

Signals & Systems

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<https://sites.google.com/site/ntusands/>

https://ceiba.ntu.edu.tw/1072EE2011_04

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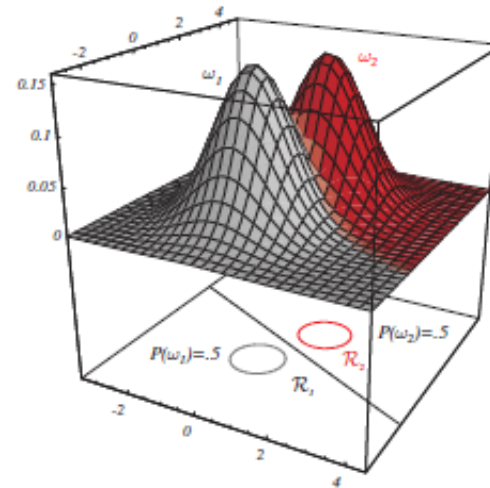
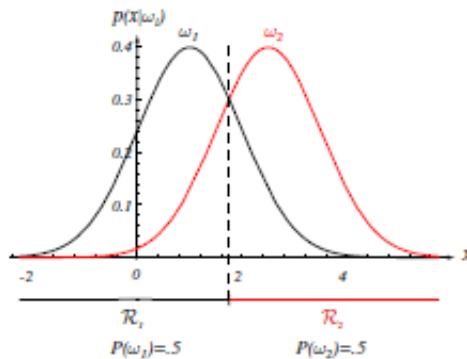
Outline

- Ch. 2 LTI Systems
- Ch. 3 FS of Periodic Signals
- Ch. 4 CTFT
- Ch. 5 DTFT
- Ch. 6 Time and Freq. Characterization of Signals and Systems
- Ch. 7 Sampling
- Ch. 9 Laplace Transform
- Ch. 10 z-Transform
- Ch. 8 Comm. Systems

