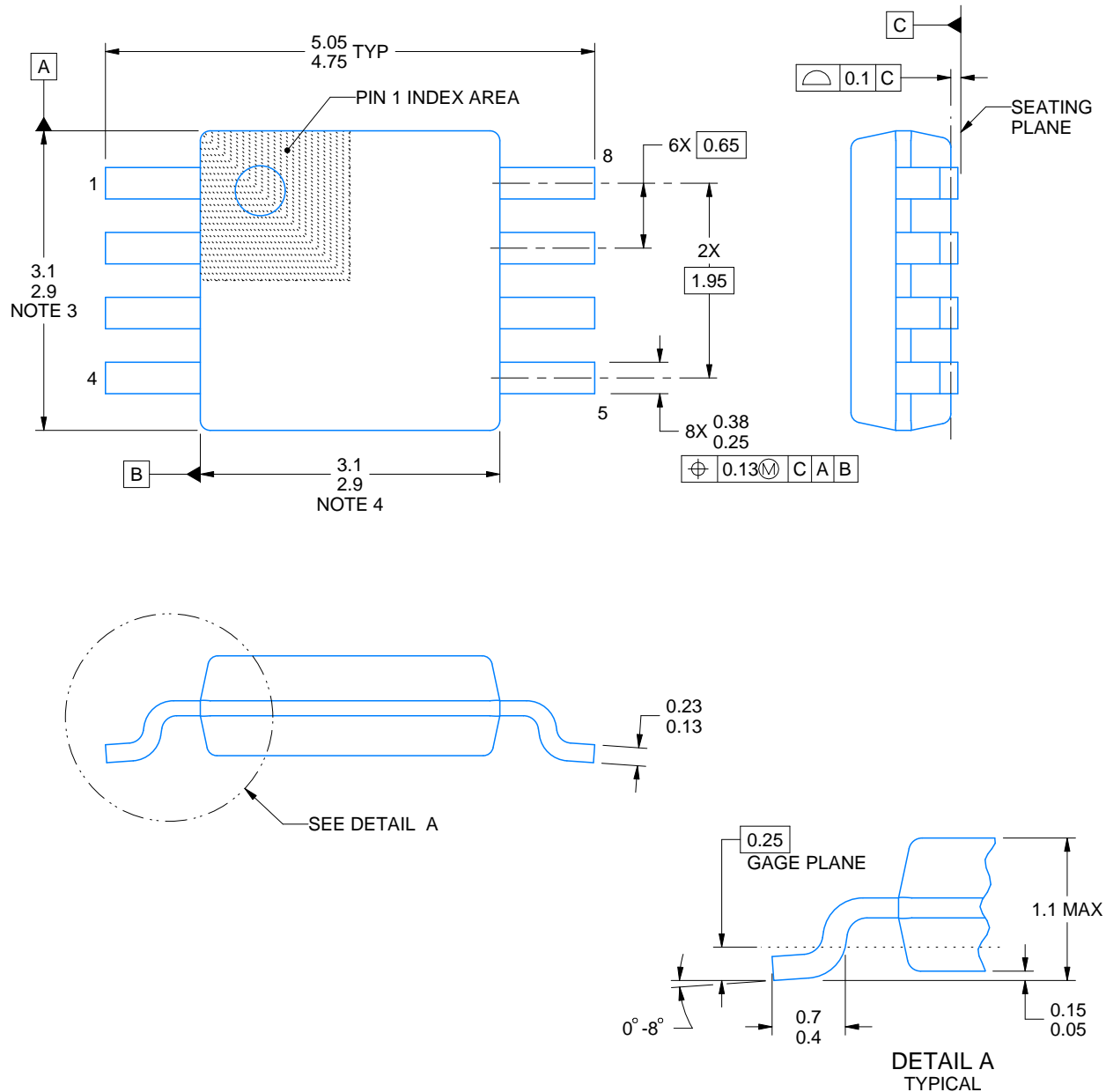


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
INA333AIDGKR	VSSOP	DGK	8	2500	366.0	364.0	50.0
INA333AIDGKT	VSSOP	DGK	8	250	366.0	364.0	50.0
INA333AIDRGRG4	SON	DRG	8	3000	353.0	353.0	32.0
INA333AIDRGT	SON	DRG	8	250	213.0	191.0	35.0

**DGK0008A****PACKAGE OUTLINE****VSSOP - 1.1 mm max height**

SMALL OUTLINE PACKAGE



4214862/A 04/2023

**NOTES:**

PowerPAD is a trademark of Texas Instruments.

