

# Constrained Delaunay Triangulations

## CDTs

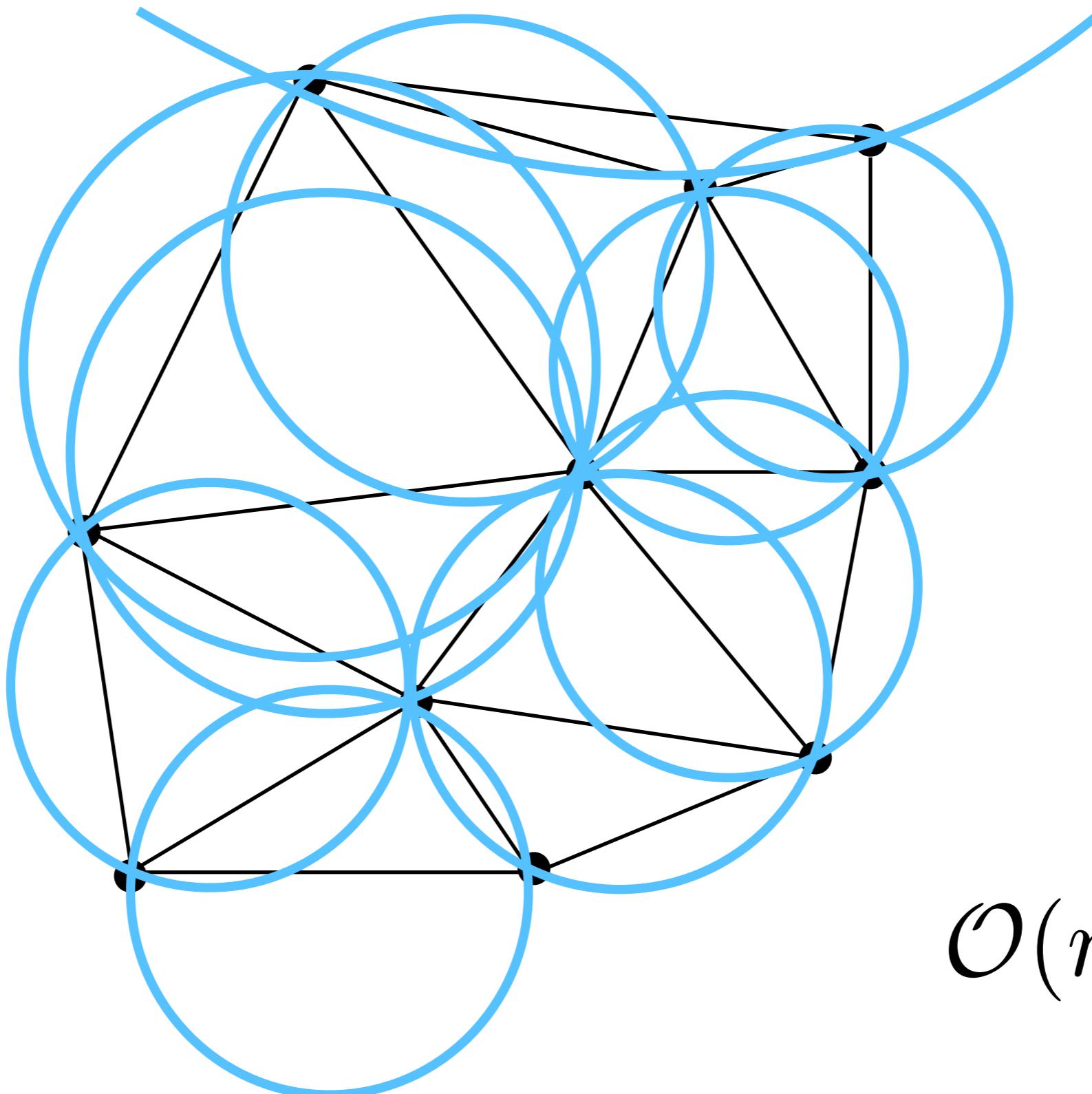


Борис Николаевич Делонé  
Boris Nikoláievich Deloné

L. Paul Chew

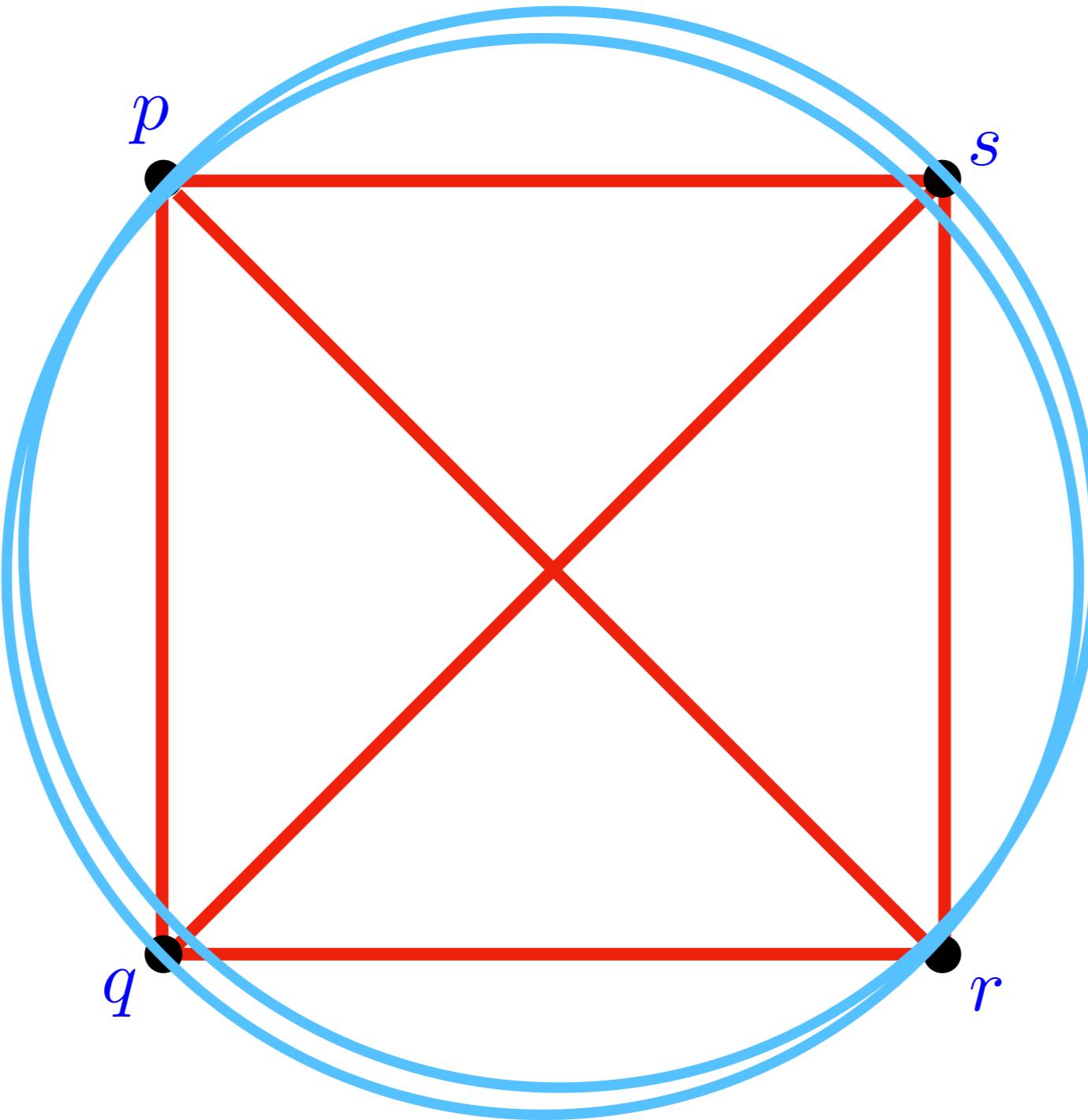


# Triangulaciones de Delaunay


$$O(n \log n)$$

# Triangulaciones de Delaunay

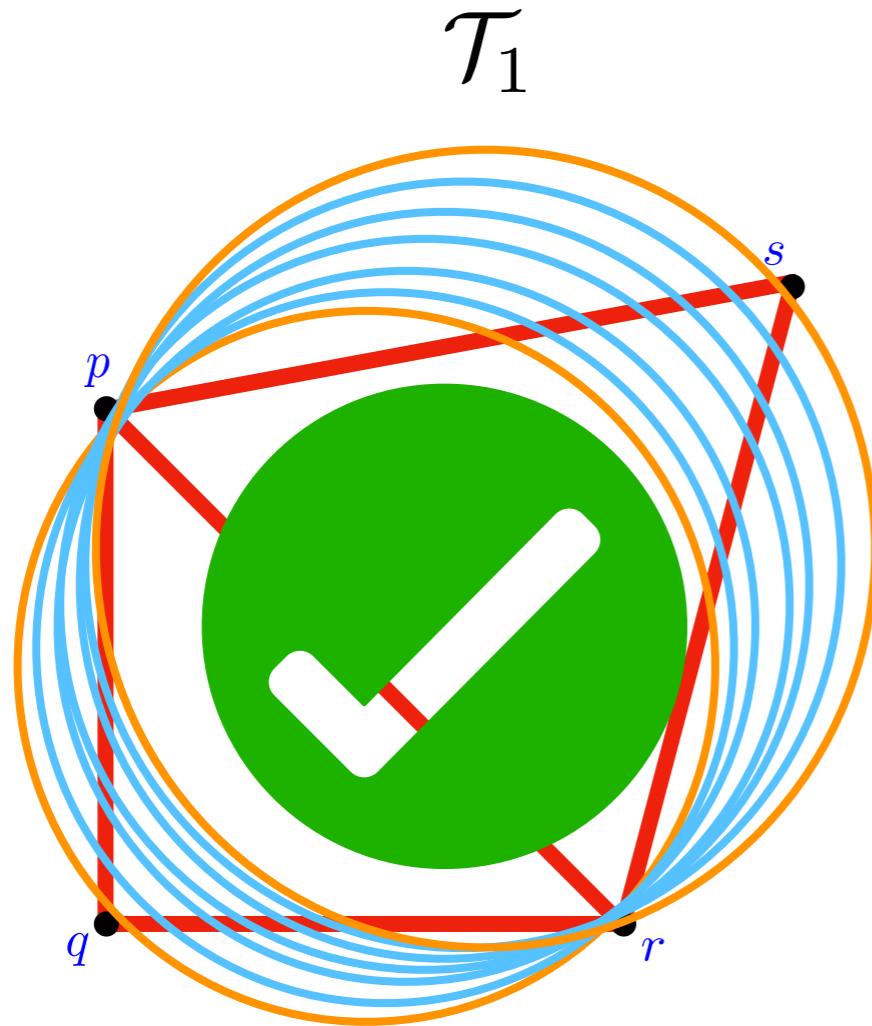
## Unicidad



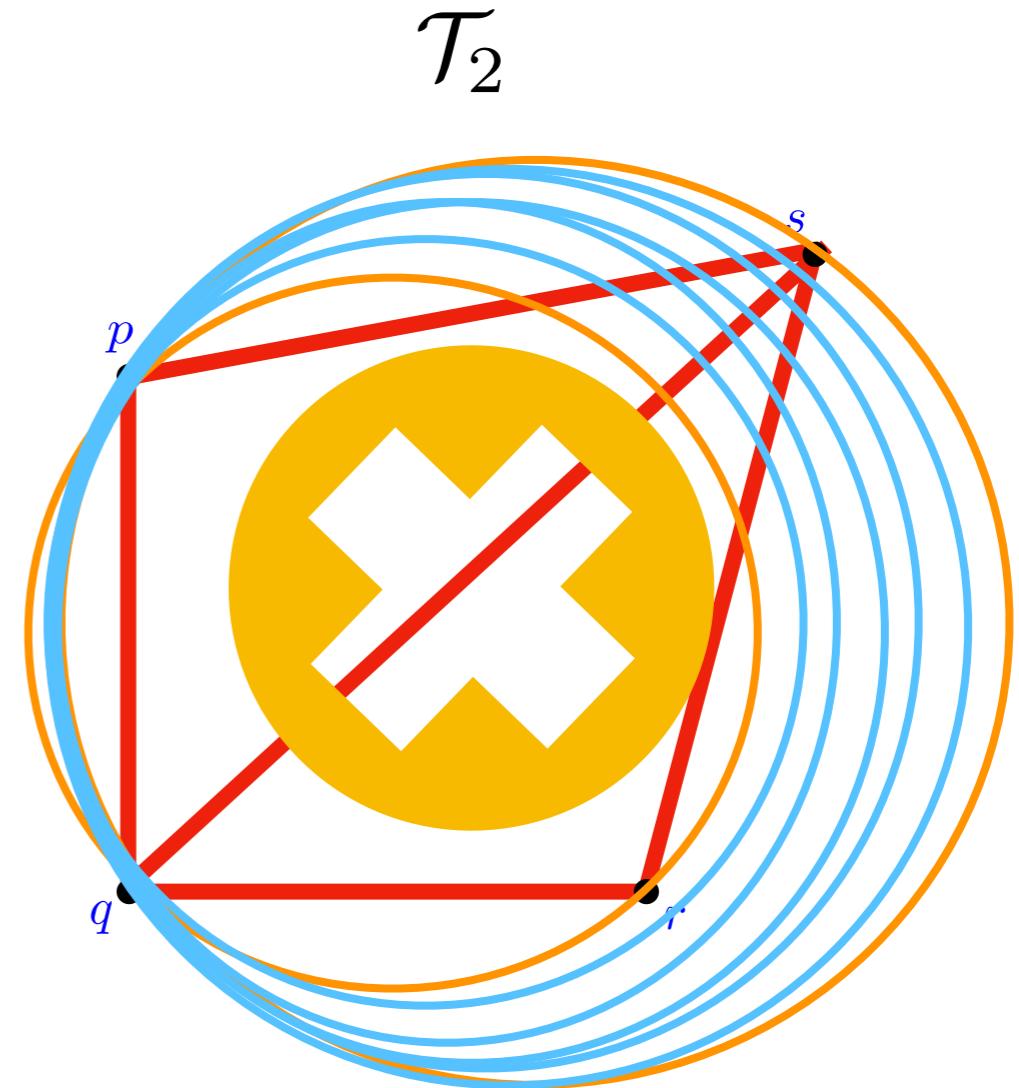
4 vértices cocirculares

# Triangulaciones de Delaunay

## Unicidad



$\mathcal{C}_1$



$\mathcal{C}_2$

# Diagrama de Voronoi

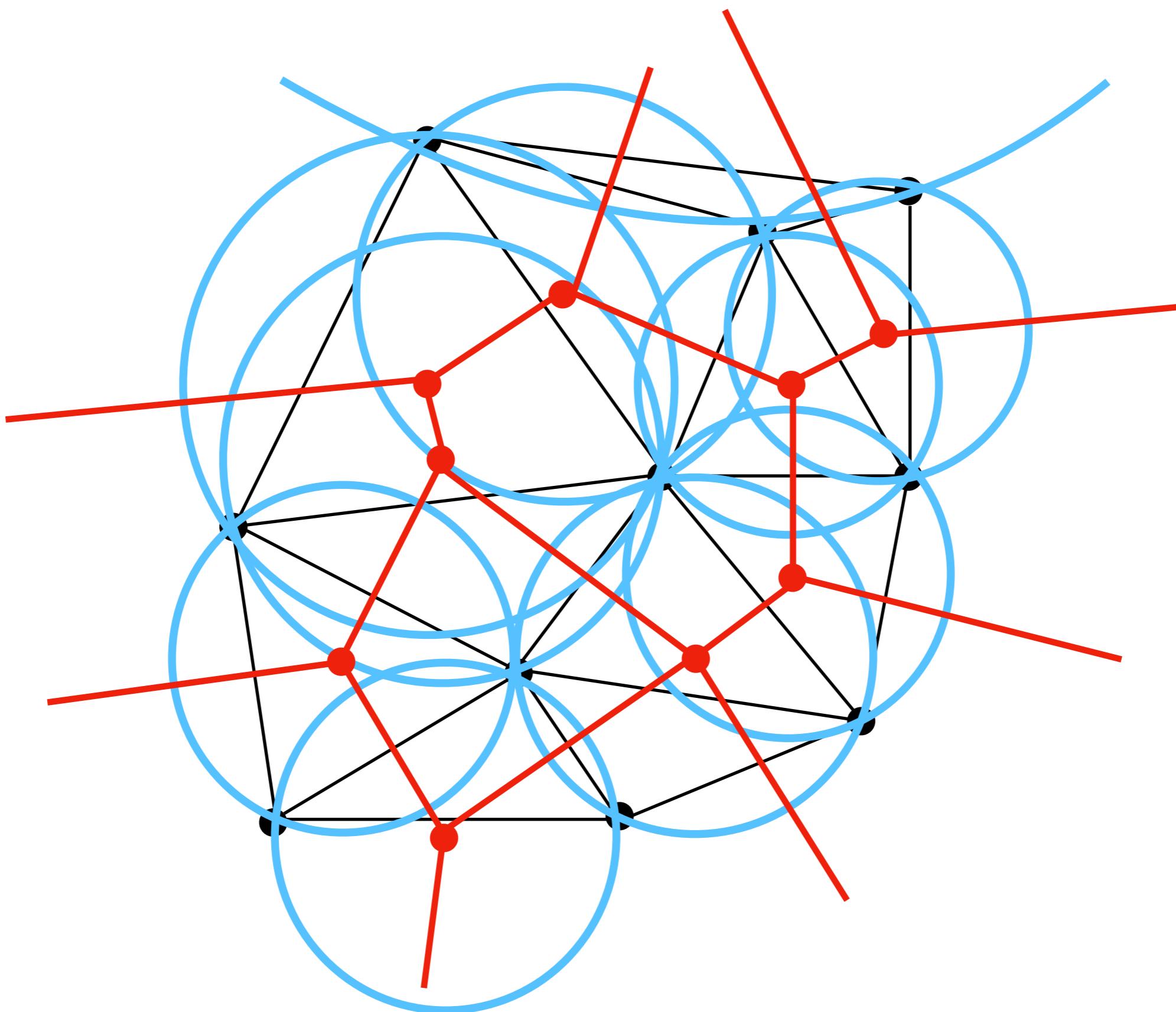
$$P \subset \mathbb{R}^2$$

$$P = \{p_1, p_2, \dots, p_n\}$$

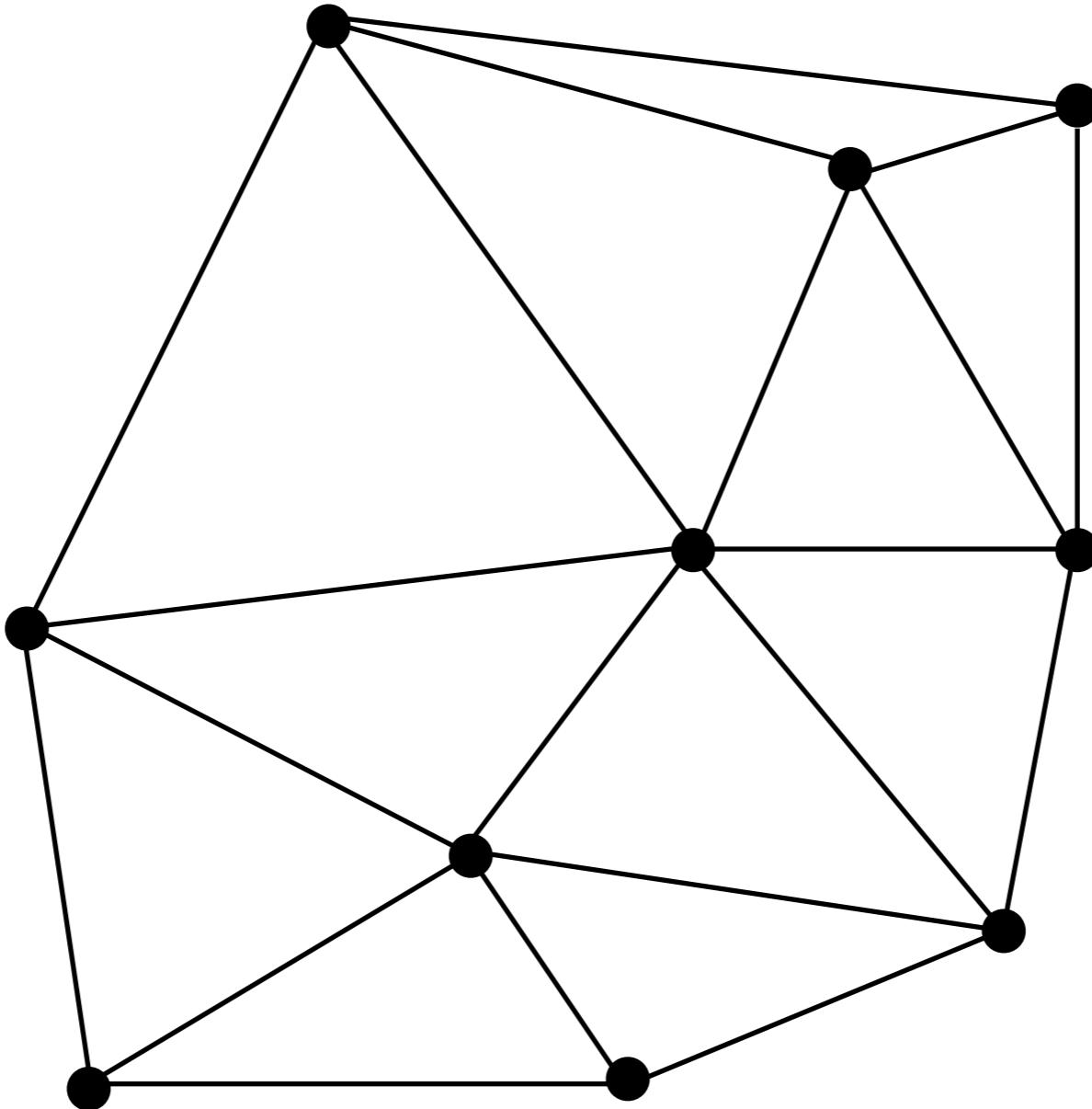
$$\mathcal{VD}(P)$$

$$q \in \mathcal{V}(p_i) \Leftrightarrow \text{dist}(p_i, q) \leq \text{dist}(p_j, q) \forall p_j \in P, j \neq i$$

