More Efficient Sorting: Mergesort and Quicksort

Recursive Sorts

Recursive sorts Divide the data roughly in half and are called Again on the smaller data sets. This is called the Divide-and-Conquer paradigm. We will see 2 recursive sorts:

- Merge Sort
- QuickSort

Divide-and-Conquer

- Divide-and-conquer paradigm:
 - Divide: divide one large problem into 2 smaller problems of the same type.
 - Recur: solve the 2 subproblems.
 - Conquer: combine the 2 solutions into a solution to the larger problem.
- The base case for the recursion are subproblems of manageable size, usually 0 or 1.

Merge-sort is a sorting algorithm based on the divide-and-conquer paradigm

Merge Sort

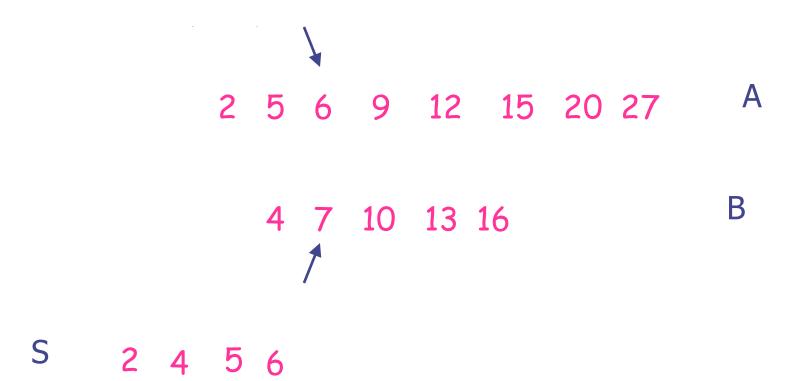
Merge-Sort

Merge-sort on an input sequence S with n elements consists of three steps:

- Divide: partition into 2 groups of about n/2 each
- Recur: recursively sort S_1 and S_2
- Conquer: merge S_1 and S_2 into a unique sorted sequence

Merging Two Sorted Sequences

- lacktriangle The conquer step merges the 2 sorted sequences A and B into one sorted sequence S
- ♦ How: Compare the lowest element of each of A and B and insert whichever is smaller.
- igoplus Merging two sorted sequences, each with <math>n/2 elements and implemented by means of a doubly linked list, takes O(n) time



Merging Two Sorted Sequences

```
Algorithm merge(A, B)
   Input sorted sequences A and B
   Output sorted sequence of A \cup B
   S \leftarrow empty sequence
   while !A.isEmpty() \land !B.isEmpty()
       if isLessThan(A.first().element(), B.first().element())
           S.insertLast(A.remove(A.first()))
       else
                                              Not In-Place
           S.insertLast(B.remove(B.first()))
   while !A.isEmpty()
          S.insertLast(A.remove(A.first()))
   while !B.isEmpty()
          S.insertLast(B.remove(B.first()))
   return S
```

Merge-Sort

```
Algorithm mergeSort(S)

Input sequence S with n elements,

Output sequence S sorted

if S.size() > 1

(S_1, S_2) \leftarrow partition(S, n/2)

mergeSort(S_1)

mergeSort(S_2)

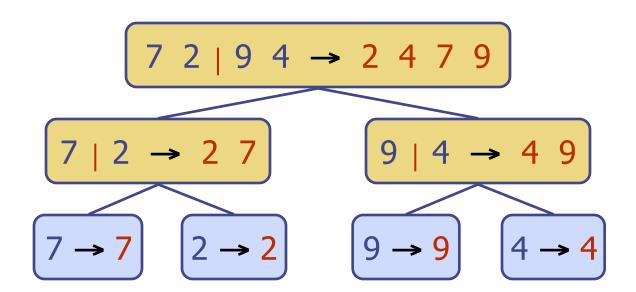
S \leftarrow merge(S_1, S_2)
```

Not In-Place

Merge-Sort Tree

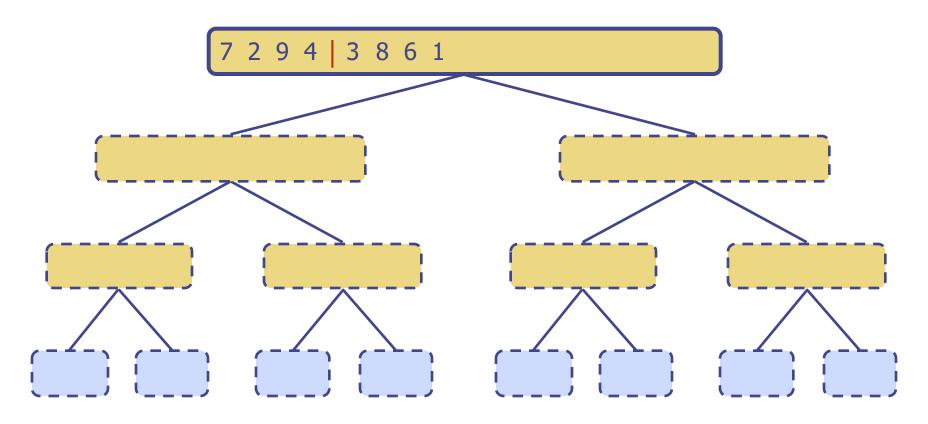
An execution of merge-sort is depicted by a binary tree

- each node represents a recursive call of merge-sort and stores
 - unsorted sequence before the execution and its partition
 - sorted sequence at the end of the execution
- the root is the initial call
- the children are calls on subsequences
- the leaves are calls on sequences of size 0 or 1

