# Strategic Programming

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Recursive functions are known to be suited to express computations on recursive data types, such as lists and trees. For example, we can define in Haskell the algebraic data type *Tree* modeling a binary tree where integer values are stored in its leaf nodes,

```
\begin{array}{c} \mathbf{data} \ \mathit{Tree} = \mathit{Leaf} \, \mathit{Int} \\ \mid \ \mathit{Fork} \ \mathit{Tree} \ \mathit{Tree} \end{array}
```

and straightforwardly implement a recursive function that computes its minimum value:

```
treemin :: Tree \rightarrow Int
treemin (Leaf i) = i
treemin (Fork l r) = min (treemin l) (treemin r)
```

The use of algebraic data types and pattern matching makes the program concise, and easy to understand and manipulate.

When we consider bigger data types, however, we lose this conciseness and elegance! Let us consider the (sub)language of **let** expressions as incorporated in most functional languages, including Haskell. Next, we show two examples of programs in the **let** language, which corresponds to correct *Haskell* code.

We can easily define the abstract (syntactic) structure of  $\mathbf{let}$  expressions by the following heterogeneous data type  $\mathbf{Let}$ .

```
 \begin{aligned} \mathbf{data} \ Let &= Let \ List \ Exp \\ \mathbf{data} \ List &= Assign \quad String \ Exp \ List \\ &\mid Nested Let \ String \ Let \ List \\ &\mid Empty List \end{aligned}   \begin{aligned} \mathbf{data} \ Exp &= Add \quad Exp \ Exp \\ &\mid Mul \quad Exp \ Exp \\ &\mid Neg \quad Exp \\ &\mid Const \ Int \\ &\mid Var \quad String \end{aligned}
```

Let us consider that we wish to *optimize* this Haskell fragment by eliminating addition with 0. Obviously, can define a recursive function that performs the desired transformation.

```
optimize :: Let \rightarrow Let
optimize (Let \ l \ e) = Let (optimizeList \ l) (optimizeExp \ e)
optimizeList :: List \rightarrow List
optimizeList (Assign s e l)
                                 = Assign \ s \ (optimizeExp \ e) \ (optimizeList \ l)
optimizeList\ (NestedLet\ s\ l\ ls) = NestedLet\ s\ (optimize\ l)\ (optimizeList\ l)
optimizeList EmptyList
                                 = EmptyList
optimizeExp :: Exp \rightarrow Exp
optimizeExp (Add e (Const 0)) = e
optimizeExp (Add (Const 0) e) = e
optimizeExp (Add e1 e2)
                                 = Add (optimizeExp \ e1) (optimizeExp \ e2)
optimizeExp (Mul e1 e2)
                                 = Mul (optimizeExp \ e1) (optimizeExp \ e2)
optimizeExp(Neg e)
                                 = Neg (optimizeExp e)
optimizeExp (Const i)
                                 = Const i
optimizeExp(Vars)
                                 = Var s
```

Looking in detail to this definition we see that only in two alternative definitions of function optimize Exp the function does useful work: it applies the arithmetic expression rule. All other alternatives contain boring code, just expressing the recursion on Let trees. In fact, our optimization is defined by three functions - optimize, optimizeList, and optimizeExp - expressed on eleven alternative definitions. This number of definitions correspond to the three data types that contain nine constructors: The additional two alternatives are the ones where interesting work is being done.

In this example, we have considered a tiny subset of the Haskell language: **let** expressions. Things get much more complex when we consider large scale language transformations. Let us consider that we wish to perform the above optimization in full Haskell code. The algebraic data type defining the abstract syntax of Haskell<sup>1</sup> contains 116 constructors across 30 data types. As a consequence, performing such a simple transformation would (probably) require the definition of 30 functions containing more than one hundred *boring* alternatives!

Obviously, we should **not write** such complex and large recursive functions. Thus, we need a different programming abstraction to express large scale language transformations. In this context, strategic term rewriting is an extremely suitable formalism [1, 2], since it provides a solution that just defines the work to be done in the constructors (tree nodes) of interest, and "ignores" all the others. The key idea underlying strategic programming is the separation of problem-specific ingredients of traversal functionality (i.e., type specific basic actions) and reusable traversal schemes (i.e., traversal control).

<sup>&</sup>lt;sup>1</sup> available in the Haskell library https://hackage.haskell.org/package/haskell-src-1.0.4/docs/Language-Haskell-Syntax.html

Let us return to our **let** optimization problem. In the style of strategic programming we define we a constructor/node specific rewriting function expressing the desired transformation/optimization:

```
expr :: Exp \rightarrow Exp

expr (Add \ e \ (Const \ 0)) = e

expr \ (Add \ (Const \ 0) \ e) = e

expr \ e

expr \ e
```

where the first two alternatives define the optimization: when either of the sub-expressions of an Add expression is the constant 0, then it returns the other sub-expression. The last alternative defines the default behavior for all other cases, returning the original expression.

Having defined the type specific transformation, we use *strategic functions* to apply it while traversing the tree according to a recursion scheme (*i.e.*, a strategy). Next, we show how we express it in strategic programming:  $^2$  the *apply* function, applies the strategy  $full\_td$  that performs a  $full\_top\_down$  traversal on the input tree t. Thus, the worker function expr is applied to tree nodes in a full top down traversal scheme.

```
optimize \ t = apply \ (full\_td \ expr) \ t
```

In this particular case we used a full top down traversal scheme. Strategic programming, however, offer many of typical traversal schemes such as full bottom up, once bottom up, innermost, etc.

