

/*FARM AUTOMATION MAIN SOURCE CODE*/

/******

- Controller: ATmega32 (8 MHz)
- Compiler: AVR STUDIO 4.5
- Date: 27 April 2011

*****/

#include <avr/io.h>

#include <util/delay.h>

#include "I2C.h"

#include "lcd.h"

#include "ds1307.h"

void ShowMainMenu();

void SetTime();

void SetonTime();

void SetoffTime();

void SetDate();

static void InitADC(void);

static long ReadTemp(void);

static void DisplayReading(long Reading);

unsigned char flag1=0,check=0,i=0;

/******

Function Name: InitADC

Purpose : Initializes ADC

*****/

static void InitADC(void)

{

 // 1. ADC Enable

 // 2. ADC Prescaler Select Bits: ADPS2 ADPS1 ADPS0 => 1 1 1 =>

Prescaler = 128

 ADCSRA = _BV(ADEN) | _BV(ADPS2) | _BV(ADPS1) | _BV(ADPS0);

 ADMUX=(1<<REFS0);

 ADMUX=(1<<REFS1);

 ADCSRA |= _BV(ADSC);

 while(!(ADCSRA & (1<<ADIF)));

 return;

}

/******

Function Name: ReadTemp

Purpose : Returns ADC value after conversion

*****/

static long ReadTemp(void)

{

 ADCSRA |= _BV(ADSC);

 //Wait for conversion to complete

 while(!(ADCSRA & (1<<ADIF)));

```

        //_delay_ms(5000);
        //Clear ADIF by writing one to it
        ADCSRA|=(1<<ADIF);
        return ADC;
    }

/*****
Function Name: DisplayReading
Purpose      : Displays voltage reading on LCD
*****/
static void DisplayReading(long Reading)
{
    int d2, d3, d4;
    int voltage;
    unsigned char a[2]={0xDF,'\0'};
    voltage= Reading/4;
    d4=voltage%10;
    voltage=voltage/10;
    d3=voltage%10;
    d2=voltage/10;
    if ((d4<=3) && (d3<=3) && (d2==0))
    {
        DDRB|=(1<<PB5)|(1<<PB3);//sprinkler
        PORTB &=0xD7;
    }

    if ((d4>3) && (d3=3) && (d2==0))
    {
        check=PINC;
        check &= (0b00111000);

        if(check==0b00000000)//HIGH LEVEL
        {
            DDRB|=(1<<PB5);//sprinkler
            PORTB|=(1<<5);
            PORTB &=0xF7;
            LCDClear();
            LCDWriteString("SPRINKLER'S ON");
            _delay_ms(2000);
            _delay_ms(2000);
            _delay_ms(2000);
        }
        else if(check==0b00100000)
        {
            DDRB|=(1<<PB3);//drip

            PORTB|=(1<<3);
            PORTB &=0xDF;
            LCDClear();
            LCDWriteString("DRIP SYSTEM ON");
            _delay_ms(2000);
            _delay_ms(2000);
            _delay_ms(2000);
        }
    }
}

```

```

    }
    else if(check==0b00110000)
    {
        DDRB|=(1<<PB5)|(1<<PB3); //_BV(3);
        PORTB &=0xD7;
        LCDClear();
        LCDWriteString("Message!!!");
        LCDWriteStringXY(0,1,"LOW WATER LEVEL");
        _delay_ms(2000);
        _delay_ms(2000);
        _delay_ms(2000);
    }
    for(i=0;i<5;i++)
        _delay_ms(1000);
    LCDClear();
}

LCDWriteString(" T:");
LCDWriteInt(d2,1);
LCDWriteInt(d3,1);
LCDWriteInt(d4,1);
LCDWriteString(a);
LCDWriteString("C");
_delay_ms(500);

return;
}

```

```
uint8_t PREV_PINB=0xFF;
```

```

/*
Function to test the current status of keys(0 to 2)

```

```

returns
0 if NOT pressed
1 if Pressed
*/
uint8_t GetKeyStatus(uint8_t key)
{
    return (!(PINB & (1<<key)));
}

```

```

/*
Function to test the previous status of keys(0 to 2)

```

```

returns
0 if NOT pressed
1 if Pressed
*/
uint8_t GetPrevKeyStatus(uint8_t key)
{
    return (!(PREV_PINB & (1<<key)));
}

