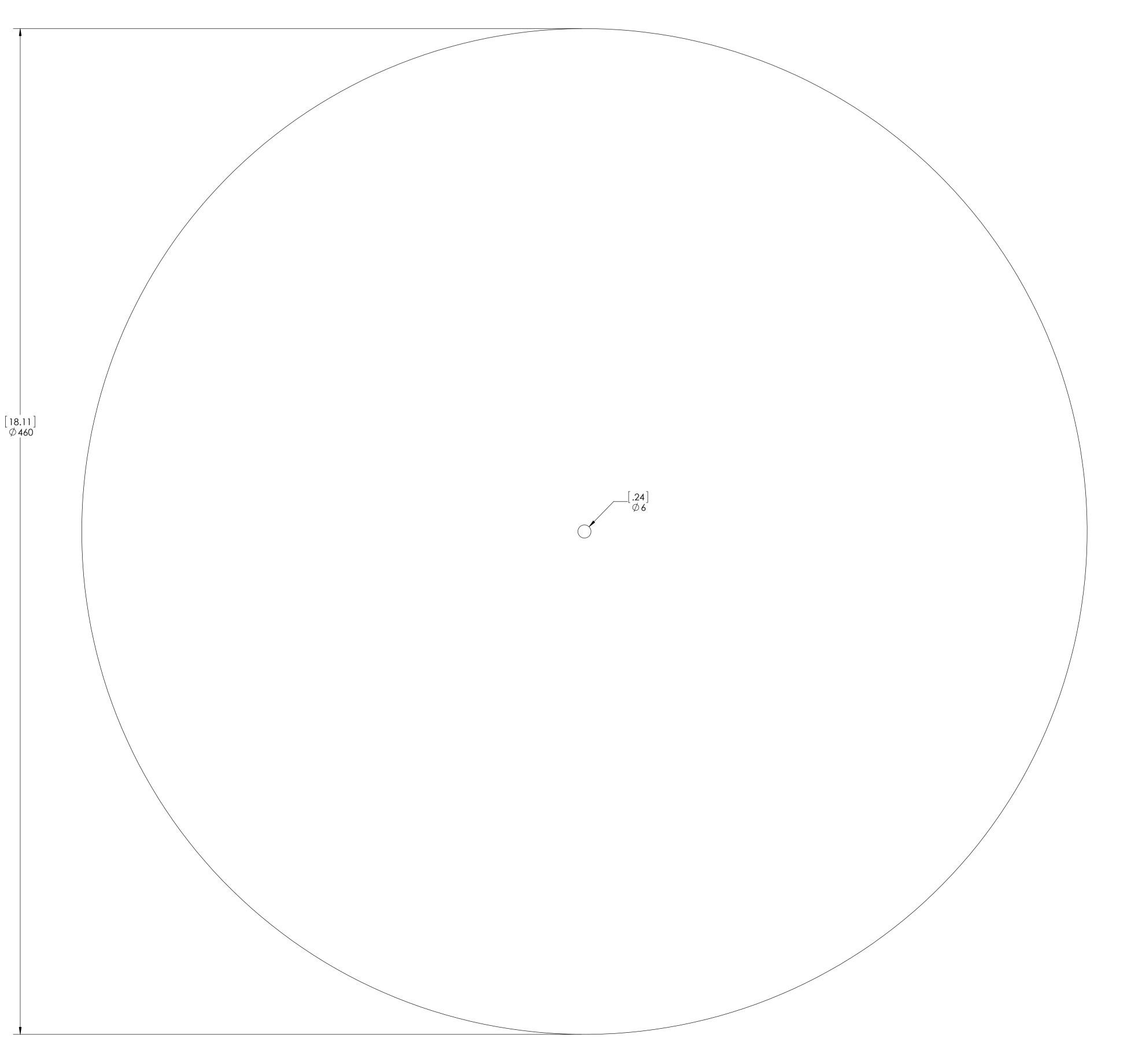
This circle prevents arm from getting caught on tabs. No tabs are glued onto this circle.



