# Q# 0.10 Language Quick Reference

Primitive Types	
64-bit integers	Int
Double-precision floats	Double
Booleans	Bool
	e.g.: true or false
Qubits	Qubit
Pauli basis	Pauli
	e.g.: PauliI, PauliX, PauliY, or PauliZ
Measurement	Result
results	e.g.: Zero or One
Sequences of	Range
integers	e.g.: 110 or 510
Strings	String
	e.g.: "Hello Quantum!"
"Return no	Unit
information" type	e.g.: ()

Derived Types	
Arrays	elementType[]
Tuples	(type0, type1,) e.g.: (Int, Qubit)
Functions	<pre>input -&gt; output e.g.: ArcCos : (Double) -&gt; Double</pre>
Operations	<pre>input =&gt; output is variants e.g.: H : (Qubit =&gt; Unit is Adj)</pre>

User-Defined Ty	pes
Declare UDT with anonymous items	newtype <i>Name</i> = (Type, Type); e.g.: newtype <i>Pair</i> = (Int, Int);
Define UDT literal	<pre>Name(baseTupleLiteral) e.g.: let origin = Pair(0, 0);</pre>
Unwrap operator ! (convert UDT to underlying type) Declare UDT with named items	<pre>VarName! e.g.: let originTuple = origin!;   (now originTuple = (0, 0)) newtype Name =           (Name1: Type, Name2: Type);</pre>
	<pre>e.g.: newtype Complex =     (Re : Double, Im : Double);</pre>
Accessing named items of UDTs	<pre>VarName::ItemName e.g.: complexVariable::Re</pre>
Update-and- reassign for named UDT items	<pre>set VarName w/= ItemName &lt;- val; e.g.: mutable p = Complex(0., 0.); set p w/= Re &lt;- 1.0;</pre>

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Symbols and Variables

Declare immutable symbol

Declare mutable symbol (variable)

Update mutable symbol (variable)

Update mutable symbol (variable)

