Artificial Intelligence Nanodegree

Convolutional Neural Networks

Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

Note: Once you have completed all of the code implementations, you need to finalize your work by exporting the iPython Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to \n", "**File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

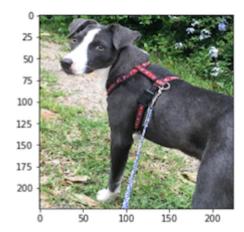
Note: Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains **optional** "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this IPython notebook.

Why We're Here

In this notebook, you will make the first steps towards developing an algorithm that could be used as part of a mobile or web app. At the end of this project, your code will accept any user-supplied image as input. If a dog is detected in the image, it will provide an estimate of the dog's breed. If a human is detected, it will provide an estimate of the dog breed that is most resembling. The image below displays potential sample output of your finished project (... but we expect that each student's algorithm will behave differently!).

hello, dog! your predicted breed is ... American Staffordshire terrier



In this real-world setting, you will need to piece together a series of models to perform different tasks; for instance, the algorithm that detects humans in an image will be different from the CNN that infers dog breed. There are many points of possible failure, and no perfect algorithm exists. Your imperfect solution will nonetheless create a fun user experience!

The Road Ahead

We break the notebook into separate steps. Feel free to use the links below to navigate the notebook.

- Step 0: Import Datasets
- Step 1: Detect Humans
- Step 2: Detect Dogs
- Step 3: Create a CNN to Classify Dog Breeds (from Scratch)
- Step 4: Use a CNN to Classify Dog Breeds (using Transfer Learning)
- Step 5: Create a CNN to Classify Dog Breeds (using Transfer Learning)
- Step 6: Write your Algorithm
- Step 7: Test Your Algorithm

Step 0: Import Datasets

Import Dog Dataset

In the code cell below, we import a dataset of dog images. We populate a few variables through the use of the load files function from the scikit-learn library:

- train files, valid files, test files numpy arrays containing file paths to images
- train_targets, valid_targets, test_targets numpy arrays containing onehot-encoded classification labels
 - The first of atting the land and a second control for the control of the land.

```
In [1]: from sklearn.datasets import load files
        from keras.utils import np utils
        import numpy as np
        from glob import glob
        # define function to load train, test, and validation datasets
        def load dataset(path):
            data = load files(path)
            dog files = np.array(data['filenames'])
            dog_targets = np_utils.to_categorical(np.array(data['target']), 133)
            return dog files, dog targets
        # load train, test, and validation datasets
        train files, train targets = load dataset('/floyd/input/dogimages/train'
        valid files, valid targets = load dataset('/floyd/input/dogimages/valid'
        test files, test targets = load dataset('/floyd/input/dogimages/test')
        # load list of dog names
        dog names = [item[20:-1] for item in sorted(glob("/floyd/input/dogimage
        s/train/*/"))]
        # print statistics about the dataset
        print('There are %d total dog categories.' % len(dog names))
        print('There are %s total dog images.\n' % len(np.hstack([train_files, v
        alid files, test files[)))
        print('There are %d training dog images.' % len(train files))
        print('There are %d validation dog images.' % len(valid files))
        print('There are %d test dog images.'% len(test files))
        Using TensorFlow backend.
```

```
There are 133 total dog categories. There are 8351 total dog images.

There are 6680 training dog images. There are 835 validation dog images. There are 836 test dog images.
```

Import Human Dataset

In the code cell below, we import a dataset of human images, where the file paths are stored in the numpy array human_files.

```
In [2]: import random
    random.seed(8675309)

# load filenames in shuffled human dataset
    human_files = np.array(glob("/floyd/input/lfw/*/*"))
    random.shuffle(human_files)

# print statistics about the dataset
    print('There are %d total human images.' % len(human_files))
```

There are 13233 total human images.

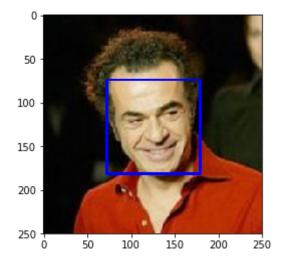
Step 1: Detect Humans

We use OpenCV's implementation of Haar feature-based cascade classifiers
http://docs.opencv.org/trunk/d7/d8b/tutorial_py_face_detection.html) to detect human faces in images. OpenCV provides many pre-trained face detectors, stored as XML files on https://github.com/opencv/opencv/tree/master/data/haarcascades). We have downloaded one of these detectors and stored it in the haarcascades directory.

In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

```
In [3]:
        import cv2
        import matplotlib.pyplot as plt
        %matplotlib inline
        # extract pre-trained face detector
        face cascade = cv2.CascadeClassifier('haarcascades/haarcascade frontalfa
        ce alt.xml')
        # load color (BGR) image
        img = cv2.imread(human_files[3])
        # convert BGR image to grayscale
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        # find faces in image
        faces = face_cascade.detectMultiScale(gray)
        # print number of faces detected in the image
        print('Number of faces detected:', len(faces))
        # get bounding box for each detected face
        for (x,y,w,h) in faces:
            # add bounding box to color image
            cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)
        # convert BGR image to RGB for plotting
        cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
        # display the image, along with bounding box
        plt.imshow(cv_rgb)
        plt.show()
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

Write a Human Face Detector

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face_detector, takes a string-valued file path to an image as input and appears in the code block below.

