POA LAB EXPERIMENTS

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Division	Α
Batch	A4
Branch	Computer Engineering
Semester	5
Subject	Processor Organization and Architecture
Subject Code	DJ19CEL502

Experiment List

Exp. No.	Aim	Page No							
1	To implement Booth's multiplication algorithm.	3							
2	To study and implement Restoring division algorithm.	11							
3	To implement non restoring binary division method	21							
4	Implement Sequential Memory Organization with given details: Processor can access one word at a time (Word accessible memory), L1 cache can store max 32 words, L2 cache can store 128 words, main memory has the capacity of 2048 bytes. Consider TL1=20 ns, TL2=60ns, TMM=120ns. Create output table containing								
	Processor Request (Sp. Word) Location of Hit Average Memory Access Time								
5	Study various microprocessors and microcontrollers used in the market specifically targeting Aircrafts and Automated Vehicles.								
6	Simulate fully associative mapping and set associative mapping using mini MIPS Simulator and. Modify to create tag size bits as 16 instead of 8 and compare the performance of 3 different organizations with this modification.	54							
7	Study and Simulate (Stepwise) Experiments of MIPS Programming available at using MIPS simulator. Modify the given programs to implement 1) To add 10 nos. 2) to print message "Hello MIPS" 3) To Reverse the input string (e.g."ABC" - "CBA").	64							
8	Run the simulator using the given link https://yjdoc2.github.io/8086-emulator-web/compile . Study and execute First 6 examples from the repository https://github.com/YJDoc2/8086-Emulator/tree/master/examples .								
9	Write Programs using Assembly Language: 1. To implement Macros for calculating Factorial of a number 2. To study and Implement DOS interrupts. Eg: calculate and display Sum of 2 user entered inputs using DOS interrupt								
10	Write a Program using ALP to Simulate Microcontroller interfacing with 7 segment display. Display your SAP ID using this tool.	86							

EXPERIMENT - 1

AIM: To demonstrate Booth's Algorithm for multiplication of 2 signed binary numbers.

Submission Sheet

SAP ID	Name of Student	Date of Experiment	Date of Submission	Remarks
60004190057	Junaid Girkar	01-10-2021	01-10-2021	

THEORY:

Booth algorithm gives a procedure for multiplying binary integers in signed 2's complement representation in an efficient way, i.e., less number of additions/subtractions required. It operates on the fact that strings of 0's in the multiplier require no addition but just shifting and a string of 1's in the multiplier from bit weight 2'm can be treated as 2'(k+1) to 2'm.

Booth's algorithm can be implemented by repeatedly adding (with ordinary unsigned binary addition) one of two predetermined values A and S to a product P, then performing a rightward arithmetic shift on P. Let \mathbf{m} and \mathbf{r} be the multiplicand and multiplier, respectively; and let x and y represent the number of bits in \mathbf{m} and \mathbf{r} .

- 1. Determine the values of A and S, and the initial value of P. All of these numbers should have a length equal to (x + y + 1).
 - 1. A: Fill the most significant (leftmost) bits with the value of \mathbf{m} . Fill the remaining (y + 1) bits with zeros.
 - 2. S: Fill the most significant bits with the value of $(-\mathbf{m})$ in two's complement notation. Fill the remaining (y + 1) bits with zeros.
 - 3. P: Fill the most significant *x* bits with zeros. To the right of this, append the value of **r**. Fill the least significant (rightmost) bit with a zero.
- 2. Determine the two least significant (rightmost) bits of P.
 - 1. If they are 01, find the value of P + A. Ignore any overflow.
 - 2. If they are 10, find the value of *P* + *S*. Ignore any overflow.
 - 3. If they are 00, do nothing. Use *P* directly in the next step.
 - 4. If they are 11, do nothing. Use P directly in the next step.







- 3. Arithmetically shift the value obtained in the 2nd step by a single place to the right. Let *P* now equal this new value.
- 4. Repeat steps 2 and 3 until they have been done *y* times.
- 5. Drop the least significant (rightmost) bit from *P*. This is the product of **m** and **r**.

TIME COMPLEXITY: O(n) * (complexity_of_addition + complexity_of_shift)

EXAMPLE: Multiplication of 7 and 3

Qn	Q _{n+1}	M = (0111) M' + 1 = (1001) & Operation	AC	Q	Q _{n+1}	SC
1	0	Initial	0000	0011	0	4
		Subtract (M' + 1)	1001			
			1001			
		Perform Arithmetic Right Shift operations (ashr)	1100	1001	1	3
1	1	Perform Arithmetic Right Shift operations (ashr)	1110	0100	1	2
0	1	Addition (A + M)	0111			
			0101	0100		
		Perform Arithmetic right shift operation	0010	1010	0	1
0	0	Perform Arithmetic right shift operation	0001	0101	0	0

Final Answer =
$$(0001 \ 0101)2$$

= $(21)_{10}$

CODE:

#include<stdio.h>
#include<stdlib.h>
#include<string.h>

void rightShift();

int main()



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```
printf("\n");
 printf("BOOTH's Algorithm\n");
  printf("\n");
 printf("Enter two numbers that are to be multiplied: ");//taking two numbers as inputs
 int a,b;
 scanf("%d %d",&a,&b);
 int ap=a,bp=b;
 if(ap<0) // Negetive values check
    ap*=-1;
 if(bp<0) bp*=-1;
 if(bp>ap) //taking greater VALUE as multiplicand
    ap=bp+ap-(bp=ap);
    a=b+a-(b=a);
 }
 int t1=ap,t2=bp;
 int ab[35]={};
 int bb[35]={};
 int i=0;
 while(t1>0)
    ab[i]=t1%2;
    j++;
    t1/=2;
 }
 ab[i]=0;
 int j=0;
 while(t2>0)
    bb[i]=t2%2;
    j++;
    t2/=2;
 while(j<=i) //equating bits to the previous(ab) binary number(ab will either be larger or equal to
bb).
    bb[j++]=0;
 int nb=i+1; //nb is number of bits
 i=0; j=0;
 while(i<nb/2) //converting VALUES to binary
    ab[i]=ab[nb-i-1]+ab[i]-(ab[nb-i-1]=ab[i]);
    j++;
 }
 i=0;
 while(i<nb/2) { bb[i]=bb[nb-i-1]+bb[i]-(bb[nb-i-1]=bb[i]); i++; } int x[35]=\{0\}; int y[35]=\{0\}; i=0; if (a>=0)
//taking actual binary numbers
```



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```
{ //x is multiplicand and y is multiplier
     while(i<nb)
    x[i]=ab[i+++1];
  else //2's complimant
  {
     while(i<nb) { if(ab[i]==0) x[i]=1; else x[i]=0; i++; } i=1; x[nb-i]++; while(x[nb-i]==2) { x[nb-i]=0; i++;
x[nb-i]++; \} i=0; if(b>=0)
  {
     while(i<nb)
       y[i]=bb[i+++1];
  else //2's complimant
     while(i<nb) { if(bb[i]==0) y[i]=1; else y[i]=0; i++; } i=1; y[nb-i]++; while(y[nb-i]==2) { y[nb-i]=0; i++;
y[nb-i]++; } } printf("\n"); //output starts here printf("Multiplicand (Q) %d -> ",a);
  i=0:
  printf("Multiplicand (Q) -> ");
  while(i<nb) printf("%d",x[i++]); printf("\nMultiplier (M) %d -> ",b);
  i=0:
  while(i<nb)
     printf("%d",y[i++]);
  printf("\n");
  i=0;
  int ym[35]={0}; //calculating -M
  if(b<0)
  {
    while(i<nb)</pre>
    ym[i]=bb[i+++1];
  }
  else
  {
     while(i<nb) { if(bb[i]==0) ym[i]=1; else ym[i]=0; i++; } i=1; ym[nb-i]++; while(ym[nb-i]==2) {
ym[nb-i]=0; i++; ym[nb-i]++; } printf("we use -(M) i.e. %d -> ",-b);
  i=0;
  while(i<nb)
     printf("%d",ym[i++]);
  printf("\n");
  int q0=0;
  int p[35]={0}; //p here is value that is stored in accumulator. initially set to zero.
  int steps=nb;
  printf("\n");
  printf("n\t");
  i=0;
  while(i<nb)
    if(i*2==nb || i*2==nb-1)
```



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```
printf("A");
  else
  printf(" ");
  i++;
}
printf(" ");
i=0;
while(i<nb)
  if(i*2==nb || i*2==nb-1)
     printf("Q\t");
  else
     printf(" ");
  i++;
printf(" Q-1");
printf("\n");
j=<mark>0</mark>;
while(steps-) //counting down steps.
  printf("%d
                   ",j++);
  i=0;
  while(i<nb)
     printf("%d",p[i++]);
  printf(" ");
  i=0;
  while(i<nb)</pre>
     printf("%d",x[i++]);
  printf(" ");
  printf("%d\n",q0);
  if(x[nb-1]==0 \&\& q0==0) //0-0 condition
     q0=x[nb-1];
     rightShift(p,x,nb);
  else if(x[nb-1]==0 && q0==1) //0-1 condition
     printf(" A + M ");
     i=0;
     while(i<nb)</pre>
       printf("%d",y[i++]);
     i=0;
     while(i<nb)</pre>
       p[nb-i-1]+=y[nb-i-1];
       if(p[nb-i-1]==2)
```



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```
p[nb-i-1]=0;
       if(nb-i-1!=0)
       p[nb-i-2]++;
    }
    if(p[nb-i-1]==3)
       p[nb-i-1]=1;
       if(nb-i-1!=0)
       p[nb-i-2]++;
    j++;
  }
  printf("\n
                  ");
  i=0;
  while(i<nb)
    printf("%d",p[i++]);
  printf("\n");
  q0=x[nb-1];
  rightShift(p,x,nb);
else if(x[nb-1]==1 && q0==0) //1-0 condition
  printf(" A - M ");
  i=0;
  while(i<nb)</pre>
    printf("%d",ym[i++]);
  i=0;
  while(i<nb)
    p[nb-i-1]+=ym[nb-i-1];
    if(p[nb-i-1]==2)
       p[nb-i-1]=0;
       if(nb-i-1!=0)
       p[nb-i-2]++;
    if(p[nb-i-1]==3)
       p[nb-i-1]=1;
       if(nb-i-1!=0)
       p[nb-i-2]++;
    i++;
  printf("\n
                  ");
  i=0;
```



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```
while(i<nb)
          printf("%d",p[i++]);
       printf("\n");
       q0=x[nb-1];
       rightShift(p,x,nb);
    else if(x[nb-1]==1 && q0==1) //1-1 condition
       q0=x[nb-1];
       rightShift(p,x,nb);
    }
  }
  printf("%d
                   ",j);
  i=0;
  while(i<nb)</pre>
    printf("%d",p[i++]);
  printf(" ");
  i=0;
  while(i<nb)
    printf("%d",x[i++]);
  printf(" ");
  printf("%d\n",q0);
  printf("\n");
  printf("Final Product in signed binary number is : ");
  i=0;
  while(i<nb)
    printf("%d",p[i++]);
  i=0;
  printf(" ");
  while(i<nb)</pre>
    printf("%d",x[i++]);
  printf("\n\n");
  return 0;
void rightShift(int p[],int x[],int nb)
  int i=0;
  while(nb-i-1)
    x[nb-i-1]=x[nb-i-2];
    i++;
  }
  x[0]=p[nb-1];
  i=0;
  while(nb-i-1)
```



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```
{
    p[nb-i-1]=p[nb-i-2];
    i++;
}
```

OUTPUT:

```
BOOTH's Algorithm
Enter two numbers that are to be multiplied: 20 35
Multiplicand (Q) -> 0100011
Multiplier (M) 20 -> 0010100
we use -(M) i.e. -20 -> 1101100
n
           A
                   Q
                             Q-1
0
          0000000 0100011 0
    A - M 1101100
          1101100
          1110110 0010001 1
2
          1111011 0001000 1
    A + M 0010100
          0001111
          0000111 1000100 0
3
4
5
          0000011 1100010 0
          0000001 1110001 0
    A - M 1101100
          1101101
          1110110 1111000 1
    A + M 0010100
          0001010
          0000101 0111100 0
Final Product in signed binary number is: 0000101 0111100
...Program finished with exit code 0
Press ENTER to exit console.
```

EXPERIMENT - 2

AIM: To demonstrate the Restoring Division Algorithm for 2 unsigned binary numbers.

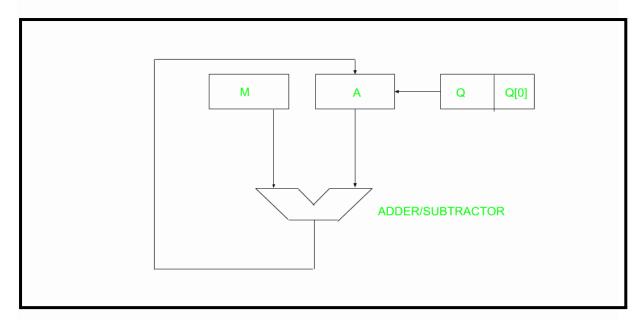
Submission Sheet

SAP ID	Name of Student	Date of Experiment	Date of Submission	Remarks
60004190057	Junaid Girkar	08-10-2021	08-10-2021	

THEORY:

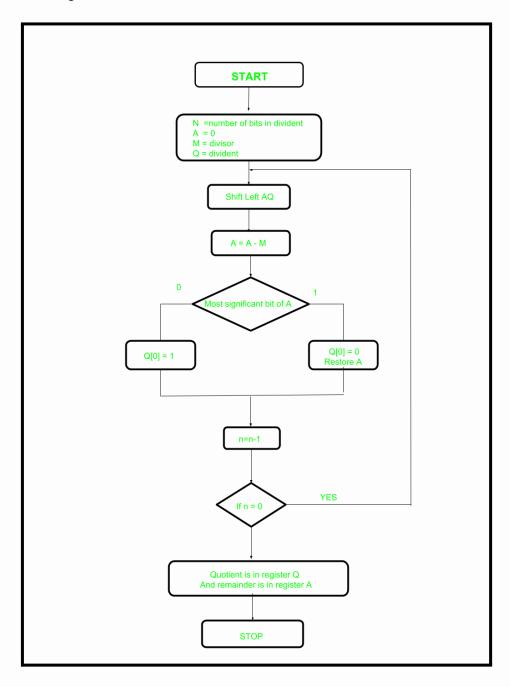
A division algorithm provides a quotient and a remainder when we divide two number. They are generally of two type **slow algorithm and fast algorithm**. Slow division algorithm are restoring, non-restoring, non-performing restoring, SRT algorithm and under fast comes Newton–Raphson and Goldschmidt.