Bonus Lecture: Machine Learning 101

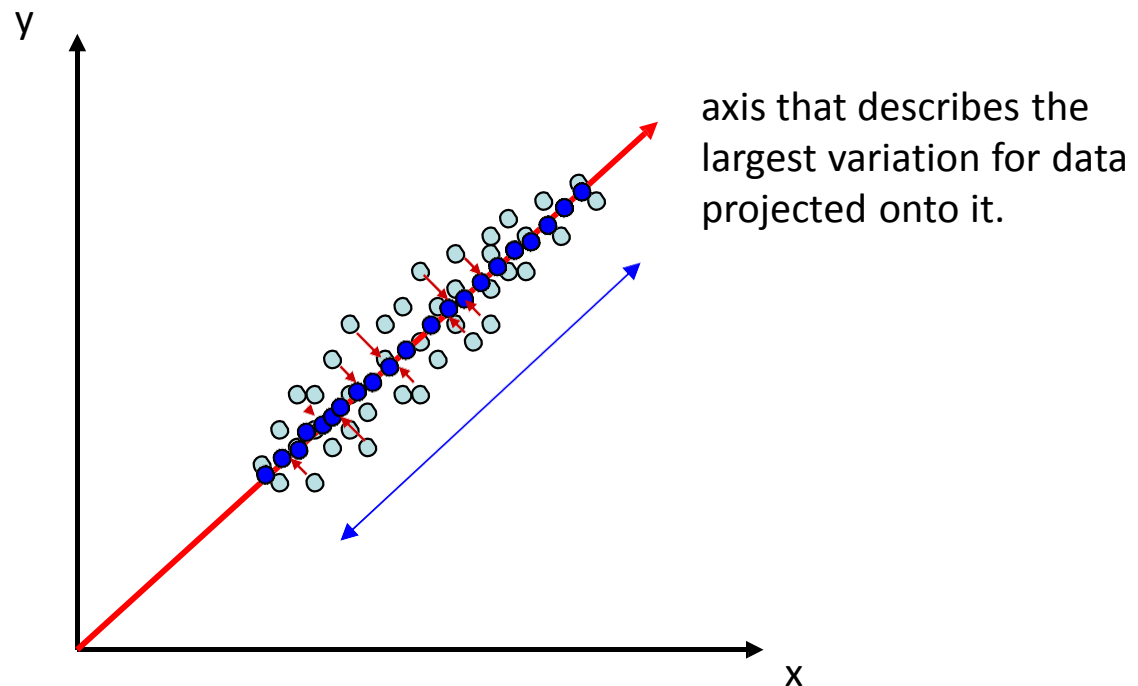
Machine Learning 101

- From Probability to Bayes Decision Rule
- Brief Review of Linear Algebra & Linear System
- Unsupervised vs. Supervised Learning
 - Clustering & Dimension Reduction
 - Training, testing, & validation
 - Linear Classification



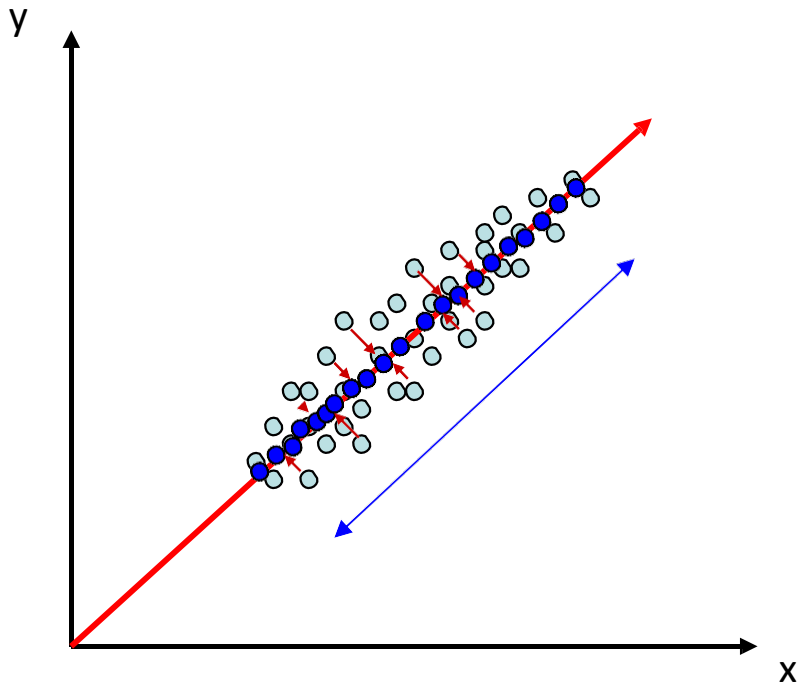
Dimension Reduction

- Principal Component Analysis (PCA)
 - Unsupervised & linear dimension reduction
 - Related to Eigenfaces, etc. feature extraction and classification techniques
 - Still very popular despite of its simplicity and effectiveness.
 - Goal:
 - Determine the projection, so that the variation of projected data is maximized.



Formulation & Derivation for PCA

- Input: a set of instances \mathbf{x} without label info
- Output: a projection vector $\boldsymbol{\omega}$ maximizing the variance of the projected data
- In other words, we need to maximize $\text{var}(\boldsymbol{\omega}^T \mathbf{x})$ with $\|\boldsymbol{\omega}\| = 1$.



Formulation & Derivation for PCA (cont'd)

- Lagrangian optimization for PCA

Eigenanalysis & PCA

- Find the eigenvectors \mathbf{e}_i and the corresponding eigenvalues λ_i
 - The direction \mathbf{e}_i captures the variance of λ_i .
 - But, which eigenvectors to use? All of them?
- A $d \times d$ covariance matrix contains a maximum of d eigenvector/eigenvalue pairs.
 - Which \mathbf{e}_i (and thus λ_i) to consider?
 - Assume N images of size $M \times M$ pixels, we have dimension $d = M^2$.
 - What is the rank of Σ ?
 - Thus, at most non-zero eigenvalues can be obtained.

Eigenanalysis & PCA (cont'd)

- Image reconstruction via PCA
 - Expand a signal (e.g., an input image) via eigenvectors as bases
 - With symmetric matrices (e.g., covariance matrix), eigenvectors are orthogonal.
 - They can be regarded as unit basis vectors to span any instance in the d -dim space.