As we can see in the strategic solution of *optimize*, in strategic programming our solutions focus on the nodes/constructors where work needs to be performed, while omitting the nodes/constructors where no work needs to be performed. As result, strategic programming provides concise and elegant solutions to express large scale language engineering tasks.

To define generic strategies we need a generic mechanism to traverse and transform trees. Next, we introduce the zipper data structure that offers a generic mechanism to navigate on tree data structures and perform generic tree transformations. After that we show how to express strategic programming via Zippers. Then, we show the use of the developed Ztrategic library in practice, by giving examples of the use of most of its strategies.

#### 1 Functional Zippers

Zippers were originally conceived by Huet [3] to represent a tree together with a subtree that is the focus of attention. During a computation, the focus may move left, up, down or right within the tree. Generic manipulation of a zipper is provided through a set of predefined functions that allow access to all of the nodes of the tree for inspection or modification.

<sup>&</sup>lt;sup>2</sup> We omit here some details of this definition. They will be defined and explained in the remainder of this text.

In order to illustrate the use of zippers, let us again consider again the binary leaf-tree Tree data type. Next, we define a tree  $t_1$  of this type:

```
t_1 :: Tree
t_1 = Fork (Leaf 3)
(Fork (Leaf 2)
(Leaf 4))
```

When we consider  $t_1$  as a whole, we notice that each of the subtrees occupies a certain location in tree. In fact, a location of a subtree may be represented by the subtree itself and by the rest of the tree. Thus, the rest of the tree can be viewed as the context of that subtree.

One of the possible ways to represent this context is as a path from the top of the tree to the node which is the focus of attention (where the subtree has its root). This means that it is possible to use contexts and subtrees to define any position in the tree, while creating a setting where navigation is provided by the contextual information of a path applied to a tree.

For example, if we wish to put the focus in Leaf 2, its context in tree  $t_1$  is:

```
tree = Fork (Leaf 3) 
(Fork \otimes 
(Leaf 4))
```

where  $\otimes$  points the exact location where Leaf 4 occurs. One possible way to represent this context consists in defining a path from the top of the tree to the position which is the focus of attention. To reach Leaf 2 in tree  $t_1$ , we need to go right (down the right branch) and then left (down the left one). In practice, this means that given the tree  $t_1$ , then the path [right, left] would suffice in indicating the location in the tree we want to focus our attention on.

This is precisely the main concept behind zippers. Using the idea of having pairs of information composed by paths and trees, we may represent any positions in a tree and, better yet, this setting allows an easy navigation as we only have to remove parts of the path if we want to go to the top of the tree, or add information if we want to go further down.

Using this idea, we may represent contexts as instances of the following data-type:

A value  $L\ c\ t$  represents the left part of a branch of which the right part is t and whose parent has context c. Similarly, a value  $R\ t\ c$  represents the right part of a branch of which the left part is t and whose parent has context c. The value Top represents the top of the tree. Returning to our example, we may represent the context of  $Leaf\ 2$  in the tree as:

```
context :: Cxt \ Tree

context = L \ (R \ (Leaf \ 3) \ Top) \ (Leaf \ 4)
```

which is the same as saying that the focus results from going to the left in a subtree whose right side is *Leaf* 4. This subtree is obtained from going to the right from the top tree, whose left side is *Leaf* 3.

Having defined the context of a subtree, we may define a location on a tree as one of its subtrees together with its context:

```
type Loc \ a = (a, Cxt \ a)
```

We are now ready to present the definition of useful functions that manipulate locations on binary trees. First, we can define a function that goes down the left branch of a tree:

```
left :: Loc Tree \rightarrow Loc Tree left (Fork l \ r, c) = (l, L \ c \ r)
```

This function takes a tuple with a tree and a context (a Loc) and creates a new tuple, where the left side of the tree becomes the new tree, and a new context is created, extending the previous one with a data constructor L whose right sides becomes the right side of the previous tree. Similarly, we introduce a function that goes down the right branch:

```
right :: Loc \ Tree \rightarrow Loc \ Tree

right \ (Fork \ l \ r, c) = (r, R \ l \ c)
```

Going up in the tree corresponds to removing "directions" from the path. The function *parent* goes up on a tree location:

```
parent :: Loc Tree \rightarrow Loc Tree
parent (t, L \ c \ r) = (Fork \ t \ r, c)
parent (t, R \ l \ c) = (Fork \ l \ t, c)
```

This function has two alternatives: when it gets as argument a location whose context is a left side (L), then it creates a new location where the right side of the context is moved to a new tree and the left side is kept as the context (c). The second alternative does the opposite when the context of the location is a right side (R).

Finally, we define a function zipper that creates a tree location from a tree (where we define an empty context):

```
zipper :: Tree \rightarrow Loc Tree

zipper t = (t, Top)
```

and we also define another function that extracts a tree from a tree location, by simply taking the first element of the location pair:

```
value :: Loc \ Tree \rightarrow Tree
value = fst
```

Having defined a zipper-based function to navigate in binary-trees, we can now focus the attention on subtree Leaf 2 of  $t_1$  as follows:

```
leafWith2 :: Loc Tree

leafWith2 = left (right (zipper t_1))
```

Once the subtree that is the focus of our attention is reached, we may perform several actions on it. One such action would be to edit that subtree: we may want, for example, to decrement its leaf value by one. Using the zipper functions defined so far, this is expressed as follows:

```
edit = let (Leaf v, cxt) = leaf With 2

subtree' = (Leaf (v - 1), cxt)

in value (parent (parent subtree'))
```

with edit producing the result:

```
edited = Fork (Leaf 3)
(Fork (Leaf 1)
(Leaf 4))
```

In conclusion, we have just presented an instance of a zipper for the *Tree* data type, and we showed how to navigate and to express transformations on such trees. In the next section, we present a generic zipper *Haskell* library that offers this functionality to any data type.

