

Neural networks for classification

Inteligencia Artificial

3° INF



Supervised learning: classification

Machine learning by **induction from labeled data**

$$\mathcal{D} = \{(\mathbf{x}_n, c_n)\}_{n=1}^N$$

$\mathbf{x} \in \mathcal{X}$: vector of **attributes**, features, independent variables,

Bias term
 $x_{n0} = 1$

input variables. covariates...

$$\mathbf{x}_n^T = (x_{n0} \ x_{n1} \ x_{n2} \ \dots \ x_{nD}) \text{ [(D + 1)-dimensional vector]}$$

$c \in \mathcal{C}$: (class) **label**, dependent variable, outcome, target, ...

Classification: Labels c are **discrete** (e.g. $c \in \{C_1, \dots, C_K\}$)

Learning algorithm: \mathcal{L}

\mathbf{w} : Model parameters

$$\mathcal{L}: \mathcal{D} = \{(\mathbf{x}_n, c_n)\}_{n=1}^N \rightarrow h(\cdot; \mathbf{w})$$

$$h(\cdot; \mathbf{w}): \mathbf{x} \in \mathcal{X} \rightarrow h(\mathbf{x}; \mathbf{w}) \in \{C_1, \dots, C_K\}$$

Binary classification

n	x_{n1}	x_{n2}	...	x_{nD}	c_n
1	2.3	0	...	10.3	C_0
2	2.5	1	...	13.1	C_1
3	2.6	0	...	-2.7	C_1
4	2.7	-1	...	-5.4	C_0
5	2.9	0	...	2.1	C_1
6	3.1	0	...	-10.9	C_0

Binary classification

0-1 encoding of the **labeled data**

$$\mathcal{D} = \{(\mathbf{x}_n, c_n)\}_{n=1}^N \Rightarrow \mathcal{D} = \{(\mathbf{x}_n, t_n)\}_{n=1}^N; \quad t_n = \begin{cases} 0 & \text{if } c_n = C_0 \\ 1 & \text{if } c_n = C_1 \end{cases}$$

$$\mathcal{L}: \mathcal{D} = \{(\mathbf{x}_n, c_n)\}_{n=1}^N \rightarrow o(\cdot; \mathbf{w})$$

$$z(\cdot; \mathbf{w}): \mathbf{x} \in \mathcal{X} \rightarrow z(\mathbf{x}; \mathbf{w}) \in \mathbb{R}$$

$$o(\mathbf{x}; \mathbf{w}) = \varphi^{(o)}(z(\mathbf{x}; \mathbf{w})) \in [0,1]$$

- The output $o(\mathbf{x}; \mathbf{w})$ is an estimate of the class C_1 posterior

Discriminative model

$$\hat{p}(C_1 | \mathbf{x}, \mathbf{w}) = \varphi^{(o)}(z(\mathbf{x}; \mathbf{w}))$$

Logistic regression: $\varphi^{(o)}(z) = \sigma(z) = \frac{1}{1+e^{-z}}$

Probit regression: $\varphi^{(o)}(z) = \Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z e^{-\frac{y^2}{2}} dy$

Binary classification: 0-1 encoding

n	x_{n1}	x_{n2}	...	x_{nD}	t_n
1	2.3	0	...	10.3	0
2	2.5	1	...	13.1	1
3	2.6	0	...	-2.7	1
4	2.7	-1	...	-5.4	0
5	2.9	0	...	2.1	1
6	3.1	0	...	-10.9	0

From posteriors to decisions

- To output the class label, we compare the posterior of C_1 with some threshold in the interval $[0,1]$

$$h(\mathbf{x}; \mathbf{w}) = \begin{cases} C_1 & \text{if } p(C_1|\mathbf{x}, \mathbf{w}) \geq \text{threshold} \\ C_0 & \text{if } p(C_1|\mathbf{x}, \mathbf{w}) < \text{threshold} \end{cases}$$

- If misclassification costs are equal:

- Error if prediction is C_1 : $p(C_0|\mathbf{x}, \mathbf{w})$
- Error if prediction is C_0 : $p(C_1|\mathbf{x}, \mathbf{w})$

Optimal (minimal error)
classification rule

Predict

C_1 when $p(C_0|\mathbf{x}, \mathbf{w}) \leq p(C_1|\mathbf{x}, \mathbf{w}) \Rightarrow p(C_1|\mathbf{x}, \mathbf{w}) \geq 1/2$

C_0 otherwise $\Rightarrow p(C_1|\mathbf{x}, \mathbf{w}) < 1/2$

Optimal threshold

Unequal classification costs

Cost of classifying an example of class C_0 as class C_1

- Cost if prediction is C_1 : $p(C_0|\mathbf{x}, \mathbf{w})cost_{10} + p(C_1|\mathbf{x}, \mathbf{w})cost_{11}$
- Cost if prediction is C_0 : $p(C_0|\mathbf{x}, \mathbf{w})cost_{00} + p(C_1|\mathbf{x}, \mathbf{w})cost_{01}$

C_1 prediction cost = C_0 prediction cost

Cost of correctly classifying a class C_0 example (typically, 0)

Cost of classifying an example of class C_1 as class C_0

Minimal cost classification rule:

Predict

C_1 when $p(C_1|\mathbf{x}, \mathbf{w}) \geq \text{threshold}^*$

C_0 when $p(C_1|\mathbf{x}, \mathbf{w}) < \text{threshold}^*$

Optimal threshold

E.g. If $cost_{10} - cost_{00} = 2(cost_{01} - cost_{11})$
 $\text{threshold}^* = 2/3$ (it is less likely to predict C_1)

$$\text{threshold}^* = \frac{cost_{10} - cost_{00}}{cost_{10} - cost_{00} + cost_{01} - cost_{11}}$$

Learning by maximum likelihood

Samples assumed to be iid (independent identically distributed)

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \mathcal{L}(\mathbf{w})$$

- Likelihood of the model, given $\mathcal{D} = \{(\mathbf{x}_n, t_n)\}_{n=1}^N$

$$\mathcal{L}(\mathbf{w}) = \hat{P}(\{t_n\}_{n=1}^N | \{\mathbf{x}_n\}_{n=1}^N, \mathbf{w}) = \prod_{n=1}^N \hat{p}(t_n | \mathbf{x}_n, \mathbf{w}) =$$

Factorizes because samples are assumed to be independent

$$= \prod_{n=1}^N (\hat{p}(C_0 | \mathbf{x}_n, \mathbf{w}))^{1-t_n} (\hat{p}(C_1 | \mathbf{x}_n, \mathbf{w}))^{t_n}$$

Estimate of class posterior

Same distribution: samples are assumed to be identically dist.

- Log-likelihood function

$$\log \mathcal{L}(\mathbf{w}) = \sum_{n=1}^N ((1 - t_n) \log \hat{p}(C_0 | \mathbf{x}_n, \mathbf{w}) + t_n \log \hat{p}(C_1 | \mathbf{x}_n, \mathbf{w}))$$

Same maximizer as $\mathcal{L}(\mathbf{w})$ (log is monotone)

Minimization of the cross-entropy error

$$\mathbf{w}^* = \arg \min_{\mathbf{w}} CE(\mathbf{w})$$

- Cross-entropy error

$$CE(\mathbf{w}) = -\log \mathcal{L}(\mathbf{w})$$

Same as maximizer of $\mathcal{L}(\mathbf{w})$

$$\begin{aligned} &= -\sum_{n=1}^N \left((1 - t_n) \log \hat{p}(C_0 | \mathbf{x}_n, \mathbf{w}) + t_n \log \hat{p}(C_1 | \mathbf{x}_n, \mathbf{w}) \right) \\ &= -\sum_{n=1}^N \left((1 - t_n) \log(1 - \hat{p}(C_1 | \mathbf{x}_n, \mathbf{w})) + t_n \log \hat{p}(C_1 | \mathbf{x}_n, \mathbf{w}) \right) \end{aligned}$$

