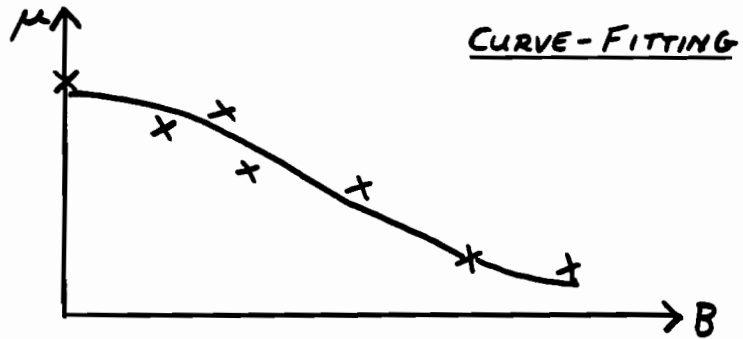
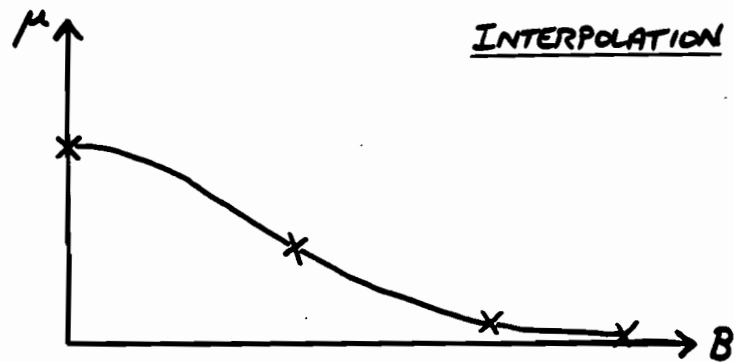


CURVE-FITTING & INTERPOLATION



x = GIVEN DATA

NEED: SMOOTH CURVE CLOSE TO GIVEN POINTS

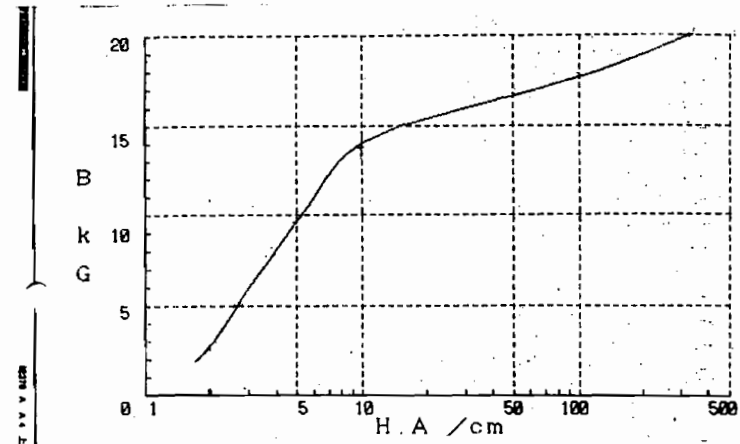


x = GIVEN DATA

NEED: SMOOTH CURVE THROUGH GIVEN POINTS

CV 1

A B-H CURVE

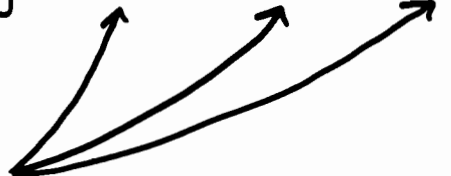


CV 2

LEAST-SQUARES CURVE-FITTING

e.g.,

TRY A SMOOTH CURVE OF THE
FORM:

$$y = ax^2 + bx + c$$


CHOOSE THESE 3 PARAMETERS
SO THAT THE CURVE LIES AS
CLOSE AS POSSIBLE TO THE
DATA POINTS:

$$(x_1, y_1), \dots, (x_N, y_N).$$

i.e., SO THAT

$$y(x_k) \text{ IS CLOSE TO } y_k \\ \text{FOR } k = 1, \dots, N.$$

DEFINE AN ERROR E :

$$E = \sum_{k=1}^N (y(x_k) - y_k)^2 \\ = \sum_{k=1}^N (ax_k^2 + bx_k + c - y_k)^2$$