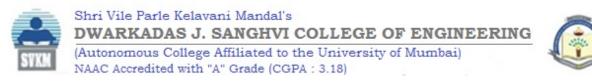
In this article, will be performing restoring algorithm for unsigned integer. Restoring term is due to fact that value of register A is restored after each iteration.





Here, register Q contain quotient and register A contain remainder. Here, n-bit dividend is loaded in Q and divisor is loaded in M. Value of Register is initially kept 0 and this is the register whose value is restored during iteration due to which it is named Restoring.





Let's pick the step involved:

- Step-1: First the registers are initialized with corresponding values (Q = Dividend, M = Divisor, A = 0, n = number of bits in dividend)
- **Step-2:** Then the content of register A and Q is shifted right as if they are a single unit
- Step-3: Then content of register M is subtracted from A and result is stored in
- Step-4: Then the most significant bit of the A is checked if it is 0 the least significant bit of Q is set to 1 otherwise if it is 1 the least significant bit of Q is set to 0 and value of register A is restored i.e the value of A before the subtraction with M
- **Step-5:** The value of counter n is decremented
- **Step-6:** If the value of n becomes zero we get of the loop otherwise we repeat fro step 2
- Step-7: Finally, the register Q contain the quotient and A contain remainder



Examples:

Perform Division Restoring Algorithm Dividend = 11

Divisor = 3

n	М	А	Q	Operation
4	00011	00000	1011	initialize
	00011	00001	011_	shift left AQ
	00011	11110	011_	A=A-M
	00011	00001	0110	Q[0]=0 And restore A
3	00011	00010	110_	shift left AQ
	00011	11111	110_	A=A-M
	00011	00010	1100	Q[0]=0
2	00011	00101	100_	shift left AQ
	00011	00010	100_	A=A-M
	00011	00010	1001	Q[0]=1
1	00011	00101	001_	shift left AQ
	00011	00010	001_	A=A-M
	00011	00010	0011	Q[0]=1

Remember to restore the value of A, most significant bit of A is 1. As that register Q contains the quotient, i.e. 3 and register A contains remainder 2.

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#include<stdio.h> #include<conio.h> #include<math.h>



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```
int getsize(int x)
{
int c;
if(x <= 1)
c = 2;
else if (x < 4)
c = 2;
else if(x< 8)
c = 3;
else if(x < 16)
c = 4;
else if(x < 32)
c = 5;
else if(x < 64)
c = 6;
else if(x< 128)
c = 7;
else if(x< 256)
c = 8;
else if(x< 512)
c = 9;
return c;
int max(int x,int y)
if(x < y)
return(y);
else
return(x);
void main()
int B,Q,Z,M,c,c1,e,f,g,h,i,j,x,y,ch,in,S,G,P;
int a[24],b[12],b1[12],q[12],carry=0,count=0,option;
long num;
printf("|\t\tPROGRAM FOR RESTORING DIVISION\t\t|\n");
```



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```
printf("\n\nENTER DIVIDEND\t: ");
scanf("%d",&Q);
y = getsize(Q);
printf("ENTER DIVISOR\t: ");
scanf("%d",&M);
x = getsize(M);
Z = max(x,y);
printf("\n\tTOTAL BITS CONSIDERED FOR RESULT => %d",2*Z+1);
printf("\n\tINITiALLY A IS RESET TO ZERO:");
for(i=0;i<=Z;i++)
printf("%d ",a[i]=0);
for(i=Z;i>=0;i--)
b1[i] = b[i] = M%2;
M = M/2;
b1[i] = 1-b1[i];
carry = 1;
for(i=Z;i>=0;i--)
c1 = b1[i]^carry;
carry = b1[i]&&carry;
b1[i]=c1;
for(i=2*Z;i>Z;i--)
a[i] = Q%2;
Q = Q/2;
printf("\n\n\tDivisor\t\t(M)\t: ");
for(i=0;i<=Z;i++)
printf("%d ",b[i]);
printf("\n\t2'C Divisor\t(-M)\t: ");
for(i=0;i<=Z;i++)
printf("%d ",b1[i]);
printf("\n\tDividend\t(Q)\t: ");
for(i=Z+1;i<=2*Z;i++)
printf("%d ",a[i]);
printf("\n\n\tBITS CONSIDERED:[ A ]\t [ M ]");
```



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```
printf("\n\t\t\t");
for(i=0;i<=Z;i++)
printf("%d ",a[i]);
printf(" ");
for(i=Z+1;i<=2*Z;i++)
printf("%d ",a[i]);
count = Z;
do{
for(i=0;i<2*Z;i++)
a[i] = a[i+1];
printf("\n\nLeft Shift\t\t");
for(i=0;i<=Z;i++)
printf("%d ",a[i]);
printf(" ");
for(i=Z+1;i< 2*Z;i++)
printf("%d ",a[i]);
carry=0;
for(i=Z;i>=0;i--)
S=a[i]^(b1[i]^carry);
G=a[i]&&b1[i];
P=a[i]^b1[i];
carry=G||(P&&carry);
a[i]=S;
printf("\nA< -A-M \t\t");</pre>
for(i=0;i<=Z;i++)
printf("%d ",a[i]);
printf(" ");
for(i=Z+1;i<2*Z;i++)
printf("%d ",a[i]);
ch=a[0];
printf("\nBIT Q:%d",ch);
switch (ch)
case 0: a[2*Z]=1;
printf(" Q0< -1\t\t");</pre>
for(i=0;i<=Z;i++)
printf("%d ",a[i]);
```



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```
printf(" ");
for(i=Z+1;i<=2*Z;i++)
printf("%d ",a[i]);
break;
case 1: a[2*Z]=0;
printf(" Q0< -0\t\t");</pre>
for(i=0;i<=Z;i++)
printf("%d ",a[i]);
printf(" ");
for(i=Z+1;i< 2*Z;i++)
printf("%d ",a[i]);
carry=0;
for(i=Z;i>=0;i--)
S=a[i]^(b[i]^carry);
G=a[i]&&b[i];
P=a[i]^b[i];
carry=G||(P&&carry);
a[i]=S;
printf("\nA< -A+M");</pre>
printf("\t\t");
for(i=0;i<=Z;i++)
printf("%d ",a[i]);
printf(" ");
for(i=Z+1;i<=2*Z;i++)
printf("%d ",a[i]);
break;
count--;
}while(count!=0);
num=0;
printf("\n\n\t\tQUOTIENT IN BITS :");
for(i=Z+1;i<=2*Z;i++)
printf("%d ",a[i]);
num=num+pow(2,2*Z-i)*a[i];
```



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```
printf("\n\t\tOUOTIENT IN DECIMAL :%Id",num);
num=0;
printf("\n\t\tREMAINDER IN BITS :");
for(i=0;i<=Z;i++)
{
    printf("%d ",a[i]);
    num=num+pow(2,Z-i)*a[i];
}
printf("\n\t\tREMAINDER IN DECIMAL :%Id",num);
getch();
getch();
}</pre>
```



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OUTPUT:

0011 01.															
1		PROGRAM	FC	OR	RE	181	OF	RIN	G I)I(718	310	ON		;
вишер р	IVIDEND	. 17													
	VIDEND														
		TS CONS													
	INITIALI	LY A IS I	RES	3EJ	ניים	O	ZI	ERO	0:0	0	0	0	0	0	
	Divisor		(1)	1)			:	0	0 0) 1	L () ()		
	2'C Divi	sor	(-	-M)			:	1	1 1	. 1	. () ()		
	Dividend	i	((2)			:	1	0 0) () 1	L			
	BITS CON	SIDERED:													
			0	0	0	0	0	0	1	0	0	0	1		
Left Shi	ft		0	0	0	0	0	1	0	0	0	1			
A< -A-M									0						
BIT Q:1	Q0< -0		1	1	1	1	0	1	0	0	0	1			
M+A- >A									0				0		
Left Shi	ft		0	0	0	0	1	0	0	0	1	0			
M-A- >A			1	1	1	1	1	0	0	0	1	0			
BIT Q:1	Q0< -0		1	1	1	1	1	0	0	0	1	0			
M+A- >A			0	0	0	0	1	0	0	0	1	0	0		
Left Shi	ft		0	0	0	1	0	0	0	1	0	0			
A< -A-M			0	0	0	0	0	0	0	1	0	0			
BIT Q:0	Q0< -1		0	0	0	0	0	0	0	1	0	0	1		
Left Shi	ft		0	0	0	0	0	0	1	0	0	1			
A< -A-M			1	1	1	1	0	0	1	0	0	1			
BIT Q:1	Q0< -0		1	1	1	1	0	0	1	0	0	1			
A< -A+W			0	0	0	0	0	0	1	0	0	1	0		
Left Sh	ft		0	0	0	0	0	1	0	0	1	0			
A< -A-M			1	1	1	1	0	1	0	0	1	0			
BIT Q:1	Q0< -0		1	1	1	1	0	1	0	0	1	0			
M+A- >A			0	0	0	0	0	1	0	0	1	0	0		
		QUOTIENT		IN	В	TS	3 :	0	0 1) ()			
		OUOTIENT	!	N	DE	C	MZ	ΛL	: 4						
		REMAINDE	ER	11	I	311	!S	: 0	0	0	0	0	1		
		REMAINDE	cR	II	I)E(!IN	IAL	:1	Ļ					

CONCLUSION: From this experiment, we learn how to use the restoring division algorithm to divide unsigned bits. We understood that it is a type of slow algorithm along with non-restoring division. We also learn how to write the code for the same algorithm in C language and implement it successfully.

EXPERIMENT - 3

Aim: To study and implement non-restoring division algorithms.

Submission Sheet

SAP ID	Name of Student	Date of Experiment	Date of Submission	Remarks
60004190057	Junaid Girkar	30-10-2021	30-10-2021	

Theory

A division algorithm is an algorithm which, given two integers N and D, computes their quotient and/or remainder, the result of Euclidean division. Division algorithms fall into two main categories: slow division and fast division. Slow division algorithms produce one digit of the final quotient per iteration. Examples of slow division include restoring, non-performing restoring, non-restoring, and SRT division. Fast division methods start with a close approximation to the final quotient and produce twice as many digits of the final quotient on each iteration.

Newton-Raphson and Goldschmidt algorithms fall into this category.

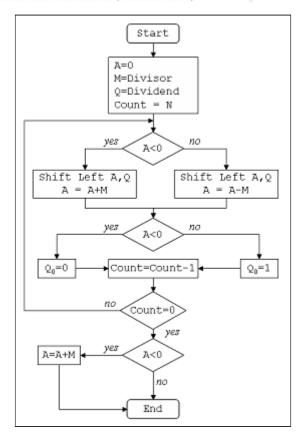
Non-Restoring division, it is less complex than the restoring one because simpler operations are involved i.e. addition and subtraction, also now the restoring step is performed. In the method, rely on the sign bit of the register which initially contains zero named as A.

Here is the flow chart given below.

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Algorithm

- 1) Set the value of register A as 0 (N bits)
- 2) Set the value of register M as Divisor (N bits)
- 3) Set the value of register Q as Dividend (N bits)
- 4) Concatenate A with Q {A,Q}
- 5) Repeat the following "N" number of times (here N is no. of bits in divisor):

```
If the sign bit of A equals 0,
shift A and Q combined left by 1 bit and subtract M from A,
else shift A and Q combined left by 1 bit and add M to A
Now if sign bit of A equals 0, then set Q[0] as 1, else set Q[0]
```

- 6) Finally if the sign bit of A equals 1 then add M to A.
- 7) Assign A as remainder and Q as quotient.

Example:

Dividend (A) = 101110, ie 46, and Divisor (B) = 010111, ie 23.



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Initialization:

Set Register A = Dividend = 000000
Set Register Q = Dividend = 101110
(So AQ = 000000 101110, Q0 = LSB of Q = 0)
Set M = Divisor = 010111, M' = 2's complement of M = 101001
Set Count = 6, since 6 digits operation is being done here.

After this we start the algorithm, which I have shown in a table below: In the table, SHL(AQ) denotes shift left AQ by one position leaving Q0 blank. Similarly, a square symbol in Q0 position denote, it is to be calculated later

Action	Α	Q	Count
Initial	000 000	101 110	6
$A > 0 \Rightarrow SHL (AQ)$	000 001	011 10□	
A = A-M	101 010	011 10□	
A < 0 => Q0 = 0	101 010	011 100	5
$A < 0 \Rightarrow SHL (AQ)$	010 100	111 00□	
A = A+M	101 011	111 00□	
$A < 0 \Rightarrow Q0 = 0$	101 011	111 000	4
A < 0 => SHL (AQ)	010 111	110 00□	
A = A+M	101 110	110 00□	
A < 0 => Q0 = 0	101 110	110 000	3
A < 0 => SHL (AQ)	011 101	100 00□	
A = A+M	110 100	100 00□	
A < 0 => Q0 = 0	110 100	100 000	2
A < 0 => SHL (AQ)	101 001	000 00□	
A = A+M	000 000	000 00□	
A < 0 => Q0 = 1	000 000	000 001	1
$A > 0 \Rightarrow SHL(AQ)$	000 000	000 01□	
A = A+M	101 001	000 01□	
A < 0 => Q0 = 1	101 001	000 010	0
Count has rea	ched Zero,	So final ste	ps
A < 0 => A = A+M	000 000	000 010	
	Reminder	Quotient	



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CODE:

```
#include<stdio.h>
#include<malloc.h>
int *a,*q,*m,*mc,*c,n,d;
int powr(int x,int y)
int s=1,i;
for(i=0;i<y;i++)</pre>
  s=s*x;
return s;
}
void print(int arr[],int n)
int i;
for(i=0;i<n;i++)</pre>
 printf("%d ",arr[i]);
void bin(int n, int arr[]){
    int r, i = 0;
    do{
        r = n \% 2;
        n /= 2;
        arr[i] = r;
        i++;
    }while(n > 0);
void set(int array[], int x){
    int i, tmp[20] = \{0\};
    for(i = x -1; i >= 0; i--)
 tmp[x-1-i]=array[i];
for(i=0;i<x;i++)</pre>
 array[i]=tmp[i];
int len(int x)
int i=0;
while(powr(2,i)<=x) i++;</pre>
return ++i;
```



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```
void addBinary(int a1[], int a2[])
    int bi[2]=\{0\}, ca[20]=\{0\};
    int t=len(n),tmp=0;
    int *su=(int*)malloc(sizeof(int)*len(n));
while(t-->0)
{
 tmp=a1[t]+a2[t]+ca[t];
 bin(tmp,bi);
 su[t]=bi[0];
 ca[t-1]=bi[1];
 bi[0]=0;bi[1]=0;
}
for(t=0;t<len(n);t++)</pre>
 a1[t]=su[t];
free(su);
}
void twoCom(int arr[]){
    int i;
    int *one=(int*)malloc(sizeof(int)*len(n));
    for(i=0;i<len(n)-1;i++)</pre>
 one[i]=0;
one[i]=1;
    for(i = 0; i < len(n); i++){}
        arr[i]=1-arr[i];
    addBinary(arr, one);
    free(one);
void ls(int alen,int blen)
int i=0;
for(i=0;i<alen-1;i++)</pre>
 a[i]=a[i+1];
a[i]=q[0];
for(i=0;i<blen-1;i++)</pre>
 q[i]=q[i+1];
q[i]=-1;
}
```



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```
void printag()
print(a,len(n));
printf("\t");
print(q,len(n)-1);
printf("\t");
printf("\n");
int main()
int i,cnt=0;
printf("Enter The Numerator/Denominator: ");
scanf("%d/%d",&n,&d);
q=(int*)malloc(sizeof(int)*len(n)-1);
bin (n,q);
m=(int*)malloc(sizeof(int)*(len(n)));
bin(d,m);
a=(int*)malloc(sizeof(int)*(len(n)));
for(i=0;i<len(n);i++)</pre>
 a[i]=0;
mc=(int*)malloc(sizeof(int)*(len(n)));
bin(d,mc);
set(q,len(n)-1);
set(m,len(n));
set(mc,len(n));
twoCom(mc);
cnt=len(n)-1;
printf("\t A\t\t Q\t\t M\t Count\n");
printf("\t-----\t\t-----\t\t-----
while(cnt>0)
 printf("\t");
 print(a,len(n));
 printf("\t");
 print(q,len(n)-1);
 printf("\t");
 print(m,len(n));
 printf("\t%d\n",cnt);
 if(a[0]==1)
 {
```



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```
ls(len(n), len(n)-1);
   printf("LSHIFT\t");
   printag();
   addBinary(a,m);
   printf("A=A+M\t");
  printaq();
  }
 else
   ls(len(n), len(n)-1);
  printf("LSHIFT\t");
   printaq();
   addBinary(a,mc);
   printf("A=A-M\t");
  printaq();
 if(a[0]==1)
   q[len(n)-2]=0;
  addBinary(a,m);
 }
 else
   q[len(n)-2]=1;
 printf("A=A+M\t");
 printaq();
 cnt-=1;
 printf("\n");
}
return 0;
}
```



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OUTPUT:

Enter T	he	Mı	1me	a 773	ato	r/Den	om:	i na	a tr	ar.	10/3	Į.						
Liicer i	110	IVI	A	510	100	L/ Dell	Jill.		2	<i>.</i>	10/5	,			M			Count
	-	-					-						-	-				
	0	0	0	0	0		1	0	1	0			0	0	0	1	1	4
LSHIFT	0	0	0	0	1		0	1	0	-1								
A=A-M	1	1	1	1	0		0	1	0	-1								
A=A+M	0	0	0	0	1		0	1	0	0								
	0	0	0	0	1		0	1	0	0			0	0	0	1	1	3
LSHIFT	0	0	0	1	0		1	0	0	-1								
A=A-M	1	1	1	1	1		1	0	0	-1								
A=A+M	0	0	0	1	0		1	0	0	0								
	0	0	0	1	0		1	0	0	0			0	0	0	1	1	2
LSHIFT	0	0	1	0	1		0	0	0	-1								
A=A-M	0	0	0	1	0		0	0	0	-1								
A=A+M	0	0	0	1	0		0	0	0	1								
	0	0	0	1	0		0	0	0	1			0	0	0	1	1	1
LSHIFT	0	0	1	0	0		0	0	1	-1								
A=A-M	0	0	0	0	1		0	0	1	-1								
A=A+M	0	0	0	0	1		0	0	1	1								

Conclusion:

The non-restorative division algorithm is an efficient way to perform binary division compared to traditional subtractive based algorithms by using the faster processed bit shift commands in the CPU registers. The algorithm is simple enough to be implemented in hardware in equipment like Arithmometers while also generalising to complex modern day systems. The algorithm serves as a good example in showing that considering lower-level system dependencies and physical limitations can be used to optimize algorithms. Non-restorative algorithm is more efficient than restorative algorithm as it uses simpler commands in terms of addition and subtraction, however it is slower than other algorithms.

EXPERIMENT - 4

Aim:

Implement Sequential memory organization with following details:

- Processor can access 1 word = 4 bytes.
- L1 cache can store max = 32 words.
- L2 cache can store max =128 words.
- Main memory can store max = 2048 bytes.

Submission Sheet

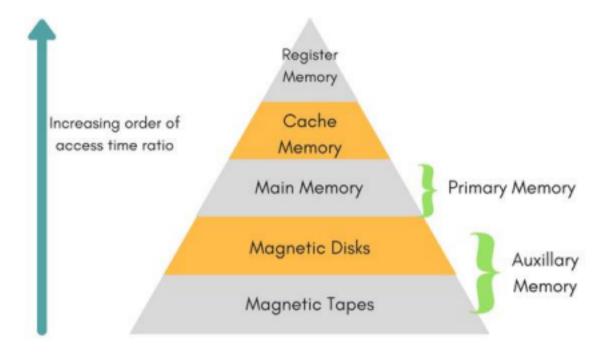
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60004190057	Junaid Girkar	30-10-2021	30-10-2021	

Theory:

In Computer System Design, Memory Hierarchy is an enhancement to organize the memory such that it can minimize the access time. The Memory Hierarchy was developed based on a program behaviour known as locality of references. The figure below clearly demonstrates the different levels of memory hierarchy:







This Memory Hierarchy Design is divided into 2 main types:

- External Memory or Secondary Memory Comprising of Magnetic Disk, Optical Disk, Magnetic Tape i.e., peripheral storage devices which are accessible by the processor via I/O Module.
- Internal Memory or Primary Memory Comprising of Main Memory, Cache Memory & CPU registers. This is directly accessible by the processor.

Levels of memory:

• Level 1 or Register –

It is a type of memory in which data is stored and accepted that are immediately stored in CPU. Most commonly used register is accumulator, Program counter, address register etc.

• Level 2 or Cache memory –

It is the fastest memory which has faster access time where data is temporarily stored for faster access.

• Level 3 or Main Memory –

It is memory on which computer works currently. It is small in size and once power is off data no longer stays in this memory.



• Level 4 or Secondary Memory –

It is external memory which is not as fast as main memory but data stays permanently in this memory.

Types of Cache:

• Primary Cache –

A primary cache is always located on the processor chip. This cache is small and its access time is comparable to that of processor registers.

• Secondary Cache -

Secondary cache is placed between the primary cache and the rest of the memory. It is referred to as the level 2 (L2) cache. Often, the Level 2 cache is also housed on the processor chip.

Code:

```
memory.cpp
#include<bits/stdc++.h>
#include<time.h>
using namespace std;
int main() {
vector<double> lc1(32,-1);
vector<double> lc2(64,-1);
 double lc1Time = 20;
 double lc2Time = 60;
 double mainMemoryTime = 120;
 double totalHits = 0;
 double lc1Hits = 0;
 double lc2Hits = ∅;
 double count = 0;
 int fr1 = -1;
int re1 = 0;
 int fr2 = -1;
int re2 = 0;
char key = 100;
 srand(time(∅));
 cout<<"Sequential Memory Organization:"<<endl<<endl;</pre>
 cout<<" "<<"Requirement"<<setw(22)<<"Location of Hit"<<" "<<setw(15)<<"Avg.</pre>
Access Time"<<endl;
while(key--) {
 count++;
```



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```
double avgTime = 0;
double input = rand()%512;
bool f1 = false;
bool f2 = false;
for(double i=0; i<32; i++) {
if(lc1[i]==input) {
lc1Hits++;
f1 = true;
f2 = true;
avgTime += (lc1Hits/(count))*lc1Time + (1-
(lc1Hits/(count)))*(lc2Hits/(count-lc1Hits))*(lc1Time+lc2Time) + (1-
(lc1Hits/(count)))*(1-(lc2Hits/(count
lc1Hits)))*1*(lc1Time+lc2Time+mainMemoryTime);
cout<<setw(12)<<input<<" "<<setw(20)<<"L1 Cache"<<"</pre>
"<<setw(8)<<avgTime<<endl;
}
if(!f1) {
double b = input/2;
for(double i=0; i<64; i++) {
if(lc2[i]==b) {
lc2Hits++;
f2 = true;
// found in 2
if(re1==fr1) {
re1 = (re1+1)\%32;
fr1 = (fr1+1)\%32;
lc1[fr1] = input;
avgTime += (lc1Hits/(count))*lc1Time + (1-
(lc1Hits/(count)))*(lc2Hits/(count-lc1Hits))*(lc1Time+lc2Time) + (1-
(lc1Hits/(count)))*(1-(lc2Hits/(count
lc1Hits)))*1*(lc1Time+lc2Time+mainMemoryTime);
cout<<setw(12)<<input<<" "<<setw(20)<<"L2 Cache"<<" "<<setw(8)<<avgTime<<endl;</pre>
}
}
}
if(!f2) {
double b = input/2;
if(re2==fr2) {
re2 = (re2+1)\%64;
}
fr2 = (fr2+1)\%64;
lc2[fr2] = b;
if(re1==fr1) {
re1 = (re1+1)\%32;
```



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```
}
 fr1 = (fr1+1)\%32;
 lc1[fr1] = input;
  avgTime += (lc1Hits/(count))*lc1Time + (1-
(lc1Hits/(count)))*(lc2Hits/(count-lc1Hits))*(lc1Time+lc2Time) + (1-
(lc1Hits/(count)))*(1-(lc2Hits/(count
lc1Hits)))*1*(lc1Time+lc2Time+mainMemoryTime);
 cout<<setw(12)<<input<<" "<<setw(20)<<"Main Memory"<<"</pre>
"<<setw(8)<<avgTime<<endl;
 }
 }
 cout<<endl;
  cout<<"L1 Hit Ratio (H1) = "<<lc1Hits<<"/"<<count<<" =</pre>
"<<(double)lc1Hits/count<<endl;</pre>
 cout<<"L1 Access Time (T1) = "<<lc1Time<<" ns"<<endl<<endl;</pre>
 cout<<"L2 Hit Ratio (H2) = "<<lc2Hits<<"/"<<(count-lc1Hits)<<" =</pre>
"<<(double)lc2Hits/(count-lc1Hits)<<endl;</pre>
 cout<<"L2 Access Time (T2) = "<<lc2Time<<" ns"<<endl<<endl;</pre>
 cout<<"Main Memory Hit Ratio (Hm) = "<<1<<endl;</pre>
  cout<<"Main memory Access Time = "<<mainMemoryTime<<" ns"<<endl<<endl;</pre>
 cout<<"Average Access Time = [H1*T1] + [(1-H1)*H2*(T1+T2)] + [(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(1-H1)*(
H2)*Hm*(T1+T2+Tm)]"<<endl;
 double finalAns = ((double)lc1Hits/count)*lc1Time + (1-
((double)lc1Hits/count))*((double)lc2Hits/(100-lc1Hits))*(lc1Time+lc2Time) + (1-
((double)lc1Hits/count))*(1-((double)lc2Hits/(count
lc1Hits)))*1*(lc1Time+lc2Time+mainMemoryTime);
 cout<<"Average Access Time = "<<finalAns<<" ns"<<endl;</pre>
 return 0;
```

Output:

```
Sequential Memory Organization:
Requirement Location of Hit Avg. Access Time
353 Main Memory 200
372 Main Memory 200
89 Main Memory 200
189 Main Memory 200
265 Main Memory 200
423 Main Memory 200
379 Main Memory 200
107 Main Memory 200
8 Main Memory 200
217 Main Memory 200
```