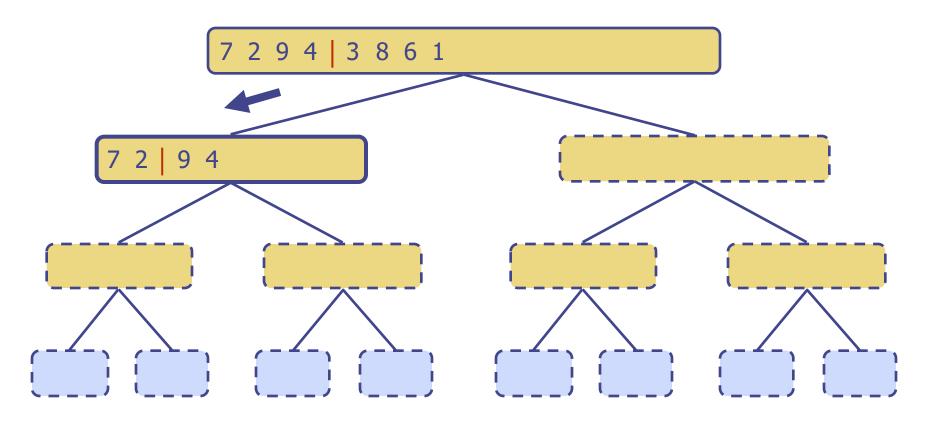


Execution Example

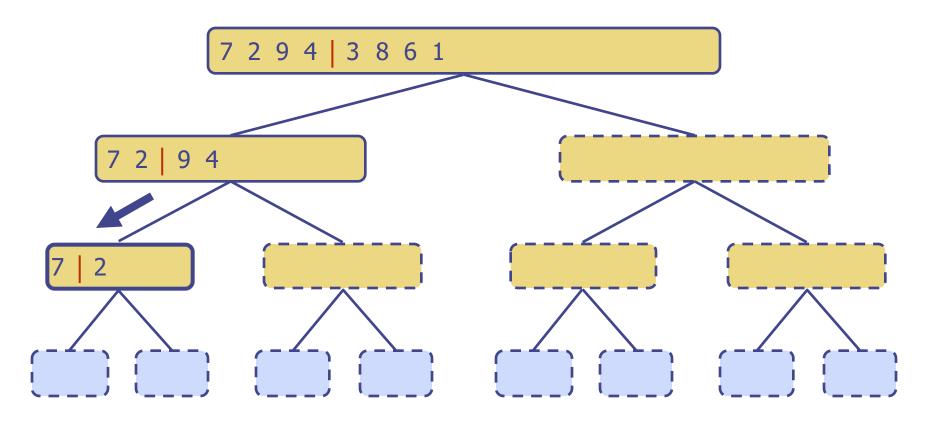
Partition



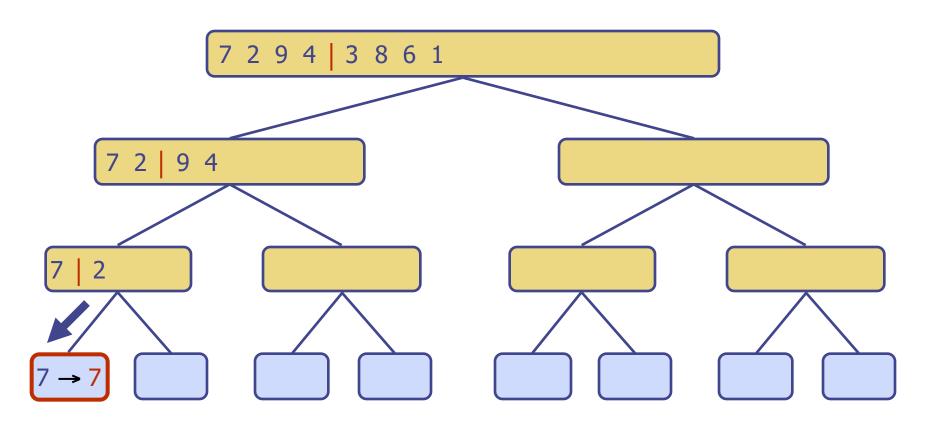
Recursive call, partition



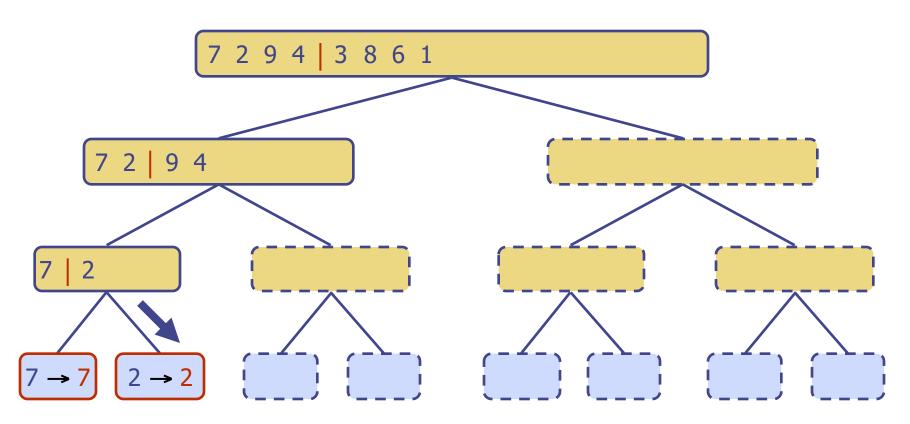
Recursive call, partition



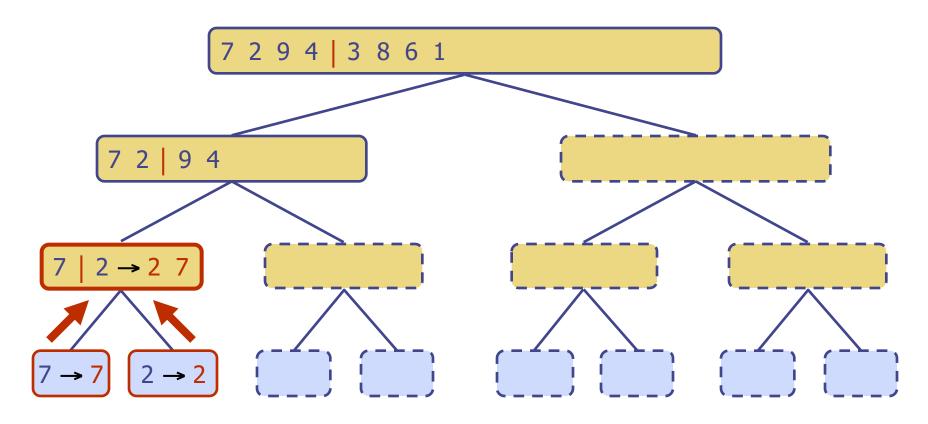
Recursive call, base case



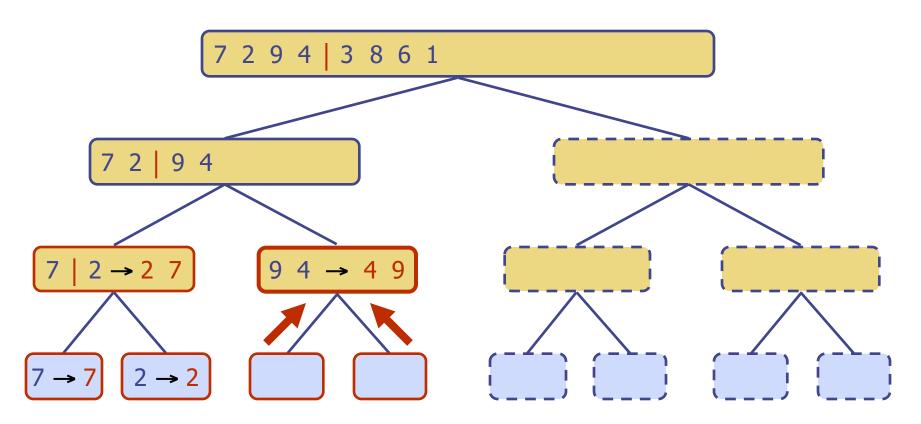
Recursive call, base case



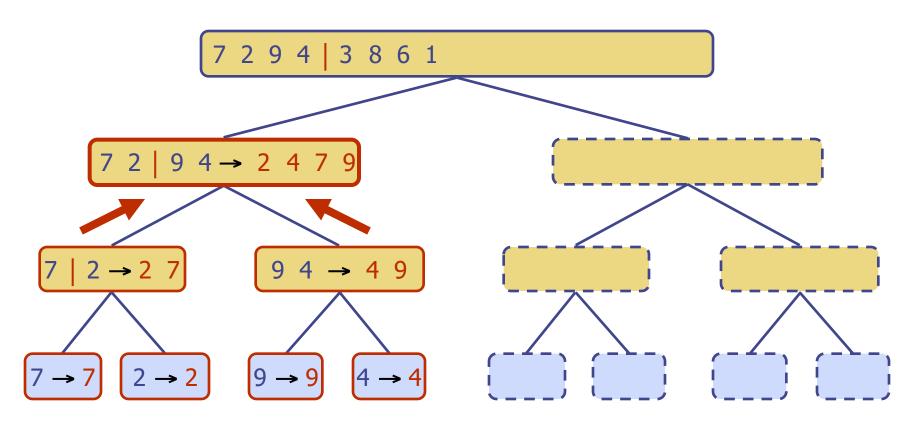
Merge



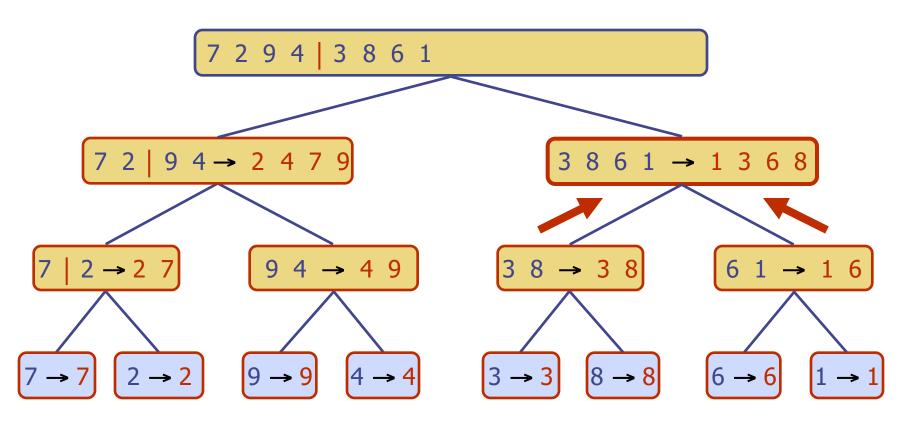
Recursive call, ..., base case, merge



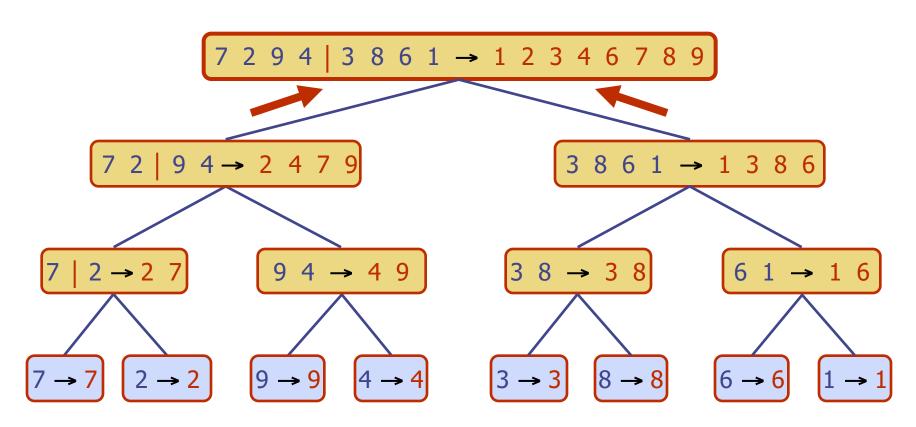
Merge



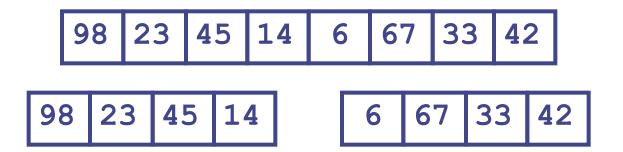
*Recursive call, ..., merge, merge

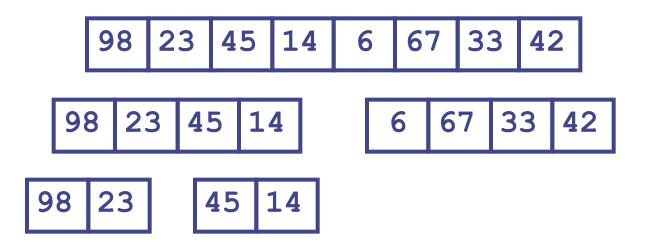


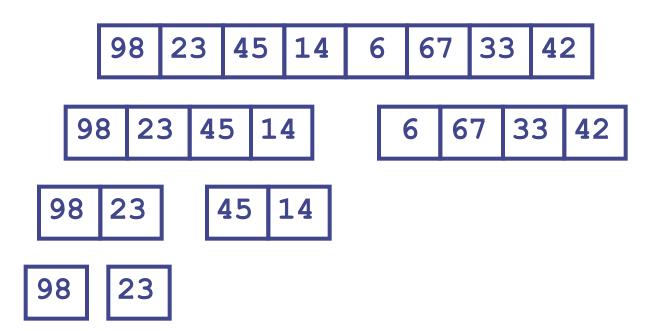
Merge

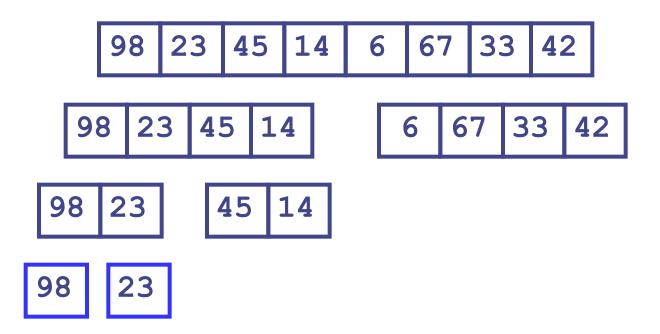


98	23	45	14	6	67	33	42

