

## PIC Book's Errata

The following errors were pointed out by Prof. Jian Peng

1. On pp 29, Figure 1-2 is not printed clearly.
2. On pp 53, Table 2-3, two instructions are printed wrong. Line 4 the instruction 'DECFSNZ' should be 'DCFSNZ'. Line 7 the instruction 'INCSNZ' should be 'INFSNZ'.
3. On pp 102, code for Example 3-4. The line "LOP\_2 COMPF PORTB, F" should be: "LOP\_2 COMF PORTB, F"
4. On pp 104, under 'BZ' instruction, the second line of the short sample code is "JZ OVER". It should be "BZ OVER".
5. On pp 262, Example 7-13, "Write a C18 program to monitor bit PC5." PC5 should be RC5 to be consistent with PIC naming convention.
6. On pp 339, "Figure 9-5 Timer 0 16-bit Block Diagram", the labeling for PSA bit is wrong. (I have noticed that this figure is directly from the PIC datasheet, and it is wrong in the datasheet.) For PSA bit, 0 should be using the prescaler, and 1 should be bypassing the prescaler.
7. On pp 348, the second line under section "8-bit mode programming of Timer0", 'TMRL0' should be 'TMR0L'.
8. On pp 349, Example 9-16, last sentence of the description, "and the TH value to do that". TH should be TMR0L. Again, the second line from the bottom, "... when TMR0H=00." TMR0H should be TMR0L.
9. On pp 353, Figure 9-10, the line "T1CKPS2:T1CKPS0 D5 D4 Timer1 prescaler selector". T1CKPS2 should be T1CKPS1.
10. On pp 355, last paragraph, "In Example 9-23, we are using Timer1 as an event counter that counts up as clock pulses are fed into pin 3.5." Timer1 should be Timer0, and pin 3.5 should be pin T0CKI/RA4.
11. On pp 358, Example 9-24. The description of the problem says "Set the initial value of TMR0L to -60", yet in the code, the initial value is 0. Here is the code snippet from the book:

```
HERE MOVLW 0x0 ;TMR0L = 0
MOVWF TMR0L ;load Timer0
```

The description or the code needs modification so that they are consistent.

12. On pp 361, Example 9-27, there is a code error in the second line from the bottom:  
BCF PIR1, TMR1ON

This line should be "BCF T1CON, TMR1ON".

13. On pp 397, the 6th line from the bottom:  
"Desired Baud Rate =  $F_{osc}/64(X+1) = 10 \text{ MHz}/64(X+1) = 6250 \text{ Hz}/(X+1)$ "  
The number 6250 should be 156250.
14. On pp 400, Figure 10-9, under the description of BRGH bit, "We can double the baud rate...". The word 'double' should be 'quadruple'.
15. On pp 436, inside the main(void code):  
INTCONbits.TMR0IE = 1; //enable Timer0 interrupt  
INTCONbits.TMR0IE = 1; //enable Timer1 interrupt

The second line should be "PIE1bits.TMR1IE = 1". This line will enable Timer1 interrupt.

16. On pp 464, the chk\_isr code:

```
void chk_isr(void)
{
    if (PIR1bits.TMR1IF == 1) //Timer0 cause interrupt?
```

"PIR1bits.TMR1IF == 1" should be "INTCONbits.TMR0IF == 1".

17. On pp 465, there are two minor comments mistakes. For the line inside T0\_ISR(void)  
myPC0bit = ~myPC0bit; //toggle RB1

RB1 should be RC0.

For the line inside T1\_ISR(void)

myPC1bit = ~myPC1bit; //toggle RB1

RB1 should be RC1.

18. On pp 510, the last sentence of the first paragraph, “Notice that Tad cannot be faster than 1.6 ms.” ‘1.6 ms’ should be ‘1.6  $\mu$ s’.

| Page | Error           | Name                      | Affiliation                 |
|------|-----------------|---------------------------|-----------------------------|
| 104  | JZ should be BZ | Prof. Jessica J. du Maine | St. Louis Community College |
| 109  | JZ should be BZ | Prof. Jessica J. du Maine | St. Louis Community College |

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