87 Main Memory 191.429

Shri Vile Parle Kelavani Mandal's

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155 Main Memory 200 294 Main Memory 200 192 Main Memory 200 47 Main Memory 200 348 Main Memory 200 217 L1 Cache 188.75 264 Main Memory 189.412 375 Main Memory 190 100 Main Memory 190.526 351 Main Memory 191 476 Main Memory 191.429 12 Main Memory 191.818 178 Main Memory 192.174 138 Main Memory 192.5 338 Main Memory 192.8 250 Main Memory 193.077 306 Main Memory 193.333 363 Main Memory 193.571 208 Main Memory 193.793 99 Main Memory 194 143 Main Memory 194.194 205 Main Memory 194.375 381 Main Memory 194.545 34 Main Memory 194.706 329 Main Memory 194.857 259 Main Memory 195 245 Main Memory 195.135 429 Main Memory 195.263 7 Main Memory 195.385 228 Main Memory 195.5 65 Main Memory 195.61 320 Main Memory 195.714 46 Main Memory 195.814 19 Main Memory 195.909 262 Main Memory 196 56 Main Memory 196.087 178 L1 Cache 192.34 132 Main Memory 192.5 252 Main Memory 192.653 189 L2 Cache 190.4 301 Main Memory 190.588 315 Main Memory 190.769 418 Main Memory 190.943 163 Main Memory 191.111 302 Main Memory 191.273



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49 Main Memory 191.579 402 Main Memory 191.724 467 Main Memory 191.864 80 Main Memory 192 462 Main Memory 192.131 101 Main Memory 192.258 410 Main Memory 192.381 125 Main Memory 192.5 3 Main Memory 192.615 465 Main Memory 192.727 116 Main Memory 192.836 217 L2 Cache 191.176 368 Main Memory 191.304 71 Main Memory 191.429 27 Main Memory 191.549 262 L1 Cache 189.167 190 Main Memory 189.315 283 Main Memory 189.459 166 Main Memory 189.6 146 Main Memory 189.737 469 Main Memory 189.87 229 Main Memory 190 347 Main Memory 190.127 122 Main Memory 190.25 335 Main Memory 190.37 296 Main Memory 190.488 452 Main Memory 190.602 492 Main Memory 190.714 44 Main Memory 190.824 305 Main Memory 190.93 261 Main Memory 191.034 81 Main Memory 191.136 455 Main Memory 191.236 66 Main Memory 191.333 364 Main Memory 191.429 139 Main Memory 191.522 8 Main Memory 191.613 240 Main Memory 191.702 74 Main Memory 191.789 379 Main Memory 191.875 476 Main Memory 191.959 458 Main Memory 192.041 1 Main Memory 192.121 455 L1 Cache 190.4 L1 Hit Ratio (H1) = 4/100 = 0.04L1 Access Time (T1) = 20 ns



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```
L2 Hit Ratio (H2) = 2/96 = 0.0208333

L2 Access Time (T2) = 60 ns

Main Memory Hit Ratio (Hm) = 1

Main memory Access Time = 120 ns

Average Access Time = [H1*T1] + [(1-H1)*H2*(T1+T2)] + [(1-H1)*(1-H2)*Hm*(T1+T2+Tm)]

Average Access Time = 190.4 ns
```

Conclusion:

We learnt about sequential memory organization and implemented it in C++ programming language successfully on the given problem statement in a 2-Level Cache Memory architecture for 100 different number words required by the processor.

EXPERIMENT - 5

AIM: To simulates a direct-mapped cache

Submission Sheet

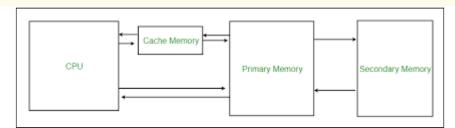
SAP ID	Name of Student	Date of Experiment	Date of Submission	Remarks
60004190057	Junaid Girkar	17-12-2021	17-12-2021	

THEORY:

cache memory, also called cache, supplementary memory system that temporarily stores frequently used instructions and data for quicker processing by the central processing unit (CPU) of a computer. The cache augments, and is an extension of, a computer's main memory. Both main memory and cache are internal random-access memories (RAMs) that use semiconductor-based transistor circuits. Cache holds a copy of only the most frequently used information or program codes stored in the main memory. The smaller capacity of the cache reduces the time required to locate data within it and provide it to the CPU for processing.

When a computer's CPU accesses its internal memory, it first checks to see if the information it needs is stored in the cache. If it is, the cache returns the data to the CPU. If the information is not in the cache, the CPU retrieves it from the main memory. Disk cache memory operates similarly, but the cache is used to hold data that have recently been written on, or retrieved from, a magnetic disk or other external storage device.

Hit ratio = hit / (hit + miss) = no. of hits/total accesses.



DIRECT CACHE MAPPING:

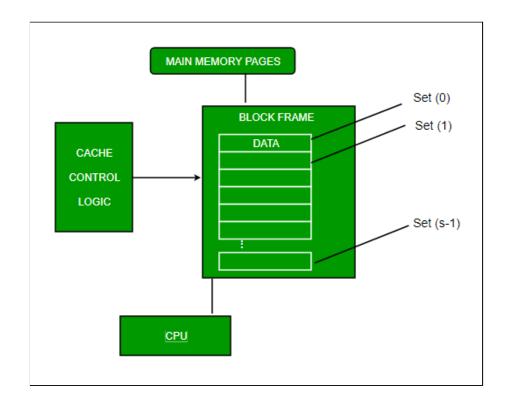


The simplest technique, known as direct mapping, maps each block of main memory into only one possible cache line. or

In Direct mapping, assign each memory block to a specific line in the cache. If a line is previously taken up by a memory block when a new block needs to be loaded, the old block is trashed. An address space is split into two parts: index field and a tag field. The cache is used to store the tag field whereas the rest is stored in the main memory. Direct mapping's performance is directly proportional to the Hit ratio.

```
i = j modulo m
where
i=cache line number
j= main memory block number
m=number of lines in the cache
```

For purposes of cache access, each main memory address can be viewed as consisting of three fields. The least significant w bits identify a unique word or byte within a block of main memory. In most contemporary machines, the address is at the byte level. The remaining s bits specify one of the 2s blocks of main memory. The cache logic interprets these s bits as a tag of s-r bits (most significant portion) and a line field of r bits. This latter field identifies one of the m=2r lines of the cache.



8 Bit:

NXVZ

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CODE:

```
#include <stdio.h>
int tag[8];
int main()
  int addr:
  int i, j, t;
  int hits, accesses;
  FILE *fp;
  fp = fopen("trace.txt", "r");
  hits = 0:
  accesses = 0;
  while (fscanf(fp, "%x", &addr) > 0) {
    /* simulate a direct-mapped cache with 8 words */
    accesses += 1;
    printf("%3d: 0x%08x ", accesses, addr);
    i = (addr >> 2) & 7;
    t = addr | 0x1f;
    if (tag[i] == t) {
       hits += 1:
       printf("Hit%d", i);
    } else {
       /* allocate entry */
       printf("Miss");
      tag[i] = t;
    for (i = 0; i < 8; i++)
       printf("0x%08x ", tag[i]);
    printf("\n");
  printf("Hits = %d, Accesses = %d, Hit ratio = %f\n", hits, accesses,
((float)hits)/accesses);
  close(fp);
```

OUTPUT:



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3:	0x80000008	Miss	0x8000001f	0x8000001f	0x8000001f	0x00000000	0x00000000	0x00000000	0x00000000	0×00000000
4:	0x8000000c	Miss	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000	0x00000000	0x00000000	0x00000000
5:	0x00000020	Miss	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x00000000	0x00000000	0x00000000	0x00000000
6:	0x80000010	Miss	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000	0x00000000	0x00000000
7:	0x80000014	Miss	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000	0x00000000
8:	0x80000018	Miss	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000
9:	0x8000000c	Hit3	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000
10:	0x00000024	Miss	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000
	0x80000010									
	0x80000014									
	0x80000018									
	0x8000000c									
	0x00000028									
	0x80000010									
	0x80000014									
	0x80000018 0x8000000c									
	0x0000002c									
	0x80000010									
	0x80000010									
	0x80000014 0x80000018									
	0x80000010									
	0x000000000000000000000000000000000000									
	0x80000010									
	0x80000014									
	0x80000018									
	0x8000000c									
	0x00000034									
31:	0x80000010	Hit4	0x0000003f	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x0000003f	0x8000001f	0x00000000
32:	0x80000014	Miss	0x0000003f	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000
33:	0x80000018	Hit6	0x0000003f	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000
34:	0x8000000c	Hit3	0x0000003f	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000
35:	0x00000038	Miss	0x0000003f	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x0000003f	0x00000000
36:	0x80000010	Hit4	0x0000003f	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x0000003f	0x00000000
37:	0x80000014	Hit5	0x0000003f	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x0000003f	0x00000000
38:	0x80000018	Miss	0x0000003f	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000
39:	0x8000000c	Hit3	0x0000003f	0x0000003f	0x0000003f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x00000000
	0x0000003c									
	0x80000010									
	0x80000014									
	0x80000018									
	0x8000000c									
	0x00000040									
	0x80000010									
	0x80000014									
	0x80000018									
	0x8000000c 0x00000044									
	0x80000010									
	0x80000010									
	0x80000014 0x80000018									
	0x80000016									
	0x000000000000000000000000000000000000									
	0x80000010									
	0x80000014									
	0x80000018									
59:	0x8000000c	Hit3	0x0000005f	0x0000005f	0x0000005f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x0000003f
60:	0x0000004c	Miss	0x0000005f	0x0000005f	0x0000005f	0x0000005f	0x8000001f	0x8000001f	0x8000001f	0x0000003f
61:	0x80000010	Hit4	0x0000005f	0x0000005f	0x0000005f	0x0000005f	0x8000001f	0x8000001f	0x8000001f	0x0000003f
62:	0x80000014	Hit5	0x0000005f	0x0000005f	0x0000005f	0x0000005f	0x8000001f	0x8000001f	0x8000001f	0x0000003f
63:	0x80000018	Hit6	0x0000005f	0x0000005f	0x0000005f	0x0000005f	0x8000001f	0x8000001f	0x8000001f	0x0000003f
64:	0x8000000c	Miss	0x0000005f	0x0000005f	0x0000005f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x0000003f
65:	0x00000050	Miss	0x0000005f	0x0000005f	0x0000005f	0x8000001f	0x0000005f	0x8000001f	0x8000001f	0x0000003f
66:	0x80000010	Miss	0x0000005f	0x0000005f	0x0000005f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x0000003f
67:	0x80000014	Hit5	0x0000005f	0x0000005f	0x0000005f	0x8000001f	0x8000001f	0x8000001f	0x8000001f	0x0000003f
	0x80000018									
	0x8000000c									
	0x00000054									
/1:	0x80000010	HIT4	0X0000005†	0X0000005†	0X0000005†	0000001+	0000001+	0X0000005†	0X8000001†	ихииииии3†



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```
72: 0x80000014 Miss 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000003f
 73: 0x80000018 Hit6 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000003f
74: 0x8000000c Hit3 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000003f
75: 0x00000058 Miss 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x00000005f 0x00000003f
76: 0x80000010 Hit4 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000003f
77: 0x80000014 Hit5 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000003f
78: 0x80000018 Miss 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000003f
79: 0x8000000c Hit3 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000003f
 80: 0x0000005c Miss 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
81: 0x80000010 Hit4 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
82: 0x80000014 Hit5 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f
83: 0x80000018 Hit6 0x0000005f 0x00000005f 0x80000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f
84: 0x8000000c Hit3 0x0000005f 0x00000005f 0x80000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f
85: 0x00000060 Miss 0x0000007f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
86: 0x80000010 Hit4 0x0000007f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
87: 0x80000014 Hit5 0x0000007f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
88: 0x80000018 Hit6 0x0000007f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000005f
89: 0x8000000c Hit3 0x0000007f 0x00000005f 0x80000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f
90: 0x00000064 Miss 0x0000007f 0x0000007f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
91: 0x80000010 Hit4 0x0000007f 0x0000007f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f
92: 0x80000014 Hit5 0x0000007f 0x0000007f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
93: 0x80000018 Hit6 0x0000007f 0x0000007f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
94: 0x8000000c Hit3 0x0000007f 0x00000007f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
95: 0x00000068 Miss 0x0000007f 0x0000007f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f
96: 0x80000010 Hit4 0x0000007f 0x0000007f 0x0000007f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f
97: 0x80000014 Hit5 0x0000007f 0x0000007f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f
98: 0x80000018 Hit6 0x0000007f 0x00000007f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f
99: 0x8000000c Hit3 0x0000007f 0x0000007f 0x0000007f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
100: 0x0000006c Miss 0x0000007f 0x0000007f 0x00000007f 0x00000007f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
101: 0x80000010 Hit4 0x0000007f 0x0000007f 0x0000007f 0x0000007f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
102: 0x80000014 Hit5 0x0000007f 0x00000007f 0x00000007f 0x00000007f 0x8000001f 0x8000001f 0x8000001f 0x0000005f
103: 0x80000018 Hit6 0x0000007f 0x0000007f 0x00000007f 0x00000007f 0x8000001f 0x8000001f 0x8000001f 0x8000001f
Hits = 68, Accesses = 103, Hit ratio = 0.660194
```

16 Bit:

CODE:

```
#include <stdio.h>
int tag[16];
int main()
{
   int addr;
   int i, j, t;
   int hits, accesses;
FILE *fp;

fp = fopen("trace.txt", "r");
   hits = 0;
   accesses = 0;
```