Practical Issues in PCA

- Assume we have $N = 100$ images of size 200×200 pixels (i.e., $d = 40000$).
- What is the size of the covariance matrix? What's its rank?
- What can we do? **Gram Matrix Trick!**

Let's See an Example (CMU AMP Face Database)

- Let's take 5 face images x 13 people = 65 images, each is of size $64 \times 64 = 4096$ pixels.
- # of eigenvectors are expected to use for perfectly reconstructing the input = 64.
- Let's check it out!



What Do the Eigenvectors/Eigenfaces Look Like?

Mean



V1



V2



V3



V4



V5



V6



V7



V8



V9



V10



V11



V12



V13



V14



V15



All 64 Eigenvectors, do we need them all?



Use only 1 eigenvector, MSE = 1233

MSE=1233.16



Use 2 eigenvectors, MSE = 1027

MSE=1027.63



Use 3 eigenvectors, MSE = 758

MSE=758.13



Use 4 eigenvectors, MSE = 634

MSE=634.54



Use 8 eigenvectors, MSE = 285

MSE=285.08



With 20 eigenvectors, MSE = 87

MSE=87.93



With 30 eigenvectors, MSE = 20

MSE=20.55



With 50 eigenvectors, MSE = 2.14

MSE=2.14



With 60 eigenvectors, MSE = 0.06

MSE=0.06



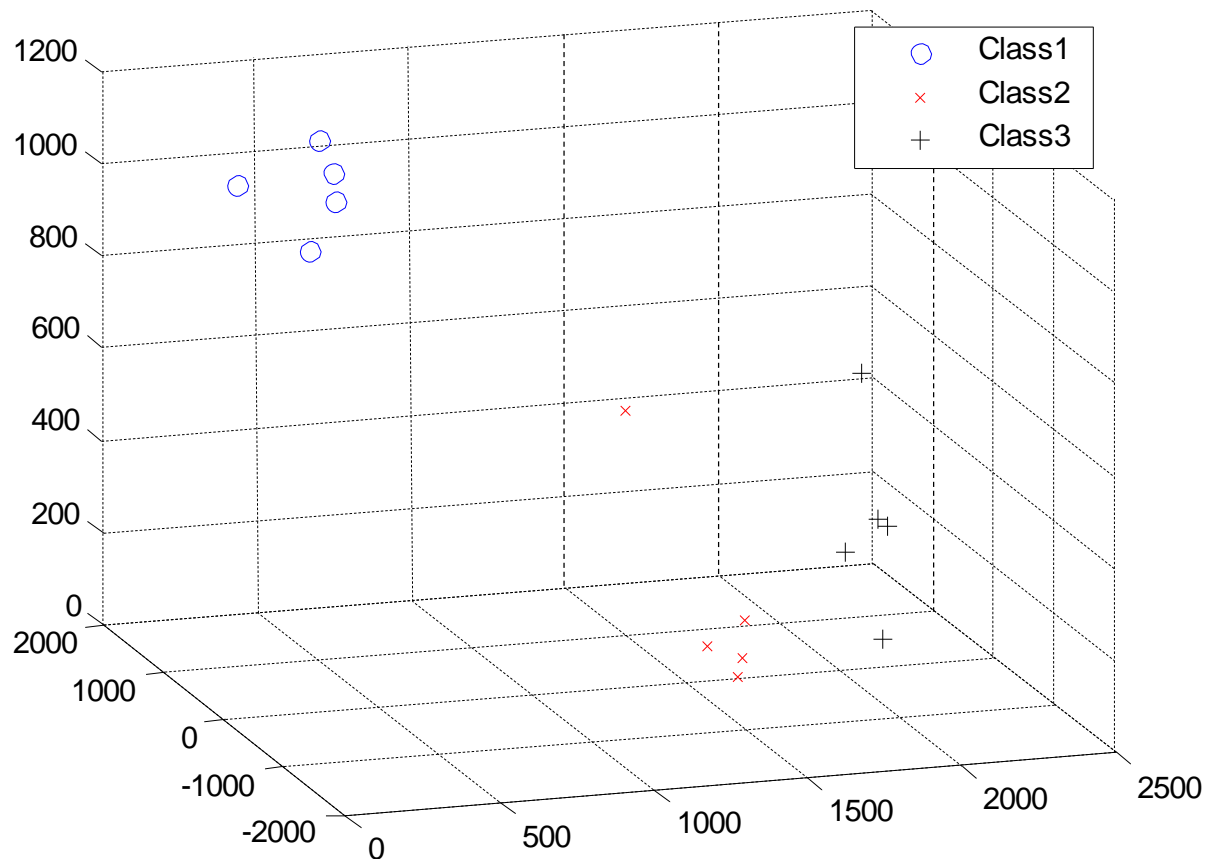
All 64 eigenvectors, MSE = 0

MSE=0.00



Final Remarks

- Linear & unsupervised dimension reduction
- PCA can be applied as a feature extraction/preprocessing technique.