```
In [4]: # returns "True" if face is detected in image stored at img_path
    def face_detector(img_path):
        img = cv2.imread(img_path)
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        faces = face_cascade.detectMultiScale(gray)
        return len(faces) > 0
```

(IMPLEMENTATION) Assess the Human Face Detector

Question 1: Use the code cell below to test the performance of the face detector function.

- What percentage of the first 100 images in human files have a detected human face?
- What percentage of the first 100 images in dog files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human_files_short and dog_files_short.

Answer:

```
In [5]: human_files_short = human_files[:100]
    dog_files_short = train_files[:100]
    # Do NOT modify the code above this line.

## TODO: Test the performance of the face_detector algorithm
    ## on the images in human_files_short and dog_files_short.
    human_faces_detected = np.sum(list(map(face_detector, human_files_short)))
    print(f'Total human faces detected: {human_faces_detected}')

dog_faces_detected = np.sum(list(map(face_detector, dog_files_short)))
    print(f'Total dog faces_detected: {dog_faces_detected}')
```

Total human faces detected: 99
Total dog faces detected: 12

Question 2: This algorithmic choice necessitates that we communicate to the user that we accept human images only when they provide a clear view of a face (otherwise, we risk having unneccessarily frustrated users!). In your opinion, is this a reasonable expectation to pose on the user? If not, can you think of a way to detect humans in images that does not necessitate an image with a clearly presented face?

Answer: In many existing apps, the user is required to provide a clear image of his face. I don't think it is an unreasonable request to ask users to provide an image in which their face is the main "object" or "focus".

If we would have to go further down that path, we could consider using an algorithm including human features detection beyond the face, such as in https://github.com/ITCoders/Human-detection-and-Tracking).

Answer:

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this **optional** task, report performance on each of the datasets.

```
In [6]: ## (Optional) TODO: Report the performance of another
## face detection algorithm on the LFW dataset
### Feel free to use as many code cells as needed.
```

One improvement we could try to make is in reducing the number of dogs detected in images. To do that, we could try including eye detection and see if a lower amount of dogs are detected without lowering the number of humans detected. We will ignore whether or not the eyes are in the face for now.

```
In [7]: eye_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_eye.xml')
```

```
In [8]: # returns "True" if face and eyes are detected in image stored at img_pa
        th
        def face detector adjusted(img path):
            img = cv2.imread(img_path)
            gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
            faces = face cascade.detectMultiScale(gray)
            eyes = eye cascade.detectMultiScale(gray)
            return len(faces) > 0 and len(eyes) > 0
        human faces_detected = np.sum(list(map(face_detector_adjusted, human_fil
        es short)))
        print(f'Total human faces detected: {human faces detected}')
        dog faces detected = np.sum(list(map(face detector adjusted, dog files s
        hort)))
        print(f'Total dog faces detected: {dog_faces_detected}')
        Total human faces detected: 88
        Total dog faces detected: 8
```

We obtain a reduction of humans and dogs detected compared to our previous detector. This doesn't help much. Another approach could be tweaking the detectMultiScale params as shown in https://docs.opencv.org/trunk/d7/d8b/tutorial_py_face_detection.html (https://docs.opencv.org/trunk/d7/d8b/tutorial_py_face_detection.html).

We could also try other popular face recognition libraries such as https://github.com/ageitgey/face_recognition. (https://github.com/ageitgey/face_recognition).

Since this step is optional, we'll leave it there for now.

Step 2: Detect Dogs

In this section, we use a pre-trained ResNet-50

(http://ethereon.github.io/netscope/#/gist/db945b393d40bfa26006) model to detect dogs in images. Our first line of code downloads the ResNet-50 model, along with weights that have been trained on ImageNet (http://www.image-net.org/), a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories (https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a). Given an image, this pre-trained ResNet-50 model returns a prediction (derived from the available categories in ImageNet) for the object that is contained in the image.

```
In [9]: from keras.applications.resnet50 import ResNet50

# define ResNet50 model
ResNet50_model = ResNet50(weights='imagenet')
```

Pre-process the Data

When using TensorFlow as backend, Keras CNNs require a 4D array (which we'll also refer to as a 4D tensor) as input, with shape

```
(nb_samples, rows, columns, channels),
```

where nb_samples corresponds to the total number of images (or samples), and rows, columns, and channels correspond to the number of rows, columns, and channels for each image, respectively.

The path_to_tensor function below takes a string-valued file path to a color image as input and returns a 4D tensor suitable for supplying to a Keras CNN. The function first loads the image and resizes it to a square image that is 224×224 pixels. Next, the image is converted to an array, which is then resized to a 4D tensor. In this case, since we are working with color images, each image has three channels. Likewise, since we are processing a single image (or sample), the returned tensor will always have shape

```
(1, 224, 224, 3).
```

The paths_to_tensor function takes a numpy array of string-valued image paths as input and returns a 4D tensor with shape

```
(nb_samples, 224, 224, 3).
```

Here, nb_samples is the number of samples, or number of images, in the supplied array of image paths. It is best to think of nb_samples as the number of 3D tensors (where each 3D tensor corresponds to a different image) in your dataset!