# 2 Generic Zippers

Generic zippers are available as a *Haskell* library [4], which works for both homogeneous and heterogeneous data types. In order to show the expressiveness of this library we shall start by navigating in the homogeneous *Tree* data type. After that we will show how generic zippers can navigate in heterogeneous ones.

In order to navigate on tree  $t_1$ , first, the data type needs to be an instance of the Data and Typeable. Any data type that has an instance of the Data and Typeable type classes can be navigated using generic zippers. This is, for example, the case of Haskell pre-defined list data type. In the case of our Tree data type we need to define those instances. Next, we use the deriving primitive to produce them.

```
data Tree = Leaf Int
| Fork Tree Tree
deriving (Data, Typeable)

Now, we use the generic zipper library function to Zipper: Data \ a \Rightarrow a \rightarrow Zipper \ a. to transform a tree into a zipper:
t'_1 = Zipper Tree
t'_1 = to Zipper \ t_1
```

This function produces an aggregate data structure which is easy to traverse and update. For example, we may move the focus of attention on  $t'_1$  from the topmost node to the leaf containing the number 3, as follows:

```
leafWith3 :: Tree

leafWith3 = (fromJust . getHole . fromJust . down') t'_1
```

where the zipper library function

```
down' :: Zipper a \to Maybe (Zipper a)
```

goes down to the leftmost (immediate) child of a node, whereas function

```
getHole :: Typeable\ b \Rightarrow Zipper\ a \rightarrow Maybe\ b
```

extracts the node under focus from a zipper. The library also includes a function down to go to the rightmost (immediate) child of a node, and functions up, left, and right to navigate in the directions their names indicate.

All these functions wrap the result inside a Maybe data type to make them total. To simplify our example we are unwrapping it using the function fromJust.<sup>3</sup> The function leafWith3 navigates from the tree's root via the shortest path to the desired leaf. Next, we navigate to that leaf after visiting all nodes in the tree as expressed by fullVisit in a compositional style. To avoid the use of fromJust and also to obtain a more natural left-to-right writing/reading of the navigation on trees, we can adopt an applicative functional style as expressed by fullVisit', where the predefined  $monadic\ binding\ function\ (\gg=)$  allows the value returned from the first computation to influence the choice of the next one.

```
full Visit' :: Tree
fullVisit :: Tree
fullVisit = (fromJust . getHole .
                                         fullVisit' = fromJust \$ down' t'_1
                                                                ≫ down
            from Just . left
            from Just . up
                                                                ≫ down
            from Just . left
                                                                ≫ left
            from Just . down
                                                                ≫ up
                                                                ≫ left
            from Just . down
            fromJust . down') t'_1
                                                                ≫ getHole
```

Obviously, not all tree paths are valid. Next, we present an unfeasible one:

Generic zippers provide an uniform way to navigate in heterogeneous data structures, without the need of distinguishing which type of nodes it is traversing.

<sup>&</sup>lt;sup>3</sup> Actually, we are not really checking for totality, otherwise we would have to test each function call against a set of possible results.

Let us consider that the *Let* data type has been updated to derive instances of classes *Data* and *Typeable*.

Show example of navigation on let

#### 2.1 Transformations with Zippers

Generic Zippers do not only support navigation on heterogeneous trees (as showed before), but they also support generic transformations. In fact, the zipper library contains functions for the transformation of the data structure being traversed. The function

```
trans :: GenericT \rightarrow \mathsf{Zipper}\ a \rightarrow \mathsf{Zipper}\ a
```

applies a generic transformation to the node the zipper is currently pointing to; while

```
transM :: GenericM \ m \rightarrow \mathsf{Zipper} \ a \rightarrow m \ (\mathsf{Zipper} \ a)
```

applies a generic monadic transformation.

In order to show a zipper-based transformation, let us consider that we wish to increment a constant in a **let** expression. We begin by defining a function incConstant that increments constants, and use the generic function mkT (from the generics library [5]) to generalize this type-specific function to all types:

```
incConstant :: Exp \rightarrow Exp

incConstant (Const \ n) = Const \ (n+1)

incConstantG :: GenericT

incConstantG = mkT \ incConstant
```

This function has type GenericT (meaning GenericTransformation) that is the required type of trans. To transform the assignment c=2 (in p) to c=3 we just have to navigate to the desired constant and then apply trans, as follows<sup>4</sup>:

```
\begin{array}{l} incrC :: Maybe \ (\mathsf{Zipper} \ \underline{Let}) \\ incrC = \mathbf{do} \ t_2 \leftarrow \mathsf{down'} \quad t_1 \\ t_{-3} \leftarrow \mathsf{down'} \ t_2 \\ t_{-4} \leftarrow \mathsf{right} \quad t_{-3} \\ t_{-5} \leftarrow \mathsf{right} \quad t_{-4} \\ t_{-6} \leftarrow \mathsf{down'} \ t_{-5} \\ t_{-7} \leftarrow \mathsf{right} \quad t_{-6} \\ return \ (trans \ incConstantG \ t_{-7}) \end{array}
```

### 3 Zipper-based Strategic Programming

The two key ingredients for expressing strategic term re-writing are: a generic data structure traversal mechanism and a generic data structure transformation

<sup>&</sup>lt;sup>4</sup> Given that *Maybe* is a monad, this time we avoided the repeated use of *fromJust* by writing the code in a monadic style.

mechanism. As we showed in Section 2, generic zippers provide both mechanisms and, thus, they are the key ingredient to express strategic programming as we will show in this Section.

