

Advanced Algorithms (I)

Chihao Zhang

Shanghai Jiao Tong University

Feb. 25, 2019

ADVANCED ALGORITHMS

ADVANCED ALGORITHMS

In the course, we will learn **Approximation Algorithms**

ADVANCED ALGORITHMS

In the course, we will learn **Approximation Algorithms**

- ▶ linear programming, semi-definite programming
- ▶ spectral method
- ▶ random walks
- ▶ ...

ADVANCED ALGORITHMS

In the course, we will learn **Approximation Algorithms**

- ▶ linear programming, semi-definite programming
- ▶ spectral method
- ▶ random walks
- ▶ ...

We will emphasize on

- ▶ tools for designing approximation algorithms
- ▶ rigorous analysis of algorithms

COURSE INFO

COURSE INFO

- ▶ Instructor: Chihao Zhang
- ▶ Course Homepage:
<http://chihaozhang.com/teaching/AA2019spring/>
- ▶ Office Hour: every Monday, 7:00pm - 9:00pm

COURSE INFO

- ▶ Instructor: Chihao Zhang
- ▶ Course Homepage:
<http://chihaozhang.com/teaching/AA2019spring/>
- ▶ Office Hour: every Monday, 7:00pm - 9:00pm

Grading Policy

- ▶ Homework 30%
- ▶ Mid-term Exam 30%
- ▶ Course Project 40%

MaxSAT

MaxSAT

Given a CNF formula ϕ , is it satisfiable?

MaxSAT

Given a CNF formula ϕ , is it satisfiable?

$$\phi = (x_1 \vee x_3 \vee \bar{x}_{29}) \wedge (\bar{x}_3 \vee x_7) \wedge \cdots \wedge (\bar{x}_{33} \vee \bar{x}_{34} \vee x_{90} \vee x_{126})$$

MaxSAT

Given a CNF formula ϕ , is it satisfiable?

$$\phi = (x_1 \vee x_3 \vee \bar{x}_{29}) \wedge (\bar{x}_3 \vee x_7) \wedge \cdots \wedge (\bar{x}_{33} \vee \bar{x}_{34} \vee x_{90} \vee x_{126})$$

NP-hard, we look at its **optimization version**.

MaxSAT

Given a CNF formula ϕ , is it satisfiable?

$$\phi = (x_1 \vee x_3 \vee \bar{x}_{29}) \wedge (\bar{x}_3 \vee x_7) \wedge \cdots \wedge (\bar{x}_{33} \vee \bar{x}_{34} \vee x_{90} \vee x_{126})$$

NP-hard, we look at its **optimization version**.

MaxSAT

Input: A CNF formula $\phi = C_1 \wedge C_2 \cdots \wedge C_m$.

Problem: Compute an assignment that satisfies maximum number of clauses.

MaxSAT

Given a CNF formula ϕ , is it satisfiable?

$$\phi = (x_1 \vee x_3 \vee \bar{x}_{29}) \wedge (\bar{x}_3 \vee x_7) \wedge \cdots \wedge (\bar{x}_{33} \vee \bar{x}_{34} \vee x_{90} \vee x_{126})$$

NP-hard, we look at its **optimization version**.

MaxSAT

Input: A CNF formula $\phi = C_1 \wedge C_2 \cdots \wedge C_m$.

Problem: Compute an assignment that satisfies maximum number of clauses.

Harder than SAT, so we look for an **approximate solution**.

Tossing a Coin

TOSSING A COIN

An instance ϕ

- ▶ The variable sets $V = \{x_1, x_2, \dots, x_n\}$
- ▶ The set of clauses $C = \{C_1, C_2, \dots, C_m\}$
- ▶ Each clause C_i contains ℓ_i literals

TOSSING A COIN

An instance ϕ

- ▶ The variable sets $V = \{x_1, x_2, \dots, x_n\}$
- ▶ The set of clauses $C = \{C_1, C_2, \dots, C_m\}$
- ▶ Each clause C_i contains ℓ_i literals

We first consider the following simple algorithm:



TOSSING A COIN

An instance ϕ

- ▶ The variable sets $V = \{x_1, x_2, \dots, x_n\}$
- ▶ The set of clauses $C = \{C_1, C_2, \dots, C_m\}$
- ▶ Each clause C_i contains ℓ_i literals

We first consider the following simple algorithm:

- ▶ For each variable x_i , toss an independent fair coin.

Tossing A Coin

An instance ϕ

- ▶ The variable sets $V = \{x_1, x_2, \dots, x_n\}$
- ▶ The set of clauses $C = \{C_1, C_2, \dots, C_m\}$
- ▶ Each clause C_i contains ℓ_i literals

We first consider the following simple algorithm:

- ▶ For each variable x_i , toss an **independent fair** coin.
- ▶ If the coin goes HEAD, we set x_i **true**, otherwise we set x_i **false**.

ANALYSIS

ANALYSIS

The outcome of the algorithm is **random**, we are interested in its **expectation**.

ANALYSIS

The outcome of the algorithm is **random**, we are interested in its **expectation**.

For this particular algorithm, it can be **derandomized**.

ANALYSIS

The outcome of the algorithm is **random**, we are interested in its **expectation**.

For this particular algorithm, it can be **derandomized**.

$$\mathbf{E} [X] = \sum_{i=1}^m \mathbf{Pr} [C_i \text{ is satisfied}]$$

ANALYSIS

The outcome of the algorithm is **random**, we are interested in its **expectation**.

For this particular algorithm, it can be **derandomized**.

$$\mathbf{E} [X] = \sum_{i=1}^m \mathbf{Pr} [C_i \text{ is satisfied}] = \sum_{i=1}^m \left(1 - 2^{-\ell_i}\right) \geq \frac{m}{2}.$$

ANALYSIS

The outcome of the algorithm is **random**, we are interested in its **expectation**.

For this particular algorithm, it can be **derandomized**.

$$\mathbf{E} [X] = \sum_{i=1}^m \mathbf{Pr} [C_i \text{ is satisfied}] = \sum_{i=1}^m \left(1 - 2^{-\ell_i}\right) \geq \frac{m}{2}.$$

On the otherhand,

$$\mathbf{OPT} \leq m.$$

ANALYSIS

The outcome of the algorithm is **random**, we are interested in its **expectation**.

For this particular algorithm, it can be **derandomized**.

$$\mathbf{E}[X] = \sum_{i=1}^m \mathbf{Pr}[C_i \text{ is satisfied}] = \sum_{i=1}^m (1 - 2^{-\ell_i}) \geq \frac{m}{2}.$$

On the otherhand,

$$\mathbf{OPT} \leq m.$$

Therefore,

$$\mathbf{E}[X] \geq \frac{1}{2} \cdot \mathbf{OPT}.$$

Can we improve the previous algorithm?

Can we improve the previous algorithm?

Observations

- ▶ the worst case happens when for some singleton clause, i.e., $\ell_i = 1$;

Can we improve the previous algorithm?

Observations

- ▶ the worst case happens when for some singleton clause, i.e., $\ell_i = 1$;
- ▶ for a singleton $C = x$, if there is no $C' = \bar{x}$, then we can increase the probability of x to be true;

Can we improve the previous algorithm?

Observations

- ▶ the worst case happens when for some singleton clause, i.e., $\ell_i = 1$;
- ▶ for a singleton $C = x$, **if there is no $C' = \bar{x}$** , then we can increase the probability of x to be true;
- ▶ otherwise, we can improve the **upper bound** for **OPT!** (x and \bar{x} cannot be both satisfied)

TOSSING A BIASED COIN

TOSSING A BIASED COIN

Let the p -biased coin be with probability p to HEAD, $1 - p$ to TAIL.

