
VALUING AMERICAN OPTIONS IN A PATH SIMULATION MODEL

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ABSTRACT

The goal of this paper is to dispel the prevailing belief that American-style options cannot be valued efficiently in a simulation model, and thus remove what has been considered a major impediment to the use of a simulation models for valuing financial instruments. This is accomplished by presenting a general algorithm for estimating the value of American options on an underlying instrument or index for which the arbitrage-free probability distribution of paths through time can be simulated. The general algorithm is tested by means of an example for which the exact option premium can be determined.

1. INTRODUCTION

Mathematicians seem to resort to simulation models to analyze a problem only when all other methods fail to yield a solution. In the field of financial economics, evidence of this tendency to avoid simulation models is found in the proliferation of published binomial and multinomial lattice solutions (or their equivalent) to the problem of valuing instruments with cash flows or payoffs contingent on interest rates or stock prices, ((1), (2), (4), (5), (8), (9), (10), (12), (13), (14), (15), (16), (17), (18), (19), (20), (21), (22), and (23)). However, market makers who deal in today's complicated financial instruments and investors who buy and sell them are beginning to sense a need for more realistic multi-factor models of the stochastic dynamics of interest rates, foreign exchange rates, stock prices, and commodity prices. These more complex models demand analysis by means of simulation because constructing approximate solutions to their underlying nonlinear differential equations (and sometimes *mixed* differential-integral equations) is extremely difficult.

Generally, the use of simulation models to value financial instru-

ments has been restricted to assets that have path-dependent cash flows or payoffs - for example, mortgage-backed securities, including collateralized mortgage obligations (CMO_S), and esoteric derivative instruments such as "look-back" options ((7) and (11)). (An exception, at least in the academic literature, if not in practice, is the paper by Boyle (3) which examines how Monte Carlo simulation can be used to value European-style options.) Indeed, it has been felt that simulation models could not be used to value American-style options efficiently ((7) and (8)). Ideally, a broker-dealer would like to be able to use a *single* method to value its entire book and a financial intermediary would like to be able to use a *single* method to analyze its entire asset-liability condition. I believe that simulation models offer that possibility.

Simulation models consume large amounts of computer processing time and some problems have heretofore required too much execution time to be handled practically by means of simulation. However, the arrival of powerful workstations, servers, and parallel-processors has rendered simulation feasible in many situations where it previously was not, a condition that can only improve with time as the pace of major technological advances continues to accelerate. In many situations, a *single sample* of paths can be generated and then *used repeatedly* to value many different instruments - for example, a dealer's entire book of interest rate swaps, caps, floors, and swaptions, a dealer's entire book of stock index derivatives or of currency swaps and options, or a financial intermediary's entire portfolio of fixed-income securities. Simulation may not be the best method when each financial instrument must be valued on the basis of its own random sample of paths, but this situation can often be avoided by designing the simulation properly.

A little background on options is provided in Section 2. The algorithm for valuing American options is described in Section 3 and tested by means of an example in Section 4. The issue of bias in the estimator of the option premium is examined in Section 5, after which the example is revisited in Section 6. Finally, Section 7 summarizes the paper.

2. OPTIONS BACKGROUND

A textbook by Cox and Rubinstein (6) provides a comprehensive treatment of the subject of options. This section merely serves to define basic terms that are used throughout the paper. It is assumed that the reader is familiar with the general subject area, including various models for pricing options.

An option is an agreement between two parties in which one party, the seller, grants to the other party, the buyer, the right to buy (*call* option) or sell (*put* option) a specified amount of an asset at a specified price up to a specified date. The price at which the underlying asset may be bought (call option) or sold (put option) is referred to as the *exercise price* or *strike price* of the option. The last date on which the option may be exercised by its purchaser is known as the *expiration date*. The price that the option purchaser must pay to the option seller for his/her right to exercise the option is referred to as the option *premium*.

The value of an option consists of two components - intrinsic value and time value. *Intrinsic value* is the amount the option is worth if it is exercised immediately. For a call option, the intrinsic value is equal to the larger of (i) zero, and (ii) the market price of the underlying asset minus the strike price of the option. For a put option, the intrinsic value is equal to the larger of (i) zero, and (ii) the strike price of the option minus the market price of the underlying asset. *Time value* is the option premium minus the intrinsic value. An option is a "wasting" asset because its time value decays to zero as the date of expiration approaches. An option is said to be *in the money* if its intrinsic value is positive, *at the money* if its strike price is equal to the market price of the underlying asset, and *out of the money* otherwise.