```

```

unsigned char
key_flag=0,stage,to1,to2,ts1,ts2,to3,to4,to5,to6,ts3,ts4,ts5,ts6,dt1,mn1,yr
1,do1,do2,do3,do4,do5,do6;

int main()
{
    //Wait Util Other device startup
    _delay_ms(50);

    //Initialize the LCD Module
    LCDInit(0x00);
    DDRC|=_BV(5)|_BV(3)|_BV(4);
    PORTC|=_BV(3)|_BV(4)|_BV(5);
    // DDRB|=_BV(3)|_BV(4);
    //PORTB&=0xE7;

    DDRC|=~_BV(5)|~_BV(3)|~_BV(4);
    PINC |=_BV(3)|_BV(4)|_BV(5); //input pins
    DDRC|=_BV(6); //output pin
    PORTC &=0xBF;

    //Initialize I2C Bus
    I2CInit();
    InitADC();

    //Enable Pull ups on keys
    PORTB|=0xFF;

    /*Initializing RTC with intial conditions*/

    #define CH 7

    uint8_t temp;
    DS1307Read(0x00,&temp);
    temp&=~(1<<CH); //Clear CH bit of RTC
    DS1307Write(0x00,temp);

    DS1307Read(0x02,&temp);
    temp|=(0b00000000); //Set 24Hour BIT
    DS1307Write(0x02,temp); //Write Back to DS1307

    DS1307Read(0x04,&temp); //Set dATE Mode
    temp=(0b00010101);
    DS1307Write(0x04,temp); //Write Back to DS1307

    DS1307Read(0x05,&temp); //Set month Mode
    temp=(0b00000101);
    DS1307Write(0x05,temp); //Write Back to DS1307

```

```

DS1307Read(0x06,&temp);           //Set year Mode
temp=(0b00010001);
DS1307Write(0x06,temp);           //Write Back to DS1307

DS1307Read(0x03,&temp);           //Set day Mode
temp=(0b00000111);
DS1307Write(0x03,temp);           //Write Back to DS1307

LCDClear();

LCDWriteString("  WELCOME!!!");
_delay_ms(5000);
_delay_ms(5000);
_delay_ms(5000);
_delay_ms(5000);

LCDClear();
//LCDLoading();

LCDWriteString(" RTC BASED ");
LCDWriteStringXY(0,1,"AUTOMATED FARM");
_delay_ms(5000);
_delay_ms(5000);
_delay_ms(5000);
_delay_ms(5000);

LCDClear();
// LCDLoading();

char Time[12],Time1[10]; //hh:mm:ss AM/PM
unsigned int t,flag=0;
//Now Read and format time
uint8_t data;

while(1)
{
    DS1307Read(0x00,&data);           //Reading sec
    Time[8]='\0';
    Time[7]=0x30+(data & 0b00001111);
    Time[6]=0x30+((data & 0b01110000)>>4);
    Time[5]=': ';

    DS1307Read(0x01,&data);           //Reading minute

    Time[4]=0x30+(data & 0b00001111);
    Time[3]=0x30+((data & 0b01110000)>>4);
    Time[2]=': ';

    DS1307Read(0x02,&data);           //Reading hr

    Time[1]=0x30|(data & 0b00001111);

```

```

Time[0]=0x30|((data & 0b00110000)>>4);

if((Time[1]==ts2)&&(Time[0]==ts1)&&(Time[6]==ts5)&&(Time[3]==ts3)&&(Time[4]
==ts4)&&(Time[7]==ts6))
//Edited @2
{
    DDRC|=(1<<PC6);
    PORTC &=0xBF;
    flag=1;
    LCDClear();
    LCDWriteString("    Motor off!!!");
    _delay_ms(5000);
    _delay_ms(5000);
}

DS1307Read(0x04,&data);
//DATE
Time1[1]=(0x30+(data & 0b00001111));
Time1[0]=(48+((data & 0b00110000)>>4));

//month
DS1307Read(0x05,&data);
Time1[4]=(0x30+(data & 0b00001111));
Time1[3]=(0x30+((data & 0b00010000)>>4));
Time1[2]='.';

//Year
DS1307Read(0x06,&data);
Time1[9]=(0x30+(data & 0b00001111));
Time1[8]=(0x30+((data & 0b11110000)>>4));
Time1[5]='.';
Time1[6]=50;
Time1[7]=48;

if((Time[1]==to2)&&(Time[0]==to1)&&(Time[6]==to5)&&(Time[3]==to3)&&(Time[4]
==to4)&&(Time[7]==to6))
//Edited @2
{
    DDRC|=(1<<PC6);
    PORTC|=0xff;
    flag=1;
    LCDClear();
    LCDWriteString("    Motor on!!!");
    _delay_ms(5000);
    _delay_ms(5000);
}
LCDClear();
LCDWriteString(Time);
DisplayReading(ReadTemp());
LCDWriteStringXY(0,1,Time1);

