

COMP 250

Lecture 19

(rooted) trees

Oct. 23, 2017

Linear Data Structures

linked list

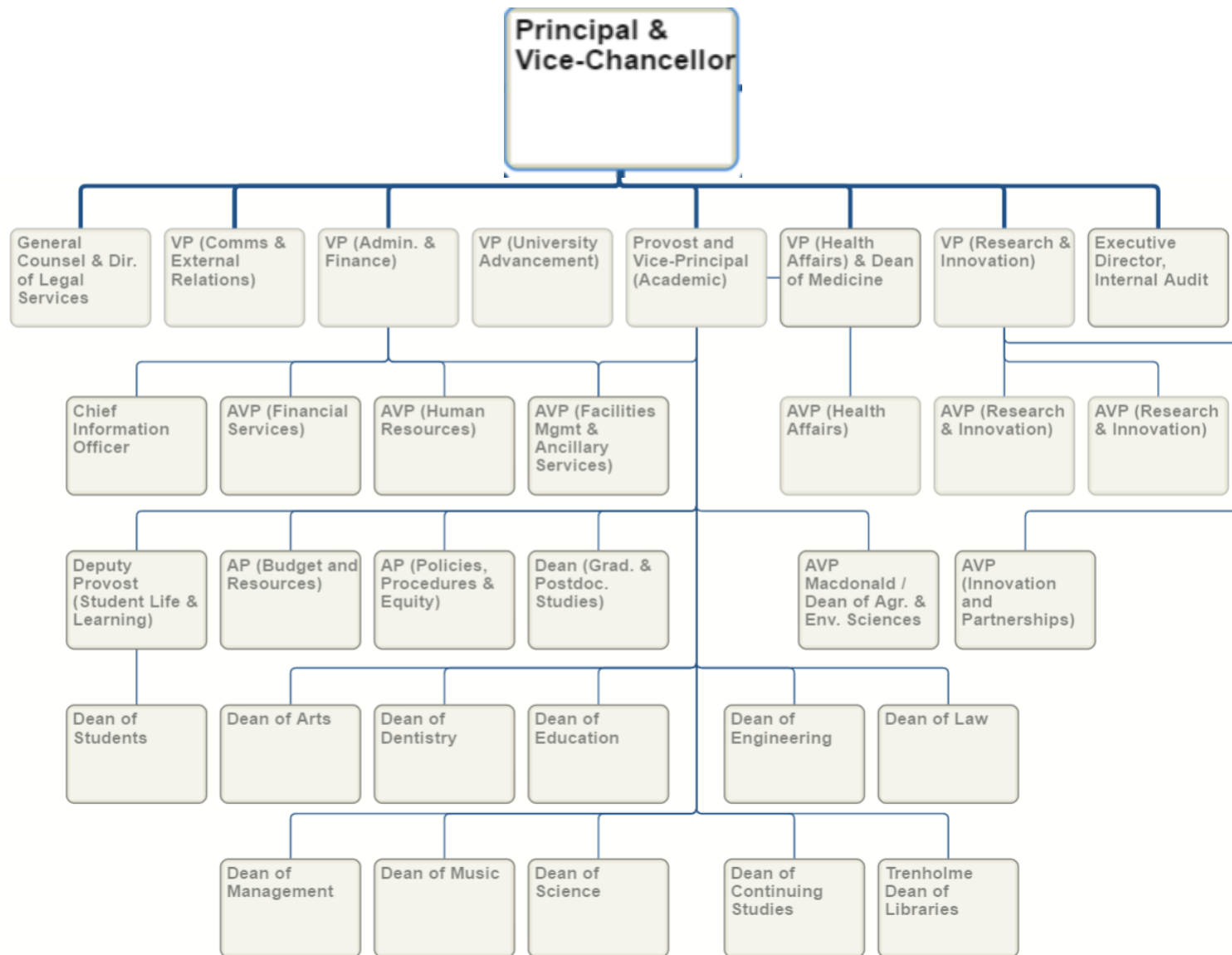