 - E.g., Use the top 3 eigenvectors to project data into a 3D space for classification.

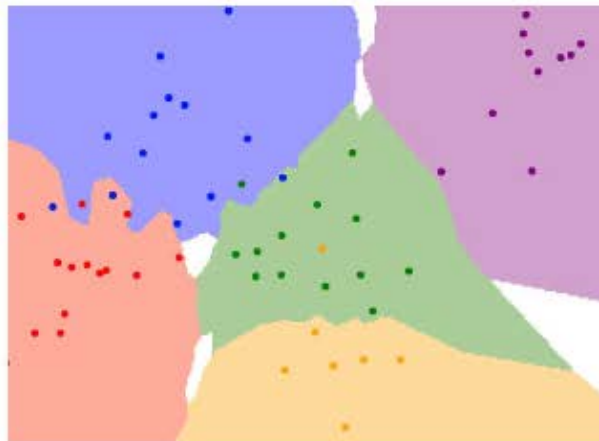


Final Remarks (cont'd)

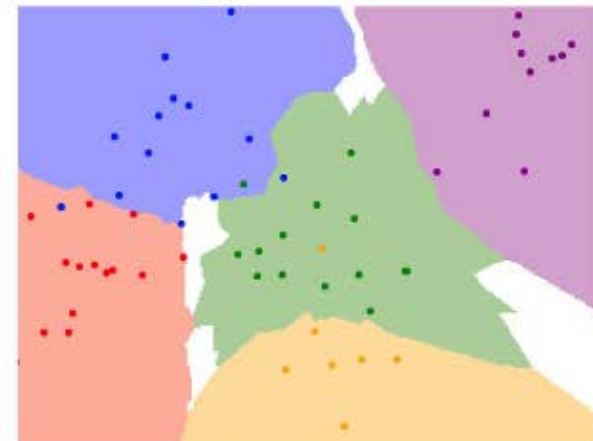
- How do we classify? For example...
 - Given a test face input, project into the same 3D space (by the same 3 eigenvectors).
 - The resulting vector in the 3D space is the **feature** for this test input.
 - We can do a simple **Nearest Neighbor (NN)** classification with Euclidean distance, which calculates the distance to all the projected training data in this space.
 - If NN, then the **label of the closest training instance** determines the classification output.
 - If **k-nearest neighbors (k-NN)**, then k-nearest neighbors need to **vote** for the decision.



k = 1



k = 3



k = 5

Demo available at <http://vision.stanford.edu/teaching/cs231n-demos/knn/>

Final Remarks (cont'd)

- If labels for each data is provided → [Linear Discriminant Analysis \(LDA\)](#)
 - LDA is also known as Fisher's discriminant analysis.
 - Eigenface vs. Fisherface (IEEE Trans. PAMI 1997)
- If linear DR is not sufficient, and **non-linear DR** is of interest...
 - Isomap, locally linear embedding (LLE), etc.
 - **t-distributed stochastic neighbor embedding (t-SNE)** (by G. Hinton & L. van der Maaten)