Apply-and-reassign set varName operator= expression e.g.: set counter += 1;
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Functions and Operations
Define function
                    function Name(in0 : type0, ...)
(classical routine)
                    : returnType {
                         // function body
Call function
                    Name(parameters)
                    e.g.: let two = Sqrt(4.0);
                    operation Name(in0 : type0, ...)
Define operation
(quantum routine)
                    : returnType {
with explicitly
                         body { ... }
specified body,
                         adjoint { ... }
controlled and
                         controlled { ... }
adjoint variants
                         adjoint controlled { ... }
                    operation Name(in0 : type0, ...)
Define operation
with automatically
                    : returnType is Adj + Ctl {
generated adjoint
and controlled
variants
Call operation
                    Name(parameters)
                    e.g.: Ry(0.5 * PI(), q);
Call adjoint
                    Adjoint Name(parameters)
operation
                    e.g.: Adjoint Ry(0.5 * PI(), q);
Call controlled
                    Controlled Name(controlQubits,
operation
                         parameters)
                    e.g.: Controlled Ry(controls,
                         (0.5 * PI(), target));
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Control Flow
Iterate over
                    for (index in range) {
a range of numbers
                         // Use integer index
                    e.g.: for (i in 0..N-1) { ... }
While loop
                    while (condition) {
(within functions)
Iterate over
                    for (val in array) {
an array
                         // Use value val
                    e.g.: for (q in register) { ... }
Repeat-until-
                    repeat { ... }
success loop
                    until (condition)
                    fixup { ... }
Conditional
                    if (cond1) { ... }
statement
                    elif (cond2) { ... }
                    else { ... }
Ternary operator
                    condition ? caseTrue | caseFalse
Return a value
                     return value
Stop with an error
                    fail "Error message"
Conjugations
                     within { ... }
(ABA^{\dagger} \text{ pattern})
                    apply { ... }
```

Arrays						
Allocate array	<pre>mutable name = new Type[length]</pre>					
	e.g.: mutable b = new Bool[2];					
Get array length	Length(name)					
Access k-th element	name[k]					
	NB: indices are 0-based					
Assign k-th element	set name w/= k <- value					
(copy-and-update)	e.g.: set b w/= 0 <- true;					
Array literal	[value0, value1,]					
	e.g.: let b = [true, false, true];					
Array concatenation	array1 + array2					
	e.g.: let t = [1, 2, 3] + [4, 5];					
Slicing (subarray)	name[sliceRange]					
	e.g.: if t = [1, 2, 3, 4, 5], then					
	t[1 3] is [2, 3, 4]					
t[3] is [4, 5]						
	t[ 1] is [1, 2]					
	t[0 2] is [1, 3, 5]					
	t[1] is [5, 4, 3, 2, 1]					

Debugging (classical)						
Print a string	Message("Hello Quantum!")					
Print an	<pre>Message(\$"Value = {val}")</pre>					
interpolated string						

### Resources

Documentation	
Quantum	https://docs.microsoft.com/
Development Kit	quantum
Q# Language	https://docs.microsoft.com/
Reference	quantum/language
Q# Libraries	https://docs.microsoft.com/
Reference	qsharp/api

Q# Code Repositories						
QDK Samples	https://github.com/microsoft/ quantum					