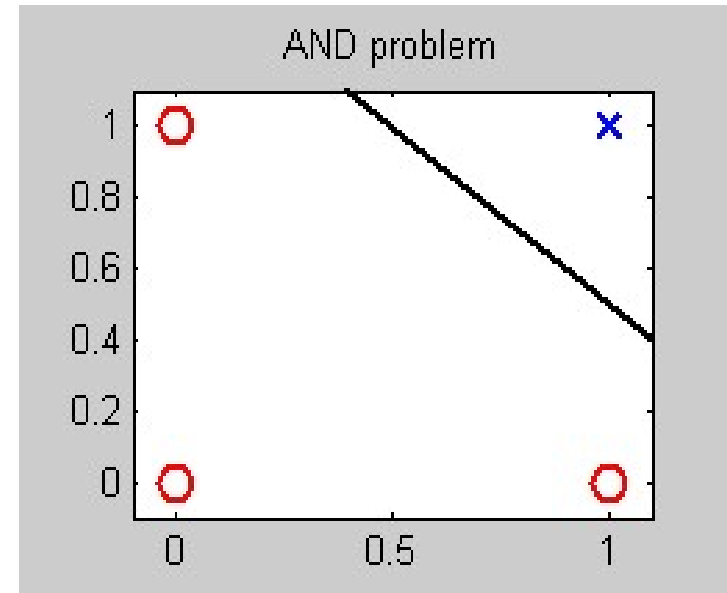
- Discriminative model: $\hat{p}(C_1 | \mathbf{x}, \mathbf{w}) = \varphi^{(o)}(z(\mathbf{x}_n; \mathbf{w}))$

$$CE(\mathbf{w}) = -\sum_{n=1}^N \left((1 - t_n) \log \left(1 - \underbrace{\varphi^{(o)}(z(\mathbf{x}_n; \mathbf{w}))}_{\hat{p}(C_0 | \mathbf{x}, \mathbf{w})} \right) + t_n \log \left(\underbrace{\varphi^{(o)}(z(\mathbf{x}_n; \mathbf{w}))}_{\hat{p}(C_1 | \mathbf{x}, \mathbf{w})} \right) \right)$$

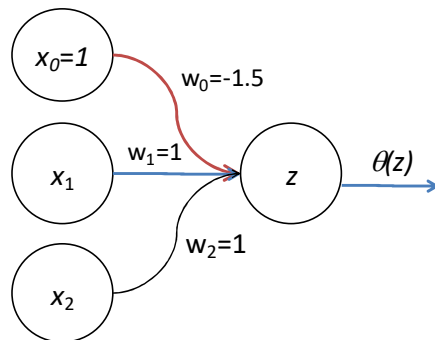
AND: A linearly separable problem

■ The AND classification problem

x_1	x_2	t
0	0	0
0	1	0
1	0	0
1	1	1



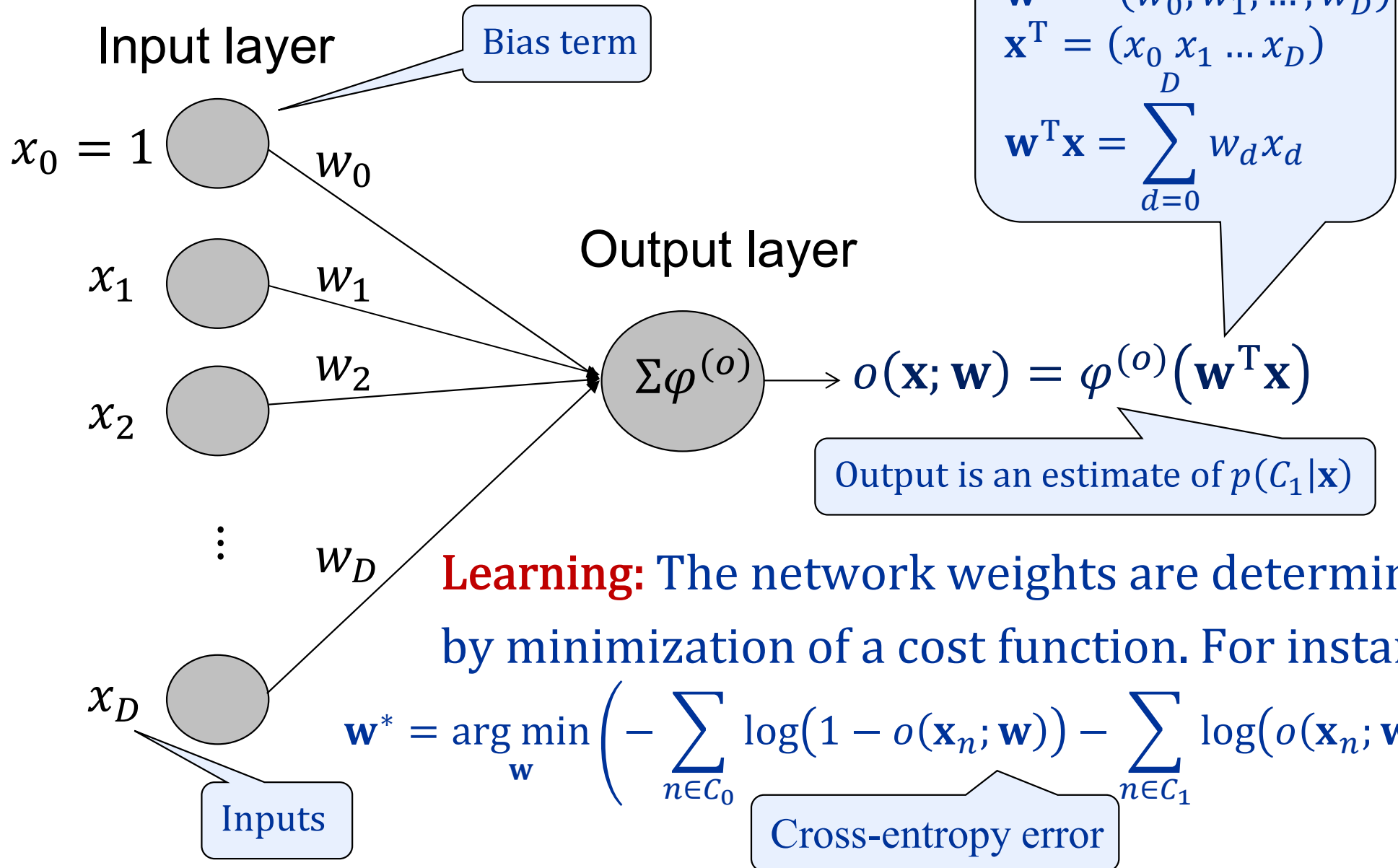
■ Single-layer perceptron



x_1	x_2	$z = w_0x_0 + w_1x_1 + w_2x_2$	$h(\mathbf{x}) = \theta(z) = \begin{cases} 1 & \text{if } z > 0 \\ 0.5 & \text{if } z = 0 \\ 0 & \text{if } z < 0 \end{cases}$
0	0	-1.5	0
0	1	-0.5	0
1	0	-0.5	0
1	1	0.5	1

Single layer perceptron

Can solve only linearly separable problems



Logistic regression

- Class posteriors

$$p(C_1|\mathbf{x}, \mathbf{w}) = \frac{1}{1 + e^{-z(\mathbf{x}; \mathbf{w})}}$$

$$p(C_0|\mathbf{x}, \mathbf{w}) = 1 - p(C_1|\mathbf{x}, \mathbf{w}) = \frac{e^{-z(\mathbf{x}; \mathbf{w})}}{1 + e^{-z(\mathbf{x}; \mathbf{w})}} = \frac{1}{1 + e^{z(\mathbf{x}; \mathbf{w})}}$$