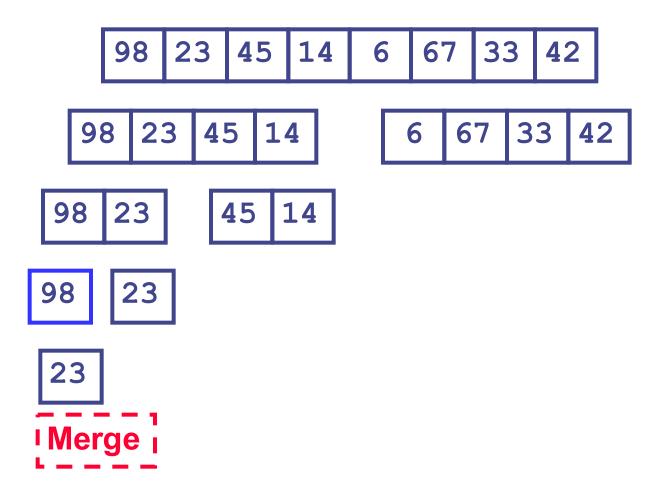


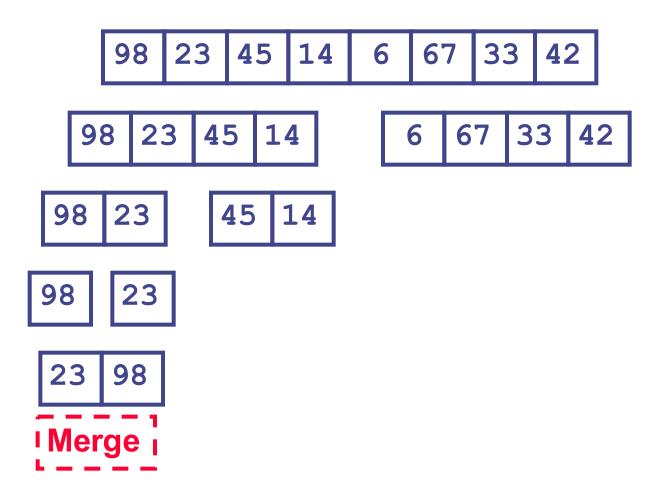


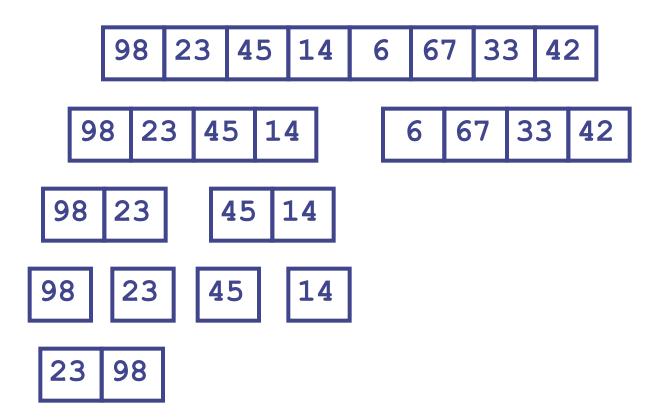


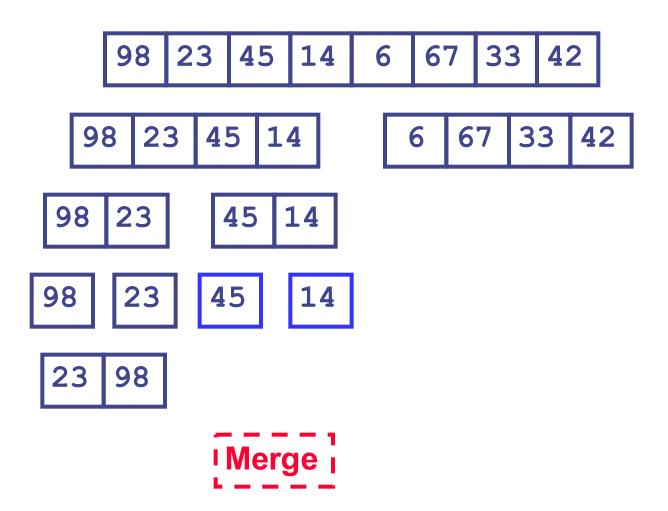


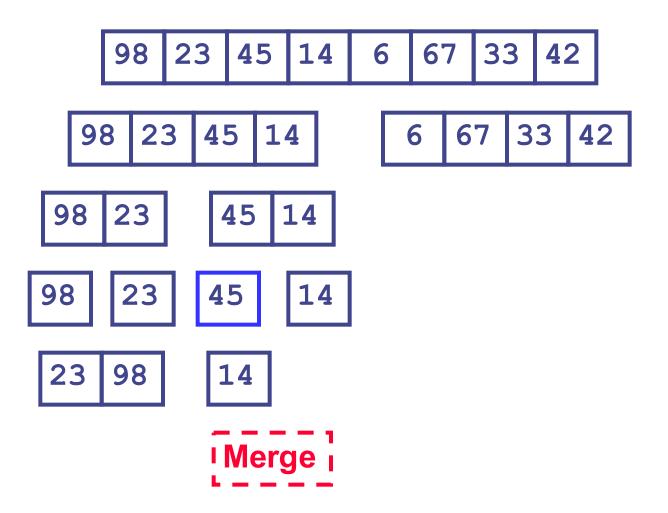


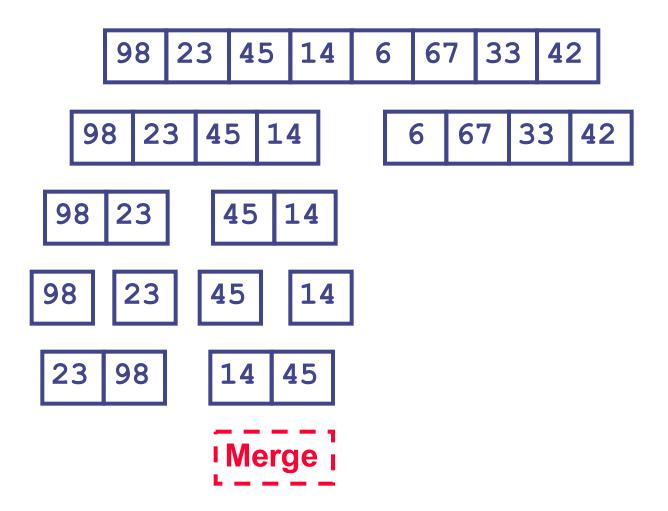


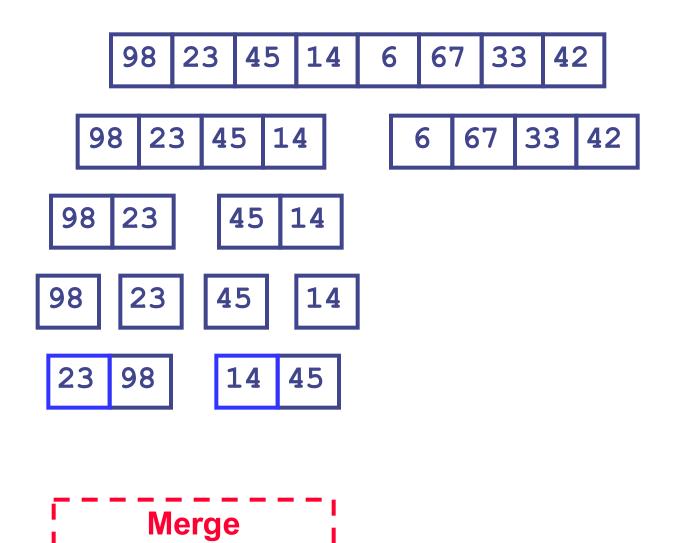


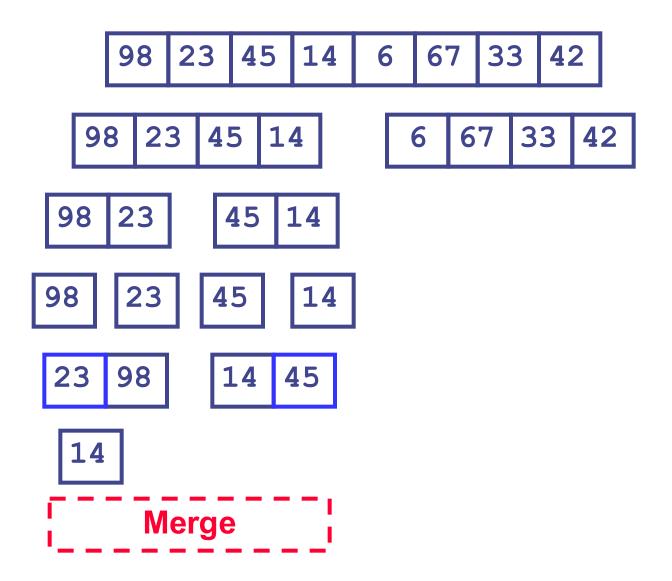


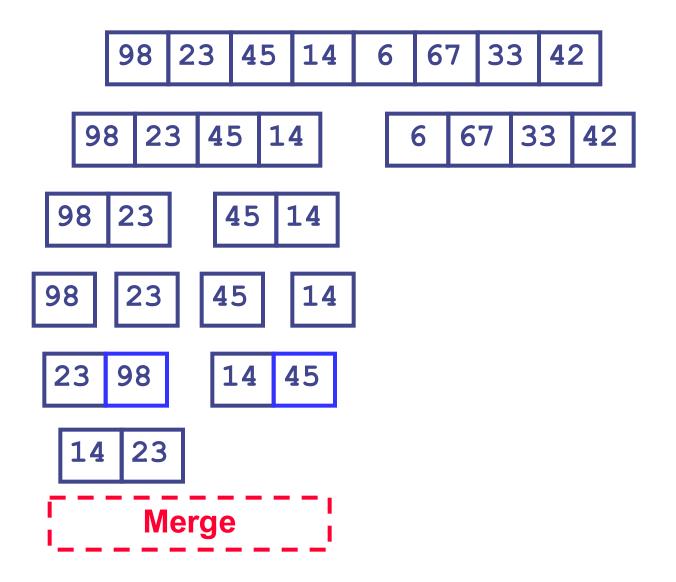


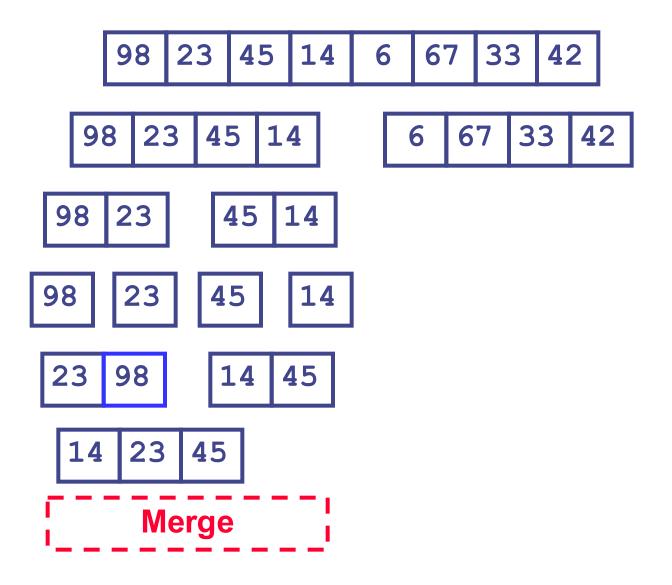


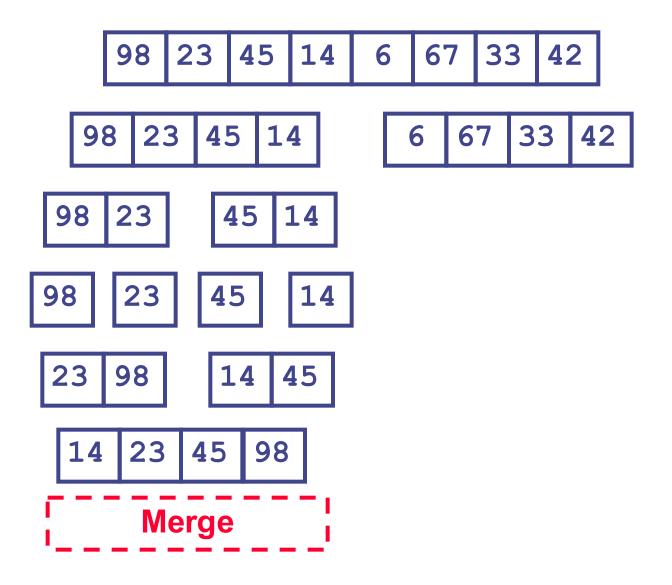


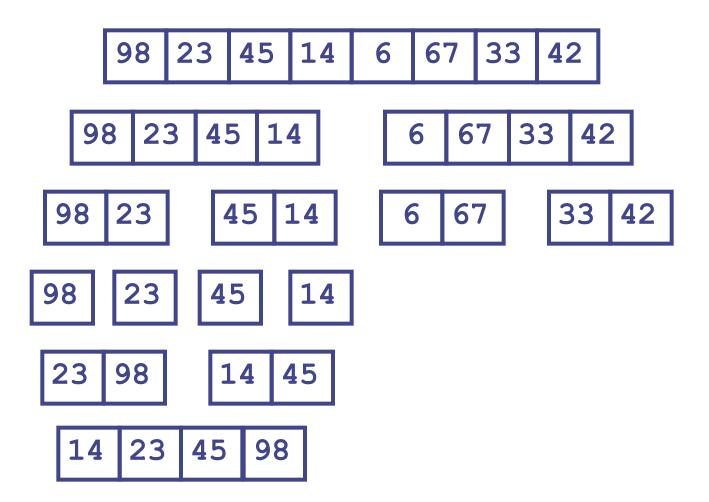


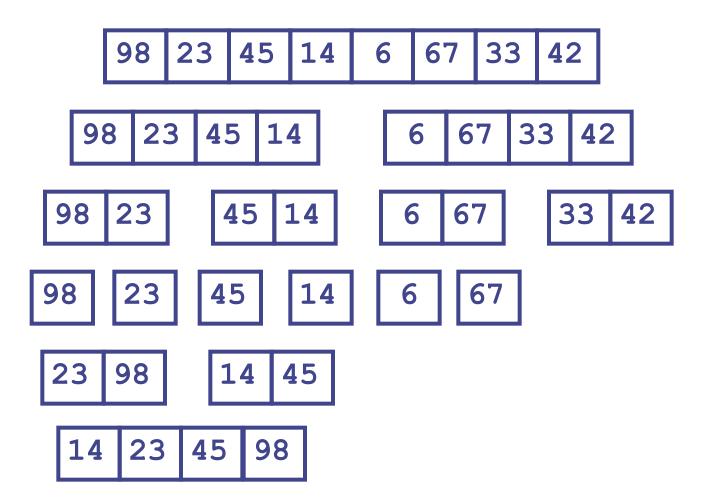


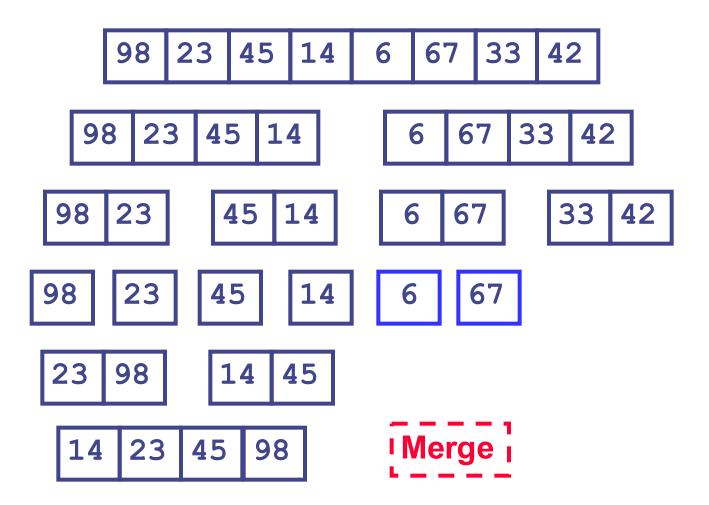


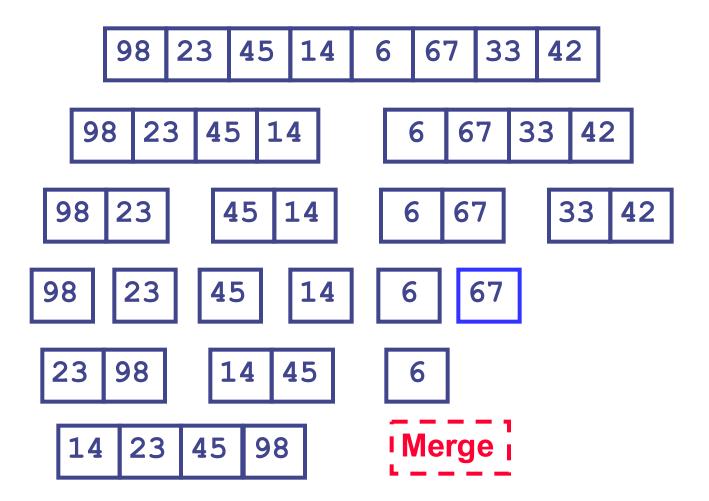


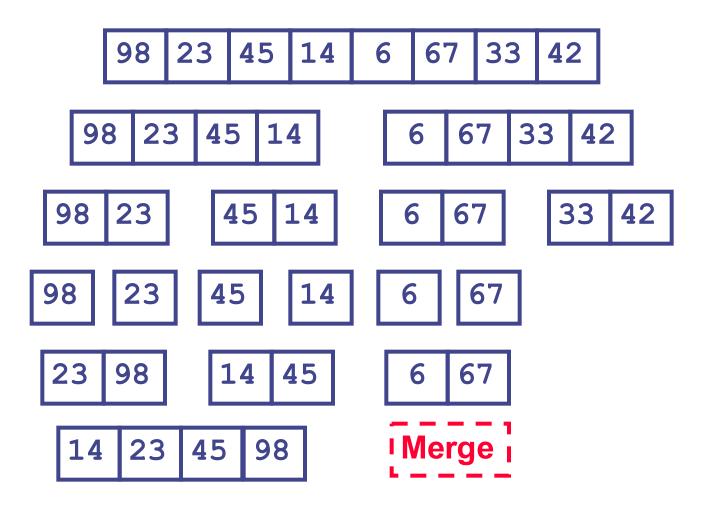


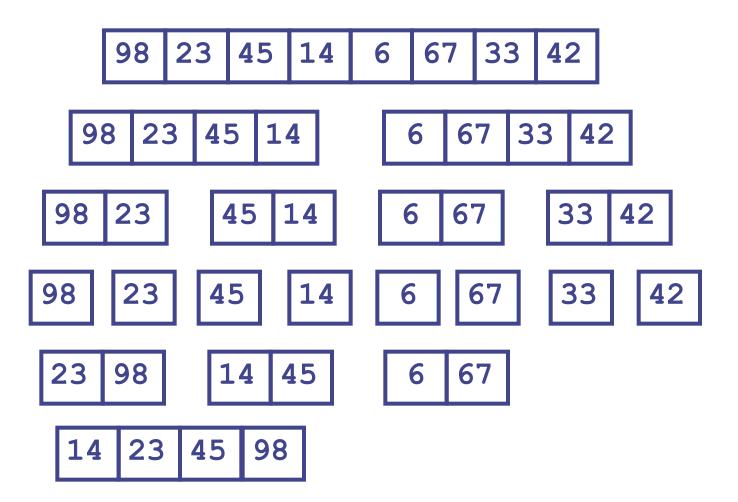


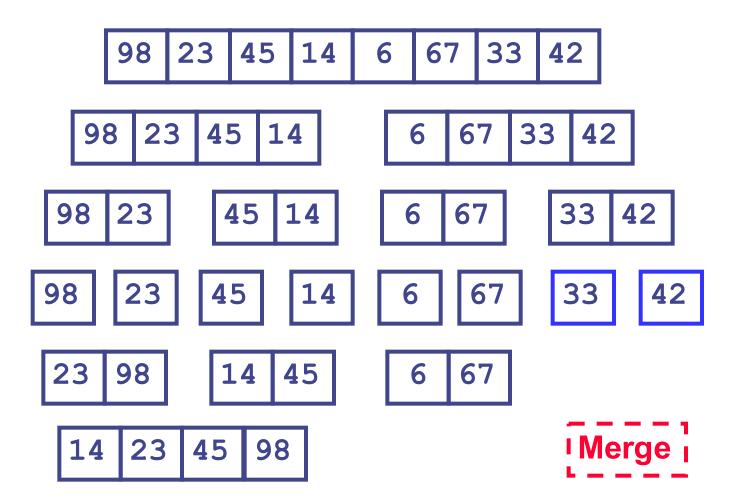


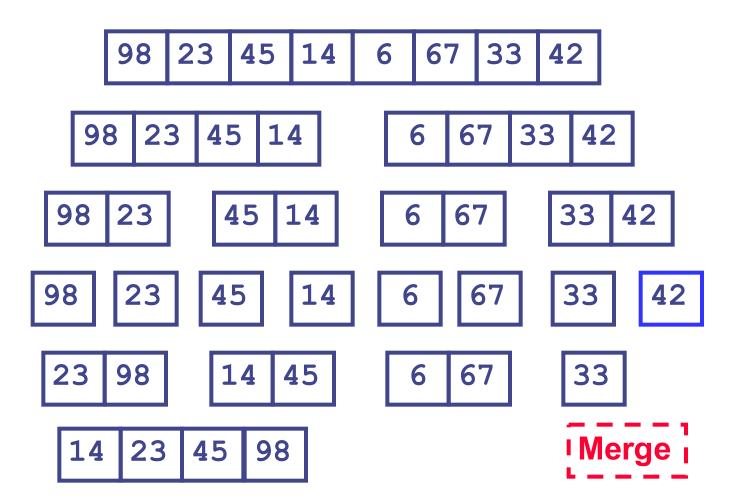


