

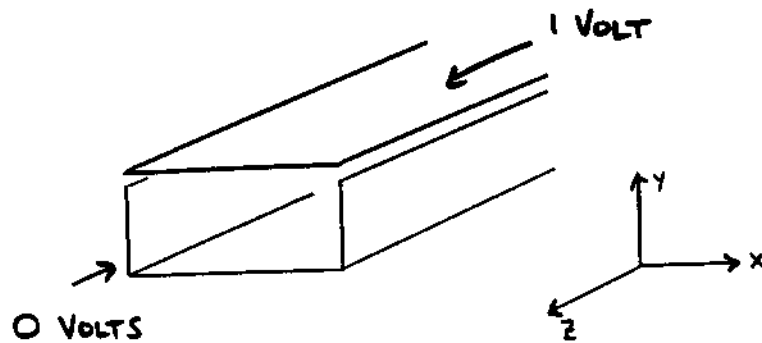
THE METHOD OF FINITE DIFFERENCES

FOR 2D, SOME OF THE EARLIEST APPLICATIONS WERE:

RUNGE, 1908 } POISSON EQUATION
RICHARDSON, 1910 }

ELLIPTIC EQUATIONS

EXAMPLE: AN ELECTROSTATIC PROBLEM WITH TRANSLATIONAL SYMMETRY.



THE GOVERNING EQUATIONS OF ELECTROSTATICS ARE:

$$\nabla \times \underline{E} = 0$$

$$\nabla \cdot \underline{D} = 0 \quad \leftarrow \rho = 0 : \text{CHARGE-FREE REGION}$$

AND IN THE AIR (\approx FREE-SPACE):

$$\underline{D} = \epsilon_0 \underline{E}$$

ALSO, INSIDE CONDUCTORS

$$\underline{E} = 0$$

AND AT THE SURFACE OF CONDUCTORS

$$\underline{E}_{\text{TANGENTIAL}} = 0$$



FROM $\nabla \times \underline{E} = 0$, IT FOLLOWS:

$$\underline{E} = -\nabla\phi$$

AND SO

$$\underline{D} = -\epsilon_0 \nabla\phi$$

AND

$$\nabla \cdot (-\epsilon_0 \nabla\phi) = 0$$

$$\Rightarrow \nabla \cdot \nabla\phi = 0$$

$$\text{OR } \nabla^2\phi = 0 \quad \text{IN THE AIR.}$$

$$\text{e.g., } \frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} + \frac{\partial^2\phi}{\partial z^2} = 0. \quad (\text{IN CARTESIAN COORDINATES})$$

AT THE SURFACE OF A CONDUCTOR, $\underline{E}_{\text{TANG}} = 0$

$$\Rightarrow \text{grad } \phi \cdot \underline{t} = 0$$

$$\text{i.e., } \frac{\partial\phi}{\partial t} = 0$$

WHERE: \underline{t} IS A UNIT VECTOR TANGENT TO THE SURFACE.

FD 3

$\Rightarrow \phi = \text{CONSTANT ON THE SURFACE OF A CONDUCTOR.}$

FOR THE CASE OF TRANSLATIONAL SYMMETRY,

$$\frac{\partial}{\partial z} \equiv 0$$

HENCE,

$$\nabla^2\phi \equiv \frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} \quad (\text{IN CARTESIAN COORDINATES})$$

THEN THE MATHEMATICAL FORMULATION IS THE FOLLOWING ELLIPTIC B.V.P.:

FIND $\phi(x,y)$ SUCH THAT

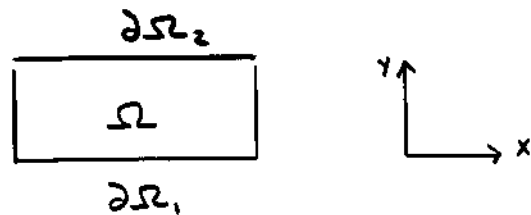
$$\frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} = 0 \quad \text{IN } \Omega$$

