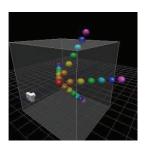
Introduction to Computer Science Lecture 9: Computer 3D Graphics

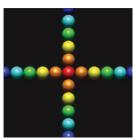
Tian-Li Yu

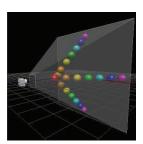
Taiwan Evolutionary Intelligence Laboratory (TEIL)
Department of Electrical Engineering
National Taiwan University
tianliyu@cc.ee.ntu.edu.tw

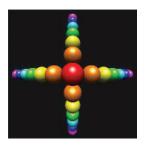
Slides made by Tian-Li Yu, Jie-Wei Wu, and Chu-Yu Hsu

Parallel vs. Prospective Projection









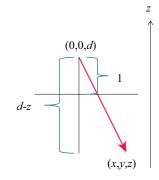
Simple Projection

- Suppose camera is fixed at (0,0,d).
- Projection plane is fixed at z = d 1
- Usually keep z information
- Parallel projection

$$(x,y,z) \rightarrow (x,y,z)$$

Prospective projection

$$(x, y, z) \rightarrow (\frac{x}{d-z}, \frac{y}{d-z}, z)$$



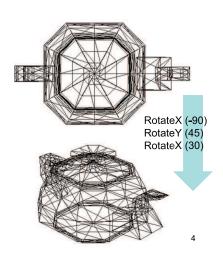
Translations & Rotations

- Translations
 - Simply add a vector.
- Rotations

$$R_X(\theta) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{bmatrix}$$

$$R_Y(\theta) = \begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}$$

$$R_Z(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \end{bmatrix}$$



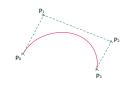
Modeling

- Typically use triangles and quadrangles.
- Easy to compute the normal vector.
- How to increase resolution?
 - Spline and Bézier curves



Bézier Curves

- May be defined on different degree of polynomials.
- Here we introduce the cubic one with 4 control points:



$$((1-t)+t)^3 = (1-t)^3 + 3t(1-t)^2 + 3t^2(1-t) + t^3$$

$$P(t) = (1-t)^3 P_0 + 3t(1-t)^2 P_1 + 3t^2(1-t) P_2 + t^3 P_3$$

Recursive Subdivision

 A cubic Bézier curve can be subdivided into two cubic curves.

Given any t (0.4),

$$-P_{11}=(1-t)P_0+tP_1$$

$$-P_{21} = (1-t)P_1 + tP_2$$

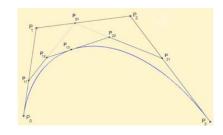
$$-P_{31}=(1-t)P_2+tP_3$$

-
$$P_{12} = (1-t)P_{11} + tP_{21}$$

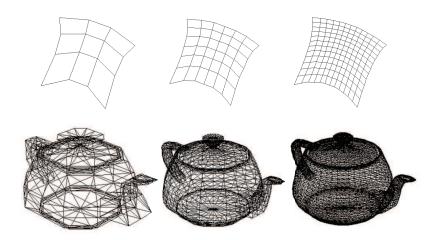
-
$$P_{22} = (1-t)P_{21} + tP_{31}$$

-
$$P_{13} = (1-t)P_{12} + tP_{22}$$

- $P_0, P_{11}, P_{12}, P_{13}$ forms one curve.
- P_{13} , P_{22} , P_{31} , P_{3} forms the other.



Recursive Subdivision



Lighting

- Ambient lighting
- Directional lighting
- Point lighting

$$I = I_a + \frac{(1 - I_a)}{1 + \alpha d + \beta d^2}$$

- d: distance between light source and target.
- I_a: intensity of ambient light.





Shading

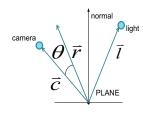
 \vec{n} : normal vector of plane.

 \vec{l} : normal vector of light.

 \vec{c} : normal vector of camera.

 \vec{r} : normal vector of reflection.

- Phong model
 - Ambient + Diffusion + Specular
- Diffusion: $\vec{n} \cdot \vec{l}$
- Specular: $(\cos \theta)^s$
 - Higher s → more mirror-like surface

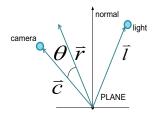


Specular

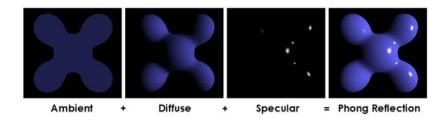
$$\vec{l} + \vec{r} = 2(\vec{l} \cdot \vec{n})\vec{n}$$

$$\vec{r} = 2(\vec{l} \cdot \vec{n})\vec{n} - \vec{l}$$

$$\cos \theta = \vec{r} \cdot \vec{c} = (2(\vec{l} \cdot \vec{n})\vec{n} - \vec{l}) \cdot \vec{c}$$



Put It All Together



$$C = I_a \cdot C_o + \frac{1 - I_a}{1 + \alpha d + \beta d^2} \left(k_d \cdot \vec{n} \cdot \vec{l} \cdot C_o + (1 - k_d) \cos^s \theta \cdot C_l \right)$$

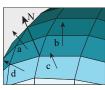
Summary of Parameters

Properties of light	
la	Ambient light intensity (0~1)
α,β	Degree of point lighting
C_l	Color of light
7	Normal vector of light direction

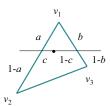
Properties of object	
k _d	Diffusion coefficient ($k_d = 1 - k_s$: specular coefficient)
S	Shininess: how mirror-like
Co	Color of the object
п	Normal vector of the plane

Flat, Gouraud, and Phong Shadings

- Flat: one triangle, one color.
- Gouraud: interpolation of vertices colors.
- Phong: interpolation of vertices normal vectors.



Vertex normal



$$(1-c)((1-a)v_1+av_2)+c((1-b)v_1+bv_3)$$

Flat, Gouraud, and Phong Shadings

