Data structure and Algorithms

Project

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MIE1

Project topic: ADT MultiMap – implementation on a singly lined list on an array. Every node contains a key and a doubly linked list with dynamic allocation of all the values belonging to that key.

Problem statement and justification:

<u>Problem statement:</u> Implement an application which is a synonyms dictionary. For example: "beautiful" is synonym to "pretty", "handsome", "good-looking" "lovely". We also would like to be able to add words and synonyms to that words or delete certain words or synonyms and to be able to see all words.

<u>Justification:</u> the problem obviously requires to associate a word with synonyms, so we need a container that can hold key-values pair. Words are the keys and the synonyms are the values. A key can have multiple values.

ADT MultiMap - Domain and Interface

Domain:

MM = {mm|mm is a Multimap with <TKey, TValue> pairs; a Tkey can have multiple associated Tvalue}

Interface:

-init (mm):

pre: true

post: mm ∈ MM, mm is an empty multimap

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-destroy(mm):
         pre: mm \in MM
         post: the multimap was destroyed
-add(mm, k, v):
         pre: mm ∈ MM, k – TKey, v – TValue
         post: mm' \in MM, mm' = mmU < k, v >
-remove(mm, k, v):
         pre: mm ∈ MM, k – TKey, v – Tvalue
        remove \leftarrow \begin{cases} \text{true, if < k, v > } \in \text{mm, mm'} \in \text{MM, mm'} = \text{mm-} < \text{k, v >} \\ \text{false, otherwise} \end{cases}
-search(mm, k, l):
         pre: mm \in MM, k – TKey
         post: I \in L, I is the list of values associated to the key k. If k is not in the multimap, I is the
empty list.
-iterator(mm, it):
         pre: mm ∈ MM
         post: it \in I, it is an iterator over mm, the current element from it is the first pair from
mm, or, it is invalid if mm is empty
-size(mm):
         pre: mm ∈ MM
         post: size ← the number of pairs from mm
```

ADT Iterator – Domain *and* **Interface**:

Domain:

I = {it | it is an iterator over multimap }

Interface:

```
    init(it, mm):
        pre: mm is a MultiMap
        post: it∈ I and it points to the first element in mm if mm is not empty or it is not valid
```

```
- getCurrent(it):
                pre: it∈ I, it is valid
                post: getCurrent ← e, e ∈MM, e is the current element from it
                throws: an exception if it is not valid
        -next(it):
                pre: it \in I, it is valid(it)
                post: it'∈ I, the current element from it' points to the next element from the
        multimap, or, if the current element from it was the last element from the multimap, it' is
        invalid
                throws: an exception if it is not valid
        - valid(it):
                pre: it I ∈
                       True, if the current element from it is valid
                post: →
                        false, otherwise
ADT Representation:
VNode: (node for the doubly linked list)
        value: TValue
        next: ↑ VNode
        previous: ↑ VNode
```

DLL: (doubly linked list for values)
tail: 个 VNode
head: 个 VNode

TElem: (key and values list) key: TKey values: DLL

TElemITERATOR(key -value)
Key:TKey
Value:TValue

```
MultiMap: (container with an static array of TElem) 
Elems: TElem[cap]
```

nextPost: Integer[cap]

cap: Integer // capacity of arrays

sizeKV: Integer // how many values are in total headList: Integer // head of singley linked list

firstEmpty: Integer // first empty position on elems array

MultiMapIterator:

mm:MM

currentElement: Integer currentNode: ↑VNode

counter: Integer // to count how many values that were "read" from MultiMap

<u>Implementation in pseudocode (and complexity)</u>

ADT MultiMap:

```
Subalgorithm init(mm) is:  mm.cap \leftarrow 30 \\ mm.len \leftarrow 0 \\ mm.headList \leftarrow -1 \\ mm.firstEmpty \leftarrow 0 \\ mm.sizeKV \leftarrow 0 \\ for i \leftarrow 0,29 \ execute \\ mm.elems[i] \leftarrow \{NILL, NILL\} \\ mm.nextPos[i] \leftarrow i+1 \\ end-for \\ mm.nextPos[mm.cap] \leftarrow -1 \\ end-subalgorithm \\ //\Omega(cap) - cap is capacity of arrays
```