Before we discuss how to model strategies via zippers, let us return to our **let** optimization problem. Next, we present the type specific transformation function where we return a *Maybe* result to express transformations that may fail (that is, do nothing).

```
expr :: Exp \rightarrow Maybe Exp

expr (Add e (Const 0)) = Just e

expr (Add (Const 0) e) = Just e

expr e = Just e
```

This function applies to Exp nodes only. To express our **let** optimization, however, we need a generic mechanism that traverses Let trees, applying this function when visiting Add expressions. This is where strategic term rewriting comes to the rescue: It provides recursion patterns (i.e., strategies) to traverse the (generic) tree, like, for example, top-down or bottom-up traversals. It also includes functions to apply a node specific rewriting function (like expr) according to a given strategy. Next, we show the strategic solution of our optimization where expr is applied to the input tree in a full top-down strategy. This is a Type Preserving (TP) transformation since the input and result trees have the same type:

```
optimize :: Zipper Let \rightarrow Maybe (Zipper Let)
optimize t = applyTP (full\_tdTP step) t
where step = idTP 'adhocTP' expr
```

We have just presented our first (zipper-based) strategic function. Here, step is a transformation to be applied by function applyTP to all nodes of the input tree t (of type Zipper Let) using a full top-down traversal scheme (function full\_tdTP). The rewrite step behaves like the identity function (idTP) by default with our expr function to perform the type-specific transformation, and the adhocTP combinator joining them into a single function. In this solution, we clearly see that the traversal function full\_tdTP needs to navigate heterogeneous trees, as it is the case of Let expressions. Moreover, the traversal functions also need to apply transformations at specific nodes, as it is the case of function expr. Thus, we will rely again on zippers to provide such a generic transformation and tree-walk mechanism to embed strategic programming in Haskell. In fact, our strategic combinators work with zippers as in the definition of optimize.

In the next section we describe how data structure transformations are directly supported by zippers. Then, in Section 3.1 we present in detail the embedding of strategies using the generic zipper mechanism.

#### 3.1 Strategic Programming with Zippers

In this section we introduce Ztrategic, our embedding of strategic programming using generic zippers. The embedding directly follows the work of Laemmel and Visser on the Strafunski library [6, 7]. Before we present the powerful

and reusable strategic functions providing control on tree traversals, such as topdown, bottom-up, innermost, etc., let us show some simple basic combinators that work at the zipper level, and are the building blocks of our embedding.

We start by defining a function that elevates a transformation to the zipper level. In other words, we define how a function that is supposed to operate directly on one data type is converted into a transformation that operates on a zipper.

```
zTryApplyM :: (Typeable \ a, Typeable \ b) \Rightarrow (a \rightarrow Maybe \ b) \rightarrow TP \ c
zTryApplyM \ f = transM \ (join \ . \ cast \ . \ f \ . \ fromJust \ . \ cast)
```

The definition of zTryApplyM relies on transformations on zippers, thus reusing the generic zipper library transM function. To build a valid transformation for the transM function, we use the  $cast::a \rightarrow Maybe\ b$  function, that tries to cast a given data from type a to type b. In this case, we use it to cast the data the zipper is focused on into a type our original transformation f can be applied to. Then, function f is applied, and its result is cast back to its original type. Should any of these casts, or the function f itself, fail, the failure propagates and the resulting zipper transformation will also fail. The use of the monadic version of the zipper generic transformation guarantees the handling of such partiality. It should be noticed that failure can occur in two situations: the type cast fails when the types do not match. Moreover, the function f fails when the function itself dictates that no change is to be applied. Signaling failure in the application of transformations is important for strategies where a transformation is applied once, only.

zTryApplyM returns a TP c, in which TP is a type for specifying Type-Preserving transformations on zippers, and c is the type of the zipper. For example, if we are applying transformations on a zipper built upon the Let data type, then those transformations are of type TP Let.

```
\mathbf{type}\;\mathsf{TP}\;a=\mathsf{Zipper}\;a\to Maybe\;(\mathsf{Zipper}\;a)
```

Very much like Strafunski, we introduce the type  $\mathsf{TU}\ m\ d$  for Type-Unifying operations, which aim to gather data of type d into the data structure m.

```
type TU m \ d = (forall \ a \ . \ Zipper \ a \rightarrow m \ d)
```

For example, to collect in a list all the defined names in a **let** expression, the corresponding type-unifying strategy would be of type TU [] *String*. We will present such a transformation and implement it later in this section.

Next, we define a combinator to compose two transformations, building a more complex zipper transformation that tries to apply each of the initial transformations in sequence, skipping transformations that fail.

```
\mbox{adhocTP} :: Typeable \ a \Rightarrow \mbox{TP} \ e \rightarrow (a \rightarrow Maybe \ a) \rightarrow \mbox{TP} \ e \\ \mbox{adhocTP} \ f \ g \ z = maybeKeep \ f \ (\mbox{zTryApplyM} \ g) \ z
```

The adhocTP function receives transformations f and g as parameters, as well as zipper z. It converts g, which is a simple (i.e. non-zipper) Haskell function, into a zipper transformation, and uses the auxiliary function maybeKeep to try to apply the two transformations to the zipper z, ignoring if it fails.