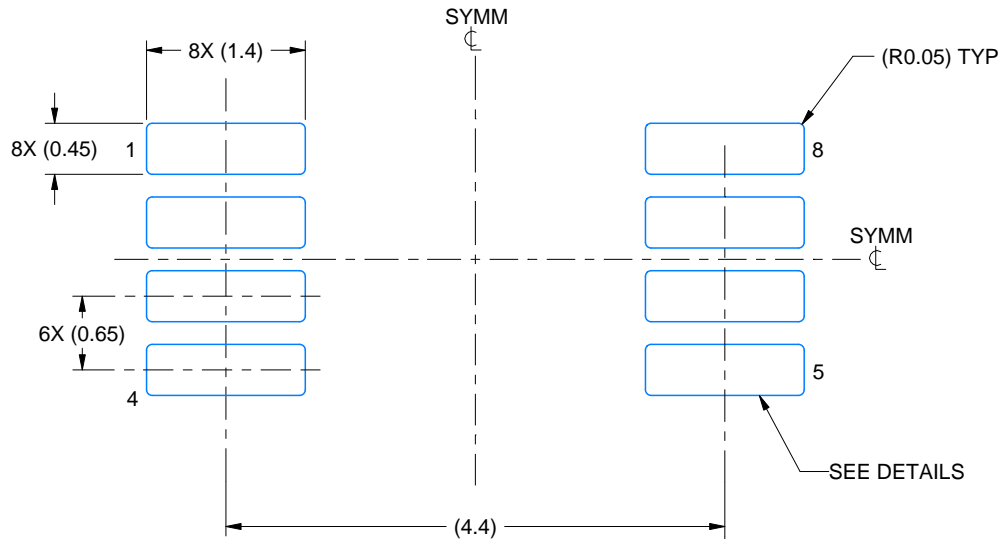
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
5. Reference JEDEC registration MO-187.

# EXAMPLE BOARD LAYOUT

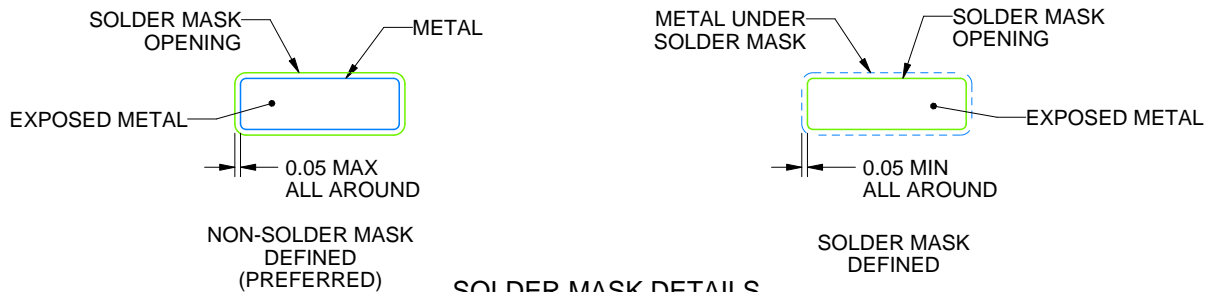
DGK0008A

™ VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE: 15X



SOLDER MASK DETAILS

4214862/A 04/2023

NOTES: (continued)