```
// auxiliary function
Subalgorithm findKeyPos(mm,k) is:
       current←mm.headList
       while current ≠ -1 and mm.elems[current].first ≠ k execute
               current ← mm.nextPos[current]
       end-while
       if current ≠ -1 then
               findKeyPos ← current
       else
               findKeyPos←-1
       end-if
end-subalgorithm
// O(cap) – cap is capacity of array
Subalgorithm add(mm, k, v) is:
       If mm.firstEmpty = -1 then
               @throw "full"
       Else
               Pos ← mm.findKeyPos(k)
               If pos = -1 then
                      If mm.isEmpty() then:
                              newPosition←mm.firstEmpty
                              mm.elems[newPosition].first←c
                              n = allocate()
                              [n].value ← v
                              [n].next←NILL
                              [n].previous←NILL
                              mm.elems[newPosition].second.head←n
                              mm.elems[newPosition].second.tail←n
                              mm.firstEmpty \( \shape \text{mm.nextPos[mm.firstEmpty]} \)
                              mm.nextPos[newPosition] ←mm.headList
                              mm.headList←newPosition
                              mm.len←mm.len+1
                              mm.sizeKV←mm.sizeKV+1
                      else:
                              pozCurrent←1
                              nodCurrent←mm.headList
                              while nodCurrent ≠ -1 and pozCurrent<mm.firstEmpty-1 execute:
                                     pozCurrent←pozCurrent+1
                                     nodCurrent←mm.nextPos[nodCurrent]
                              end-while
                              if nodCurrent ≠ -1 then:
                                     newElem ← mm.firstEmpty
```

```
mm.elems[newElem].first←k
                                  n=allocate()
                                  [n].value \leftarrow v;
                                  [n].next←NILL
                                  [n].previous←NILL
                                  mm.elems[newElem].second.head←n
                                  mm.elems[newEelm].second.tail←n
                                  mm.len←mm.len+1
                                  mm.nextPos[nodCurrent] ← newElem
                           end-if
                           mm.sizeKV←mm.sizeKV+1
                    end-if
             else:
                    n←allocate()
                    [n].value←v
                    [n].previous←mm.elems[pos].second.tail
                    [mm.elems[pos].second.tail].next←n
                    mm.elems[pos].second.tail←n
                    [mm.elems[pos].second.tail].next←n
                    mm.sizeKV←mm.sizeKV+1
             end-if
end-subalgorithm
//WC=0(capacity) BC= \Omega(1)
Subalgorithm remove(mm, k, v) is:
      pos←mm.findKeyPos(k)
      if pos = -1 then:
             remove ← false
      else:
             if mm.elems[pos].second.tail=mm.elems[pos].second.head then:
                    nodC←mm.headList
                    prevNode←-1
                    while nodC ≠ -1 and mm.elems[nodC].first≠k execute:
                           prevNode ← nodC
                           nodC←mm.nextPos[nodC]
                    end-while
                    if nodC=mm.headList then:
                           mm.elems[mm.headList].first←NILL
                           mm.headList← mm.nextPos[mm.headList]
                           mm.sizeKV←mm.sizeKV-1
```

mm.firstEmpty \(\bullet\) mm.nextPos[mm.firstEmpty]

```
mm.elems[nodC].first←NILL
                             mm.nextPos[prevNode] ←mm.nextPos[nodC]
                             mm.sizeKV←mm.sizeKV-1
                      end-if
                      mm.nextPos[nodC] ←mm.firstEmpty
                      mm.firstEmpty←nodC
                      mm.len←mm.len-1
              else
                      [currentNode] ← mm.elems[pos].second.head
                      While currentNode≠ NILL and [currentNode].value ≠ v execute:
                             currentNode ← [currentNode].next
                      end-while
                      [deletedNode]=currentNode
                      If currentNode ≠ NILL then:
                             If currentNode = mm.elems[pos].second.head then:
                                   mm.elems[pos].second.head ← mm.elems[pos].second.head.next
                                   [mm.elems[pos].second.head].previous ← NILL
                                   mm.sizeKV←mm.sizeKV-1
                                   remove←true
                             else:
                                if currentNode = mm.elems[pos].second.tail then:
                                    mm.elems[pos].second.tail \( \shape \) mm.elems[pos].second.tail.previous
                                   mm.elems[pos].second.tail.next←NILL
                                   mm.sizeKV←mm.sizeKV-1
                                   remove←true
                                else:
                                    [[currentNode].next].previous ← [[currentNode].previous
                                     [[currentNode].previous].next ← [[currentNode].next
                                     mm.sizeKV←mm.sizeKV-1
                                     return true
                                end-if
                             end-if
                      else:
                             remove ← false
                      end-if
              end-if
       end-if
end-subalgorithm
//WC=0(capacity) BC= \Omega (1)
```

else