QDK Libraries	<pre>https://github.com/microsoft/ QuantumLibraries</pre>					
Quantum Katas (tutorials)	https://github.com/microsoft/ QuantumKatas					
Q# compiler and extensions	<pre>https://github.com/microsoft/ qsharp-compiler</pre>					
Simulation framework	<pre>https://github.com/microsoft/ qsharp-runtime</pre>					
Jupyter kernel and Python host	<pre>https://github.com/microsoft/ iqsharp</pre>					
Source code for the documentation	https://github.com/ MicrosoftDocs/quantum-docs-pr					

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## **Debugging (quantum)**

Print amplitudes of wave function Assert that a qubit is in  $|0\rangle$  or  $|1\rangle$  state DumpMachine("dump.txt") AssertQubit(Zero, zeroQubit) AssertQubit(One, oneQubit)

### Measurements

Measure qubit in Pauli Z basis yields a Result (Zero or One) Reset qubit to  $|0\rangle$  Reset an array of qubits to  $|0.0\rangle$  ResetAll(register)

## **Working with Q# from command line**

## **Command Line Basics**

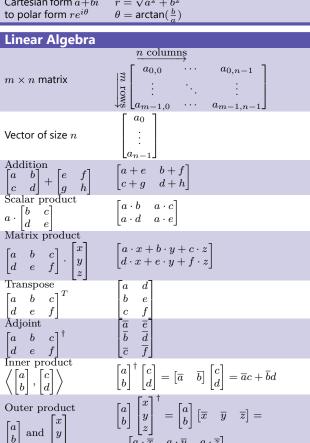
Change directory cd dirname
Go to home cd ~
Go up one directory cd ..
Make new directory mkdir dirname
Open current code .

#### Working with Q# Projects

Create new project	<pre>dotnet new console -lang Q#output project-dir</pre>
Change directory to project directory	cd project-dir
Build project	dotnet build
Run all unit tests	dotnet test

## Math reference

#### **Complex Arithmetic** (a+bi)+(c+di)(a+c)+(b+d)i(a+bi)(c+di) $a \cdot c + a \cdot di + b \cdot ci + (b \cdot d)i^2 =$ $= (a \cdot c - b \cdot d) + (a \cdot d + b \cdot c)i$ Complex conjugate $\overline{a+bi} = a-bi$ $\frac{a+bi}{c+di} \cdot 1 = \frac{a+bi}{c+di} \cdot \frac{c-di}{c-di} = \frac{(a+bi)(c+di)}{c^2+d^2}$ Division $\frac{a+bi}{c+di}$ $\sqrt{a^2+b^2}$ Modulus |a + bi| $\cos \theta + i \sin \theta$ $e^{a+bi}$ $e^a \cdot e^{bi} = e^a \cos b + ie^a \sin b$ $r^{a+bi}$ $r^a \cdot r^{bi} = r^a \cdot e^{bi \ln r} =$ $= r^a \cos(b \ln r) + i \cdot r^a \sin(b \ln r)$ Polar form $re^{i\theta}$ to $a = r \cos \theta$ Cartesian form a+bi $b = r \sin \theta$ Cartesian form a+bi $r = \sqrt{a^2 + b^2}$ to polar form $re^{i\theta}$ $\theta = \arctan(\frac{b}{a})$



 $b \cdot \overline{x} \quad b \cdot \overline{y} \quad b \cdot \overline{z}$ 

Gates reference							
Single Qubit gates						1 (10) 1 (14)	
Gate	Matrix representation	Ket-bra representation	Applying to $ \psi angle$	$=\alpha\left 0\right\rangle +\beta\left 1\right\rangle$	Applying to basis states:	$\ket{0}, \ket{1}, \ket{+}, \ket{-}$ and	$ \pm i\rangle = \frac{1}{\sqrt{2}}( 0\rangle \pm i 1\rangle)$
Χ	$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$	$ 0\rangle \langle 1  +  1\rangle \langle 0 $	$ \psi\rangle = \alpha  1\rangle + \beta$	$B\ket{0}$	$X  0\rangle =  1\rangle X  1\rangle =  0\rangle$	$\begin{array}{l} X \mid + \rangle = \mid + \rangle \\ X \mid - \rangle = - \mid - \rangle \end{array}$	$egin{aligned} X \left  i  ight angle &= i \left  -i  ight angle \ X \left  -i  ight angle &= -i \left  i  ight angle \end{aligned}$
Υ	$\begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$	$i(\ket{1}\bra{0}-\ket{0}\bra{1})$	$Y  \psi\rangle = i (\alpha  1\rangle$	$-\beta\ket{0}$ )	$Y  0\rangle = i  1\rangle Y  1\rangle = -i  0\rangle$	$Y \mid + \rangle = -i \mid - \rangle$ $Y \mid - \rangle = i \mid + \rangle$	$egin{aligned} Y\ket{i} &= \ket{i} \ Y\ket{-i} &= -\ket{-i} \end{aligned}$
Z	$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$	$ 0\rangle \left\langle 0 - 1\right\rangle \left\langle 1 $	$Z \psi\rangle = \alpha 0\rangle -$	$-\beta \ket{1}$	$Z  0\rangle =  0\rangle$ $Z  1\rangle = - 1\rangle$	$Z \mid + \rangle = \mid - \rangle$ $Z \mid - \rangle = \mid + \rangle$	$egin{aligned} Z \ket{i} &= \ket{-i} \ Z \ket{-i} &= \ket{i} \end{aligned}$