array

Non-Linear Data Structures

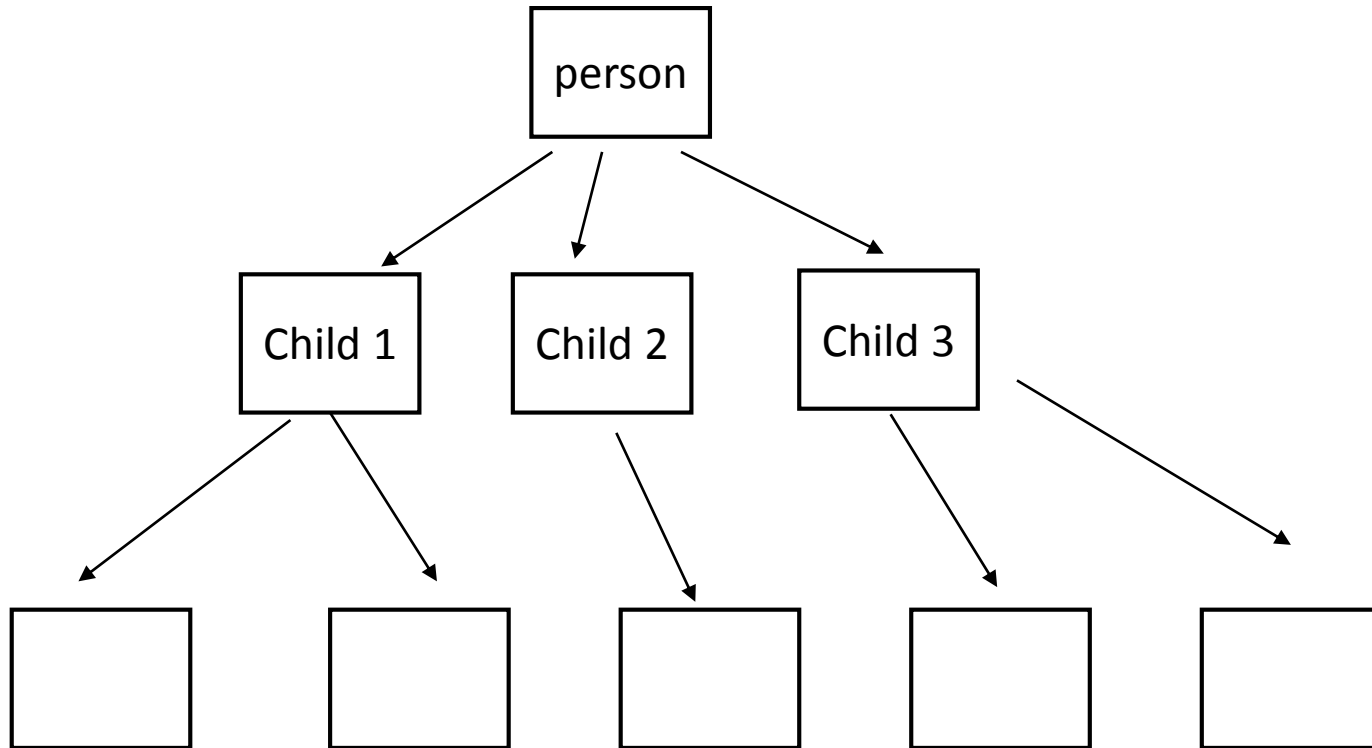
tree

graph

Tree Example: Organization Hierarchy (McGill)