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```
while (fscanf(fp, "%x", &addr) > 0) {
    /* simulate a direct-mapped cache with 8 words */
    accesses += 1:
    printf("%3d: 0x%08x", accesses, addr);
    i = (addr >> 2) & 15:
    t = addr | 0x1f:
    if (tag[i] == t) {
      hits += 1;
       printf("Hit%d ", i);
    } else {
       /* allocate entry */
       printf("Miss");
      tag[i] = t:
    for (i = 0; i < 16; i++)
       printf("0x%08x ", tag[i]);
    printf("\n");
  printf("Hits = %d, Accesses = %d, Hit ratio = %f\n", hits, accesses,
((float)hits)/accesses);
  close(fp);
```

OUTPUT:

- 14: 0x8000000c Hit3 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x00000000



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- 20: 0x0000001 0x80000001 0x80000001 0x80000000 0x80000000 0x80000001 0x80000001 0x80000001 0x000000000
- 22: 0x80000014 Hit5 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x800000000 0x00000003f 0x00000003f 0x00000003f 0x000000000 0x000000000 0x000000000

- 25: 0x00000030 Miss 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x00000000 0x00000000 0x00000000
- 26: 0x80000010 Hit4 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000000 0x000000000 0x000000000
- 27: 0x80000014 Hit5 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000000 0x00000000 0x00000000
- 28: 0x80000018 Hit6 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x00000000 0x00000000 0x000000000
- 29: 0x8000000c Hit3 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x000000000 0x000000000 0x000000000

- 32: 0x80000014 Hit5 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x000000000 0x000000000
- 33: 0x80000018 Hit6 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x000000000 0x000000000

- 39: 0x8000000c Hit3 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x00000000 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x000000000
- 40: 0x0000003c Miss 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f
- 41: 0x80000010 Hit4 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f
- 43: 0x80000018 Hit6 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f
- 45: 0x00000040 Miss 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f
- 47: 0x80000014 Hit5 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f
- 48: 0x80000018 Hit6 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f



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49: 0x8000000c Hit3 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 0x0000003f 50: 0x00000044 Miss 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x000000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 0x0000003f 51: 0x80000010 Hit4 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 0x0000003f 52: 0x80000014 Hit5 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 53: 0x80000018 Hit6 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 54: 0x8000000c Hit3 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 55: 0x00000048 Miss 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x000000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 56: 0x80000010 Hit4 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 57: 0x80000014 Hit5 0x0000005f 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x000000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 0x0000003f 58: 0x80000018 Hit6 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 59: 0x8000000c Hit3 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 60: 0x0000004c Miss 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 61: 0x80000010 Hit4 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 62: 0x80000014 Hit5 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 63: 0x80000018 Hit6 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 64: 0x8000000c Miss 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 0x0000003f 65: 0x00000050 Miss 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x0000005f 0x8000001f 0x8000001f 0x80000001f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 66: 0x80000010 Miss 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 67: 0x80000014 Hit5 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 68: 0x80000018 Hit6 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 69: 0x8000000c Hit3 0x0000005f 0x00000005f 0x80000001f 0x8000001f 0x8000001f 0x80000001f 0x80000001f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 70: 0x00000054 Miss 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x0000005f 0x8000001f 0x00000005f 0x80000001f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 71: 0x80000010 Hit4 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x00000005f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 0x0000003f 72: 0x80000014 Miss 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x000000000 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 73: 0x80000018 Hit6 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x000000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 74: 0x8000000c Hit3 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 75: 0x00000058 Miss 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x80000001f 0x00000005f 0x000000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 76: 0x80000010 Hit4 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 77: 0x80000014 Hit5 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x00000005f 0x000000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 78: 0x80000018 Miss 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 79: 0x8000000c Hit3 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 80: 0x0000005c Miss 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 81: 0x80000010 Hit4 0x0000005f 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f

82: 0x80000014 Hit5 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f

83: 0x80000018 Hit6 0x0000005f 0x00000005f 0x80000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f

0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f



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0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 84: 0x8000000c Hit3 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 85: 0x00000060 Miss 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 86: 0x80000010 Hit4 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 87: 0x80000014 Hit5 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 88: 0x80000018 Hit6 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 89: 0x8000000c Hit3 0x0000005f 0x00000005f 0x80000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x00000003f 0x00000003f 0x0000003f 0x0000003f 90: 0x00000064 Miss 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000007f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 91: 0x80000010 Hit4 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 92: 0x80000014 Hit5 0x0000005f 0x00000005f 0x80000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000007f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 93: 0x80000018 Hit6 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 94: 0x8000000c Hit3 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000007f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 95: 0x00000068 Miss 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000005f 0x0000007f 0x0000007f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 96: 0x80000010 Hit4 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000007f 0x0000007f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 97: 0x80000014 Hit5 0x0000005f 0x00000005f 0x80000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000007f 0x0000007f 0x00000007f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 0x00000003f 98: 0x80000018 Hit6 0x0000005f 0x0000005f 0x0000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000007f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 99: 0x8000000c Hit3 0x0000005f 0x00000005f 0x80000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x0000007f 0x0000007f 0x0000007f 0x0000003f 0x00000003f 0x00000003f 0x00000003f 100: 0x0000006c Miss 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000007f 0x0000007f 0x0000007f 0x00000003f 0x00000003f 0x0000003f 101: 0x80000010 Hit4 0x0000005f 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f 0x0000007f 0x0000007f 0x00000007f 0x00000007f 0x00000003f 0x00000003f 0x00000003f 102: 0x80000014 Hit5 0x0000005f 0x0000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x0000005f

103: 0x80000018 Hit6 0x0000005f 0x00000005f 0x00000005f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f

0x0000007f 0x0000007f 0x0000007f 0x0000007f 0x0000003f 0x0000003f 0x0000003f 0x0000003f

0x0000007f 0x0000007f 0x0000007f 0x0000007f 0x00000003f 0x00000003f 0x00000003f

Hits = 72, Accesses = 103, Hit ratio = 0.699029



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32 Bit:

CODE:

```
#include <stdio.h>
#include <stdio.h>
int tag[32];
int main()
       int addr;
       int i, j, t;
       int hits, accesses;
       FILE *fp;
       fp = fopen("trace.txt", "r");
       hits = 0;
       accesses = 0;
       while (fscanf(fp, "%x", &addr) > 0) {
       /* simulate a direct-mapped cache with 8 words */
         accesses += 1:
    printf("%3d: 0x%08x ", accesses, addr);
       i = (addr >> 2) & 31;
       t = addr | 0x1f;
       if (tag[i] == t) {
       hits += 1;
       printf("Hit%d ", i);
       } else {
       /* allocate entry */
       printf("Miss");
       tag[i] = t;
       }
       for (i = 0; i < 32; i++)
       printf("0x%08x ", tag[i]);
    printf("\n");
  printf("Hits = %d, Accesses = %d, Hit ratio = %f\n", hits, accesses,
((float)hits)/accesses);
       close(fp);
```



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OUTPUT:



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- 52: 0x80000014 Hit5 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x00000000



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69: 0x8000000c Hit3 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x8000001f 0x80000001f 0x80000001f 0x800000000 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x0000003f 0x00000005f



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Hits = 76, Accesses = 103, Hit ratio = 0.737864

Comparison Table

Number of Bits	Hits	Accesses	Hit Ratio
8	68	103	0.660194
16	72	103	0.699029
32	76	103	0.737864

CONCLUSION:

Cache memory is the closest to the CPU, it reduces the access time from Main Memory. There are 3 ways to map cache to Main memory: Direct mapping, Associative mapping, and Set-Associative mapping. In Direct mapping, each memory block is assigned to a specific line in the cache. It is a simple way to map blocks but it has a lower cache hit ratio, as there is only one cache line available in a set. Every time a new memory is referenced to the same set, the cache line is replaced, this is the drawback of Direct Mapping.

As seen from the comparison table above which is derived from our program output, as we go on increasing the number of bits in cache memory, the hit ratio also increases.

EXPERIMENT - 6

Aim

To implement fully associative mapping and set associative mapping.

Submission Sheet

SAP ID	Name of Student	Date of Experiment	Date of Submission	Remarks
60004190057	Junaid Girkar	6-11-2021	6-11-2021	

Theory

A CPU cache is a hardware used by the central processing unit (CPU) of a computer to reduce the average cost (time) of accessing data from the main memory. A cache is a smaller, faster memory, located closer to a processor core, which stores copies of the data from frequently used main memory locations. Cache memory is costlier than main memory or disk memory but economical than CPU registers. It is an extremely fast memory type that acts as a buffer between RAM and the CPU, and holds frequently requested data and instructions so that they are immediately available to the CPU when needed.

Fully associative mapping

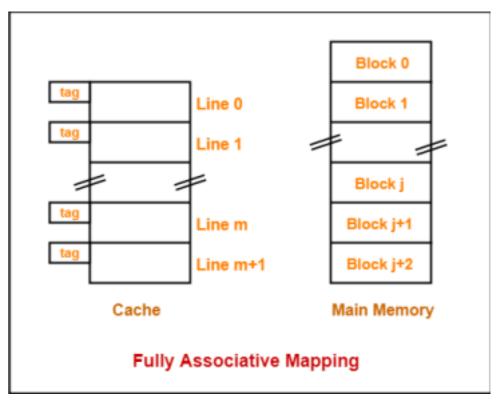
Fully Associative Mapping is a cache mapping technique that allows to map a block of main memory to any freely available cache line. In this type of mapping, the associative memory is used to store content and addresses of the memory word. Any block can go into any line of the cache. This means that the word id bits are used to identify which word in the block is needed, but the tag becomes all of the remaining bits. This enables the placement of any word at any place in the cache memory. It is considered to be the fastest and the most flexible mapping form.



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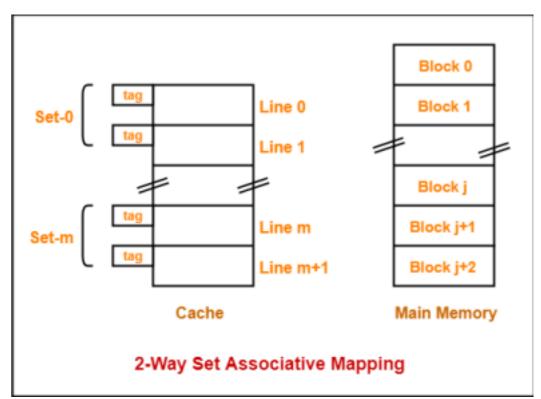




Set associative mapping

Set-associative cache is a trade-off between direct-mapped cache and fully associative cache. This form of mapping is an enhanced form of direct mapping where the drawbacks of direct

mapping is removed. Set associative addresses the problem of possible thrashing in the direct mapping method. It does this by saying that instead of having exactly one line that a block can map to in the cache, we will group a few lines together creating a *set*. Then a block in memory can map to any one of the lines of a specific sea. Set-associative mapping allows that each word that is present in the cache can have two or more words in the main memory for the same index address. Set associative cache mapping combines the best of direct and associative cache mapping techniques.



Prelab code for generating trace file

main: addu \$t0,\$0,\$0
addiu \$t1,\$0,80
addu \$t2,\$0,\$0

loop: lw \$t3,array(\$t0)

addu \$t2,\$t2,\$t3



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```
addiu $t0,$t0,4
bne $t0,$t1,loop
*done: beq $0,$0,done
array: .word 1,2,3,4,5,6,7,8,9,10
.word 11,12,13,14,15,16,17,18,19,20
```

Fully Associative Mapping – 8 bit Code:

```
#include <stdio.h>
int tag[8];
int mru[8] = \{7,6,5,4,3,2,1,0\};
void mruUpdate(int index)
{
int i;
// find index in mru
for (i = 0; i < 8; i++)
if (mru[i] == index)
break;
// move earlier refs one later
while (i > 0) {
mru[i] = mru[i-1];
i--;
}
mru[0] = index;
int main( )
{
int addr;
int i, j, t;
int hits, accesses;
FILE *fp;
fp = fopen("trace.txt", "r");
hits = 0;
accesses = 0;
while (fscanf(fp, "%x", &addr) > 0) {
/* simulate fully associative cache with 8 words */
accesses += 1;
printf("%3d: 0x%08x ", accesses, addr);
for (i = 0; i < 8; i++) {
if (tag[i] == addr) {
hits += 1;
printf("Hit%d ", i);
mruUpdate(i);
```



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```
break;
}
if (i == 8) {
/* allocate entry */
printf("Miss ");
i = mru[7];
tag[i] = addr;
mruUpdate(i);
for (i = 0; i < 8; i++)
printf("0x%08x ", tag[i]);
for (i = 0; i < 8; i++)
printf("%d ", mru[i]);
printf("\n");
printf("Hits = %d, Accesses = %d, Hit ratio = %f\n", hits, accesses,
((float)hits)/accesses);
pclose(fp);
```

Output:

```
79: explonement Hit3 @x00000054 excellents &x000000052 explonement &x000000052 explonement &x000000053 explonement &x000000053 explonement &x000000053 explonement &x000000053 explonement &x000000018 explonement &x00000018 &x00000018 &x000000018 &x00000018 &x00000018
```

Fully Associative Mapping – 16 bit

Code:

```
#include <stdio.h>
int tag[16];
int mru[16] = {15,14,13,12,11,10,9,8,7,6,5,4,3,2,1,0};
void mruUpdate(int index)
```



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```
{
int i;
// find index in mru
for (i = 0; i < 16; i++)
if (mru[i] == index)
break;
// move earlier refs one later
while (i > 0) {
mru[i] = mru[i-1];
i--;
}
mru[0] = index;
int main( )
{
int addr;
int i, j, t;
int hits, accesses;
FILE *fp;
fp = fopen("trace.txt", "r");
hits = 0;
accesses = 0;
while (fscanf(fp, "x", &addr) > 0) {
/* simulate fully associative cache with 16 words */
accesses += 1;
printf("%3d: 0x%08x ", accesses, addr);
for (i = 0; i < 16; i++) {
if (tag[i] == addr) {
hits += 1;
printf("Hit%d ", i);
mruUpdate(i);
break;
}
}
if (i == 16) {
/* allocate entry */
printf("Miss ");
i = mru[15];
tag[i] = addr;
mruUpdate(i);
}
for (i = 0; i < 16; i++)
printf("0x%08x ", tag[i]);
printf("\n ");
```