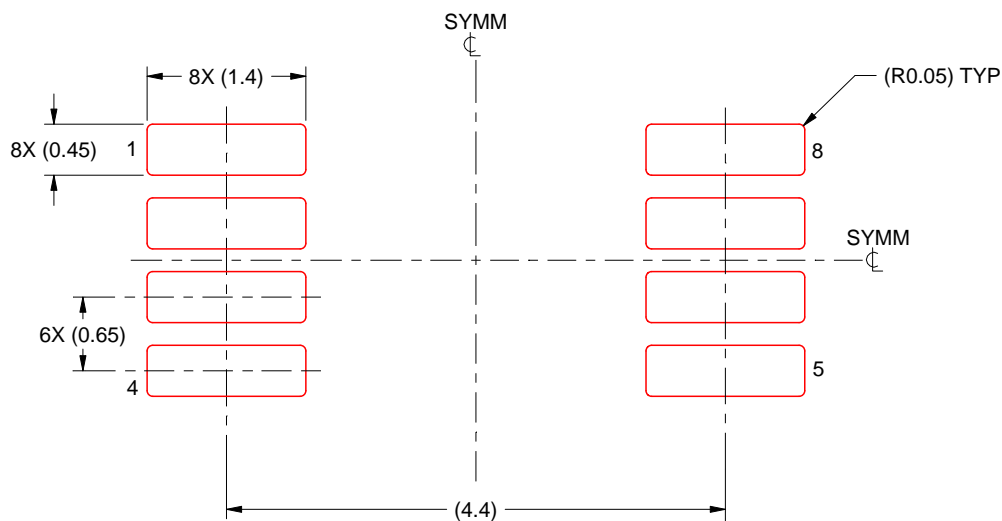
6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.
9. Size of metal pad may vary due to creepage requirement.

## EXAMPLE STENCIL DESIGN

DGK0008A

™ VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE



SOLDER PASTE EXAMPLE  
SCALE: 15X

4214862/A 04/2023

NOTES: (continued)

11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
12. Board assembly site may have different recommendations for stencil design.