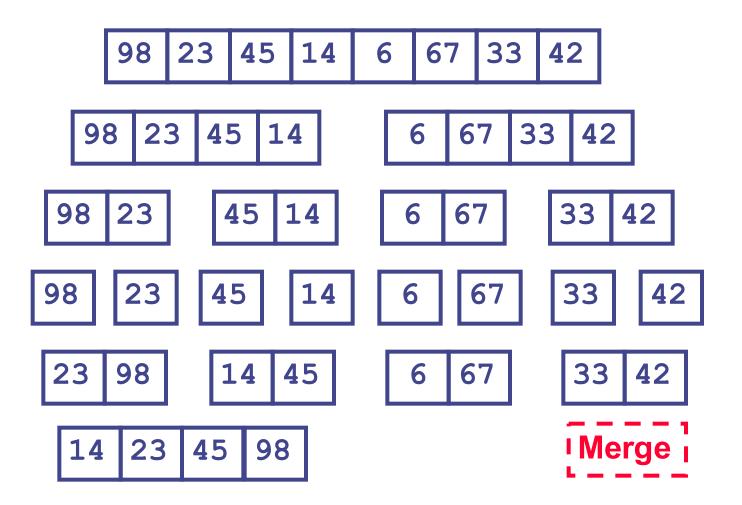


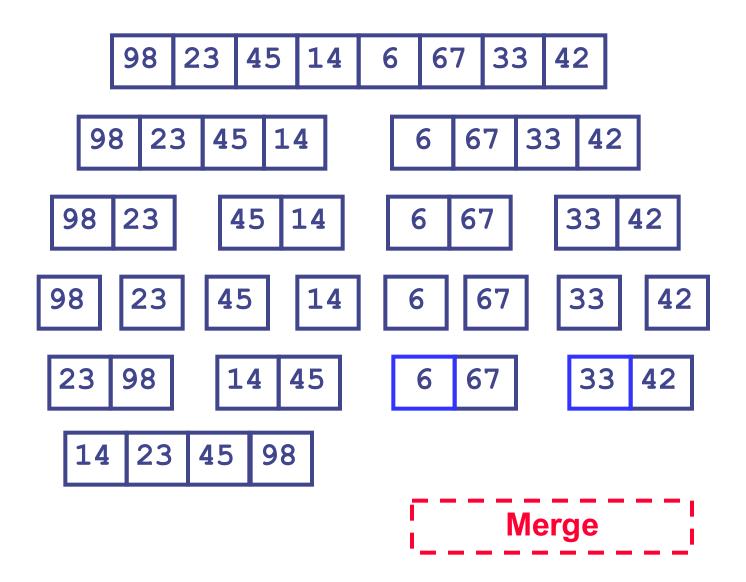


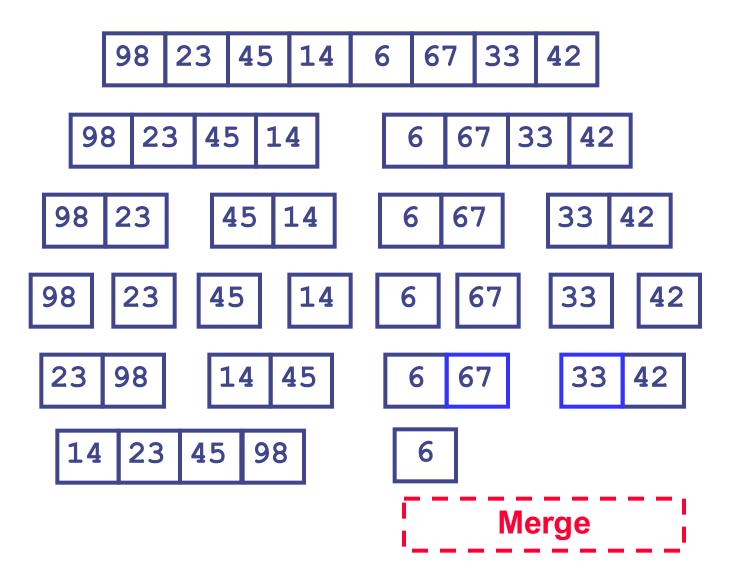


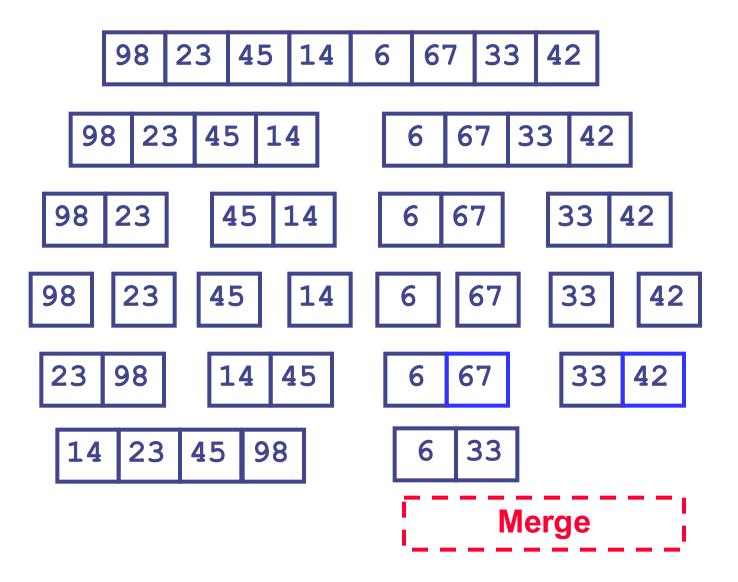


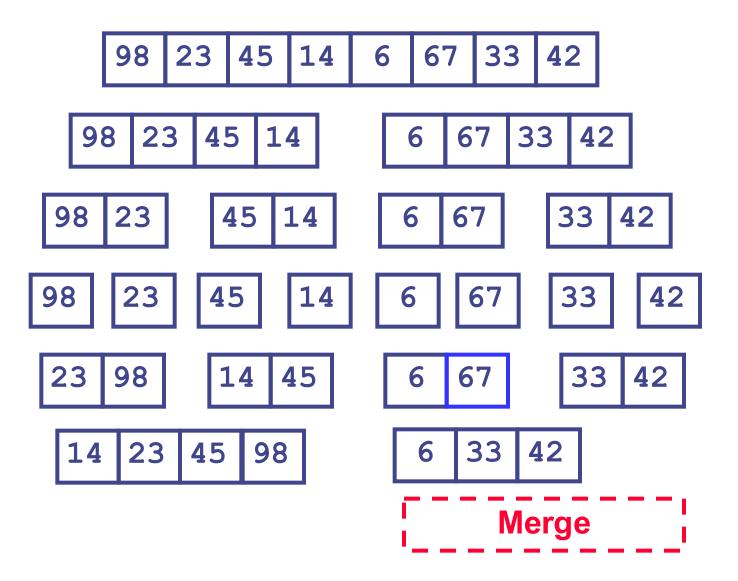


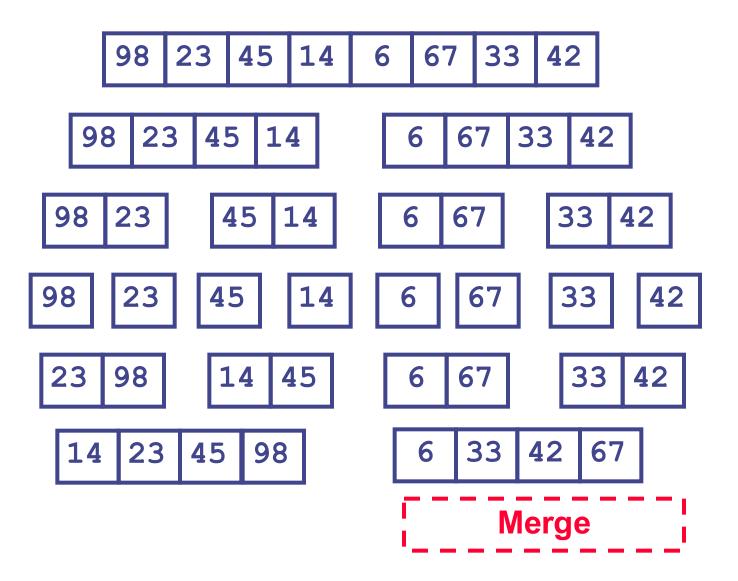


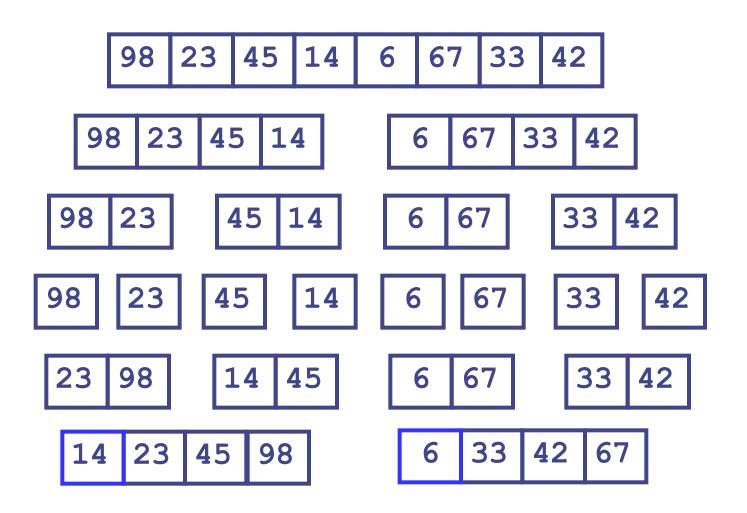


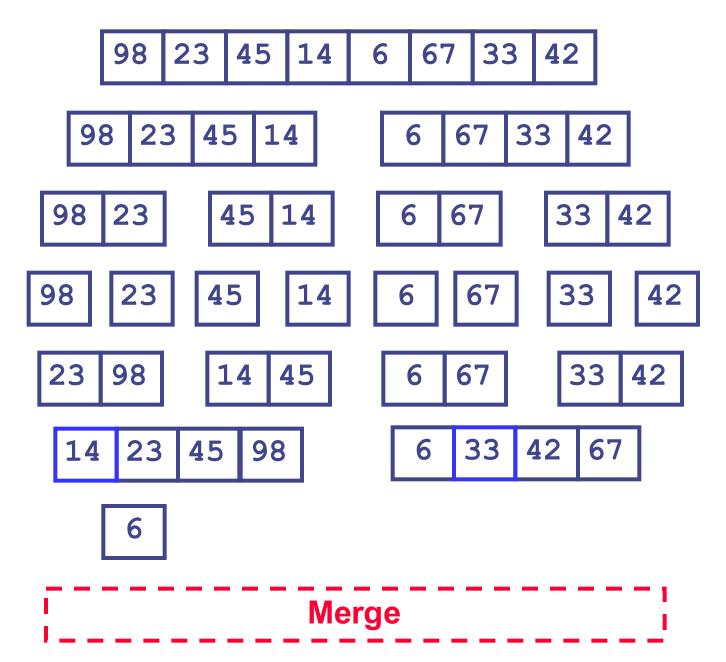


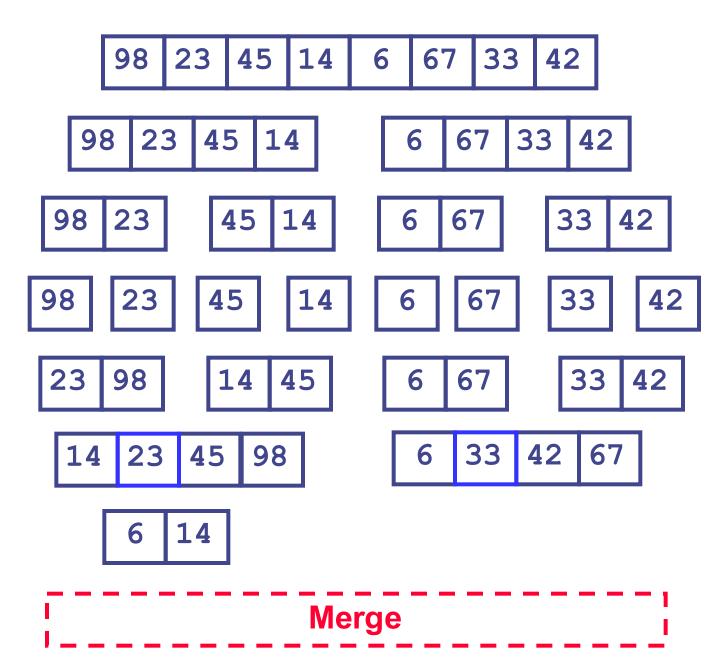


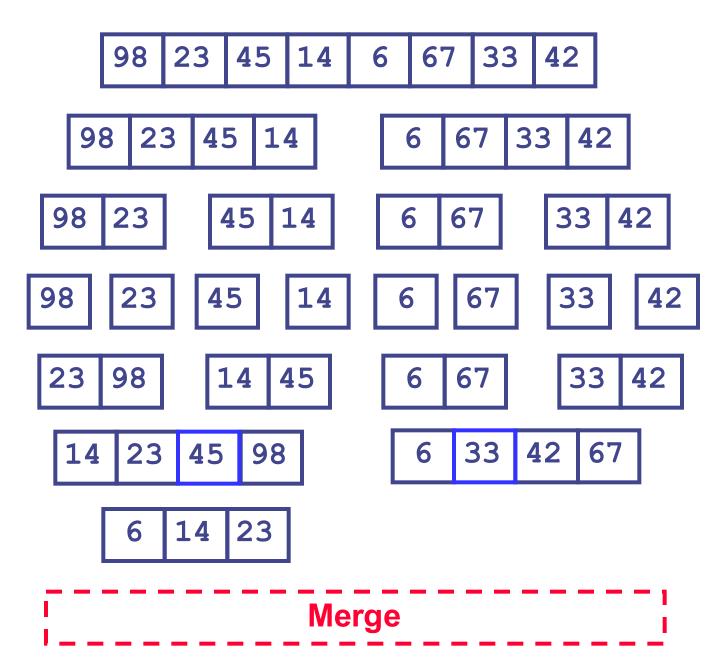


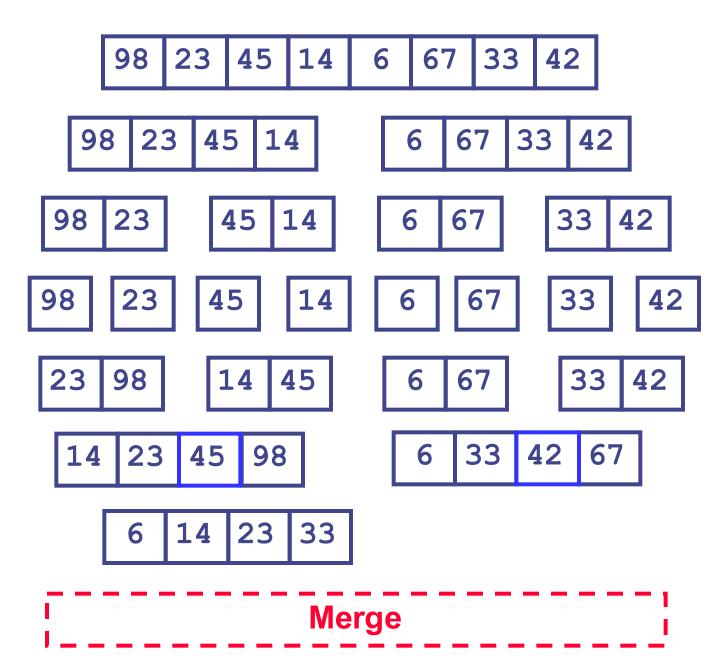


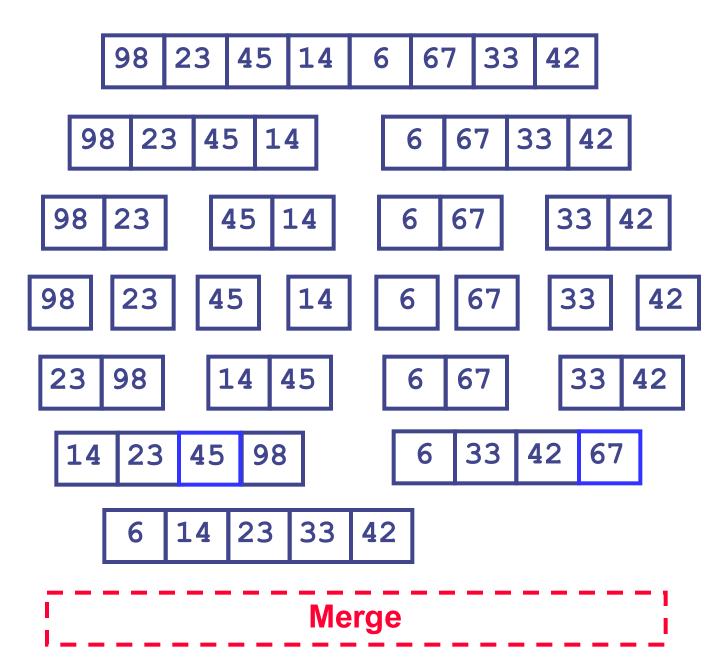


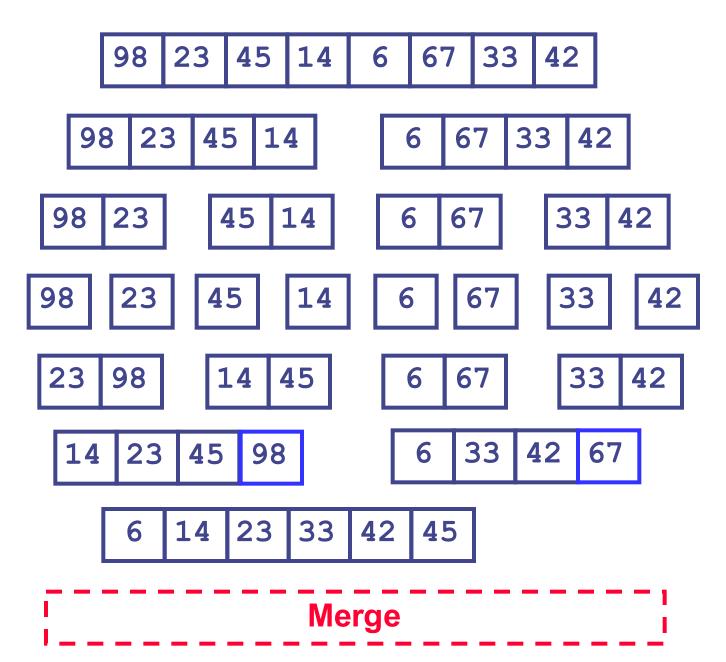


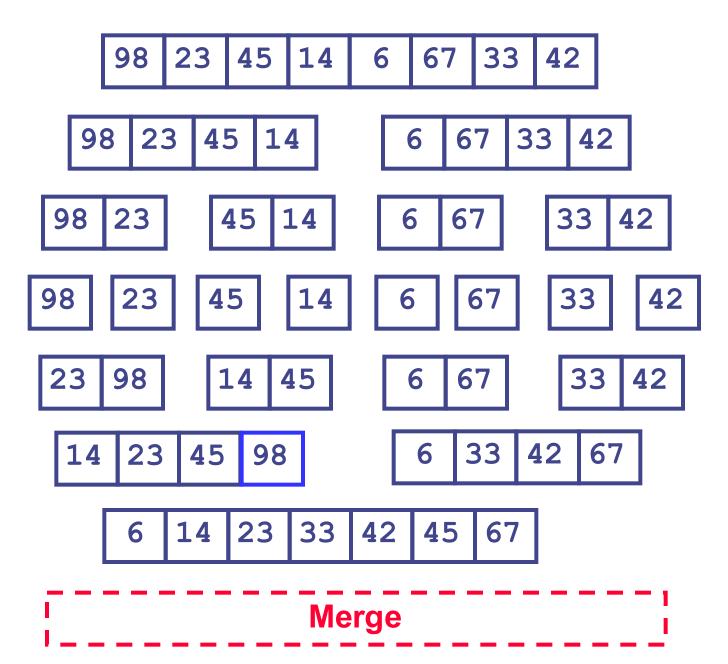


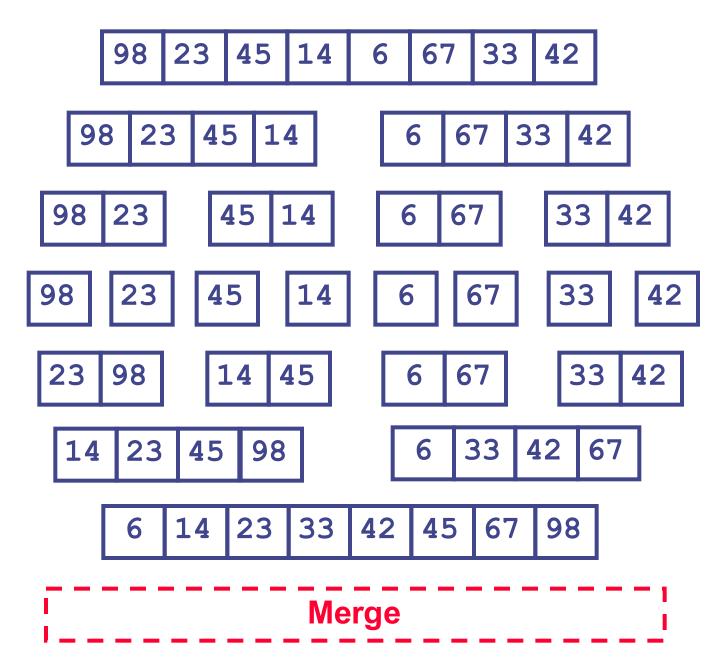


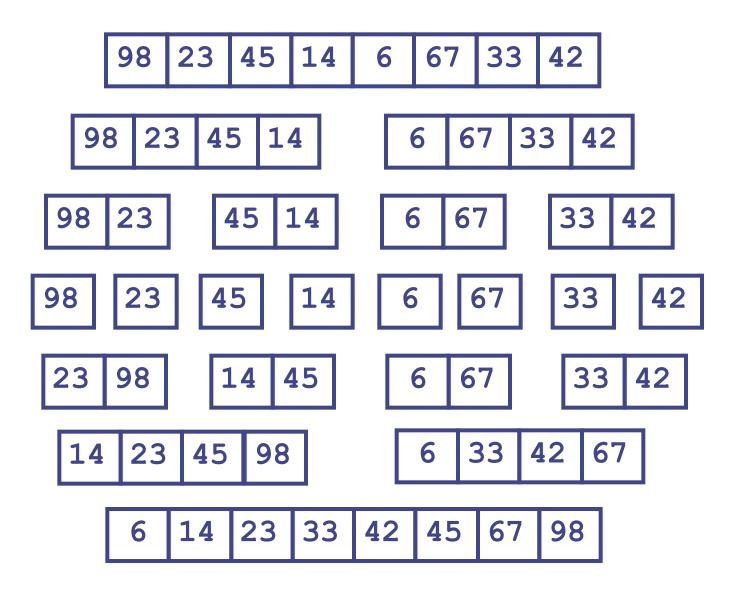


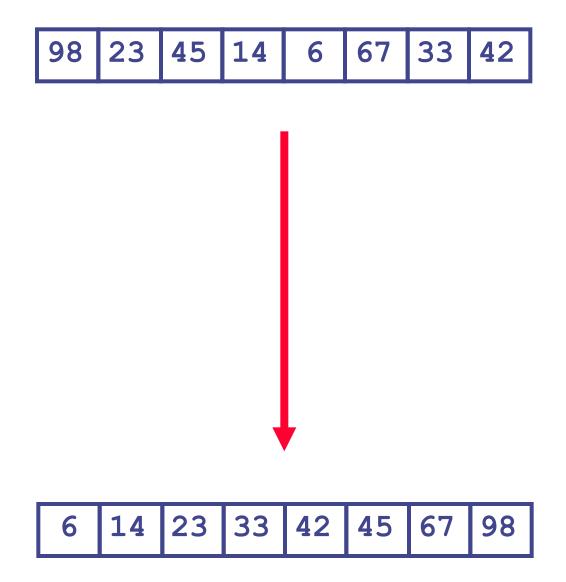






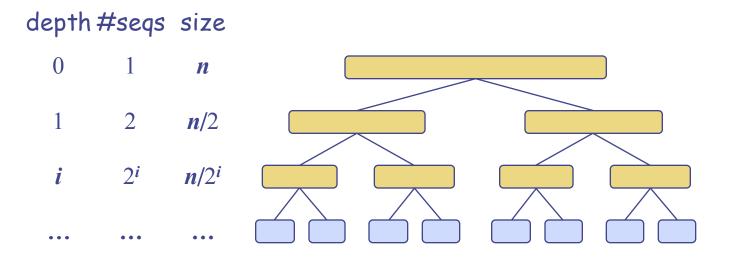






Analysis of Merge-Sort

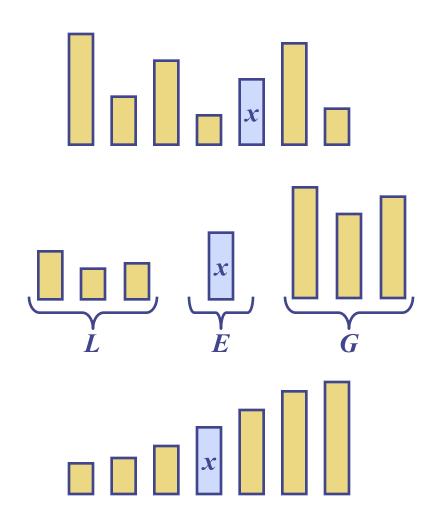