TOSSING A BIASED COIN

Let the p -biased coin be with probability p to HEAD, $1 - p$ to TAIL.



TOSSING A BIASED COIN

Let the p -biased coin be with probability p to HEAD, $1 - p$ to TAIL.

- For each variable x_i , toss an independent p -biased coin.

TOSSING A BIASED COIN

Let the p -biased coin be with probability p to HEAD, $1 - p$ to TAIL.

- ▶ For each variable x_i , toss an independent p -biased coin.
- ▶ If the coin goes HEAD, we set x_i **true**, otherwise we set x_i **false**.

ANALYSIS

ANALYSIS

Assumption for Clauses of ϕ

- ▶ More positive singletons than negative singletons.

ANALYSIS

Assumption for Clauses of ϕ

- ▶ More positive singletons than negative singletons.
- ▶ There are t pairs of x and \bar{x} .

ANALYSIS

Assumption for Clauses of ϕ

- ▶ More positive singletons than negative singletons.
- ▶ There are t pairs of x and \bar{x} .
- ▶ $p \geq \frac{1}{2}$.

$$\mathbf{E}[X] \geq t + (m - 2t) \min\{p, 1 - p^2\}.$$

ANALYSIS

Assumption for Clauses of ϕ

- ▶ More positive singletons than negative singletons.
- ▶ There are t pairs of x and \bar{x} .
- ▶ $p \geq \frac{1}{2}$.

$$\mathbf{E}[X] \geq t + (m - 2t) \min\{p, 1 - p^2\}.$$

The new upper bound for **OPT**:

$$\mathbf{OPT} \leq m - t$$

ANALYSIS

Assumption for Clauses of ϕ

- ▶ More positive singletons than negative singletons.
- ▶ There are t pairs of x and \bar{x} .
- ▶ $p \geq \frac{1}{2}$.

$$\mathbf{E}[X] \geq t + (m - 2t) \min\{p, 1 - p^2\}.$$

The new upper bound for **OPT**:

$$\mathbf{OPT} \leq m - t$$

Combine them and obtain

$$\mathbf{E}[X] \geq \alpha \cdot \mathbf{OPT}$$

where $\alpha \approx 0.618$.

Can we further improve the algorithm?

Can we further improve the algorithm?

We can use **different coins** for each variable, e.g., in

$$\phi = x_1 \wedge (x_1 \vee \bar{x}_2),$$

we prefer to set x_1 to **true**.

Can we further improve the algorithm?

We can use **different coins** for each variable, e.g., in

$$\phi = x_1 \wedge (x_1 \vee \bar{x}_2),$$

we prefer to set x_1 to **true**.

How can we make use of the information?

Can we further improve the algorithm?

We can use **different coins** for each variable, e.g., in

$$\phi = x_1 \wedge (x_1 \vee \bar{x}_2),$$

we prefer to set x_1 to **true**.

How can we make use of the information?

Linear Programming helps.

TOSSING CLEVER COINS

TOSSING CLEVER COINS

We introduce the following variables.

TOSSING CLEVER COINS

We introduce the following variables.

- ▶ for every $i \in [n]$, y_i indicates whether x_i is true;
- ▶ for every $j \in [m]$, z_j indicates whether C_j is satisfied.

TOSSING CLEVER COINS

We introduce the following variables.

- ▶ for every $i \in [n]$, y_i indicates whether x_i is true;
- ▶ for every $j \in [m]$, z_j indicates whether C_j is satisfied.

$$\begin{aligned} & \max \quad \sum_{j=1}^m z_j \\ \text{subject to} \quad & \sum_{i \in P_j} y_i + \sum_{k \in N_j} (1 - y_k) \geq z_j, \quad \forall j \in [m] \text{ s.t. } C_j = \bigvee_{i \in P_j} x_i \vee \bigvee_{k \in N_j} \bar{x}_k \\ & z_j \in \{0, 1\}, \quad \forall j \in [m] \\ & y_i \in \{0, 1\}, \quad \forall i \in [n] \end{aligned}$$

TOSSING CLEVER COINS

We introduce the following variables.

- ▶ for every $i \in [n]$, y_i indicates whether x_i is true;
- ▶ for every $j \in [m]$, z_j indicates whether C_j is satisfied.

$$\begin{aligned} & \max \quad \sum_{j=1}^m z_j \\ \text{subject to} \quad & \sum_{i \in P_j} y_i + \sum_{k \in N_j} (1 - y_k) \geq z_j, \quad \forall j \in [m] \text{ s.t. } C_j = \bigvee_{i \in P_j} x_i \vee \bigvee_{k \in N_j} \bar{x}_k \\ & z_j \in \{0, 1\}, \quad \forall j \in [m] \\ & y_i \in \{0, 1\}, \quad \forall i \in [n] \end{aligned}$$

This **integer program** is equivalent to MaxSAT.

RELAXATION

RELAXATION

There is no efficient algorithm for **integer programming** in general

RELAXATION

There is no efficient algorithm for **integer programming** in general

Therefore, we relax its **non-linear** constraints

RELAXATION

There is no efficient algorithm for **integer programming** in general

Therefore, we relax its **non-linear** constraints

$$\begin{aligned} \max \quad & \sum_{j=1}^m z_j \\ \text{subject to} \quad & \sum_{i \in P_j} y_i + \sum_{k \in N_j} (1 - y_k) \geq z_j, \quad \forall j \in [m] \text{ s.t. } C_j = \bigvee_{i \in P_j} x_i \vee \bigvee_{k \in N_j} \bar{x}_k \\ & 0 \leq z_j \leq 1, \quad \forall j \in [m] \\ & 0 \leq y_i \leq 1, \quad \forall i \in [n] \end{aligned}$$

RELAXATION

There is no efficient algorithm for **integer programming** in general

Therefore, we relax its **non-linear** constraints

$$\begin{aligned} \max \quad & \sum_{j=1}^m z_j \\ \text{subject to} \quad & \sum_{i \in P_j} y_i + \sum_{k \in P_j} (1 - y_k) \geq z_j, \quad \forall j \in [m] \text{ s.t. } C_j = \bigvee_{i \in P_j} x_i \vee \bigvee_{k \in N_j} \bar{x}_k \\ & 0 \leq z_j \leq 1, \quad \forall j \in [m] \\ & 0 \leq y_i \leq 1, \quad \forall i \in [n] \end{aligned}$$

We can solve this LP in **poly-time**

ALGORITHM

ALGORITHM

Let $\left(\{y_i^*\}_{i \in [n]}, \{z_j^*\}_{j \in [m]} \right)$ be an optimal solution of the LP.

ALGORITHM

Let $\left(\{y_i^*\}_{i \in [n]}, \{z_j^*\}_{j \in [m]} \right)$ be an optimal solution of the LP.



ALGORITHM

Let $\left(\{y_i^*\}_{i \in [n]}, \{z_j^*\}_{j \in [m]} \right)$ be an optimal solution of the LP.

- For each variable x_i , toss an independent y_i^* -biased coin.

ALGORITHM

Let $\left(\{y_i^*\}_{i \in [n]}, \{z_j^*\}_{j \in [m]} \right)$ be an optimal solution of the LP.