FIND a , b , & c THAT

MINIMIZES THE SQUARED ERROR, E .

i.e., REQUIRE :

$$\left. \begin{aligned} \frac{\partial E}{\partial a} &= 0 \\ \frac{\partial E}{\partial b} &= 0 \\ \frac{\partial E}{\partial c} &= 0 \end{aligned} \right\} \begin{array}{l} 3 \text{ SIMULTANEOUS} \\ \text{EQUATIONS IN} \\ 3 \text{ UNKNOWN,} \\ a, b, c \end{array}$$

$$\text{OR, } \left. \begin{aligned} 2 \sum_{k=1}^N x_k^2 (ax_k^2 + bx_k + c - y_k) &= 0 \\ 2 \sum_{k=1}^N x_k (ax_k^2 + bx_k + c - y_k) &= 0 \\ 2 \sum_{k=1}^N (ax_k^2 + bx_k + c - y_k) &= 0 \end{aligned} \right\}$$

CV 5

MORE GENERALLY :

$$y = \sum_{j=1}^n a_j g_j(x)$$

i.e., $y(x)$ IS A LINEAR COMBINATION
OF $g_1(x), \dots, g_n(x)$.

$$E = \sum_{k=1}^N \left(\sum_{j=1}^n a_j g_j(x_k) - y_k \right)^2$$

FOR $i = 1, \dots, n$:

$$\left[\frac{\partial E}{\partial a_i} = 0 \right]$$

CV 6

\Rightarrow FOR $i = 1, \dots, n$:

$$\left[\sum_{k=1}^N 2 \left(\sum_{j=1}^n a_j g_j(x_k) - y_k \right) g_i(x_k) \right] = 0$$

CHANGE ORDER OF THE SUMMATION :

\Rightarrow FOR $i = 1, \dots, n$:

$$\left[\sum_{j=1}^n \left[\sum_{k=1}^N g_i(x_k) g_j(x_k) \right] a_j \right] = \sum_{k=1}^N g_i(x_k) y_k$$

OR,

$$\underline{\underline{G}} \underline{\underline{a}} = \underline{\underline{b}}$$

\Rightarrow SOLVE FOR a.

NOTE :

$$G_{ij} = \sum_{k=1}^N g_i(x_k) g_j(x_k)$$

$$b_i = \sum_{k=1}^N g_i(x_k) y_k$$

ALSO, NOTE THAT G IS SYMMETRIC.

THE CHOICE OF g_j 's

(i) WHOLE DOMAIN

i.e., EACH g_j IS NONZERO
OVER THE WHOLE RANGE

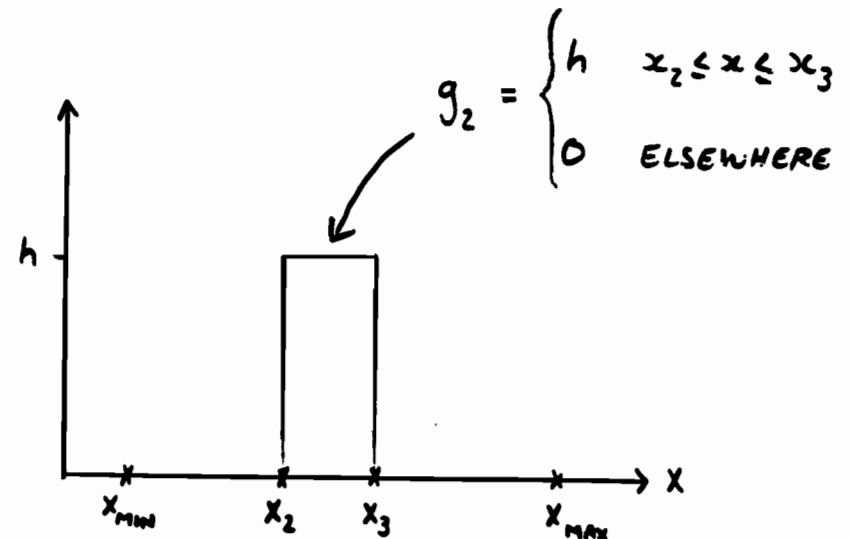
$$x_{\min} \rightarrow x_{\max}$$

e.g., x^2 , x , 1 .