An option is called *European* if its purchaser can exercise it only on the expiration date or *American* if its purchaser can exercise it on at least one date before the expiration date as well as on the expiration date. Strictly speaking, the only "optional" feature of a European option is that its purchaser is not forced to exercise the option if it is out of the money. However, an American option has true "optional" features because its purchaser has a *choice of dates* on which to exercise the option.

3. THE VALUATION ALGORITHM

For convenience the underlying asset will be referred to as a "stock", but the entire development in this section applies to any type of asset or index for which the arbitrage-free probability distribution of paths through time can be simulated. The paper by Tilley (24) discusses what is meant by "arbitrage free" and shows how arbitrage-free paths of interest rates can be sampled stochastically. The example in Section 4 of this paper utilizes paths of stock prices that are sampled from a probability distribution for which the mean has been adjusted to render

it arbitrage free.

We consider how to evaluate put and call options on a stock. The options are exercisable only at specified epochs t_1, t_2, \dots, t_N , which shall be indexed 1, 2, \dots , N for convenience. The origin of time is $t = 0$, which shall be indexed as epoch 0. The options can be considered to be first exercisable at epoch 0 or at epoch 1, as appropriate. A path of stock prices is a sequence $S(0), S(1), S(2), \dots, S(N)$, where the arguments of S refer to the epoch indexes at which the stock prices occur. All paths of stock prices emanate from the initial stock price $S(0)$. The simulation procedure involves the random generation of a finite sample of R such paths and the estimation of option prices from that sample. The k th path in the sample is represented by the sequence $S(0), S(k, 1), S(k, 2), \dots, S(k, N)$, where the first index refers to the path and the second index refers to the epoch index. Two paths of stock prices are represented in Figure 1. Let $d(k, t)$ be the present value at epoch t on path k of a \$ 1 payment occurring at epoch $t + 1$ on path k . Let $D(k, t)$ be the present value at epoch 0 of a \$ 1 payment occurring at epoch t on path k , computed by the product of the discount factors $d(k, s)$ from $s = 0$ to $s = t - 1$.

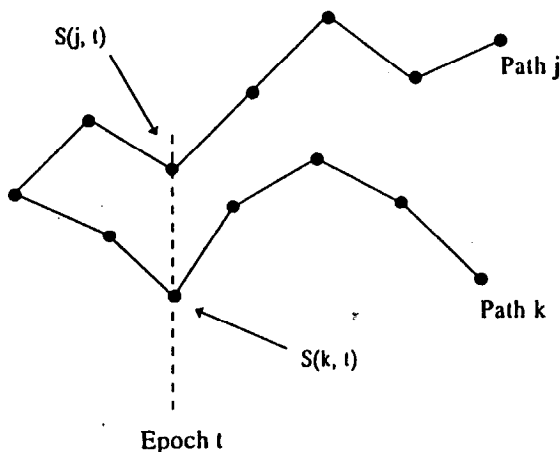


Fig. 1

Assume that the option has strike prices that can depend on the date of exercise but not on the stock price at the time of exercise. Let $X(1), X(2), \dots, X(N)$ denote the sequence of exercise prices at epochs 1, 2, \dots , N , respectively. Typical stock options have a constant strike price X independent of date of exercise, but typical call options in private placement bonds do not. The intrinsic value $I(k, t)$ of the

option on path k at epoch t can now be defined as:

$$I(k, t) = \begin{cases} \text{maximum} & [0, S(k, t) - X(t)] & \text{for a call option} \\ \text{maximum} & [0, X(t) - S(k, t)] & \text{for a put option.} \end{cases}$$

Finally, let $z(k, t)$ be the “exercise or hold” indicator variable which takes the value 0 if the option is not exercised at epoch t on path k and which takes the value 1 if the option is exercised at epoch t on path k . Clearly, either $z(k, t) = 0$ at all epochs t along path k or $z(k, t_*) = 1$ at one and only one epoch t_* along path k . If such a t_* exists, it is the date at which the option is exercised on path k .

The price of any asset is known at epoch 0 if its cash flows are known at all epochs along all possible paths. That price is calculated in two steps: first, compute for each path k the present value at epoch 0 of the asset's cash flows along that path using the path-specific discount factors $D(k, t)$, and second, average across all paths the present values computed in the first step. It is essential that the paths be drawn from the appropriate arbitrage-free distribution. More details on this general valuation procedure can be found in the paper by Tilley (24). On a given stock price path, the “cash flow” for an option is zero at every epoch other than the one at which the option is exercised. At exercise, the option's “cash flow” is equal to its payoff, which is its intrinsic value. Assuming the usual situation that all randomly sampled stock price paths are equally likely with probability weight R^{-1} , we can express the option premium estimator by the following equation:

$$\text{Premium Estimator} = R^{-1} \sum_{\substack{\text{all} \\ \text{paths} \\ k}} \sum_{\substack{\text{all} \\ \text{epochs} \\ t}} z(k, t) D(k, t) I(k, t).$$