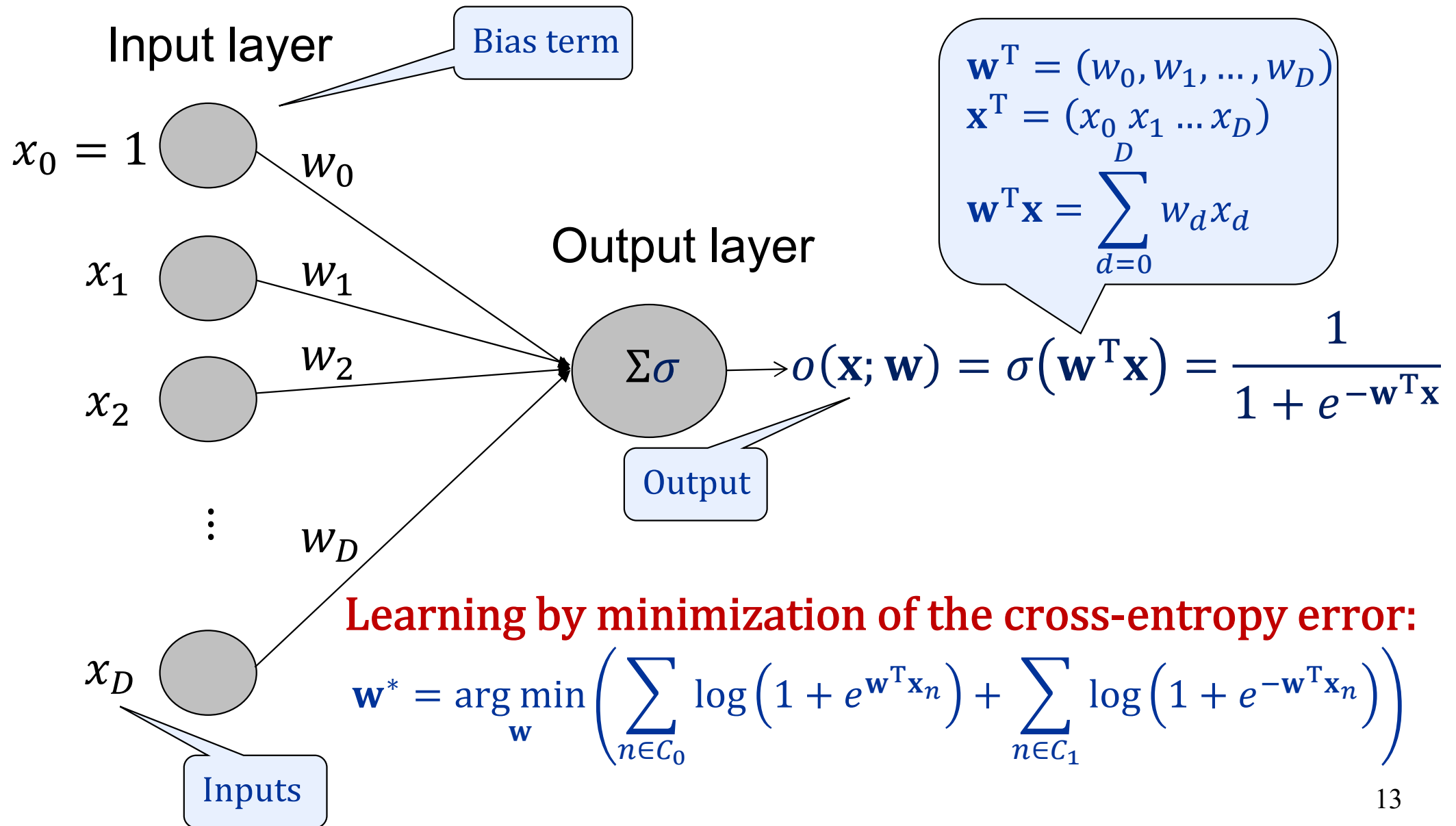
- Log-odds: $z(\mathbf{x}; \mathbf{w}) = \log \frac{p(C_1|\mathbf{x}, \mathbf{w})}{p(C_0|\mathbf{x}, \mathbf{w})}$

$$\begin{aligned}\mathbf{w}^T &= (w_0, w_1, \dots, w_D) \\ \mathbf{x}^T &= (x_0 \ x_1 \ \dots \ x_D)\end{aligned}$$

- Linear model for log-odds: $z(\mathbf{x}; \mathbf{w}) = \mathbf{w}^T \mathbf{x} = \sum_{d=0}^D w_d x_d$

Single-layer perceptron!

Single layer perceptron: logistic regression



Cross entropy error for logistic regression

$$\mathbf{w}^* = \arg \min_{\mathbf{w}} CE(\mathbf{w})$$

$$\frac{\partial \sigma(\mathbf{w}^T \mathbf{x}_n)}{\partial \mathbf{w}} = \mathbf{x}_n \sigma(\mathbf{w}^T \mathbf{x}_n) (1 - \sigma(\mathbf{w}^T \mathbf{x}_n))$$

■ Cross-entropy error

$$CE(\mathbf{w}) = - \sum_{n=1}^N \left((1 - t_n) \log(1 - \sigma(\mathbf{w}^T \mathbf{x}_n)) + t_n \log \sigma(\mathbf{w}^T \mathbf{x}_n) \right)$$

■ Gradient of the cross-entropy error

$$\frac{\partial}{\partial \mathbf{w}} CE(\mathbf{w}) = \sum_{n=1}^N \left((1 - t_n) \mathbf{x}_n \sigma(\mathbf{w}^T \mathbf{x}_n) - t_n \mathbf{x}_n (1 - \sigma(\mathbf{w}^T \mathbf{x}_n)) \right)$$

$$\delta_n = \sigma(\mathbf{w}^T \mathbf{x}_n) - t_n$$

$$= \sum_{n=1}^N (\sigma(\mathbf{w}^T \mathbf{x}_n) - t_n) \mathbf{x}_n = \sum_{n=1}^N \delta_n \mathbf{x}_n$$

Single-layer perceptron: Batch learning

INPUT: Training instances: $\mathcal{D} = \{(\mathbf{x}_n, t_n)\}_{n=1}^N$

Learning parameter: $\eta > 0$

OUTPUT: $\mathbf{w}^* = \arg \min_{\mathbf{w}} CE(\mathbf{w})$

Attributes should be scaled!

1. Randomly initialize $\mathbf{w} \sim U[-0.5, 0.5]^{(D+1)}$

2. $n_{epoch} = 0$

2. While convergence criteria are not met

Similar to Rosenblatt!

$\delta_n = \sigma(\mathbf{w}^T \mathbf{x}_n) - t_n$
prediction error

2.1 Increment epoch counter: $n_{epoch} = n_{epoch} + 1$

2.2 Calculate the network outputs: $\sigma(\mathbf{w}^T \mathbf{x}_n); n = 1, \dots, N$

2.2 Calculate the gradient: $\frac{\partial}{\partial \mathbf{w}} CE(\mathbf{w}) = \sum_{n=1}^N \delta_n \mathbf{x}_n$

2.3 Update weights: $\mathbf{w} = \mathbf{w} - \eta \sum_{n=1}^N \delta_n \mathbf{x}_n$

Single-layer perceptron: Online learning

INPUT: Training instances: $\mathcal{D} = \{(\mathbf{x}_n, t_n)\}_{n=1}^N$

 Learning parameter: $\eta > 0$

OUTPUT: $\mathbf{w}^* = \arg \min_{\mathbf{w}} CE(\mathbf{w})$

1. Randomly initialize $\mathbf{w} \sim U[-0.5, 0.5]^{(D+1)}$

2. $n_{epoch} = 0$

3. While convergence criteria are not met

 3.1 Increment epoch counter: $n_{epoch} = n_{epoch} + 1$

 3.2 For $n = 1, \dots, N$

 Calculate the network output: $\sigma(\mathbf{w}^T \mathbf{x}_n)$

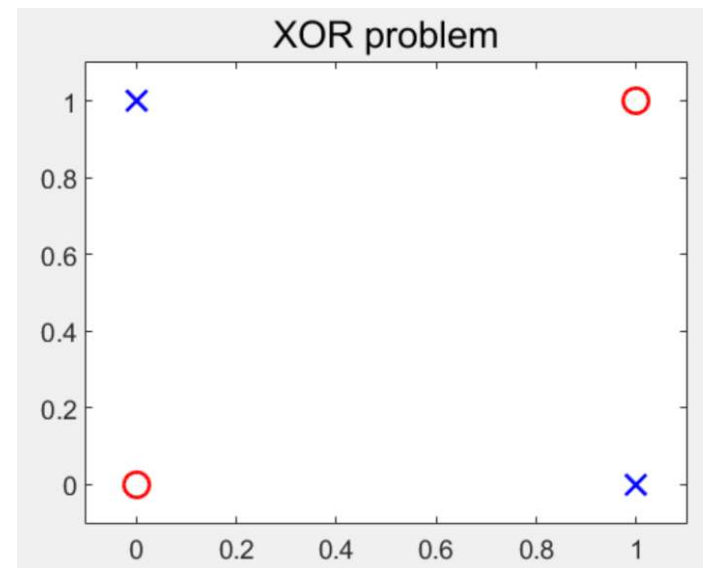
 Calculate prediction error: $\delta_n = \sigma(\mathbf{w}^T \mathbf{x}_n) - t_n$