(ii) SUBDOMAIN

i.e., EACH g_j IS NONZERO
ONLY OVER ITS OWN INTERVAL

e.g.,



LAGRANGE'S POLYNOMIALS
AS SUBDOMAIN FUNCTIONS

FOR $j = 1, \dots, n$, LET

$$L_j(x) = \frac{F_j(x)}{F_j(x_j)}$$

WHERE

$$F_j(x) = \prod_{\substack{r=1, n \\ r \neq j}} (x - x_r)$$

x_1, \dots, x_n = SET OF GIVEN
VALUES

L_k IS AN $(n-1)^{\text{ST}}$ ORDER

POLYNOMIAL WITH THE PROPERTY :

$$L_k(x_j) = \begin{cases} 1 & \text{IF } j = k \\ 0 & \text{OTHERWISE} \end{cases}$$

e.g., $n = 2$: FIRST-ORDER

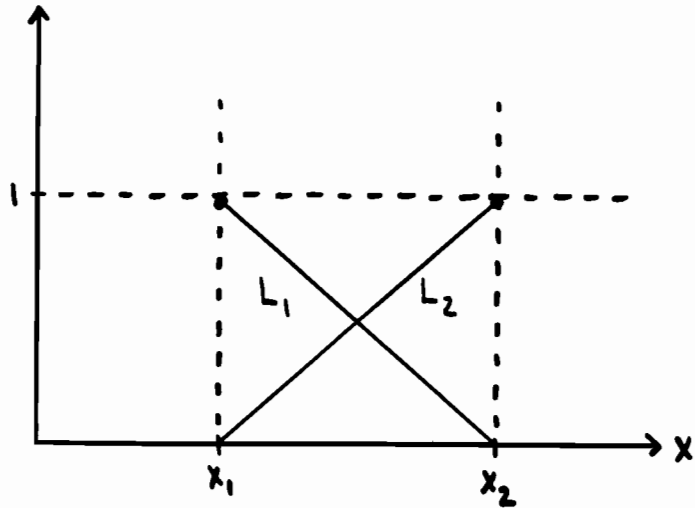
$$F_1(x) = x - x_2$$

$$F_2(x) = x - x_1$$

$$L_1(x) = F_1(x)/F_1(x_1) = \frac{x - x_2}{x_1 - x_2}$$

$$L_2(x) = F_2(x)/F_2(x_2) = \frac{x - x_1}{x_2 - x_1}$$

FIG. 1: FIRST-ORDER 1-D LAGRANGE
SUBDOMAIN BASIS FUNCTIONS



$$L_1(x) = \frac{x - x_2}{x_1 - x_2}, \quad x_1 \leq x \leq x_2$$

$$L_2(x) = \frac{x - x_1}{x_2 - x_1}, \quad x_1 \leq x \leq x_2$$

AN IMPORTANT FEATURE OF
LAGRANGE'S POLYNOMIALS IS:

IF

$$y(x) = \sum_{j=1}^n a_j L_j(x)$$

THEN

$$a_1 = y(x_1)$$

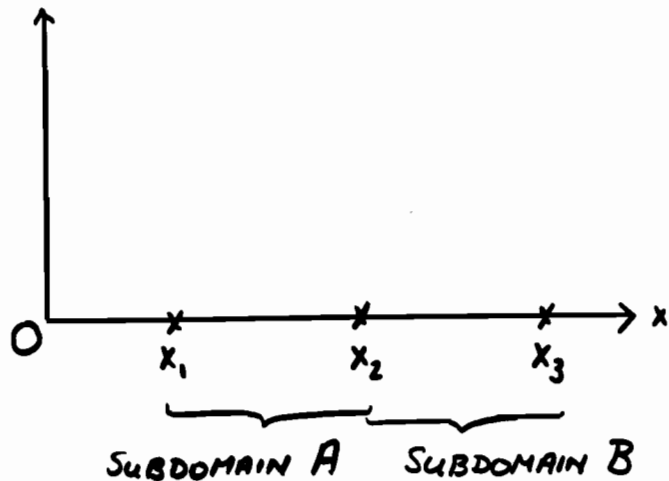
$$a_2 = y(x_2)$$

$$\vdots$$

$$a_n = y(x_n)$$

i.e., THE PARAMETERS a_j ARE
THE VALUES OF y AT
THE POINTS $x_1, \dots, x_j, \dots, x_n$.

CONSIDER 2 ADJACENT
SUBDOMAINS, A AND B :



USE FIRST-ORDER LAGRANGE
POLYNOMIALS ON EACH.

⇒ USE x_1, x_2 FOR A

USE x_2, x_3 FOR B

$$y(x) = \begin{cases} a_1^A L_1^A(x) + a_2^A L_2^A(x), & \text{IN } x_1 \leq x \leq x_2 \\ a_1^B L_1^B(x) + a_2^B L_2^B(x) & \text{IN } x_2 \leq x \leq x_3 \end{cases}$$

THERE ARE APPARENTLY 4 PARAMETERS:

$$a_1^A, a_2^A, a_1^B, a_2^B$$

BUT, RECALL THAT :

$$a_1^A = y(x_1)$$

$$a_2^A = y(x_2) \quad (\text{VALUE IN A})$$

$$a_1^B = y(x_2) \quad (\text{VALUE IN B})$$

$$a_2^B = y(x_3)$$

So, For A CONTINUOUS CURVE :

$$a_2^A = a_1^B$$

IF WE DENOTE $y(x_j)$ AS y_j :

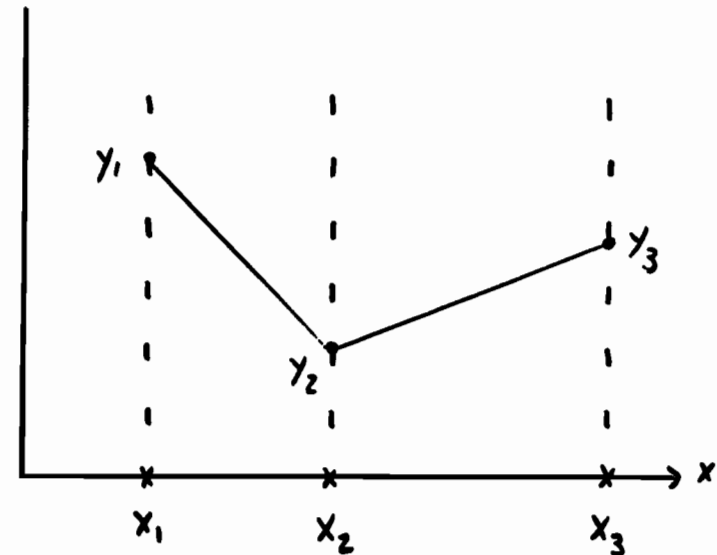
$$y(x) = \begin{cases} y_1 L_1^A(x) + y_2 L_2^A(x) & \text{IN } x_1 \leq x \leq x_2 \\ y_2 L_1^B(x) + y_3 L_2^B(x) & \text{IN } x_2 \leq x \leq x_3 \end{cases}$$

i.e., THERE ARE ONLY 3 PARAMETERS :

y_1 , y_2 , AND y_3 .

A TYPICAL CURVE $y(x)$ OF THIS

KIND IS :



SUCH A CURVE IS SAID TO BE
PIECEWISE LINEAR.

