AI-lab1

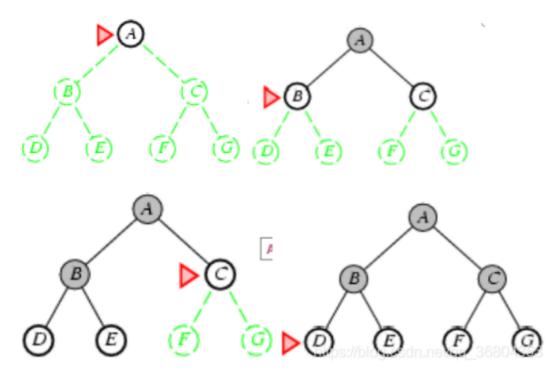
雷雨轩 PB18111791

Search

BFS

算法介绍

- 即宽度优先搜索,即从根节点开始扩展,接着扩展根节点的所有直接后继,然后在扩展这些直接后继的后继,依次类推。在下一层结点扩展前,搜索树上本层深度的结点都已扩展完毕
- 主要的实现思路是利用队列来实现,即FIFO,根节点最先进也最先扩展,然后依次出队的是直接后继,然后才是后继的后继。



• 书上伪代码

function BREADTH-FIRST-SEARCH(problem) returns a solution, or failure

```
node:- a node with STATE = problem.INITIAL-STATE, PATH-COST = 0
if problem.GOAL-TEST(node.STATE) then return SOLUTION(node)
frontier -- a FIFO queue with node as the only element
explored -- an empty set
loop do

if EMPTY?(frontier) then return failure
node -- POP(frontier) /* chooses the shallowest node in frontier */
add node.STATE to explored
for each action in problem.ACTIONS(node.STATE) do
child -- CHILD-NODE(problem, node, action)
if child.STATE is not in explored or frontier then
if problem.GOAL-TEST(child.STATE) then return SOLUTION(child)
frontier -- INSERT(child, frontier)
```

• 宽度优先搜索是完备的

- 若可以找到目标节点,那么一定是最浅的目标节点,最浅的目标节点不一定就是目标节点。如果路径是非递减函数,宽度搜索是最优的
- 时间复杂度:结点后继为b个,树深度为d,则最坏为 $b+b^2+\ldots+b^d=O(b^d)$
- 空间复杂度:假定是把所有已扩展的结点都作保存,所以复杂度仍为 $O(b^d)$,由边缘结点集决定

实验过程

• 实现思路比较简单,而且以前程序设计也写过类似的代码,所以只需要清楚实验所提供的接口,即可轻松实现

```
def myBreadthFirstSearch(problem):
   # YOUR CODE HERE
   visited={}
   Queue=util.Queue() #BFS需要用队列
   Queue.push((problem.getStartState(),None))
   while not Queue.isEmpty():
       state , prev_state = Queue.pop()
       if problem.isGoalState(state):#已到达目标结点
           solution = [state]
           while prev_state != None:
               solution.append(prev_state)
               prev_state = visited[prev_state]
           return solution[::-1]
       if state not in visited:#如果该结点没访问,则访问该结点,并把其邻居全部入队
           visited[state]=prev_state
           for next_state,step_cost in problem.getChildren(state):
               Queue.push((next_state,state))
    return []
```

• 代码与DFS非常相似,唯一不同的地方在于,BFS用的是队列,而DFS用的是栈,所以结点访问次序 有区别

A*

算法介绍

- A*算法的评价函数为: f(n)=g(n)+h(n),即同时计算了开始结点到当前结点已花费的代价,以及从当前结点到目标结点的估计代价
- 若想找到最小代价的解,扩展最小的f(n)是合理的,所以A*算法完备且最优
- 保证最优性的条件:可采纳性和一致性
 - 。 若h(n)可采纳,则A*的树搜索版本是最优的
 - 若h(n)一致,则A*的图搜索算法是最优的

实验过程

• 因为存在f(n)值的比较,所以考虑采用优先队列,队列中存放的元素为((state,prev_state,cost),f(n))

代码如下

```
def myAStarSearch(problem, heuristic):
    # YOUR CODE HERE
```

```
visited={}#维护每个状态的前驱结点
   pq=util.PriorityQueue()
   start_state=problem.getStartState()
   cur_cost=0#记录从初始状态出发,到当前结点的总代价
   pq.update((start_state, None, 0), 0+heuristic(start_state))
   while not pq.isEmpty():
       state,prev_state,cur_cost=pq.pop()
       if problem.isGoalState(state):#是目标结点,则返回其路径
           solution = [state]
           while prev_state is not None:
               solution.append(prev_state)
               prev_state = visited[prev_state]
           return solution[::-1]
       if state not in visited:
           visited[state]=prev_state
           for next_state,step_cost in problem.getChildren(state):
               next_cost=cur_cost+step_cost
pq.update((next_state, state, next_cost), next_cost+heuristic(next_state))
   return []
```