# Diagrama de Voronoi

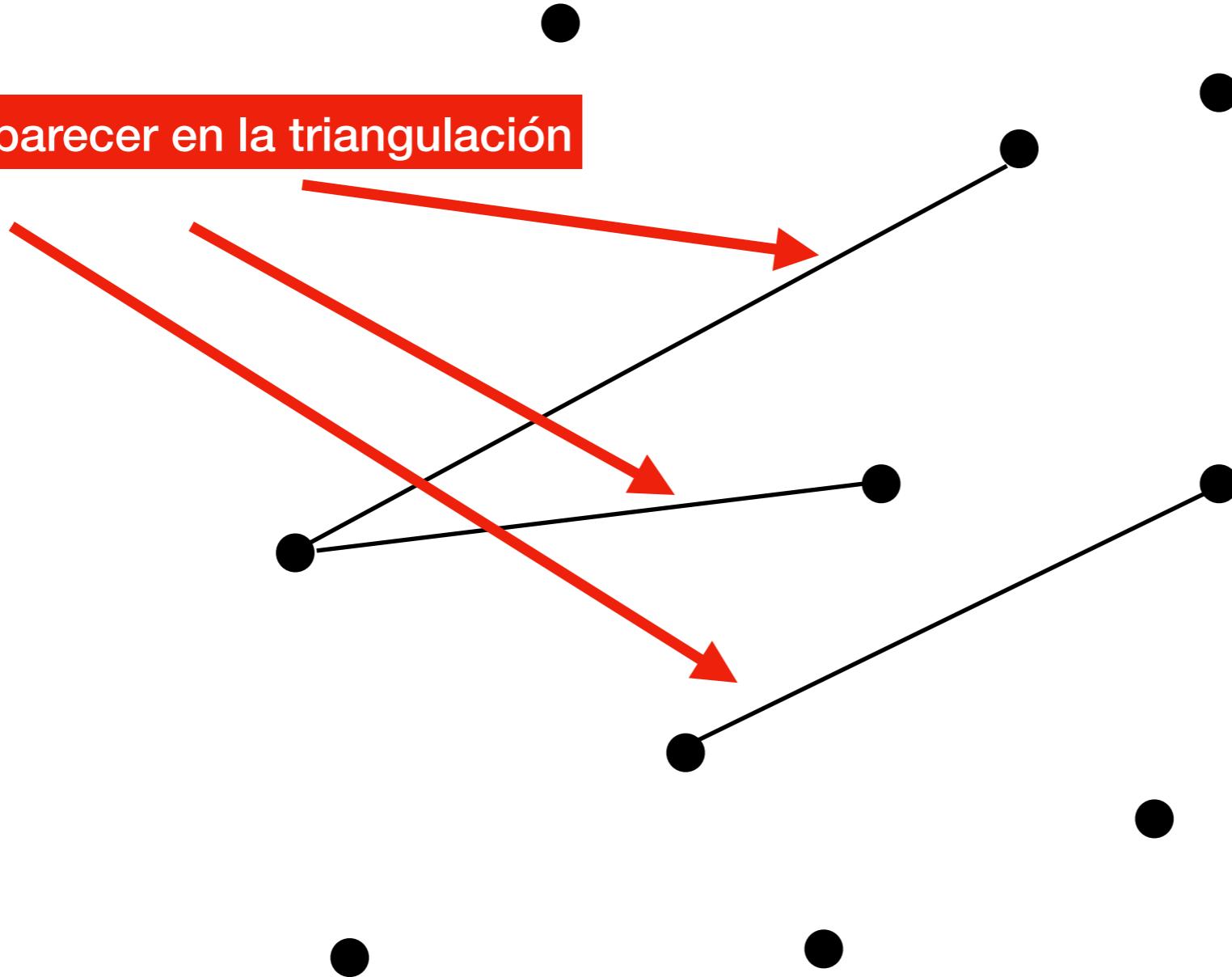


## Triangulación de Delaunay



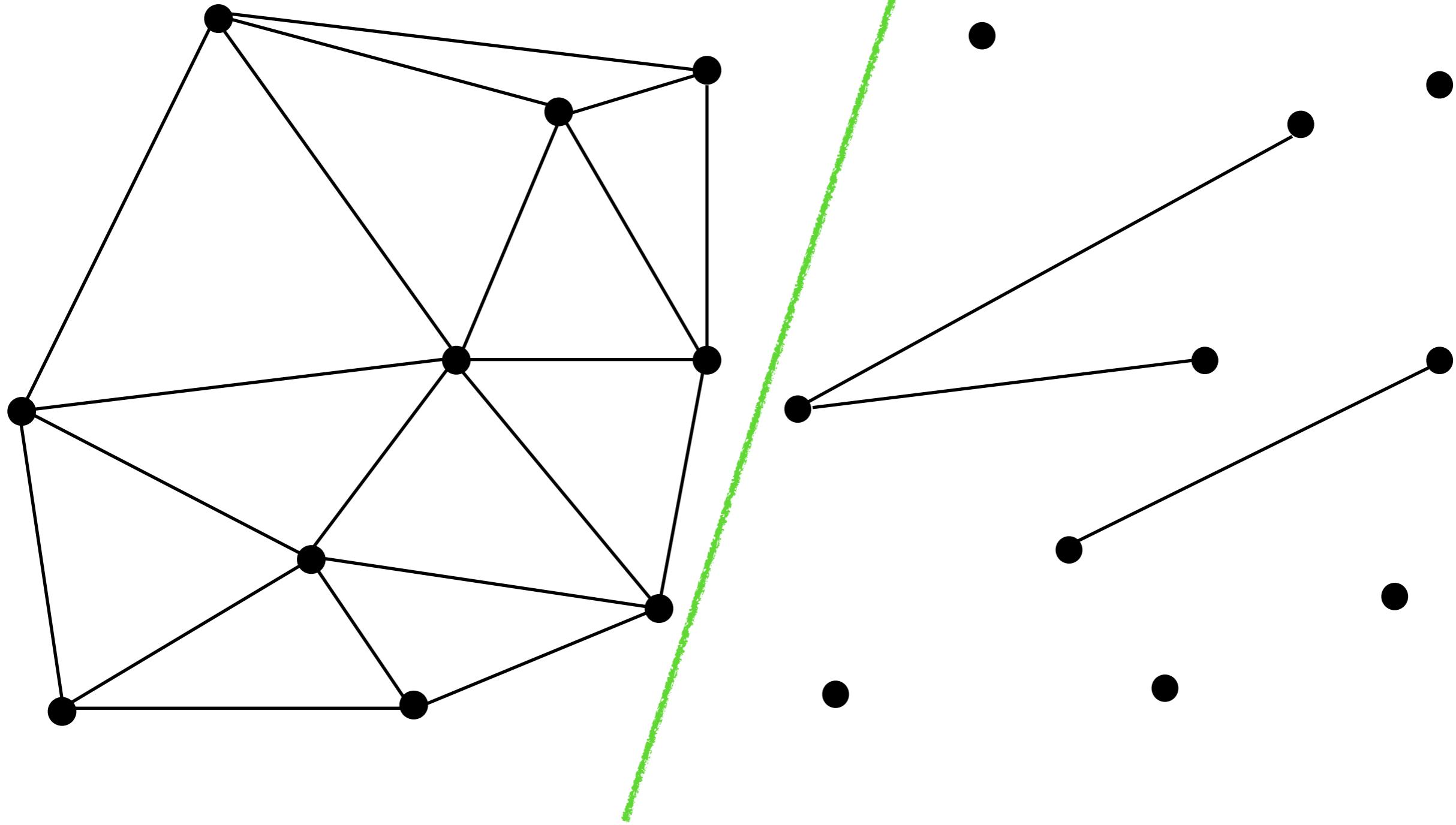
$G = (V, E)$  plana

Deben aparecer en la triangulación



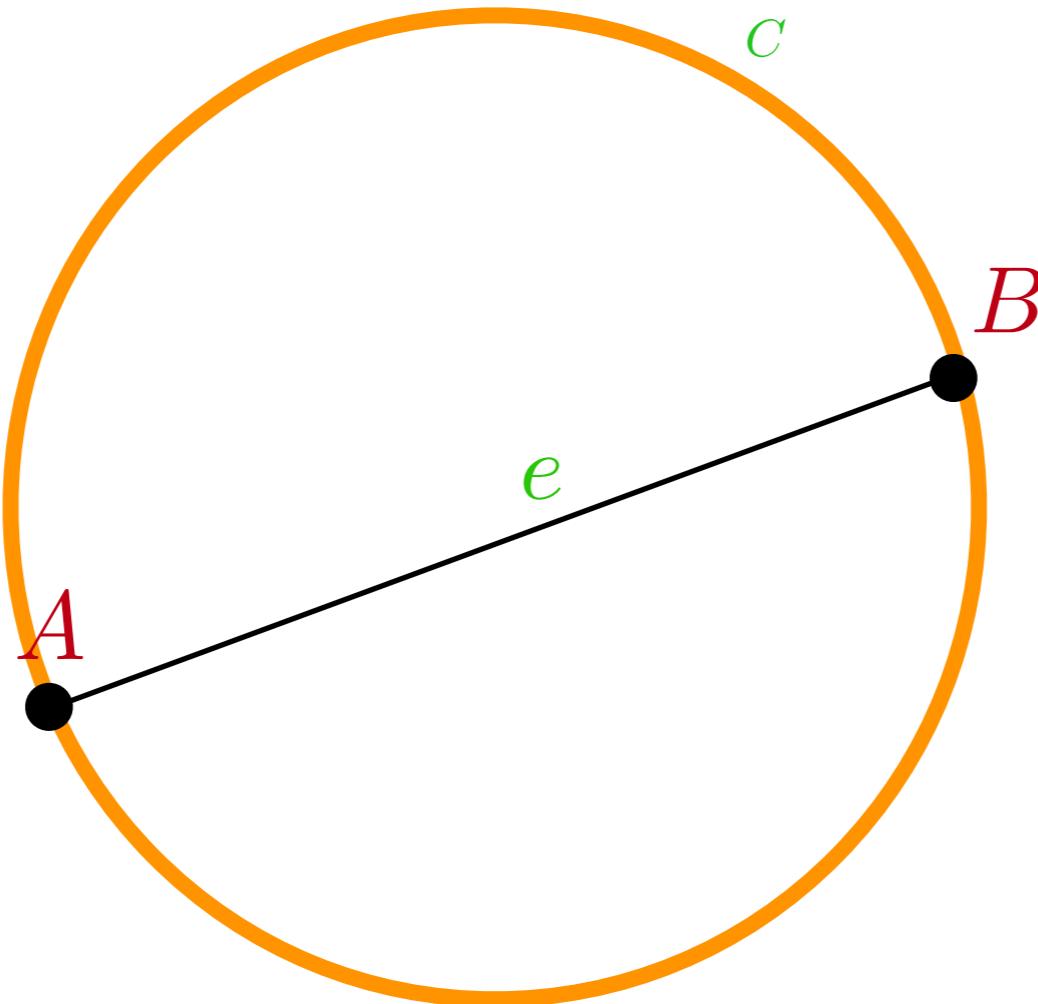
# CDT

Acercarnos a  $\mathcal{D}(G)$



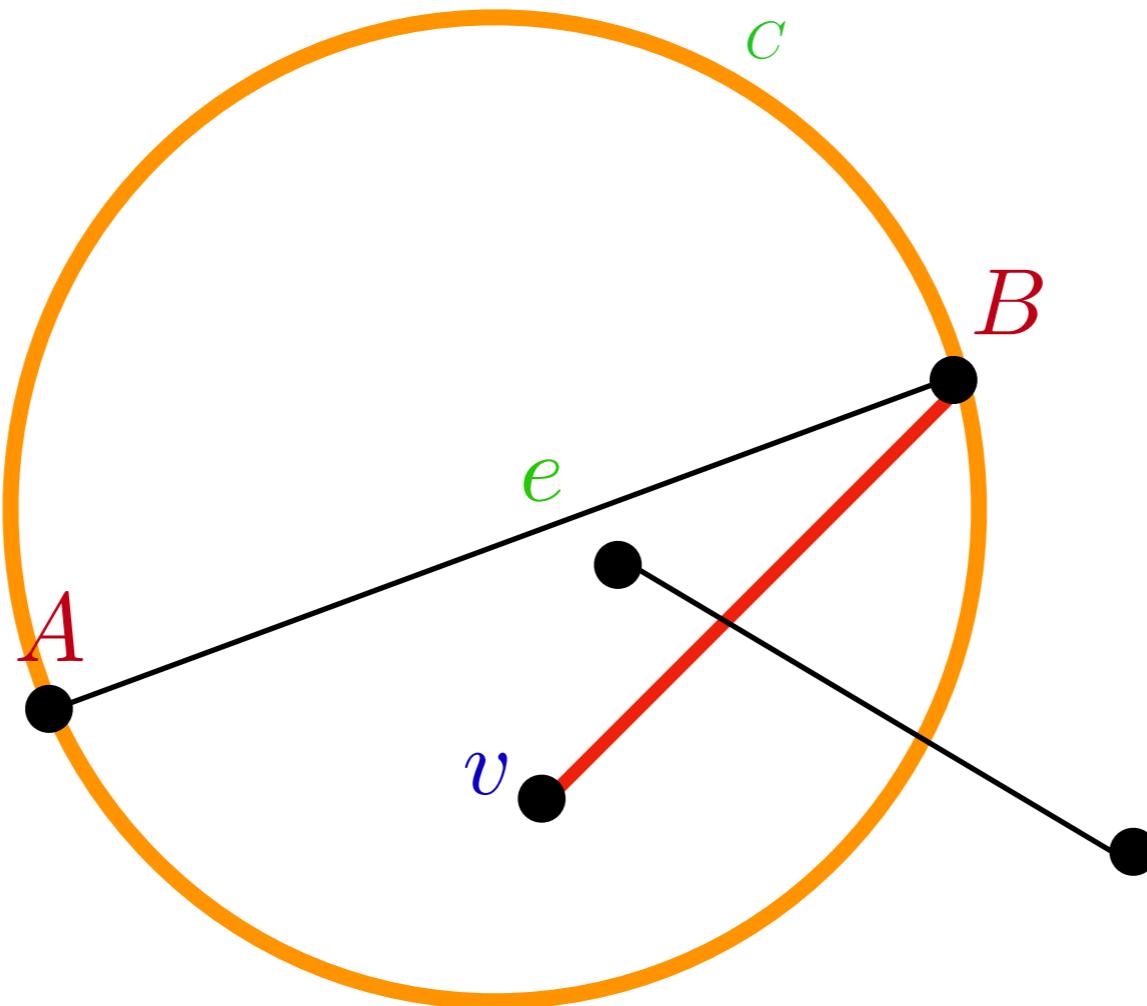
## Definición

1.  $\forall e \in E(T) \exists c$



## Definición

2. Si  $v$  en  $c \Rightarrow \cancel{\text{eye}} \text{ por } A \text{ ó } B$



## Aplicaciones

$S \subset \mathbb{R}^2$  Conjunto de puntos

$\mathcal{D}(S)$  La triangulación de Delaunay

$\mathcal{E}(S)$  EMST