HERMITE'S POLYNOMIALS AS
SUBDOMAIN FUNCTIONS

CONSIDER THE POLYNOMIALS

FOR $j = 1, \dots, n$:

$$U_j(x) = [1 - 2L'_j(x_j)(x - x_j)] L_j^2(x)$$

$$V_j(x) = (x - x_j) L_j^2(x)$$

WHERE $x_1, \dots, x_n =$ GIVEN x VALUES

$L_j(x) =$ LAGRANGE POLYNOMIAL,
DEGREE $(n-1)$

$$L'_j(x) = \frac{dL_j}{dx}$$

IT IS POSSIBLE TO PROVE THE
FOLLOWING :

$$U_j(x_i) = \delta_{ij}$$

$$U'_j(x_i) = 0$$

$$V_j(x_i) = 0$$

$$V'_j(x_i) = \delta_{ij}$$

(δ_{ij} IS THE KRONECKER DELTA)

U_j AND V_j ARE POLYNOMIALS
OF DEGREE $(2n-1)$.

e.g., $n = 2 \Rightarrow$ DEGREE 3 (CUBIC)

$$L_1(x) = \frac{x-x_2}{x_1-x_2} ; L_1' = \frac{1}{x_1-x_2}$$

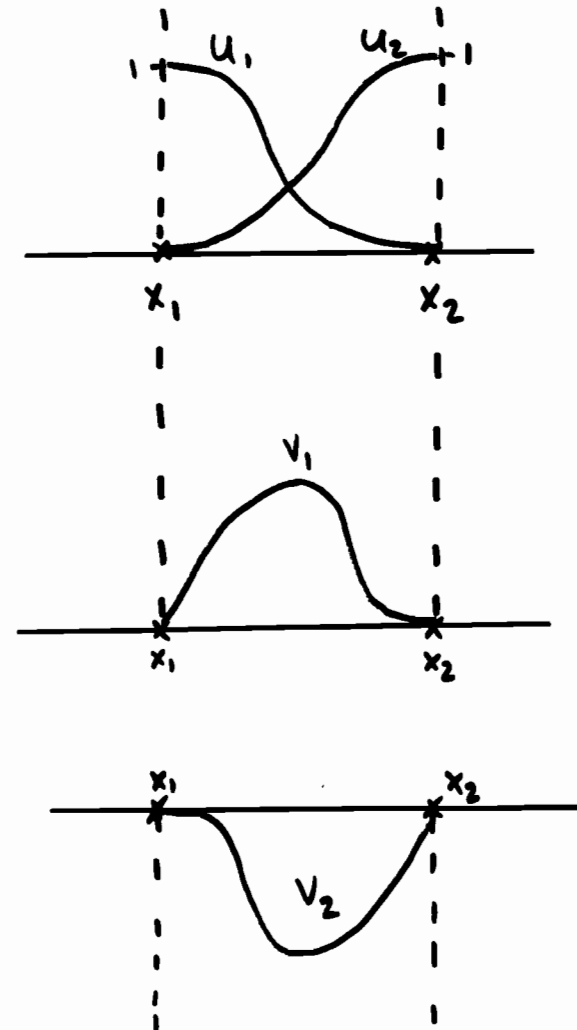
$$L_2(x) = \frac{x-x_1}{x_2-x_1} ; L_2' = \frac{1}{x_2-x_1}$$

$$U_1(x) = \left[1 - \frac{2}{x_1-x_2}(x-x_1) \right] \left(\frac{x-x_2}{x_1-x_2} \right)^2$$

$$U_2(x) = \left[1 - \frac{2}{x_2-x_1}(x-x_2) \right] \left(\frac{x-x_1}{x_2-x_1} \right)^2$$

$$V_1(x) = (x-x_1) \left(\frac{x-x_2}{x_1-x_2} \right)^2$$

$$V_2(x) = (x-x_2) \left(\frac{x-x_1}{x_2-x_1} \right)^2$$



NOW IF :

$$y(x) = \sum_{j=1}^n a_j U_j(x) + b_j V_j(x)$$

THEN :