$$\phi = 0 \quad \text{ON } \partial\Omega_1$$

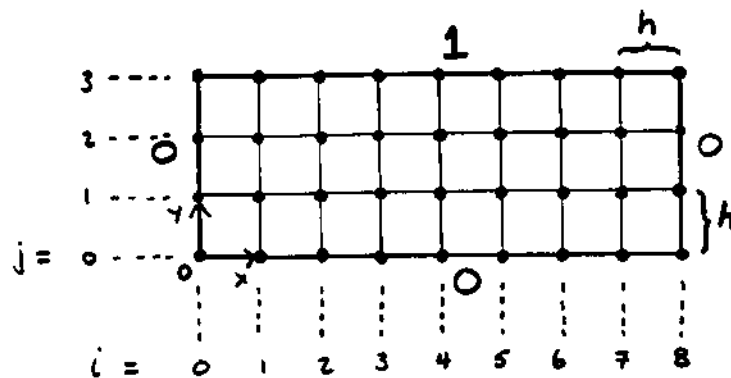
$$\phi = 1 \quad \text{ON } \partial\Omega_2$$

FD 4

WHERE



TO SOLVE THE PROBLEM, WE SET UP
A REGULAR GRID OR MESH OF NODES
THROUGHOUT Ω :



LABEL THE NODES i, j SO THE
COORDINATES OF NODE i, j ARE

$$x_i = ih$$

$$y_j = jh$$

NOW, WE WISH TO FIND THE VALUES OF ϕ
AT THE NODES, I.E., TO FIND

$$\phi_{ij} = \phi(x_i, y_j)$$

WE ALREADY KNOW ϕ_{ij} ON $\partial\Omega_1$ & $\partial\Omega_2$:

$$\phi_{ij} = 0 \text{ FOR } j=0, i=0, \dots, 8$$

$$\phi_{ij} = 0 \text{ FOR } i=0, j=0, \dots, 2$$

$$\phi_{ij} = 0 \text{ FOR } i=8, j=0, \dots, 2$$

$$\phi_{ij} = 1 \text{ FOR } j=3, i=0, \dots, 8$$

TO FIND THE VALUES OF ϕ AT THE INTERIOR NODES, WE DERIVE FOR EACH SUCH NODE AN EQUATION THAT APPROXIMATES THE P.D.E.

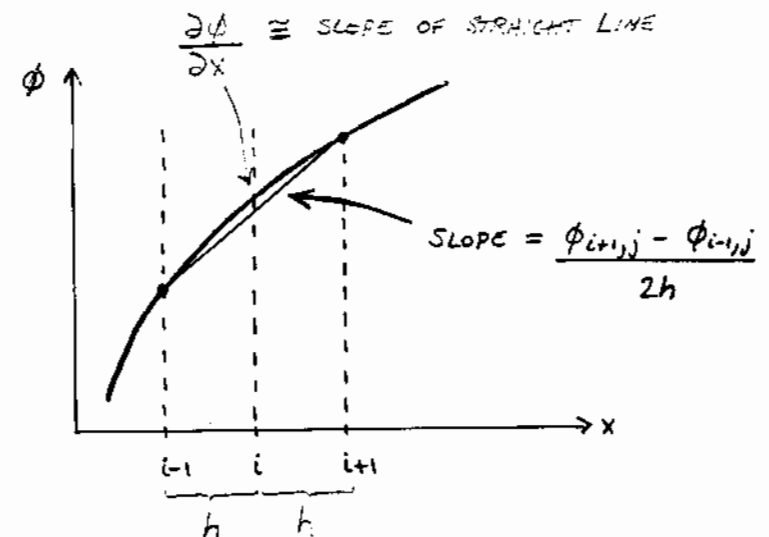
TO DO THIS WE NEED A FINITE DIFFERENCE FORMULA FOR:

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \quad \text{AT NODE } i, j$$

[e.g.,

A FINITE DIFFERENCE FORMULA FOR $\frac{\partial \phi}{\partial x}$ AT NODE i, j IS:

$$\frac{\phi_{i+1,j} - \phi_{i-1,j}}{2h}$$



WHAT IS A FINITE DIFFERENCE FORMULA FOR $\frac{\partial \phi}{\partial y}$ AT NODE i, j ?