- ▶ For each variable x_i , toss an independent y_i^* -biased coin.
- ▶ If the coin goes HEAD, we set x_i **true**, otherwise we set x_i **false**.

ANALYSIS

ANALYSIS

A typical upper bound of **OPT** for LP based algorithms is

$$\mathbf{OPT} \leq \mathbf{OPT}(LP) = \sum_{j=1}^m z_j^*$$

ANALYSIS

A typical upper bound of **OPT** for LP based algorithms is

$$\mathbf{OPT} \leq \mathbf{OPT}(LP) = \sum_{j=1}^m z_j^*$$

We can further establish

$$\mathbf{E}[X] \geq \left(1 - \frac{1}{e}\right) \sum_{j=1}^m z_j^*.$$

ANALYSIS

A typical upper bound of **OPT** for LP based algorithms is

$$\mathbf{OPT} \leq \mathbf{OPT}(LP) = \sum_{j=1}^m z_j^*$$

We can further establish

$$\mathbf{E}[X] \geq \left(1 - \frac{1}{e}\right) \sum_{j=1}^m z_j^*.$$

Therefore, the LP rounding is a $\left(1 - \frac{1}{e}\right)$ -approximation algorithm for MaxSAT

Advanced Algorithms (II)

Chihao Zhang

Shanghai Jiao Tong University

Mar. 4, 2019

MaxSAT

MaxSAT

Recall that we can obtain a $\frac{3}{4}$ -approximation by choosing the better of the two.

MaxSAT

Recall that we can obtain a $\frac{3}{4}$ -approximation by choosing the better of the two.

We show that this ratio can also be achieved via direct rounding.

MaxSAT

Recall that we can obtain a $\frac{3}{4}$ -approximation by **choosing the better of the two**.

We show that this ratio can also be achieved via direct **rounding**.

Recall that we have the following **linear programming relaxation**.

$$\begin{aligned} & \max \quad \sum_{j=1}^m z_j \\ & \text{subject to} \quad \sum_{i \in P_j} y_i + \sum_{k \in N_j} (1 - y_k) \geq z_j, \quad \forall C_j = \bigvee_{i \in P_j} x_i \vee \bigvee_{k \in N_j} \bar{x}_k \\ & \quad z_j \in [0, 1], \quad \forall j \in [m] \\ & \quad y_i \in [0, 1], \quad \forall i \in [n] \end{aligned}$$

Let $\{y_i^*\}_{i \in [n]}, \{z_j^*\}_{j \in [m]}$ be an optimal solution of the LP.

Let $\{y_i^*\}_{i \in [n]}, \{z_j^*\}_{j \in [m]}$ be an optimal solution of the LP.

Instead of tossing y_i^* -biased coins, we toss $f(y_i^*)$ -biased coins for some function $f(\cdot) \in [0, 1]$.

Let $\{y_i^*\}_{i \in [n]}, \{z_j^*\}_{j \in [m]}$ be an optimal solution of the LP.

Instead of tossing y_i^* -biased coins, we toss $f(y_i^*)$ -biased coins for some function $f(\cdot) \in [0, 1]$.

For $C_j = \bigvee_{i \in P_j} x_i \vee \bigvee_{k \in N_j} \bar{x}_k$,

$$\Pr [C_j \text{ is not satisfied}] = \prod_{i \in P_j} (1 - f(y_i^*)) \prod_{k \in N_j} f(y_k^*).$$

Let $\{y_i^*\}_{i \in [n]}, \{z_j^*\}_{j \in [m]}$ be an optimal solution of the LP.

Instead of tossing y_i^* -biased coins, we toss $f(y_i^*)$ -biased coins for some function $f(\cdot) \in [0, 1]$.

For $C_j = \bigvee_{i \in P_j} x_i \vee \bigvee_{k \in N_j} \bar{x}_k$,

$$\Pr [C_j \text{ is not satisfied}] = \prod_{i \in P_j} (1 - f(y_i^*)) \prod_{k \in N_j} f(y_k^*).$$

We can choose a suitable f to get $\frac{3}{4}$ approximation.

INTEGRALITY GAP

INTEGRALITY GAP

In most **LP based** approximation algorithms, the upper bound for the OPT is

$$\mathbf{OPT} \leq \mathbf{OPT}(LP).$$

INTEGRALITY GAP

In most **LP based** approximation algorithms, the upper bound for the OPT is

$$\text{OPT} \leq \text{OPT}(LP).$$

Then we establish

$$\text{OPT}^* \geq \alpha \cdot \text{OPT}(LP) \geq \alpha \cdot \text{OPT}.$$

INTEGRALITY GAP

In most **LP based** approximation algorithms, the upper bound for the OPT is

$$\text{OPT} \leq \text{OPT}(\text{LP}).$$

Then we establish

$$\text{OPT}^* \geq \alpha \cdot \text{OPT}(\text{LP}) \geq \alpha \cdot \text{OPT}.$$

If we already know

$$\text{OPT} \leq \beta \cdot \text{OPT}(\text{LP}),$$

INTEGRALITY GAP

In most **LP based** approximation algorithms, the upper bound for the OPT is

$$\mathbf{OPT} \leq \mathbf{OPT}(LP).$$

Then we establish

$$OPT^* \geq \alpha \cdot \mathbf{OPT}(LP) \geq \alpha \cdot \mathbf{OPT}.$$

If we already know

$$\mathbf{OPT} \leq \beta \cdot \mathbf{OPT}(LP),$$

then we cannot have $\alpha > \beta$!

INTEGRALITY GAP

In most **LP based** approximation algorithms, the upper bound for the OPT is

$$\mathbf{OPT} \leq \mathbf{OPT}(LP).$$

Then we establish

$$OPT^* \geq \alpha \cdot \mathbf{OPT}(LP) \geq \alpha \cdot \mathbf{OPT}.$$

If we already know

$$\mathbf{OPT} \leq \beta \cdot \mathbf{OPT}(LP),$$

then we cannot have $\alpha > \beta$!

The ratio β is called the **integrality gap** of **the** LP relaxation.

INTEGRALITY GAP FOR MAXSAT

INTEGRALITY GAP FOR MAXSAT

Consider the instance,

$$(x_1 \vee x_2) \wedge (x_1 \vee \bar{x}_2) \wedge (\bar{x}_1 \vee x_2) \wedge (\bar{x}_1 \vee \bar{x}_2)$$

INTEGRALITY GAP FOR MAXSAT

Consider the instance,

$$(x_1 \vee x_2) \wedge (x_1 \vee \bar{x}_2) \wedge (\bar{x}_1 \vee x_2) \wedge (\bar{x}_1 \vee \bar{x}_2)$$

OPT = 3 and **OPT**(*LP*) = 4.

INTEGRALITY GAP FOR MAXSAT

Consider the instance,

$$(x_1 \vee x_2) \wedge (x_1 \vee \bar{x}_2) \wedge (\bar{x}_1 \vee x_2) \wedge (\bar{x}_1 \vee \bar{x}_2)$$

OPT = 3 and **OPT**(LP) = 4.

The **integrality gap** of our LP is $\frac{3}{4}$.

INTEGRALITY GAP FOR MAXSAT

Consider the instance,

$$(x_1 \vee x_2) \wedge (x_1 \vee \bar{x}_2) \wedge (\bar{x}_1 \vee x_2) \wedge (\bar{x}_1 \vee \bar{x}_2)$$

OPT = 3 and **OPT**(*LP*) = 4.

The **integrality gap** of our LP is $\frac{3}{4}$.

