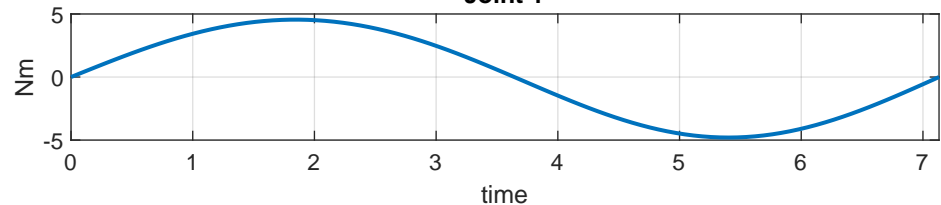
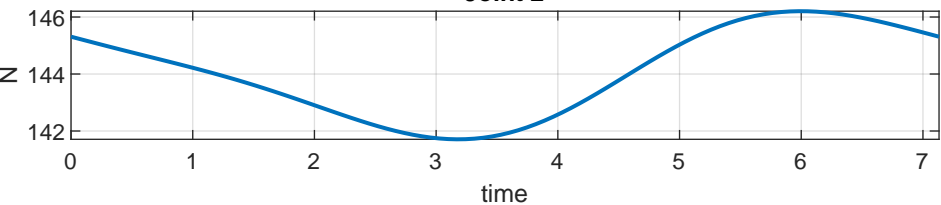


Actuator torques and forces from P1 to P2

Joint 1



Joint 2



Joint 3