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```
for (i = 0; i < 16; i++)
printf("%d ", mru[i]);
printf("\n");
}
printf("Hits = %d, Accesses = %d, Hit ratio = %f\n", hits, accesses,
((float)hits)/accesses);
close(fp);
}</pre>
```

SVKM

Shri Vile Parle Kelavani Mandal's

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Output: Fully Associative Mapping – 16 bit

```
96: 0.30000018 HIT5 0.00000014 0.00000016 0.00000016 0.00000016 0.00000016 0.00000016 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.00000014 0.
```

<u>Set Associative Mapping – 16 bit</u>

Code:

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
void main() {
int** tags = malloc(2 * sizeof(int*));
tags[0] = malloc(16 * sizeof(int));
tags[1] = malloc(16 * sizeof(int));
int mru[8] = {1,1,1,1,1,1,1,1};
int sets = 8;
int addr;
int hits, accesses;
FILE *fp;
fp = fopen("trace.txt", "r");
hits = 0;
accesses = 0;
while (fscanf(fp, "%x", &addr) > 0) {
accesses++;
int setNum = (addr >> 2) & (int)(pow(2, log2(sets)) - 1);
```



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```
int addrTag = addr >> (2 + (int)log2(sets));
printf("\n%3d: 0x%08x ", accesses, addr);
int i;
for(i = 0; i < 2; ++i) {
if(tags[i][setNum] == addrTag) {
printf("Hit %d", i);
hits++;
mru[setNum] = i;
break;
}
}
if(i == 2) {
printf("Miss");
tags[(mru[setNum] + 1) % 2][setNum] = addrTag;
mru[setNum] = (mru[setNum] + 1) % 2;
}
printf("\nTags:\n");
for(int i = 0; i < sets; ++i) {</pre>
printf("Set %2d: 0x%08x 0x%08x ", i, tags[0][i], tags[0][1]);
printf("\n");
printf("\nHits = %d, Accesses = %d, Hit ratio = %f\n", hits, accesses,
((float)hits)/accesses);
fclose(fp);
}
```

Output: Set Associative Mapping – 16 bit



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```
78: 0x30000036 Hit 0
Tags:
5xt 0: 9xfc000000 0xfc000000 Set 1: 9xfc000000 0xfc000000 Set 2: 9xfc000000 0xfc000000 0xfc000000 Set 4: 8xfc000000 0xfc000000 0xfc000000 Set 5: 9xfc000000 0xfc000000 Set 5: 9xfc000000 0xfc000000 Set 6: 9xfc000000 0xfc000000 Set 7: 9xfc000000 0xfc000000 0xfc000000 Set 4: 8xfc000000 0xfc000000 0xfc000000 Set 6: 9xfc000000 0xfc000000 0xfc000000 Set 7: 9xfc000000 0xfc000000 0xfc000000 Set 4: 8xfc000000 0xfc000000 Set 8: 8xfc000000 0xfc000000 Set 8: 8xfc000000 0xfc000000 Set 8: 8xfc000000 Set 8: 8xfc000000 0xfc000000 Set 8: 8xfc000000 Set 8: 8xfc00000
```

Conclusion

A cache is a smaller, quicker memory that stores copies of software instructions and data that are utilized regularly in the operation of programs and is positioned closer to the processor core. The program's overall speed is improved by having quick access to these commands. In this experiment, we learnt about fully associative mapping and set associative mapping and implemented them in a C program.

EXPERIMENT - 7

Aim: Study and Simulate (Stepwise) Experiments of MIPS Programming available at MIPS simulator. Modify the given programs to implement

- 1) Add 10 nos.
- 2) to print message "Hello MIPS"
- 3) To Reverse the input string (e.g. "ABC" "CBA").

Submission Sheet

SAP ID	Name of Student	Date of Experiment	Date of Submission	Remarks
60004190057	Junaid Girkar	26/11/21	26/11/21	

Theory:

MIPS assembly language simply refers to the assembly language of the MIPS processor. The term MIPS is an acronym for Microprocessor without Interlocked Pipeline Stages. It is a reduced-instruction set architecture developed by an organization called MIPS Technologies. The MIPS assembly language is a very useful language to learn because many embedded systems run on the MIPS processor.

MIPS Architecture

Data Types

- 1. All the instructions in MIPS are 32 bits.
- 2. A byte in the MIPS architecture represents 8 bits; a halfword represents 2 bytes (16 bits) and a word represents 4 bytes (32 bits).
- 3. Each character used in the MIPS architecture requires 1 byte of storage. Each integer used requires 4 bytes of storage.

Literals

In the MIPS architecture, literals represent all numbers (e.g. 5), characters enclosed in single quotes (e.g. 'g') and strings enclosed in double quotes (e.g. "Deadpool").

Code 1: To add 10 numbers

Registers

MIPS architecture uses 32 general-purpose registers. Each register in this architecture is preceded by '\$' in the assembly language instruction. You can address these registers in one of two ways. Either use the register's number (that is, from \$0 to \$31), or the register's name (for example, \$11).

MIPS Structure

General structure of a program created using the MIPS assembly language

A typical program created using the MIPS assembly language has two main parts. They are the data declaration section of the program and the code section of the program.

Data declaration section of a MIPS assembly language program

The data declaration section of the program is the part of the program identified with the assembler directive .data. This is the part of the program in which all the variables to be used in the program are created and defined. It is also the part of the program where storage is allocated in the main memory (RAM). The MIPS assembly language program declares variables as follows: name: .storage_type value(s).

The "name" refers to the name of the variable being created. The "storage_type" refers to the type of data that the variable is meant to store. The "value(s)" refers to the information to be stored in the variable being created.

Code section of the MIPS assembly language program

The code section of the program is the part of the program in which the instructions to be executed by the program are written. It is placed in the section of the program identified with the assembler directive .text. The starting point for the code section of the program is marked with the label "main" and the ending point for the code section of the program is marked with an exit system call. This section of a MIPS assembly language program typically involves the manipulation of registers and the performance of arithmetic operations.

CODE 1: Addition of 10 numbers

```
.data
array: .word 5,6,12,4,19,8,4,21,9,1
length: .word 10
sum: .word 0
myMessage: .ascii "Sum of 10 nos. in the given array is: "
.text
main:
la $t0, array # Base address
li $t1, 0 # i = 0
lw $t2,length # $t2 = length
li $t3, 0 # sum = 0
sumLoop:
lw $t4, ($t0) # $t4 = array[i]
add $t3, $t3, $t4 # sum = sum + array[i]
```

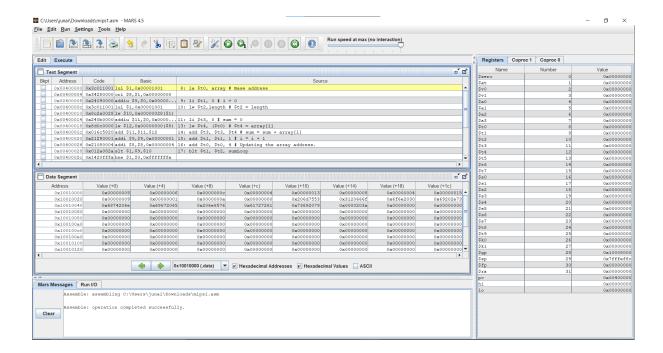


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```
add $t1, $t1, 1 # i = i + 1
add $t0, $t0, 4 # Updating the array address.
blt $t1, $t2, sumLoop
sw $t3, sum
li $v0, 4
la $a0, myMessage
syscall
li $v0, 1
move $a0, $t3
syscall
```



Code 2: To print Hello World

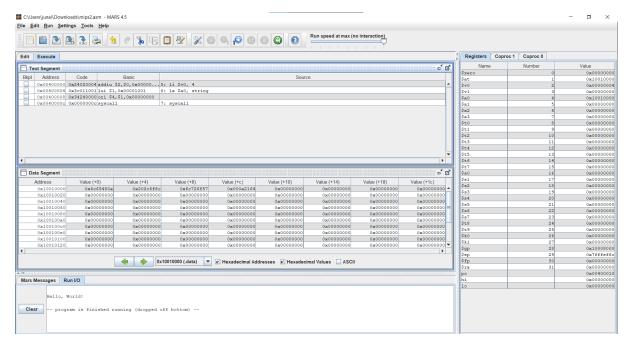
```
.data
string: .asciiz "\nHello, World!\n"
.text
main:
li $v0, 4
la $a0, string
syscall
```



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CODE 3: To Reverse the input string (e.g."ABC" - "CBA").

```
.data

str: .asciiz "India"

str_msg1: .asciiz "Original string: "

str_msg2: .asciiz "Reversed string: "

str_nl: .asciiz "\n"

str_len: .word 0

.text

main:

#print original string

la $a0,str_msg1 #leading text

li $v0,4

syscall

la $a0,str #original string

li $v0,4
```



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```
syscall
la $a0,str_nl #new Line
li $v0, 4
syscall
#get length
add $t0,$zero,$zero #initialize registers when needed
add $a0,$zero,$zero
add $a1,$zero,$zero
la $a0,str #loads the address of the string
la $a1,str
aetLen:
       lb $t0,0($a0) #load first byte
       begz $t0,saveLen
       addi $a0,$a0,1
       j getLen #jump back to start of this loop
saveLen:
       subu $t0,$a0,$a1 #len = address of null terminator - str address
       sw $t0,str_len
#reverse the string
add $t0,$zero,$zero #address of the beginning of str
add $t1,$zero,$zero #address of the end of str
add $t2,$zero,$zero
add $t3,$zero,$zero
revString:
       #find the index of the last character before the end of the string
       la $t0,str #loads the address of the start of the string
       lw $t1,str_len #loads the length of the string
       addu $t1,$t0,$t1
       subi $t1,$t1,1
       loop:
               lb $t2,0($t0) #load the first character
               lb $t3,0($t1) #load the last character
               ble $t1,$t0,printRev
               sb $t3,0($t0)
               sb $t2,0($t1)
               addi $t0,$t0,1
               subi $t1,$t1,1 #and loop until we reach the middle
              loop
#print the reversed version of the text
printRev:
       add $a0,$zero,$zero #initialize the a0 registry
       la $a0,str_msg2 #leading text
       li $v0,4
```



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syscall

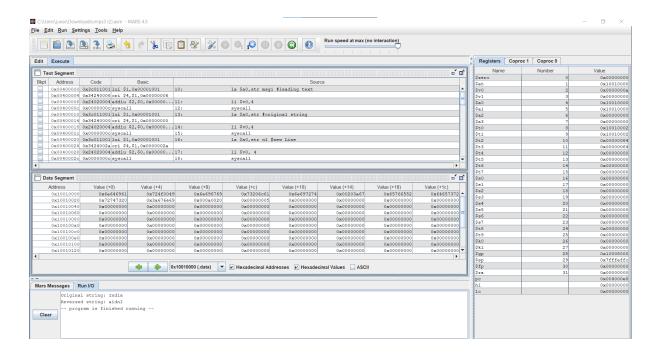
la \$a0,str #reversed string

li \$v0,4

syscall

li \$v0,10 #exit program

syscall



Mars Messages Run I/O

Original string: India Reversed string: aidnI
-- program is finished running --

EXPERIMENT - 8

Aim: Run the simulator using the given link

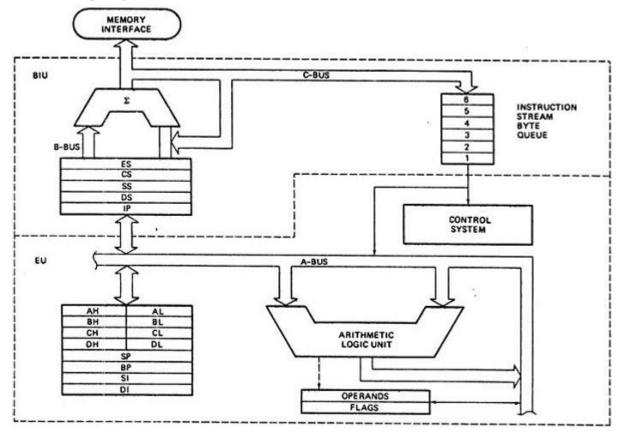
https://yjdoc2.github.io/8086-emulator-web/compile. Study and execute First 6 examples from the repository https://github.com/YJDoc2/8086-Emulator/tree/master/examples

Submission Sheet

SAP ID	Name of Student	Date of Experiment	Date of Submission	Remarks
60004190057	Junaid Girkar	17/12/21	17/12/21	

Architecture of 8086

The following diagram depicts the architecture of a 8086 Microprocessor -



Pins on 8086:

AD0-AD15 (Address Data Bus): Bidirectional address/data lines. These are low order address bus. They are multiplexed with data.

When these lines are used to transmit memory address, the symbol A is used instead of AD, for example, A0- A15.

A16 - A19 (Output): High order address lines. These are multiplexed with status signals.

A16/S3, A17/S4: A16 and A17 are multiplexed with segment identifier signals S3 and S4.

A18/S5: A18 is multiplexed with interrupt status S5.

A19/S6: A19 is multiplexed with status signal S6.

BHE/S7 (Output): Bus High Enable/Status. During T1, it is low. It enables the data onto the most significant half of the data bus, D8-D15. 8-bit devices connected to the upper half of the data bus use BHE signal. It is multiplexed with status signal S7. S7 signal is available during T3 and T4.

RD (Read): For read operation. It is an output signal. It is active when LOW.

Ready (Input): The addressed memory or I/O sends acknowledgment through this pin.

When HIGH, it denotes that the peripheral is ready to transfer data.

RESET (Input): System reset. The signal is active HIGH.

CLK (input): Clock 5, 8 or 10 MHz.

INTR: Interrupt Request.

NMI (Input): Non-maskable interrupt request.

TEST (Input): Wait for test control. When LOW the microprocessor continues execution

otherwise waits.

VCC: Power supply +5V dc.