UNLESS OTHERWISE SPECIFIED:
DIMENSIONS ARE IN MILLIMETERS
SURFACE FINISH:
TOLERANCES:
LINEAR:
ANGULAR:

NAME SIGNATURE DATE

DRAWN
CHK'D
APPV'D
MFG
Q.A
MATERIAL:

DEBUR AND
BREAK SHARP
EDGES

DO NOT SCALE DRAWING
REVISION

TITLE:

DO NOT SCALE DRAWING
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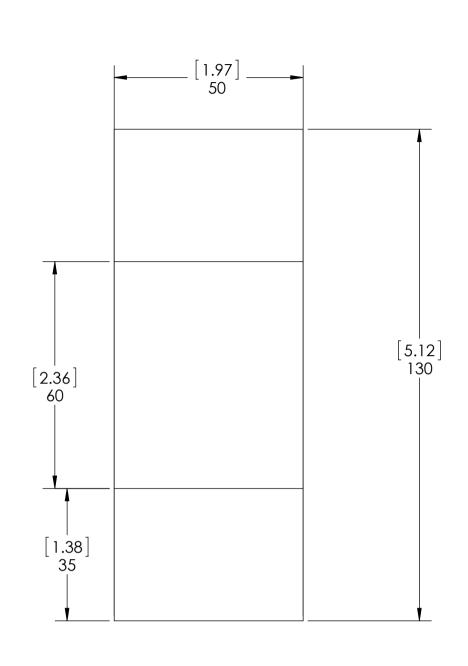
APPN'D

MATERIAL:

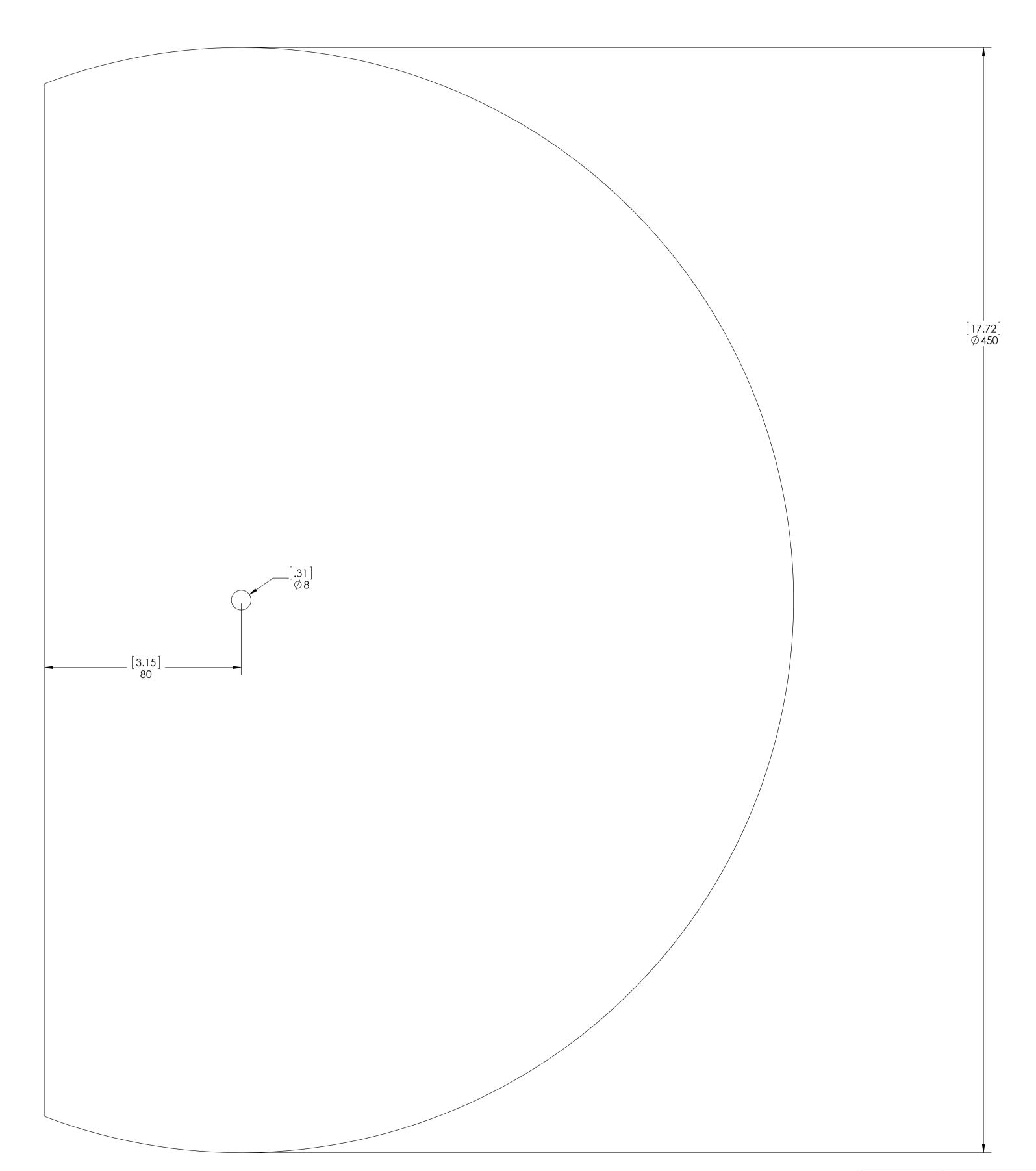
DWG NO.