TO DERIVE A FINITE DIFFERENCE FORMULA
FOR $\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2}$, WE EXPAND ϕ IN

A TAYLOR SERIES ABOUT i, j :

$$\phi(x_i + h, y_j) = \phi(x_i, y_j)$$

$$+ h \left. \frac{\partial \phi}{\partial x} \right|_{i,j} \quad \leftarrow \text{EVALUATED AT } i,j$$

$$+ \frac{h^2}{2!} \left. \frac{\partial^2 \phi}{\partial x^2} \right|_{i,j}$$

$$+ \frac{h^3}{3!} \left. \frac{\partial^3 \phi}{\partial x^3} \right|_{i,j}$$

$$+ O(h^4) \quad \text{AS } h \rightarrow 0$$

O NOTATION

$f(x)$ IS $O(g(x))$ AS $x \rightarrow 0$

MEANS:

THERE ARE NUMBERS c, k SUCH THAT

$$|f(x)| \leq k |g(x)| \quad \forall \quad x < c$$

e.g.,

$$f(x) = 4x^3 + 2x^2 + x$$

$$= O(x) \quad \text{AS } x \rightarrow 0$$

$$f(x) = \sin \pi x = O(x) \quad \text{AS } x \rightarrow 0$$

$$f(x) = 4x^2 + \sin x + \frac{1}{x} = O\left(\frac{1}{x}\right) \quad \text{AS } x \rightarrow 0$$

ALSO

$f(x)$ is $O(g(x))$ as $x \rightarrow \infty$ MEANS:

THERE ARE NUMBERS c, k SUCH THAT

$$|f(x)| < k |g(x)| \quad \forall x > c$$

e.g.,

$$\begin{aligned} f(x) &= 4x^3 + 2x^2 + x \\ &= O(x^3) \quad \text{AS } x \rightarrow \infty \end{aligned}$$

$$f(x) = \sin \pi x = O(1) \quad \text{AS } x \rightarrow \infty$$

$$f(x) = 4x^2 + \sin x + \frac{1}{x} = O(x^2) \quad \text{AS } x \rightarrow \infty$$

FD 11

ALSO,

$$\phi(x_i - h, y_j) = \phi(x_i, y_j)$$

$$- h \left. \frac{\partial \phi}{\partial x} \right|_{i,j}$$

$$+ \frac{h^2}{2!} \left. \frac{\partial^2 \phi}{\partial x^2} \right|_{i,j}$$

$$- \frac{h^3}{3!} \left. \frac{\partial^3 \phi}{\partial x^3} \right|_{i,j}$$

$$+ O(h^4)$$

Now, ADDING $\phi(x_i + h, y_j)$ AND $\phi(x_i - h, y_j)$:

FD 12

$$\begin{aligned}
 & \phi(x_i + h, y_j) + \phi(x_i - h, y_j) \\
 &= 2\phi(x_i, y_j) \\
 &+ h^2 \frac{\partial^2 \phi}{\partial x^2} \Big|_{i,j} \\
 &+ O(h^4)
 \end{aligned}$$

OR,

$$\phi_{i+1,j} + \phi_{i-1,j} = 2\phi_{i,j} + h^2 \frac{\partial^2 \phi}{\partial x^2} \Big|_{i,j} + O(h^4)$$

RE-ARRANGING, WE GET :

$$\begin{aligned}
 \frac{\partial^2 \phi}{\partial x^2} \Big|_{i,j} &= \frac{1}{h^2} (\phi_{i+1,j} + \phi_{i-1,j} - 2\phi_{i,j}) \\
 &+ O(h^2)
 \end{aligned}$$

IN A SIMILAR WAY, WE GET :

$$\begin{aligned}
 \frac{\partial^2 \phi}{\partial y^2} \Big|_{i,j} &= \frac{1}{h^2} (\phi_{i,j+1} + \phi_{i,j-1} - 2\phi_{i,j}) \\
 &+ O(h^2)
 \end{aligned}$$

ADDING $\frac{\partial^2 \phi}{\partial x^2} \Big|_{i,j}$ AND $\frac{\partial^2 \phi}{\partial y^2} \Big|_{i,j}$, WE GET

A FINITE DIFFERENCE FORMULA FOR $\nabla^2 \phi \Big|_{i,j}$:

$$\nabla^2 \phi|_{i,j} \cong \frac{1}{h^2} \left(\phi_{i+1,j} + \phi_{i-1,j} + \phi_{i,j+1} + \phi_{i,j-1} - 4\phi_{i,j} \right)$$