```
Subalgorithm search(mm, k) is:
       pos ← mm.findKeyPos(k)
       if pos = -1 then:
               search ← @empty vector
       else
               current=allocate()
               current←mm.elems[pos].second.head
               values (values vector<TValue>)
               while current ≠ NILL execute:
                       values.push_back([current].value)
                       current← current.next
               end-while
               search←values
       end-if
end-subalgorithm
// BC= \Omega(1) WC=AC=O(capacity)
Subalgorithm size(mm) is:
       s←mm.sizeKV
end-subalgorithm
//\Omega(1)
Subalgorithm isEmpty(mm) is:
       If mm.sizeKV=0 then:
               isEmpty←1
       else
               isEmpty ← 0
end-subalgorithm
// Ω(1)
Subalgorithm iterator(mm) is:
       iterator ← MultiMapIterator([mm])
end-subalgorithm
//\Omega(1)
```

MultiMapIterator:

```
Subalgorithm init(it,mm) is:
        It.currentElement ← 0
        It.currentNode←mm.elems[it.currentElement].second.head
        It.counter←0
End-subalgorithm
//\Omega(1)
Subalgorithm getCurrent(it) is:
        k←mm.elems[it.currentElement].first
       v←[it.currentNode].value
        getCurrent ← {k,v}
end-subalgorithm
//\Omega(1)
Subalgorithm valid(it) is:
        If it.counter=mm.sizeKV then:
               valid←false
        else:
               valid←true
        end-if
end-subalgorithm
//\Omega(1)
Subalgorithm next() is:
        If [it.currentNode].next=NILL then:
               It.current←mm.nextPos[it.currentElement]
               It.currentNode ← mm.elems[it.currentElement].second.head
               It.counter←it.counter+1
        Else:
               It.currentNode←[it.currentNode].next
               It.counter←it.counter+1
        End-if
End-subalgorithm
//\Omega(1)
Subalgorithm first(it) is:
        It.currentElement←mm.headList
        It.currentNode←mm.elems[it.currentElement].second.head
        It.counter←0
End-subalgorithm
// Ω(1)
```

Tests:

```
#include "Tests.h"
#include "MultiMap.h"
#include "MultiMapIterator.h"
#include <assert.h>
#include <vector>
#include<iostream>
void testAll() {
      MultiMap m;
      m.add(1, 100);
      m.add(2, 200);
      m.add(3, 300);
      m.add(1, 500);
      m.add(1, 600);
      m.add(1, 300);
      m.add(1, 200);
      m.add(2, 800);
      m.add(3, 500);
      m.add(2, 600);
      m.add(3, 700);
      m.add(4, 800);
       m.add(5, 900);
      m.add(4, 8000);
       assert(m.size() == 14);
       assert(m.remove(6, 600) == false);
       assert(m.remove(1, 500) == true);
       assert(m.remove(2, 200) == true);
       assert(m.remove(1, 5100) == false);
       assert(m.remove(3, 700) == true);
       assert(m.remove(4, 8000) == true);
       assert(m.remove(4, 800) == true);
       assert(m.remove(5, 900) == true);
       assert(m.remove(2, 800) == true);
       assert(m.remove(2, 600) == true);
       assert(m.size() == 6);
      m.add(1, 500);
      m.add(1, 700);
      m.add(2, 300);
       vector<TValue> v,v1;
       v=m.search(6);
       assert(v.size()==0);
       v=m.search(1);
       assert(v.size()==6);
       m.add(1, 500);
      m.add(1, 500);
       v = m.search(1);
       assert(v.size() == 8);
       v1 = \{ 100, 600, 300, 200, 500, 700, 500, 500 \};
       assert(v == v1);
```

```
m.add(4, 800);
       v = m.search(4);
      v1 = \{ 800 \};
       assert(v.size() == 1);
       assert(v == v1);
      v = m.search(1);
       assert(v != v1);
       assert(m.isEmpty() == false);
      MultiMapIterator im = m.iterator();
       assert(im.valid() == true);
      while (im.valid()) {
              im.getCurrent();
              im.next();
       }
       assert(im.valid() == false);
       im.first();
       assert(im.valid() == true);
}
```