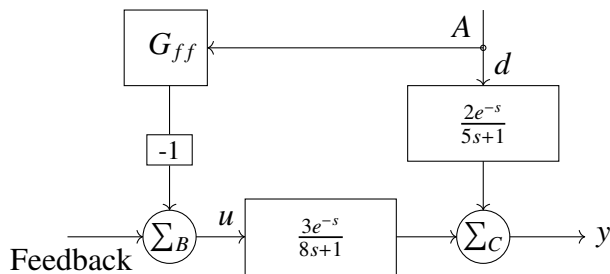


# Question 23, CH Gate 2022

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**Question:** The appropriate feedforward compensator,  $G_{ff}$ , in the shown block diagram is



**Solution:**

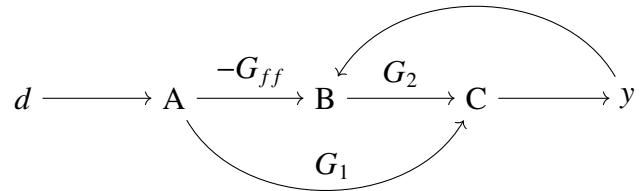
Symbol	Value	Description
$y$	-	Signal
$d$	-	Disturbance
$H$	?	Transfer function of the system
$G_1$	$\frac{2e^{-s}}{5s+1}$	Gains Given
$G_2$	$\frac{3e^{-s}}{8s+1}$	
$P_1$	$-G_2G_{ff}$	Gain of the 1st forward path
$P_2$	$G_1$	Gain of the 2nd forward path
$\Delta$	1	Determinant of the graph
$\Delta_1$	1	Determinant of the graph removing the 1st forward path
$\Delta_2$	1	Determinant of the graph removing the 2nd forward path

TABLE 0  
INPUT PARAMETERS

In an ideal system, the output  $y$  must be independent of the disturbance  $d$ . This means, the transfer function

$$\frac{Y(s)}{D(s)} = 0$$

The signal flow graph for this system is given by



1) **Theory:** For such a system, Mason's Gain formula can be used. From Table 0

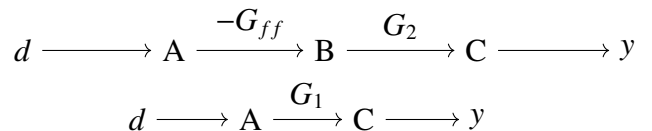
$$H = \sum_i \frac{\Delta_i P_i}{\Delta} \quad (1)$$

If  $L_i$  denotes the loop gain of  $i$ th Loop

$$\Delta = 1 - \sum_i L_i + \sum_i \sum_j L_i L_j - \dots \quad (2)$$

$\Delta_i$  is the value of  $\Delta$  without the nodes contained by the  $i$ th path.

2) Here, there are 2 forward paths



For these paths,

$$P_1 = -G_2G_{ff} \quad (3)$$

$$P_2 = G_1 \quad (4)$$

$$\Delta_1 = \Delta_2 = 1 - (0) \quad (5)$$

$$\Delta = 1 - (0) = 1 \quad (6)$$

From (1) and Table 0

$$H = G_1 - G_2G_{ff} \quad (7)$$

Since  $H = 0$ ,

$$G_1 - G_2G_{ff} = 0 \quad (8)$$

$$\Rightarrow G_{ff} = \frac{G_1}{G_2} = \frac{2}{3} \frac{8s+1}{5s+1} \quad (9)$$