OR, PICTORIALLY :

$$\nabla^2 \phi|_{i,j} \cong \frac{1}{h^2} \left\{ \begin{array}{c} \textcircled{+1} \\ | \\ \textcircled{+1} - \textcircled{4} - \textcircled{+1} \\ | \\ \textcircled{+1} \end{array} \right\}$$

"COMPUTATIONAL MOLECULE"

THIS IS SAID TO BE A FIVE-POINT
DIFFERENCE FORMULA

THIS DIFFERENCE FORMULA IS SAID TO BE
A SECOND-ORDER APPROXIMATION TO
 $\nabla^2 \phi|_{i,j}$, SINCE

$$\nabla^2 \phi|_{i,j} - \frac{1}{h^2} \left\{ \begin{array}{c} \textcircled{+1} \\ | \\ \textcircled{+1} - \textcircled{4} - \textcircled{+1} \\ | \\ \textcircled{+1} \end{array} \right\}$$

$$= O(h^2) \text{ as } h \rightarrow 0.$$

N.B. $e(x)$ IS AN n^{th} -ORDER
APPROXIMATION TO $E(x)$ W.R.T.
 h IF n IS THE LARGEST
INTEGER SUCH THAT

$$|e - E| = O(h^n) \text{ as } h \rightarrow 0$$

THE EQUATION WE NEED FOR EACH
INTERIOR NODE IS JUST THE FINITE DIFFERENCE
 APPROXIMATION TO

$$\nabla^2 \phi|_{i,j} = 0$$

i.e.,

$$\frac{1}{h^2} \left\{ \begin{array}{c} \text{+1} \\ \text{+1} \text{---} \text{(-4)} \text{---} \text{+1} \\ \text{+1} \end{array} \right\} = 0.$$

IF THERE ARE n INTERIOR NODES, THERE
 WILL BE n EQUATIONS, AND n UNKNOWNNS.

WE HAVE REDUCED THE PROBLEM TO A SET
 OF ALGEBRAIC EQUATIONS.

IN MATRIX FORM :

$$\underline{\underline{A}} \underline{\phi}_c = \underline{b}$$

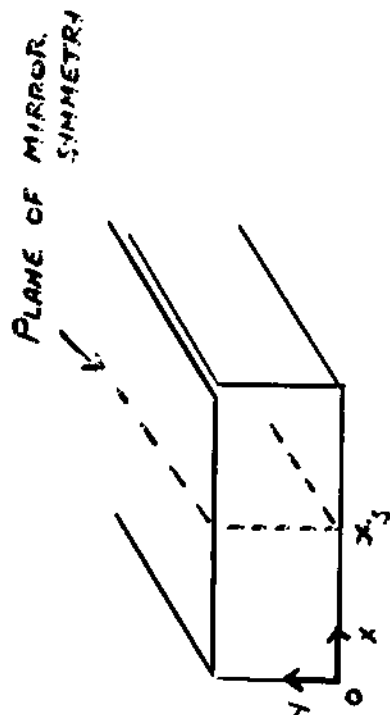
WHERE :

$$\underline{\phi}_c = \begin{bmatrix} \phi_{1,1} \\ \phi_{1,2} \\ \phi_{2,1} \\ \phi_{2,2} \\ \vdots \\ \vdots \\ \phi_{7,1} \\ \phi_{7,2} \end{bmatrix}$$

THESE n (=14)
 UNKNOWNNS MAY BE
 ORDERED IN ANY
 WAY.

MAKING USE OF SYMMETRY

THE PROBLEM WE HAVE BEEN SOLVING HAS A PLANE OF MIRROR SYMMETRY (AS WELL AS TRANSLATIONAL SYMMETRY):



WE KNOW THAT THE POTENTIAL WILL BE EVEN ABOUT THIS PLANE OF SYMMETRY:

$$\phi(x_3 + \Delta x, y) = \phi(x_3 - \Delta x, y)$$

i.e.,



PD 20

A

	(1,1)	(1,2)	(2,1)	(2,2)	(3,1)	(3,2)	(4,1)	(4,2)	(5,1)	(5,2)	(6,1)	(6,2)	(7,1)	(7,2)
(1,1)	-4	1	1											
(1,2)	1	-4		1										
(2,1)	1		-4	1	1									
(2,2)		1	1	-4		1								
(3,1)			1		-4	1	1							
(3,2)				1	1	-4		1						
(4,1)					1		-4	1	1					
(4,2)						1	1	-4		1				
(5,1)							1		-4	1	1			
(5,2)								1	1	-4		1		
(6,1)									1		-4	1	1	
(6,2)										1	1	-4		1
(7,1)											1		-4	1
(7,2)												1	1	-4