1	$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$	$ 0\rangle \langle 0  +  1\rangle \langle 1 $	$I\ket{\psi}=\ket{\psi}$				
Н	$\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$	$ 0\rangle\left\langle + + 1\right\rangle\left\langle - $	$H \psi\rangle = \alpha +\rangle$	$+\beta \left -\right\rangle = \frac{\alpha+\beta}{\sqrt{2}} \left 0\right\rangle + \frac{\alpha-\beta}{\sqrt{2}} \left 1\right\rangle$	$H  0\rangle =  +\rangle$ $H  1\rangle =  -\rangle$	$\begin{array}{l} H \mid + \rangle = \mid 0 \rangle \\ H \mid - \rangle = \mid 1 \rangle \end{array}$	$H \left  i \right\rangle = e^{i\pi/4} \left  -i \right\rangle \ H \left  -i \right\rangle = e^{-i\pi/4} \left  i \right\rangle$
S	$\begin{bmatrix} 1 & 0 \\ 0 & i \end{bmatrix}$	$ 0\rangle \left\langle 0\right  + i \left 1\right\rangle \left\langle 1\right $	$S\left \psi\right\rangle = \alpha\left 0\right\rangle +$	$ieta\ket{1}$	$S  0\rangle =  0\rangle$ $S  1\rangle = i  1\rangle$	$S \ket{+} = \ket{i}$ $S \ket{-} = \ket{-i}$	$S  i\rangle =  -\rangle$ $S  -i\rangle =  +\rangle$
Т	$\begin{bmatrix} 1 & 0 \\ 0 & e^{i\pi/4} \end{bmatrix}$	$\left 0\right\rangle \left\langle 0\right +e^{i\pi/4}\left 1\right\rangle \left\langle 1\right $	$T\left \psi\right\rangle = \alpha\left 0\right\rangle +$	$-e^{i\pi/4}eta\ket{1}$	$T\left 0\right\rangle = \left 0\right\rangle$	$T\left 1\right\rangle = e^{i\pi/4}\left 1\right\rangle$	
$R_x(\theta)$	$\begin{bmatrix} \cos\frac{\theta}{2} & -i\sin\frac{\theta}{2} \\ -i\sin\frac{\theta}{2} & \cos\frac{\theta}{2} \end{bmatrix}$	$\begin{array}{l} \cos \frac{\theta}{2} \left  0 \right\rangle \left\langle 0 \right  - i \sin \frac{\theta}{2} \left  1 \right\rangle \left\langle 0 \right  - \\ - i \sin \frac{\theta}{2} \left  0 \right\rangle \left\langle 1 \right  + \cos \frac{\theta}{2} \left  1 \right\rangle \left\langle 1 \right  \end{array}$	$R_x(\theta)  \psi\rangle = (\epsilon + (\beta \cos \frac{\theta}{2} - i\epsilon))$	$lpha\cosrac{ heta}{2}-ieta\sinrac{ heta}{2})\ket{0}+ lpha\sinrac{ heta}{2})\ket{1}$	$R_x(\theta)  0\rangle = \\ = \cos \frac{\theta}{2}  0\rangle - i \sin \frac{\theta}{2}  1\rangle$	$R_x(\theta) \left  1 \right\rangle = \\ = \cos \frac{\theta}{2} \left  1 \right\rangle - i \sin \frac{\theta}{2} \left  0 \right\rangle$	
$R_y(\theta)$	$\begin{bmatrix} \cos\frac{\theta}{2} & -\sin\frac{\theta}{2} \\ \sin\frac{\theta}{2} & \cos\frac{\theta}{2} \end{bmatrix}$	$\cos\frac{\theta}{2}\left 0\right\rangle\left\langle 0\right +\sin\frac{\theta}{2}\left 1\right\rangle\left\langle 0\right -\\-\sin\frac{\theta}{2}\left 0\right\rangle\left\langle 1\right +\cos\frac{\theta}{2}\left 1\right\rangle\left\langle 1\right $	$R_y(\theta)  \psi\rangle = (\alpha + (\beta \cos \frac{\theta}{2} + \alpha))$	$\cosrac{ heta}{2}-eta\sinrac{ heta}{2})\ket{0}+ \sinrac{ heta}{2})\ket{1}$	$R_y(\theta)  0\rangle = \\ = \cos \frac{\theta}{2}  0\rangle + \sin \frac{\theta}{2}  1\rangle$	$egin{aligned} R_y( heta) \left  1  ight angle = & \cos rac{ heta}{2} \left  1  ight angle - \sin rac{ heta}{2} \left  0  ight angle \end{aligned}$	
$R_z(\theta)$	$\begin{bmatrix} e^{-i\theta/2} & 0 \\ 0 & e^{i\theta/2} \end{bmatrix}$	$e^{-i\theta/2}\left 0\right\rangle \left\langle 0\right +e^{i\theta/2}\left 1\right\rangle \left\langle 1\right $	$R_z(\theta)  \psi\rangle = \alpha \epsilon$	$e^{-i\theta/2} \left  0 \right\rangle + \beta e^{i\theta/2} \left  1 \right\rangle$	$R_z(\theta)  0\rangle = e^{-i\theta/2}  0\rangle$	$R_z(\theta) \ket{1} = e^{i\theta/2} \ket{1}$	