$\forall e \in E(\mathcal{E}(S)), e \in E(\mathcal{D}(S))$



$\mathcal{E}(S) \subseteq \mathcal{D}(S)$

$e = (u, v) \in E(\mathcal{E}(S)) \ni e \notin E(\mathcal{D}(S))$



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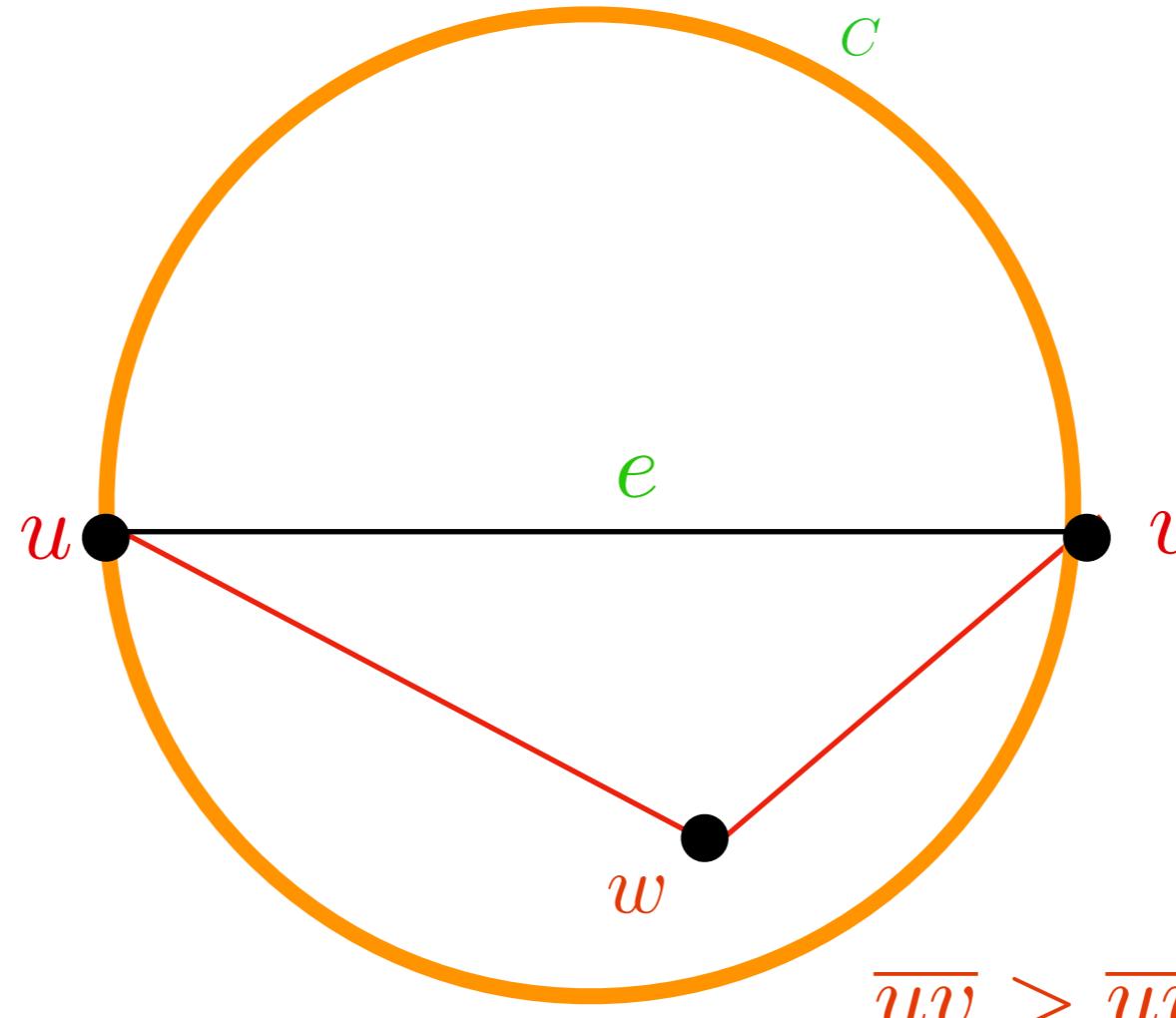
EMSTs Restringidos

## Aplicaciones

Diámetro

$\overline{uv}$

$e \notin E(\mathcal{D}(S))$



$$\overline{uv} > \overline{uw} \wedge \overline{uv} > \overline{vw}$$

!



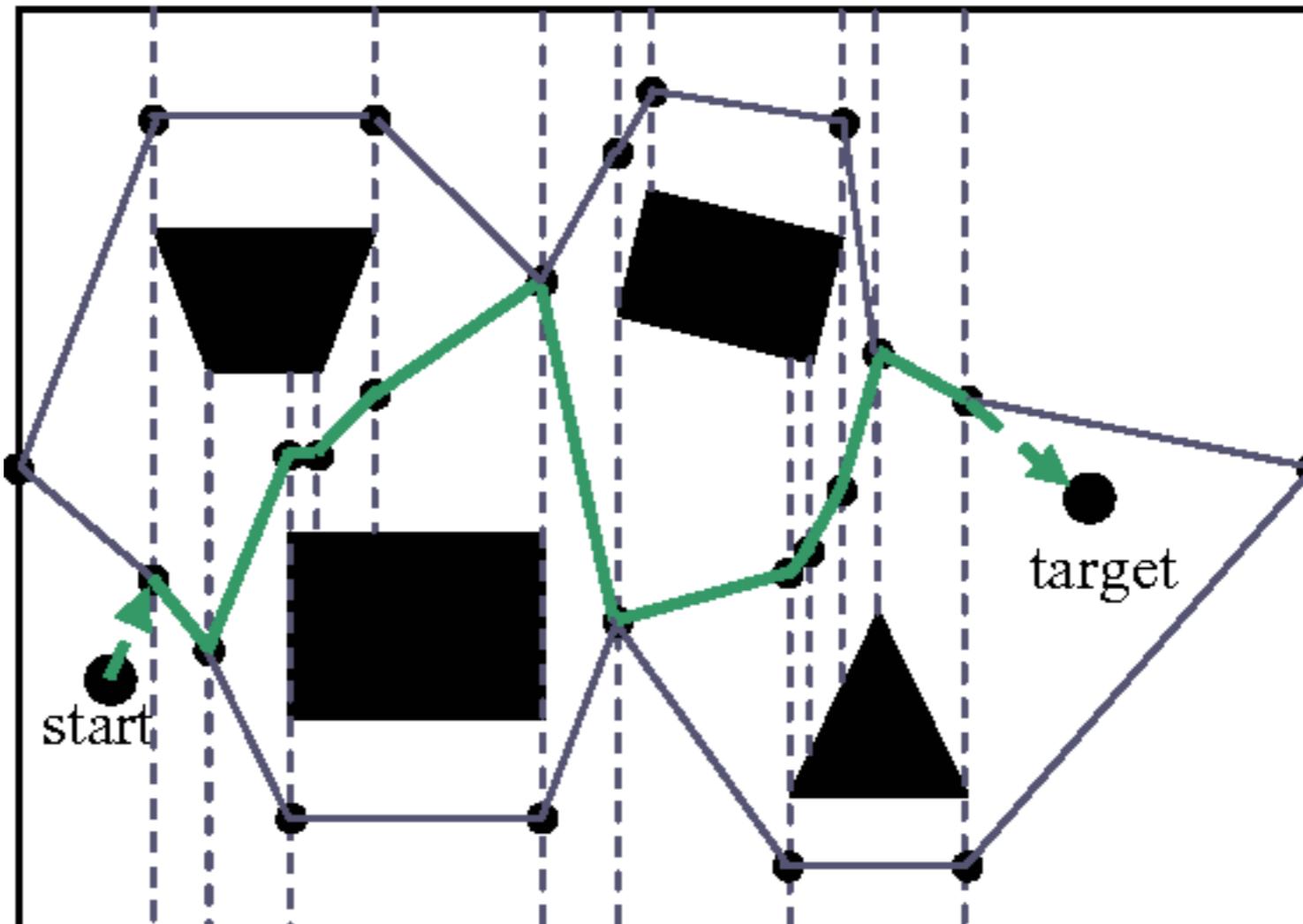
EMSTs Restringidos

## Aplicaciones



EMSTs Restringidos

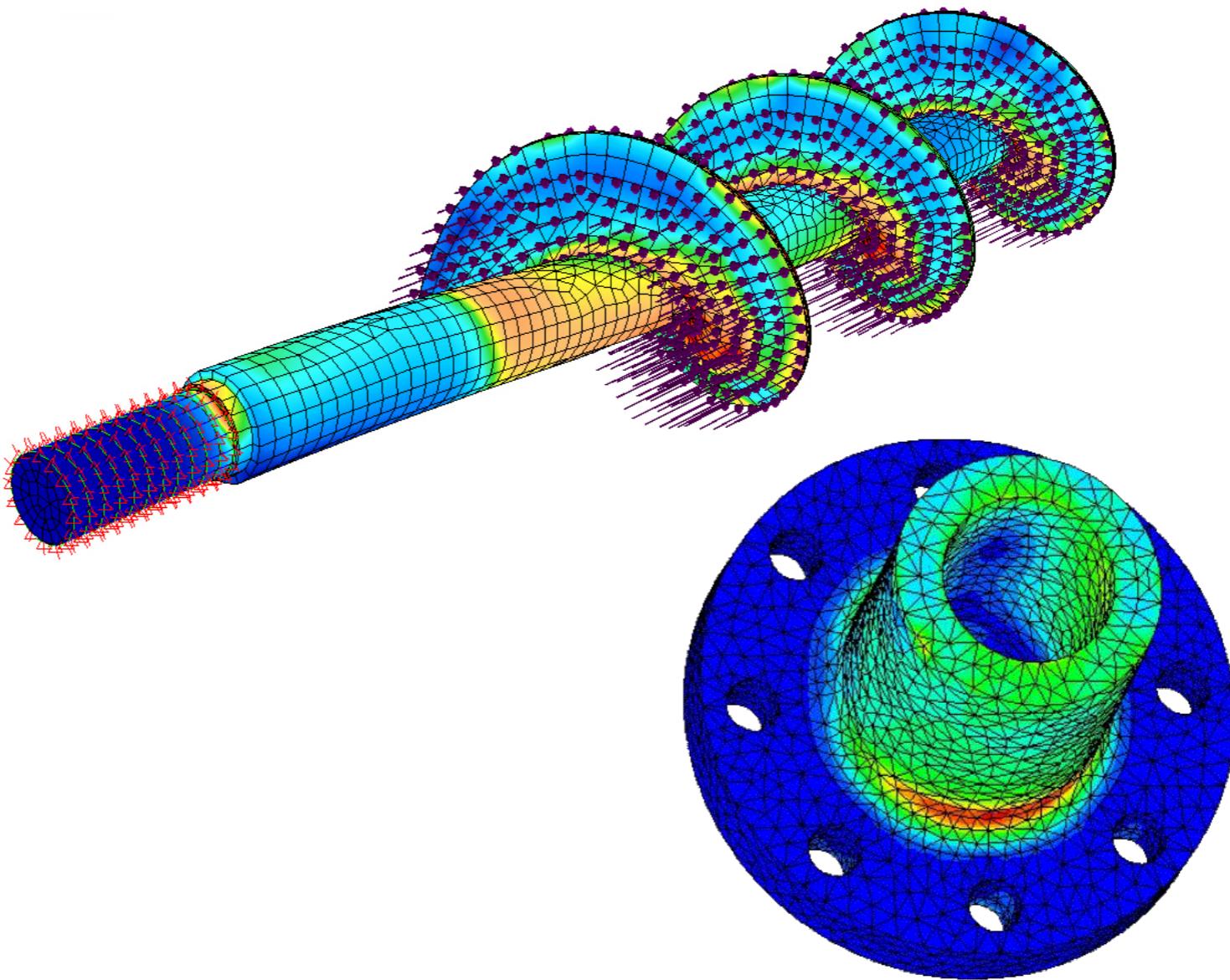
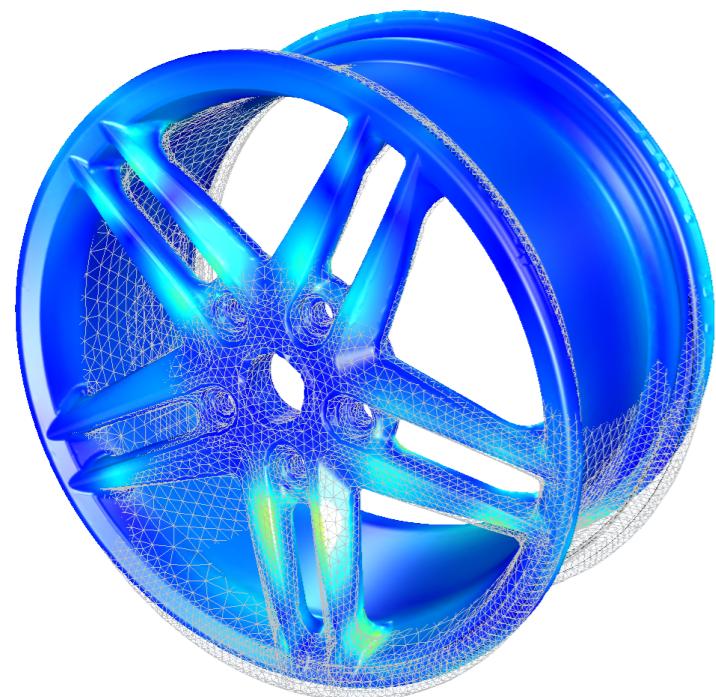
## Aplicaciones