Thus, to estimate the price of the option, we need to estimate the exercise-or-hold indicator function $z(k, t)$, given a finite sample of R paths drawn from an arbitrage-free distribution of paths. The algorithm presented in this section for estimating $z(k, t)$ mimics the standard backward induction algorithm implemented on a connected lattice for estimating the value of an American option. A discussion of this standard technique can be found in the textbook by Cox and Rubinstein (6). The latest epoch at which the option can be exercised is its expiration date. On that date, represented by epoch N , $z(k, N) = 1$ if and only if $I(k, N) > 0$. The general step that is performed at epoch t in the backward induction algorithm includes eight substeps, which are described as follows:

1. Reorder the stock price paths by stock price, from lowest price to highest price for a call option or from highest price to lowest price for a put option. Reindex the paths from 1 to R according to the reordering.
2. For each path k , compute the intrinsic value $I(k, t)$ of the option.
3. Partition the set of R ordered paths into Q distinct bundles of P paths each. Assign the first P paths to the first bundle, the second P paths to the second bundle, and so on, and finally the last P paths to the Q th bundle. It is assumed that P and Q are integer factors of R .
4. For each path k , the option's "holding value" $H(k, t)$ is computed as the following mathematical expectation taken over all paths in the bundle containing the path k :

$$H(k, t) = d(k, t) P^{-1} \sum_{\substack{\text{all } j \\ \text{in bundle} \\ \text{containing } k}} V(j, t+1).$$

The variable $V(k, t)$ is fully defined in substep 8 below. At epoch N , $V(k, N) = I(k, N)$ for all k .

5. For each path, compare the holding value $H(k, t)$ to the intrinsic value $I(k, t)$ and decide "tentatively" whether to exercise or hold. Define an indicator variable $x(k, t)$ as follows:

$$x(k, t) = \begin{cases} 1 & \text{if } I(k, t) > H(k, t) & \text{Exercise} \\ 0 & \text{if } H(k, t) \geq I(k, t) & \text{Hold.} \end{cases}$$

6. Examine the sequence of 0's and 1's $\{x(k, t); k = 1, 2, \dots, R\}$. Determine a "sharp" boundary between the hold decision and the exercise decision as the start of the first string of 1's the length of which exceeds the length of every subsequent string of 0's. Let $k_*(t)$ denote the path index (in the sample as *ordered* in substep 1 above) of the leading 1 in such a string. The "transition zone" between *hold* and *exercise* is defined as the sequence of 0's and 1's that begins with the first 1 and ends with the last 0. An example is given below:

Boundary
 \downarrow
 0 0 ... 0 1 1 0 0 0 1 1 1 1 1 0 0 ... 1 1

7. Define a new exercise or hold indicator variable $y(k, t)$ that incorporates the sharp boundary as follows:

$$y(k, t) = \begin{cases} 1 & \text{for } k \geq k_*(t) \\ 0 & \text{for } k < k_*(t). \end{cases}$$

8. For each path k , define the current value $V(k, t)$ of the option as follows:

$$V(k, t) = \begin{cases} I(k, t) & \text{if } y(k, t) = 1 \\ H(k, t) & \text{if } y(k, t) = 0. \end{cases}$$

After the algorithm has been processed backward from epoch N to epoch 1 (or epoch 0 if immediate exercise is permitted), the indicator variable $z(k, t)$ for $t < N$ is estimated as follows:

$$z(k, t) = \begin{cases} 1 & \text{if } y(k, t) = 1 \text{ and } y(k, s) = 0 \text{ for all } s < t \\ 0 & \text{otherwise.} \end{cases}$$

This completes the description of the algorithm for valuing an American option.

It is useful to characterize the partition of R paths into Q bundles of P paths each by defining a “bundling parameter” α by means of the equation $Q = R^\alpha$, and therefore, $P = R^{1-\alpha}$. It is clear that $0 \leq \alpha \leq 1$. The value $\alpha = 0$ corresponds to the partition into a single bundle of R paths, and the value $\alpha = 1$ corresponds to the partition into R bundles of one path each. A particular American option valuation algorithm can now be fully described by the sample size R , the technique used to sample paths, and the bundling parameter α . If α is restricted to rational numbers, we can fix α and take sensible limits as $R \rightarrow \infty$ to investigate the convergence properties of the option premium estimator. For example, with $\alpha = 2/5$, we can examine sample sizes equal to $2^5, 3^5, 4^5, \dots$ paths for which we can study the estimators associated with the partitions $Q = 2^2, 3^2, 4^2, \dots$ bundles and $P = 2^3, 3^3, 4^3, \dots$ paths per bundle, respectively.