```
In [10]: from keras.preprocessing import image
    from tqdm import tqdm

def path_to_tensor(img_path):
        # loads RGB image as PIL.Image.Image type
        img = image.load_img(img_path, target_size=(224, 224))
        # convert PIL.Image.Image type to 3D tensor with shape (224, 224, 3)
        x = image.img_to_array(img)
        # convert 3D tensor to 4D tensor with shape (1, 224, 224, 3) and ret
        urn 4D tensor
        return np.expand_dims(x, axis=0)

def paths_to_tensor(img_paths):
        list_of_tensors = [path_to_tensor(img_path) for img_path in tqdm(img_paths)]
        return np.vstack(list_of_tensors)
```

Making Predictions with ResNet-50

Getting the 4D tensor ready for ResNet-50, and for any other pre-trained model in Keras, requires some additional processing. First, the RGB image is converted to BGR by reordering the channels. All pre-trained models have the additional normalization step that the mean pixel (expressed in RGB as [103.939, 116.779, 123.68] and calculated from all pixels in all images in ImageNet) must be subtracted from every pixel in each image. This is implemented in the imported function <code>preprocess_input</code>. If you're curious, you can check the code for <code>preprocess_input</code> here (https://github.com/fchollet/keras/blob/master/keras/applications/imagenet_utils.py).

Now that we have a way to format our image for supplying to ResNet-50, we are now ready to use the model to extract the predictions. This is accomplished with the predict method, which returns an array whose i-th entry is the model's predicted probability that the image belongs to the i-th ImageNet category. This is implemented in the ResNet50_predict_labels function below.

By taking the argmax of the predicted probability vector, we obtain an integer corresponding to the model's predicted object class, which we can identify with an object category through the use of this <u>dictionary</u> (https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a).

```
In [11]: from keras.applications.resnet50 import preprocess_input, decode_predict
ions

def ResNet50_predict_labels(img_path):
    # returns prediction vector for image located at img_path
    img = preprocess_input(path_to_tensor(img_path))
    return np.argmax(ResNet50_model.predict(img))
```

Write a Dog Detector

While looking at the <u>dictionary (https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a)</u>, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained ResNet-50 model, we need only check if the ResNet50_predict_labels function above returns a value between 151 and 268 (inclusive).

We use these ideas to complete the dog_detector function below, which returns True if a dog is detected in an image (and False if not).

```
In [12]: ### returns "True" if a dog is detected in the image stored at img_path
    def dog_detector(img_path):
        prediction = ResNet50_predict_labels(img_path)
        return ((prediction <= 268) & (prediction >= 151))
```

(IMPLEMENTATION) Assess the Dog Detector

Question 3: Use the code cell below to test the performance of your dog detector function.

- What percentage of the images in human_files_short have a detected dog? 0%
- What percentage of the images in dog_files_short have a detected dog? 100%

Answer:

```
In [13]: ### TODO: Test the performance of the dog_detector function
    ### on the images in human_files_short and dog_files_short.
    human_faces_detected = np.sum(list(map(dog_detector, human_files_short
    )))
    print(f'Total human faces detected: {human_faces_detected}')

    dog_faces_detected = np.sum(list(map(dog_detector, dog_files_short)))
    print(f'Total dog faces detected: {dog_faces_detected}')

Total human faces detected: 2
```

Total human faces detected: 2 Total dog faces detected: 100

Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

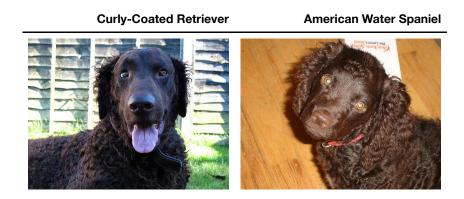
Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN **from scratch** (so, you can't use transfer learning **yet**!), and you must attain a test accuracy of at least 1%. In Step 5 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

Be careful with adding too many trainable layers! More parameters means longer training, which means you are more likely to need a GPU to accelerate the training process. Thankfully, Keras provides a handy estimate of the time that each epoch is likely to take; you can extrapolate this estimate to figure out how long it will take for your algorithm to train.

We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that **even a human** would have great difficulty in distinguishing between a Brittany and a Welsh Springer Spaniel.



It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).



Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.

Yellow Labrador Chocolate Labrador Black Labrador

Yellow Labrador Chocolate Labrador Black Labrador Black Labrador







We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

```
In [14]: from PIL import ImageFile
ImageFile.LOAD_TRUNCATED_IMAGES = True

# pre-process the data for Keras
train_tensors = paths_to_tensor(train_files).astype('float32')/255
valid_tensors = paths_to_tensor(valid_files).astype('float32')/255
test_tensors = paths_to_tensor(test_files).astype('float32')/255

100% | 6680/6680 [01:56<00:00, 57.24it/s]
100% | 835/835 [00:13<00:00, 60.49it/s]
100% | 836/836 [00:12<00:00, 66.34it/s]</pre>
```

(IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. At the end of your code cell block, summarize the layers of your model by executing the line:

```
model.summary()
```

We have imported some Python modules to get you started, but feel free to import as many modules as you need. If you end up getting stuck, here's a hint that specifies a model that trains relatively fast on CPU and attains >1% test accuracy in 5 epochs:



Question 4: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. If you chose to use the hinted architecture above, describe why you think that CNN architecture should work well for the image classification task.

Answer:

```
In [15]: from keras.layers import Conv2D, MaxPooling2D, GlobalAveragePooling2D
         from keras.layers import Dropout, Flatten, Dense
         from keras.models import Sequential
         model = Sequential([
             Conv2D(32, (3, 3), activation='relu', input_shape=(224, 224, 3)),
             Conv2D(32, (3, 3), activation='relu'),
             MaxPooling2D(pool size=(2, 2)),
             Dropout(0.25),
             Conv2D(64, (3, 3), activation='relu'),
             Conv2D(64, (3, 3), activation='relu'),
             MaxPooling2D(pool_size=(2, 2)),
             Dropout(0.25),
             Flatten(),
             Dense(256, activation='relu'),
             Dropout(0.5),
             Dense(133, activation='softmax')
         ])
```

TODO: Define your architecture.

I tried a VGG like convolutional neural network based on <u>Keras documentation (https://keras.io/gettingstarted/sequential-model-guide/)</u> and <u>VGG scientific paper (https://arxiv.org/pdf/1409.1556.pdf)</u>.

The images, starting as 224x224 RGB image inputs, are passed through convolutional layers with 3x3 filters/kernels (the smallest size to capture the notions of left/right - up/down - center) and a stride of 1 pixel.

Max-pooling is performed over a 2×2 pixel window, with stride 2 after each stack of convolutional layers.

Dropout is also performed after each stack of convolutional layers + max-pooling to prevent overfitting.

Flattening is then performed to prepare the inputs for the densely-connected neural layers sequence.

Why you think that CNN architecture should work well for the image classification task

To the way a traditional neural network is structured, a relatively straightforward change can make even huge images more manageable. As the general applicability of neural networks is well-known, this advantage turns into a liability when dealing with images.

The convolutional neural networks make a conscious tradeoff: if a network is designed for specifically handling the images, some generalizability has to be sacrificed for a much more feasible solution. In that sense, CNNs are more efficient for images tasks (and other similar tasks), but may be less applicable in other contexts.

source (https://www.kdnuggets.com/2017/08/convolutional-neural-networks-image-recognition.html)

```
In [16]: model.summary()
```

Layer (type)	Output	Shape	Param #
conv2d_1 (Conv2D)	(None,	222, 222, 32)	896
conv2d_2 (Conv2D)	(None,	220, 220, 32)	9248
max_pooling2d_2 (MaxPooling2	(None,	110, 110, 32)	0
dropout_1 (Dropout)	(None,	110, 110, 32)	0
conv2d_3 (Conv2D)	(None,	108, 108, 64)	18496
conv2d_4 (Conv2D)	(None,	106, 106, 64)	36928
max_pooling2d_3 (MaxPooling2	(None,	53, 53, 64)	0
dropout_2 (Dropout)	(None,	53, 53, 64)	0
flatten_1 (Flatten)	(None,	179776)	0
dense_1 (Dense)	(None,	256)	46022912
dropout_3 (Dropout)	(None,	256)	0
dense_2 (Dense)	(None,	133)	34181
Total params: 46,122,661 Trainable params: 46,122,661 Non-trainable params: 0	=====		======

Compile the Model

```
In [17]: model.compile(optimizer='rmsprop', loss='categorical_crossentropy', metr
    ics=['accuracy'])
```

(IMPLEMENTATION) Train the Model

Train your model in the code cell below. Use model checkpointing to save the model that attains the best validation loss.

You are welcome to <u>augment the training data (https://blog.keras.io/building-powerful-image-classification-models-using-very-little-data.html)</u>, but this is not a requirement.

```
In [18]: from keras.callbacks import ModelCheckpoint
       ### TODO: specify the number of epochs that you would like to use to tra
       in the model.
       epochs = 5
       ### Do NOT modify the code below this line.
       checkpointer = ModelCheckpoint(filepath='saved models/weights.best.from_
       scratch.hdf5',
                                verbose=1, save_best_only=True)
       model.fit(train tensors, train targets,
               validation data=(valid tensors, valid targets),
               epochs=epochs, batch_size=20, callbacks=[checkpointer], verbos
       e=1)
       Train on 6680 samples, validate on 835 samples
       Epoch 1/5
       59 - acc: 0.0082 - val_loss: 4.8796 - val_acc: 0.0108
       Epoch 00001: val loss improved from inf to 4.87963, saving model to sav
       ed_models/weights.best.from_scratch.hdf5
       Epoch 2/5
       6 - acc: 0.0094 - val loss: 4.8700 - val acc: 0.0108
       Epoch 00002: val loss improved from 4.87963 to 4.86998, saving model to
       saved models/weights.best.from scratch.hdf5
       Epoch 3/5
       4 - acc: 0.0111 - val loss: 4.8687 - val acc: 0.0108
       Epoch 00003: val loss improved from 4.86998 to 4.86873, saving model to
       saved models/weights.best.from scratch.hdf5
       Epoch 4/5
       4 - acc: 0.0109 - val loss: 4.8685 - val acc: 0.0108
       Epoch 00004: val loss improved from 4.86873 to 4.86855, saving model to
       saved models/weights.best.from scratch.hdf5
       Epoch 5/5
       4 - acc: 0.0106 - val loss: 4.8686 - val acc: 0.0108
       Epoch 00005: val loss did not improve from 4.86855
Out[18]: <keras.callbacks.History at 0x7f121ce96a20>
```

Load the Model with the Best Validation Loss