Next, we use adhocTP, written as an infix operator, which combines the zipper function failTP with our basic transformation *expr* function:

```
step = failTP 'adhocTP' expr
```

Thus, we do not need to express type-specific transformations as functions that work on zippers. It is the use of zTryApplyM in adhocTP that transforms a *Haskell* function (*expr* in this case) into a zipper one, hidden from these definitions.

The function failTP is a pre-defined transformation that always fails and idTP is the identity transformation that always succeeds. They provide the basis for construction of complex transformations through composition. We omit here their simple definitions. The functions we have presented already allow the definition of arbitrarily complex transformations for zippers. Such transformations, however, are always applied on the node the zipper is focusing on. Let us consider a combinator that navigates in the zipper.

```
allTPright :: TP a \to TP a allTPright f z = case right z of Nothing \to return \ z Just \ r \quad \to fmap \ (from Just \ . \ left) \ (f \ r)
```

This function is a combinator that, given a type-preserving transformation f for zipper z, will attempt to apply f to the node that is located to the right of the node the zipper is pointing to. To do this, the zipper function right is used to try to navigate to the right; if it fails, we return the original zipper. If it succeeds, we apply transformation f and then we navigate left again. There is a similar combinator allTPdown but navigating downwards and then upwards.

With all these tools at our disposal, we can define generic traversal schemes by combining them. Next, we define the traversal scheme used in the function opt, which we defined at the start of the section. This traversal scheme navigates through the whole data structure, in a top-down approach.

```
 \begin{split} \text{full\_tdTP} &:: \text{TP } a \rightarrow \text{TP } a \\ \text{full\_tdTP } f &= \text{allTPdown (full\_tdTP } f) \text{ `seqTP'} \\ &\quad \text{allTPright (full\_tdTP } f) \text{ `seqTP' } f \end{split}
```

We skip the explanation of the seqTP operator as it is relatively similar to the adhocTP operator we have described before, albeit simpler; we interpret this as a sequence operator. This function receives as input a type-preserving transformation f, and (reading the code from right to left) it applies it to the focused node itself, then to the nodes below the currently focused node, then to the nodes to the right of the focused node. To apply this transformation to the nodes below the current node, for example, we use the allTPdown combinator we

mentioned above, and we recursively apply  $full_tdTP f$  to the node below. The same logic applies in regards to navigating to the right.

We can define several traversal schemes similar to this one by changing the combinators used, or their sequence. For example, by inverting the order in which the combinators are sequenced, we define a bottom-up traversal. By using different combinators, we can define choice, allowing for partial traversals in the data structure. We previously defined a rewrite strategy where we use full\_tdTP to define a full, top-down traversal, which is not ideal. Because we intend to optimize *Exp* nodes, changing one node might make it possible to optimize the node above, which would have already been processed in a top-down traversal. Instead, we define a different traversal scheme, for repeated application of a transformation until a fixed point is reached:

```
innermost :: TP a \rightarrow TP a
innermost s = \text{repeatTP (once\_buTP } s)
```

We omit the definitions of once\_buTP and repeatTP as they are similar to the presented definitions. The combinator repeatTP applies a given transformation repeatedly, until a fixed point is reached, that is, until the data structure stops being changed by the transformation. The transformation being applied repeatedly is defined with the once\_buTP combinator, which applies s once, anywhere on the data structure. When the application once\_buTP fails, repeatTP understands a fixed point is reached. Because the once\_buTP bottom-up combinator is used, the traversal scheme is innermost, since it prioritizes the innermost nodes. The pre-defined outermost strategy uses the once\_tdTP combinator instead. The full API of our zipper-based strategic library is presented in Fig. 1.

### 4 Ztrategic Library: Examples

Let us return to our **let** running example. Next, we show a **let** fragment that we will use to show the power of strategic programming.

```
example = \mathbf{let} \ a = b - 16
c = 8
w = \mathbf{let} \ y = \mathbf{let} \ q = 3 + 4
\mathbf{in} \ q
z = 0 + a + 0
\mathbf{in} \ z + b
b = (c + 3) - c
\mathbf{in} \ c + a - w
```

Looking at this **let** program we can see that several arithmetic rules can be applied, namely, we can remove the two additions with zero in the definition of z, and we can perform the addition of 3 with 4 in the nested definition on q.