Corollary. We cannot beat $\frac{3}{4}$ if we use **OPT** \leq **OPT**(*LP*) upper bound.

MINIMUM LABEL CUT

MINIMUM LABEL CUT

MINIMUM LABEL s - t CUT

Input: A graph $G = (V, E)$; a set of labels $[L] = \{1, 2, \dots, L\}$ such that each $e \in E$ is labelled with one $\ell(e) \in [L]$; two vertices $s, t \in V$.

Problem: Compute a minimum **set of labels** $L' \subseteq [L]$ such that the removal of all edges with label in L' disconnects s and t .

MINIMUM LABEL CUT

MINIMUM LABEL s - t CUT

Input: A graph $G = (V, E)$; a set of labels $[L] = \{1, 2, \dots, L\}$ such that each $e \in E$ is labelled with one $\ell(e) \in [L]$; two vertices $s, t \in V$.

Problem: Compute a minimum **set of labels** $L' \subseteq [L]$ such that the removal of all edges with label in L' disconnects s and t .

NP-hard, and even hard to approximate with **any constant ratio** (unless **NP = P**).

LP RELAXATION

LP RELAXATION

We introduce a variable z_j for each label $j \in [L]$. Let $\mathcal{P}_{s,t}$ be the collection of paths between s and t .

LP RELAXATION

We introduce a variable z_j for each label $j \in [L]$. Let $\mathcal{P}_{s,t}$ be the collection of paths between s and t .

$$\begin{aligned} \min \quad & \sum_{j=1}^L z_j \\ \text{subject to} \quad & \sum_{e \in P} z_{\ell(e)} \geq 1, \quad \forall P \in \mathcal{P}_{s,t} \\ & z_j \in [0, 1], \quad \forall j \in [L] \end{aligned}$$

LP RELAXATION

We introduce a variable z_j for each label $j \in [L]$. Let $\mathcal{P}_{s,t}$ be the collection of paths between s and t .

$$\begin{aligned} \min \quad & \sum_{j=1}^L z_j \\ \text{subject to} \quad & \sum_{e \in P} z_{\ell(e)} \geq 1, \quad \forall P \in \mathcal{P}_{s,t} \\ & z_j \in [0, 1], \quad \forall j \in [L] \end{aligned}$$

Q1: How to solve this LP efficiently?

LP RELAXATION

We introduce a variable z_j for each label $j \in [L]$. Let $\mathcal{P}_{s,t}$ be the collection of paths between s and t .

$$\begin{aligned} \min \quad & \sum_{j=1}^L z_j \\ \text{subject to} \quad & \sum_{e \in P} z_{\ell(e)} \geq 1, \quad \forall P \in \mathcal{P}_{s,t} \\ & z_j \in [0, 1], \quad \forall j \in [L] \end{aligned}$$

Q1: How to solve this LP efficiently?

Q2: What is the integrality gap of this LP?

LP RELAXATION

We introduce a variable z_j for each label $j \in [L]$. Let $\mathcal{P}_{s,t}$ be the collection of paths between s and t .

$$\begin{aligned} \min \quad & \sum_{j=1}^L z_j \\ \text{subject to} \quad & \sum_{e \in P} z_{\ell(e)} \geq 1, \quad \forall P \in \mathcal{P}_{s,t} \\ & z_j \in [0, 1], \quad \forall j \in [L] \end{aligned}$$

Q1: How to solve this LP efficiently?

Q2: What is the integrality gap of this LP? $\Omega(m)$.

SEPARATION ORACLE

SEPARATION ORACLE

We can solve the LP in poly-time using **ellipsoid method** provided a **separation oracle**:

SEPARATION ORACLE

We can solve the LP in poly-time using **ellipsoid method** provided a **separation oracle**:

Given a point, in PTIME either

- ▶ confirm it is a feasible solution; or
- ▶ find a violated constraint.

SEPARATION ORACLE

We can solve the LP in poly-time using **ellipsoid method** provided a **separation oracle**:

Given a point, in PTIME either

- ▶ confirm it is a feasible solution; or
- ▶ find a violated constraint.

Oracle here: shortest s - t path

BEAT THE INTEGRALITY GAP

BEAT THE INTEGRALITY GAP

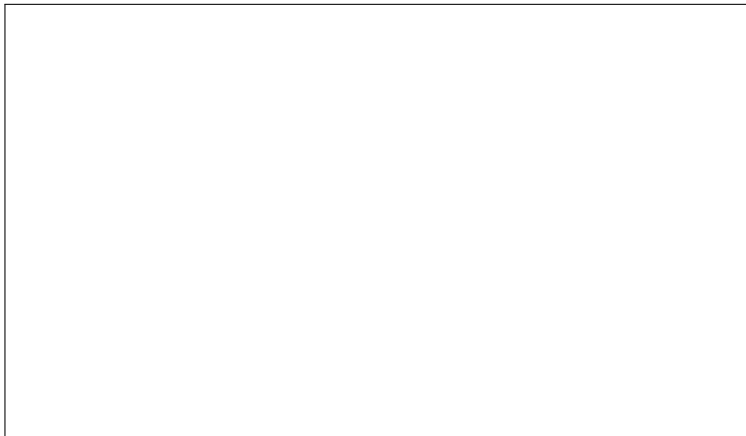
- ▶ Obtain a partial solution via **rounding**;

BEAT THE INTEGRALITY GAP

- ▶ Obtain a partial solution via **rounding**;
- ▶ Complement the solution by **combinatorial construction**.

BEAT THE INTEGRALITY GAP

- ▶ Obtain a partial solution via **rounding**;
- ▶ Complement the solution by **combinatorial construction**.



BEAT THE INTEGRALITY GAP

- ▶ Obtain a partial solution via **rounding**;
- ▶ Complement the solution by **combinatorial construction**.

Let $\{z_j^*\}_{j \in [L]}$ be an optimal solution of the LP. Let $\beta > 0$ be a parameter.

BEAT THE INTEGRALITY GAP

- ▶ Obtain a partial solution via **rounding**;
- ▶ Complement the solution by **combinatorial construction**.

Let $\{z_j^*\}_{j \in [L]}$ be an optimal solution of the LP. Let $\beta > 0$ be a parameter.

1. Let $L_1 \triangleq \{j \in L : z_j^* \geq \beta\}$.

BEAT THE INTEGRALITY GAP

- ▶ Obtain a partial solution via **rounding**;
- ▶ Complement the solution by **combinatorial construction**.

Let $\{z_j^*\}_{j \in [L]}$ be an optimal solution of the LP. Let $\beta > 0$ be a parameter.

1. Let $L_1 \triangleq \{j \in L : z_j^* \geq \beta\}$.
2. Let G' be the graph obtained from G by removing edges with label in L_1 .

BEAT THE INTEGRALITY GAP

- ▶ Obtain a partial solution via **rounding**;
- ▶ Complement the solution by **combinatorial construction**.

Let $\{z_j^*\}_{j \in [L]}$ be an optimal solution of the LP. Let $\beta > 0$ be a parameter.

1. Let $L_1 \triangleq \{j \in L : z_j^* \geq \beta\}$.
2. Let G' be the graph obtained from G by removing edges with label in L_1 .
3. Let F be the minimum s - t cut of G' , L_2 be the labels of edges in F .

BEAT THE INTEGRALITY GAP

- ▶ Obtain a partial solution via **rounding**;
- ▶ Complement the solution by **combinatorial construction**.

Let $\{z_j^*\}_{j \in [L]}$ be an optimal solution of the LP. Let $\beta > 0$ be a parameter.

