

Chaoyang Wang

MSR student of CMU Robotics Institute

Interested in computer vision & machine learning.

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Education

- **Carnegie Mellon University** M.S. in robotics
Supervised by Prof. Simon Lucey 2016 - 2018
- **Shanghai Jiao Tong University** M.S. & B.E. in CS
Member of ACM Teaching Reform Class(top 28 students selected) 2009 - 2016

Publications

1. "Learning Depth from Monocular Videos using Direct Methods", **CVPR** 2018,
Chaoyang Wang, Jose Miguel Buenaposada, Rui Zhu, Simon Lucey.
2. "Deep-LK for Efficient Adaptive Object Tracking", **ICRA** 2018,
Chaoyang Wang, Hamed Kiani, Chen-Hsuan Lin, Simon Lucey.
3. "Object-Centric Photometric Bundle Adjustment with Deep Shape Prior", **WACV** 2018,
Rui Zhu, Chaoyang Wang, Chen-Hsuan Lin, Simon Lucey.
4. "Rethinking Reprojection: Closing the Loop for Pose-aware Shape Reconstruction from a Single Image", **ICCV(spotlight)** 2017,
Rui Zhu, Hamed Kiani, Chaoyang Wang, Simon Lucey.
5. "Object Proposal by Multi-branched Hierarchical Segmentation", **CVPR** 2015,
Chaoyang Wang, Long Zhao, Shuang Liang, Liqing Zhang, Jinyuan Jia, Yichen Wei,
6. "Binocular Photometric Stereo Acquisition and Reconstruction for 3D Talking Head Applications", **INTERSPEECH** 2013,
Chaoyang Wang, Lijuan Wang, Yasuyuki Matsushita, Bojun Huang, Magnetron Chen, Frank K. Soong.
7. "Semantic Photometric Bundle Adjustment on Natural Sequences", arXiv:1712.00110,
Rui Zhu, Chaoyang Wang, Ziyang Wang, Simon Lucey.

Research Experience

- **Carnegie Mellon University, CI2CV Lab** 09/2016 - present
Advisor: Prof. Simon Lucey, collaborate with Prof. Hongdong Li
 - Incorporated direct visual SLAM techniques for the purpose of unsupervised learning a monocular depth estimator from ego-centric videos. Achieved comparable accuracy compared to state of the arts trained with supervision.
 - Proposed a Deep-LK object tracker, which achieves comparable accuracy compared to state of the arts, while running at 100fps on GPU, and over 20fps on CPU.
 - Trained a 3D object reconstruction network with supervision from both synthetic data and objects' silhouette in real-life photos. This work was the first of its kind able to predict 3D voxel representation of an object together with its pose.
- **Microsoft Research Asia, Visual Computing Group** 07/2014-05/2015
Advisor: Dr. Yichen Wei

- Proposed a multi-branch hierarchical region proposal algorithm to speed up and improve object detection.
- Developed a cost-sensitive learning algorithm to optimize the face detection and facial landmark regression pipeline, sped up by more than 40% with minor accuracy reduction.

• **Brain-like Computing&Machine Intelligence Lab**

09/2013-05/2014

Advisor: Prof. Liqing Zhang

- Learning discriminative object part detectors from multi-layer CNN features.
- Line-of-interest pedestrian counting in surveillance video.

• **Microsoft Research Asia, Speech Group**

07/2012 - 03/2013

Advisor: Prof. Frank K. Soong, Prof. Yasuyuki Matsushita, Dr. Lijuan Wang

- Worked on photo-realistic text-to-speech talking head synthesis.
- Built a binocular photometric stereo system for facial performance data acquisition. The system is able to reconstruct accurate 3D human face with fine surface details such as wrinkles.

Recent Awards, Grants & Honours

National Scholarship (top 2%)	2015
Microsoft Research Asia Excellent Internship Award	2015
First-class Academic Scholarship, Shanghai Jiao Tong Univ(top 10%).	2013, 2014 & 2015
Microsoft Research Asia Young Fellowship(3 students each school)	2012
Second Prize in Physics Contest for Shanghai College Students	2010

Professional Activities

- Reviewer for ICRA 2018 and 3DV 2017.
- Teaching assistant for “CS377: Project Workshop of Database System”, 2013.
- Student volunteer for IEEE FG 2013.

Programming Skills

- C, C++, Matlab, Java, Python, Lua

English Test Scores

- TOFEL: 106 (S:22, W:28, L:29, R:27)
- GRE: 323 (V:153, Q:170), AW:3.5