```
In [19]: model.load_weights('saved_models/weights.best.from_scratch.hdf5')
```

Test the Model

Try out your model on the test dataset of dog images. Ensure that your test accuracy is greater than 1%.

Step 4: Use a CNN to Classify Dog Breeds

To reduce training time without sacrificing accuracy, we show you how to train a CNN using transfer learning. In the following step, you will get a chance to use transfer learning to train your own CNN.

Obtain Bottleneck Features

```
In [21]: bottleneck_features = np.load('/floyd/input/bottleneck_features/DogVGG16
    Data.npz')
    train_VGG16 = bottleneck_features['train']
    valid_VGG16 = bottleneck_features['valid']
    test_VGG16 = bottleneck_features['test']
```

Model Architecture

The model uses the the pre-trained VGG-16 model as a fixed feature extractor, where the last convolutional output of VGG-16 is fed as input to our model. We only add a global average pooling layer and a fully connected layer, where the latter contains one node for each dog category and is equipped with a softmax.

```
In [22]: VGG16_model = Sequential()
    VGG16_model.add(GlobalAveragePooling2D(input_shape=train_VGG16.shape[1
    :]))
    VGG16_model.add(Dense(133, activation='softmax'))
    VGG16_model.summary()
```

Compile the Model

```
In [23]: VGG16_model.compile(loss='categorical_crossentropy', optimizer='rmsprop'
, metrics=['accuracy'])
```

Train the Model

```
Train on 6680 samples, validate on 835 samples
Epoch 1/20
881 - acc: 0.1335 - val loss: 10.0211 - val acc: 0.2551
Epoch 00001: val_loss improved from inf to 10.02112, saving model to sa
ved models/weights.best.VGG16.hdf5
Epoch 2/20
15 - acc: 0.3132 - val loss: 9.2851 - val acc: 0.3090
Epoch 00002: val_loss improved from 10.02112 to 9.28507, saving model t
o saved models/weights.best.VGG16.hdf5
Epoch 3/20
40 - acc: 0.3819 - val_loss: 9.0261 - val_acc: 0.3413
Epoch 00003: val_loss improved from 9.28507 to 9.02610, saving model to
saved_models/weights.best.VGG16.hdf5
Epoch 4/20
02 - acc: 0.4219 - val_loss: 8.7385 - val_acc: 0.3605
Epoch 00004: val_loss improved from 9.02610 to 8.73850, saving model to
saved_models/weights.best.VGG16.hdf5
Epoch 5/20
60 - acc: 0.4476 - val loss: 8.4531 - val acc: 0.3904
Epoch 00005: val loss improved from 8.73850 to 8.45310, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 6/20
38 - acc: 0.4666 - val loss: 8.4094 - val acc: 0.3904
Epoch 00006: val loss improved from 8.45310 to 8.40943, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 7/20
32 - acc: 0.4819 - val loss: 8.3929 - val acc: 0.3928
Epoch 00007: val loss improved from 8.40943 to 8.39290, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 8/20
94 - acc: 0.4996 - val loss: 8.2093 - val acc: 0.4192
Epoch 00008: val loss improved from 8.39290 to 8.20932, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 9/20
53 - acc: 0.5117 - val loss: 7.9373 - val acc: 0.4287
Epoch 00009: val loss improved from 8.20932 to 7.93734, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 10/20
```

```
04 - acc: 0.5331 - val loss: 7.8584 - val acc: 0.4287
Epoch 00010: val_loss improved from 7.93734 to 7.85844, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 11/20
42 - acc: 0.5355 - val loss: 7.8052 - val acc: 0.4419
Epoch 00011: val loss improved from 7.85844 to 7.80520, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 12/20
91 - acc: 0.5383 - val loss: 7.7882 - val acc: 0.4443
Epoch 00012: val loss improved from 7.80520 to 7.78817, saving model to
saved_models/weights.best.VGG16.hdf5
Epoch 13/20
19 - acc: 0.5470 - val_loss: 7.6585 - val_acc: 0.4431
Epoch 00013: val loss improved from 7.78817 to 7.65853, saving model to
saved_models/weights.best.VGG16.hdf5
Epoch 14/20
88 - acc: 0.5621 - val_loss: 7.4649 - val_acc: 0.4587
Epoch 00014: val loss improved from 7.65853 to 7.46490, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 15/20
75 - acc: 0.5710 - val_loss: 7.4760 - val_acc: 0.4623
Epoch 00015: val loss did not improve from 7.46490
Epoch 16/20
46 - acc: 0.5795 - val loss: 7.4881 - val acc: 0.4527
Epoch 00016: val loss did not improve from 7.46490
Epoch 17/20
6680/6680 [============= ] - 1s 176us/step - loss: 6.50
81 - acc: 0.5843 - val loss: 7.3456 - val acc: 0.4623
Epoch 00017: val loss improved from 7.46490 to 7.34558, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 18/20
67 - acc: 0.5882 - val_loss: 7.2964 - val_acc: 0.4707
Epoch 00018: val loss improved from 7.34558 to 7.29637, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 19/20
96 - acc: 0.5937 - val loss: 7.2123 - val acc: 0.4778
Epoch 00019: val loss improved from 7.29637 to 7.21227, saving model to
saved models/weights.best.VGG16.hdf5
Epoch 20/20
```

Load the Model with the Best Validation Loss