For any exercise hold decision algorithm with α fixed and $0 < \alpha < 1$, it can be proved that the option premium estimate must converge to the proper result as $R \rightarrow \infty$. This follows from the observation that the algorithm for determining the exercise hold decision variable is based on the standard backward induction algorithm for valuing American options and that all sources of error arise from P , Q , and R being finite. For finite R , imprecision in the premium estimates arises because (1) the

continuous distribution of stock prices at each epoch is not sampled sufficiently finely, and (2) the mathematical expectation in substep 4 above is approximated by an average over a finite number of paths. Imprecision of the first type can be reduced by increasing Q , the number of bundles. Imprecision of the second type can be reduced by increasing P , the number of paths per bundle. For fixed R , increasing Q means decreasing P , and vice versa, implying a tradeoff between the first and second types of imprecision. However, if α is held constant at some value in the interval $(0,1)$, then both types of imprecision are eliminated simultaneously as $R \rightarrow \infty$, because then *both* $Q \rightarrow \infty$ and $P \rightarrow \infty$.

The distinction between the variables $y(k,t)$ and $x(k,t)$ disappears as $R \rightarrow \infty$ and α is held constant at a value other than zero or one. As $R \rightarrow \infty$, the boundary between a decision to exercise the option and a decision to hold the option becomes sharper and sharper - that is, at each epoch, the transition zone with alternating strings of 1's and 0's occurs over a smaller and smaller interval of stock prices. Defining a sharp boundary by means of substep 6 above generally improves the convergence of the algorithm considerably for any α in the interval $(0,1)$ and also generally broadens considerably the interval of α over which the option premium estimates are good. Generally, the option premium estimate based on a given sample size, sampling technique, and bundling parameter is more accurate when a sharp exercise hold boundary is determined than when it is not. However, the *ultimate* convergence of the exercise hold decision algorithm to the exact option premium does *not* depend at all on whether substep 6 above is implemented - that is, whether a distinction is drawn between $y(k,t)$ and $x(k,t)$ or whether $y(k,t) \equiv x(k,t)$ for all k and t .

4. AN EXAMPLE

To test the algorithm presented in the preceding section, we consider the situation of a non-dividend-paying stock. Let $S(t)$ denote the price of the stock at time t . We assume that the random variable $\ln[S(t)/S(0)]$ is normally distributed with mean μt and variance $\sigma^2 t$. We further assume that the yield curve is flat and that interest rates are constant over time at an annual effective rate r . In order for the distribution of stock price movements to be arbitrage free over time, it must be true that $\mu = \ln[1+r] - \sigma^2/2$. Refer to the textbook by Cox and Rubinstein (6) for a proof of this statement.

When a non-dividend-paying stock is the underlying asset, the price

of an American call option must be exactly the same as the price of an otherwise identical European call option (6). The price of an American put option must be no less than the price of an otherwise identical European put option, but the former will in general exceed the latter (6). Therefore, we test the valuation algorithm on a *put option* that is first exercisable in one quarter of a year and is exercisable every quarter of a year thereafter until its expiration in three years. The stock price has logarithmic volatility σ equal to 30%. The initial price of the stock $S(0)$ is 40, the strike price X of the option is 45 at all epochs, and the annual effective interest rate r is 7%. Paths of stock price movements are generated randomly by stratified sampling of the standard normal density as described in Tilley (24). Random samples of size $7!=5,040$ are used so that many different partitions can be examined.

Table 1 - Bundling parameter alpha for various partitions of 5,040 paths

PARTITION			PARTITION		
Number of Bundles	Paths per Bundle	Bundling parameter Alpha	Number of Bundles	Paths per Bundle	Bundling parameter Alpha
1	5040	.00000	72	70	.50165
2	2520	.00131	80	63	.51401
3	1600	.12887	84	60	.51973
4	1260	.16261	90	56	.52783
5	1000	.18879	105	48	.54591
6	840	.21017	112	45	.55348
7	720	.22825	120	42	.56157
8	630	.24392	126	40	.56730
9	560	.25773	140	36	.57965
10	504	.27009	144	35	.58296
12	420	.29148	168	30	.60104
14	360	.30956	180	28	.60913
15	336	.31765	210	24	.62721
16	315	.32522	240	21	.64288
18	280	.33904	252	20	.64860
20	252	.35140	280	18	.66096
21	240	.35712	315	16	.67478
24	210	.37279	336	15	.68235
28	180	.39087	360	14	.69044
30	168	.39896	420	12	.70852
35	144	.41704	504	10	.72991
36	140	.42035	560	9	.74227
40	126	.43270	630	8	.75608
42	120	.43843	720	7	.77175
45	112	.44652	840	6	.78983
48	105	.45409	1800	5	.81121
56	90	.47217	1260	4	.83739
60	84	.48027	1680	3	.87113
63	80	.48599	2520	2	.91869
70	72	.49835	5040	1	1.00000