1. Let $L_1 \triangleq \{j \in L : z_j^* \geq \beta\}$.
2. Let G' be the graph obtained from G by removing edges with label in L_1 .
3. Let F be the minimum s - t cut of G' , L_2 be the labels of edges in F .
4. Return $L_1 \cup L_2$.

BOUNDING L_1 AND L_2

BOUNDING L_1 AND L_2

It is clear that

$$|L_1| \leq \sum_{j \in [L]} \frac{1}{\beta} \cdot z_j^* = \frac{1}{\beta} \cdot \mathbf{OPT}(LP) \leq \frac{1}{\beta} \cdot \mathbf{OPT}.$$

BOUNDING L_1 AND L_2

It is clear that

$$|L_1| \leq \sum_{j \in [L]} \frac{1}{\beta} \cdot z_j^* = \frac{1}{\beta} \cdot \mathbf{OPT}(LP) \leq \frac{1}{\beta} \cdot \mathbf{OPT}.$$

On the otherhand, there cannot be too many **edge disjoint** paths between s and t in G' :

BOUNDING L_1 AND L_2

It is clear that

$$|L_1| \leq \sum_{j \in [L]} \frac{1}{\beta} \cdot z_j^* = \frac{1}{\beta} \cdot \mathbf{OPT}(LP) \leq \frac{1}{\beta} \cdot \mathbf{OPT}.$$

On the otherhand, there cannot be too many **edge disjoint** paths between s and t in G' :

- ▶ at least $\frac{1}{\beta}$ edges on each s - t path;
- ▶ at most $\frac{m - |L_1|}{1/\beta} = \beta(m - |L_1|)$ such paths;
- ▶ therefore $|L_2| \leq |F| \leq \beta(m - |L_1|)$ (**Menger's theorem**).

THE CHOICE OF β

THE CHOICE OF β

We already have

$$|L_1| + |L_2| \leq \frac{1}{\beta} \cdot \mathbf{OPT} + \beta(m - |L_1|) \leq \frac{1}{\beta} \cdot \mathbf{OPT} + \beta m.$$

Setting $\beta = \sqrt{\frac{\mathbf{OPT}}{m}}$ yields an $O\left(m^{\frac{1}{2}}\right)$ approximation.

THE CHOICE OF β

We already have

$$|L_1| + |L_2| \leq \frac{1}{\beta} \cdot \mathbf{OPT} + \beta(m - |L_1|) \leq \frac{1}{\beta} \cdot \mathbf{OPT} + \beta m.$$

Setting $\beta = \sqrt{\frac{\mathbf{OPT}}{m}}$ yields an $O\left(m^{\frac{1}{2}}\right)$ approximation.

Remark

Instead of using Menger's theorem, we can find a small cut by BFS from s .

THE CHOICE OF β

We already have

$$|L_1| + |L_2| \leq \frac{1}{\beta} \cdot \mathbf{OPT} + \beta(m - |L_1|) \leq \frac{1}{\beta} \cdot \mathbf{OPT} + \beta m.$$

Setting $\beta = \sqrt{\frac{\mathbf{OPT}}{m}}$ yields an $O\left(m^{\frac{1}{2}}\right)$ approximation.

Remark

Instead of using Menger's theorem, we can find a small cut by BFS from s .

Exercise. Find an $O\left(n^{\frac{2}{3}}\right)$ -approx algorithm via **rounding** + **BFS**.

Advanced Algorithms (III)

Chihao Zhang

Shanghai Jiao Tong University

Mar. 11, 2019

MaxCut

MAXCUT

MAXCUT

Input: An undirected graph $G = (V, E)$.

Problem: A set $S \subseteq V$ that maximizes $|E(S, \bar{S})|$.

MAXCUT

MAXCUT

Input: An undirected graph $G = (V, E)$.

Problem: A set $S \subseteq V$ that maximizes $|E(S, \bar{S})|$.

NP-hard

MAXCUT

MAXCUT

Input: An undirected graph $G = (V, E)$.

Problem: A set $S \subseteq V$ that maximizes $|E(S, \bar{S})|$.

NP-hard

Similar to MAX2SAT, **tossing a fair coin** yields an $\frac{1}{2}$ -approximation.
(**Exercise**)

MAXCUT

MAXCUT

Input: An undirected graph $G = (V, E)$.

Problem: A set $S \subseteq V$ that maximizes $|E(S, \bar{S})|$.

NP-hard

Similar to MAX2SAT, **tossing a fair coin** yields an $\frac{1}{2}$ -approximation.
(**Exercise**)

Can we find clever coins via LP relaxation...?

LP FOR MAXCUT

LP FOR MAXCUT

- ▶ introduce a variable $x_u \in \{0, 1\}$ for every $u \in V$.

LP FOR MAXCUT

- ▶ introduce a variable $x_u \in \{0, 1\}$ for every $u \in V$.
- ▶ introduce a variable $y_{u,v} \in \{0, 1\}$ for every edge $e = \{u, v\}$.

LP FOR MAXCUT

- ▶ introduce a variable $x_u \in \{0, 1\}$ for every $u \in V$.
- ▶ introduce a variable $y_{u,v} \in \{0, 1\}$ for every edge $e = \{u, v\}$.

The cost function is $\sum_{e=\{u,v\} \in E} y_{u,v}$.

LP FOR MAXCUT

- ▶ introduce a variable $x_u \in \{0, 1\}$ for every $u \in V$.
- ▶ introduce a variable $y_{u,v} \in \{0, 1\}$ for every edge $e = \{u, v\}$.

The cost function is $\sum_{e=\{u,v\} \in E} y_{u,v}$.

How to write **linear constraints** for a **cut**?

LP FOR MAXCUT

- ▶ introduce a variable $x_u \in \{0, 1\}$ for every $u \in V$.
- ▶ introduce a variable $y_{u,v} \in \{0, 1\}$ for every edge $e = \{u, v\}$.

The cost function is $\sum_{e=\{u,v\} \in E} y_{u,v}$.

How to write **linear constraints** for a **cut**?

idea: Let $F = \{\{u, v\} \in E : y_{u,v} = 1\}$, we view (S, \bar{S}, F) as a **bipartite** subgraph of G .

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.
- ▶ introduce constraints for being bipartite graph metric.

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.
- ▶ introduce constraints for being bipartite graph metric.
- ▶ introduce constraints to rule out odd cycles.