```
In [25]: VGG16_model.load_weights('saved_models/weights.best.VGG16.hdf5')
```

Test the Model

Now, we can use the CNN to test how well it identifies breed within our test dataset of dog images. We print the test accuracy below.

```
In [26]: # get index of predicted dog breed for each image in test set
VGG16_predictions = [np.argmax(VGG16_model.predict(np.expand_dims(featur
e, axis=0))) for feature in test_VGG16]

# report test accuracy
test_accuracy = 100*np.sum(np.array(VGG16_predictions)==np.argmax(test_t
argets, axis=1))/len(VGG16_predictions)
print('Test accuracy: %.4f%%' % test_accuracy)
```

Test accuracy: 49.1627%

Predict Dog Breed with the Model

```
In [27]: from extract_bottleneck_features import *

def VGG16_predict_breed(img_path):
    # extract bottleneck features
    bottleneck_feature = extract_VGG16(path_to_tensor(img_path))
    # obtain predicted vector
    predicted_vector = VGG16_model.predict(bottleneck_feature)
    # return dog breed that is predicted by the model
    return dog_names[np.argmax(predicted_vector)]

print(VGG16_predict_breed("/floyd/input/images/Curly-coated_retriever_03
896.jpg"))

Downloading data from https://github.com/fchollet/deep-learning-models/
releases/download/v0.1/vgg16 weights tf dim ordering tf kernels notop.h
```

es/train/055.Curly-coated retriever

Step 5: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

In Step 4, we used transfer learning to create a CNN using VGG-16 bottleneck features. In this section, you must use the bottleneck features from a different pre-trained model. To make things easier for you, we have precomputed the features for all of the networks that are currently available in Keras:

- VGG-19 (https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogVGG19Data.npz) bottleneck features
- ResNet-50 (https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogResnet50Data.npz)
 bottleneck features
- Inception (https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogInceptionV3Data.npz)
 bottleneck features
- Xception (https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogXceptionData.npz)
 bottleneck features

The files are encoded as such:

```
Dog{network}Data.npz
```

where {network}, in the above filename, can be one of VGG19, Resnet50, InceptionV3, or Xception. Pick one of the above architectures, download the corresponding bottleneck features, and store the downloaded file in the bottleneck features/ folder in the repository.

(IMPLEMENTATION) Obtain Bottleneck Features

In the code block below, extract the bottleneck features corresponding to the train, test, and validation sets by running the following:

(IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. At the end of your code cell block, summarize the layers of your model by executing the line:

```
Resnet50_model.summary()
```

```
In [29]: Resnet50_model = Sequential()
   Resnet50_model.add(GlobalAveragePooling2D(input_shape=train_Resnet50.sha
   pe[1:]))
   Resnet50_model.add(Dense(133, activation='softmax'))
```

Question 5: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

Answer: We use a similar approach as in <u>Step 4</u> but with a different starting algorithm: ResNet-50.

The model uses the pre-trained ResNet-50 model as a fixed feature extractor, where the last convolutional output of ResNet-50 is fed as input to our model. ResNet50 is a 50 layer Residual Network (see last paragraph as to why residual networks are important [1 (https://arxiv.org/pdf/1512.03385.pdf)]), and its detailed architecture can be seen here [2 (http://ethereon.github.io/netscope/#/gist/db945b393d40bfa26006)].

Again, like in step 4, we only add a global average pooling layer and a fully connected layer, where the latter contains one node for each dog category and is equipped with a softmax.

We chose the ResNet-50 because the ResNet architecture solves the common problem of **degredation** (e.g. with the network depth increasing, accuracy gets saturated and then degrades rapidly) in deep networks by adding **residual blocks** where intermediate layers of a block learn a residual function with reference to the block input [3] (https://www.jeremyjordan.me/convnet-architectures/#resnet).

(IMPLEMENTATION) Compile the Model

(IMPLEMENTATION) Train the Model

Train your model in the code cell below. Use model checkpointing to save the model that attains the best validation loss.

You are welcome to <u>augment the training data (https://blog.keras.io/building-powerful-image-classification-models-using-very-little-data.html</u>), but this is not a requirement.