Table 1 lists the values of the bundling parameter α that correspond to each of the 60 different partitions of 5,040 paths into equal-sized bundles.

The exact price of the three-year American put option with quarterly exercise intervals was determined to be 7.941 by using a binomial lattice with 1,200 time periods constructed according to the procedure described in Cox and Rubinstein (6). This is approximately 1.61 higher than the price of the corresponding three-year European put option. Using a *single* sample of 5,040 paths, the exercise-decision algorithm described in the preceding section was tested for all partitions having at least 12 bundles but no more than 420 bundles. The result are displayed in Figure 2.

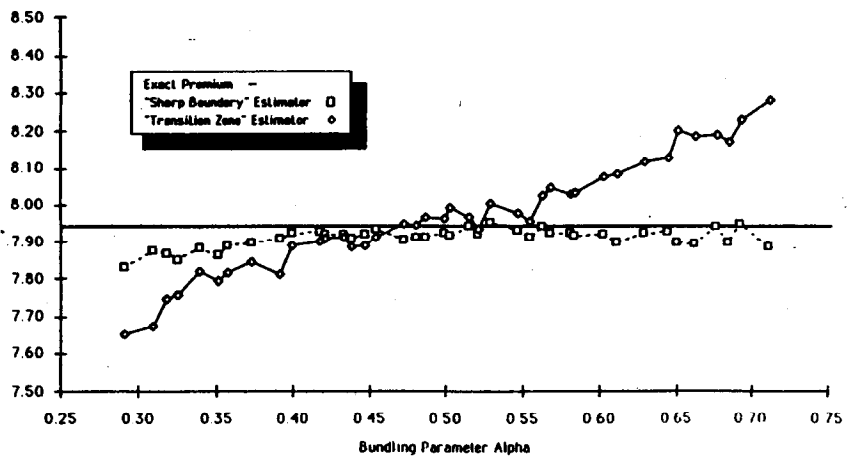


Fig. 2 Premium Estimates for 3-year American Put Option (5,040 Paths Partitioned 40 Ways into Exercise-Decision Bundles)

In Figure 2, the graph depicted as a solid line connecting "diamonds" corresponds to application of the algorithm without substep 6 - that is, with a *transition zone* from hold to exercise, not a sharp boundary between hold and exercise. The graph depicted as a broken line connecting "squares" corresponds to application of the algorithm with step 6 included - that is, with a *sharp boundary* between hold and exercise. The horizontal line across the graph at a vertical axis value of 7.941 marks the exact option premium. Figure 2 clearly demonstrates the importance of including substep 6 in the algorithm. When a sharp boundary is determined, the option premium estimates are essentially flat across an interval from $\alpha = 0.29$ to $\alpha = 0.71$ and cover a range of only 12 cents. However, when only a transition zone is utilized, the

option premium estimates rise more or less steadily as the bundling parameter is increased and cover a range of approximately 63 cents, more than five times the range obtained when a sharp boundary is utilized!

To study the efficiency of estimation, the “70 bundles by 72 paths per bundle” partition was used on 1,000 independent samples of 5,040 paths each. Each sample gives rise to an estimate of the put option premium. The frequency histogram of these 1,000 estimates is plotted in Figure 3. The inset box indicates that the mean of the estimates is 7.971 and the standard deviation of the estimates is 0.053. The solid line graph superimposed on the frequency histogram is that of a normal density function with the same mean and standard deviation as the option premium estimator. By eye alone, one can see that the algorithm produces premium estimates that are normally distributed. What seems surprising is that the premium estimator is *biased*. The mean estimate of 7.971 is 3 cents higher than the exact premium of 7.941, which is about 17.9 times the standard deviation of $5.3/\sqrt{1000}$ cents. Despite the bias, it is evident that the algorithm is able to estimate the option premium quite tightly.