- The height h of the merge-sort tree is $O(\log n)$
 - at each recursive call we divide in half the sequence,
- lacktriangle The overall amount or work done at the nodes of depth i is O(n)
 - we partition and merge 2^i sequences of size $n/2^i$
 - we make 2^{i+1} recursive calls
- \bullet Thus, the total running time of merge-sort is $O(n \log n)$



Quick-Sort

Quick-Sort

- Quick-sort is a sorting algorithm based on the divide-and-conquer paradigm:
 - Divide: pick an element x
 (called pivot) and partition S
 into
 - L elements less than x
 - E elements equal x
 - G elements greater than x
 - \blacksquare Recur: sort L and G
 - Conquer: join L, E and G





QuickSort(S)

 $i \leftarrow PIVOT$

 $x \leftarrow S.elemAtRank(i)$

 $(L,E,G) \leftarrow Partition(S,x)$

QuickSort(L)

QuickSort(G)

combine L,E,G

In this example the PIVOT is chosen randomly, but we could decide always to choose the first element of the array, or the last.

Partition

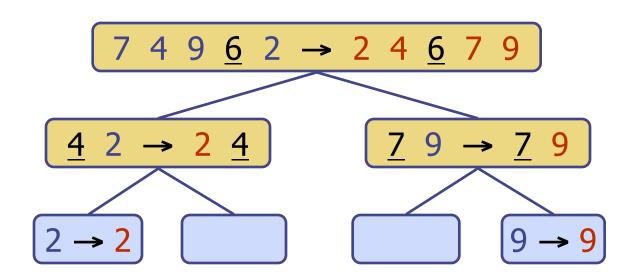
- We partition an input sequence as follows:
 - We remove, in turn, each element y from S and
 - We insert y into L, E or G, depending on the result of the comparison with the pivot x
- ◆ Each insertion and removal is at the beginning or at the end of a sequence, and hence takes O(1) time
- \bullet Thus, the partition step of quick-sort takes O(n) time

Not in-place

```
Algorithm partition(S, p)
    Input sequence S, position p of pivot
    Output subsequences L, E, G of the
        elements of S less than, equal to,
        or greater than the pivot, resp.
   L, E, G \leftarrow empty sequences
   x \leftarrow S.remove(p)