PD 19

INTUITIVELY, WE HAVE :

$$\left. \frac{\partial \phi}{\partial x} \right|_{x_s} = 0$$

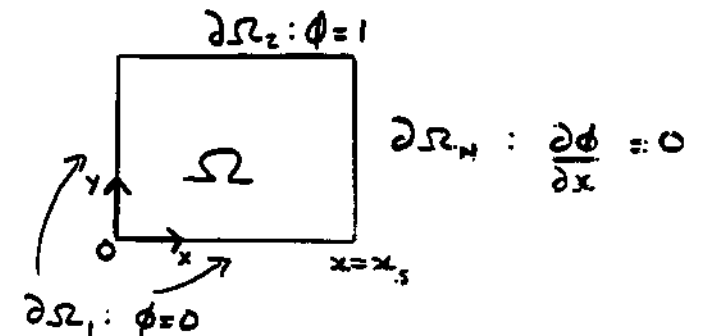
AND THIS IS INDEED WHAT HAPPENS ON A PLANE OF SYMMETRY.

⇒ WHY SOLVE FOR ϕ IN BOTH HALVES?

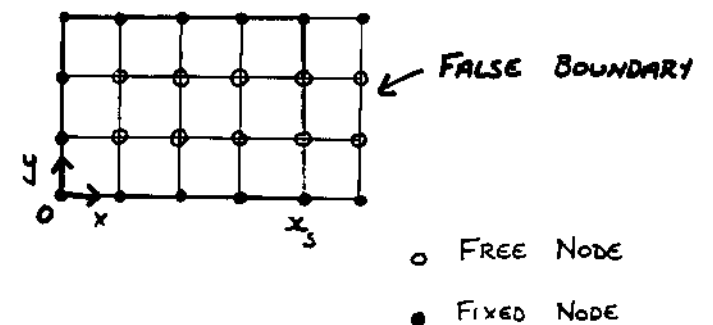
IT IS MORE EFFICIENT TO SOLVE THE FOLLOWING BVP :

$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0 \quad \text{IN } \Omega$	
DIRICHLET BOUNDARY CONDITIONS	$\begin{cases} \phi = 0 & \text{ON } \partial\Omega_1 \\ \phi = 1 & \text{ON } \partial\Omega_2 \end{cases}$
NEUMANN BOUNDARY CONDITIONS	$\left\{ \frac{\partial \phi}{\partial x} = 0 \text{ ON } \partial\Omega_M \right.$

FD 21



WHAT ABOUT THE FINITE DIFFERENCE SOLUTION?



(NOTE: AS WE SEE, BOUNDARY NODES MAY BE FREE!)

FD 21

HENCE, THERE ARE 10 FREE NODES, i.e.,
10 UNKNOWN VALUES OF POTENTIAL.

APPLYING

$$\nabla^2 \phi = 0$$

IN FINITE DIFFERENCE FORM AT EACH OF THE 8
 FREE NODES IN Ω OR ON $\partial\Omega$ GIVES 8 EQNS.

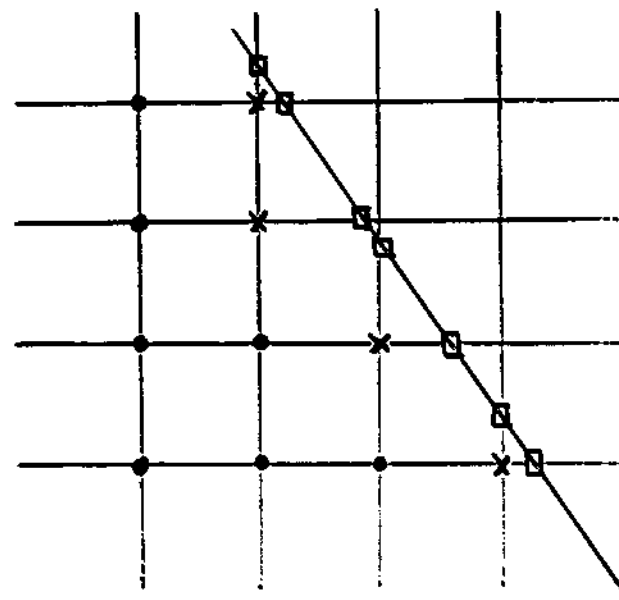
THE REMAINING 2 EQUATIONS COME FROM
 APPLYING THE NEUMANN BOUNDARY CONDITION:

$$\frac{\partial \phi}{\partial x} = 0$$

IN FINITE DIFFERENCE FORM AT EACH OF
 THE 3 FREE NODES ON $\partial\Omega_N$.

$$\frac{\partial \phi}{\partial x} = 0 \rightarrow \frac{\phi_{i+1,j} - \phi_{i-1,j}}{2h} = 0.$$

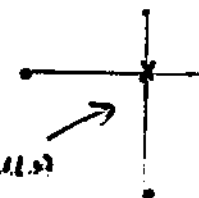
ARBITRARY BOUNDARIES



• REGULAR NODE

□ BOUNDARY NODE

x SPECIAL NODE



FD FORMULA
 FOR THIS NODE?

SOME ITERATIVE METHODS OF SOLUTION

$$\text{OF } \underline{A} \underline{\phi}_c = \underline{b}$$

1. SIMPLE RELAXATION

a) JACOBI METHOD (1844)

(a.k.a. "SIMULTANEOUS RELAXATION")

STEP 0: GUESS $\underline{\phi}_c^{(0)}$; $k=0$

STEP 1: CONSTRUCT $\underline{\phi}_c^{(k+1)}$ USING

$$\phi_{i+1,j}^{(k)} + \phi_{i-1,j}^{(k)} + \phi_{i,j+1}^{(k)} + \phi_{i,j-1}^{(k)} - 4\phi_{i,j}^{(k+1)} = 0$$

OR,

$$\phi_{i,j}^{(k+1)} = \frac{1}{4} (\phi_{i+1,j}^{(k)} + \phi_{i-1,j}^{(k)} + \phi_{i,j+1}^{(k)} + \phi_{i,j-1}^{(k)})$$

(REMEMBER, BOUNDARY VALUES OF ϕ ARE FIXED
DO NOT CHANGE WITH k).

FD 25

STEP 2:

IF

$$R_{i,j}^{(k+1)} = \phi_{i+1,j}^{(k+1)} + \phi_{i-1,j}^{(k+1)}$$

$$+ \phi_{i,j+1}^{(k+1)} + \phi_{i,j-1}^{(k+1)}$$

$$- 4\phi_{i,j}^{(k+1)}$$

= RESIDUAL AT NODE i,j

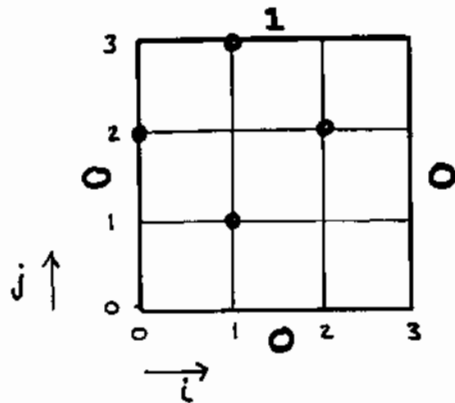
IS SMALL ENOUGH AT EACH NODE, STOP.

OTHERWISE, $k = k+1$ AND GO BACK TO
STEP 1.

(NOTE: "SMALL ENOUGH" RELATIVE TO $|\phi_{i,j}^{(k+1)}|$)

FD 26

EXAMPLE



- SIMPLE, BUT
- SLOW TO CONVERGE
(e.g. FOR $N \times N$ GRID $\sim O(N^2)$ ITERATIONS)

b) GAUSS-SEIDEL METHOD (1874)

STEP 0: GUESS $\phi_c^{(0)}$; $k=0$

STEP 1: CONSTRUCT $\phi_c^{(k+1)}$ USING

$$\phi_{i,j}^{(k+1)} = \frac{1}{4} \left(\phi_{i-1,j}^{(k+1)} + \phi_{i,j-1}^{(k+1)} + \phi_{i+1,j}^{(k)} + \phi_{i,j+1}^{(k)} \right)$$

THIS IS POSSIBLE, PROVIDED

$$\phi_{i-1,j}^{(k+1)} \text{ AND } \phi_{i,j-1}^{(k+1)}$$

ARE COMPUTED BEFORE $\phi_{i,j}^{(k+1)}$.

