

Assignment 2 CDA

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1 Familiarization with the data

The dataset contains a total of 44 signals, with some being static values, other being sinusoid signals, and others being partially discrete (as in, they can rise or drop at certain points). L-signals tend to be more sinusoidal, F-signals tend to be "partially discrete", and S-signals are all binary signals.

All the signals together seem to have little correlation. Some combinations of signals are reasonably correlated: e.g. L_T3 and P_J302 have a 0.42 correlation coefficient. Moreover, the signal P_J302 in figure 1 looks cyclic. A cyclic signal like this is much easier to predict than a 'random' signal, since there is a rough base model that it adheres to. This signal's values are within a clear band at about 2-6 on the Y-axis. In such a case it is very easy to come up with a basic anomaly detection technique: if the signal moves outside this band this would be a clear sign of an anomaly. Plotting the mean error we saw for the ARMA prediction on signal L_T1, we saw that there were only 2 cases where the error was greater than three times the standard deviation.

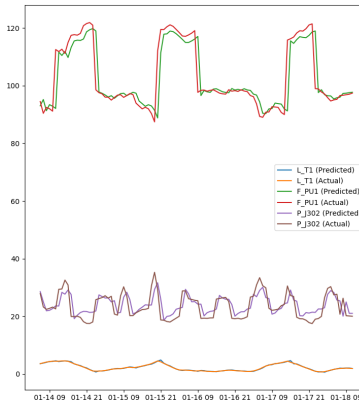


Figure 1: Visualization of some signals. The red and greens signals are partially discrete. Figure 2: ARMA predictions on some signals. The predictions work better on signals with less variance

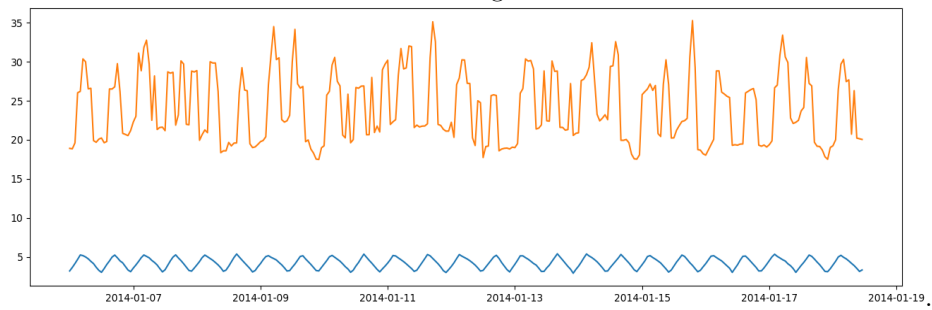


Figure 3: Signals L_T3 and P_J302. The peaks are roughly aligned.

2 ARMA

The script `ARMA.py` learns a ARMA model for any particular sensor. The parameters for the model are determined by testing out different p 's and q 's and then looking at the AIC value of the fitted model. A lower AIC means a better fit. Fitting the models takes quite some time, and as such the search space for parameters is limited. For p , only values in the range of $[0, 8]$ are tested, and for q , only values in the range of $[0, 2]$ are tested. Both these ranges are inclusive. We thought these ranges would still allow for a reasonable search space while limiting the time taken to search for the ideal parameters.

After the predictions are done, the predicted values are compared to the actual values. The difference between the two is used, and then the mean of the absolute values is computed, along with the standard deviation of the absolute values. An attack is detected if a predicted value differs from the actual value by more than the absolute mean plus three times the standard deviation. The sensors that have cyclic time series can be modelled effectively by ARMA, and the anomalies that can be detected are contextual anomalies.

3 Discrete models

For this task, we used the SAX method as shown in class. The script `SAX.py` is a script that can discretize a time series using SAX. The script was provided by Qin Lin, and we altered a few things to make it work with Python 3.

4 PCA

5 Comparison