GND: Ground.

Operating Modes of 8086

There are two operating modes of operation for Intel 8086, namely the minimum mode and the maximum mode.

When only one 8086 CPU is to be used in a microprocessor system, the 8086 is used in the Minimum mode of operation.

In a multiprocessor system 8086 operates in the Maximum mode.

ADDRESSING:

The 8086 microprocessors have 8 addressing modes. Two addressing modes have been provided for instructions which operate on register or immediate data.

These two addressing modes are:

Register Addressing: In register addressing, the operand is placed in one of the 16-bit or 8-bit general purpose registers.

Example

- MOV AX, CX
- ADD AL, BL
- ADD CX, DX

Immediate Addressing: In immediate addressing, the operand is specified in the instruction itself.

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Example

- MOV AL, 35H
- MOV BX, 0301H
- MOV [0401], 3598H
- ADD AX, 4836H

The remaining 6 addressing modes specify the location of an operand which is placed in a memory.

These 6 addressing modes are:

Direct Addressing: In direct addressing mode, the operand?s offset is given in the instruction as an 8-bit or 16-bit displacement element.

Example

ADD AL, [0301]

The instruction adds the content of the offset address 0301 to AL. the operand is placed at the given offset (0301) within the data segment DS.

Register Indirect Addressing: The operand's offset is placed in any one of the registers BX, BP, SI or DI as specified in the instruction.

Example

MOV AX, [BX]

It moves the contents of memory locations addressed by the register BX to the register AX.

Based Addressing: The operand's offset is the sum of an 8-bit or 16-bit displacement and the contents of the base register BX or BP. BX is used as base register for data segment, and the BP is used as a base register for stack segment.

Effective address (Offset) = [BX + 8-bit or 16-bit displacement].

Example

- MOV AL, [BX+05]; an example of 8-bit displacement.
- MOV AL, [BX + 1346H]; example of 16-bit displacement.

Indexed Addressing: The offset of an operand is the sum of the content of an index register SI or DI and an 8-bit or 16-bit displacement.

Offset (Effective Address) = [SI or DI + 8-bit or 16-bit displacement] Example

- MOV AX, [SI + 05]; 8-bit displacement.
- MOV AX, [SI + 1528H]; 16-bit displacement.

Based Indexed Addressing: The offset of operand is the sum of the content of a base register BX or BP and an index register SI or DI.

Effective Address (Offset) = [BX or BP] + [SI or DI]

Here, BX is used for a base register for data segment, and BP is used as a base register for stack segment.

Example

- ADD AX, [BX + SI]
- MOV CX, [BX + SI]

Based Indexed with Displacement: In this mode of addressing, the operand's offset is given by:

Effective Address (Offset) = [BX or BP] + [SI or DI] + 8-bit or 16-bit displacement Example

- MOV AX, [BX + SI + 05]; 8-bit displacement
- MOV AX, [BX + SI + 1235H]; 16-bit displacement

1. Program to add two word length number

```
; Program to add two word length numbers

OPR1: DW 0x6459; declare first number

OPR2: DW 0x8420; declare second number

RESULT: DW 0; declare place to store result
; actual entry point of the program

start:

MOV AX, word OPR1; move first number to AX

MOV BX, word OPR2; move second number to BX

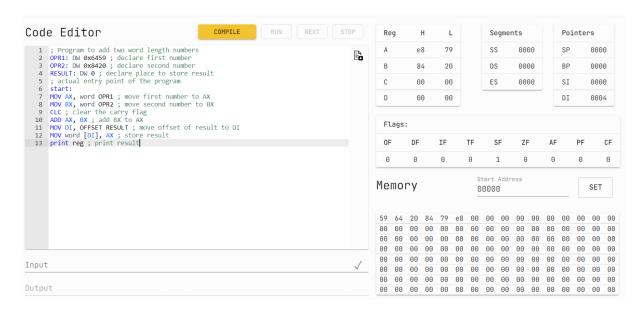
CLC; clear the carry flag

ADD AX, BX; add BX to AX

MOV DI, OFFSET RESULT; move offset of result to DI

MOV word [DI], AX; store result

print reg; print result
```



2. A Program to move data from one segment to another.

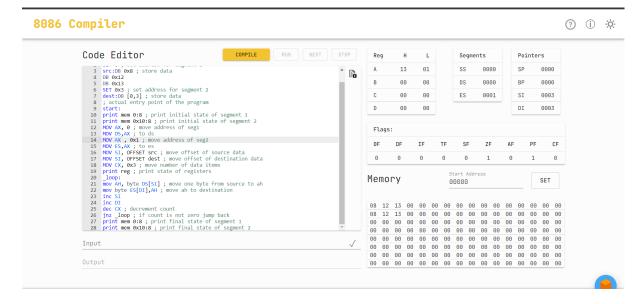
```
; A Program to move data from one segment to another
SET 0; set address for segment 1
src:DB 0x8 ; store data
DB 0x12
DB 0x13
SET 0x3; set address for segment 2
dest:DB [0,3]; store data
; actual entry point of the program
start:
print mem 0:8 ; print initial state of segment 1
print mem 0x10:8 ; print initial state of segment 2
MOV AX, 0; move address of seg1
MOV DS, AX; to ds
MOV AX , 0x1 ; move address of seg2
MOV ES, AX; to es
MOV SI, OFFSET src; move offset of source data
MOV SI, OFFSET dest; move offset of destination data
MOV CX, 0x3; move number of data items
print reg ; print state of registers
_loop:
mov AH, byte DS[SI]; move one byte from source to ah
mov byte ES[DI], AH; move ah to destination
inc SI
inc DI
dec CX; decrement count
jnz _loop ; if count is not zero jump back
print mem 0:8 ; print final state of segment 1
print mem 0x10:8 ; print final state of segment 2
```



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3. Program to calculate factorial using looping.

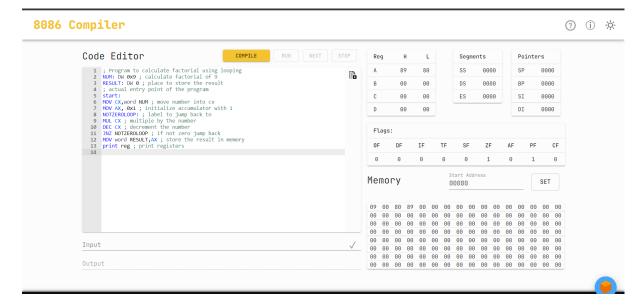
```
; Program to calculate factorial using looping
NUM: DW 0x9; calculate factorial of 9
RESULT: DW 0; place to store the result
; actual entry point of the program
start:
MOV CX,word NUM; move number into cx
MOV AX, 0x1; initialize accumulator with 1
NOTZEROLOOP: ; label to jump back to
MUL CX; multiple by the number
DEC CX; decrement the number
JNZ NOTZEROLOOP; if not zero jump back
MOV word RESULT,AX; store the result in memory
print reg; print registers
```



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4. Program to show use of interrupts.

```
; Program to show use of interrupts
; Also, Hello World program !
hello: DB "Hello World"; store string
; actual entry point of the program, must be present
start:

MOV AH, 0x13; move BIOS interrupt number in AH
MOV CX, 11; move length of string in cx

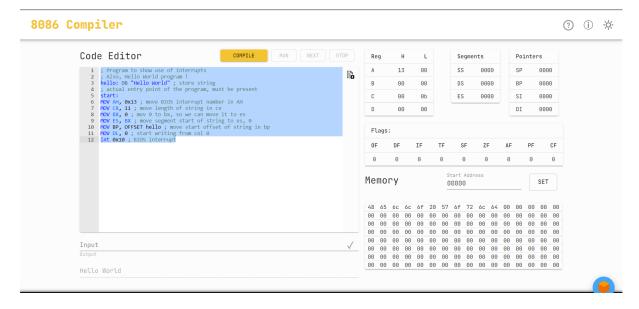
MOV BX, 0; mov 0 to bx, so we can move it to es
MOV ES, BX; move segment start of string to es, 0
MOV BP, OFFSET hello; move start offset of string in bp
MOV DL, 0; start writing from col 0
int 0x10; BIOS interrupt
```



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5. Program to calculate LCM and GCD of two numbers.

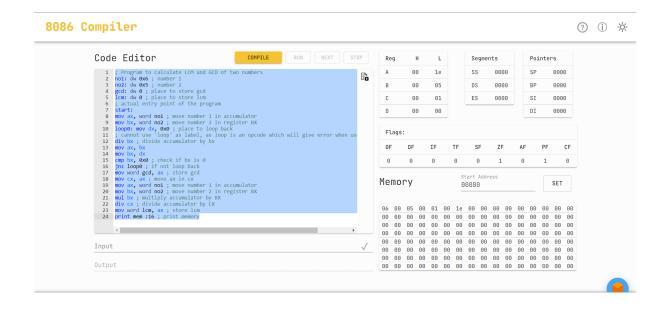
```
; Program to calculate LCM and GCD of two numbers
no1: dw 0x6; number 1
no2: dw 0x5; number 2
gcd: dw 0; place to store gcd
lcm: dw 0 ; place to store lcm
; actual entry point of the program
start:
mov ax, word no1; move number 1 in accumulator
mov bx, word no2; move number 2 in register BX
loop0: mov dx, 0x0; place to loop back
; cannot use 'loop' as label, as loop is an opcode which will give error
when used with jumps
div bx; divide accumulator by bx
mov ax, bx
mov bx, dx
cmp bx, 0x0; check if bx is 0
jnz loop0 ; if not loop back
mov word gcd, ax; store gcd
mov cx, ax; move ax in cx
mov ax, word no1; move number 1 in accumulator
mov bx, word no2; move number 2 in register BX
mul bx; multiply accumulator by BX
div cx; divide accumulator by CX
mov word lcm, ax; store lcm
print mem :16 ; print memory
```



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6. A program to sort the numbers in descending order, using bubble sort

```
; A program to sort the numbers in descending order, using bubble sort
vals:DB 0xF; declaration of the numbers
DB 0x5A
DB 0x24
DB 0x2
DB 0x56
last: DB 0; declaring an element to get total number of elements later
; actual entry point of the program
start:
print mem :8 ; print initial state of memory
MOV CH, OFFSET last; move number of elements to CH
outer: ; loop label for outer loop
MOV CL, OFFSET last; move number of elements to CL
MOV SI, OFFSET vals; move offset of values to si
inner: ; loop label for inner loop
MOV AX, word [SI]; move two adjacent numbers to AX
CMP AL, AH; compare both values
JNC skip; jump to skip if first num is greater than second
XCHG AL, AH; exchange both numbers
MOV word [SI], AX; move exchanged numbers to memory
skip:
INC SI; increment SI
DEC CL; decrement inner loop counter
JNZ inner; jump back to inner if counter is not zero
```



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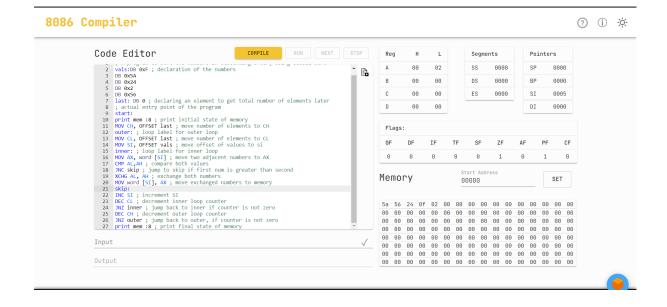


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DEC CH; decrement outer loop counter

JNZ outer; jump back to outer, if counter is not zero

print mem :8 ; print final state of memory



EXPERIMENT - 9

AIM: Write Programs using Assembly Language:

- 1. To implement Macros for calculating Factorial of a number.
- 2. To study and Implement DOS interrupts. Calculate and display Sum of 2 user entered inputs using DOS interrupt

Submission Sheet

SAP ID	Name of Student	Date of Experiment	Date of Submission	Remarks
60004190057	Junaid Girkar	17/12/21	17/12/21	

Theory:

Macros: Writing a macro is another way of ensuring modular programming in assembly language. A macro is a sequence of instructions, assigned by a name and could be used anywhere in the program. In NASM, macros are defined with %macro and %endmacro directives. The macro begins with the %macro directive and ends with the %endmacro directive. The Syntax for macro definition –

%macro macro_name number_of_params <macro body> %endmacro

Where, number_of_params specifies the number parameters, macro_name specifies the name of the macro. The macro is invoked by using the macro name along with the necessary parameters. When you need to use some sequence of instructions many times in a program, you can put those instructions in a macro and use it instead of writing the instructions all the time

Macros are just like procedures, but not really. Macros look like procedures, but they exist only until your code is compiled, after compilation all macros are replaced with real instructions. If you declared a macro and never used it in your code, compiler will simply ignore it. Unlike procedures, macros should be defined above the code that uses it.

The advantage of using Macro is that it avoids the overhead time involved in calling and returning (as in the procedures). Therefore, the execution of Macros is faster as compared to procedures. Another advantage is that there is no need for accessing stack or providing any separate memory to it for storing and returning the address locations while shifting the processor controls in the program.

But it should be noted that every time you call a macro, the assembler of the microprocessor places the entire set of Macro instructions in the mainline program from where the call to Macro is being made. This is known as Macro expansion. Due to this, the program code (which uses Macros) takes more memory space than the code which uses procedures for implementing the same task using the same set of instructions.

DOS Interrupts

Interrupt is the method of creating a temporary halt during program execution and allows peripheral devices to access the microprocessor. The microprocessor responds to that interrupt with an ISR (Interrupt Service Routine), which is a short program to instruct the microprocessor on how to handle the interrupt. The following image shows the types of interrupts we have in a 8086 microprocessor –

DOS Interrupt is a Software Interrupt. INT 21H is a DOS interrupt. It is one of the most commonly used interrupts while writing code in 8086 assembly language. To use the DOS interrupt 21H load AH with the desired sub-function. Load other required parameters in other registers, and make a call to INT 21H.

