# Signals and Systems MATLAB HW3 Deadline: 2019/05/31 before 23:59

The objective of this homework is to learn some MATLAB commands about the digital filter design and one of its applications.

### **Digital Filters**

In this section, you will learn how to use the following MATLAB commands:

### 1.1 Background

A causal, nonideal lowpass filter is designed with frequency response  $H(e^{jw})$  and its difference equation is specified as

$$a_1 y[n] = \sum_{k=1}^{N} b_k x[n-k] - \sum_{k=2}^{M} a_k y[n-k+1]$$

where x[n] and y[n] denote the input signal and the output signal, respectively.

• To obtain the frequency response of the filter, the MATLAB command **freqz**, ex:

$$[H, w] = \text{freqz}(b, a, K);$$

returns the K-point complex frequency response vector H and the K-point frequency vector w in radians/sample of the filter:

$$H(e^{jw}) = \frac{b_1 + b_2 e^{jw} + \dots + b_N e^{jNw}}{a_1 + a_2 e^{jw} + \dots + a_M e^{jMw}}$$

given numerator and denominator coefficients in vectors b and a where

$$a = [a_1, a_2, \cdots, a_M]$$

and

$$b = [b_1, b_2, \cdots, b_N].$$

• The MATLAB command **butter**, ex:

$$[b,a] = \text{butter}(L, f_c)$$

designs an IIR filter with a Butterworth response of order L and returns the transfer function of numerator b and denominator a coefficient vectors (length L+1) of an Lth-order lowpass digital Butterworth filter with normalized cutoff

frequency  $f_c$ . The cutoff frequency  $f_c$  of the filter is normalized so that it lies in the interval [0,1], with 1 corresponding to  $w = \pi$ .

• An input signal vector x if filtered by a lowpass filter with numerator b and denominator a. To obtain the output signal y, we may use the MATLAB command filter, ex:

$$y = filter(b, a, x)$$
.

## 1.2 Questions

1. A discrete-time signal is written as

$$x[n] = cos(2\pi(n-1)T_s), n = 1,2,\cdots,100$$

where  $T_s$  denotes the sampling interval and the sampling frequency is  $f_s = 1/T_s = 10$ Hz. Program a MATLAB script (save as mybutter1.m file) to do the following:

- (a) (5%) Use the MATLAB function **plot** to plot x[n] v.s. n.
- (b) (15%) Obtain a Butterworth lowpass digital filter  $H(e^{jw})$  by the MATLAB function **butter** with the following specifications:

Filter order: L=3

Cutoff frequency:  $f_c = 0.1$ 

Please write down the transfer function  $H(e^{jw})$  of the filter in your report and use the MATLAB function **plot** to plot the magnitude response (in dB) v.s. w interval  $[0,\pi]$  and the phase response (in degree) v.s. w interval  $[0,\pi]$  of this filter  $H(e^{jw})$ . Moreover, use the MATLAB function **plot** to plot the output signal y[n] v.s. n of inputting x[n] into the filter  $H(e^{jw})$ . So, there are total 3 figures in this problem.

- (c) (15%) Please repeat part (b) with L=7,  $f_c=0.1$  and  $f_s=10$ Hz.
- (d) (15%) Please repeat part (b) with L=3,  $f_c=0.5$  and  $f_s=10$ Hz.
- (e) (10%) What is the effect of increasing L? What about increasing  $f_c$ ? Please explain it in your report.

**Note:**It is better that total 9 figures in (b)(c)(d) can become 9 sub-figures, which are integrated into a big figure while executing your **mybutter1.m** file.

2. An input signal is written as

$$x[n] = cos(2\pi(n-1)T_s) + 2cos(2\pi f_1(n-1)T_s), n = 1,2,\dots, M.$$

where  $T_s$ =0.002,  $f_l$ =100 and M=1000.

Program a MATLAB script (save as mybutter2.m file) to do the following:

- (a) (10%) Use the MATLAB function **plot** to plot x[n] v.s. n.
- (b) (15%) Obtain a 16-order Butterworth <u>lowpass</u> digital filter by the MATLAB function **butter** such that the output

$$y[n] \approx cos(2\pi(n-1)T_s), n = 1,2,\dots,M$$

when inputting x[n] into the filter.

Please write down transfer function  $H(e^{jw})$  of this filter in your report and use the

MATLAB function **plot** to plot the output signal y[n] v.s. n.

(c) (15%) Obtain a 16-order Butterworth <u>bandpass</u> digital filter by the MATLAB function **butter** such that the output

$$y[n] \approx 2 \cos(2\pi f_1(n-1)T_s), n = 1,2,\dots, M$$

when inputting x[n] into the filter.

Please write down transfer function  $H(e^{jw})$  of this filter in your report and use the MATLAB function **plot** to plot the output signal y[n] v.s. n.

**Note:** It is better that total 3 figures in (a)(b)(c) can become 3 sub-figures, which are integrated into a big figure while executing your **mybutter2.m** file.

#### 1.3 CEIBA Submission

- 1. Please upload a compressed file (.zip, .rar or .tar), which includes your **m-files** (save as **mybutter1.m** & **mybutter2.m** file) and a **word file** (save as **report.doc** file). Please show the relevant plots mentioned above in the word file (report.doc) and answer the questions.
- 2. The compressed file name should be **ID MATLAB3**.

(ex: B07901xxx MATLAB3)