 Update weights: $\mathbf{w} = \mathbf{w} - \eta \delta_n \mathbf{x}_n$

XOR: A non-linearly separable problem

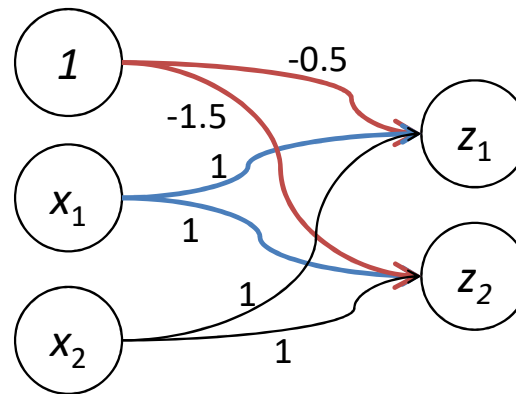
- The single-layer perceptron can only address problems that are linearly separable
- Therefore, the simple XOR problem, which is not linearly separable, cannot be solved using this learning machine.

x_1	x_2	t
0	0	1
0	1	0
1	0	0
1	1	1

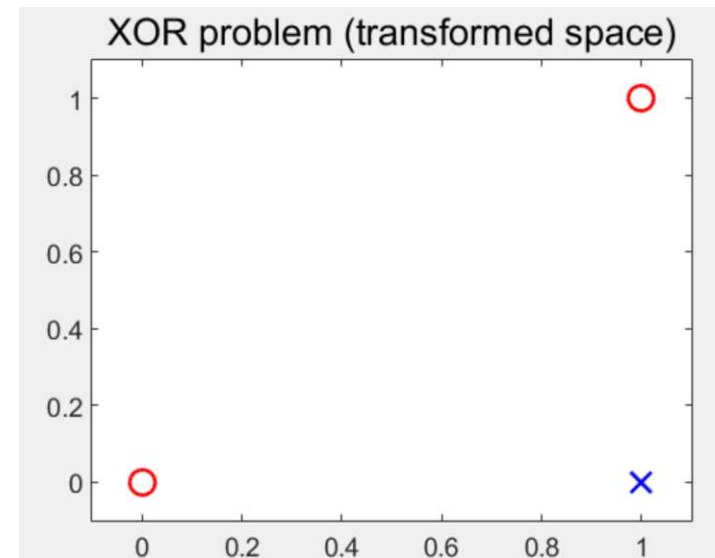


XOR: Non-linear feature construction

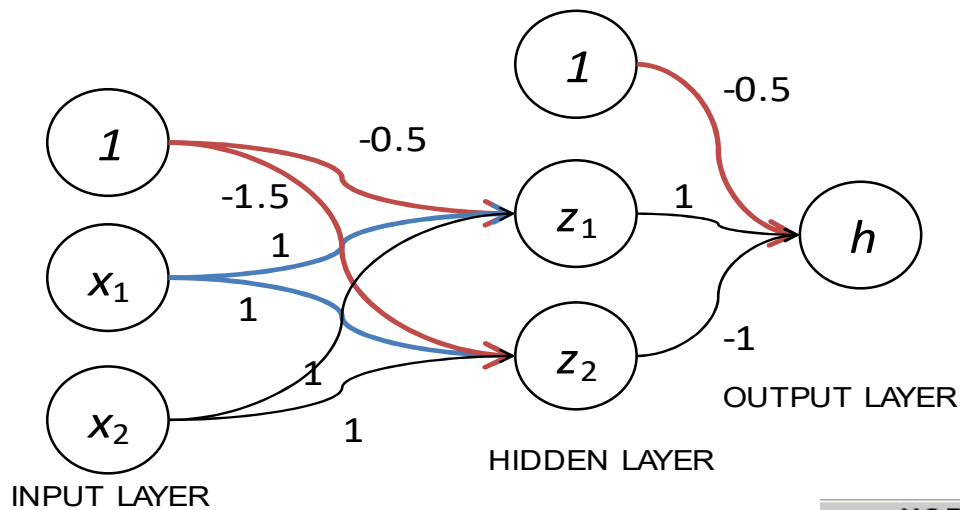
- Consider the XOR problem in a transformed feature space



x_1	x_2	z_1	z_2	t
0	0	0	0	0
0	1	1	0	1
1	0	1	0	1
1	1	1	1	0



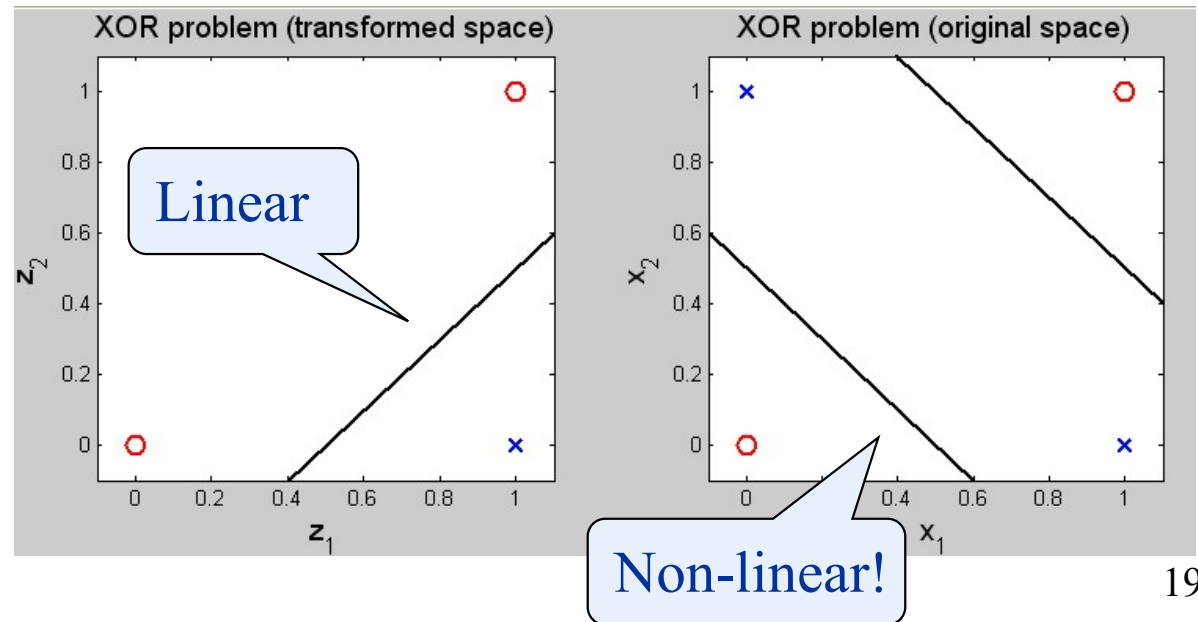
XOR: A linear model in feature space



$$\begin{cases} z_1 = \theta(x_1 + x_2 - 0.5) \\ z_2 = \theta(x_1 + x_2 - 1.5) \end{cases}$$