```
Train on 6680 samples, validate on 835 samples
Epoch 1/10
88 - acc: 0.6076 - val loss: 0.8438 - val acc: 0.7401
Epoch 00001: val_loss improved from inf to 0.84379, saving model to sav
ed models/weights.best.Resnet50.hdf5
Epoch 2/10
23 - acc: 0.8681 - val loss: 0.7115 - val acc: 0.7928
Epoch 00002: val_loss improved from 0.84379 to 0.71148, saving model to
saved_models/weights.best.Resnet50.hdf5
Epoch 3/10
94 - acc: 0.9123 - val_loss: 0.6785 - val_acc: 0.8120
Epoch 00003: val_loss improved from 0.71148 to 0.67848, saving model to
saved_models/weights.best.Resnet50.hdf5
Epoch 4/10
45 - acc: 0.9466 - val_loss: 0.6863 - val_acc: 0.8036
Epoch 00004: val_loss did not improve from 0.67848
Epoch 5/10
66 - acc: 0.9620 - val loss: 0.7191 - val acc: 0.7976
Epoch 00005: val loss did not improve from 0.67848
Epoch 6/10
78 - acc: 0.9744 - val loss: 0.7212 - val acc: 0.8060
Epoch 00006: val loss did not improve from 0.67848
Epoch 7/10
6680/6680 [============= ] - 1s 149us/step - loss: 0.06
06 - acc: 0.9813 - val loss: 0.7677 - val acc: 0.8132
Epoch 00007: val loss did not improve from 0.67848
Epoch 8/10
52 - acc: 0.9882 - val_loss: 0.7397 - val_acc: 0.8132
Epoch 00008: val loss did not improve from 0.67848
Epoch 9/10
63 - acc: 0.9909 - val loss: 0.7245 - val acc: 0.8084
Epoch 00009: val loss did not improve from 0.67848
Epoch 10/10
76 - acc: 0.9927 - val loss: 0.7395 - val acc: 0.8180
Epoch 00010: val loss did not improve from 0.67848
```

Out[32]: <keras.callbacks.History at 0x7f1202efcc50>

(IMPLEMENTATION)Load the Model with the Best Validation Loss

```
In [33]: ### TODO: Load the model weights with the best validation loss.

# add by_name param to prefer layer differences clash https://github.co
m/keras-team/keras/issues/11612#issuecomment-437339619
ResNet50_model.load_weights('saved_models/weights.best.Resnet50.hdf5', b
y_name=True)
```

(IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Ensure that your test accuracy is greater than 60%.

```
In [34]: ### TODO: Calculate classification accuracy on the test dataset.
# get index of predicted dog breed for each image in test set
Resnet50_predictions = [np.argmax(Resnet50_model.predict(np.expand_dims(
    feature, axis=0))) for feature in test_Resnet50]

# report test accuracy
test_accuracy = 100*np.sum(np.array(Resnet50_predictions)==np.argmax(test_targets, axis=1))/len(Resnet50_predictions)
print('Test_accuracy: %.4f%%' % test_accuracy)
```

Test accuracy: 81.9378%

(IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

Similar to the analogous function in Step 5, your function should have three steps:

- 1. Extract the bottleneck features corresponding to the chosen CNN model.
- 2. Supply the bottleneck features as input to the model to return the predicted vector. Note that the argmax of this prediction vector gives the index of the predicted dog breed.
- 3. Use the dog_names array defined in Step 0 of this notebook to return the corresponding breed.

The functions to extract the bottleneck features can be found in <code>extract_bottleneck_features.py</code>, and they have been imported in an earlier code cell. To obtain the bottleneck features corresponding to your chosen CNN architecture, you need to use the function

```
extract_{network}
```

where {network}, in the above filename, should be one of VGG19, Resnet50, InceptionV3, or Xception.

```
In [35]: ### TODO: Write a function that takes a path to an image as input
    ### and returns the dog breed that is predicted by the model.
    from extract_bottleneck_features import *

def Resnet50_predict_breed(img_path):
    # extract bottleneck features
    bottleneck_feature = extract_Resnet50(path_to_tensor(img_path))
    # we use pooling="avg" in the extraction method and adjust dimension
    ality afterward
    # based on https://stackoverflow.com/a/51233565/9443669
    bottleneck_feature = np.expand_dims(bottleneck_feature, axis=0)
    bottleneck_feature = np.expand_dims(bottleneck_feature, axis=0)
    # obtain predicted vector
    predicted_vector = Resnet50_model.predict(bottleneck_feature)
    # return dog breed that is predicted_by the model
    return dog_names[np.argmax(predicted_vector)]
```

Step 6: Write your Algorithm

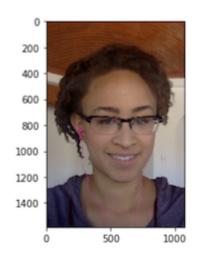
Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then,

- if a **dog** is detected in the image, return the predicted breed.
- if a **human** is detected in the image, return the resembling dog breed.
- if neither is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face_detector and dog_detector functions developed above. You are **required** to use your CNN from Step 5 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!





You look like a ... Chinese_shar-pei

(IMPLEMENTATION) Write your Algorithm