EMSTs Restringidos

Planeación de movimiento

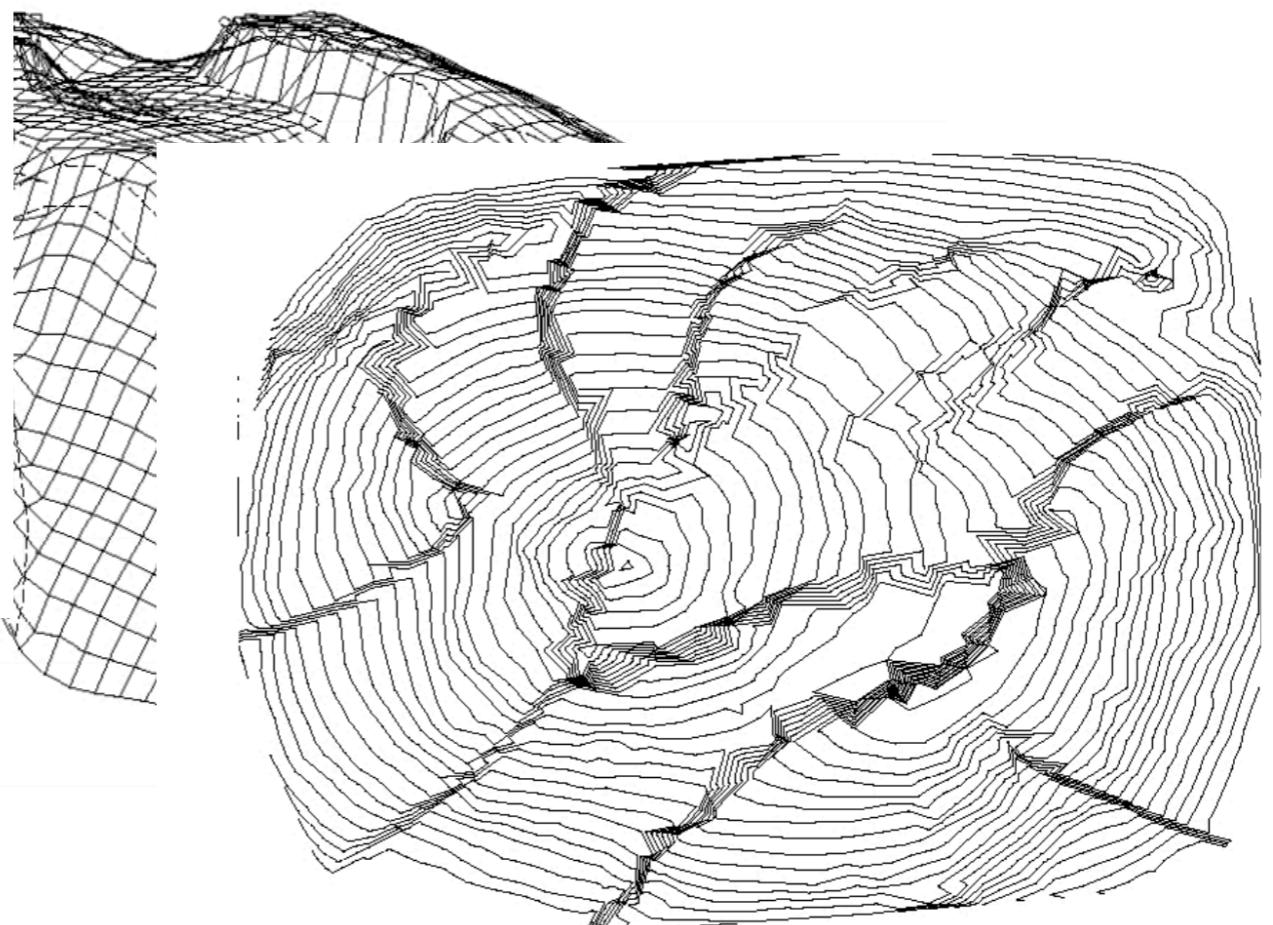
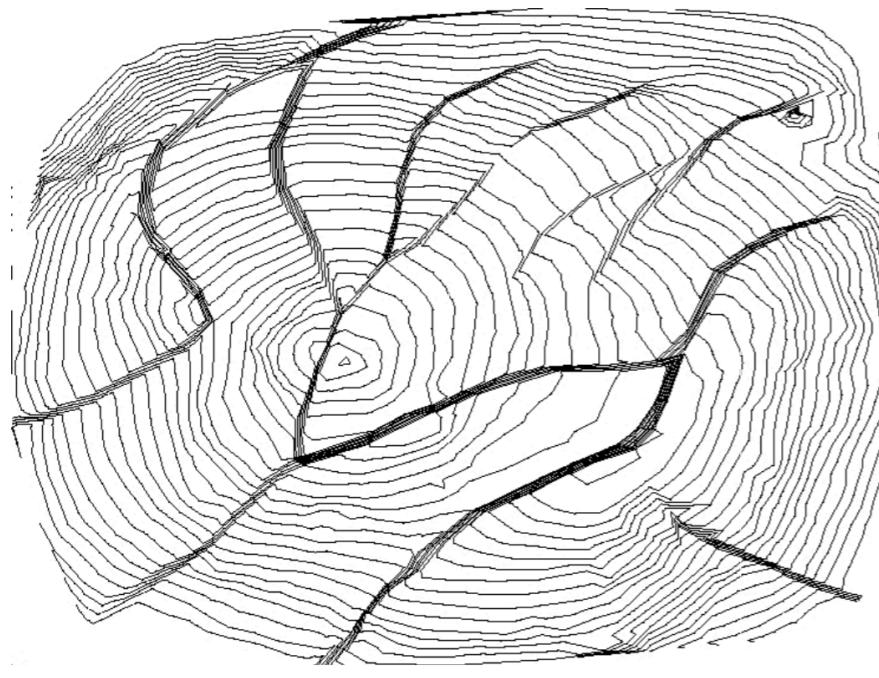
## Aplicaciones