$$h = \theta(z_1 - z_2 - 0.5)$$

x_1	x_2	z_1	z_2	h
0	0	0	0	0
0	1	1	0	1
1	0	1	0	1
1	1	1	1	0



Multi-layer perceptron

$$\mathbf{x} = \begin{pmatrix} 1 \\ x_1 \\ \vdots \\ x_D \end{pmatrix}$$

Attribute
(input) vector

input to hidden
layer weights

$$\mathbf{V} = (\mathbf{v}_1 \ \mathbf{v}_2 \ \dots \ \mathbf{v}_J)$$

$$\mathbf{v}_j^T = (v_{0j} \ v_{1j} \ \dots \ v_{Dj});$$

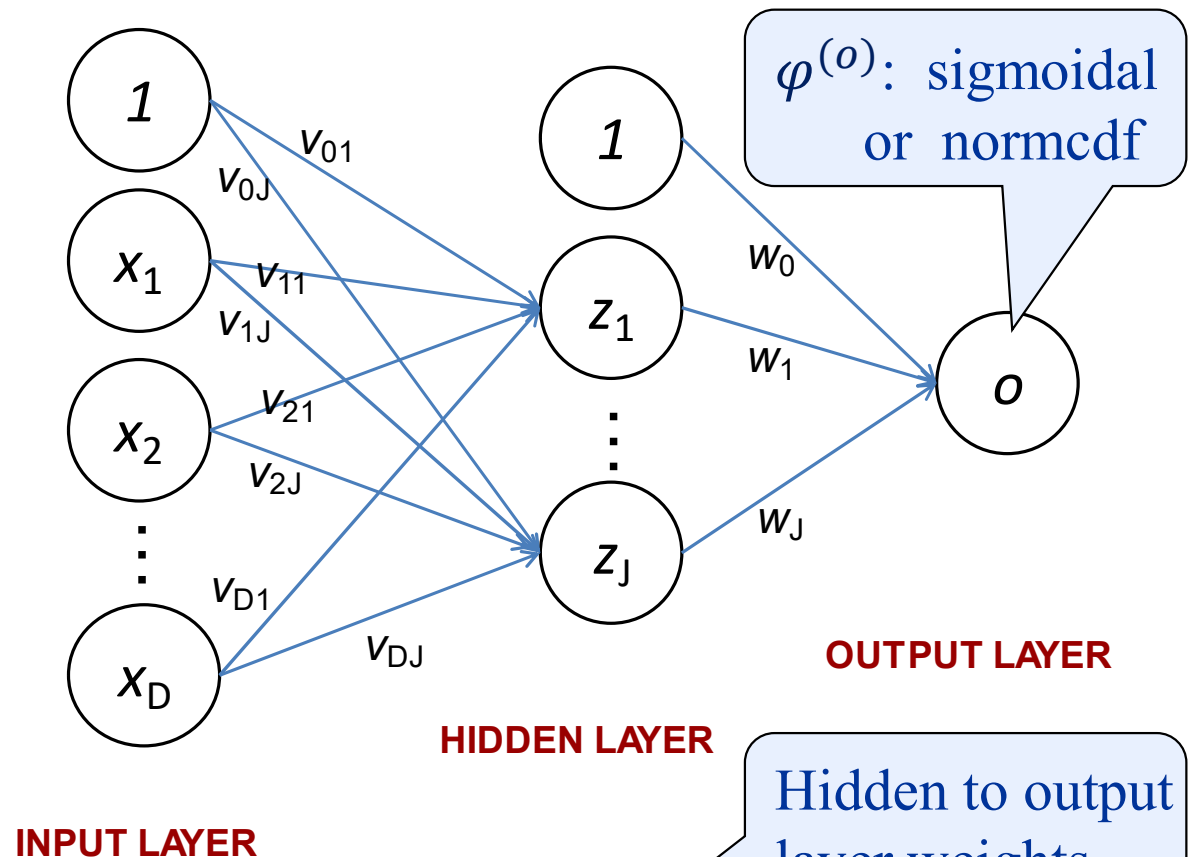
$$\mathbf{z} = \begin{pmatrix} 1 \\ z_1 \\ \vdots \\ z_J \end{pmatrix};$$

Local field

$$z_j = \phi_j^{(H)}(\mathbf{v}_j^T \mathbf{x}); \quad j = 1, 2, \dots, J;$$

Activation
function

$$o(\mathbf{x}; \mathbf{w}) = \varphi^{(o)}(\mathbf{w}^T \mathbf{z}) = \varphi^{(o)}\left(\sum_{j=0}^J w_j \phi_j^{(H)}(\mathbf{v}_j^T \mathbf{x})\right)$$



Sigmoid (logit) activation function

$$\sigma(z) = \frac{1}{1 + e^{-z}};$$

Also: transfer function

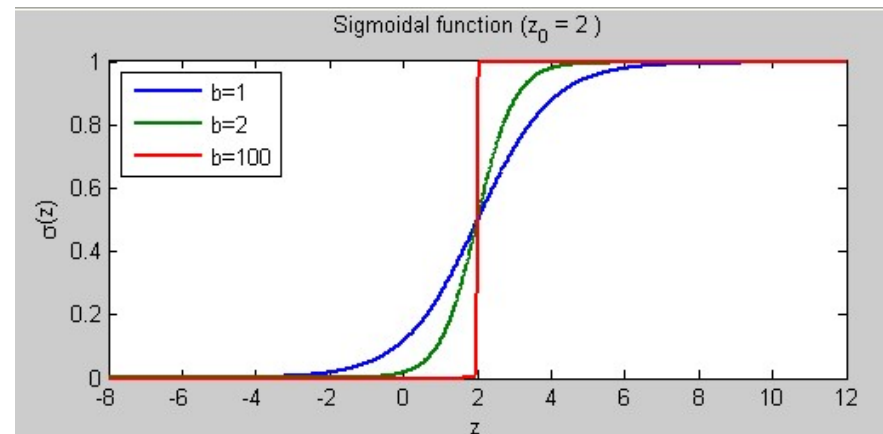
- $\sigma(-\infty) = 0; \sigma(0) = \frac{1}{2}; \sigma(+\infty) = 1;$
- Monotonically increasing: $z_2 > z_1 \Rightarrow \sigma(z_2) > \sigma(z_1)$
- Symmetry: $\sigma(-z) = 1 - \sigma(z)$
- Derivative: $\sigma'(z) = \frac{d\sigma(z)}{dz} = \sigma(z)(1 - \sigma(z))$

$$\sigma(z; z_0, b) = \frac{1}{1 + e^{-b(z-z_0)}}$$

$\frac{1}{b}$: scale

z_0 : center

$$\lim_{b \rightarrow \infty} \sigma(z; z_0, b) = \begin{cases} 0 & \text{if } z < z_0 \\ \frac{1}{2} & \text{if } z = z_0 \\ 1 & \text{if } z > z_0 \end{cases}$$



Heavyside step function

Other activation functions

In regression output layer

- **Linear:** $\varphi(z) = z$
- **Hyperbolic tangent:** $\tanh(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$

normcdf

- **Probit:** $\Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z e^{-\frac{y^2}{2}} dy$

- **softplus:** $\text{softplus}(z; z_0, b) = \frac{\log(1 + e^{-b(z-z_0)})}{b}$

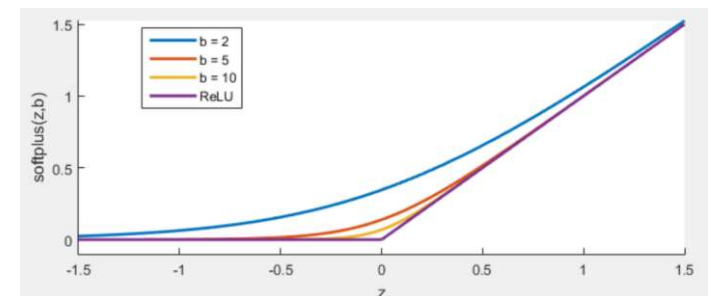
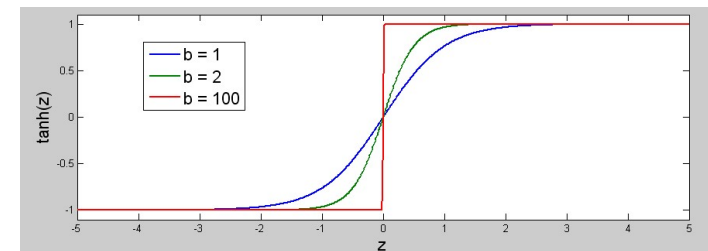
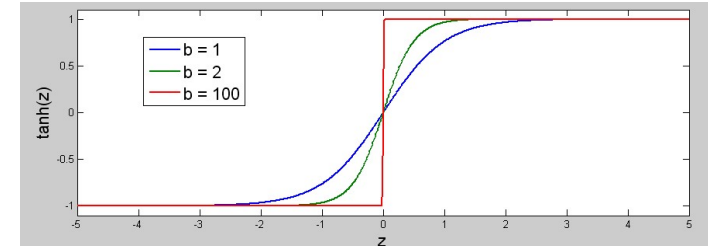
$$\lim_{b \rightarrow \infty} \text{softplus}(z; 0, b) = \text{ReLU}(z)$$