```

```

DS1307Read(0x03,&data);
t=((data & 0b00000111));
switch(t)
{

    case 1:LCDWriteStringXY(10,1," MON  ");
            break;

    case 2:LCDWriteStringXY(10,1," TUE  ");
            break;

    case 3:LCDWriteStringXY(10,1," WED  ");
            break;

    case 4:LCDWriteStringXY(10,1," THU  ");
            break;

    case 5:LCDWriteStringXY(10,1," FRI  ");
            break;

    case 6:LCDWriteStringXY(10,1," SAT  ");
            break;

    case 7 :LCDWriteStringXY(10,1," SUN  ");
            break;

}

```

```

_delay_ms(5000);

```

```

uint8_t i;
for(i=0;i<20;i++)
{

    if(GetKeyStatus(2))
    {
        //Go To Main Menu
        ShowMainMenu();
        _delay_loop_2(0);
        _delay_loop_2(0);
        _delay_loop_2(0);

    }
    _delay_loop_2(5000);
}
}

```

```

return 0;
}

```

```

void ShowMainMenu()

```

```

{
    //The Main Menu
    char *menu_items[]={ "Set Time",
                          "Set Date",
                          "Set On Time",
                          "Set off Time",
                          "Quit"
                        };

    uint8_t menu_count=5;
    uint8_t selected=0;

    while(1)
    {
        LCDClear();
        LCDWriteString("    Main Menu  ");
        LCDWriteStringXY(2,1,menu_items[selected]);
        LCDWriteStringXY(0,1,"<");
        LCDWriteStringXY(15,1,">");
        _delay_ms(5000);
        _delay_ms(5000);
        _delay_ms(5000);

        if(GetKeyStatus(1))
        {
            //Left Key(No 1) is pressed
            //Check that it was not pressed previously
            if(!GetPrevKeyStatus(1))
            {
                if(selected !=0)
                    selected--;
            }
        }

        if(GetKeyStatus(0))
        {
            //Right Key(No 0) is pressed
            //Check that it was not pressed previously
            if(!GetPrevKeyStatus(0))
            {
                if(selected !=(menu_count-1))
                    selected++;
            }
        }

        if(GetKeyStatus(2))
        {
            //Enter Key Pressed
            //Check that it was not pressed previously
            if(!GetPrevKeyStatus(2))
            {
                //Call Appropriate Function
                switch (selected)
                {
                    case 0:

```



```

        SetTime();
        //key_flag=1;
        break;

    case 1: SetDate();
        break;

    case 2: SetonTime();
        //SetonDate();
        break;
    case 3: SetoffTime();
        break;
    case 4: flag1=1;
        LCDClear();
        LCDWriteString("Thank You!!");
        _delay_ms(5000);
        _delay_ms(5000);
        _delay_ms(5000);
        // _delay_ms(500);
        break;
        //Quit
    }

    }

    if(flag1==1)
    {
        flag1=0;
        break;
    }

    PREV_PINB=PINB;

    _delay_ms(50);
}

}

void SetTime()
{

    uint8_t hr,min,sec,temp;//am_pm

    //Read the Second Register
    DS1307Read(0x00,&temp);
    sec=((temp & 0b01110000)>>4)*10+(temp & 0b00001111);

    //Read the Minute Register
    DS1307Read(0x01,&temp);
    min=((temp & 0b01110000)>>4)*10+(temp & 0b00001111);

    //Read the Hour Register
    DS1307Read(0x02,&temp);
    hr=((temp & 0b00110000)>>4)*10+(temp & 0b00001111);

```

```

//If Hour Register is 0 make it 24
if(hr==0) hr=24;

uint8_t sel=0;

while(1)
{
    LCDClear();

    LCDWriteString("00:00:00<OK>");
    LCDWriteIntXY(0,0,hr,2);
    LCDWriteIntXY(3,0,min,2);
    LCDWriteIntXY(6,0,sec,2);

    //Draw Pointer
    LCDWriteStringXY(sel*3,1,"^^");

    //Input Up key
    if(GetKeyStatus(1))
    {
        if(!GetPrevKeyStatus(1))
        {
            if(sel==0)
            {
                //Hour
                if(hr==23)
                {
                    hr=0;
                }
                else
                {
                    hr++;
                }
            }

            if(sel==1)
            {
                //Min
                if(min==59)
                {
                    min=0;
                }
                else
                {
                    min++;
                }
            }

            if(sel==2)
            {
                //Sec