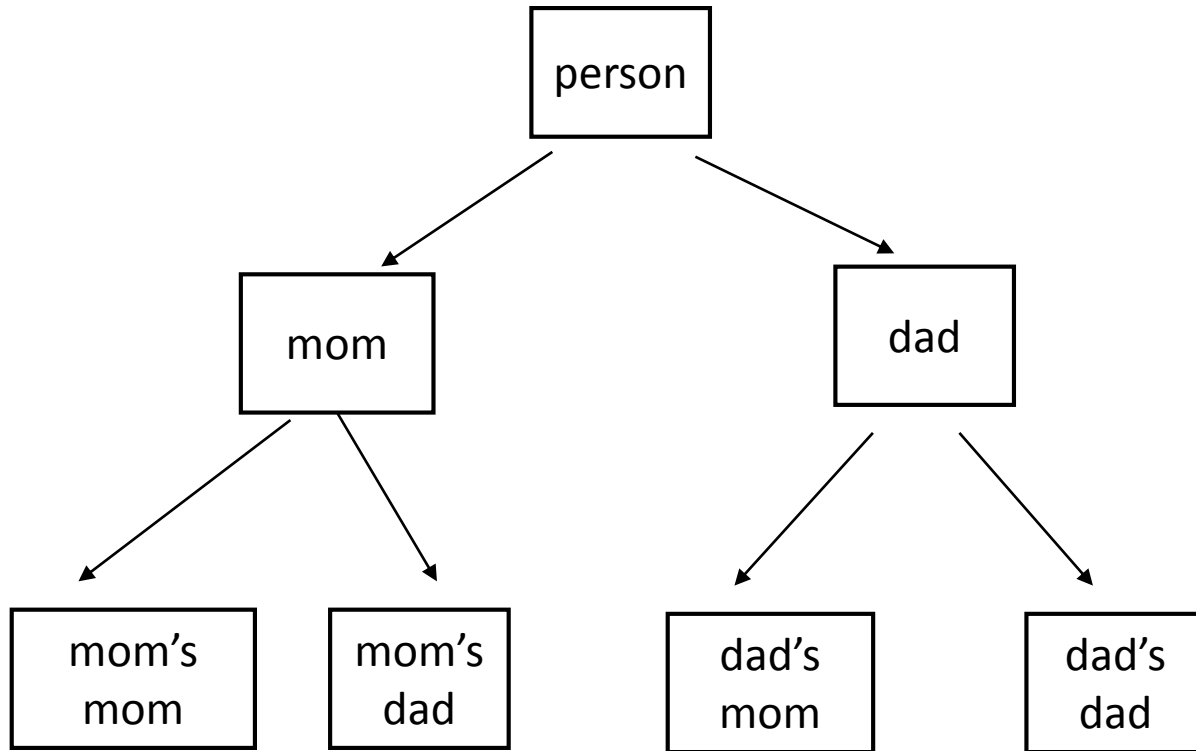


Family Tree (descendents)



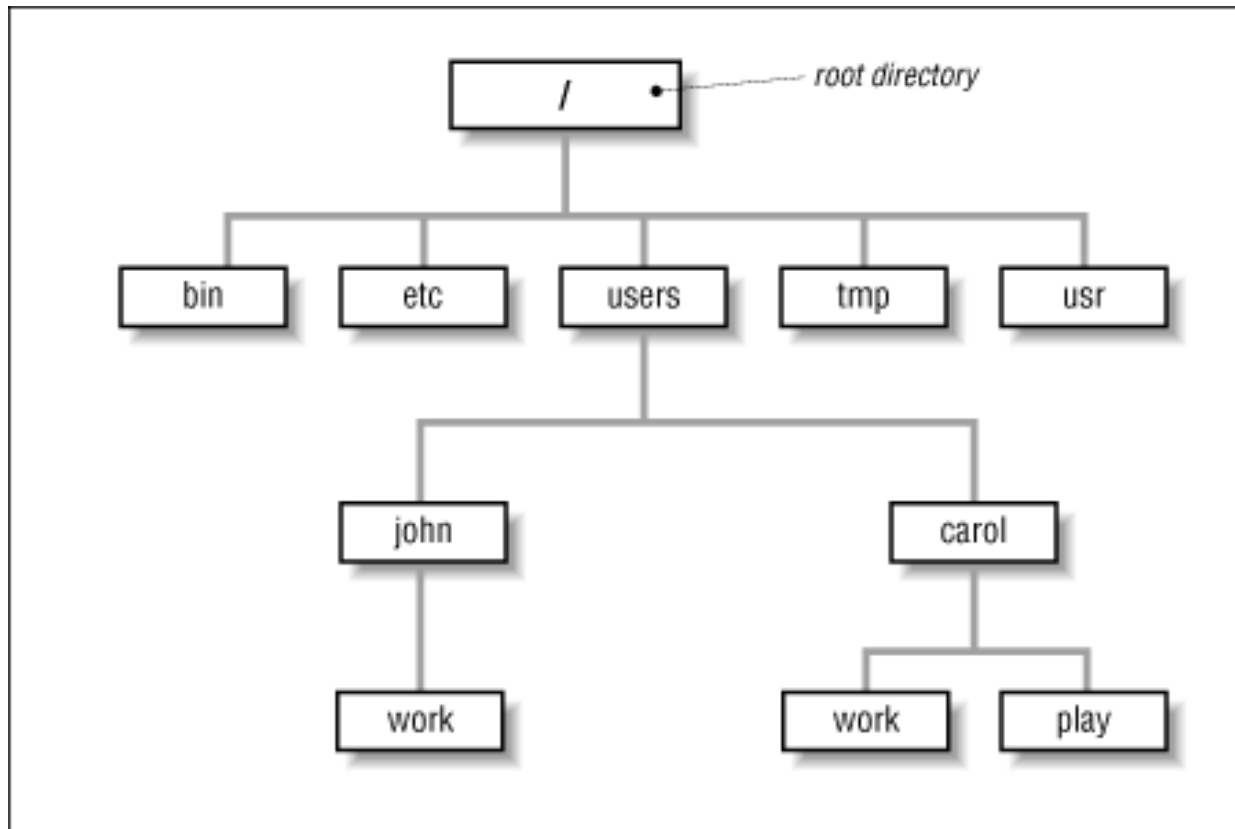
Here I ignore spouses (partner).