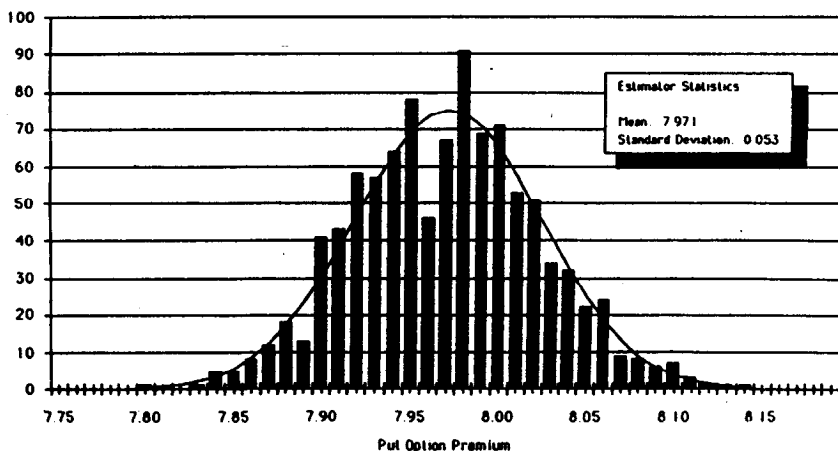


Fig. 3 Frequency Histogram for “alpha= 0.50” Premium Estimator (Based on 1,000 Samples Of 5,040 Paths Each)

5. ESTIMATOR BIAS

In this section, we investigate the source of the bias in the option premium estimates that was discovered by means of the example presented in the last section. It turns out that the bias arises because

the “optimization” is done over a *finite* sample. The bias vanishes in the limit of infinite sample size. The description of the exercise-decision algorithm in Section 3 makes it evident that estimating the premium for an American option is equivalent to estimating the exercise hold stock price boundary at each epoch at which the option can be exercised. Accordingly, we determined the “exact” boundary between holding and exercising the put option at each of the 12 exercise-decision epochs by using the Cox-Rubinstein binomial lattice that was described in the preceding section. With *full knowledge* of the exact exercise hold boundaries, the American option premium was estimated again by simulation using the *same 1,000 samples* of 5,040 paths on which the results shown in Figure 3 were based. The resulting frequency histogram of the premium estimates is shown in Figure 4.

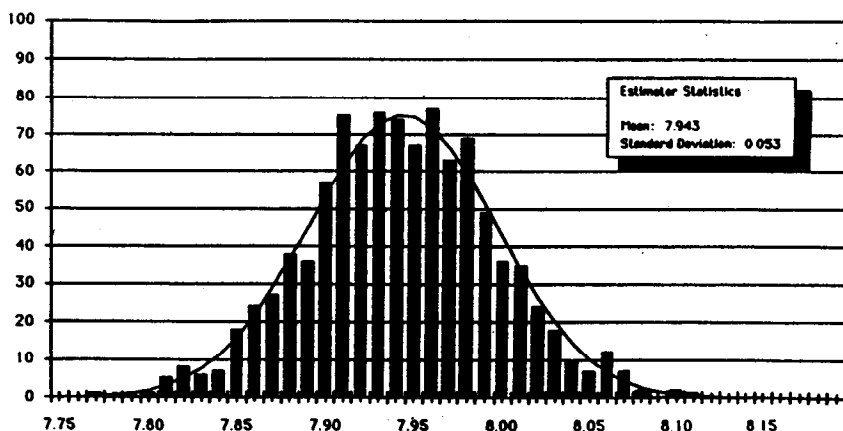


Fig. 4 Frequency Histogram for “Best” Premium Estimator (Based on 1,000 Samples Of 5,040 Paths Each)

It is seen from Figure 4 that the premium estimates are normally distributed. The standard deviation of the estimates is 5.3 cents, the same as Figure 3. However, the mean of the estimates is 7.943, only 0.2 cents higher than the exact premium. This deviation is not statistically significant at a 5% level of confidence since it is only about 1.2 times the standard deviation of $5.3/\sqrt{1000}$ cents. Thus, with full knowledge of the exact exercise-decision boundaries, the American option premium estimator is unbiased, even for finite samples of paths. We must conclude that the process of estimating the exercise hold boundaries from a finite sample of paths introduces the bias. The following analysis demonstrates the truth of this assertion.

The exact price of an American option is the value given by the premium estimator equation in Section 3 when the *infinite sample space* of stock price paths and the *exact exercise hold boundaries* are used. Determining the exact price of the option is equivalent to finding the exercise hold boundaries at all exercise-decision epochs that maximize the value given by the premium estimator equation when the infinite sample space of stock price paths is used. An approximation to the exact price is obtained by finding the exercise hold boundaries at all exercise-decision epochs that maximize the value given by the premium estimator equation when a *finite sample* of R stock price paths is used. A different approximation to the exact price is obtained by implementing the backward induction algorithm with eight substeps at each epoch that was described in Section 3. This latter estimate of the exact option price is itself an approximation to the former estimate of the exact option price, by reason of the construction of the backward induction algorithm as an optimization.