$$a_1 = y(x_1) \quad ; \quad b_1 = y'(x_1)$$

$$a_2 = y(x_2) \quad ; \quad b_2 = y'(x_2)$$

\vdots

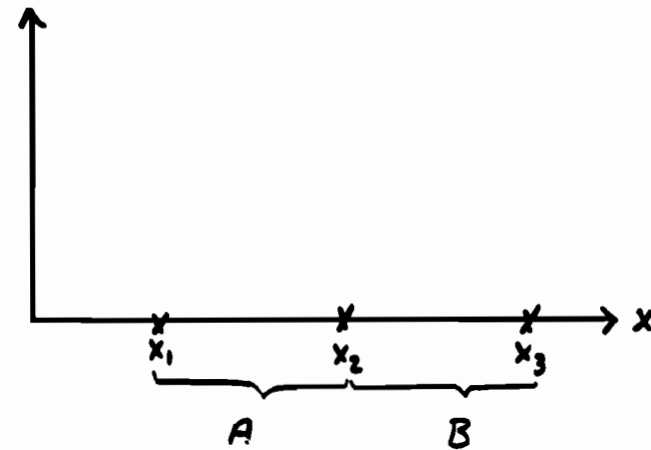
\vdots

$$a_n = y(x_n) \quad ; \quad b_n = y'(x_n)$$

i.e., THE PARAMETERS a_j ARE VALUES OF y AT THE POINTS $x_1, \dots, x_j, \dots, x_n$.

THE PARAMETERS b_j ARE VALUES OF dy/dx AT THE POINTS $x_1, \dots, x_j, \dots, x_n$.

CONSIDER 2 ADJACENT SUBDOMAINS, A AND B :



USE CUBIC HERMITE POLYNOMIALS ON EACH.

\Rightarrow USE x_1, x_2 FOR A

USE x_2, x_3 FOR B

$$y(x) = \begin{cases} a_1^A u_1^A(x) + a_2^A u_2^A(x) \\ + b_1^A v_1^A(x) + b_2^A v_2^A(x) \\ \text{IN SUBDOMAIN A} \\ \\ a_1^B u_1^B(x) + a_2^B u_2^B(x) \\ + b_1^B v_1^B(x) + b_2^B v_2^B(x) \\ \text{IN SUBDOMAIN B} \end{cases}$$

THERE ARE APPARENTLY 8 PARAMETERS

$$a_1^A, a_2^A, b_1^A, b_2^A,$$

$$a_1^B, a_2^B, b_1^B, b_2^B.$$

BUT, RECALL THAT :

$$a_1^A = y(x_1)$$

$$b_1^A = y'(x_1)$$

$$\left. \begin{matrix} a_2^A = y(x_2) \\ b_2^A = y'(x_2) \end{matrix} \right\} \text{VALUES IN A}$$

$$\left. \begin{matrix} a_1^B = y(x_2) \\ b_1^B = y'(x_2) \end{matrix} \right\} \text{VALUES IN B}$$

$$a_2^B = y(x_3)$$

$$b_2^B = y'(x_3)$$

So, For A CONTINUOUS (C_0)
CURVE :

$$Q_2^A = Q_1^B$$

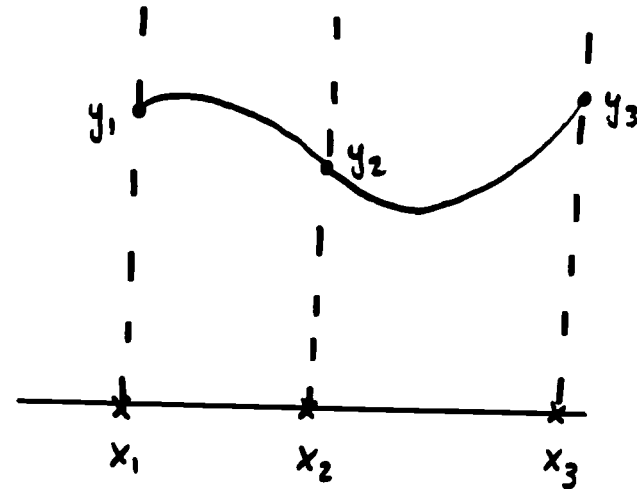
FOR A CURVE THAT ALSO HAS
CONTINUOUS SLOPE (C_1) :

$$b_2^A = b_1^B$$

i.e., THERE ARE ONLY 6 PARAMETERS:

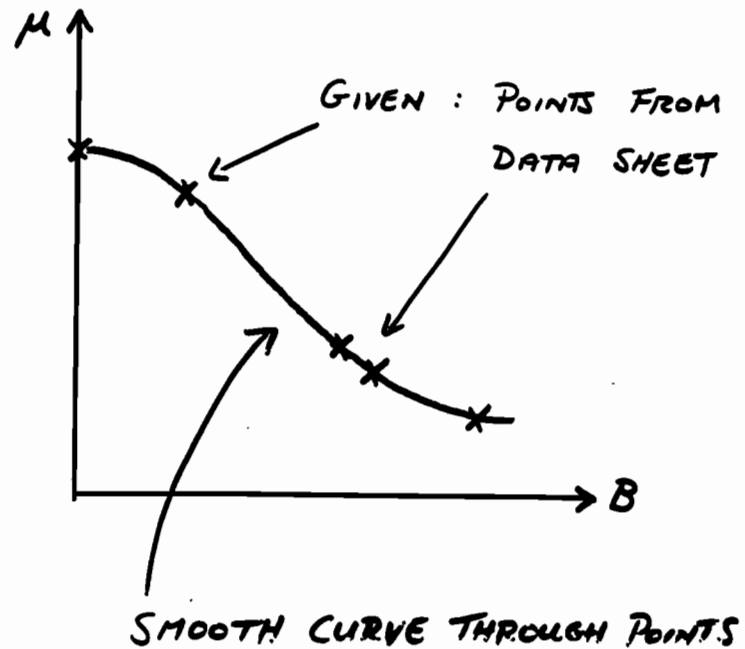
$$y_1, y_1', y_2, y_2', y_3, y_3'$$

A TYPICAL CURVE $y(x)$ IS :



INTERPOLATION

INTERPOLATION MEANS FINDING A CURVE THAT PASSES EXACTLY THROUGH A GIVEN SET OF POINTS.

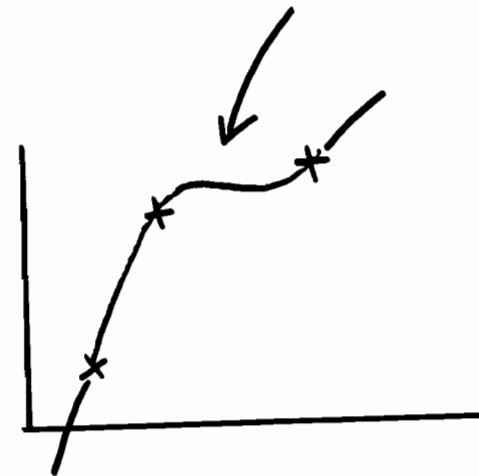


CV 29

HIGH - ORDER FULL-DOMAIN POLYNOMIALS

e.g. LAGRANGE POLYNOMIALS OF ORDER $(N-1)$, THROUGH N POINTS

- TEND TO GET "WIGGLES":

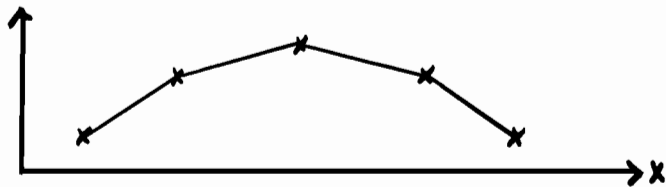


CV 30

PIECEWISE POLYNOMIALS :

a) FIRST-ORDER LAGRANGE

- SIMPLE, BUT
- NOT ALWAYS SMOOTH ENOUGH.