Family Tree (ancestors)

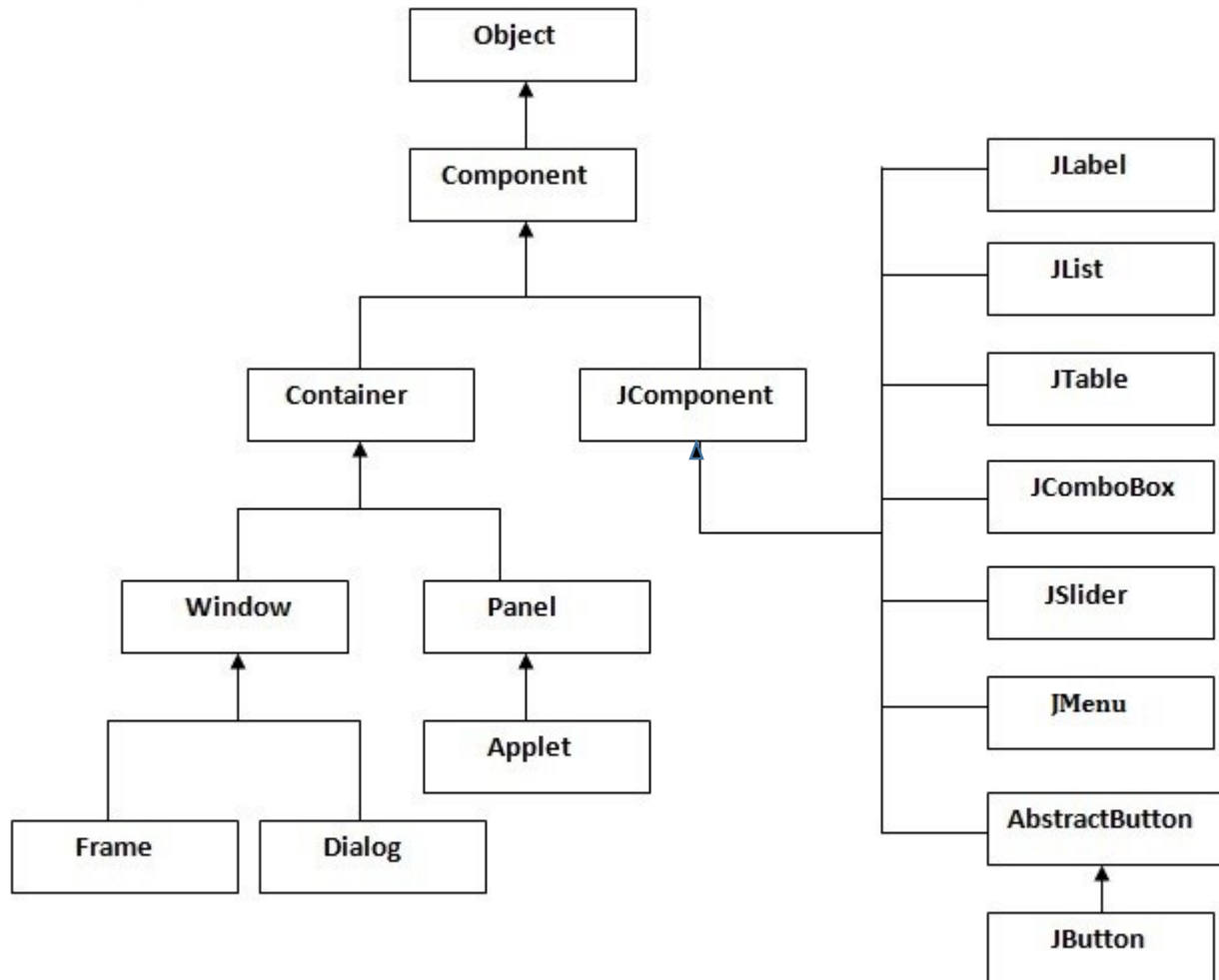


This is an example of a binary tree.