```

```

        if(sec==59)
        {
            sec=0;
        }
        else
        {
            sec++;
        }
    }

    if(sel==3)
    {
        //OK
        //break;
    }
}

//Input Down
if(GetKeyStatus(0))
{
    if(!GetPrevKeyStatus(0))
    {
        if(sel==0)
        {
            //Hour
            if(hr==0)
            {
                hr=23;
            }
            else
            {
                hr--;
            }
        }

        if(sel==1)
        {
            //Min
            if(min==0)
            {
                min=59;
            }
            else
            {
                min--;
            }
        }

        if(sel==2)
        {
            //Sec
            if(sec==0)

```

```

        {
            sec=59;
        }
        else
        {
            sec--;
        }
    }

    if(sel == 3)
    {
        //OK
        break;
    }
}

if(GetKeyStatus(2))
{
    if(!GetPrevKeyStatus(2))
    {
        //Change Selection
        if(sel==3)
            sel=0;
        else
            sel++;
    }
}

PREV_PINB=PINB;

_delay_loop_2(30000);

}

//Now write time back to RTC Module
temp=((sec/10)<<4)|(sec%10);
DS1307Write(0x00,temp);

temp=((min/10)<<4)|(min%10);
DS1307Write(0x01,temp);

temp=((hr/10)<<4)|(hr%10);
temp|=0b00000000; //24 Hr

DS1307Write(0x02,temp);
flag1=1;
LCDClear();
LCDWriteString(" Message !");
LCDWriteStringXY(0,1,"Main Time Set");
_delay_ms(5000);
_delay_ms(5000);
_delay_ms(5000);

```

```

    uint8_t i;
    for(i=0;i<10;i++)
        _delay_loop_2(0);
    return;
}

void SetonTime()
{
    uint8_t hr1,min1,sec1,temp;

    //Read the Second Register
    DS1307Read(0x00,&temp);
    sec1=((temp & 0b01110000)>>4)*10+(temp & 0b00001111);

    //Read the Minute Register
    DS1307Read(0x01,&temp);
    min1=((temp & 0b01110000)>>4)*10+(temp & 0b00001111);

    //Read the Hour Register
    DS1307Read(0x02,&temp);
    hr1=((temp & 0b00110000)>>4)*10+(temp & 0b00001111);

    //If Hour Register is 0 make it 24
    if(hr1==0) hr1=24;

    uint8_t sel=0;

    while(1)
    {
        LCDClear();

        LCDWriteString("00:00:00<OK>");
        LCDWriteIntXY(0,0,hr1,2);
        LCDWriteIntXY(3,0,min1,2);
        LCDWriteIntXY(6,0,sec1,2);

        //Draw Pointer
        LCDWriteStringXY(sel*3,1,"^^");

        //Input Up key
        if(GetKeyStatus(1))
        {
            if(!GetPrevKeyStatus(1))
            {
                if(sel==0)
                {
                    //Hour
                    if(hr1==23)
                    {
                        hr1=0;

```

```

        }
        else
        {
            hr1++;
        }
    }

    if(sel==1)
    {
        //Min
        if(min1==59)
        {
            min1=0;
        }
        else
        {
            min1++;
        }
    }

    if(sel==2)
    {
        //Sec
        if(sec1==59)
        {
            sec1=0;
        }
        else
        {
            sec1++;
        }
    }

    if(sel==3)
    {
        //OK
        //break;
    }
}

//Input Down
if(GetKeyStatus(0))
{
    if(!GetPrevKeyStatus(0))
    {
        if(sel==0)
        {
            //Hour
            if(hr1==0)
            {
                hr1=23;
            }
        }
    }
}

```

```

        else
        {
            hr1--;
        }
    }

    if(sel==1)
    {
        //Min
        if(min1==0)
        {
            min1=59;
        }
        else
        {
            min1--;
        }
    }

    if(sel==2)
    {
        //Sec
        if(sec1==0)
        {
            sec1=59;
        }
        else
        {
            sec1--;
        }
    }

    if(sel == 3)
    {
        //OK
        break;
    }
}

if(GetKeyStatus(2))
{
    if(!GetPrevKeyStatus(2))
    {
        //Change Selection
        if(sel==3)
            sel=0;
        else
            sel++;
    }
}

PREV_PINB=PINB;