To make our example more interesting, we consider more arithmetic rules that we may use to optimize let expressions. In Figure 2, we present the rules given in [8].

```
Strategy Types
    type TP a = \text{Zipper } a \rightarrow Maybe (\text{Zipper } a)
    type TU m \ d = (forall \ a \ . \ \mathsf{Zipper} \ a \to m \ d)
Primitive Strategies
                                                                                       Traversal Combinators
   idTP
                    :: \mathsf{TP}\ a
                                                                                           allTPright :: TP \ a \rightarrow TP \ a
   \mathsf{constTU} \; :: d \to \mathsf{TU} \; m \; d
                                                                                          oneTPright :: TP \ a \rightarrow TP \ a
   failTP
                    :: TP a
                                                                                           \mathsf{allTUright} \ :: \mathsf{TU} \ m \ d \to \mathsf{TU} \ m \ d
   failTU
                    :: \mathsf{TU} \ m \ d
                                                                                          \mathsf{allTPdown} \; :: \mathsf{TP} \; a \to \mathsf{TP} \; a
   tryTP
                    :: \mathsf{TP}\ a \to \mathsf{TP}\ a
                                                                                          \mathsf{oneTPdown} :: \mathsf{TP}\ a \to \mathsf{TP}\ a
   \mathsf{repeatTP} :: \mathsf{TP}\ a \to \mathsf{TP}\ a
                                                                                          \mathsf{allTUdown} \ :: \mathsf{TU} \ m \ d \to \mathsf{TU} \ m \ d
Strategic Construction
                                                                                       Traversal Strategies
   monoTP
                    :: (a \rightarrow Maybe \ b) \rightarrow \mathsf{TP} \ e
                                                                                           \mathsf{full\_tdTP} \quad :: \mathsf{TP} \stackrel{-}{a} \to \mathsf{TP} \ a
   monoTU :: (a \rightarrow m \ d) \rightarrow \mathsf{TU} \ m \ d
                                                                                          \mathsf{full\_buTP} \; :: \mathsf{TP} \; a \to \mathsf{TP} \; a
   monoTPZ :: (a \rightarrow \mathsf{Zipper}\ e \rightarrow \mathit{Maybe}\ b) \rightarrow \mathsf{TP}\ e
                                                                                          once\_tdTP :: TP \ a \rightarrow TP \ a
   monoTUZ :: (a \rightarrow \mathsf{Zipper}\ e \rightarrow m\ d) \rightarrow \mathsf{TU}\ m\ d
                                                                                          once_buTP :: TP a \to \mathsf{TP}\ a
   adhocTP :: TP e \rightarrow (a \rightarrow Maybe\ b) \rightarrow \text{TP } e
                                                                                          stop\_tdTP :: TP \ a \rightarrow TP \ a
   \mathsf{stop\_buTP} :: \mathsf{TP}\ a \to \mathsf{TP}\ a
   \mathsf{adhocTPZ} :: \mathsf{TP}\ e \to (a \to \mathsf{Zipper}\ e \to \mathit{Maybe}\ b)
                                                                                          \mathsf{innermost} \ :: \mathsf{TP} \ a \to \mathsf{TP} \ a
                           \rightarrow TP e
                                                                                          outermost :: \mathsf{TP}\ a \to \mathsf{TP}\ a
   adhocTUZ :: TU \ m \ d \rightarrow (a \rightarrow Zipper \ c \rightarrow m \ d)
                                                                                          \mathsf{full\_tdTU} \quad :: \mathsf{TU} \ m \ d \to \mathsf{TU} \ m \ d
                           \rightarrow \mathsf{TU}\ m\ d
                                                                                          \mathsf{full\_buTU} \; :: \mathsf{TU} \; m \; d \to \mathsf{TU} \; m \; d
Composition / Choice
                                                                                          \mathsf{once\_tdTU} :: \mathsf{TU}\ m\ d \to \mathsf{TU}\ m\ d
                  :: \mathsf{TP}\ a \to \mathsf{TP}\ a \to \mathsf{TP}\ a
   seqTP
                                                                                          \mathsf{once\_buTU} :: \mathsf{TU}\ m\ d \to \mathsf{TU}\ m\ d
   \mathsf{choiceTP} :: \mathsf{TP}\ a \to \mathsf{TP}\ a \to \mathsf{TP}\ a
                                                                                          stop\_tdTU :: TU m d \rightarrow TU m d
                 :: \mathsf{TU} \ m \ d \to \mathsf{TU} \ m \ d \to \mathsf{TU} \ m \ d
                                                                                          \mathsf{stop\_buTU} :: \mathsf{TU}\ m\ d \to \mathsf{TU}\ m\ d
   \mathsf{choiceTU} :: \mathsf{TU} \ m \ d \to \mathsf{TU} \ m \ d \to \mathsf{TU} \ m \ d
```

Fig. 1: Full Ztrategic API

```
add(e, const(0)) \rightarrow e \qquad (1)
add(const(0), e) \rightarrow e \qquad (2)
add(const(a), const(b)) \rightarrow const(a+b) \qquad (3)
sub(e1, e2) \rightarrow add(e1, neg(e2)) \qquad (4)
neg(neg(e)) \rightarrow e \qquad (5)
neg(const(a)) \rightarrow const(-a) \qquad (6)
```

Fig. 2: Optimization Rules

In our definition of the function expr, we already defined rewriting rules for optimizations 1 and 2. We can trivially extend this definition to consider rules 3 through 6:

```
\begin{array}{lll} expr :: Exp \rightarrow Maybe \ Exp \\ expr \ (Add \ e \ (Const \ 0)) &= Just \ e & -- \ (1) \\ expr \ (Add \ (Const \ 0) \ t) &= Just \ t & -- \ (2) \\ expr \ (Add \ (Const \ a) \ (Const \ b)) &= Just \ (Const \ (a+b)) & -- \ (3) \end{array}
```

```
\begin{array}{lll} expr \ (Sub \ a \ b) & = Just \ (Add \ a \ (Neg \ b)) & -- \ (4) \\ expr \ (Neg \ (Neg \ f)) & = Just \ f & -- \ (5) \\ expr \ (Neg \ (Const \ n)) & = Just \ (Const \ (-n)) & -- \ (6) \\ expr \ \_ & = Just \ e & -- \ default \end{array}
```

Having expressed all rewriting rules in function *expr*, now we need to use our strategic solution *optimize* that navigates in the tree while applying the rules. Next, we consider several strategies to apply this type specific transformation, which produce different optimizations.

Full Top Down Strategy: This strategy traverses the full tree while applying the transformation to the nodes where the type specific transformation holds.

Next, we show the function optimizeFTP that applies the optimizations defined by expr using the full\_tdTP strategy.

The strategic function optmizeFTP combines all the steps of our library. We define an auxiliary function step, which is the composition of the idTP default succeeding strategy with expr, the optimization function; we compose them with adhocTP. Our resulting Type-Preserving strategy will be full\_tdTP step, which applies step to the zipper repeatedly while fully traversing the tree in a top down scheme. We apply this strategy using the function  $applyTP::TP \ c \to Zipper \ c \to Maybe$  (Zipper c), which effectively applies a strategy to a zipper.