- **Rectified linear unit:** $\text{ReLU}(z) = \max(0, z)$

- **Leaky rectified linear unit:** $\text{Leaky ReLU}(z) = \begin{cases} az & \text{if } z < 0 \\ z & \text{if } z \geq 0 \end{cases}; \quad 0 < a \ll 1$

Avoids zero gradient if $z < 0$

E.g. $a = 0.01$



Multi-layer perceptron: Online learning

INPUT: Training instances: $\mathcal{D} = \{(\mathbf{x}_n, t_n)\}_{n=1}^N$

Learning parameter: $\eta > 0$

OUTPUT: $\mathbf{V}^*, \mathbf{w}^* = \arg \min_{\mathbf{V}, \mathbf{w}} CE(\mathbf{V}, \mathbf{w})$

Only one hidden layer.
Sigmoid activations.

1. Randomly initialize $\mathbf{V}, \mathbf{w} \sim U[-0.5, 0.5]^{(D+1)}$

2. $n_{epoch} = 0$

3. While convergence criteria are not met

3.1 Increment epoch counter: $n_{epoch} = n_{epoch} + 1$

3.2 For $n = 1, \dots, N$

$$z_{nj} = \sigma(\mathbf{v}_j^T \mathbf{x}_n), \quad j = 1, 2, \dots, J;$$

forward propagation

$$o_n = \sigma(\mathbf{w}^T \mathbf{z}_n)$$

network output

$$\delta_n = o_n - t_n;$$

prediction error

$$\mathbf{w} = \mathbf{w} - \eta \delta_n \mathbf{z}_n$$

weight update

$$\Delta_{nj} = z_{nj}(1 - z_{nj})\delta_n, \quad j = 1, 2, \dots, J;$$

error backpropagation

$$\mathbf{v}_j = \mathbf{v}_j - \eta \Delta_{nj} \mathbf{x}_n$$

weight update

Universal approximation property

THEOREM: “A feed-forward network with a **single hidden layer** containing a **sufficiently large number of hidden neurons** can uniformly **approximate any continuous function** on compact subsets of \mathbb{R}^D , under mild conditions on the activation function”

■ GOOD NEWS:

A neural network can be used to make optimal predictions!

■ NOT SO GOOD NEWS:

How does one find such a network?

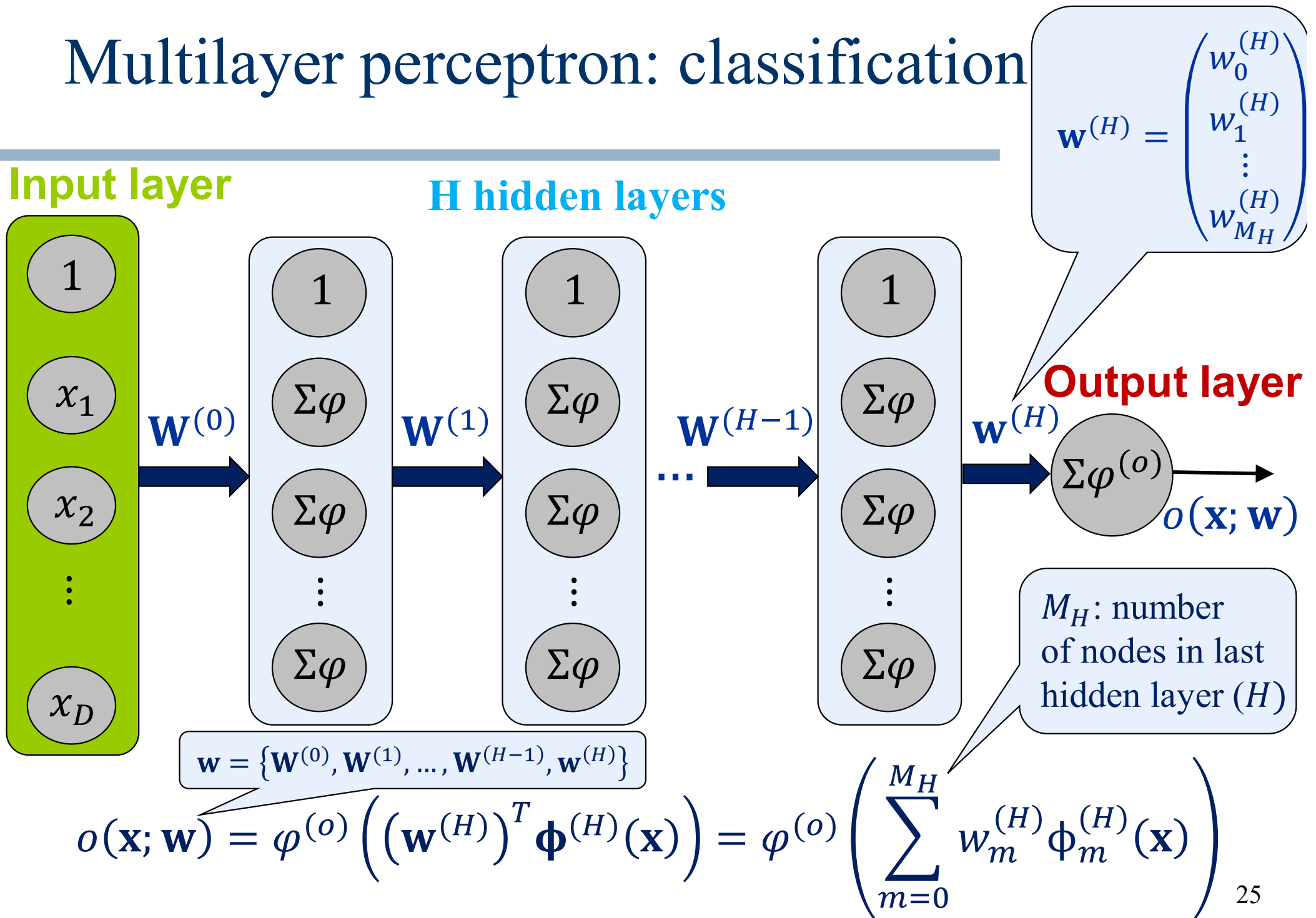
- How many neurons do we need?
- How easy is it to learn the network parameters (weights)?