nimiento

FEM

## Aplicaciones



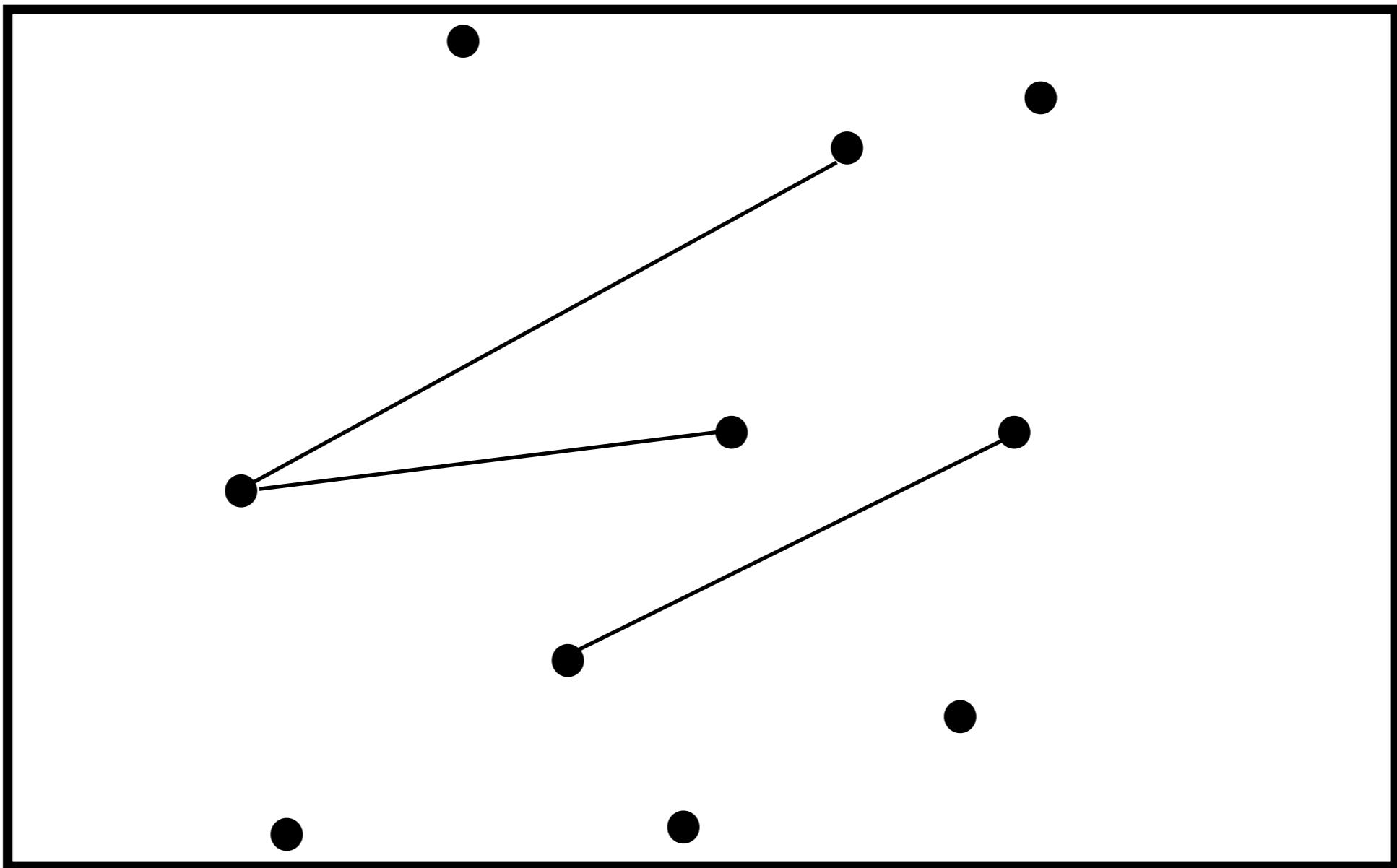
niento

FEM

Interpolación de superficies

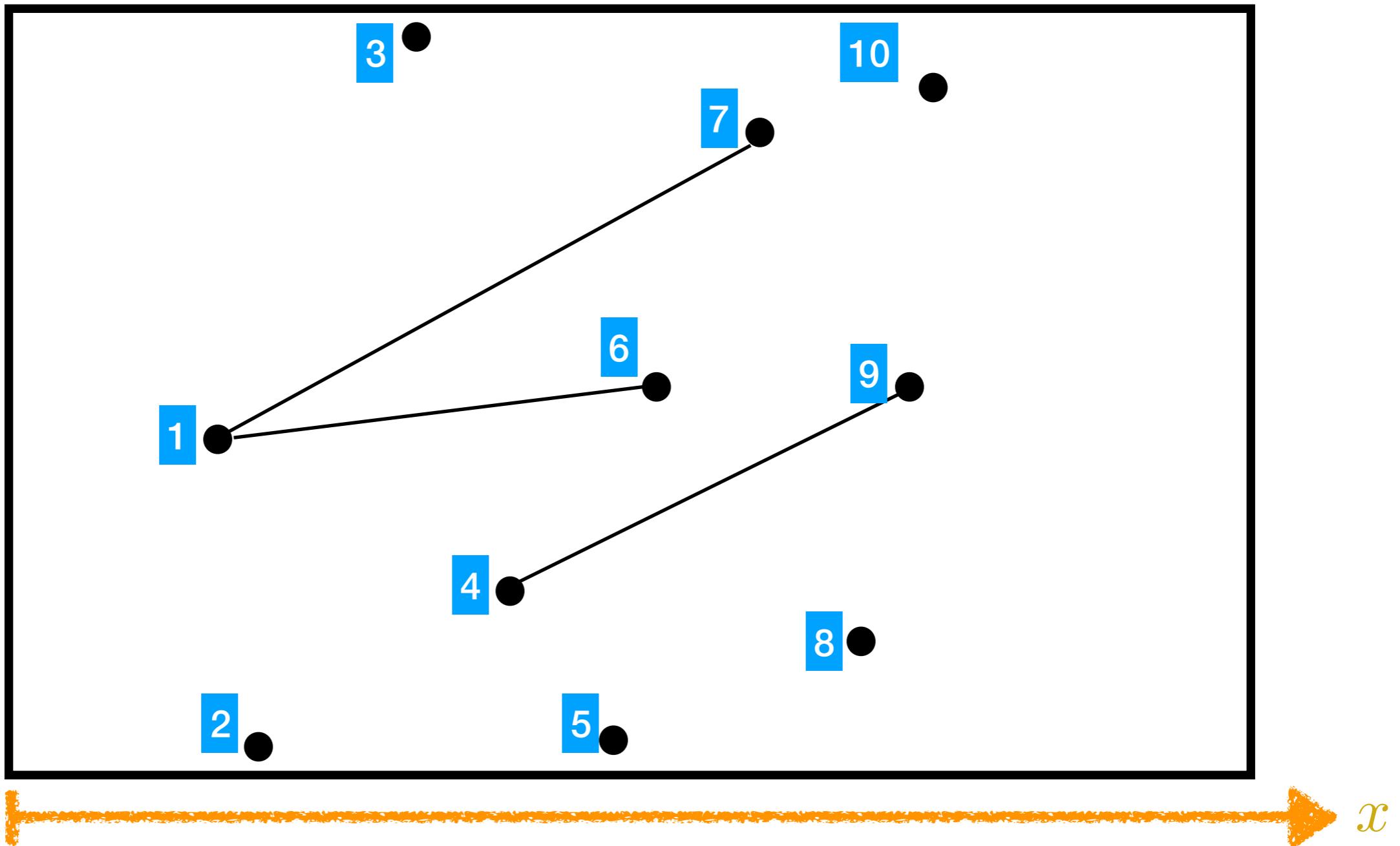
## Algoritmo

Divide y vencerás



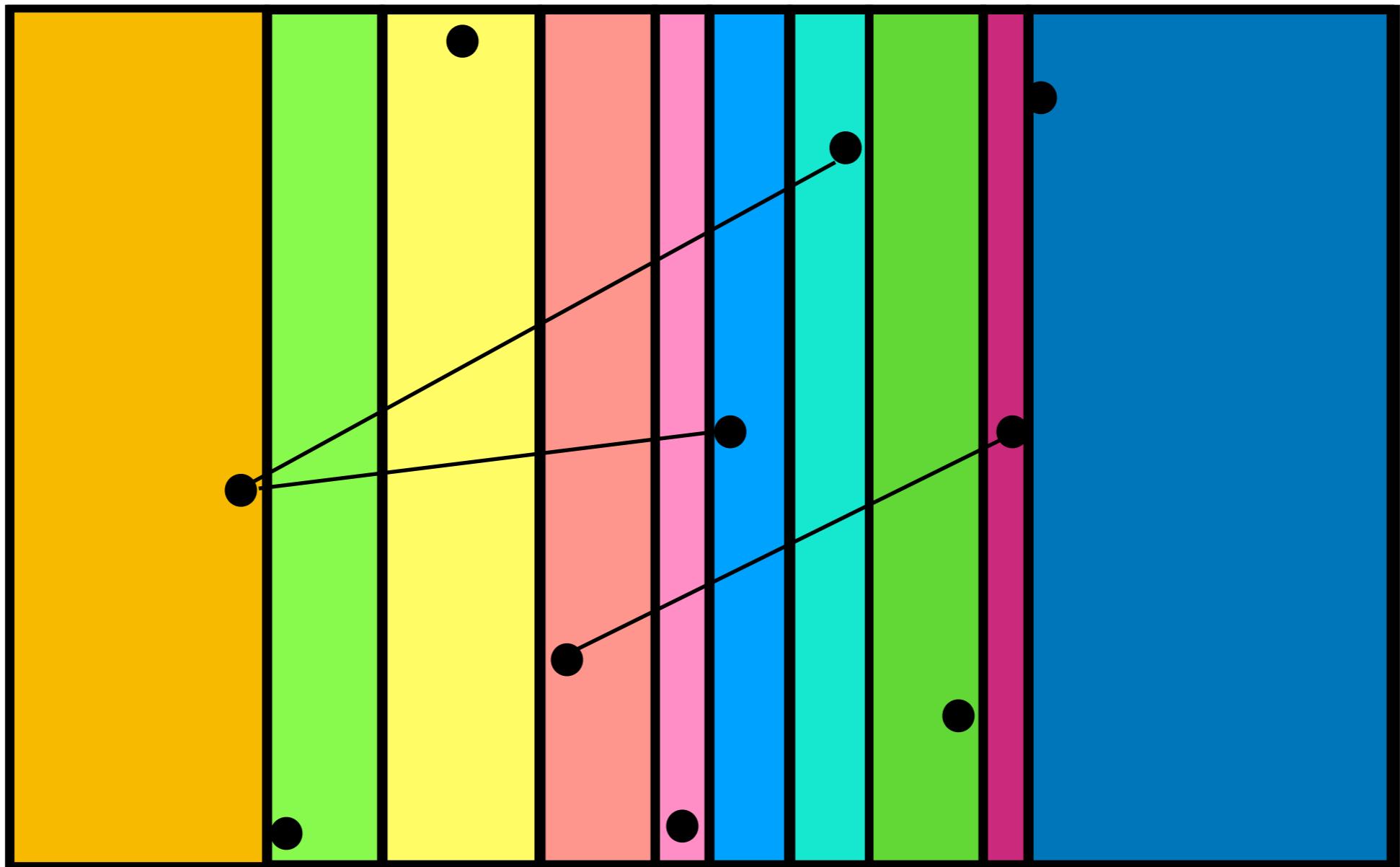
## Algoritmo

Divide y vencerás



## Algoritmo

Divide y vencerás

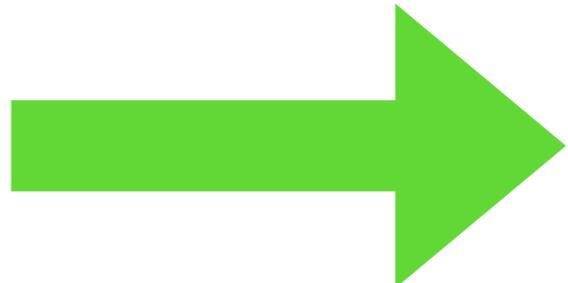


## Algoritmo

Divide y vencerás

Calcular la CDT de las franjas

eficientemente



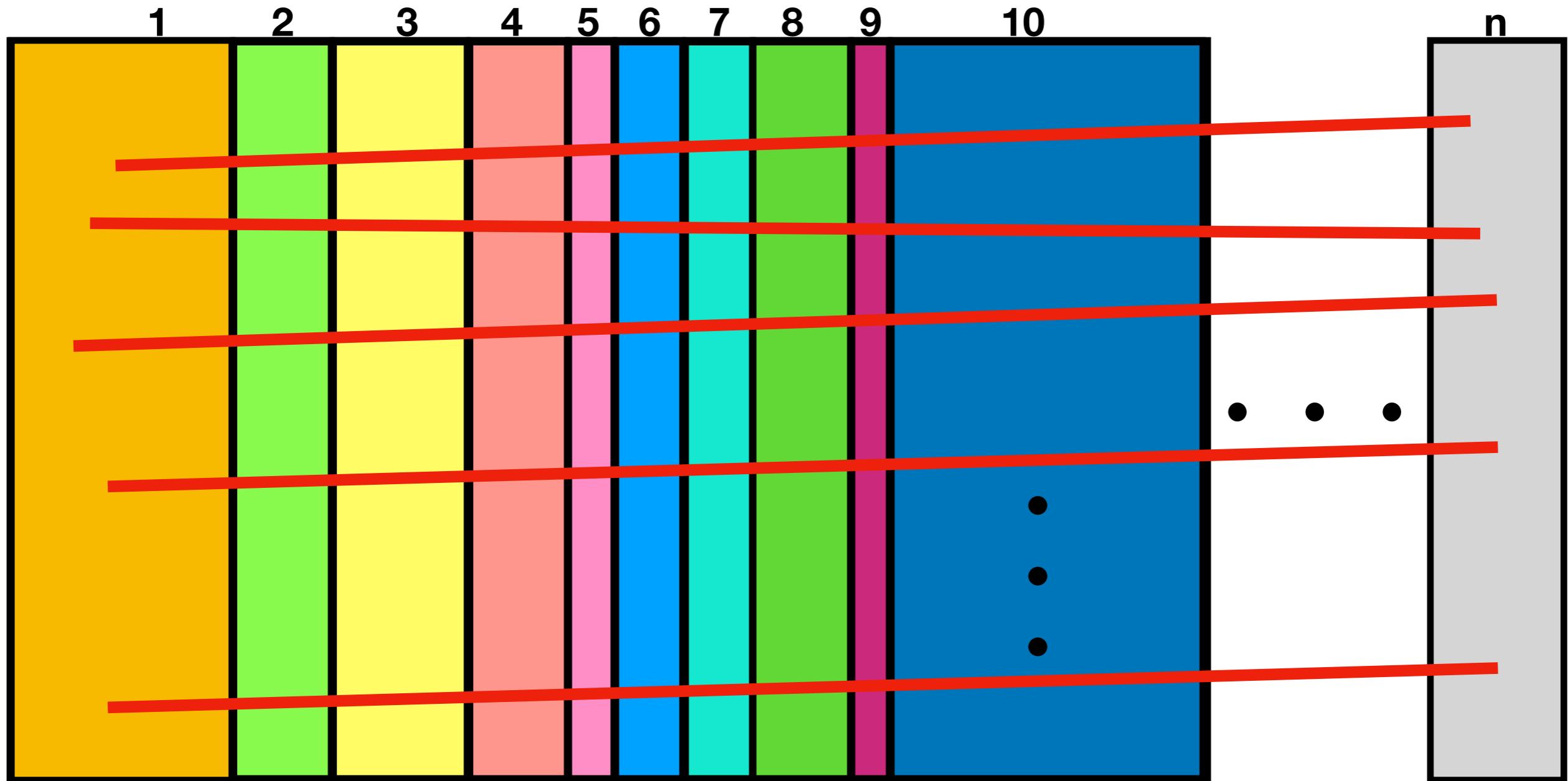
$O(n \log n)$

Combinar franjas contiguas

# Algoritmo

$$|V(G)| \in \Theta(n^2), O(n)$$

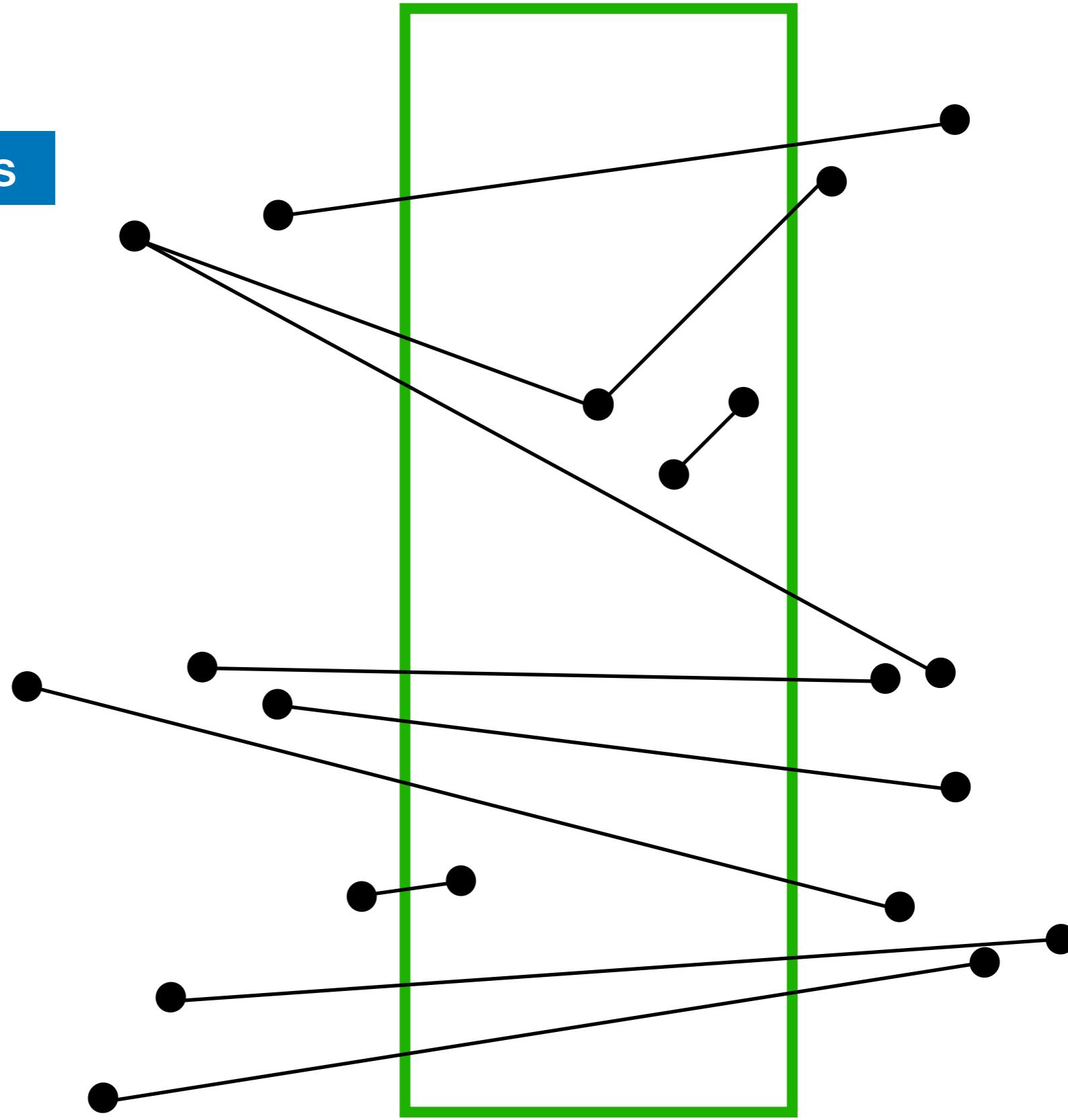
Divide y vencerás



## Algoritmo

Divide y vencerás

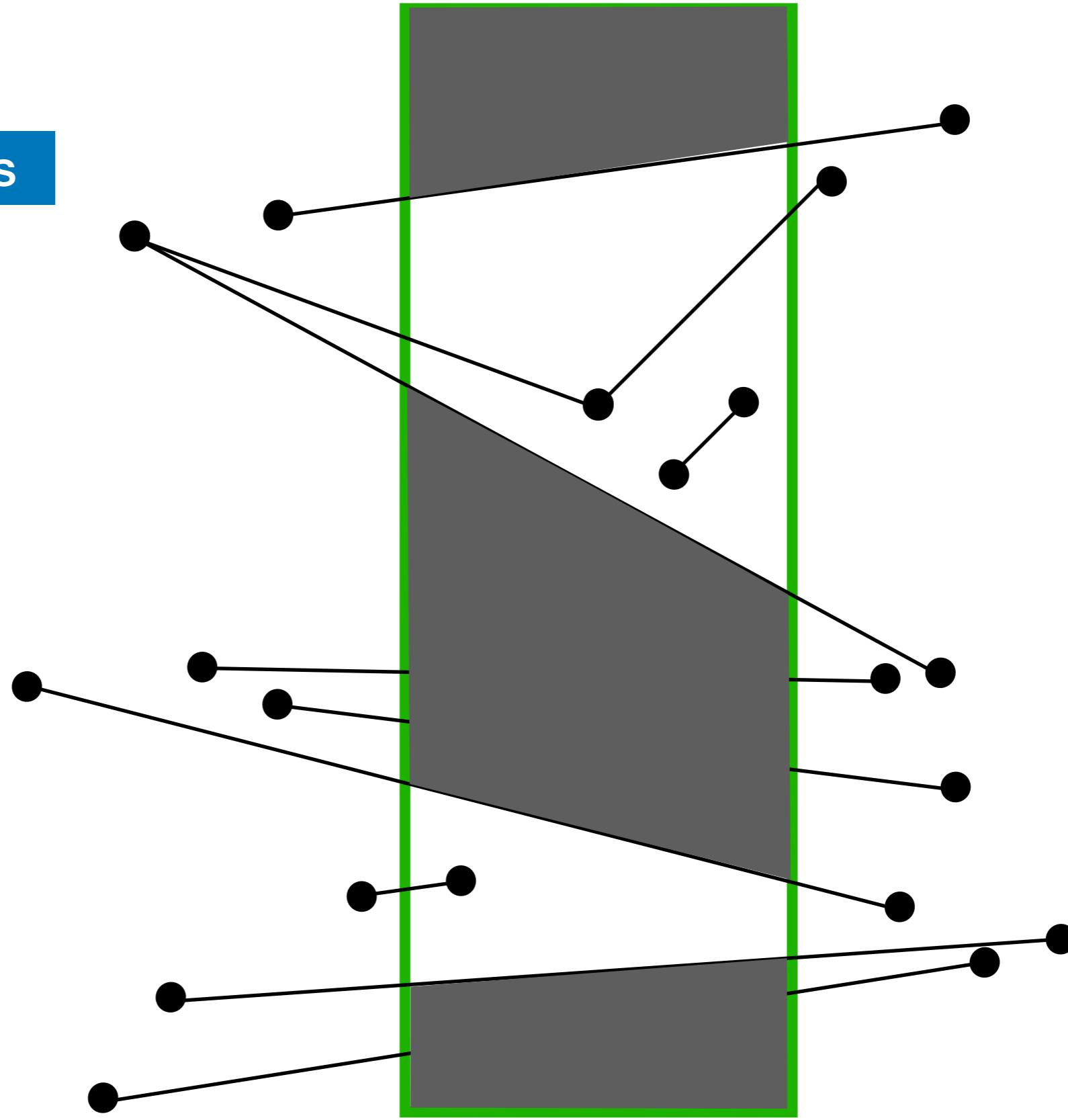