АН	Description	АН	Description
01	Read character from STDIN	02	Write character to STDOUT
05	Write character to printer	06	Console Input/Output
07	Direct char read (STDIN), no echo	08	Char read from STDIN, no echo
09	Write string to STDOUT	0A	Buffered input
ОВ	Get STDIN status	0C	Flush buffer for STDIN
0D	Disk reset	0E	Select default drive
19	Get current default drive	25	Set interrupt vector
2A	Get system date	2B	Set system date
2C	Get system time	2D	Set system time
2E	Set verify flag	30	Get DOS version
35	Get Interrupt vector		
36	Get free disk space	39	Create subdirectory



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3A	Remove subdirectory	3B	Set working directory
3C	Create file	3D	Open file
3E	Close file	3F	Read file
40	Write file	41	Delete file
42	Seek file	43	Get/Set file attributes
47	Get current directory	4C	Exit program
4D	Get return code	54	Get verify flag
56	Rename file	57	Get/Set file date

CODE:

1. Factorial using Macros.

; Program to calculate factorial of a number using a macro

NUM: DW 0x7; calculate factorial of 7

RESULT: DW 0

; Macro for factorial

MACRO fact(no) -> MUL word no <-

; actual entry point of the program

start:

MOV AX, 0x0001; initialize accumulator with 1

NOTZEROLOOP: fact(NUM);

DEC word NUM; decrement number

JNZ NOTZEROLOOP; jump back if number is not zero yet

MOV word RESULT,AX

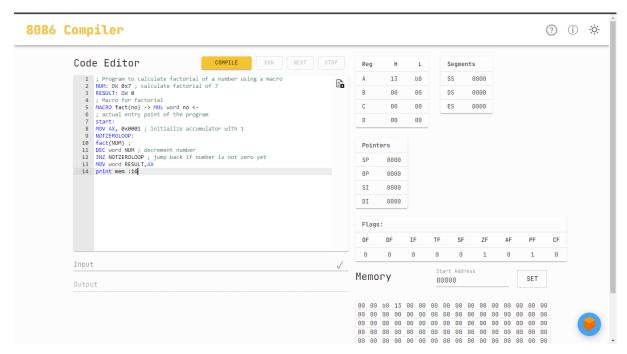
print mem:16



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2. DOS Interrupt

DATA SEGMENT NUM1 DB? NUM2 DB? **RESULT DB?** MSG1 DB 10,13,"ENTER FIRST NUMBER TO ADD: \$" MSG2 DB 10,13,"ENTER SECOND NUMBER TO ADD: \$" MSG3 DB 10,13,"RESULT OF ADDITION IS: \$" **ENDS** CODE SEGMENT ASSUME DS:DATA, CS:CODE START: **MOV AX, DATA MOV DS,AX** LEA DX,MSG1 MOV AH,9 **INT 21H** MOV AH,1 **INT 21H** SUB AL,30H MOV NUM1,AL LEA DX,MSG2 MOV AH,9 **INT 21H**



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MOV AH,1

INT 21H

SUB AL,30H

MOV NUM2,AL

ADD AL, NUM1

MOV RESULT, AL

MOV AH,0

AAA

ADD AH,30H

ADD AL,30H

MOV BX,AX

LEA DX,MSG3

MOV AH,9

INT 21H

MOV AH,2

MOV DL,BH

INT 21H

MOV AH,2

MOV DL,BL

INT 21H

MOV AH,4CH

INT 21H

ENDS

END START



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X

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Big DOSBox 0.74-3, Cpu speed: 3000 cycles, Frameskip 0, Progra...

/z Display source line with error message /zi,/zd Debug info: zi=full, zd=line numbers only

C:\>tasm Addition.asm

Turbo Assembler Version 2.51 Copyright (c) 1988, 1991 Borland International

Assembling file: Addition.asm

Error messages: None Warning messages: None Passes: 1

Remaining memory: 491k

C:\>Addition

Illegal command: Addition.

C:>>tlink Addition

Turbo Link Version 4.0 Copyright (c) 1991 Borland International

Warning: No stack

C:\>Addition

ENTER FIRST NUMBER TO ADD : 1 ENTER SECOND NUMBER TO ADD : 0 RESULT OF ADDITION IS : 01

C:\>

EXPERIMENT - 10

Aim: Write a Program using ALP to Simulate Microcontroller interfacing with 7 segment display using

http://vlabs.iitb.ac.in/vlabs-dev/labs/8051-Microcontroller-Lab/labs/exp1/simulation .php. Display your SAP ID using this tool

Submission Sheet

SAP ID	Name of Student	Date of Experiment	Date of Submission	Remarks
60004190057	Junaid Girkar	3/10/21	3/10/21	

THEORY:

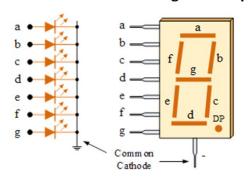
The 7-segment display consists of seven LEDs arranged in a rectangular fashion. Each of the seven LEDs is called a segment because when illuminated the segment forms part of a numerical digit (both Decimal and Hex) to be displayed. An additional 8th LED is sometimes used within the same package which is the indication of a decimal point(DP), when two or more 7-segment displays are connected together numbers greater than ten can be displayed.

So by forward biasing the appropriate pins of the LED segments in a particular order, some segments will be glowing and others will remain as it is, allowing the desired character pattern of the number to be generated on the display. This then allows us to display each of the ten decimal digits 0 to 9 on the same 7-segment display.

In the common cathode display, all the cathode connections of the LED segments are joined together to logic "0" or ground. The individual segments are illuminated by application of a "HIGH", or logic "1" signal via a current limiting resistor to forward bias the individual Anode terminals (a-g).



Common Cathode 7-segment Display



				atho					
Decimal	Individual Segments Illuminated								
Digit	а	b	С	d	е	f	g		
0	1	1	1	1	1	1			
1		1	1						
2	1	1		1	1		1		
3	1	1	1	1			1		
4		1	1			1	1		
5	1		1	1		1	1		
6	1		1	1	1	1	1		
7	1	1	1						
8	1	1	1	1	1	1	1		
9	1	1	1	1		1	1		

Common Cathode Decoding Table

CHAR	Α	В	С	D	E	F	G	HEX
	SAP ID = 60004190057							
6	1		1	1	1	1	1	5F
0	1	1	1	1	1	1		7E
4		1	1			1	1	33
1		1	1					30
9	1	1	1	1		1	1	7B
5	1		1	1		1	1	5B
7	1	1	1					70
	HEXADECIMAL = DF8874769							
D	1	1	1	1	1	1		7E
F	1				1	1	1	47
8	1	1	1	1	1	1	1	7F



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7	1	1	1					70
4		1	1			1	1	33
6	1		1	1	1	1	1	5F
9	1	1	1	1		1	1	7B
	NAME = JUNAID							
J		1	1	1				38
U		1	1	1	1	1		3E
N	1	1	1		1	1		76
Α	1	1	1		1	1	1	77
ı		1	1					30
D		1	1	1	1		1	3D

CODE:

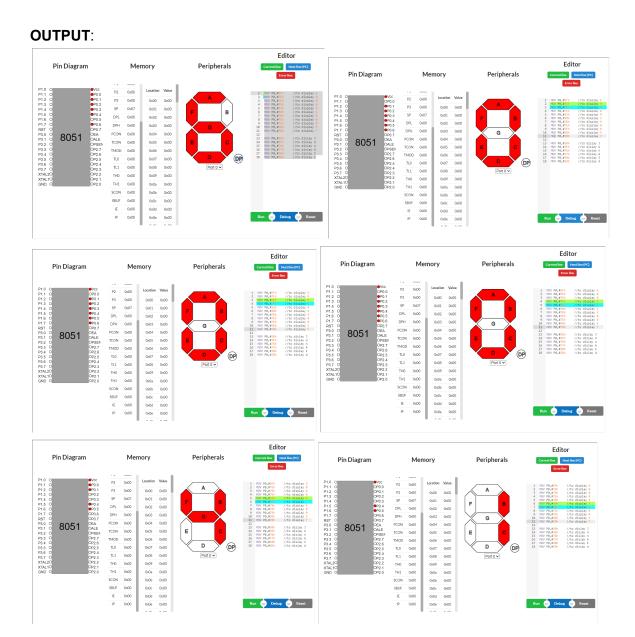
```
MOV P0,#5Fh
                //to display 6
MOV P0, #7Eh
                //to display 0
MOV P0, #7Eh
                //to display 0
MOV P0,#7Eh
                //to display 0
MOV P0,#33h
                //to display 4
MOV P0,#30h
                //to display 1
MOV P0,#7Bh
                //to display 9
MOV P0,#7Eh
                //to display 0
MOV P0,#7Eh
                //to display 0
MOV P0,#5Bh
                //to display 5
MOV P0,#70h
                //to display 7
MOV P0,#3Dh
                //to display d
                //to display F
MOV P0,#47h
MOV P0,#7Fh
                //to display 8
MOV P0,#7Fh
                //to display 8
MOV P0,#70h
                //to display 7
MOV P0,#33h
                //to display 4
MOV P0,#70h
                //to display 7
MOV P0,#5Fh
                //to display 6
MOV P0, #7Bh
                //to display 9
MOV P0,#38h
                //to display J
MOV P0,#3Eh
                //to display U
```



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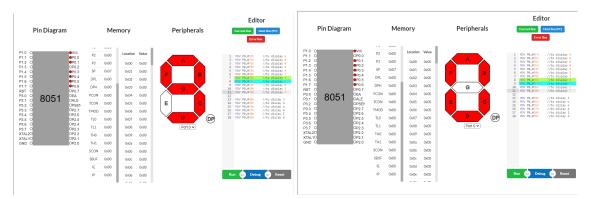
MOV P0,#76h	//to	display	n
MOV P0,#77h	//to	display	A
MOV P0,#30h	//to	display	I
MOV P0,#3Dh	//to	display	d

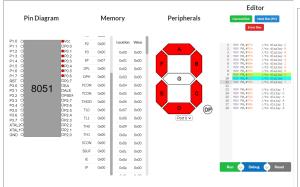


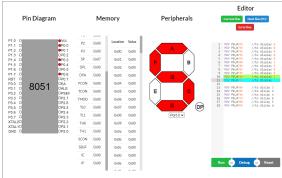


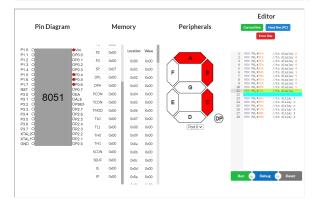
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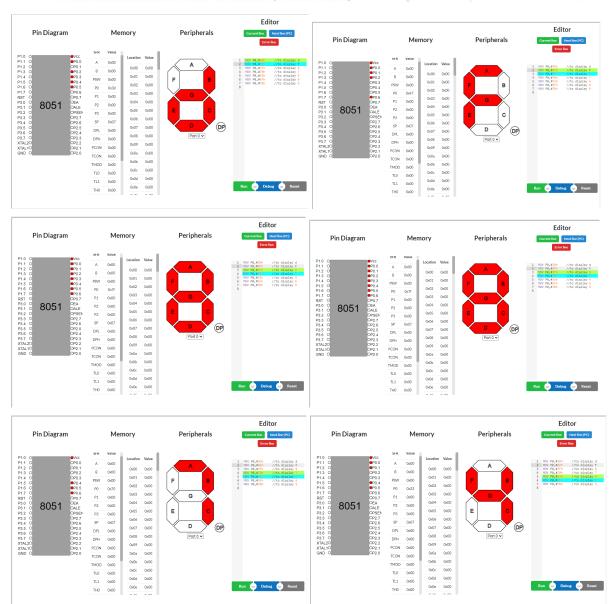






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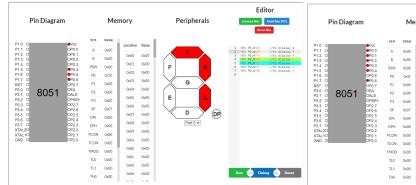


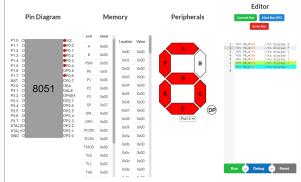


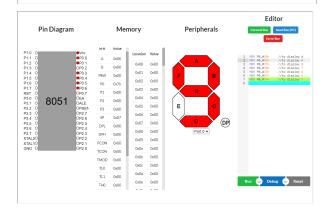


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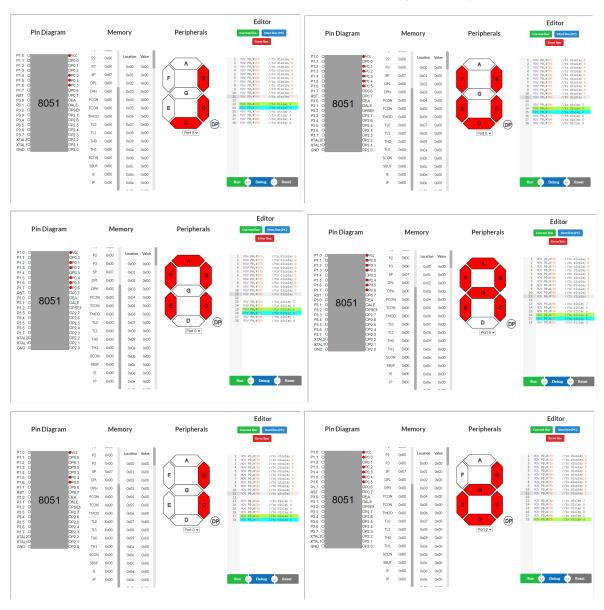




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CONCLUSION: We learn about 7 segment display and simulations using the 8051 Microcontroller. We then simulated a few examples by writing the code.