$R_1(\theta)$	$\begin{bmatrix} 1 & 0 \\ 0 & e^{i\theta} \end{bmatrix}$	$ 0\rangle \langle 0  + e^{i\theta}  1\rangle \langle 1 $	$R_1(\theta)  \psi\rangle = \alpha  $	$ 0\rangle + \beta e^{i\theta}  1\rangle$	$R_1(\theta) 0\rangle =  0\rangle$	$R_1(\theta)  1\rangle = e^{i\theta}  1\rangle$	
Two-q	ubit gates						
Gate	Matrix Representation	Ket-Bra Representation		Applying to $ \psi\rangle=\alpha 00\rangle+\beta$	$ 01\rangle + \gamma  10\rangle + \delta  11\rangle$ Ap	pplying to basis states	
CNOT	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}$	$\begin{array}{l}  00\rangle\langle00  +  01\rangle\langle01  +  11\rangle\langle10  +  10\rangle\langle11  \\ \text{Or} \\  0\rangle\langle0  \otimes I +  1\rangle\langle1  \otimes X \end{array}$		$CNOT \left  \psi \right\rangle = \alpha \left  00 \right\rangle + \beta \left  01 \right\rangle$			$NOT\ket{10} = \ket{11}$ $NOT\ket{11} = \ket{10}$
SWAP	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$	$ 00\rangle \left<00\right  + \left 01\right> \left<10\right  + \left 10\right>$	$\langle 01  +  11\rangle \langle 11 $	SWAP $ \psi\rangle=\alpha 00\rangle+\gamma 01\rangle$			$WAP \ket{10} = \ket{01} \ WAP \ket{11} = \ket{11} \ $

Controlled U	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & a_{0,0} & a_{0,1} \\ 0 & 0 & a_{1,0} & a_{1,1} \end{bmatrix}$	$ 0\rangle\langle 0 \otimes I+ 1\rangle\langle 1 \otimes U$	$ \begin{split} &C(U)\left \psi\right\rangle = \alpha\left 00\right\rangle + \gamma\left 01\right\rangle + \left(\gamma a_{0,0} + \delta a_{0,1}\right)\left 10\right\rangle + \\ &\left(\gamma a_{1,0} + \delta a_{1,1}\right)\left 11\right\rangle \end{split} $	$ \begin{array}{l} C(U) \left  00 \right\rangle = \left  00 \right\rangle \\ C(U) \left  01 \right\rangle = \left  01 \right\rangle \end{array} $	$ \begin{array}{l} C(U)   10\rangle =  1\rangle \! \otimes \! (\alpha   0\rangle \! + \! \gamma   1\rangle) \\ C(U)   11\rangle =  1\rangle \! \otimes \! (\beta   0\rangle \! + \! \delta   1\rangle) \end{array} $			
Toffoli (CCNOT) gate								
Gate	Matrix Representation	Ket-Bra Representation	Applying to $ \psi\rangle = \alpha  000\rangle + \beta  001\rangle + \gamma  010\rangle + \delta  011\rangle + \epsilon  100\rangle + \lambda  101\rangle + \eta  110\rangle + \kappa  111\rangle$	Applying to basis states				
CCNOT	$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0$	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{ll} CCNOT \left  \psi \right\rangle &= \alpha \left  000 \right\rangle + \beta \left  001 \right\rangle + \gamma \left  010 \right\rangle + \\ \delta \left  011 \right\rangle + \epsilon \left  100 \right\rangle + \lambda \left  101 \right\rangle + \kappa \left  110 \right\rangle + \eta \left  111 \right\rangle \end{array}$	$\begin{array}{l} CCNOT \hspace{.08cm}  \hspace{.08cm} 000\rangle =  \hspace{.08cm} 000\rangle \\ CCNOT \hspace{.08cm}  \hspace{.08cm} 001\rangle =  \hspace{.08cm} 001\rangle \\ CCNOT \hspace{.08cm}  \hspace{.08cm} 010\rangle =  \hspace{.08cm} 010\rangle \\ CCNOT \hspace{.08cm}  \hspace{.08cm} 011\rangle =  \hspace{.08cm} 011\rangle \end{array}$	$\begin{array}{l} CCNOT \hspace{.08cm}  \hspace{.08cm} 100\rangle \hspace{.1cm} = \hspace{.1cm}  \hspace{.08cm} 100\rangle \\ CCNOT \hspace{.08cm}  \hspace{.08cm} 101\rangle \hspace{.1cm} = \hspace{.1cm}  \hspace{.08cm} 101\rangle \\ CCNOT \hspace{.08cm}  \hspace{.08cm} 110\rangle \hspace{.1cm} = \hspace{.1cm}  \hspace{.08cm} 111\rangle \\ CCNOT \hspace{.08cm}  \hspace{.08cm} 111\rangle \hspace{.1cm} = \hspace{.1cm}  \hspace{.08cm} 110\rangle \end{array}$			