```

```

        _delay_loop_2(30000);

    }

    to2= 0x30|(hr1%10);
    to1= 0x30|(hr1/10);
    to4= 0x30|(min1%10);
    to3= 0x30|(min1/10);
    to6= 0x30|(sec1%10);
    to5= 0x30|(sec1/10);
    flag1=1;
    LCDClear();
    LCDWriteString(" Message !");
    LCDWriteStringXY(0,1,"On Time Set!!");
    _delay_ms(5000);
    _delay_ms(5000);
    _delay_ms(5000);
    _delay_ms(500);
    _delay_ms(500);
    _delay_ms(500);
    uint8_t i;
    for(i=0;i<10;i++)
        _delay_loop_2(0);
    return;
}

void SetoffTime()
{

    uint8_t hr2,min2,sec2,temp;

    //Read the Second Register
    DS1307Read(0x00,&temp);
    sec2=((temp & 0b01110000)>>4)*10+(temp & 0b00001111);

    //Read the Minute Register
    DS1307Read(0x01,&temp);
    min2=((temp & 0b01110000)>>4)*10+(temp & 0b00001111);

    //Read the Hour Register
    DS1307Read(0x02,&temp);
    hr2=((temp & 0b00110000)>>4)*10+(temp & 0b00001111);

    //If Hour Register is 0 make it 24, as 00:00:00 invalid time
    if(hr2==0) hr2=24;

    uint8_t sel=0;

    while(1)
    {
        LCDClear();

        LCDWriteString("00:00:00<OK>");
    }
}

```



```

LCDWriteIntXY(0,0,hr2,2);
LCDWriteIntXY(3,0,min2,2);
LCDWriteIntXY(6,0,sec2,2);

//Draw Pointer
LCDWriteStringXY(sel*3,1,"^^");

//Input Up key
if(GetKeyStatus(1))
{
    if(!GetPrevKeyStatus(1))
    {
        if(sel==0)
        {
            //Hour
            if(hr2==23)
            {
                hr2=0;
            }
            else
            {
                hr2++;
            }
        }

        if(sel==1)
        {
            //Min
            if(min2==59)
            {
                min2=0;
            }
            else
            {
                min2++;
            }
        }

        if(sel==2)
        {
            //Sec
            if(sec2==59)
            {
                sec2=0;
            }
            else
            {
                sec2++;
            }
        }

        if(sel==3)
        {

```

```

        //OK
        //break;
    }
}

//Input Down
if(GetKeyStatus(0))
{
    if(!GetPrevKeyStatus(0))
    {
        if(sel==0)
        {
            //Hour
            if(hr2==0)
            {
                hr2=23;
            }
            else
            {
                hr2--;
            }
        }

        if(sel==1)
        {
            //Min
            if(min2==0)
            {
                min2=59;
            }
            else
            {
                min2--;
            }
        }

        if(sel==2)
        {
            //Sec
            if(sec2==0)
            {
                sec2=59;
            }
            else
            {
                sec2--;
            }
        }

        if(sel == 3)
        {
            //OK
            break;
        }
    }
}

```

```

        }
    }

    if(GetKeyStatus(2))
    {
        if(!GetPrevKeyStatus(2))
        {
            //Change Selection
            if(sel==3)
                sel=0;
            else
                sel++;
        }
    }

    PREV_PINB=PINB;

    _delay_loop_2(30000);

}

ts2= 0x30|(hr2%10);
ts1= 0x30|(hr2/10);
ts4= 0x30|(min2%10);
ts3= 0x30|(min2/10);
ts6= 0x30|(sec2%10);
ts5= 0x30|(sec2/10);
flag1=1;
LCDClear();
LCDWriteString(" Message !");
LCDWriteStringXY(0,1,"Off Time Set!!");
_delay_ms(5000);
_delay_ms(5000);
_delay_ms(5000);
_delay_ms(5000);
//_delay_ms(5000);
//_delay_ms(500);
uint8_t i;
for(i=0;i<10;i++)
    _delay_loop_2(0);
return;
}

void SetDate()
{
    uint8_t dt,mn,yr,temp;
    //Read the Second Register
    DS1307Read(0x04,&temp);
    dt=((temp & 0b00110000)>>4)*10+(temp & 0b00001111);

    //Read the Minute Register
    DS1307Read(0x05,&temp);
    mn=((temp & 0b00010000)>>4)*10+(temp & 0b00001111);

```

```

//Read the Hour Register
DS1307Read(0x06,&temp);
yr=((temp & 0b11110000)>>4)*10+(temp & 0b00001111);

uint8_t sel=0;

while(1)
{
    LCDClear();

    LCDWriteString("00:00:00<OK>");
    LCDWriteIntXY(0,0,dt,2);
    LCDWriteIntXY(3,0,mn,2);
    LCDWriteIntXY(6,0,yr,2);

    //Draw Pointer
    LCDWriteStringXY(sel*3,1,"^^");

    //Input Up key
    if(GetKeyStatus(1))
    {
        if(!GetPrevKeyStatus(1))
        {
            if(sel==0)
            {
                //Date
                if(dt==31)
                {
                    dt=0;
                }
                else
                {
                    dt++;
                }
            }
            if(sel==1)
            {
                //Month
                if(mn==12)
                {
                    mn=0;
                }
                else
                {
                    mn++;
                }
            }
            if(sel==2)
            {
                //year
                if(yr==99)
                {
                    yr=0;
                }
            }
        }
    }
}