CBR - final

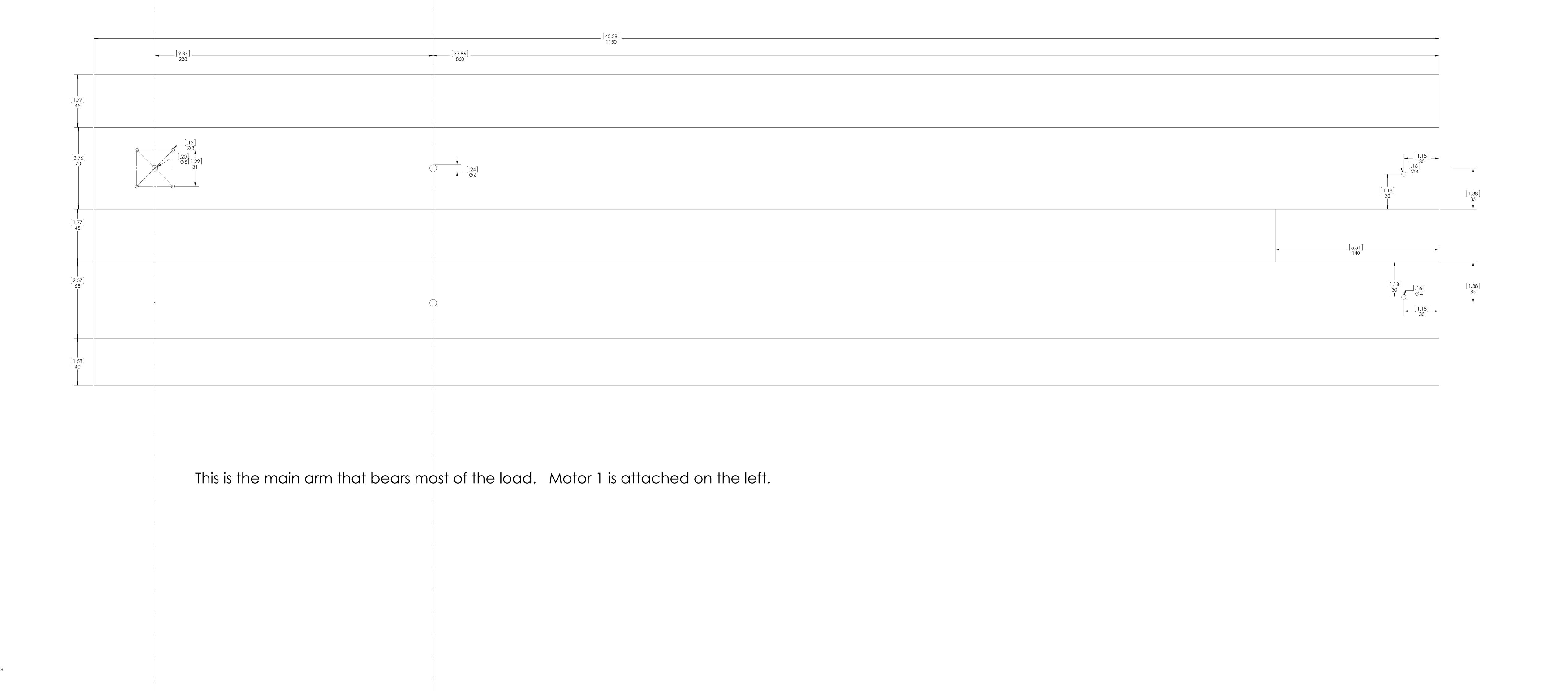
Need 2 semi-circles

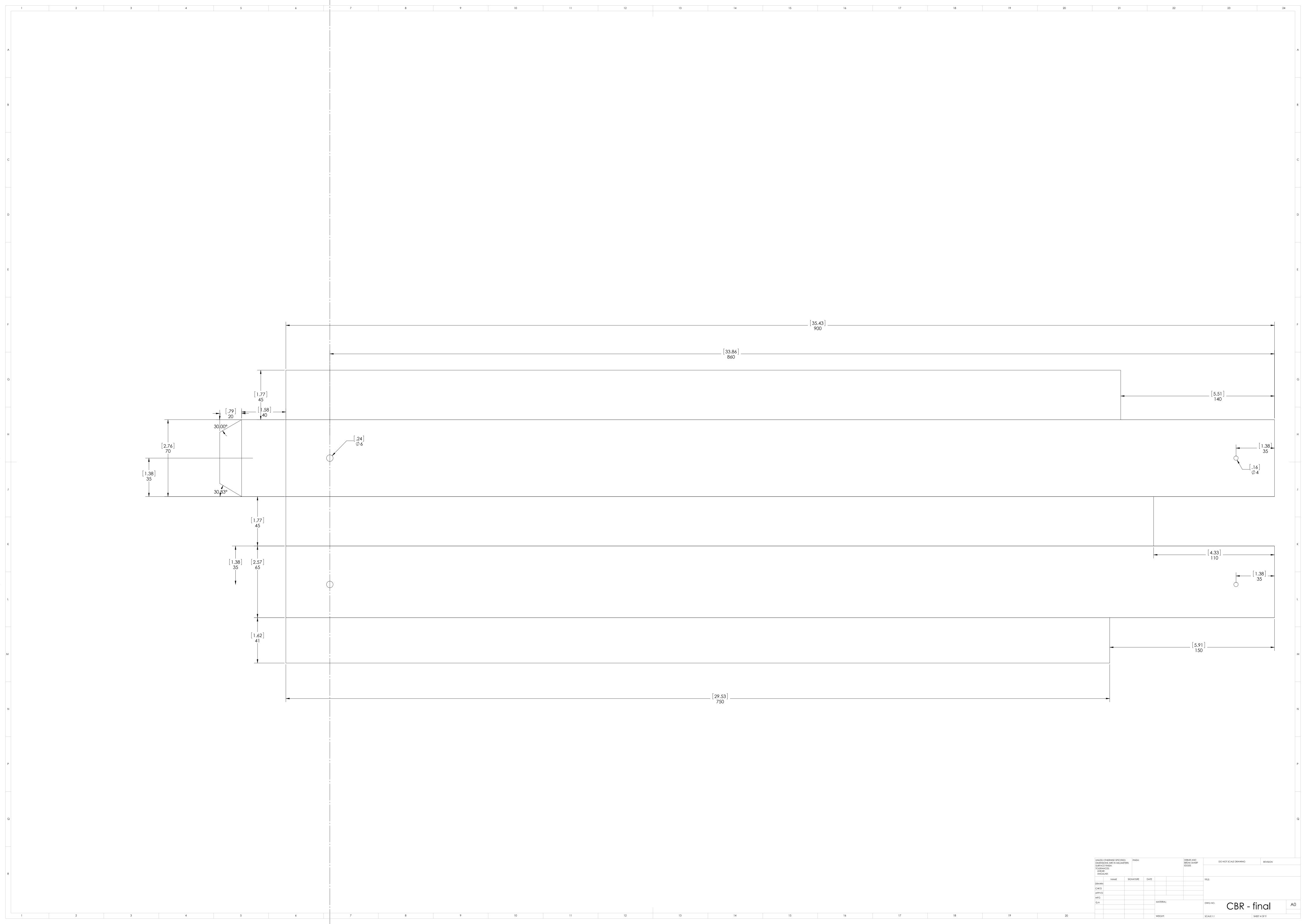