```
In [37]: from IPython.core.display import Image, display
         def clean_breed(breed):
             return breed.split(".")[-1].replace("_", " ")
         def show predicted breed(img path, label):
             breed = Resnet50 predict breed(img path)
             print(f'Hello, {label}!')
             display(Image(img_path))
             print(f'You are most likely a {clean_breed(breed)}')
             print("So cute!!!")
         def predict dog breed(img path):
             if dog detector(img path):
                 show predicted breed(img path, "cutty dog")
             elif face detector(img path):
                 show_predicted_breed(img_path, "beautiful human")
             else:
                 print("Oh no!\n\nWe were unable to detect a dog or human in the
          provided image.\n\nPlease try another image.")
                 display(Image(img path))
                 print("The above image is not working.")
```

Step 7: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that **you** look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

(IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

Question 6: Is the output better than you expected:)? Or worse:(? Provide at least three possible points of improvement for your algorithm.

Answer:

before testing our algorithm

We anticipate that the algorithm will detect dogs and humans fairly accurately. Here are our predictions:

"Color-white.jpg" --> will detect no human or dog. "michelml.jpg" --> will detect a human and should predict a breed resembling a golden retriever "/floyd/input/images/American_water_spaniel_00648.jpg" --> will detect a dog and return American_water_spaniel as breed "/floyd/input/images/sample_human_output.png" --> will detect a human and should predict Chinese shar pei as breed

"/floyd/input/images/Welsh_springer_spaniel_08203.jpg" --> will detect a dog and return Welsh_springer_spaniel as breed "/floyd/input/images/Labrador_retriever_06455.jpg" --> will detect a dog and return Labrador_retriever as breed "/floyd/input/images/American_water_spaniel_00648.jpg" --> will detect a dog and return American_water_spaniel as breed "/floyd/input/images/Brittany_02625.jpg" --> will detect a dog and return Brittany as breed

after testing our algorithm

"Color-white.jpg" --> **success** "michelml.jpg" --> **success** (we did not get a golden retriever, but a resembling breed) "/floyd/input/images/American_water_spaniel_00648.jpg" --> **failure** (we got Irish water spaniel but it was American water spaniel) "/floyd/input/images/sample_human_output.png" --> **success** (we did not get a Chinese shar pei, but a resembling breed) "/floyd/input/images/Welsh_springer_spaniel_08203.jpg" --> **success** "/floyd/input/images/Labrador_retriever_06455.jpg" --> **success**

"/floyd/input/images/American_water_spaniel_00648.jpg" --> same input as our third image "/floyd/input/images/Brittany 02625.jpg" --> **success**

6 of our 7 inputs were accurate, which is equivalent to an accuracy of 86%, more than our initial model accuracy.

ways we could improve our algorithm

- extending our dataset with additional dog images to improve accuracy
- labeling our training data with 1) the average weight and 2) the average size of a specific breed to better detect the difference between similar breed (https://dogbreedatlas.com/dog-breed-comparison-tool&irish-breed

water-spaniel-vs-american-water-spaniel)

• augmenting the number of epoch while fitting the model, which may again improve accuracy, improving the value of the cost function.

```
In [38]: ## TODO: Execute your algorithm from Step 6 on
         ## at least 6 images on your computer.
         ## Feel free to use as many code cells as needed.
         image_paths = [
             "Color-white.jpg",
             "michelml.jpg",
             "/floyd/input/images/American water spaniel 00648.jpg",
             "/floyd/input/images/sample human output.png",
             "/floyd/input/images/Welsh_springer_spaniel_08203.jpg",
             "/floyd/input/images/Labrador_retriever_06455.jpg",
             "/floyd/input/images/American_water_spaniel_00648.jpg",
             "/floyd/input/images/Brittany_02625.jpg"
         ]
         for idx, im in enumerate(image paths):
             print(f'Scenario {idx + 1}. {im}\n')
             predict dog breed(im)
             print("\n----\n\n")
```

Scenario 1. Color-white.jpg

Oh no!

We were unable to detect a dog or human in the provided image.

Please try another image.



The above image is not working.

Scenario 2. michelml.jpg

Hello, beautiful human!



You are most likely a English springer spaniel So cute!!!

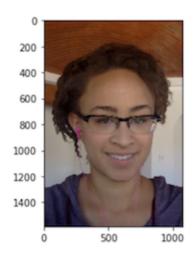
Scenario 3. /floyd/input/images/American_water_spaniel_00648.jpg
Hello, cutty dog!



You are most likely a Irish water spaniel So cute!!!

Scenario 4. /floyd/input/images/sample_human_output.png
Hello, beautiful human!

hello, human!



You look like a ... Chinese_shar-pei

You are most likely a Norwegian lundehund So cute!!!

Scenario 5. /floyd/input/images/Welsh_springer_spaniel_08203.jpg
Hello, cutty dog!



You are most likely a Welsh springer spaniel So cute!!!

Scenario 6. /floyd/input/images/Labrador_retriever_06455.jpg
Hello, cutty dog!



1782991 [RF] © www.visualphotos.com

You are most likely a Labrador retriever So cute!!!

Scenario 7. /floyd/input/images/American_water_spaniel_00648.jpg
Hello, cutty dog!



You are most likely a Irish water spaniel So cute!!!

Scenario 8. /floyd/input/images/Brittany_02625.jpg
Hello, cutty dog!



You are most likely a Brittany So cute!!!