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.
- ▶ introduce constraints for being **bipartite graph metric**.
- ▶ introduce constraints to rule out **odd cycles**.

$$\max \sum_{\{u,v\} \in E} y_{u,v}$$

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.
- ▶ introduce constraints for being **bipartite graph metric**.
- ▶ introduce constraints to rule out **odd cycles**.

$$\begin{aligned} \max \quad & \sum_{\{u,v\} \in E} y_{u,v} \\ \text{s.t.} \quad & y_{u,v} \leq y_{u,w} + y_{w,v}, \quad \forall u, v, w \in V \end{aligned}$$

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.
- ▶ introduce constraints for being **bipartite graph metric**.
- ▶ introduce constraints to rule out **odd cycles**.

$$\begin{aligned}
 \max \quad & \sum_{\{u,v\} \in E} y_{u,v} \\
 \text{s.t.} \quad & y_{u,v} \leq y_{u,w} + y_{w,v}, \quad \forall u, v, w \in V \\
 & \sum_{e=\{u,v\} \in C} y_{u,v} \leq |C| - 1, \quad \forall \text{ odd cycle } C
 \end{aligned}$$

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.
- ▶ introduce constraints for being **bipartite graph metric**.
- ▶ introduce constraints to rule out **odd cycles**.

$$\begin{aligned}
 \max \quad & \sum_{\{u,v\} \in E} y_{u,v} \\
 \text{s.t.} \quad & y_{u,v} \leq y_{u,w} + y_{w,v}, \quad \forall u, v, w \in V \\
 & y_{u,v} + y_{u,w} + y_{w,v} \leq 2, \quad \forall u, v, w \in V
 \end{aligned}$$

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.
- ▶ introduce constraints for being **bipartite graph metric**.
- ▶ introduce constraints to rule out **odd cycles**.

$$\begin{aligned}
 \max \quad & \sum_{\{u,v\} \in E} y_{u,v} \\
 \text{s.t.} \quad & y_{u,v} \leq y_{u,w} + y_{w,v}, \quad \forall u, v, w \in V \\
 & y_{u,v} + y_{u,w} + y_{w,v} \leq 2, \quad \forall u, v, w \in V \\
 & y_{u,v} = y_{v,u}, \quad \forall u, v \in V
 \end{aligned}$$

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.
- ▶ introduce constraints for being **bipartite graph metric**.
- ▶ introduce constraints to rule out **odd cycles**.

$$\begin{aligned}
 \max \quad & \sum_{\{u,v\} \in E} y_{u,v} \\
 \text{s.t.} \quad & y_{u,v} \leq y_{u,w} + y_{w,v}, \quad \forall u, v, w \in V \\
 & y_{u,v} + y_{u,w} + y_{w,v} \leq 2, \quad \forall u, v, w \in V \\
 & y_{u,v} = y_{v,u}, \quad \forall u, v \in V \\
 & y_{u,v} \in \{0, 1\}, \quad \forall u, v \in V
 \end{aligned}$$

- ▶ introduce $y_{u,v}$ and $y_{v,u}$ for every $\{u, v\} \in \binom{V}{2}$.
- ▶ introduce constraints for being **bipartite graph metric**.
- ▶ introduce constraints to rule out **odd cycles**.

$$\begin{aligned}
 \max \quad & \sum_{\{u,v\} \in E} y_{u,v} \\
 \text{s.t.} \quad & y_{u,v} \leq y_{u,w} + y_{w,v}, \quad \forall u, v, w \in V \\
 & y_{u,v} + y_{u,w} + y_{w,v} \leq 2, \quad \forall u, v, w \in V \\
 & y_{u,v} = y_{v,u}, \quad \forall u, v \in V \\
 & y_{u,v} \in [0, 1], \quad \forall u, v \in V
 \end{aligned}$$

INTERALITY GAP

INTERALITY GAP

Theorem

For every $\varepsilon > 0$, there exists a graph G such that

$$\frac{LP(G)}{\text{MAXCUT}(G)} \geq 2 - \varepsilon$$

INTENSITY GAP

Theorem

For every $\varepsilon > 0$, there exists a graph G such that

$$\frac{LP(G)}{\text{MAXCUT}(G)} \geq 2 - \varepsilon$$

Random graph $\mathcal{G}(n, p)$ for proper p ...

LP IN MATRIX FORM

LP IN MATRIX FORM

$$\begin{array}{ll}\max & 2x - 3y \\ \text{s.t.} & x + y \leq 2 \\ & 3x - y \leq 1 \\ & x \geq 0 \\ & y \geq 0\end{array}$$

LP IN MATRIX FORM

$$\begin{array}{ll}\max & 2x - 3y \\ \text{s.t.} & x + y \leq 2 \\ & 3x - y \leq 1 \\ & x \geq 0 \\ & y \geq 0\end{array}$$

$$\begin{array}{ll}\max & \begin{bmatrix} 2 & 0 \\ 0 & -3 \end{bmatrix} \bullet \begin{bmatrix} x & 0 \\ 0 & -y \end{bmatrix} \\ \text{s.t.} & \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} x & 0 \\ 0 & y \end{bmatrix} \leq 2 \\ & \begin{bmatrix} 3 & 0 \\ 0 & -1 \end{bmatrix} \bullet \begin{bmatrix} x & 0 \\ 0 & y \end{bmatrix} \leq 1 \\ & \begin{bmatrix} x & 0 \\ 0 & y \end{bmatrix} \succeq 0\end{array}$$

LP IN MATRIX FORM

$$\begin{array}{ll}\max & 2x - 3y \\ \text{s.t.} & x + y \leq 2 \\ & 3x - y \leq 1 \\ & x \geq 0 \\ & y \geq 0\end{array}$$

$$\begin{array}{ll}\max & \begin{bmatrix} 2 & 0 \\ 0 & -3 \end{bmatrix} \bullet \begin{bmatrix} x & 0 \\ 0 & -y \end{bmatrix} \\ \text{s.t.} & \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} x & 0 \\ 0 & y \end{bmatrix} \leq 2 \\ & \begin{bmatrix} 3 & 0 \\ 0 & -1 \end{bmatrix} \bullet \begin{bmatrix} x & 0 \\ 0 & y \end{bmatrix} \leq 1 \\ & \begin{bmatrix} x & 0 \\ 0 & y \end{bmatrix} \succeq 0\end{array}$$

Hadamard Product

$$A \bullet B \triangleq \sum_{1 \leq i, j \leq n} a_{ij} \cdot b_{ij}.$$

POSITIVE SEMI-DEFINITE MATRIX

Definition

An $n \times n$ symmetric matrix A is positive semi-definite if $x^T A x \geq 0$ for every vector x . We write it as

$$A \geq 0.$$

POSITIVE SEMI-DEFINITE MATRIX

Definition

An $n \times n$ symmetric matrix A is positive semi-definite if $x^T A x \geq 0$ for every vector x . We write it as

$$A \geq 0.$$

Linear Programming

$$\begin{aligned} \max \quad & c^T x \\ \text{s.t.} \quad & a_i^T x \leq b_i, \quad \forall i \in [m] \\ & x_j \geq 0, \quad \forall j \in [n] \end{aligned}$$

POSITIVE SEMI-DEFINITE MATRIX

Definition

An $n \times n$ symmetric matrix A is positive semi-definite if $x^T A x \geq 0$ for every vector x . We write it as

$$A \geq 0.$$

Linear Programming

$$\begin{aligned} \max \quad & c^T x \\ \text{s.t.} \quad & a_i^T x \leq b_i, \quad \forall i \in [m] \\ & x_j \geq 0, \quad \forall j \in [n] \end{aligned}$$

PSD Programming

$$\begin{aligned} \max \quad & C \bullet X \\ \text{s.t.} \quad & A_i \bullet X \leq b_i, \quad \forall i \in [m] \\ & X \geq 0 \end{aligned}$$

PROPERTY OF PSD MATRIX

PROPERTY OF PSD MATRIX

Theorem

For an $n \times n$ symmetric matrix, the followings are equivalent

1. $A \geq 0$;
2. A has n non-negative eigenvalues;
3. $A = V^T V$ for some $n \times n$ matrix $V = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \dots \quad \mathbf{v}_n]$.

PROPERTY OF PSD MATRIX

Theorem

For an $n \times n$ symmetric matrix, the followings are equivalent

1. $A \geq 0$;
2. A has n non-negative eigenvalues;
3. $A = V^T V$ for some $n \times n$ matrix $V = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \dots \quad \mathbf{v}_n]$.