- Need 16 tabs
 9 for large semi-circles
 7 for small semi circles



CBR - final

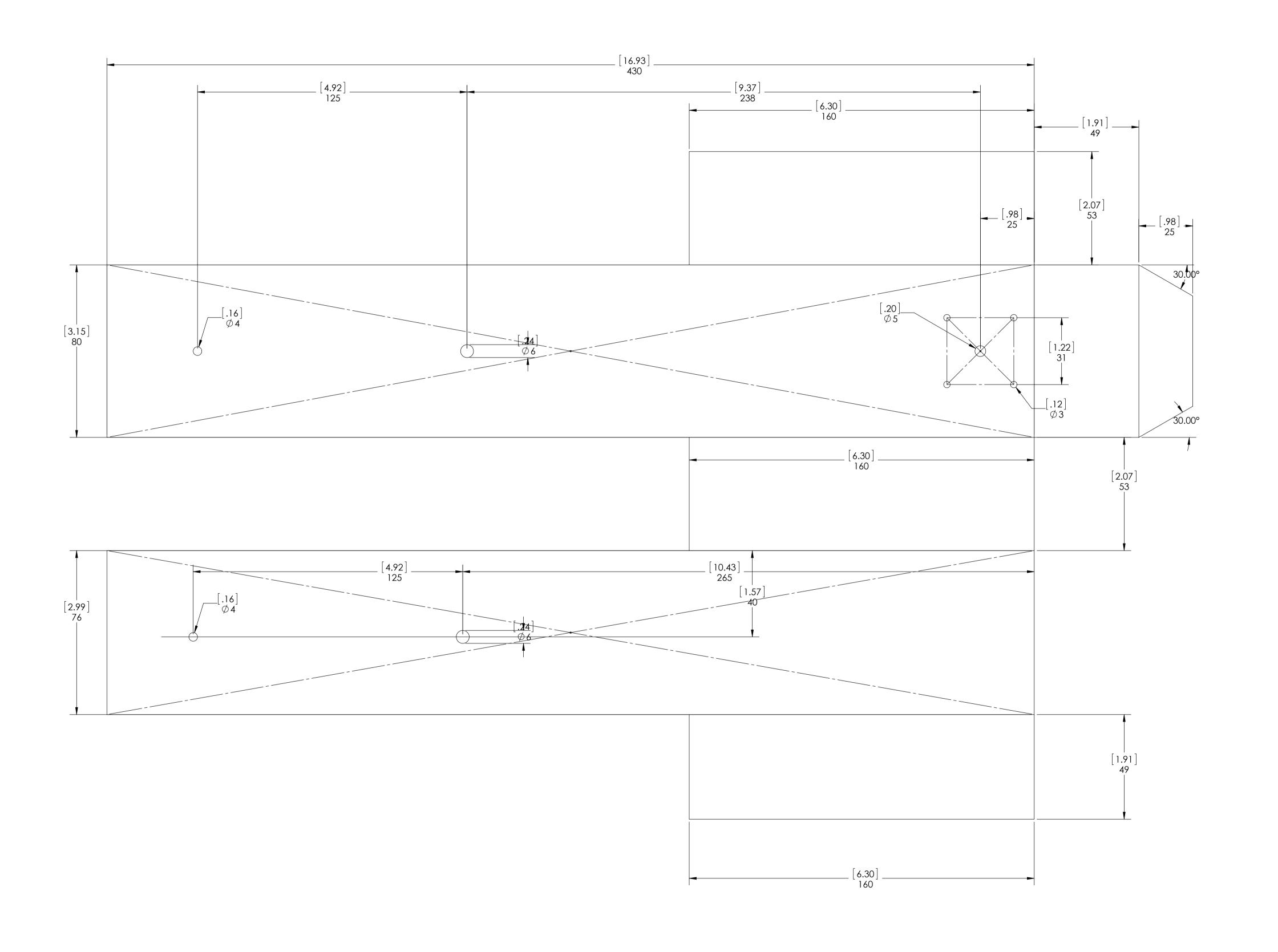




This is the arm to which the claw or camera mount is attached to.