```

```

        }
        else
        {
            yr++;
        }
    }
    if(sel==3)
    {
        //OK
        //break;
    }
}

//Input Down
if(GetKeyStatus(0))
{
    if(!GetPrevKeyStatus(0))
    {
        if(sel==0)
        {
            //Day
            if(dt==0)
            {
                dt=31;
            }
            else
            {
                dt--;
            }
        }

        if(sel==1)
        {
            //Month
            if(mn==0)
            {
                mn=12;
            }
            else
            {
                mn--;
            }
        }

        if(sel==2)
        {
            //Year
            if(yr==0)
            {
                yr=99;
            }
            else
            {

```

```

        yr--;
    }
}

if(sel == 3)
{
    //OK
    break;
}
}

if(GetKeyStatus(2))
{
    if(!GetPrevKeyStatus(2))
    {
        //Change Selection
        if(sel==3)
            sel=0;
        else
            sel++;
    }
}

PREV_PINB=PINB;

    _delay_loop_2(30000);
}
flag1=1;

temp=((yr/10)<<4)|(yr%10);
DS1307Write(0x06,temp);

temp=((mn/10)<<4)|(mn%10);
DS1307Write(0x05,temp);

temp=((dt/10)<<4)|(dt%10);
DS1307Write(0x04,temp);
LCDClear();
LCDWriteString("  Message !");
LCDWriteStringXY(0,1,"main Date Set!!");

    _delay_ms(5000);
    _delay_ms(5000);
    _delay_ms(5000);
    _delay_ms(500);
    _delay_ms(500);
    _delay_ms(500);
    uint8_t i;
    for(i=0;i<10;i++)
        _delay_loop_2(0);
    return;
}

```

/*DS1307 SOURCE FILE */

```
#include <avr/io.h>
#include <util/delay.h>
```

```
#include "I2C.h"
#include "ds1307.h"
```

```
/******
```

Function To Read Internal Registers of DS1307

address : Address of the register
data: value of register is copied to this.

Returns:

0= Failure

1= Success

```
*****/
```

```
extern void LCDByte(uint8_t c,uint8_t isdata);
```

```
uint8_t DS1307Read(uint8_t address,uint8_t *data)
```

```
{
```

```
    uint8_t res;    //result
```

```
                                //Start
```

```
    _delay_loop_2(15);
    I2CStart();
```

```
    //SLA+W (for dummy write to set register pointer)
    res=I2CWriteByte(0b11010000);    //DS1307 address + W
```

```
    //Error
    if(!res)    return FALSE;
```

```
//    LCDByte('B',1);
```

```
    //Now send the address of required register
    res=I2CWriteByte(address);
```

```
    //Error
    if(!res)    return FALSE;
```

```
    //Repeat Start
    I2CStart();
```

```
    //SLA + R
    res=I2CWriteByte(0b11010001);    //DS1307 Address + R
```

```
    //Error
    if(!res)    return FALSE;
```

```
    //Now read the value with NACK
```

```

        res=I2CReadByte(data,0);

        //Error
        if(!res)    return FALSE;

        //STOP
        I2CStop();

        return TRUE;
    }

/*****

Function To Write Internal Registers of DS1307
-----

address : Address of the register
data: value to write.

Returns:
0= Failure
1= Success
*****/

uint8_t DS1307Write(uint8_t address,uint8_t data)
{
    uint8_t res;    //result

    //Start
    I2CStart();

    //SLA+W
    res=I2CWriteByte(0b11010000);    //DS1307 address + W

    //Error
    if(!res)    return FALSE;

    //Now send the address of required register
    res=I2CWriteByte(address);

    //Error
    if(!res)    return FALSE;

    //Now write the value
    res=I2CWriteByte(data);

    //Error
    if(!res)    return FALSE;

    //STOP
    I2CStop();

    return TRUE;
}

