

The diagram illustrates a 3D grid world environment. A robot, represented by a blue circle with a red dot, is positioned at the top-left corner. A goal, represented by a green circle with a yellow star, is located at the top-right corner. Two large black squares represent obstacles. The environment is divided into a grid of cells. Red arrows indicate the possible actions (up, down, left, right) from the robot's current position. The goal cell contains a green circle with a yellow star, and the robot's current position contains a blue circle with a red dot. The environment is bounded by a red line.