To make it easier to apply this function to our examples, we make this function work on *Let* trees, and not on the Zipper of these trees.

```
 \begin{array}{l} optimizationFTD :: \underline{Let} \rightarrow \underline{Let} \\ optimizationFTD \ t = fromZipper \ (fromJust \ (applyTP \ (full\_tdTP \ step) \ (toZipper \ t))) \\ \textbf{where} \ step = idTP \ `adhocTP` \ expr \end{array}
```

When we apply *optimize* that uses the strategy full\_tdTP to the *letExample* input, we get the following result:

```
letResult = \mathbf{let} \ a = b + 16
c = 8
w = \mathbf{let} \ y = \mathbf{let} \ q = 7
\mathbf{in} \ q
z = 0 + a
\mathbf{in} \ z + b
b = (c + 3) - c
\mathbf{in} \ c + a - w
```

The full top down traversal scheme does not perform all possible optimizations. In fact, it was only able to eliminate a single occurrence of the two additions with 0. This happens because when we apply the rule that eliminates addition with 0 to the subtree 0+a+0, the first alternative definition in expr matches the input. As a result, the first pattern instantiates 0+a with the (pattern) variable e and 0 with Const 0. This line of code returns e as result, thus returning the 0+a that pattern matched with e (without performing further optimization on e).

**Innermost Strategy:** A innermost strategy applies the type specific transformation to the tree until a fix point is reached. That is to say, until no transformation can be applied and it returns as result the given input tree.

In our **let** example, in order to guarantee that all possible optimizations are applied to the input, we need to use an innermost traversal scheme. Thus, our optimization is correctly expressed as:

```
optmizeIM :: Zipper Let \rightarrow Maybe (Zipper Let) optmizeIM t = applyTP (innermost step) t where step = failTP 'adhocTP' exprFail
```

The use of failTP as the default strategy is required, as innermost reaches the fixed-point when *step* fails. It should be noticed that if we use idTP instead, *step* always succeeds, resulting in an infinite loop of this strategy!

As a consequence, we have also to update the worker function so that the default behaviour does not return a tree, but returns *Nothing* instead.

```
exprFail :: Exp \rightarrow Maybe Exp
                                                            -- (1)
exprFail (Add e (Const 0))
                                   = Just e
exprFail (Add (Const 0) t)
                                   = Just t
                                                             --(2)
exprFail\ (Add\ (Const\ a)\ (Const\ b)) = Just\ (Const\ (a+b)) -- (3)
                          = Just (Add \ a \ (Neg \ b)) -- (4)
exprFail (Sub a b)
exprFail (Neg (Neg f))
                                  = Just f
exprFail (Neg (Const n))
                                   = Just (Const(-n))
                                                            --(6)
exprFail _
                                   = Nothing
                                                            -- default
```

If we run optimizeIM with letExample, then we get the desired result:

```
letResult = \mathbf{let} \ a = b + 16
c = 8
w = \mathbf{let} \ y = \mathbf{let} \ q = 7
\mathbf{in} \ q
z = a
\mathbf{in} \ z + b
b = (c + 3) - c
\mathbf{in} \ c + a - w
```

Once Top Down Strategy: This strategy traverses the tree in a top down traversal scheme and it stops as soon it is able to apply the worker function. Thus, it applies the type specific transformation only once.

Next we show the the optimization performed using the *oce\_tdTP* strategy, which is very similar to the full\_tdTP solution we presented before.

```
optimizationOTD :: Zipper \ Let 
ightarrow Maybe \ (Zipper \ Let) \ optimizationOTD \ t = applyTP \ (once\_tdTP \ step) \ t \ where \ step = idTP \ 'adhocTP' \ expr
```

When we apply this strategic function to our *letExample* we get exactly the same tree/input! In fact, because the default behaviour of our *step* function is to apply idTP, which succeeds for any node, we are able to perform "work" in the first reached node, therefore stopping the strategy immediately. Even if the first visited node matches type with *expr* and it is applied, since it always returns a tree (even if it is the same, unchanged tree), the once\_tdTP strategy immediately applies it once and stops.

To use this strategy we need to have a worker function that fails as the default behavior. Thus, the next and correct definition uses the *wokerFail* transformation and the failTP default case.

```
optimizationOTD :: Zipper Let \rightarrow Maybe (Zipper Let) optimizationOTD t = applyTP (once_tdTP step) t where step = failTP 'adhocTP' workerFail
```

As defined by this strategy, if we apply optimization OTD to the **let** example, there is only one optimization performed: the addition of 3 and 4 in the definition of q, which is the first subtree reached in a top down recursion scheme.

```
letResult = \mathbf{let} \ a = b + 16
c = 8
w = \mathbf{let} \ y = \mathbf{let} \ q = 7
\mathbf{in} \ q
z = 0 + a + 0
\mathbf{in} \ z + b
b = (c + 3) - c
\mathbf{in} \ c + a - w
```

Once Bottom Up Strategy: This strategy traverses the tree in a bottom up traversal scheme and it stops as soon as it is able to apply the worker function. Similarly to its top down counterpart, this strategy applies the type specific transformation only once. This strategy also requires that the worker function fails in its default rule, so that the exact same input tree is not produced as result

When we use this strategy once\_buTP to apply the worker function *workerFail* to our **let** example, the first optimization that is able to perform in the addition with 0.

$$letResult = \mathbf{let} \ a = b + 16$$
$$c = 8$$

$$w = \mathbf{let} \ y = \mathbf{let} \ q = 3 + 4$$

$$\mathbf{in} \ q$$

$$z = a + 0$$

$$\mathbf{in} \ z + b$$

$$b = (c + 3) - c$$

$$\mathbf{in} \ c + a - w$$

**Stop Top Down Strategy:** This strategy applies a strategy while traversing the tree top down. However, it does not perform a full top down traversal: when the worker function is applied, then it does not go deeper in that subtree. The strategy continues performing a top down traversal in the rest of the tree.