```


/*I2C SOURCE FILE*/

```
#include <avr/io.h>
#include <util/delay.h>

#include "I2C.h"

void I2CInit()
{
    //Set up TWI Module
    TWBR = 2;
    TWSR |= (1<<TWPS1) | (1<<TWPS0);

    //Enable the TWI Module
    TWCR |= (1<<TWEN);
}

void I2CClose()
{
    //Disable the module
    TWCR &= ~(1<<TWEN);
}

void I2CStart()
{
    //Put Start Condition on Bus
    TWCR = (1<<TWINT) | (1<<TWEN) | (1<<TWSTA);

    //Poll Till Done
    while(!(TWCR & (1<<TWINT)));
}

void I2CStop()
{
    //Put Stop Condition on bus
    TWCR = (1<<TWINT) | (1<<TWEN) | (1<<TWSTO);

    //Wait for STOP to finish
    while(TWCR & (1<<TWSTO));
    //_delay_loop_2(250);
}

uint8_t I2CWriteByte(uint8_t data)
{
    TWDR = data;
    //Initiate Transfer
    TWCR = (1<<TWEN) | (1<<TWINT);
}
```

```

//Poll Till Done
while(!(TWCR & (1<<TWINT)));

//Check Status
if((TWSR & 0xF8) == 0x18 || (TWSR & 0xF8) == 0x28 || (TWSR &
0xF8) == 0x40)
{
    //SLA+W Transmitted and ACK received
    //or
    //SLA+R Transmitted and ACK received
    //or
    //DATA Transmitted and ACK received

    return TRUE;
}
else
    return FALSE; //Error
}

uint8_t I2CReadByte(uint8_t *data,uint8_t ack)
{
    //Set up ACK
    if(ack)
    {
        //return ACK after reception
        TWCR|=(1<<TWEA);
    }
    else
    {
        //return NACK after reception
        //Signals slave to stop giving more data
        //usually used for last byte read.
        TWCR&=(~(1<<TWEA));
    }

    //Now enable Reception of data by clearing TWINT
    TWCR|=(1<<TWINT);

    //Wait till done
    while(!(TWCR & (1<<TWINT)));

    //Check status
    if((TWSR & 0xF8) == 0x58 || (TWSR & 0xF8) == 0x50)
    {
        //Data received and ACK returned
        //    or
        //Data received and NACK returned

        //Read the data

```

```

        *data=TWDR;
        return TRUE;
    }
    else
        return FALSE; //Error
}

```

/*LCD HEADER FILE*/

```

#include <avr/io.h>
#include <util/delay.h>

```

```

#include "myutils.h"

```

```

#ifndef _LCD_H
#define _LCD_H

```

```

/* _____ */

```

```

/*****
    LCD CONNECTIONS
*****/

```

```

#define LCD_DATA D    //Port PD0-PD3 are connected to D4-D7

```

```

#define LCD_E D //Enable OR strobe signal

```

```

#define LCD_E_POS      PD6 //Position of enable in above port

```

```

#define LCD_RS D

```

```

#define LCD_RS_POS PD4

```

```

#define LCD_RW D

```

```

#define LCD_RW_POS PD5

```

```

/*****

```

F U N C T I O N S

```

*****/

```

```

void LCDInit(uint8_t style);
void LCDWriteString(const char *msg);
void LCDWriteInt(int val,unsigned int field_length);
void LCDGotoXY(uint8_t x,uint8_t y);
//Low level
void LCDByte(uint8_t,uint8_t);
#define LCDCmd(c) (LCDByte(c,0))
#define LCDData(d) (LCDByte(d,1))

```

```

void LCDBusyLoop();

```

```

/*****

```

F U N C T I O N S E N D

```

*****/

```

```

/*****
                                M A C R O S
*****/
#define LCDClear() LCDCmd(0b00000001);
#define LCDHome() LCDCmd(0b00000010);

#define LCDWriteStringXY(x,y,msg) {\
    LCDGotoXY(x,y);\
    LCDWriteString(msg);\
}

#define LCDWriteIntXY(x,y,val,fl) {\
    LCDGotoXY(x,y);\
    LCDWriteInt(val,fl);\
}
/*****/

/*_____*/
#endif

```

/*LCD SOURCE FILE*/

```

#include <avr/io.h>
#include <inttypes.h>
#include <util/delay.h>

#include "lcd.h"

#define LCD_DATA_PORT      PORT(LCD_DATA)
#define LCD_E_PORT         PORT(LCD_E)
#define LCD_RS_PORT        PORT(LCD_RS)
#define LCD_RW_PORT        PORT(LCD_RW)

#define LCD_DATA_DDR       DDR(LCD_DATA)
#define LCD_E_DDR          DDR(LCD_E)
#define LCD_RS_DDR         DDR(LCD_RS)
#define LCD_RW_DDR         DDR(LCD_RW)

#define LCD_DATA_PIN       PIN(LCD_DATA)

#define SET_E() (LCD_E_PORT|=(1<<LCD_E_POS))
#define SET_RS() (LCD_RS_PORT|=(1<<LCD_RS_POS))
#define SET_RW() (LCD_RW_PORT|=(1<<LCD_RW_POS))

#define CLEAR_E() (LCD_E_PORT&=~(1<<LCD_E_POS))
#define CLEAR_RS() (LCD_RS_PORT&=~(1<<LCD_RS_POS))
#define CLEAR_RW() (LCD_RW_PORT&=~(1<<LCD_RW_POS))

void LCDByte(uint8_t c,uint8_t isdata)
{
    //Sends a byte to the LCD in 4bit mode
    //cmd=0 for data