Use CV

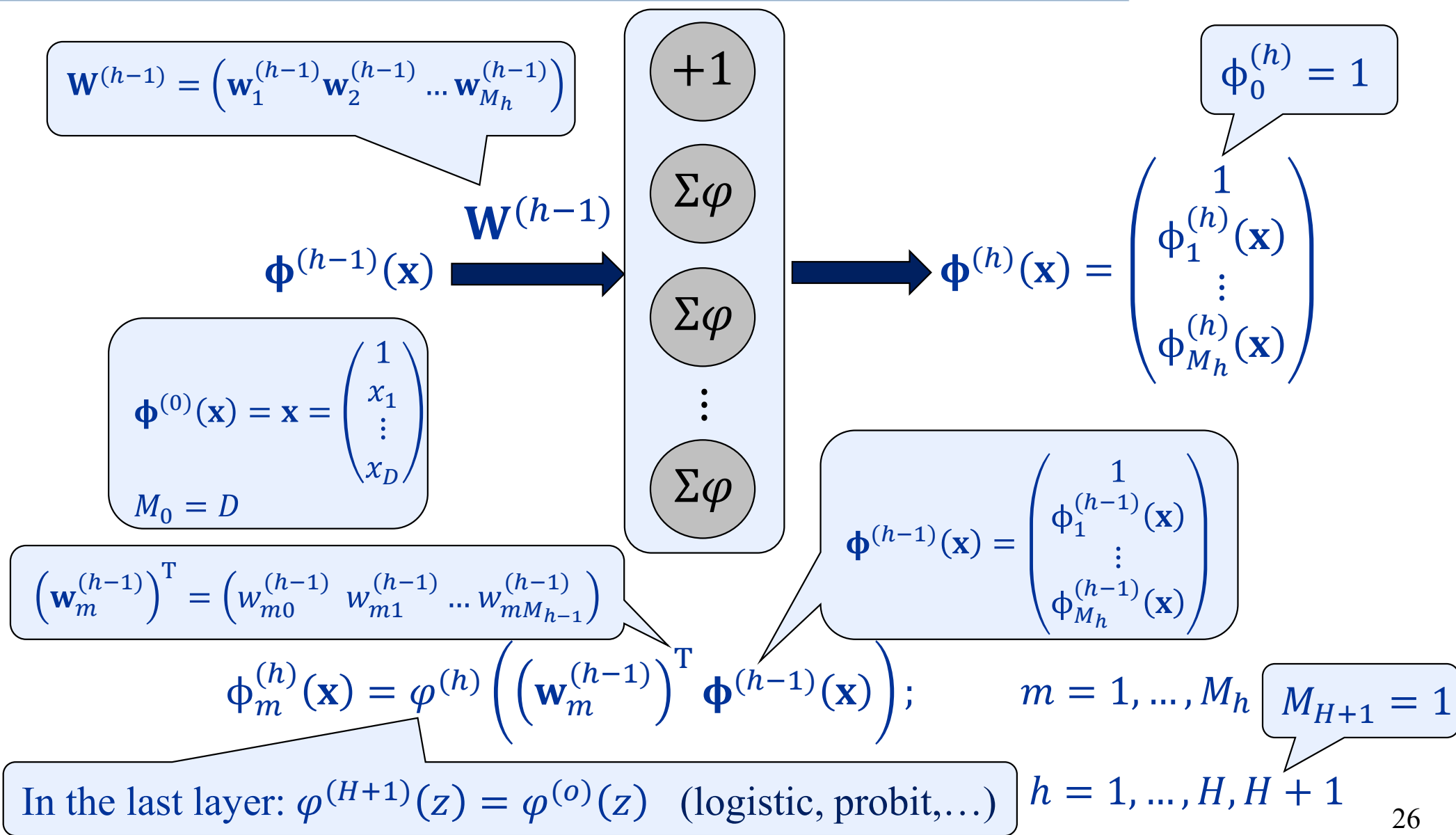
Having more than one layer can help (deep networks)

K. Hornik, M. Stinchcombe and H. White, “Multi-layer Feedforward Networks are Universal Approximators,” Neural Networks, Vol. 2, pp. 359-366 (1989).

Multilayer perceptron: classification



Output of hidden layer h



Learning the network weights

The network weights are determined by minimization of a cost function:

$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \left(\left[- \sum_{n \in C_0} \log(1 - o(\mathbf{x}_n; \mathbf{w})) - \sum_{n \in C_1} \log(o(\mathbf{x}_n; \mathbf{w})) \right] + \lambda_1 \|\mathbf{w}\|_1 + \lambda_2 \|\mathbf{w}\|_2^2 \right)$$

Use CV to select

Cross-entropy error

$\lambda_1 > 0$ L_1 penalty $\lambda_2 > 0$ L_2 penalty

- **Architecture:** Number of hidden layers / Neurons in hidden layer
- **Optimization method:** Quasi-Newton, Gradient descent, stochastic gradient descent, use of momentum... Gradients needed!
- **Hyperparameters:** Magnitude of penalties, of momentum term, maximum # of iterations, ...

Multi-class classification (K classes)

1-of K encoding of the **labeled data**

$$\mathcal{D} = \{(\mathbf{x}_n, c_n)\}_{n=1}^N \Rightarrow \mathcal{D} = \{(\mathbf{x}_n, \mathbf{t}_n)\}_{n=1}^N; \quad \mathbf{t}_n^T = (t_{n1} \ t_{n2} \ \dots \ t_{nK})$$

$$t_{nk} = \mathbb{I}[c_n = C_k] = \begin{cases} 0 & \text{if } y_n \neq C_k; \\ 1 & \text{if } y_n = C_k; \end{cases} \quad k = 1, 2, \dots, K$$

$$\mathcal{L}: \mathcal{D} = \{(\mathbf{x}_n, y_n)\}_{n=1}^N \rightarrow o(\cdot; \mathbf{w})$$

$$\mathbf{z}(\cdot; \mathbf{w}): \mathbf{x} \in \mathcal{X} \rightarrow \mathbf{z}(\mathbf{x}; \mathbf{w}) \in \mathbb{R}^K$$

$$\mathbf{o}(\mathbf{x}; \mathbf{w}) = \boldsymbol{\varphi}^{(o)}(\mathbf{z}(\mathbf{x}; \mathbf{w})) \in \Delta^K$$

Discriminative
model

$$\hat{p}(C_k | \mathbf{x}, \mathbf{w}) = \varphi_K^{(o)}(\mathbf{z}(\mathbf{x}; \mathbf{w}))$$

Probability simplex
in K dimensions

$$\left(\boldsymbol{\varphi}^{(o)}(\mathbf{z})\right)^T = \left(\varphi_1^{(o)}(\mathbf{z}) \ \dots \ \varphi_K^{(o)}(\mathbf{z})\right)$$

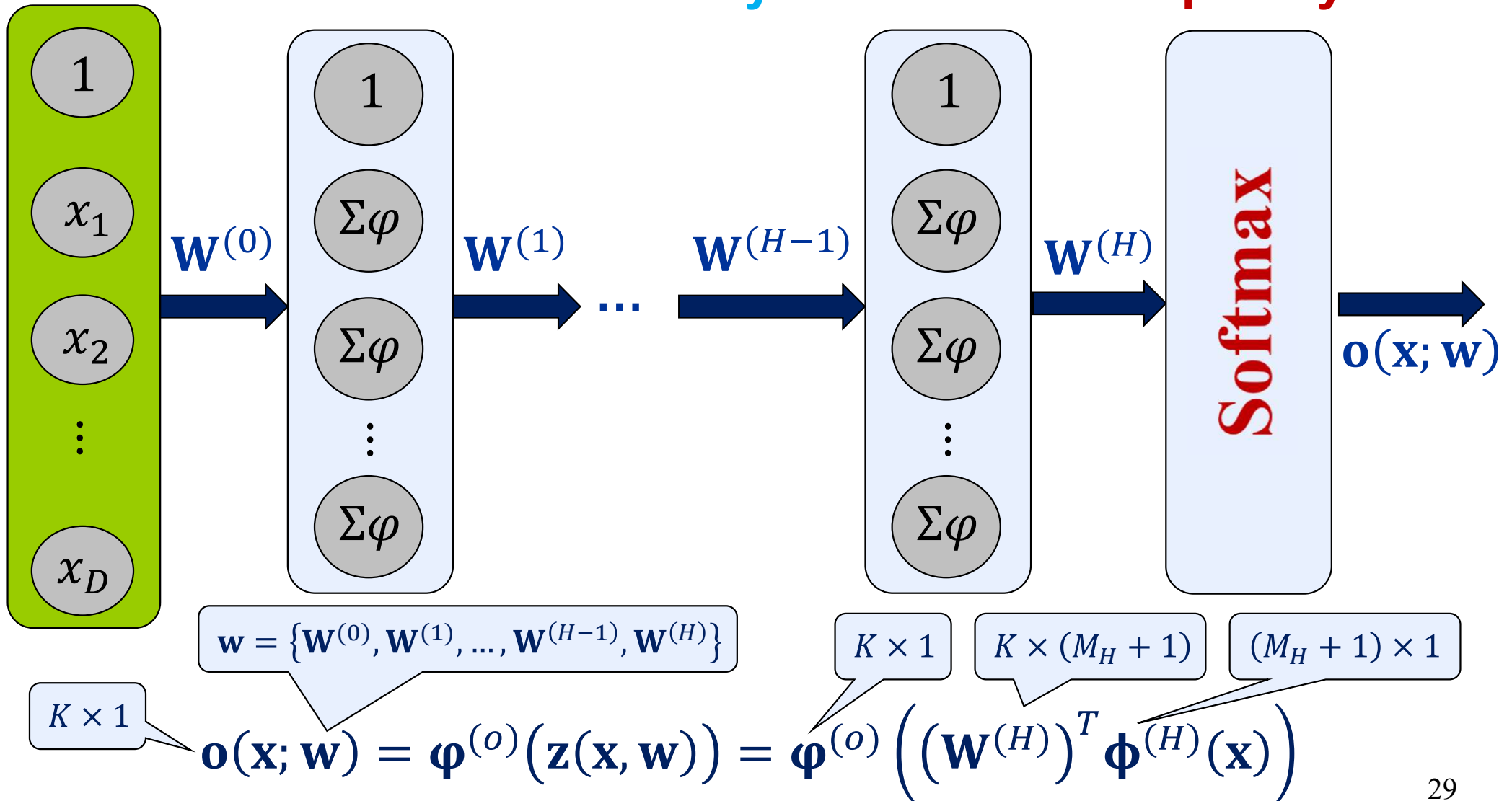
$$\begin{aligned} \varphi_k^{(o)}(\mathbf{z}) &\geq 0 & k = 1, \dots, K \\ \varphi_1^{(o)}(\mathbf{z}) + \dots + \varphi_K^{(o)}(\mathbf{z}) &= 1 \end{aligned}$$