   while !S.isEmpty()
       y \leftarrow S.remove(S.first())
       if v < x
           L.insertLast(y)
        else if y = x
            E.insertLast(y)
        else \{y > x\}
            G.insertLast(y)
    return L, E, G
```

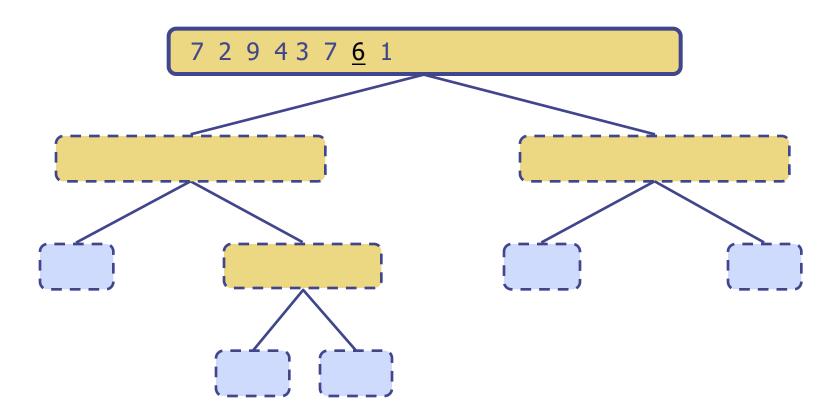
Quick-Sort Tree An execution of quick-sort is depicted by a binary tree

- - Each node represents a recursive call of quick-sort and stores
 - Unsorted sequence before the execution and its pivot
 - Sorted sequence at the end of the execution
 - The root is the initial call
 - The leaves are calls on subsequences of size 0 or 1

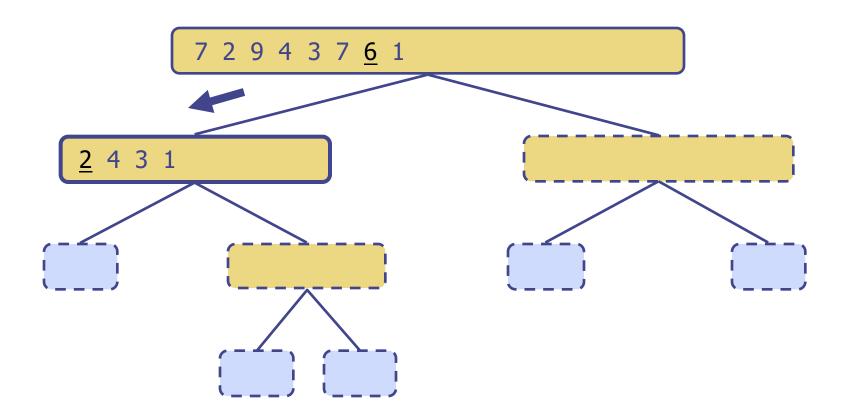


Execution Example

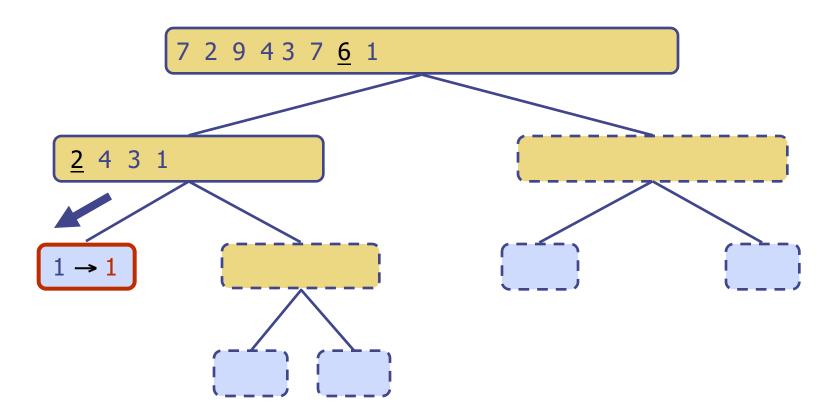
Pivot selection



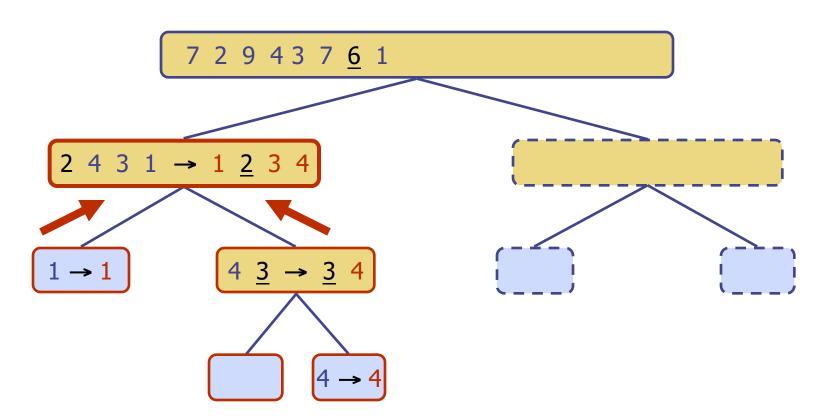
Partition, recursive call, pivot selection