We now prove the theorem using spectral theorem for symmetric matrices.

VECTOR PROGRAMMING

VECTOR PROGRAMMING

If we write $X = V^T V$ for some $V = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \dots \quad \mathbf{v}_n]$, then

PSD Programming

$$\begin{aligned} \max \quad & C \bullet X \\ \text{s.t.} \quad & A_k \bullet X \leq b_k, \quad \forall k \in [m] \\ & X \succeq 0 \end{aligned}$$

Vector Programming

$$\begin{aligned} \max \quad & \sum_{1 \leq i, j \leq n} c(i, j) \cdot \mathbf{v}_i^T \mathbf{v}_j \\ \text{s.t.} \quad & \sum_{1 \leq i, j \leq n} a_k(i, j) \cdot \mathbf{v}_i^T \mathbf{v}_j \leq b_k, \quad \forall k \in [m] \\ & \mathbf{v}_i \in \mathbb{R}^n, \quad \forall i \in [n] \end{aligned}$$

BACK TO MAXCUT

BACK TO MAXCUT

It is easy to model MAXCUT as the following **quadratic programming**.

BACK TO MAXCUT

It is easy to model MAXCUT as the following **quadratic programming**.

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{e=\{u,v\} \in E} (1 - x_u x_v) \\ \text{s.t.} \quad & x_u \in \{-1, 1\}, \quad \forall u \in V \end{aligned}$$

BACK TO MAXCUT

It is easy to model MAXCUT as the following **quadratic programming**.

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{e=\{u,v\} \in E} (1 - x_u x_v) \\ \text{s.t.} \quad & x_u \in \{-1, 1\}, \quad \forall u \in V \end{aligned}$$

We relax it to a **vector programming**, which is equivalent to an **SDP**.

BACK TO MAXCUT

It is easy to model MAXCUT as the following **quadratic programming**.

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{e=\{u,v\} \in E} (1 - x_u x_v) \\ \text{s.t.} \quad & x_u \in \{-1, 1\}, \quad \forall u \in V \end{aligned}$$

We relax it to a **vector programming**, which is equivalent to an **SDP**.

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{e=\{u,v\} \in E} (1 - \mathbf{w}_u^T \mathbf{w}_v) \\ \text{s.t.} \quad & \mathbf{w}_u \in \mathbb{R}^n, \quad \forall u \in V \\ & \|\mathbf{w}_u\|_2 = 1, \quad \forall u \in V \end{aligned}$$

BACK TO MAXCUT

It is easy to model MAXCUT as the following **quadratic programming**.

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{e=\{u,v\} \in E} (1 - x_u x_v) \\ \text{s.t.} \quad & x_u \in \{-1, 1\}, \quad \forall u \in V \end{aligned}$$

We relax it to a **vector programming**, which is equivalent to an **SDP**.

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{e=\{u,v\} \in E} (1 - \mathbf{w}_u^T \mathbf{w}_v) \\ \text{s.t.} \quad & \mathbf{w}_u \in \mathbb{R}^n, \quad \forall u \in V \\ & \|\mathbf{w}_u\|_2 = 1, \quad \forall u \in V \end{aligned}$$

ROUNDING

Let $\{\mathbf{w}_u\}$ be an optimal solution of the SDP.

ROUNDING

Let $\{\mathbf{w}_u\}$ be an optimal solution of the SDP.

Choose a **random hyperplane** to divide the vectors into two classes...

ROUNDING

Let $\{\mathbf{w}_u\}$ be an optimal solution of the SDP.

Choose a **random hyperplane** to divide the vectors into two classes...

Next week: How to implement the rounding? How to analyze the performance?

Advanced Algorithms (IV)

Chihao Zhang

Shanghai Jiao Tong University

Mar. 18, 2019

REVIEW

REVIEW

MAXCUT

Input: An undirected graph $G = (V, E)$.

Problem: A set $S \subseteq V$ that maximizes $|E(S, \bar{S})|$.

REVIEW

MAXCUT

Input: An undirected graph $G = (V, E)$.

Problem: A set $S \subseteq V$ that maximizes $|E(S, \bar{S})|$.

Integer Program

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{e=\{u,v\} \in E} (1 - x_u x_v) \\ \text{s.t.} \quad & x_u \in \{-1, 1\}, \quad \forall u \in V \end{aligned}$$

REVIEW

MAXCUT

Input: An undirected graph $G = (V, E)$.

Problem: A set $S \subseteq V$ that maximizes $|E(S, \bar{S})|$.

Integer Program

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{e=\{u,v\} \in E} (1 - x_u x_v) \\ \text{s.t.} \quad & x_u \in \{-1, 1\}, \quad \forall u \in V \end{aligned}$$

Vector Program

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{e=\{u,v\} \in E} (1 - \mathbf{w}_u^T \mathbf{w}_v) \\ \text{s.t.} \quad & \mathbf{w}_u \in \mathbb{R}^n, \quad \forall u \in V \\ & \mathbf{w}_u^T \mathbf{w}_u = 1, \quad \forall u \in V \end{aligned}$$

$$\begin{aligned}
& \max \quad \frac{1}{2} \sum_{e=\{u,v\} \in E} \left(1 - \mathbf{w}_u^T \mathbf{w}_v \right) \\
& \text{s.t.} \quad \mathbf{w}_u \in \mathbb{R}^n, \quad \forall u \in V \\
& \quad \mathbf{w}_u^T \mathbf{w}_u = 1, \quad \forall u \in V
\end{aligned}$$

is equivalent to a **positive semi-definite programming** (solvable in polynomial-time)

$$\begin{aligned}
& \max \quad \frac{1}{2} \sum_{e=\{u,v\} \in E} \left(1 - \mathbf{w}_u^T \mathbf{w}_v\right) \\
& \text{s.t.} \quad \mathbf{w}_u \in \mathbb{R}^n, \quad \forall u \in V \\
& \quad \mathbf{w}_u^T \mathbf{w}_u = 1, \quad \forall u \in V
\end{aligned}$$

is equivalent to a **positive semi-definite programming** (solvable in polynomial-time)

Let $\{\widehat{\mathbf{w}}_v\}_{v \in V}$ be an optimal solution.

$$\begin{aligned}
& \max \quad \frac{1}{2} \sum_{e=\{u,v\} \in E} \left(1 - \mathbf{w}_u^T \mathbf{w}_v\right) \\
& \text{s.t.} \quad \mathbf{w}_u \in \mathbb{R}^n, \quad \forall u \in V \\
& \quad \mathbf{w}_u^T \mathbf{w}_u = 1, \quad \forall u \in V
\end{aligned}$$

is equivalent to a **positive semi-definite programming** (solvable in polynomial-time)

Let $\{\widehat{\mathbf{w}}_v\}_{v \in V}$ be an optimal solution.

Task: Round $\{\widehat{\mathbf{w}}_v\}_{v \in V}$ to a cut

GOEMANS–WILLIAMSON ROUNDING

GOEMANS–WILLIAMSON ROUNDING

1. Pick a random hyperplane crossing the origin;
2. The plane separates V into two sets.

GOEMANS–WILLIAMSON ROUNDING

1. Pick a random hyperplane crossing the origin;
2. The plane separates V into two sets.

Implementation

1. Choose a vector $\mathbf{r} = (r_1, \dots, r_n)$ where each $r_i \sim \mathcal{N}(0, 1)$ i.i.d.
2. Let $S \triangleq \{u \in V : \mathbf{r}^T \widehat{\mathbf{w}}_u \geq 0\}$.