- 思路大致为,对每一次出队的元素
 - 。 若为目标结点,则根据visited字典以及prev_state进行回溯,得到结果
 - o 否则,若该状态尚未访问,那么标记为已访问,并且遍历其直接邻居,每个邻居n的f(n)值计算公式即 cur_cost+step_cost+heuristic(next_state)

结果分析

• BFS测试结果:

```
(ustc-ai) D:\科大\大三下\人工智能基础\lab\LAB1\search>python autograder.py -q q2
Starting on 5-28 at 21:59:56
Question q2
========
*** PASS: test_cases\q2\graph_backtrack.test
*** solution: ['1:A->C', '0:C->G']

*** expanded_states: ['A', 'B', 'C', 'D']
*** PASS: test_cases\q2\graph_bfs_vs_dfs.test
*** solution: ['1:A->G']

*** expanded_states: ['A', 'B']
*** PASS: test_cases\q2\graph_infinite.test
*** solution: ['0:A->B', '1:B->C', '1:C->G']

*** expanded_states: ['A', 'B', 'C']
*** PASS: test_cases\q2\graph_manypaths.test
       solution: ['1:A->C', '0:C->D', '1:D->F', '0:F->G']
expanded_states: ['A', 'B1', 'C', 'B2', 'D', 'E1', 'F', 'E2']
*** solution:
*** PASS: test_cases\q2\pacman_1.test
*** pacman layout: mediumMaze

*** solution length: 68
***
                                 269
      nodes expanded:
### Question q2: 4/4 ###
Finished at 21:59:56
Provisional grades
==========
Question q2: 4/4
Total: 4/4
Your grades are NOT yet registered. To register your grades, make sure
to follow your instructor's guidelines to receive credit on your project.
```

A*测试结果:

```
(ustc-ai) D:\科大\大三下\人工智能基础\lab\LAB1\search>python autograder.py -q q3
Starting on 5-28 at 22:01:52
Question q3
========
*** PASS: test_cases\q3\astar_0.test
*** solution: ['Right', 'Down', 'Down']

*** expanded_states: ['A', 'B', 'D', 'C', 'G']

*** PASS: test_cases\q3\astar_1_graph_heuristic.test

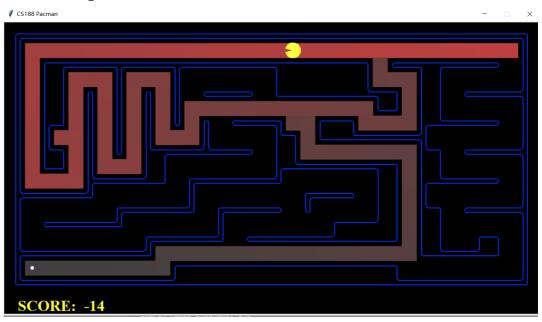
*** solution:
        solution: ['0', '0', '2'] expanded_states: ['S', 'A', 'D', 'C']
***
        solution:
***
*** PASS: test_cases\q3\astar_2_manhattan.test
***
       pacman layout:
                                    mediumMaze
        solution length: 68
***
        nodes expanded:
                                     221
*** PASS: test_cases\q3\astar_3_goalAtDequeue.test
                                     ['1:A->B', '0:B->C', '0:C->G']
['A', 'B', 'C']
***
        expanded_states:
*** PASS: test_cases\q3\graph_backtrack.test
                                     ['1:A->C', '0:C->G']
['A', 'B', 'C', 'D']
***
        expanded_states:
        solution:
***
*** PASS: test_cases\q3\graph_manypaths.test
                                    ['1:A->C', '0:C->D', '1:D->F', '0:F->G']
['A', 'B1', 'C', 'B2', 'D', 'E1', 'F', 'E2']
       solution:
       expanded_states:
### Question q3: 4/4 ###
Finished at 22:01:52
Provisional grades
===========
Question q3: 4/4
Total: 4/4
```