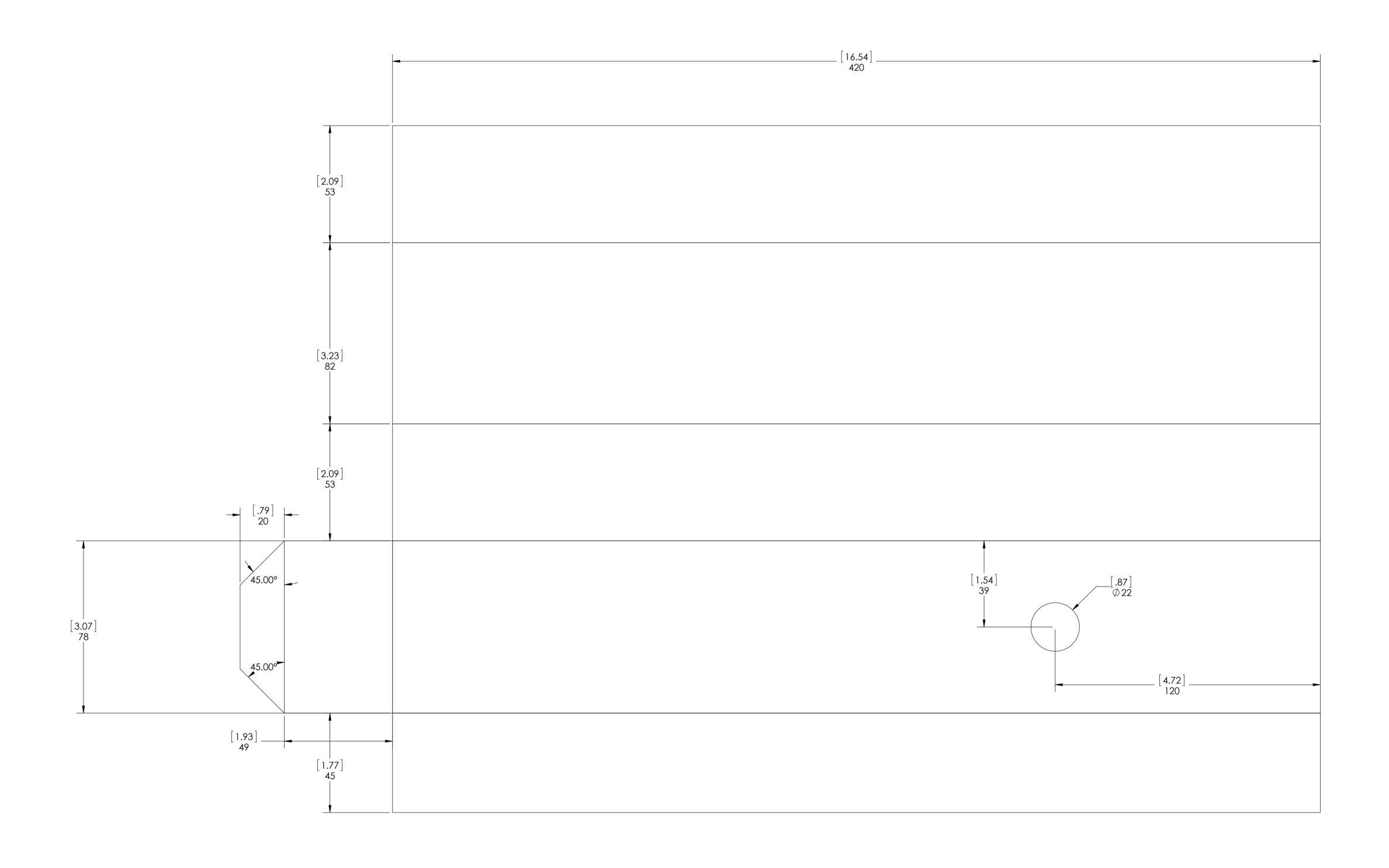


NAME SIGNATURE DATE DATE DATE TILE: DEANN CARD APPYD MIG MIG MIG MIG MIG MIG MIG MI	DRAWN CHCD APPVD MG MG MATERIAL:	DEBUR AND BREAK SHARP EDGES	DE FINISH:	UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN MILLIMET SURFACE FINISH: TOLERANCES: LINEAR: ANGULAR:	UN DI SI Tr											
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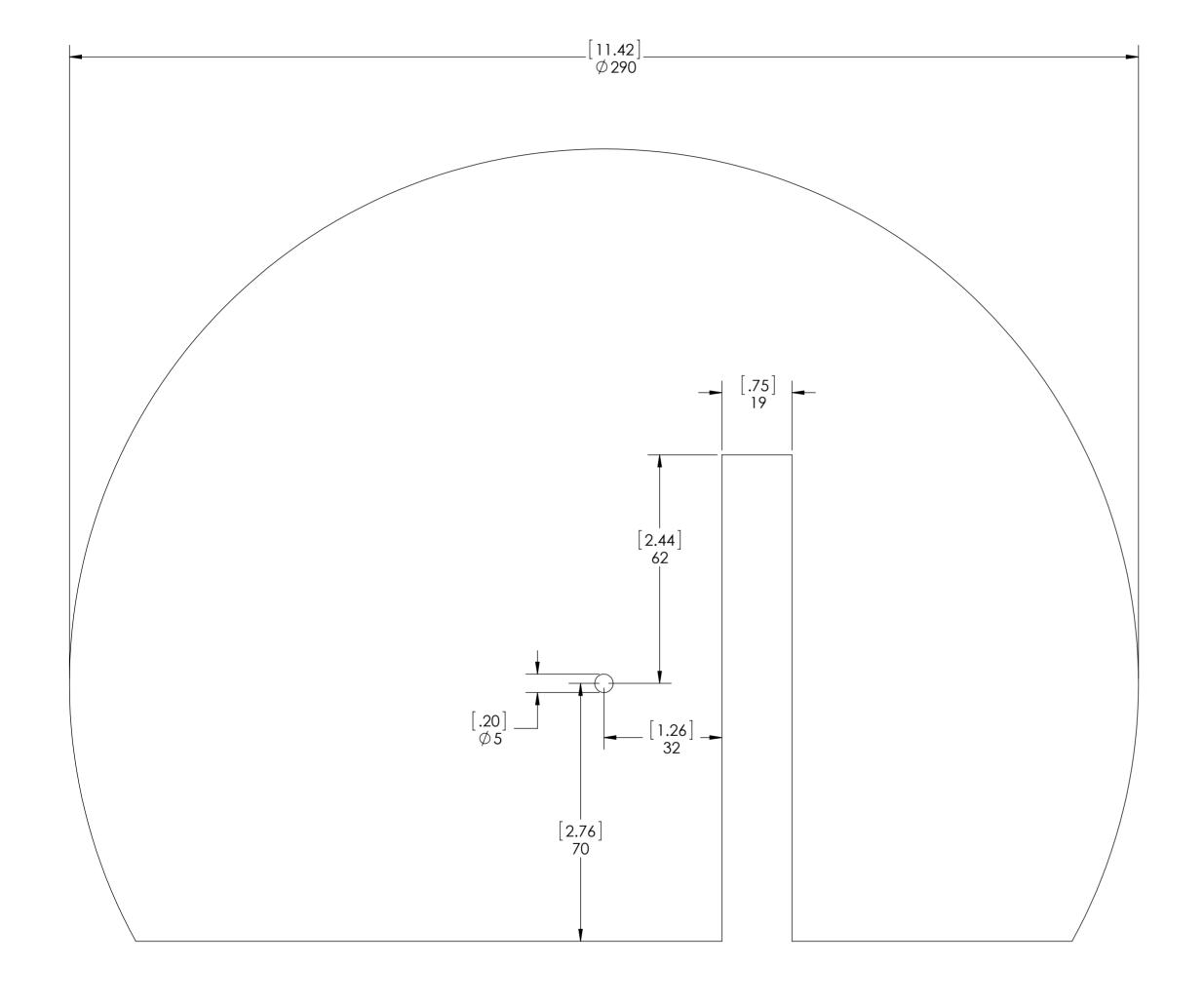
This is the counter-weight that attaches to the main arm on the same side as Motor 1. Add approximately 1 kg of pebbles or sand in a zip-lock bag. The counter-weight will help the robot pick up heavier loads.



DIMENS	UNLESS OTHERWISE SPECIFIED: DIMENSIONS ARE IN MILLIMETERS		ILLIMETERS					С	OO NOT SCALE DRAWING	REVISION	
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MFG											
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This semi-circle prevents motor from catching on tabs. No tabs are glued onto this semi-circle. Only one of these are needed. _[11.81] ∅300 [2.44] 62 _ [1.26] _**_** [2.76] 70 UNLESS OTHERWISE SPECIFIED:
DIMENSIONS ARE IN MILLIMETERS
SURFACE FINISH:
TOLERANCES:
LINEAR:
ANGULAR: DEBUR AND BREAK SHARP EDGES DO NOT SCALE DRAWING REVISION SIGNATURE DATE DRAWN CHK'D APPV'D SCALE:1:1 SHEET 8 OF 9

Need two of these semi-circles. Tabs are glued on to these. Slightly smaller than x1 semicircles. This is to give clearance for tabs.



UNLESS OTHERWISE SPECIFIED: DIMENSIONS ARE IN MILLIMETERS SURFACE FINISH: TOLERANCES: LINEAR: ANGULAR:		FINISH:				DEBUR AND BREAK SHARP	D	OO NOT SCALE DRAWING	REVISION	<u>'</u>	
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