Let E_i denote the option premium estimate obtained when the i th sample of R paths is used together with some premium estimation method. The dependence of the estimate on the estimation method used is denoted by an appropriate superscript. The superscript “ ∞ -optimal” is used to represent the estimation method that utilizes the exact boundaries determined from the finite sample space of stock price paths. The superscript “ R -optimal” is used to represent the estimation method that utilizes the boundaries which optimize the value given by the premium estimator equation when the finite sample of R paths is used. Finally, the superscript “ R -algorithm” is used to represent the estimation method that utilizes the boundaries determined from the eight substep backward induction algorithm applied to the finite sample of R paths. As a consequence of the definitions of the various types of estimate and the construction of the different estimation methods, the following inequalities hold for *any* sample i consisting of R paths:

$$E_i^{\infty\text{-optimal}} \leq E_i^{R\text{-optimal}} \quad \text{and} \quad E_i^{R\text{-algorithm}} \leq E_i^{R\text{-optimal}}.$$

Thus, the means of the various estimators computed over any finite number of samples of R paths each also satisfy the same inequalities. In practice, the strict inequality will hold “almost surely”. When the sample size is infinite, the inequalities become equalities. Because the “ ∞ -optimal” estimator is unbiased, the first inequality demonstrates that the “ R -optimal” estimator must always have positive bias. The bias tends to zero as $R \rightarrow \infty$. Furthermore, the second inequality

demonstrates that the " R -optimal" estimator must be positively biased relative to the " R -algorithm" estimator. The relative bias tends to zero as $R \rightarrow \infty$. It is indeterminable whether the " R -algorithm" estimator has positive or negative bias with respect to the " ∞ -optimal" estimator. The two inequalities also show that one should not try too hard to "perfect" the " R -algorithm" estimator in the sense of making it better than the " R -optimal" estimator, because the latter always has positive bias relative to the unbiased " ∞ -optimal" estimator.

6. EXAMPLE REVISITED

Now that we understand that the sign of the bias of the R -algorithm estimator is indeterminable, but is likely to be positive if the R -algorithm estimates the R -optimal exercise-hold decision boundaries closely, we should conduct further empirical studies of the bias.

Table 2 - Statistics for 'Alpha = 0.50' estimators of premiums for American put options

Stock Price: 40 Option Expiration: 3.00 years Exercise Interval: 0.25 years				
Stock Volatility: 30 percent Annual Interest Rate: 7 percent				
Strike Price	'Exact' Premium ⁽¹⁾	Estimator Mean ⁽²⁾	Estimator Bias	Estimator Standard Deviation ⁽²⁾
10	.003	.003	.000	.001
15	.046	.046	.000	.005
20	.242	.239	-.003	.012
25	.744	.744	.000	.020
30	1.689	1.694	.005	.027
35	3.172	3.185	.013	.038
40	5.247	5.268	.021	.044
45	7.941	7.968	.027	.055
50	11.255	11.289	.034	.063
55	15.136	15.161	.025	.059
60	19.469	19.485	.016	.054
65	24.100	24.109	.009	.044
70	28.894	28.899	.005	.034
75	33.764	33.763	-.001	.028
80	38.665	38.662	-.003	.024
85	43.576	43.574	-.002	.017
90	48.491	48.486	-.005	.015
95	53.407	53.400	-.007	.014
100	58.323	58.316	-.007	.012

(1) Calculated using the Cox-Rubinstein binomial model with 1200 time intervals

(2) Calculated using a simulation model with 100 samples of 5,040 paths and exercise boundary determined by first dominant string of 1's in the transition zone

Table 2 presents results obtained by using the *R*-algorithm estimator of Section 3 on 100 independent samples of 5,040 paths each using a partition of 70 bundles by 72 paths per bundle. Results are shown for three-year American put option with strike prices ranging from 10 to 100 in multiples of five. All other assumptions are the same as in the earlier example. The "exact" premiums were calculated as before, using the Cox-Rubinstein binomial lattice with 1,200 time intervals. The estimator bias ranges from a low of -0.7 cents to a high of +3.4 cents. The standard deviations of the estimates peak at 6.3 cents for a put option somewhat in the money. The premium estimates must be considered very accurate.