## GENERIC PACKAGE VIEW

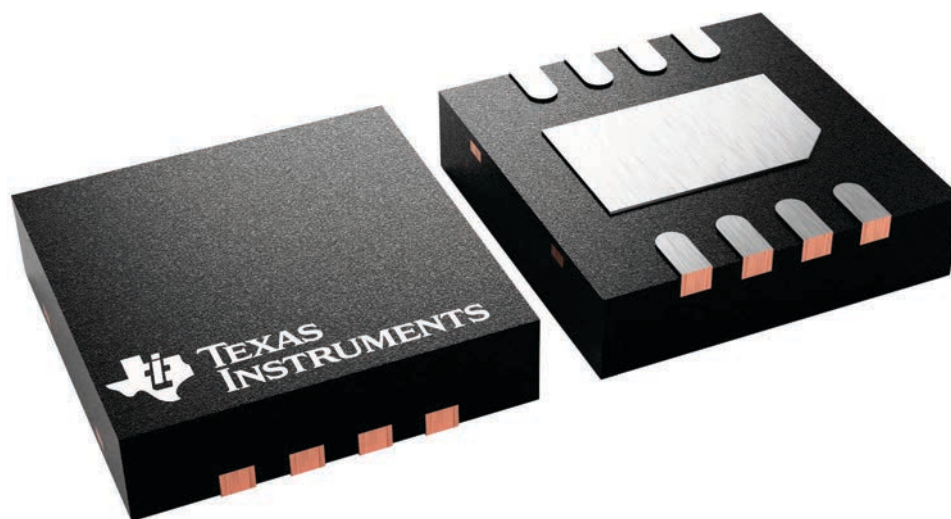
**DRG 8**

**WSON - 0.8 mm max height**

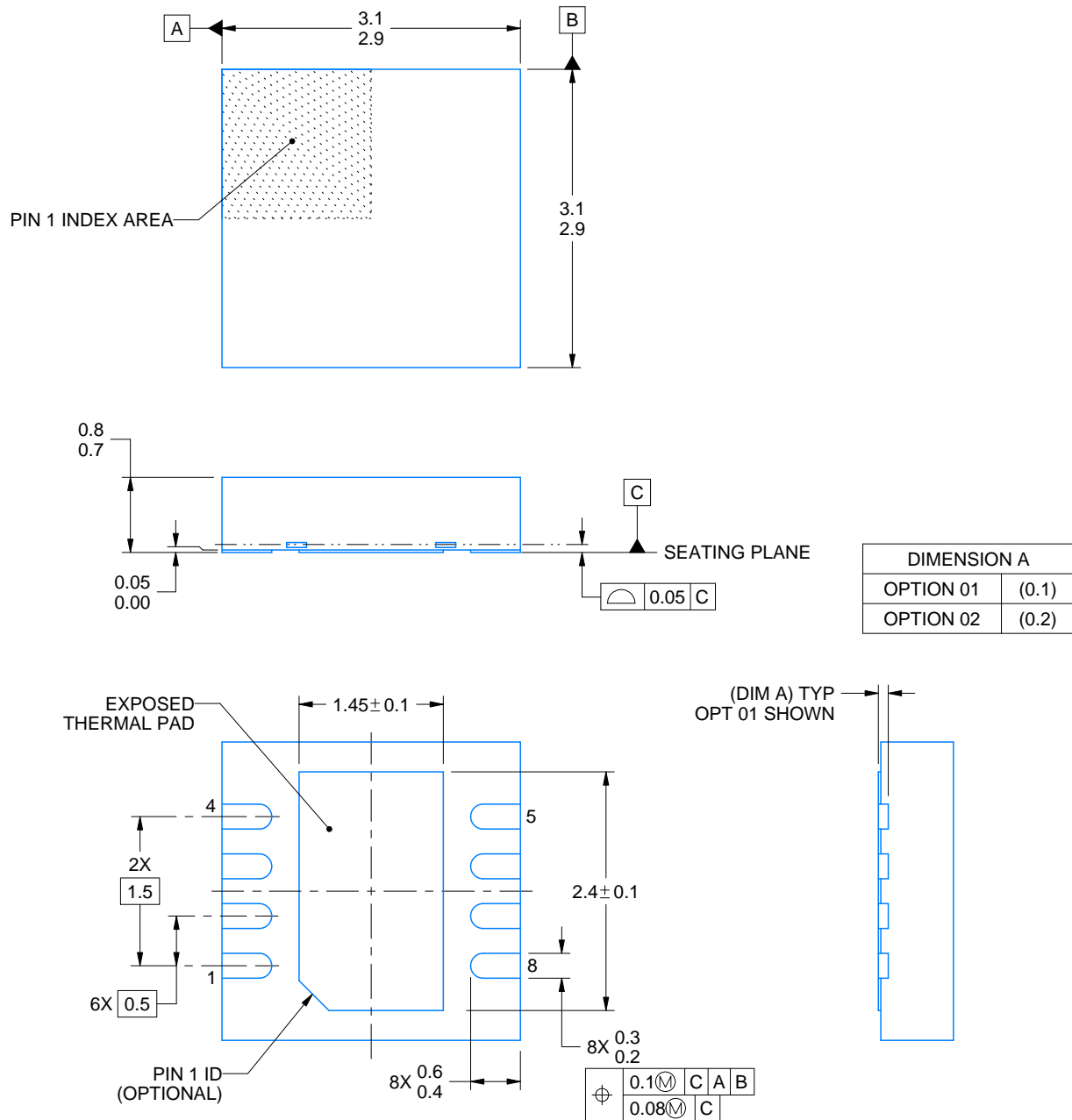
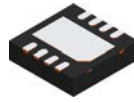
3 x 3, 0.5 mm pitch

PLASTIC SMALL OUTLINE - NO LEAD

This image is a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.