Dividir a la franja  
en regiones



## Algoritmo

Divide y vencerás

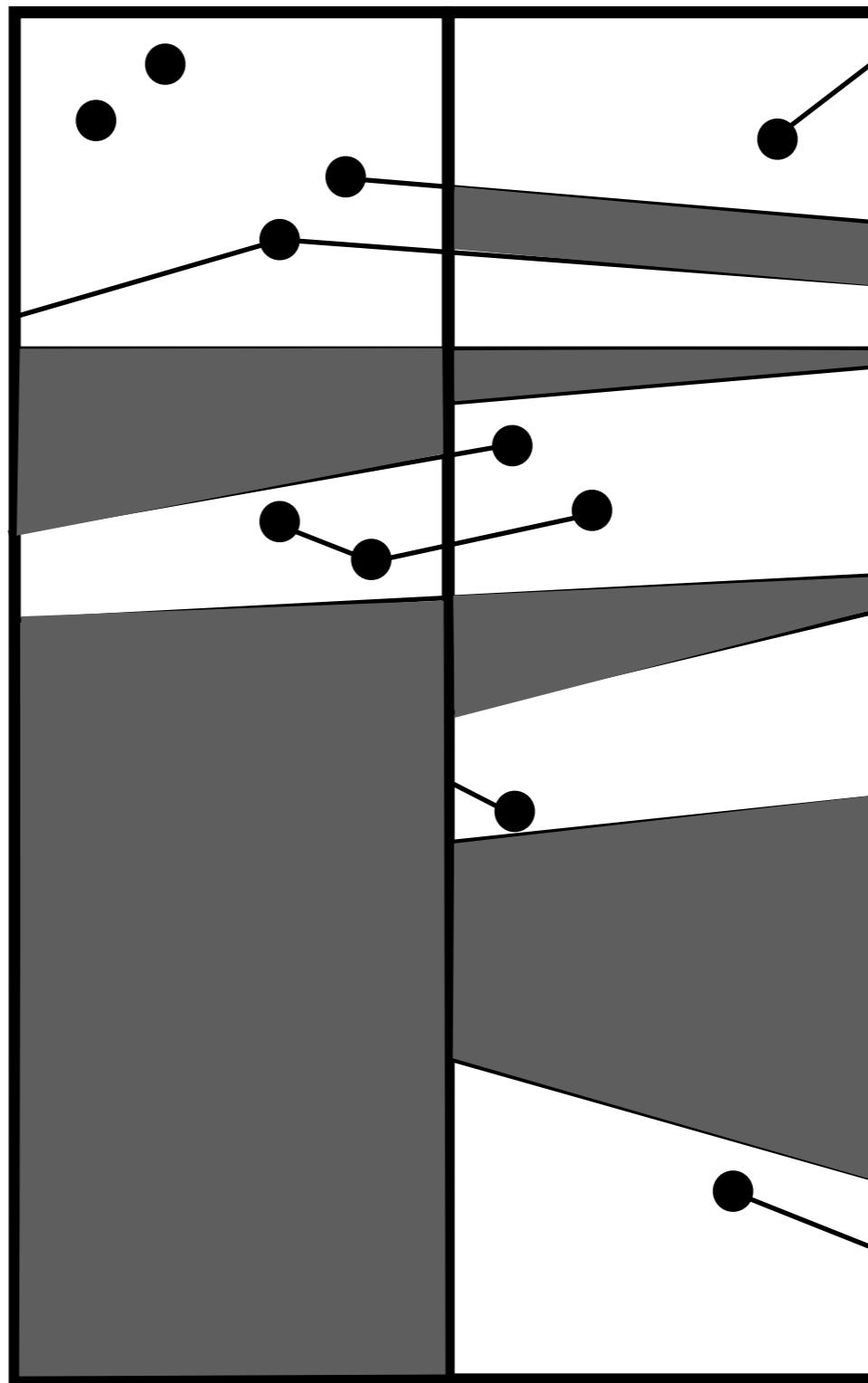
Dividir a la franja  
en regiones



## Algoritmo

Divide y vencerás

Control de las regiones

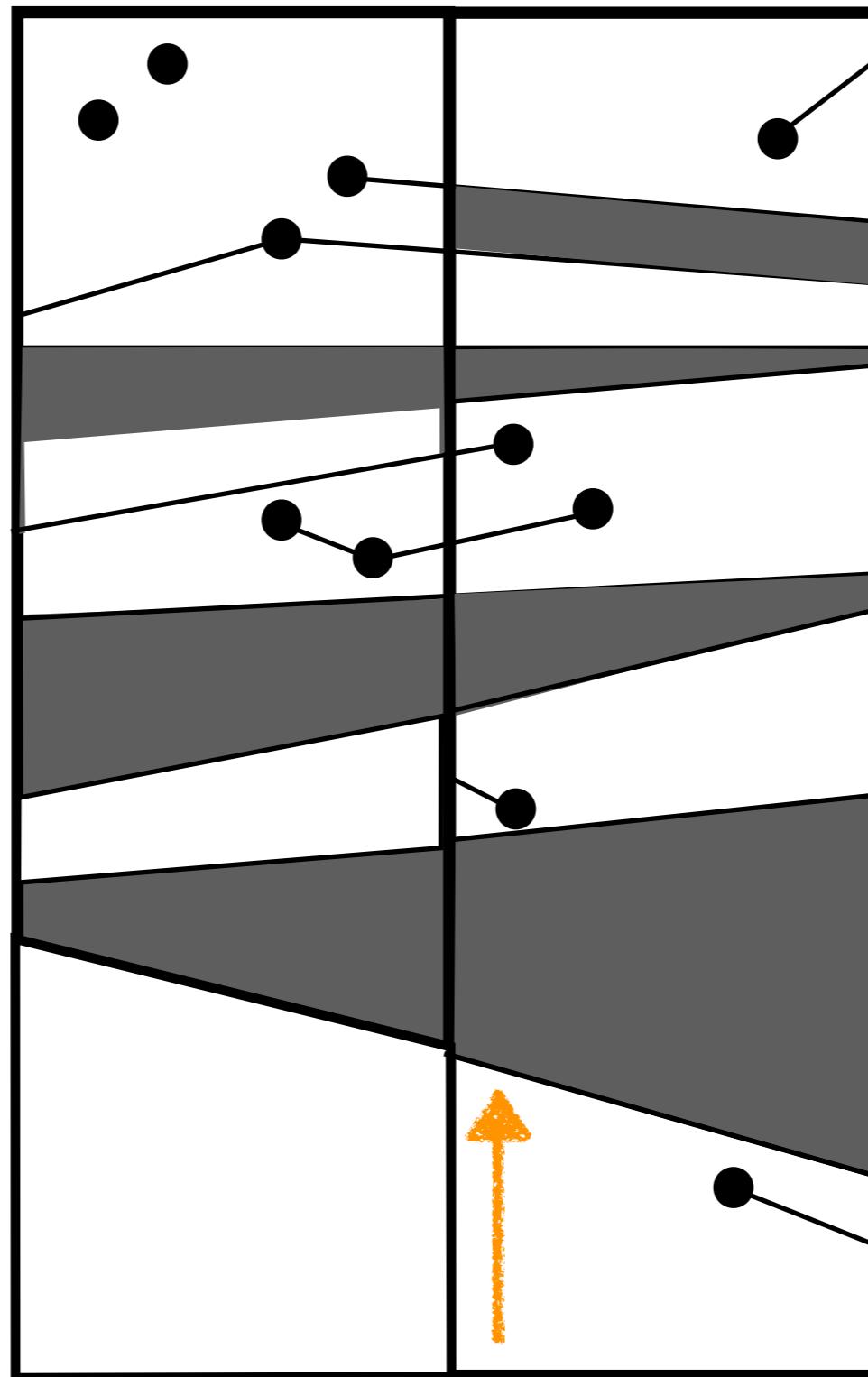


## Algoritmo

Divide y vencerás

Control de las regiones

$\mathcal{O}(v + h)$



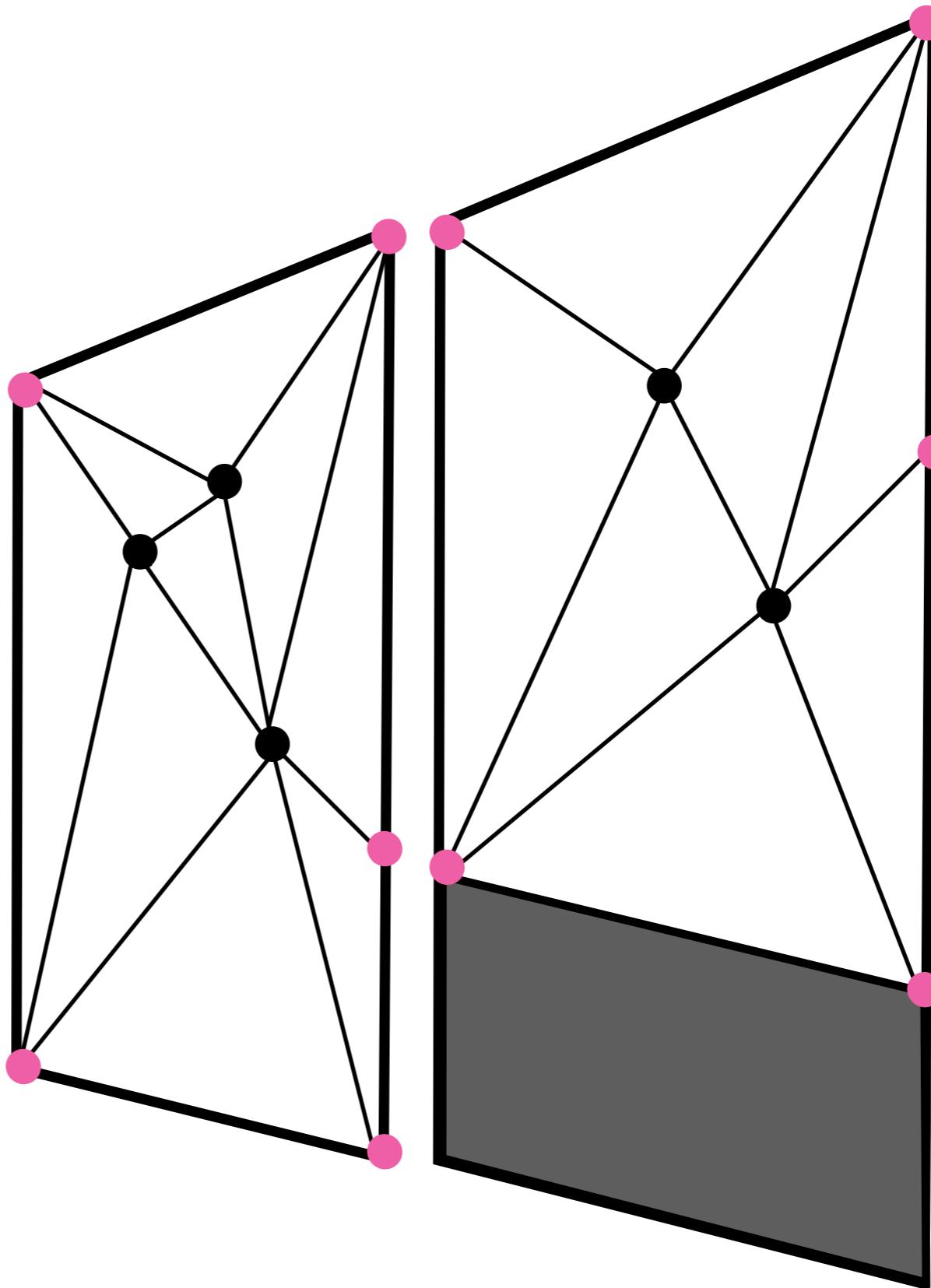
## Algoritmo

Divide y vencerás

Mezcla

Introducir vértices falsos

$\mathcal{O}(v + h)$

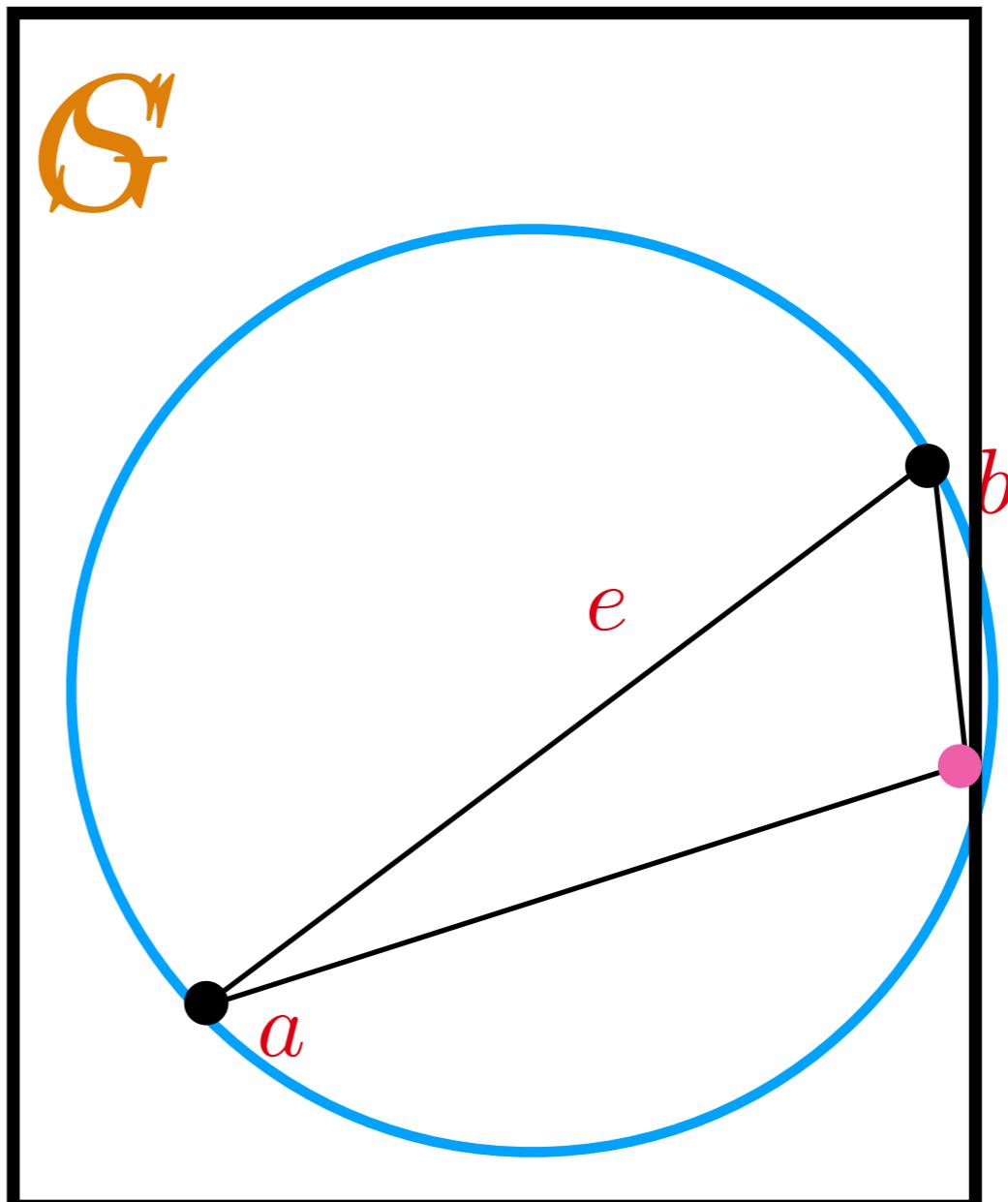


## Algoritmo

Divide y vencerás

Mezcla

Introducir vértices falsos

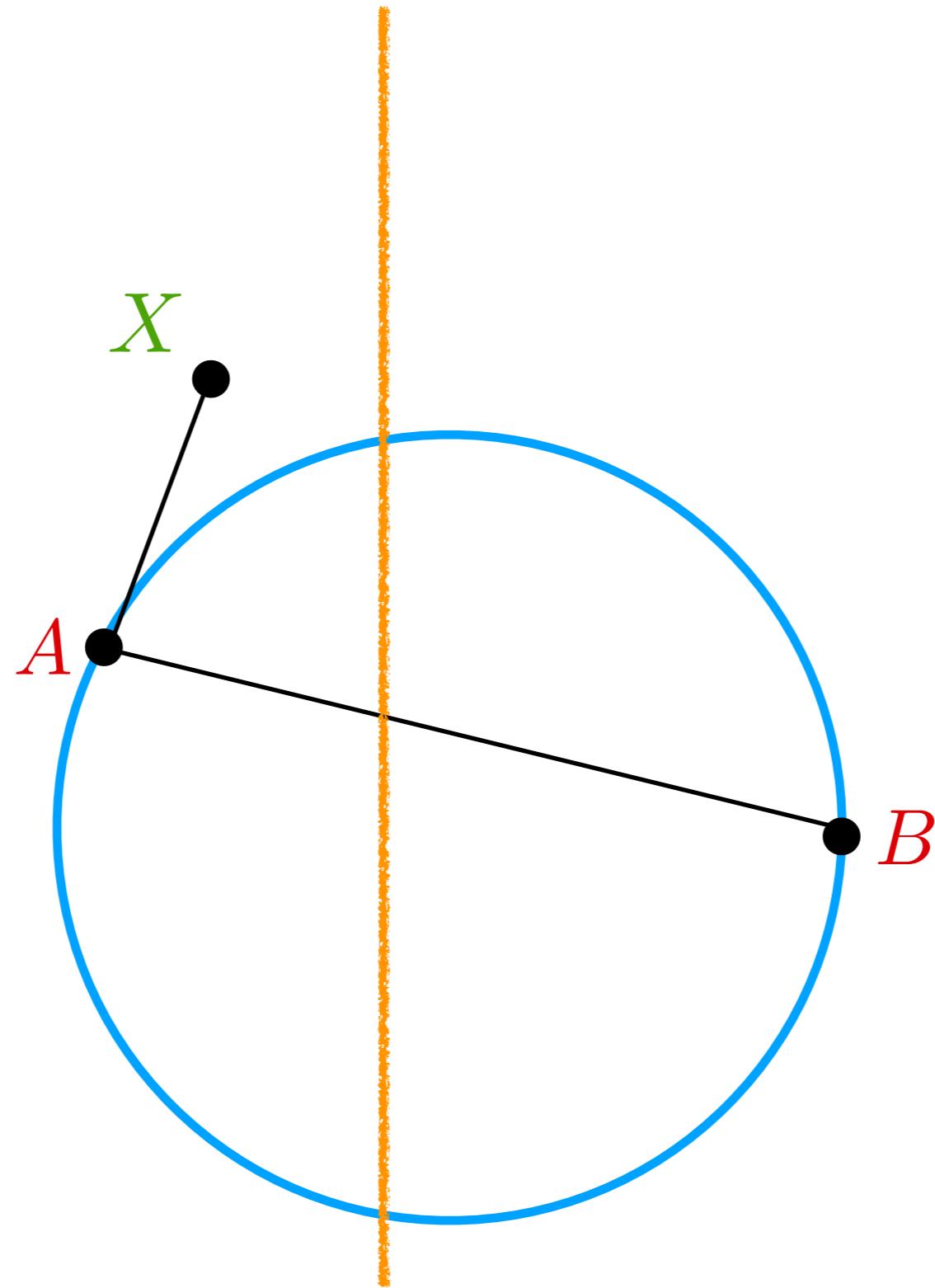


$$e = (a, b) \in E(CTD(G)) \Rightarrow e \in E(CTD(S)), \forall \text{ franja } S$$