Table 3 - Statistics for 'Alpha = 0.73' estimators of premiums for American put options

Stock Price: 40 Option Expiration: 3.00 years Exercise Interval: 0.25 years Stock Volatility: 30 percent Annual Interest Rate: 7 percent 				
Strike Price	'Exact' Premium (1)	Estimator Mean (2)	Estimator Bias	Estimator Standard Deviation(2)
10	.003	.003	.000	.001
15	.046	.048	.002	.005
20	.242	.246	.004	.012
25	.744	.750	.006	.018
30	1.689	1.697	.008	.028
35	3.172	3.178	.006	.039
40	5.247	5.255	.008	.049
45	7.941	7.943	.002	.052
50	11.255	11.260	.005	.066
55	15.136	15.139	.003	.059
60	19.469	19.468	-.001	.058
65	24.100	24.094	-.006	.049
70	28.894	28.889	-.005	.037
75	33.764	33.752	-.012	.034
80	38.665	38.654	-.011	.032
85	43.576	43.566	-.010	.021
90	48.491	48.480	-.011	.021
95	53.407	53.398	-.009	.020
100	58.323	58.315	-.008	.016

(1) Calculated using the Cox-Rubinstein binomial model with 1200 time intervals

(2) Calculated using a simulation model with 100 samples of 5,040 paths and exercise boundary determined by first dominant string of both 0's and 1's in the transition zone

Table 3 presents results similar to those in Table 2, but applying to a partition of 504 bundles by 10 paths per bundle. In this case, substep 6 of the exercise-decision algorithm was refined to account not

only for the first dominant string of 1's in the transition zone but also the last dominant string of 0's in the transition zone. As in substep 6, a boundary index is determined as the start of the first string of 1's the length of which exceeds the length of every subsequent string of 0's. Another boundary index is determined as the end of the last string of 0's the length of which exceeds the length of every previous string of 1's. In many cases, the two boundaries are identical, but if not, the "dominant 0-string" boundary must occur before the "dominant 1-string" boundary. The boundary index actually used in the revised algorithm is the arithmetic mean of the two boundary indexes, rounded appropriately. The estimator bias shown in Table 3 ranges from a low of -1.2 cents to a high of +0.8 cents. The standard deviations of the estimates are generally a little higher than their counterparts in Table 2.

Table 4 - Statistics for 'Alpha = 0.73' estimators of premiums for American put options

Stock Price: 40 Option Expiration: 3.00 years Exercise Interval: 0.25 years				
Stock Volatility: 60 percent Annual Interest Rate: 7 percent				
Strike Price	'Exact' Premium (1)	Estimator Mean (2)	Estimator Bias	Estimator Standard Deviation(2)
10	.486	.489	.003	.013
15	1.409	1.414	.005	.022
20	2.810	2.815	.005	.034
25	4.636	4.643	.007	.044
30	6.834	6.840	.006	.054
35	9.357	9.367	.010	.064
40	12.162	12.180	.018	.075
45	15.220	15.240	.020	.088
50	18.504	18.526	.022	.102
55	21.986	22.009	.023	.120
60	25.650	25.667	.017	.118
65	29.475	29.493	.018	.131
70	33.453	33.477	.024	.129
75	37.566	37.584	.018	.148
80	41.798	41.809	.011	.145
85	46.137	46.139	.002	.149
90	50.571	50.567	-.004	.149
95	55.086	55.078	-.008	.144
100	59.670	59.662	-.008	.144

(1) Calculated using the Cox-Rubinstein binomial model with 1200 time intervals

(2) Calculated using a simulation model with 100 samples of 5,040 paths and exercise boundary determined by first dominant string of both 0's and 1's in the transition zone

Table 4 presents results similar in those in Table 3, except that the stock price volatility has been doubled to 60%. Again, the estimator

biases are small, ranging from -0.8 cents to +2.4 cents. The standard deviations of the estimates are much larger, but are still very small when expressed as a percentage of the exact premiums.

7. SUMMARY AND CONCLUSIONS

This paper has presented an algorithm for valuing American options in a path simulation model and has demonstrated its accuracy by means of an example involving a put option on a non-dividend-paying stock for which the exact premium could be determined. The demonstration of the existence of a useful algorithm for valuing American options in a path simulation model should remove what has been perceived as a major impediment to the use of simulation models in valuing a broker-dealer's derivatives book and to the use of such models in analyzing the asset-liability condition of financial intermediaries.

This paper has not dealt with complexities that arise in determining exercise hold decision boundaries when multi-factor stochastic models of asset price behaviour are utilized. Empirical studies that I have conducted suggest that little modification to the algorithm presented in this paper is required to handle those situations satisfactorily, but more thorough research in this area needs to be performed and reported.

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