STEP	NODE			
	1,1	1,2	2,1	2,2
0	0	0	0	0
1	0	0.25	0	0.25
2	0.0625	0.3125	0.0625	0.3125
3		etc...		
4				
⋮				

HENCE, THE ORDER OF COMPUTATION
IS IMPORTANT.

\Rightarrow a.k.a. "SUCCESSIVE RELAXATION"

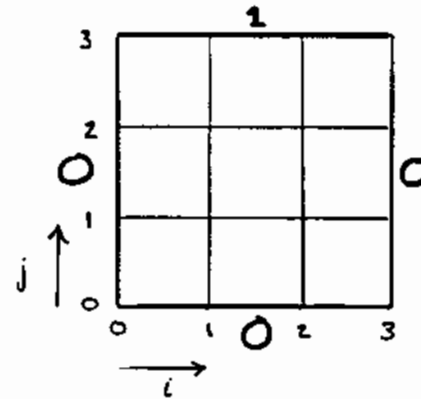
STEP 2:

IF $R_{i,j}^{(k+1)}$ IS SMALL ENOUGH AT
EACH NODE, STOP.

OTHERWISE, $k = k+1$ AND GO BACK TO
STEP 1.

- FASTER CONVERGENCE $\sim O(\frac{1}{2}N^2)$ ITERATIONS
FOR $N \times N$ GRID.

EXAMPLE



STEP	NODE			
	1,1	1,2	2,1	2,2
0	0	0	0	0
1	0	0.25	0	0.3125
2	0.0625	0.34375	0.09375	0.359375
3			etc...	
⋮				

2. OVER-RELAXATION

(OR, SUCCESSIVE OVER-RELAXATION, SOR)

IN RELAXATION METHODS, WE RELAX THE POTENTIAL AT NODE i, j TO MAKE ZERO THE QUANTITIES:

$$\phi_{i-1,j}^{(k)} + \phi_{i,j-1}^{(k)} + \phi_{i+1,j}^{(k)} + \phi_{i,j+1}^{(k)} - 4\phi_{i,j}^{(k+1)} \quad (\text{JACOBI})$$

OR,

$$\phi_{i-1,j}^{(k+1)} + \phi_{i,j-1}^{(k+1)} + \phi_{i+1,j}^{(k)} + \phi_{i,j+1}^{(k)} - 4\phi_{i,j}^{(k+1)} \quad (\text{GAUSS-SEIDEL})$$

IN OVER-RELAXATION, WE MAKE A LARGER RELAXATION.

FD 31

LET $\bar{\phi}_{i,j}^{(k+1)}$ BE THE NEW POTENTIAL AT NODE i, j DUE TO THE GAUSS-SEIDEL SCHEME.

THEN SOR MAKES THE NEW POTENTIAL AT i, j :

$$\phi_{i,j}^{(k+1)} = (1-\omega) \phi_{i,j}^{(k)} + \omega \bar{\phi}_{i,j}^{(k+1)}$$

i.e.,

$$\phi_{i,j}^{(k+1)} = (1-\omega) \phi_{i,j}^{(k)} + \frac{\omega}{4} \left(\phi_{i-1,j}^{(k+1)} + \phi_{i,j-1}^{(k+1)} + \phi_{i+1,j}^{(k)} + \phi_{i,j+1}^{(k)} \right)$$

ω IS THE RELAXATION PARAMETER

($\omega < 1 \Rightarrow$ UNDER RELAXATION ; $\omega > 1 \Rightarrow$ OVER-RELAXATION)

$\omega = 1 \rightarrow$ GAUSS-SEIDEL

$\omega = 2 \rightarrow$ THE METHOD DIVERGES

SOMEWHERE BETWEEN ($1 < \omega < 2$), SOR GIVES

FASTER CONVERGENCE THAN GAUSS-SEIDEL.

($\sim O(N)$ ITERATIONS FOR ω_{OPTIMAL} FOR $N \times N$ GRID).

FD 32