## Algoritmo

Divide y vencerás

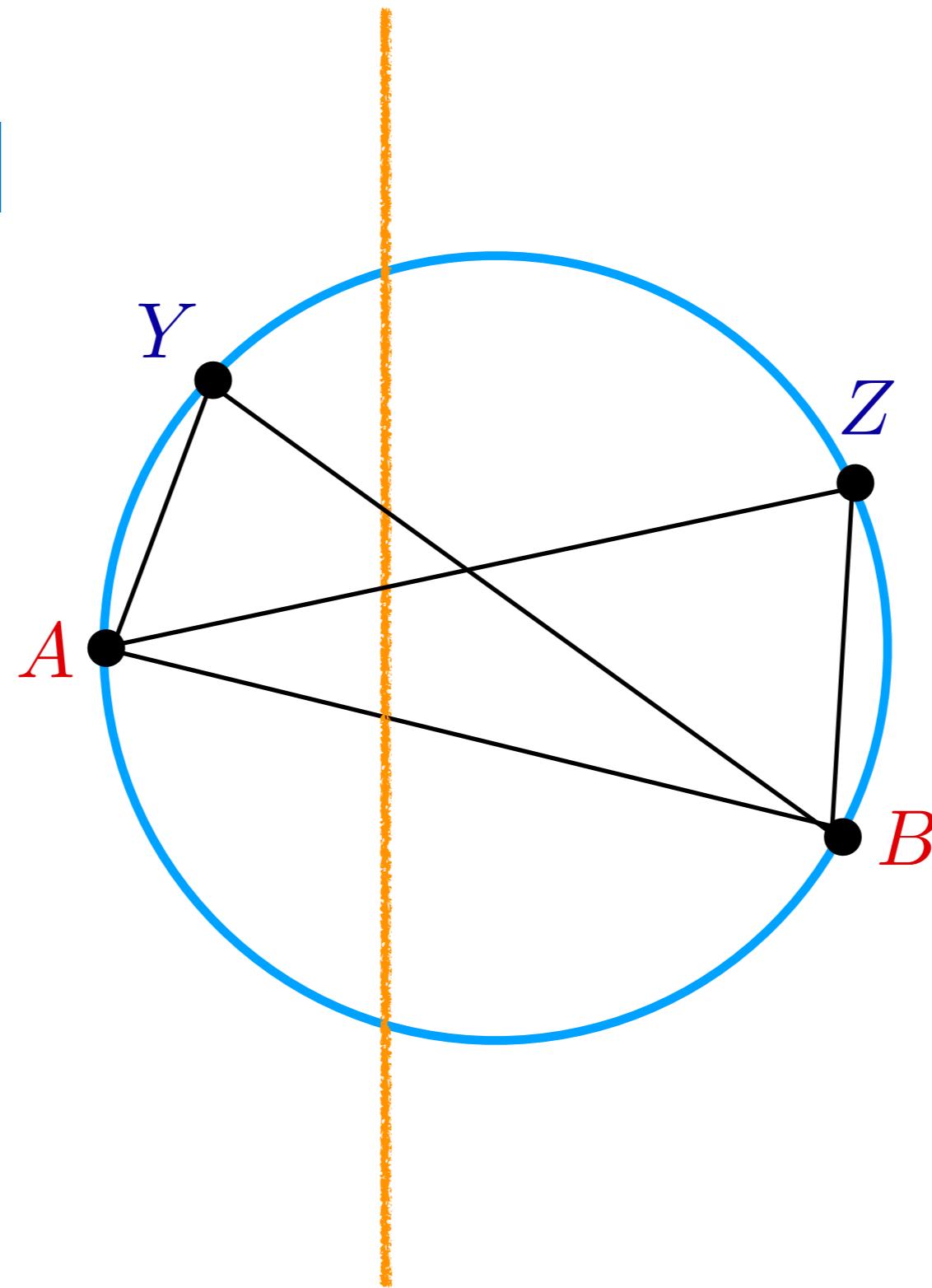
Mezcla



## Algoritmo

Divide y vencerás

Mezcla



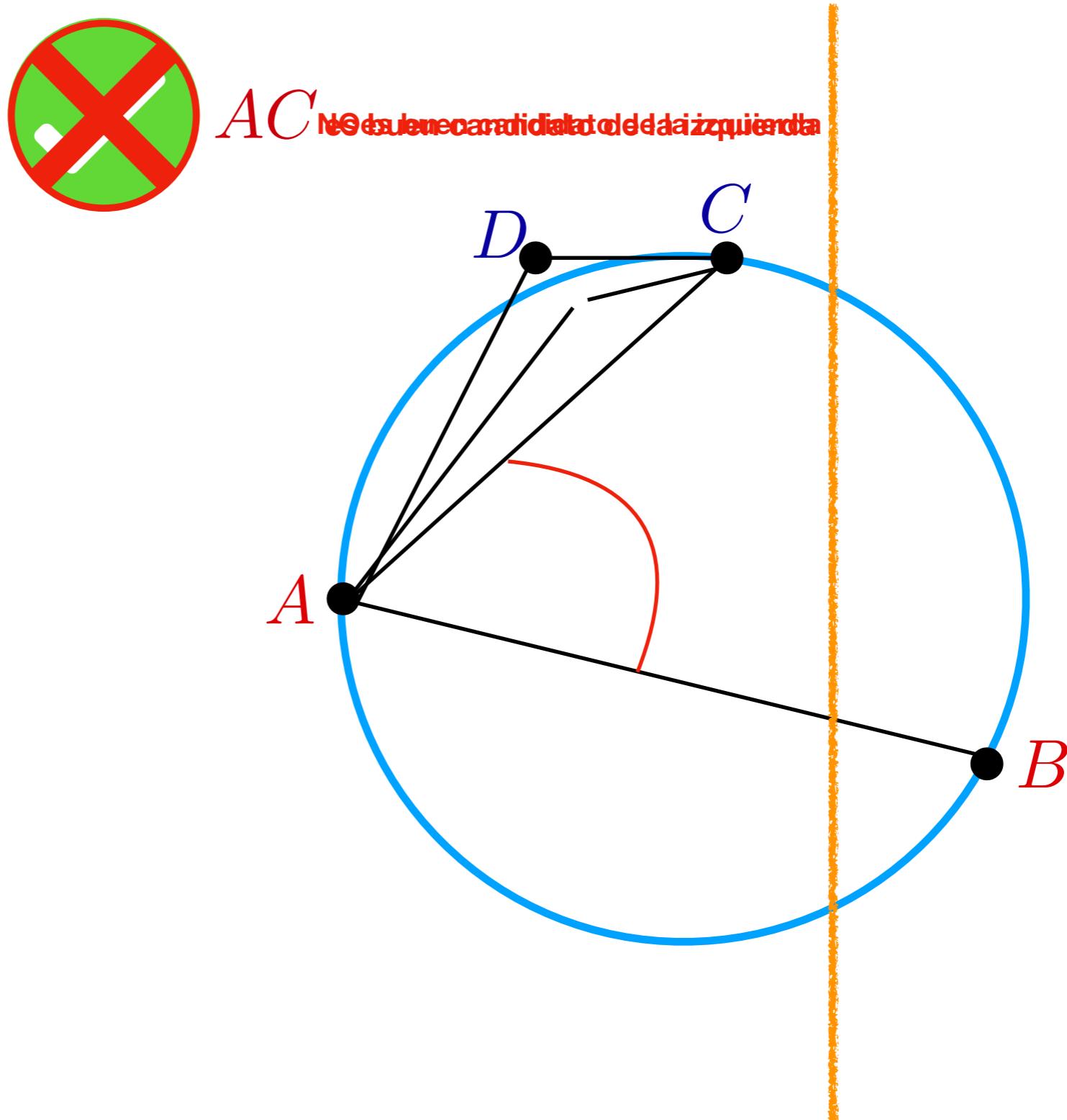
## Algoritmo

Divide y vencerás

Mezcla

Encontrar al mejor

candidato de cada lado

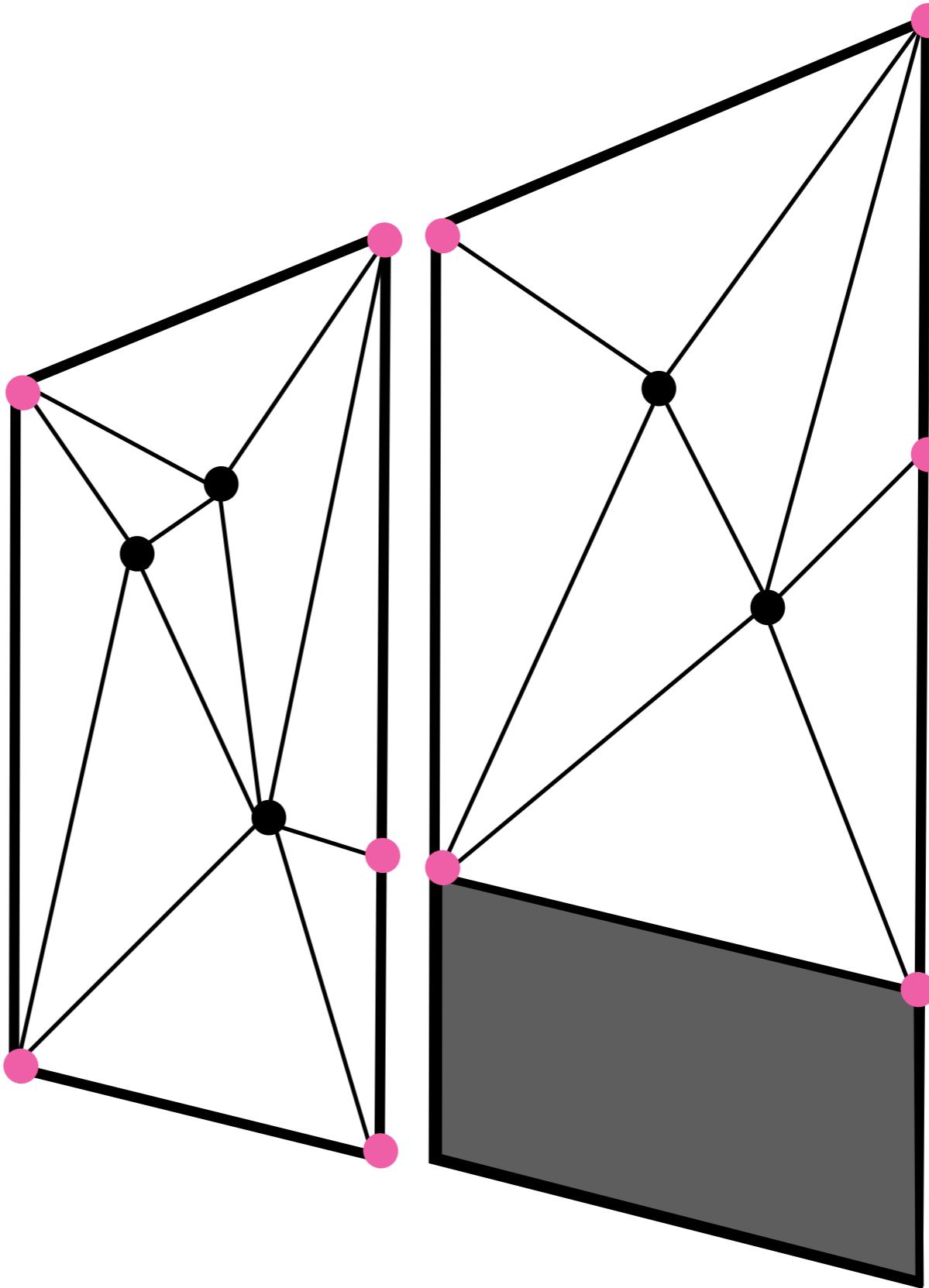


## Algoritmo

Divide y vencerás

Mezcla

1. Quitar vértices falsos.

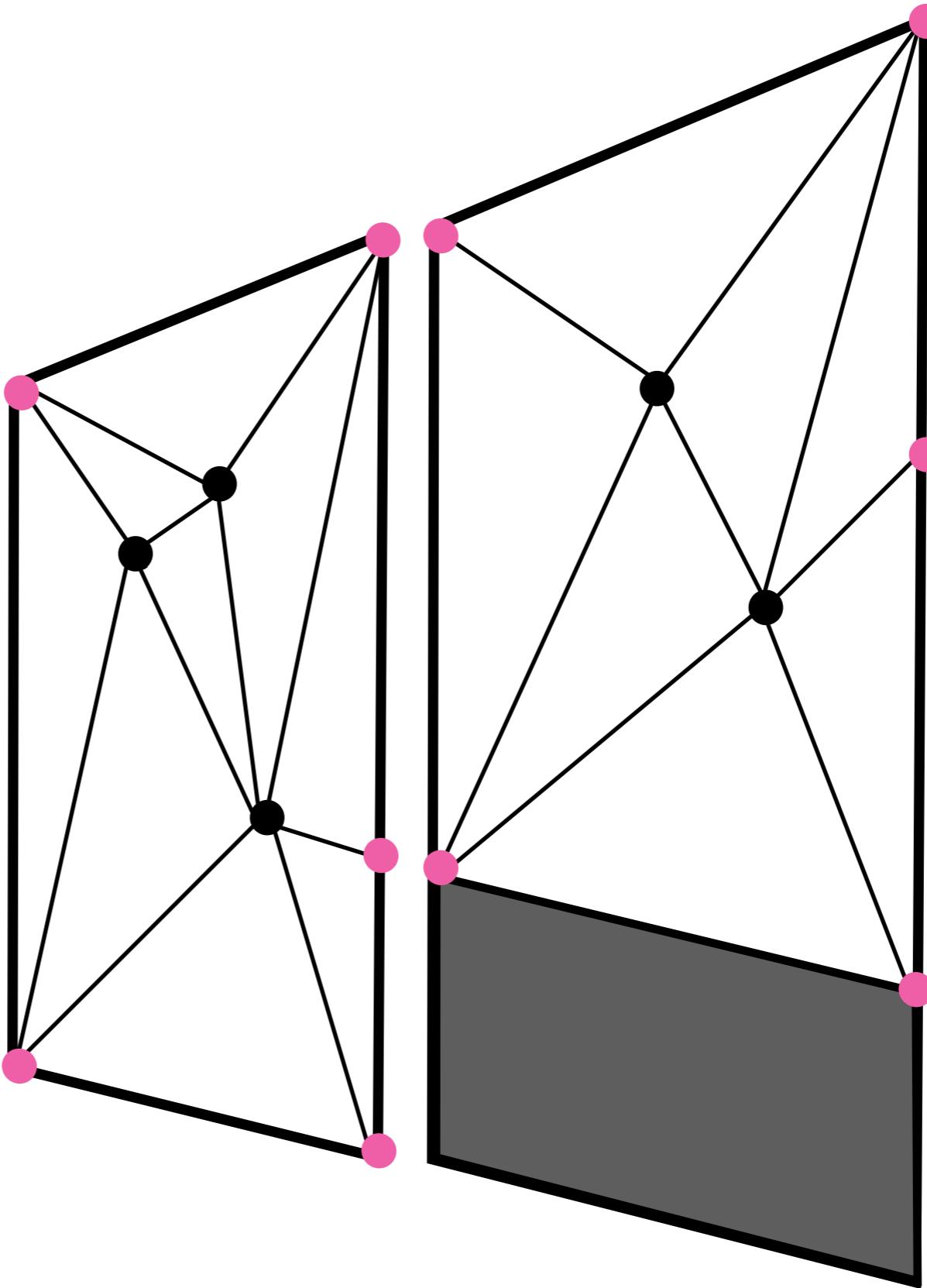


## Algoritmo

Divide y vencerás

Mezcla

1. Quitar vértices falsos.

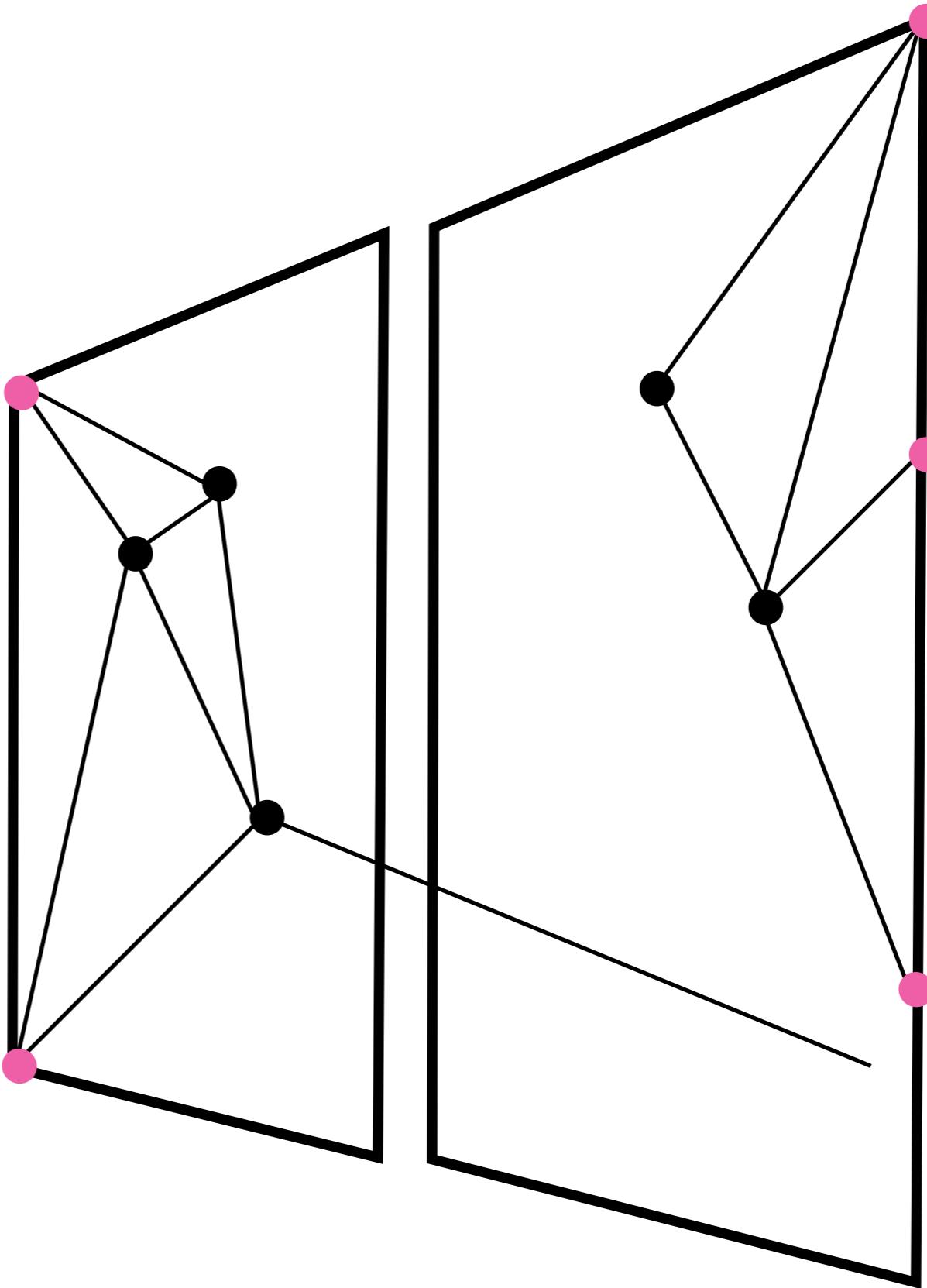


## Algoritmo

Divide y vencerás

Mezcla

1. Quitar vértices falsos.



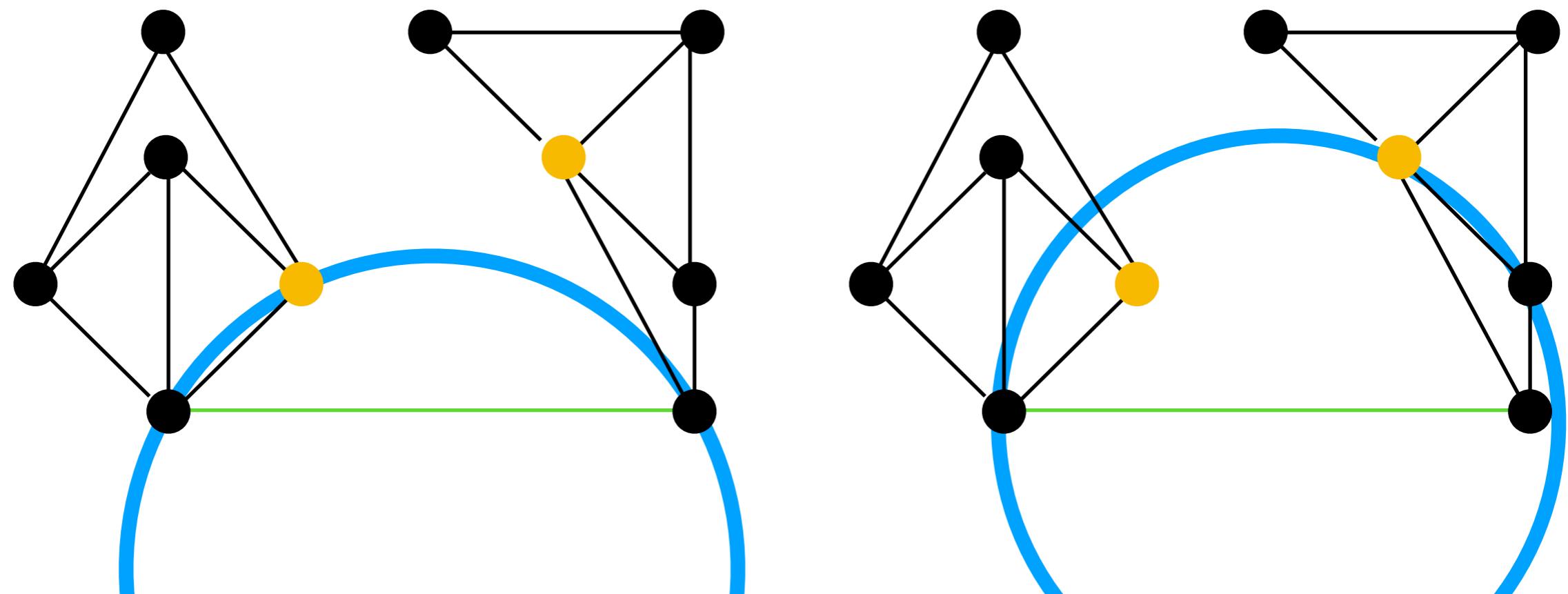
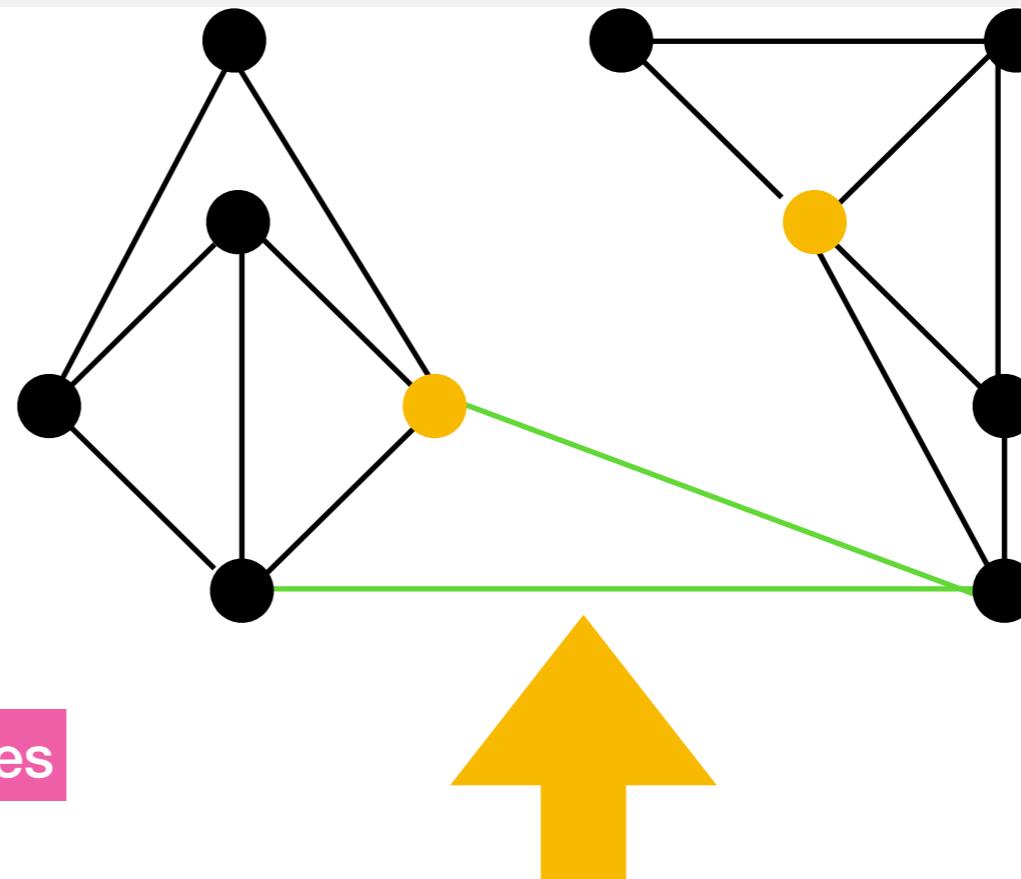