ANALYSIS

ANALYSIS

Proposition

$\frac{\mathbf{r}}{\|\mathbf{r}\|}$ is a point on S^{n-1} uniformly at random.

ANALYSIS

Proposition

$\frac{\mathbf{r}}{\|\mathbf{r}\|}$ is a point on S^{n-1} uniformly at random.

Proposition

An edge $\{u, v\} \in E$ is separated with probability $\frac{1}{\pi} \arccos(\widehat{\mathbf{w}}_u^T \widehat{\mathbf{w}}_v)$.

ANALYSIS

Proposition

$\frac{\mathbf{r}}{\|\mathbf{r}\|}$ is a point on S^{n-1} **uniformly at random**.

Proposition

An edge $\{u, v\} \in E$ is separated with probability $\frac{1}{\pi} \arccos(\widehat{\mathbf{w}}_u^T \widehat{\mathbf{w}}_v)$.

Proposition

Random hyperplane rounding is a **0.878**-approximation of MAXCUT .

QUADRATIC PROGRAM

QUADRATIC PROGRAM

We try to apply Goemans–Williamson rounding to general quadratic programs.

QUADRATIC PROGRAM

We try to apply Goemans–Williamson rounding to general quadratic programs.

Quadratic Program

$$\begin{aligned} \max \quad & \sum_{1 \leq i, j \leq n} a_{i,j} x_i x_j \\ \text{s.t.} \quad & x_i \in \{-1, +1\}, \quad i = 1, \dots, n. \end{aligned}$$

QUADRATIC PROGRAM

We try to apply Goemans–Williamson rounding to general quadratic programs.

Quadratic Program

$$\begin{aligned} \max \quad & \sum_{1 \leq i, j \leq n} a_{i,j} x_i x_j \\ \text{s.t.} \quad & x_i \in \{-1, +1\}, \quad i = 1, \dots, n. \end{aligned}$$

We assume $A = (a_{i,j})_{1 \leq i, j \leq n}$ is **positive semi-definite**.

ROUNDING

We simply follow G-W...

ROUNDING

We simply follow G-W...

Vector Program

$$\begin{aligned} \max \quad & \sum_{1 \leq i, j \leq n} a_{i,j} \mathbf{v}_i^T \mathbf{v}_j \\ \text{s.t.} \quad & \mathbf{v}_i \in \mathbb{R}^n, \quad i = 1, \dots, n. \end{aligned}$$

ROUNDING

We simply follow G-W...

Vector Program

$$\begin{aligned} \max \quad & \sum_{1 \leq i, j \leq n} a_{i,j} \mathbf{v}_i^T \mathbf{v}_j \\ \text{s.t.} \quad & \mathbf{v}_i \in \mathbb{R}^n, \quad i = 1, \dots, n. \end{aligned}$$

1. Compute $\{\widehat{\mathbf{v}}_i\}_{1 \leq i \leq n}$.
2. Pick a vector \mathbf{r} u.a.r on S^{n-1} .
3. $\hat{x}_i = 1$ if $\widehat{\mathbf{v}}_i^T \mathbf{r} \geq 0$; $\hat{x}_i = -1$ otherwise.

ANALYSIS

Proposition

$$\mathbf{E} [\hat{x}_i \hat{x}_j] = \frac{2}{\pi} \arcsin(\hat{v}_i^T \cdot \hat{v}_j).$$

Proposition

$$\mathbf{E} [\hat{x}_i \hat{x}_j] = \frac{2}{\pi} \arcsin(\hat{v}_i^T \cdot \hat{v}_j).$$

Proposition

Random hypergraph rounding is a $\frac{2}{\pi}$ -approximation of QP.

ANALYSIS

Proposition

$$\mathbb{E} [\hat{x}_i \hat{x}_j] = \frac{2}{\pi} \arcsin(\hat{v}_i^T \cdot \hat{v}_j).$$

Proposition

Random hypergraph rounding is a $\frac{2}{\pi}$ -approximation of QP.

Proof.

Use Schur product theorem. □

CORRELATION CLUSTERING

CORRELATION CLUSTERING

- ▶ Given a undirected graph $G = (V, E)$ in which each $e \in E$ has two weights $w_e^+, w_e^- \geq 0$.

CORRELATION CLUSTERING

- ▶ Given a undirected graph $G = (V, E)$ in which each $e \in E$ has two weights $w_e^+, w_e^- \geq 0$.
- ▶ Find a partition $\mathcal{S} = (S_1, \dots, S_k)$ of V .

CORRELATION CLUSTERING

- ▶ Given a undirected graph $G = (V, E)$ in which each $e \in E$ has two weights $w_e^+, w_e^- \geq 0$.
- ▶ Find a partition $\mathcal{S} = (S_1, \dots, S_k)$ of V .
- ▶ $E^+(\mathcal{S}) \triangleq$ edge in a cluster; $E^-(\mathcal{S}) \triangleq$ edges between clusters.

CORRELATION CLUSTERING

- ▶ Given a undirected graph $G = (V, E)$ in which each $e \in E$ has two weights $w_e^+, w_e^- \geq 0$.
- ▶ Find a partition $\mathcal{S} = (S_1, \dots, S_k)$ of V .
- ▶ $E^+(\mathcal{S}) \triangleq$ edge in a cluster; $E^-(\mathcal{S}) \triangleq$ edges between clusters.
- ▶ The goal is to maximize

$$\sum_{e \in E^+(\mathcal{S})} w_e^+ + \sum_{e \in E^-(\mathcal{S})} w_e^-.$$

VECTOR PROGRAM

VECTOR PROGRAM

For $1 \leq k \leq n$, let e_k be the k -th unit vector.

VECTOR PROGRAM

For $1 \leq k \leq n$, let e_k be the k -th unit vector.

$$\begin{aligned} \max \quad & \sum_{\{u,v\} \in E} \left(w_{u,v}^+ (x_u^T x_v) + w_{u,v}^- (1 - x_u^T x_v) \right) \\ \text{s.t.} \quad & x_u \in \{e_1, \dots, e_n\}, \quad \forall u \in V. \end{aligned}$$

VECTOR PROGRAM

For $1 \leq k \leq n$, let e_k be the k -th unit vector.

$$\begin{aligned} \max \quad & \sum_{\{u,v\} \in E} \left(w_{u,v}^+ (x_u^T x_v) + w_{u,v}^- (1 - x_u^T x_v) \right) \\ \text{s.t.} \quad & x_u \in \{e_1, \dots, e_n\}, \quad \forall u \in V. \end{aligned}$$

Relaxation

$$\begin{aligned} \max \quad & \sum_{\{u,v\} \in E} \left(w_{u,v}^+ (x_u^T x_v) + w_{u,v}^- (1 - x_u^T x_v) \right) \\ \text{s.t.} \quad & x_v^T x_v = 1, \quad \forall v \in V, \\ & x_u^T x_v \geq 0, \quad \forall u, v \in V, \\ & x_u \in \mathbb{R}^n, \quad \forall u \in V. \end{aligned}$$

ROUNDING

ROUNDING

Follow G-W and choose **two** hyperplanes..

ROUNDING

Follow G-W and choose **two** hyperplanes..

We always obtain **at most four** clusters.

ROUNDING

Follow G-W and choose **two** hyperplanes..

We always obtain **at most four** clusters.

Proposition

Two random hyperplane rounding is a $\frac{3}{4}$ -approximation for correlation clustering.