- DFS, BFS, A*结果比较
 - DFS

Path found with total cost of 130 in 0.0 seconds

Search nodes expanded: 146

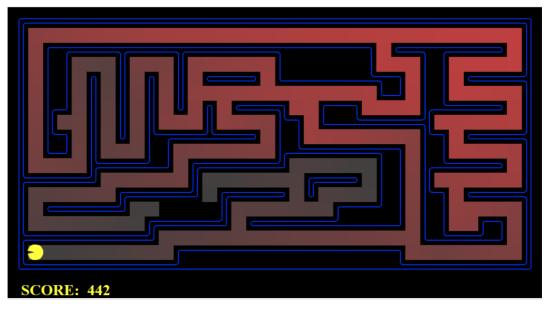
Pacman emerges victorious! Score: 380



Path found with total cost of 68 in 0.0 seconds

Search nodes expanded: 269

Pacman emerges victorious! Score: 442

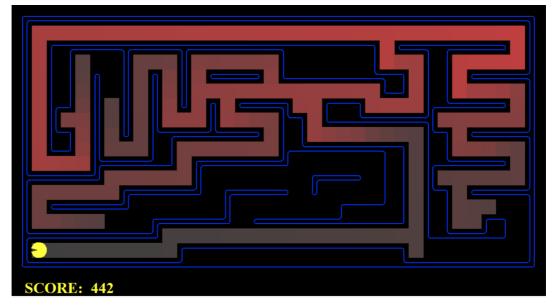


o A*

Path found with total cost of 68 in 0.0 seconds

Search nodes expanded: 221

Pacman emerges victorious! Score: 442



对比结果发现,BFS扩展的结点最少,但是走了最长、最深的路径;BFS则是访问了最多的结点,重复路径较多; A*做过的路径数在BFS和DFS之间,并且在测试里,A *扩展了更少的结点就获得了和BFS一样的分数及cost

Multiagent

minimax

算法介绍

• minimax算法的前提是双方都是做最优决策

```
function MINIMAX-DECISION(state) returns an action return arg \max_{a \in ACTIONS(s)} Min-Value(Result(state, a))
```

```
function MAX-VALUE(state) returns a utility value if TERMINAL-TEST(state) then return UTILITY(state) v \leftarrow -\infty for each a in ACTIONS(state) do v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(\text{RESULT}(s, a))) return v
```

```
function MIN-VALUE(state) returns a utility value if TERMINAL-TEST(state) then return UTILITY(state) v \leftarrow \infty for each a in ACTIONS(state) do v \leftarrow \text{MIN}(v, \text{MAX-VALUE}(\text{RESULT}(s, a))) return v
```

可知,算法的核心即递归调用:要求当前结点的极小极大值,则要求当前结点所有后继的极小极大值,并根据当前结点是MAX还是MIN来取后继的极小极大值中的max还是min

- 时间复杂度: $O(b^m)$, 后继为b个, 深度为m
- 空间复杂度: O(bm) 或 O(m), 取决于一次性生成所有后继还是每次生成一个后继

实验过程

- 实现的思路
 - 。 若为终止态,则返回效用值
 - 。 若当前为吃豆人并且depth=0,也返回当前状态和效用值,相当于depth限制了每次探索的深度,一个深度以pacman起始,到下一次轮到pacman之前。
 - o 否则,则遍历所有子结点,若当前结点为pacman,即MAX结点,则取孩子节点里minimax值最大的那个结点及分数。若为ghost结点,即MIN结点,则取孩子结点里minimax值最小的那个结点及分数。
- 代码:

```
def minimax(self, state, depth):#depth是算法搜索的深度
       if state.isTerminated():
           return None, state.evaluateScore()
        if state.isMe() and depth == 0:#即算法已经不允许继续往下搜索了
           return state, state.evaluateScore()
       best_state, best_score = None, -float('inf') if state.isMe() else
float('inf')
       if state.isMe():
           depth = depth - 1
        for child in state.getChildren():
           # YOUR CODE HERE
           _,cur_score = self.minimax(child,depth)
           #对于pacman,要求max
           if state.isMe():
               if best_score<cur_score:</pre>
                   best_score=cur_score
                   best_state=child
```

```
else:#对ghost, 要min

if best_score>cur_score:

    best_score=cur_score

    best_state=child

return best_state, best_score
```