```

```

//cmd=1 for command

//NOTE: THIS FUNCTION RETURNS ONLY WHEN LCD HAS PROCESSED THE COMMAND

uint8_t hn,ln;           //Nibbles
uint8_t temp;

hn=c>>4;
ln=(c & 0x0F);

if(isdata==0)
    CLEAR_RS();
else
    SET_RS();

_delay_us(0.500);
SET_E();

//Send high nibble

temp=(LCD_DATA_PORT & 0XF0)|(hn);
LCD_DATA_PORT=temp;

_delay_us(1);           //tEH

//Now data lines are stable pull E low for transmission

CLEAR_E();

_delay_us(1);

//Send the lower nibble
SET_E();

temp=(LCD_DATA_PORT & 0XF0)|(ln);

LCD_DATA_PORT=temp;

_delay_us(1);           //tEH

//SEND

CLEAR_E();

_delay_us(1);           //tEL

LCDBusyLoop();
}

void LCDBusyLoop()
{
    //This function waits till lcd is BUSY

    uint8_t busy,status=0x00,temp;

```

```

//Change Port to input type because we are reading data
LCD_DATA_DDR&=0xF0;

//change LCD mode
SET_RW();          //Read mode
CLEAR_RS();        //Read status

//Let the RW/RS lines stabilize

_delay_us(0.5);     //tAS

do
{
    SET_E();

    //Wait tDA for data to become available
    _delay_us(0.5);

    status=LCD_DATA_PIN;
    status=status<<4;

    _delay_us(0.5);

    //Pull E low
    CLEAR_E();
    _delay_us(1);    //tEL

    SET_E();
    _delay_us(0.5);

    temp=LCD_DATA_PIN;
    temp&=0x0F;

    status=status|temp;

    busy=status & 0b10000000;

    _delay_us(0.5);
    CLEAR_E();
    _delay_us(1);    //tEL
}while(busy);

CLEAR_RW();        //write mode
//Change Port to output
LCD_DATA_DDR|=0x0F;
}

void LCDInit(uint8_t style)
{
    //After power on Wait for LCD to Initialize
    _delay_ms(30);

```

```

//Set IO Ports
LCD_DATA_DDR|=(0x0F);
LCD_E_DDR|=(1<<LCD_E_POS);
LCD_RS_DDR|=(1<<LCD_RS_POS);
LCD_RW_DDR|=(1<<LCD_RW_POS);

LCD_DATA_PORT&=0XF0;
CLEAR_E();
CLEAR_RW();
CLEAR_RS();

_delay_us(0.3);

SET_E();
LCD_DATA_PORT|=(0b00000010);
_delay_us(1);
CLEAR_E();
_delay_us(1);

//Wait for LCD to execute the Functionset Command
LCDBusyLoop();

//Now the LCD is in 4-bit mode
LCDCmd(0b00001100|style); //Display On,cursor off,blink off is
style=0x00;
LCDCmd(0b00101000); //function set 4-bit,2 line 5x8 dot
format
LCDCmd(0b00000001);
}
void LCDWriteString(const char *msg)
{
    /*This function Writes a given string to lcd at the current cursor
    location.
    Arguments: msg: a null terminated string to print */
    while(*msg!='\0')
    {
        LCDData(*msg);
        msg++;
    }
}

void LCDWriteInt(int val,unsigned int field_length)
{
    /* This function writes a integer type value to LCD module
    Arguments:
    1)int val: Value to print
    2)unsigned int field_length :total length of field in which the value
    is printed
    must be between 1-5 if it is -1 the field length is no of digits in
    the val */

    char str[5]={0,0,0,0,0};

```

```

    int i=4,j=0;
    while(val)
    {
        str[i]=val%10;
        val=val/10;
        i--;
    }
    if(field_length== -1)
        while(str[j]==0) j++;
    else
        j=5-field_length;

    if(val<0) LCDDData('-');
    for(i=j;i<5;i++)
    {
        LCDDData(48+str[i]);
    }
}
void LCDGotoXY(uint8_t x,uint8_t y)
{
    if(x<16)
    {
        if(y) x|=0b01000000;
        x|=0b10000000;
        LCDCmd(x);
    }
}

```