## Algoritmo

Divide y vencerás

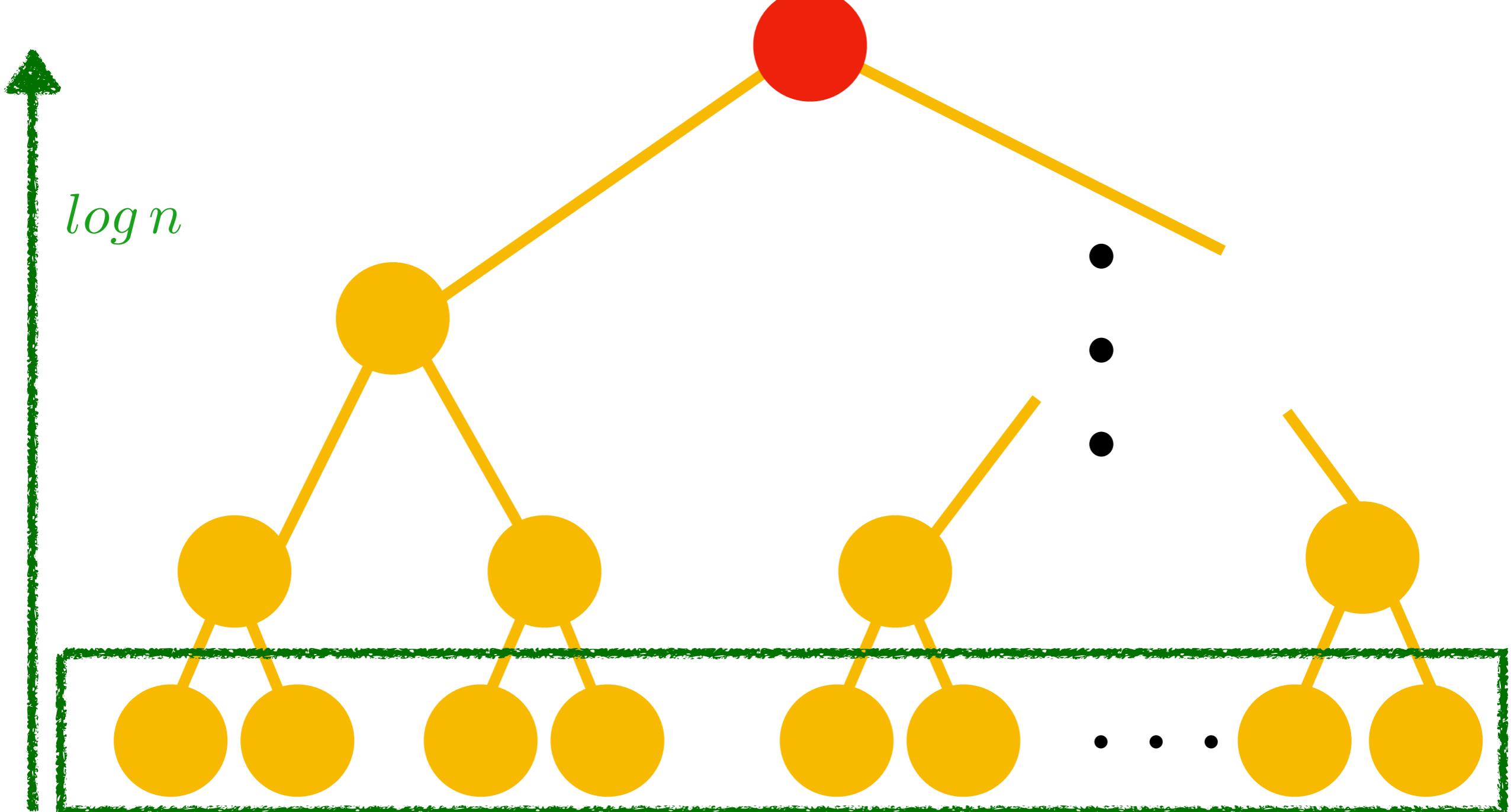
Mezcla

1. Quitar vértices falsos.

2. Mezclar CDTs de franjas adyacentes



## Complejidad



$$\mathcal{O}(|V| + |E|) = \mathcal{O}(n + n) = \mathcal{O}(n)$$

## Complejidad

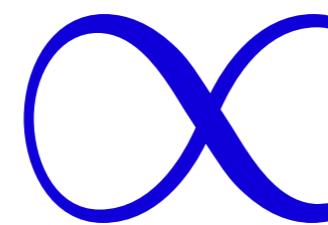
$\mathcal{O}(n \log n)$

## Complejidad

$$\Theta(n \log n)$$

## Complejidad

Ordenamiento



Triangulación de Delaunay

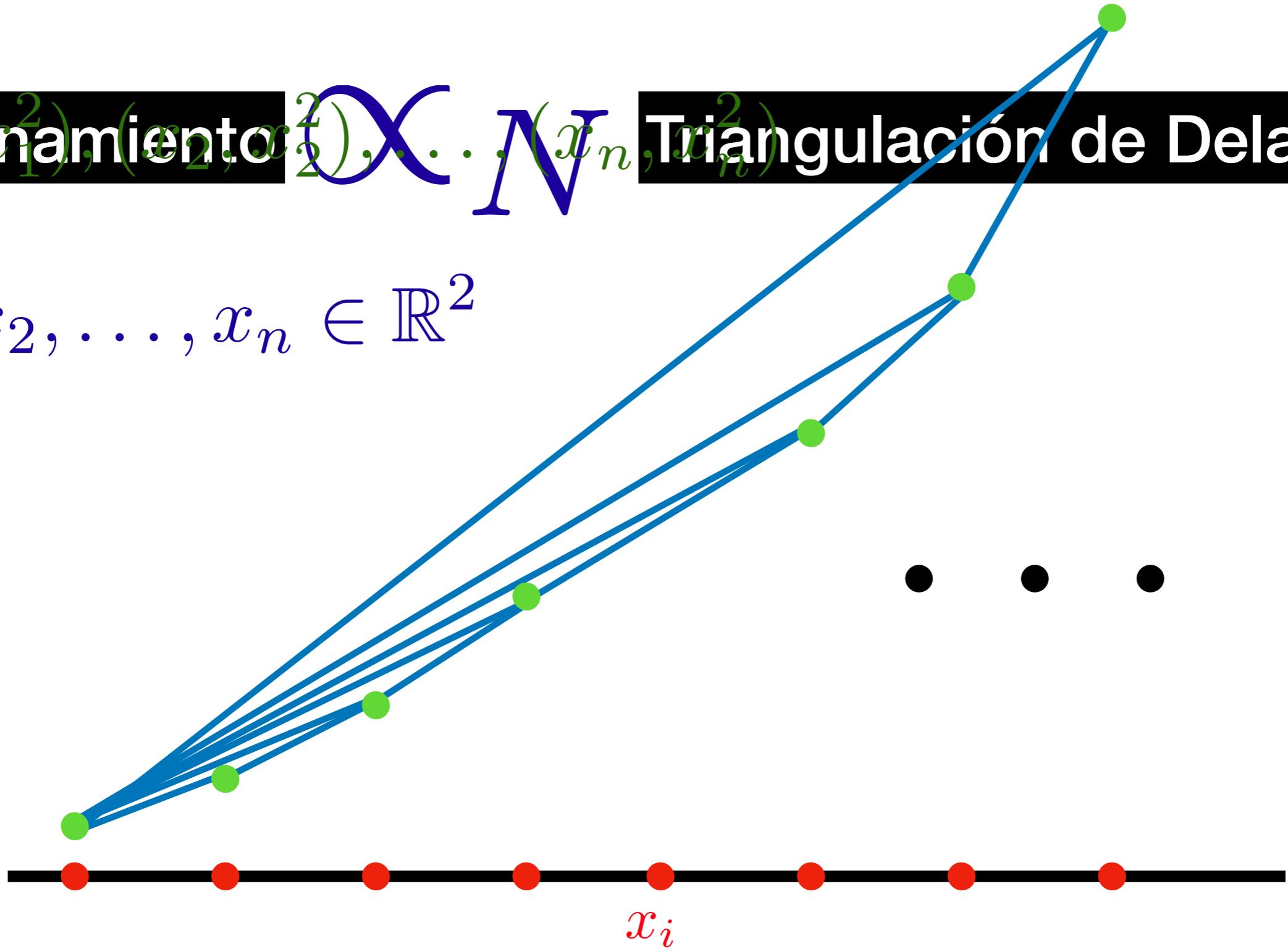
$$x_1, x_2, \dots, x_n \in \mathbb{R}^2$$



# Complejidad

(Ordenamiento)  $\propto N$  (Triangulación de Delaunay)

$$x_1, x_2, \dots, x_n \in \mathbb{R}^2$$



# Complejidad

$$\Omega(n \log n)$$