结果分析

```
Question q2
========
*** PASS: test cases\q2\0-eval-function-lose-states-1.test
*** PASS: test_cases\q2\0-eval-function-lose-states-2.test
*** PASS: test cases\q2\0-eval-function-win-states-1.test
*** PASS: test_cases\q2\0-eval-function-win-states-2.test
*** PASS: test cases\q2\0-lecture-6-tree.test
*** PASS: test_cases\q2\0-small-tree.test
*** PASS: test_cases\q2\1-1-minmax.test
*** PASS: test_cases\q2\1-2-minmax.test
*** PASS: test cases\q2\1-3-minmax.test
*** PASS: test cases\q2\1-4-minmax.test
*** PASS: test_cases\q2\1-5-minmax.test
*** PASS: test_cases\q2\1-6-minmax.test
*** PASS: test_cases\q2\1-7-minmax.test
*** PASS: test cases\q2\1-8-minmax.test
*** PASS: test_cases\q2\2-1a-vary-depth.test
*** PASS: test cases\q2\2-1b-vary-depth.test
*** PASS: test_cases\q2\2-2a-vary-depth.test
*** PASS: test_cases\q2\2-2b-vary-depth.test
*** PASS: test cases\q2\2-3a-vary-depth.test
*** PASS: test_cases\q2\2-3b-vary-depth.test
*** PASS: test_cases\q2\2-4a-vary-depth.test
*** PASS: test cases\q2\2-4b-vary-depth.test
*** PASS: test cases\q2\2-one-ghost-3level.test
*** PASS: test_cases\q2\3-one-ghost-4level.test
*** PASS: test_cases\q2\4-two-ghosts-3level.test
*** PASS: test cases\q2\5-two-ghosts-4level.test
*** PASS: test_cases\q2\6-tied-root.test
*** PASS: test_cases\q2\7-1a-check-depth-one-ghost.test
*** PASS: test_cases\q2\7-1b-check-depth-one-ghost.test
*** PASS: test_cases\q2\7-1c-check-depth-one-ghost.test
*** PASS: test_cases\q2\7-2a-check-depth-two-ghosts.test
*** PASS: test_cases\q2\7-2b-check-depth-two-ghosts.test
*** PASS: test_cases\q2\7-2c-check-depth-two-ghosts.test
```

```
*** Running MinimaxAgent on smallClassic 1 time(s).
Pacman died! Score: 84
Average Score: 84.0
Scores: 84.0
Win Rate: 0/1 (0.00)
Record:
Record:
              Loss
*** Finished running MinimaxAgent on smallClassic after 0 seconds.
*** Won 0 out of 1 games. Average score: 84.000000 ***
*** PASS: test_cases\q2\8-pacman-game.test
### Question q2: 5/5 ###
Finished at 22:29:54
Provisional grades
===========
Question q2: 5/5
Total: 5/5
Your grades are NOT yet registered. To register your grades, make sure
to follow your instructor's guidelines to receive credit on your project.
```

alpha-beta剪枝

算法介绍

- 在minimax算法的基础上,尽可能根据已知信息消除部分搜索树(即剪枝),即剪掉那些不可能影响决策的分支,在返回相同的结果的前提下减少搜索空间,提高效率
- alpha-beta剪枝的效率很大程度上依赖于检查后继状态的顺序
- 伪代码:

function ALPHA-BETA-SEARCH(state) returns an action $v \leftarrow \text{MAX-VALUE}(state, -\infty, +\infty)$ return the action in ACTIONS(state) with value v

```
function MAX-VALUE(state, \alpha, \beta) returns a utility value if TERMINAL-TEST(state) then return UTILITY(state) v \leftarrow -\infty for each a in ACTIONS(state) do v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(\text{RESULT}(s, a), \alpha, \beta)) if v \geq \beta then return v \alpha \leftarrow \text{MAX}(\alpha, v) return v
```

```
function MIN-VALUE(state, \alpha, \beta) returns a utility value if TERMINAL-TEST(state) then return UTILITY(state) v \leftarrow +\infty for each a in ACTIONS(state) do v \leftarrow \text{MIN}(v, \text{MAX-VALUE}(\text{RESULT}(s,a), \alpha, \beta)) if v \leq \alpha then return v \beta \leftarrow \text{MIN}(\beta, v) return v
```

实验过程

代码如下

```
class MyAlphaBetaAgent():
    def __init__(self, depth):
        self.depth = depth
    def alphabeta_cut(self, state, depth, alpha, beta):
        if state.isTerminated():
            return None, state.evaluateScore()
        if state.isMe() and depth == 0:
            return state, state.evaluateScore()
        best_state, best_score = None, -float('inf') if state.isMe() else
float('inf')
        if state.isMe():
            depth=depth-1
        for child in state.getChildren():
            _,cur_score = self.alphabeta_cut(child,depth,alpha,beta)
            if state.isMe():
                if cur_score>beta:
                     return child, cur_score
                alpha=max(cur_score,alpha)
                if best_score<cur_score:</pre>
                    best_score=cur_score
                    best_state=child
            else:
```

```
if cur_score<alpha:
    return child,cur_score
    beta=min(cur_score,beta)
    if best_score>cur_score:
        best_score=cur_score
        best_state=child
    return best_state,best_score

def getNextState(self, state):
    # YOUR CODE HERE
    alpha=-float('inf')#当前为止发现的MAX的最佳值选择
    beta=float('inf')#当前为止发现的MIN结点的最佳选择
    best_state,best_score=self.alphabeta_cut(state, self.depth, alpha,beta)
    return best_state
```