MLP for multiclass classification

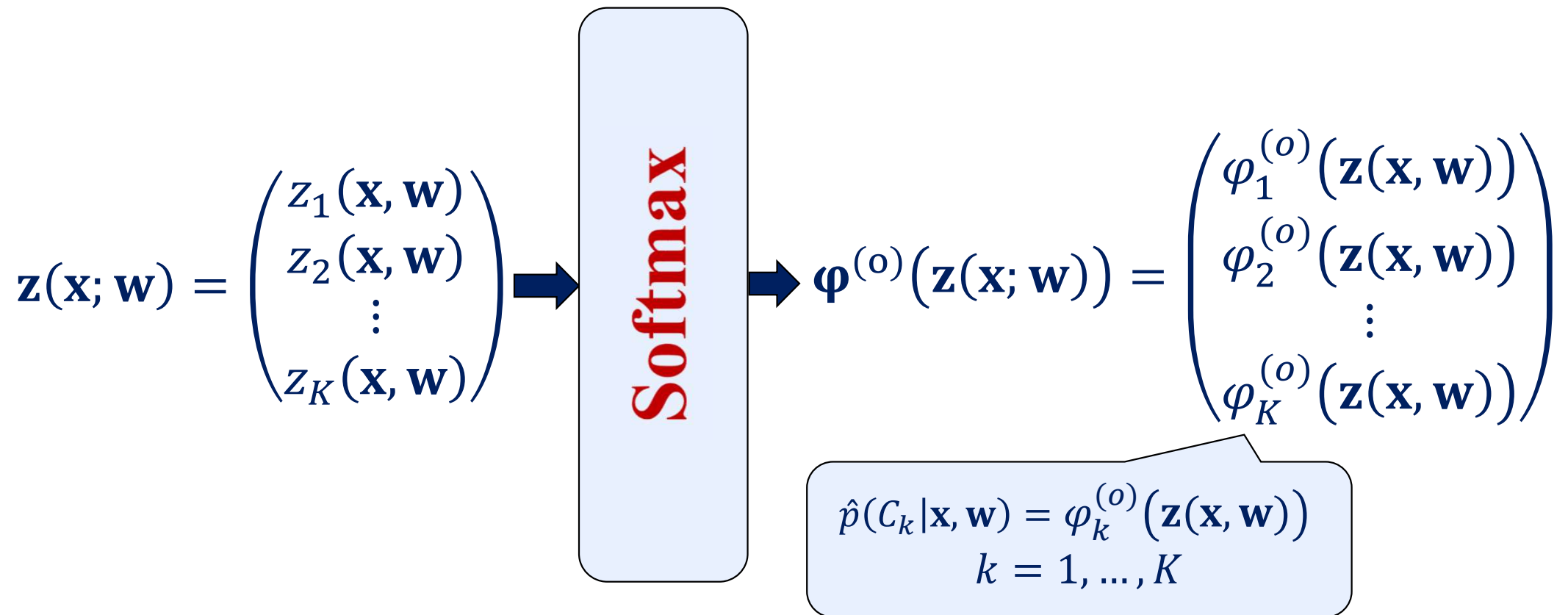
Input layer

H hidden layers

Output layer



Softmax layer



Probabilities

$$\varphi_k^{(o)}(\mathbf{z}) = \frac{e^{z_k}}{\sum_{j=1}^K e^{z_j}} \geq 0 \quad k = 1, \dots, K$$

$$\varphi_1^{(o)}(\mathbf{z}) + \dots + \varphi_K^{(o)}(\mathbf{z}) = 1$$

Learning by maximum likelihood

Samples
assumed
to be iid
(independent
identically
distributed)

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \mathcal{L}(\mathbf{w})$$

- Likelihood of the model, given $\mathcal{D} = \{(\mathbf{x}_n, \mathbf{t}_n)\}_{n=1}^N$

$$\mathcal{L}(\mathbf{w}) = \hat{P}(\{\mathbf{t}_n\}_{n=1}^N | \{\mathbf{x}_n\}_{n=1}^N, \mathbf{w}) = \prod_{n=1}^N \hat{p}(t_n | \mathbf{x}_n, \mathbf{w}) =$$

Factorizes because
samples are assumed
to be independent

$$= \prod_{n=1}^N \prod_{k=1}^K (\hat{p}(C_k | \mathbf{x}_n, \mathbf{w}))^{t_{nk}}$$

Factors equal because
samples are assumed
to be identically dist.

- Log-likelihood function

$$\log \mathcal{L}(\mathbf{w}) = \sum_{n=1}^N \sum_{k=1}^K t_{nk} \log \hat{p}(C_k | \mathbf{x}_n, \mathbf{w})$$

$$t_{nk} = \mathbb{I}[c_n = C_k]$$

Minimization of the cross-entropy error

$$\mathbf{w}^* = \arg \min_{\mathbf{w}} CE(\mathbf{w})$$

- Cross-entropy error

$$CE(\mathbf{w}) = -\log \mathcal{L}(\mathbf{w}) = -\sum_{n=1}^N \sum_{k=1}^K t_{nk} \log \hat{p}(C_k | \mathbf{x}_n, \mathbf{w})$$

- Discriminative model: $\hat{p}(C_1 | \mathbf{x}, \mathbf{w}) = \varphi_k^{(o)}(z(\mathbf{x}_n, \mathbf{w}))$

Output of the
kth neuron in
the last layer
of the MLP.

$$\widehat{CE}(\mathbf{w}) = -\sum_{n=1}^N \sum_{k=1}^K t_{nk} \log \varphi_k^{(o)}(z(\mathbf{x}_n, \mathbf{w}))$$

Neural networks summary

■ Advantages

- Excellent predictors.
- Adaptive (online learning)

■ Disadvantages

- Costly training.
- Finding appropriate architecture can be difficult
 - Number of hidden layers / nodes in each hidden layer
 - Activation function
- Determining the hyperparameters for the optimization
 - Type of optimization
 - In SGD: learning rate, size of mini-batches, momentum term, strength of regularization terms, ...
- Difficult interpretation.

State-of-the-art: Deep neural networks

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