4225794/A



4218886/A 01/2020

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

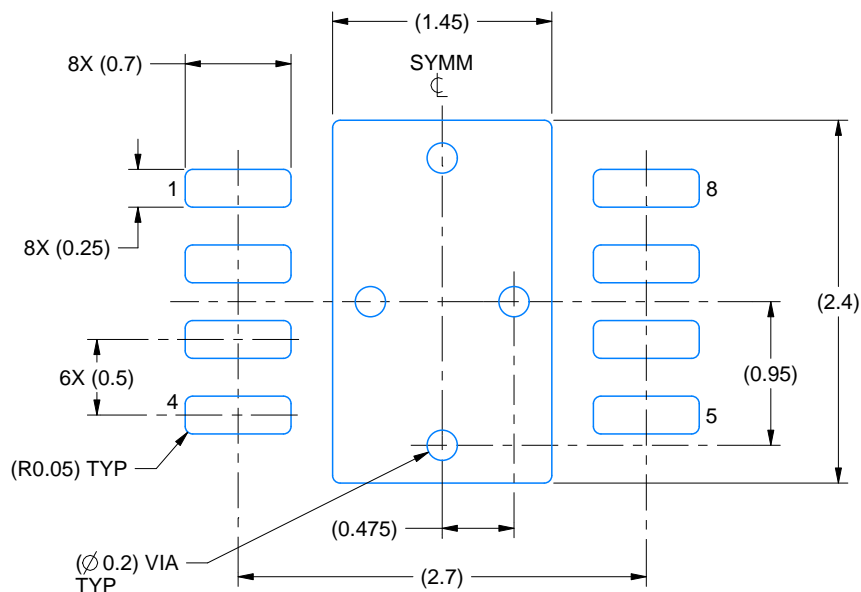


# EXAMPLE BOARD LAYOUT

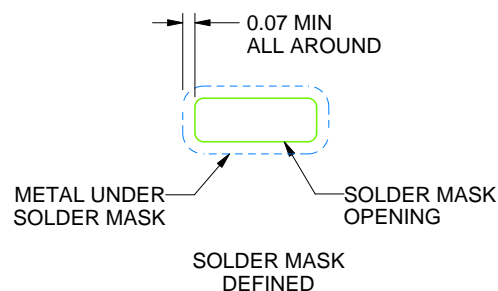
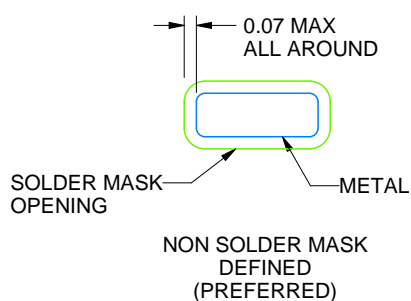
DRG0008B

WSN - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE  
SCALE:20X



SOLDER MASK DETAILS

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NOTES: (continued)

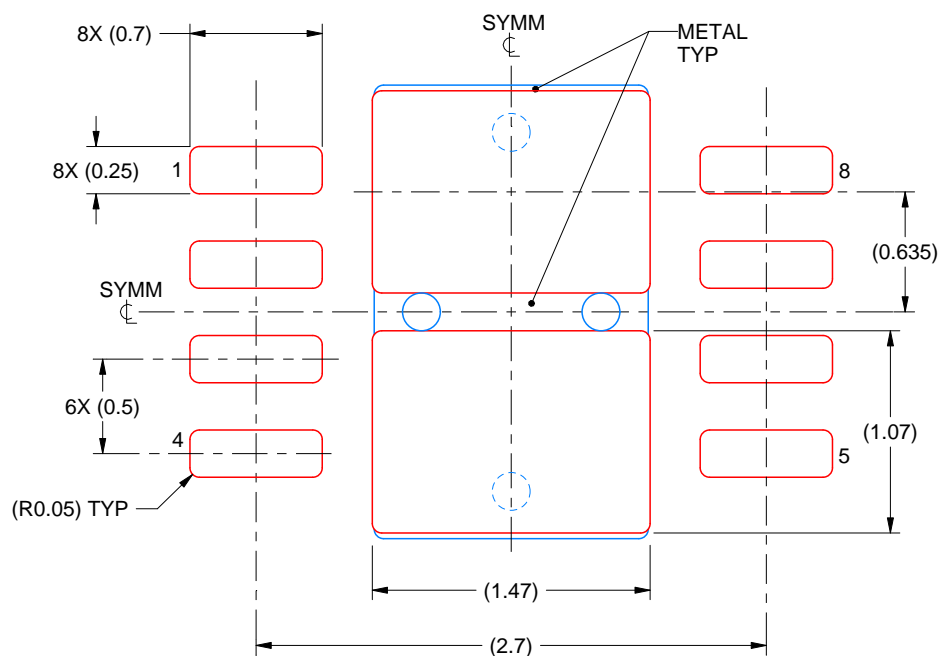
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/slue271](http://www.ti.com/lit/slue271)).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

# EXAMPLE STENCIL DESIGN

DRG0008B

WSN - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
EXPOSED PAD  
82% PRINTED SOLDER COVERAGE BY AREA  
SCALE:25X

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NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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