- 这部分的关键即是要理解对当前节点的所有子结点的遍历逻辑
 - o 对每个子结点调用alpha-beta剪枝算法获得其minimax值,即为value
 - 如果当前是pacman,并且该value>beta,那么需要剪枝,因为pacman的上一层的MIN 节点肯定不会选它,而更倾向于选beta的值。所以pacman结点剩下的子结点也不必再 探索。

否则根据值来更新alpha和当前最优状态、效用值

■ 如果当前是Ghost,并且value<alpha,那么需要剪枝,因为ghost的上一层的MAX节点肯定不会选它,而更倾向于选alpha的值。所以Ghost结点剩下的子结点也不必再探索否则根据值来更新beta和当前最优状态、效用值

结果分析

```
Question q3
=======
*** PASS: test cases\q3\0-eval-function-lose-states-1.test
*** PASS: test cases\q3\0-eval-function-lose-states-2.test
*** PASS: test cases\q3\0-eval-function-win-states-1.test
*** PASS: test cases\q3\0-eval-function-win-states-2.test
*** PASS: test_cases\q3\0-lecture-6-tree.test
*** PASS: test_cases\q3\0-small-tree.test
*** PASS: test cases\q3\1-1-minmax.test
*** PASS: test_cases\q3\1-2-minmax.test
*** PASS: test cases\q3\1-3-minmax.test
*** PASS: test_cases\q3\1-4-minmax.test
*** PASS: test_cases\q3\1-5-minmax.test
*** PASS: test_cases\q3\1-6-minmax.test
*** PASS: test_cases\q3\1-7-minmax.test
*** PASS: test_cases\q3\1-8-minmax.test
*** PASS: test_cases\q3\2-1a-vary-depth.test
*** PASS: test_cases\q3\2-1b-vary-depth.test
*** PASS: test_cases\q3\2-2a-vary-depth.test
*** PASS: test_cases\q3\2-2b-vary-depth.test
*** PASS: test_cases\q3\2-3a-vary-depth.test
*** PASS: test_cases\q3\2-3b-vary-depth.test
*** PASS: test_cases\q3\2-4a-vary-depth.test
*** PASS: test_cases\q3\2-4b-vary-depth.test
*** PASS: test_cases\q3\2-one-ghost-3level.test
*** PASS: test cases\q3\3-one-ghost-4level.test
*** PASS: test_cases\q3\4-two-ghosts-3level.test
*** PASS: test cases\q3\5-two-ghosts-4level.test
*** PASS: test_cases\q3\6-tied-root.test
*** PASS: test_cases\q3\7-1a-check-depth-one-ghost.test
*** PASS: test_cases\q3\7-1b-check-depth-one-ghost.test
*** PASS: test cases\q3\7-1c-check-depth-one-ghost.test
*** PASS: test cases\q3\7-2a-check-depth-two-ghosts.test
*** PASS: test_cases\q3\7-2b-check-depth-two-ghosts.test
*** PASS: test_cases\q3\7-2c-check-depth-two-ghosts.test
*** Running AlphaBetaAgent on smallClassic 1 time(s).
```

Pacman died! Score: 84 Average Score: 84.0 Scores: 84.0 Win Rate: 0/1 (0.00) Record: Loss *** Finished running AlphaBetaAgent on smallClassic after 0 seconds. *** Won 0 out of 1 games. Average score: 84.000000 *** *** PASS: test_cases\q3\8-pacman-game.test ### Question q3: 5/5 ### Finished at 22:35:48 Provisional grades =========== Question q3: 5/5 Total: 5/5 Your grades are NOT yet registered. To register your grades, make sure to follow your instructor's guidelines to receive credit on your project.

总结

- 通过本次实验,自己复习了5种算法的基本思路对于其理解更加深刻了,特别是alpha-beta剪枝算法,在课上学习之后当时可能没有完全理解透,再来实现代码,通过查询资料理解逻辑并实现代码后,有种醍醐灌顶的感觉
- 整体实验轻松而有效,很好的对课上所学知识进行了巩固复习,也起到了温故知新的作用。