b) CUBIC HERMITE

i.e. INTERPOLATE y AND y'

- C_1 CONTINUITY, BUT
- DERIVATIVES AT DATA POINTS ARE NOT ALWAYS AVAILABLE.

c) CUBIC SPLINES

START WITH CUBICS ON N INTERVALS : $4N$ DEGREES OF FREEDOM (DOF)

INTERPOLATE y AT $N+1$ DATA POINTS : $2N$ CONSTRAINTS

MATCH y' AND y'' AT $N-1$ DATA POINTS : $2(N-1)$ CONSTRAINTS

Fix y' AT 2 ENDS : 2 CONSTRAINTS

\Rightarrow REMAINING DOFS : 0

"DRAFTING" SPLINE : BENDS SO SLOPE AND CURVATURE ARE CONTINUOUS (C_2).

IT CAN BE SHOWN THAT:

$$a_i = \frac{1}{6h_i} (y_{i+1}'' - y_i'')$$

$$b_i = y_i''/2$$

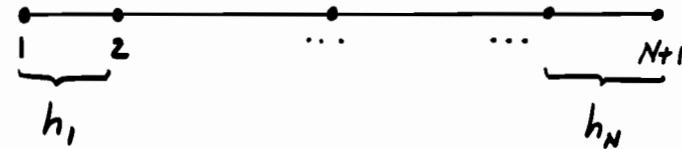
$$c_i = \frac{1}{h_i} (y_{i+1} - y_i) - \frac{h_i}{6} (y_{i+1}'' + 2y_i'')$$

$$d_i = y_i$$

⇒ GIVEN y_i AND y_i'' AT ALL THE NODES,

WE COULD USE THE EQUATIONS ABOVE

TO GET A CUBIC IN EACH SEGMENT.



ON SEGMENT i :

$$\begin{aligned} S_i(x) = & a_i (x - x_i)^3 \\ & + b_i (x - x_i)^2 \\ & + c_i (x - x_i) \\ & + d_i \end{aligned}$$

LET y_i = VALUE OF y AT x_i

y_i'' = VALUE OF $\frac{d^2 y}{dx^2}$ AT x_i

BUT WE DON'T USUALLY KNOW y_i'' .

INSTEAD : IMPOSE SLOPE CONTINUITY:

FOR $i = 1, \dots, N-1$:

$$S_i'(x_{i+1}) = S_{i+1}'(x_{i+1})$$

OR :

$$\begin{aligned} y_i'' \frac{h_i}{6} + y_{i+1}'' \left(\frac{h_i}{3} + \frac{h_{i+1}}{3} \right) + y_{i+2}'' \frac{h_{i+1}}{6} \\ = \frac{y_{i+2} - y_{i+1}}{h_{i+1}} - \frac{y_{i+1} - y_i}{h_i} \end{aligned}$$

CHOOSE $y_1'' = y_{N+1}'' = 0$ (FOR SIMPLICITY).

THEN :

$$\begin{pmatrix} \frac{h_1+h_2}{3} & \frac{h_2}{6} & & & \\ \frac{h_2}{6} & \frac{h_2+h_3}{3} & \frac{h_3}{6} & & \\ & & \ddots & \ddots & \\ & & & \ddots & \ddots \\ & & & & \ddots & \ddots \end{pmatrix} \begin{pmatrix} y_2'' \\ y_3'' \\ \vdots \\ y_N'' \end{pmatrix} = \begin{pmatrix} \frac{y_3-y_2}{h_2} - \frac{y_2-y_1}{h_1} \\ \frac{y_4-y_3}{h_3} - \frac{y_3-y_2}{h_2} \\ \vdots \\ \frac{y_{N+1}-y_N}{h_N} - \frac{y_N-y_{N-1}}{h_{N-1}} \end{pmatrix}$$

↑
SYMMETRIC TRIDIAGONAL MATRIX

SOLVE FOR $y_2'', y_3'', \dots, y_N''$

THEN GET a_i, b_i, c_i, d_i

FOR $i = 1, 2, \dots, N$.