However, if we consider the following input let example, where we switched the two definitions in the nested let.

$$\begin{aligned} example &= \mathbf{let} \ a = b - 16 \\ c &= 8 \\ w &= \mathbf{let} \ z = 0 + a + 0 \\ y &= \mathbf{let} \ q = 3 + 4 \\ &\qquad \qquad \mathbf{in} \ q \\ b &= (c + 3) - c \\ \mathbf{in} \ c + a - w \end{aligned}$$

then we get

$$\begin{aligned} let Result &= \mathbf{let} \ a &= b + 16 \\ c &= 8 \\ w &= \mathbf{let} \ z = 0 + a \\ y &= \mathbf{let} \ q = 3 + 4 \\ &\quad \mathbf{in} \ q \\ \mathbf{in} \ z + b \\ b &= (c + 3) - c \\ \mathbf{in} \ c + a - w \end{aligned}$$

#### 4.1 Type Unifying Strategies

Next, we show an example using a type-unifying strategy. We define a function names that collects all defined names in a **let** expression. First, we define a function select that focuses on the **Let** tree nodes where names are defined, namely, Assign and NestedLet. This function returns a singleton list (with the defined name) when applied to these nodes, and an empty list in the other cases.

```
\begin{array}{lll} select :: List \rightarrow [Name] \\ select \; (Assign \; s \; \_ \; \_) &= [s] \\ select \; (NestedLet \; s \; \_ \; \_) &= [s] \\ select \; \_ &= [] \end{array}
```

Now, *names* is a Type-Unifying function that traverses a given *Let* tree (inside a zipper, in our case), and produces a list with the declared names.

```
\begin{array}{l} names \ :: \ Let \rightarrow [\textit{Name}] \\ names \ t = \mathsf{applyTU} \ (\mathsf{full\_tdTU} \ step) \ (\mathsf{toZipper} \ t) \\ \mathbf{where} \ step = \mathsf{failTU} \ \text{`adhocTU} \ select \end{array}
```

The traversal strategy influences the order of the names in the resulting list. We use a top-down traversal so that the list result follows the order of the input. This is to say that

```
names (toZipper \ example) = ["a", "c", "w", "y", "q", "z", "b"]
```

If we use a full bottom-up strategy, it produces the reverse of this list.

To use the once/stop down/Bottom up strategies we need to change the worker function so that it reports failure in the default alternative. Yet again, we return a *Maybe* result, using type constructor *Nothing* to report failure.

```
select :: List \rightarrow Maybe \ [Name]
select \ (Assign \ s \_ \_) = Just \ [s]
select \ (NestedLet \ s \_ \_) = Just \ [s]
select \_ = Nothing
now, we can write
```

```
\begin{split} namesOBUF :: \textbf{L}et \rightarrow & [\textbf{N}ame] \\ namesOBUF \ t = & fromJust \ \$ \ applyTU \ (once\_buTU \ step) \ (toZipper \ t) \\ \textbf{where} \ step = & failTU \ `adhocTU \ `selectF \end{split}
```

that given example as input, it produces the singleton list ["b"].

## 4.2 Refactoring Haskell Programs

Source code smells make code harder to comprehend and they do occur in any programming language. Haskell is no exception. For example, inexperienced Haskell programmers often write  $l \equiv []$  that uses equality to check whether

a list is empty, instead of using the predefined null function. Within a strategic programming style we express the elimination of this known smell by defining the type-specific transformation which is defined in two simple alternatives: A first one, specifies the pattern of  $l \equiv [\,]$  and the transformation to be performed. A second one defines the work to be performed in all other parts of Haskell programs/trees: nothing in this case. In the first alternative, the original and refactored patterns are expressed using the data type defined the full abstract syntax of Haskell, as defined in its libraries. By just knowing the types and constructors that represent both  $l \equiv [\,]$  and  $null\ l$ , we write the following type-specific function:

```
\begin{array}{l} nullList :: HsExp \rightarrow Maybe \ HsExp \\ nullList \ (HsInfixApp \ a \ (HsQVarOp \ (UnQual \ (HsSymbol \ "=="))) \ (HsList \ [])) \\ = Just \ (HsApp \ (HsVar \ (UnQual \ (HsIdent \ "null"))) \ a) \\ nullList \ \_= Nothing \end{array}
```

Now, we define a strategic-based function that applies the *nullList* transformation to a full *Haskell* abstract syntax tree. A refactoring is a type preserving transformation, and in this case we rely in a full bottom-up tree traversal.

```
smells:: Zipper\ HsModule 	o Maybe\ (Zipper\ HsModule) smells\ h = applyTP\ (full\_buTP\ worker)\ h where\ worker = failTP\ 'adhocTP'\ nullList
```

This is the full *Haskell* program that eliminates this known smell. Together with the front-end included in the *Haskell* libraries, we produced an useful refactoring tool: for example, it processed 1139 *Haskell* files (totaling 82124 lines of code), written by first year students, and eliminated 850 code smells in those files [9].

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