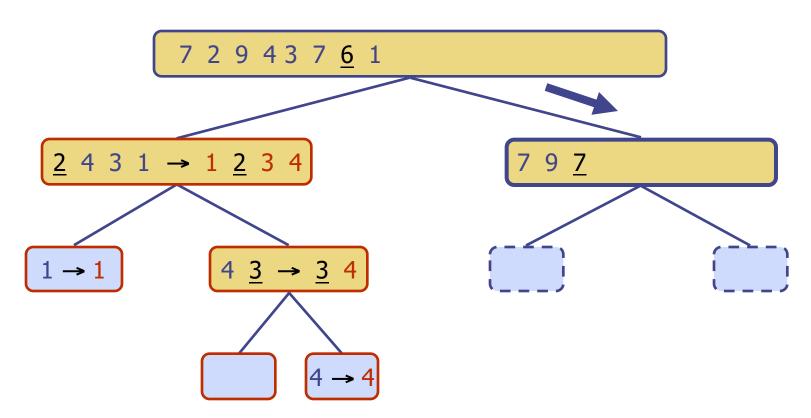
Partition, recursive call, base case



Recursive call, ..., base case, join

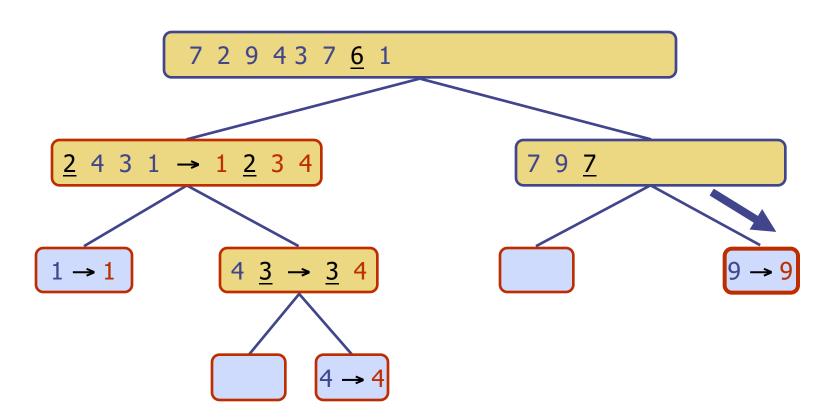


Recursive call, pivot selection



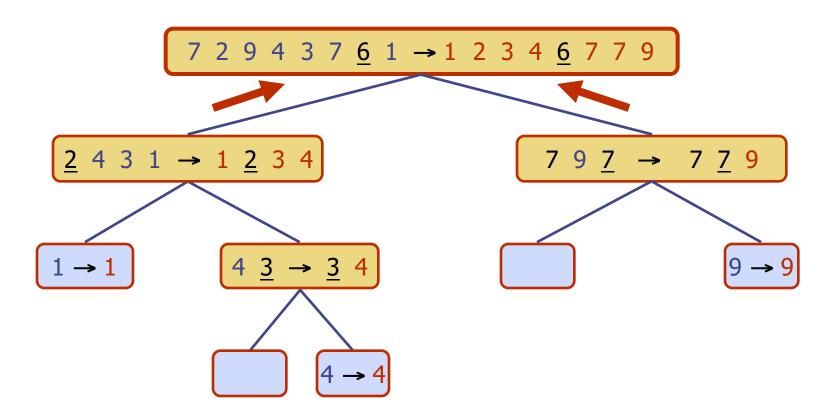
Execution Example (cont.)

Partition, ..., recursive call, base case



Execution Example (cont.)

Join, join



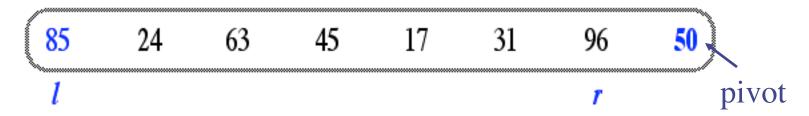
In-Place Quick-Sort

In the partition step, we use replace operations to rearrange the elements of the input sequence such that

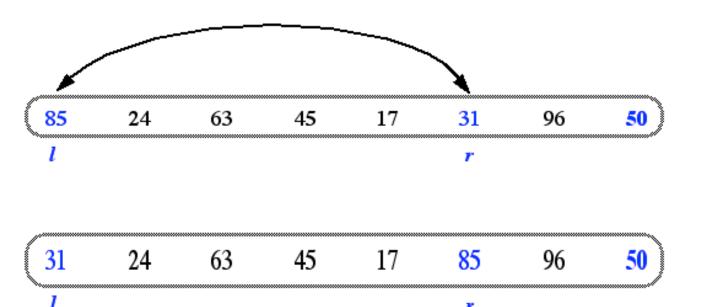
- \blacksquare the elements less than the pivot have rank less than h
- the elements equal to the pivot have rank between h and k
- the elements greater than the pivot have rank greater than k
- The recursive calls consider
 - elements with rank less than h
 - \blacksquare elements with rank greater than k

In-Place Quick-Sort

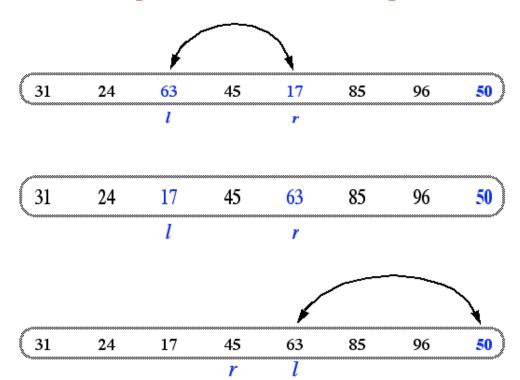
Divide step: *l* scans the sequence from the left, and *r* from the right.



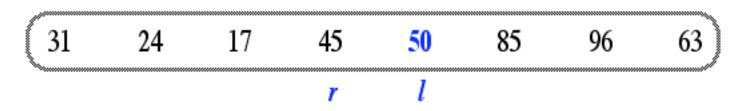
A swap is performed when 1 is at an element larger than the pivot and r is at one smaller than the pivot.



In Place Quick Sort (contd.)



A final swap with the pivot completes the divide step



In-Place Quick-Sort

```
Algorithm inPlaceQuickSort(S, l, r)
Input sequence S, ranks l and r
Output sequence S with the elements of rank between l and r
rearranged in increasing order

if l \ge r
return

i \leftarrow a random integer between l and r
x \leftarrow S.elemAtRank(i)
(h, k) \leftarrow inPlacePartition(x)
inPlaceQuickSort(S, l, h - 1)
inPlaceQuickSort(S, k + 1, r)
```

In Place Partition

- Repeat until I and r cross:
 - I traverse the array from left to right until it finds and element ≥ pivot
 - r traverse the array from right to left until it finds an element < pivot
 - Swap elements at indices l and r

Algorithm *inPlacePartition*(p,s,e)

Input: position *p* of the pivot; s and e are the sequence limits

Output: 1 and r such that:

r-1=index of the last element smaller than the pivot

1+1=index of the first element larger than the pivot

$$l \leftarrow s, r \leftarrow e-1$$

 $swap S[p]$ with $S[e], p \leftarrow e$
 $while l \leq r$
 $while S[l] < S[p]$ and $r \geq l$
 $l \leftarrow l+1$
 $swap S[r] \geq S[p]$ and $r \geq l$
 $swap S[l]$ with $S[l]$
 $swap S[l]$ with $S[p]$
 $swap S[l]$ with $S[p]$

In Place Quick-sort

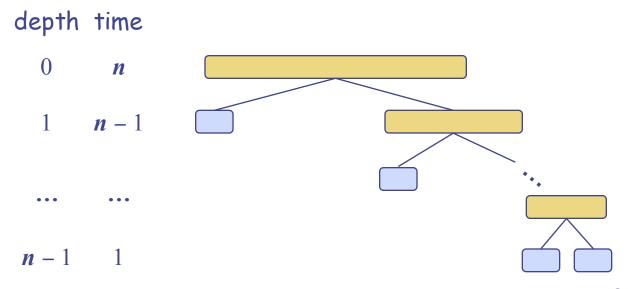
```
/** Sort the subarray S[a..b] inclusive. */
      private static <K> void quickSortInPlace(K[] S, Comparator<K> comp,
                                                                            int a, int b) {
        if (a >= b) return; // subarray is trivially sorted
        int left = a;
        int right = b-1;
 6
        K pivot = S[b];
        K temp;
                                  // temp object used for swapping
 8
        while (left <= right) {
10
          // scan until reaching value equal or larger than pivot (or right marker)
          while (left \leq right && comp.compare(S[left], pivot) < 0) left++;
11
          // scan until reaching value equal or smaller than pivot (or left marker)
12
          while (left \leq right && comp.compare(S[right], pivot) > 0) right—;
13
          if (left <= right) { // indices did not strictly cross</pre>
14
            // so swap values and shrink range
15
            temp = S[left]; S[left] = S[right]; S[right] = temp;
16
            left++; right--;
17
18
19
        // put pivot into its final place (currently marked by left index)
20
        temp = S[left]; S[left] = S[b]; S[b] = temp;
21
        // make recursive calls
22
        quickSortInPlace(S, comp, a, left -1);
23
        quickSortInPlace(S, comp, left + 1, b);
24
25
```

Worst-case Running Time

- The worst case for quick-sort occurs when the pivot is the unique minimum or maximum element
- \bullet One of L and G has size n-1 and the other has size 0
- The running time is proportional to the sum

$$n + (n - 1) + \dots + 2 + 1$$

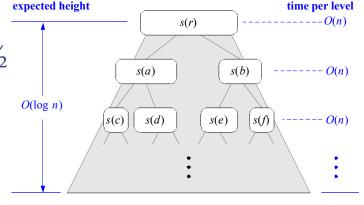
 \bullet Thus, the worst-case running time of quick-sort is $O(n^2)$



Expected Running Time

Consider a recursive call of quicksort on a sequence of size s

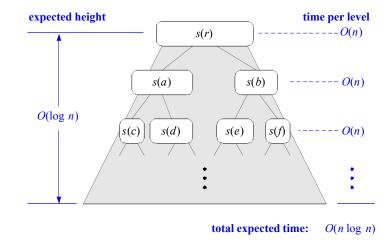
- Good call: the sizes of L and G are each less than 3s/4
- Bad call: one of L and G has size greater than 3s/4
- ◆ A call is good with probability ½ (for an element, the expected number of calls until a good call is 2)
- Hence, for a node of depth i, we expect that
 - i/2 ancestor nodes are associated with good calls
 - the expected size of the input sequence for the current call is at most $(3/4)^{i/2}n$



total expected time: $O(n \log n)$

Expected Running Time

- Thus, we have
 - For a node of depth $2\log_{4/3}n$, the expected size of the input sequence is one $((3/4)^{(2\log_{4/3}n)/2})$ n = 1)
 - The expected height of the quicksort tree is $O(\log n)$
- The overall amount or work done at the nodes of the same depth of the quick-sort tree is O(n)
- \bullet Thus, the expected running time of quick-sort is $O(n \log n)$



Algorithm	Time	Notes
selection-sort	$O(n^2)$ w.c. and av.	in-placeslow (good for small inputs)
insertion-sort	$O(n^2)$ w.c. and av.	♦ in-place♦ slow (good for small inputs)
quick-sort	$O(n^2)$ w.c. $O(n \log n)$ average	in-place, randomizedfastest (good for large inputs)
heap-sort	$O(n \log n)$ w.c. and av.	in-placefast (good for large inputs)
merge-sort	<i>O</i> (<i>n</i> log <i>n</i>) w.c. and av.	sequential data accessfast (good for huge inputs)