Tree: UNIX file system

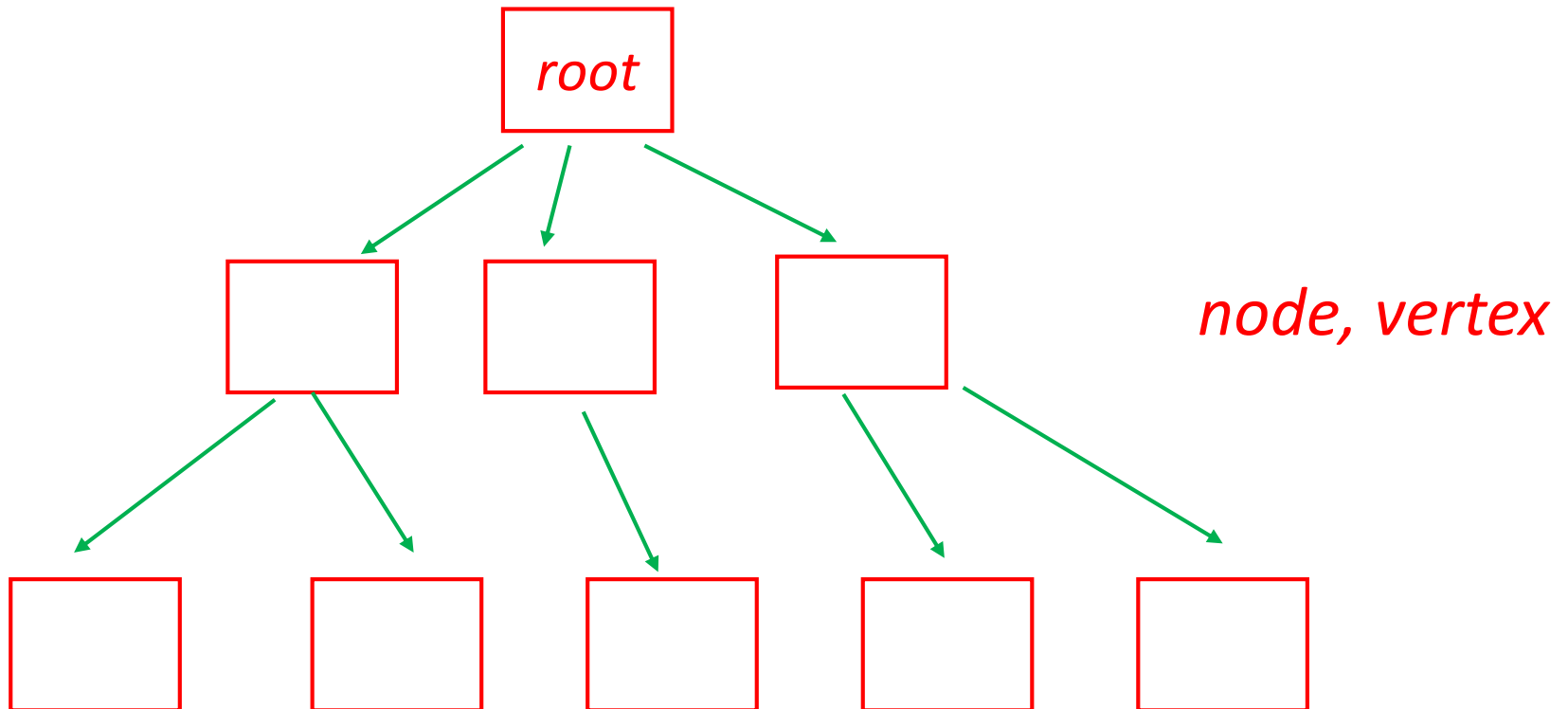


Tree: Java Classes e.g. GUI

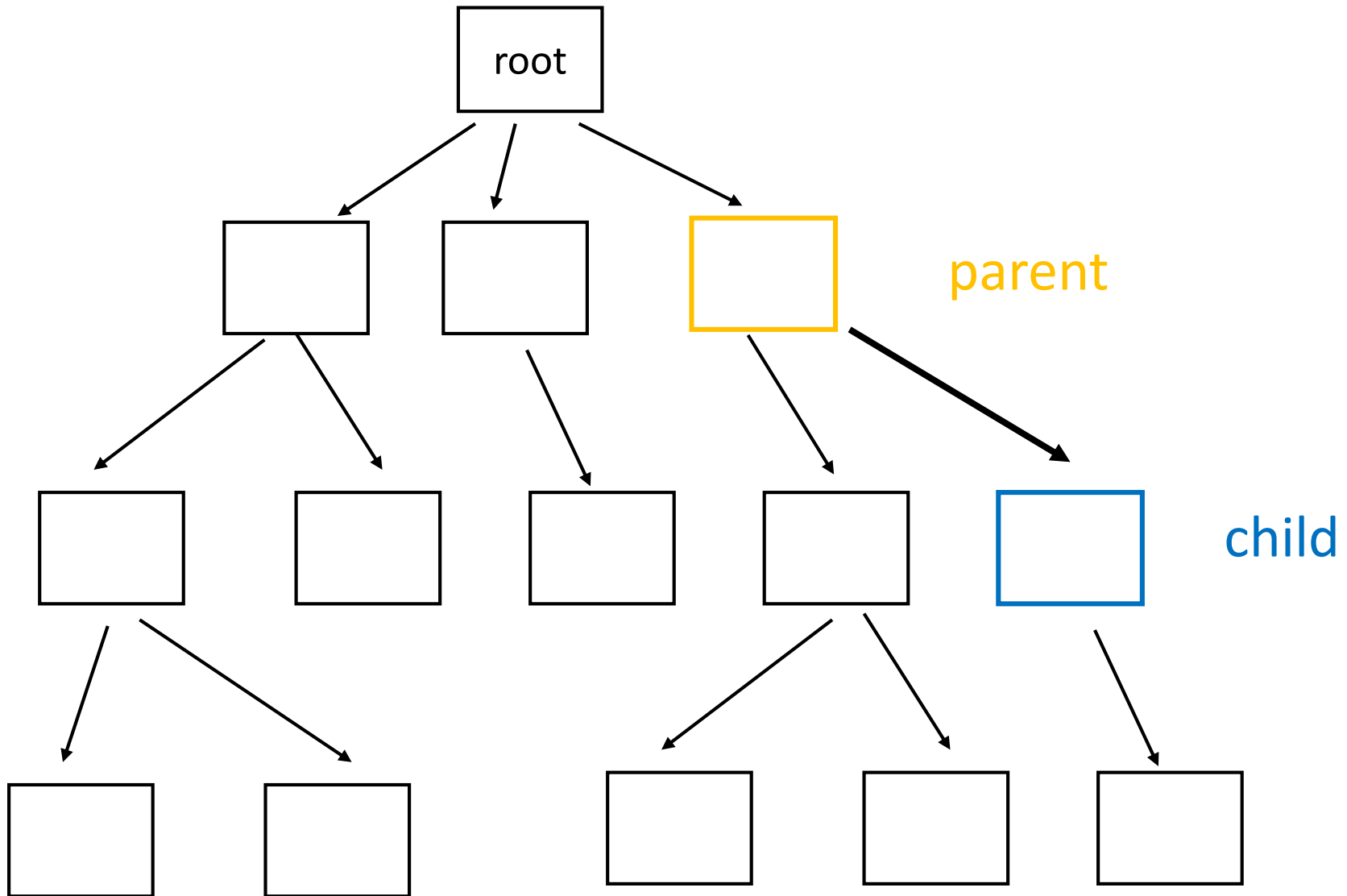


Tree Terminology

A directed edge is ordered pair: (from, to)



Every node except the root is a **child**, and has exactly one **parent**.



For some trees,

- edges are from parent to child
- edges are from child to parent
- edges are both from parent to child and child to parent.
- edge direction is ignored e.g. common with non-rooted trees (see final slide of today)

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Most of definitions today will assume edges are from parent to child.

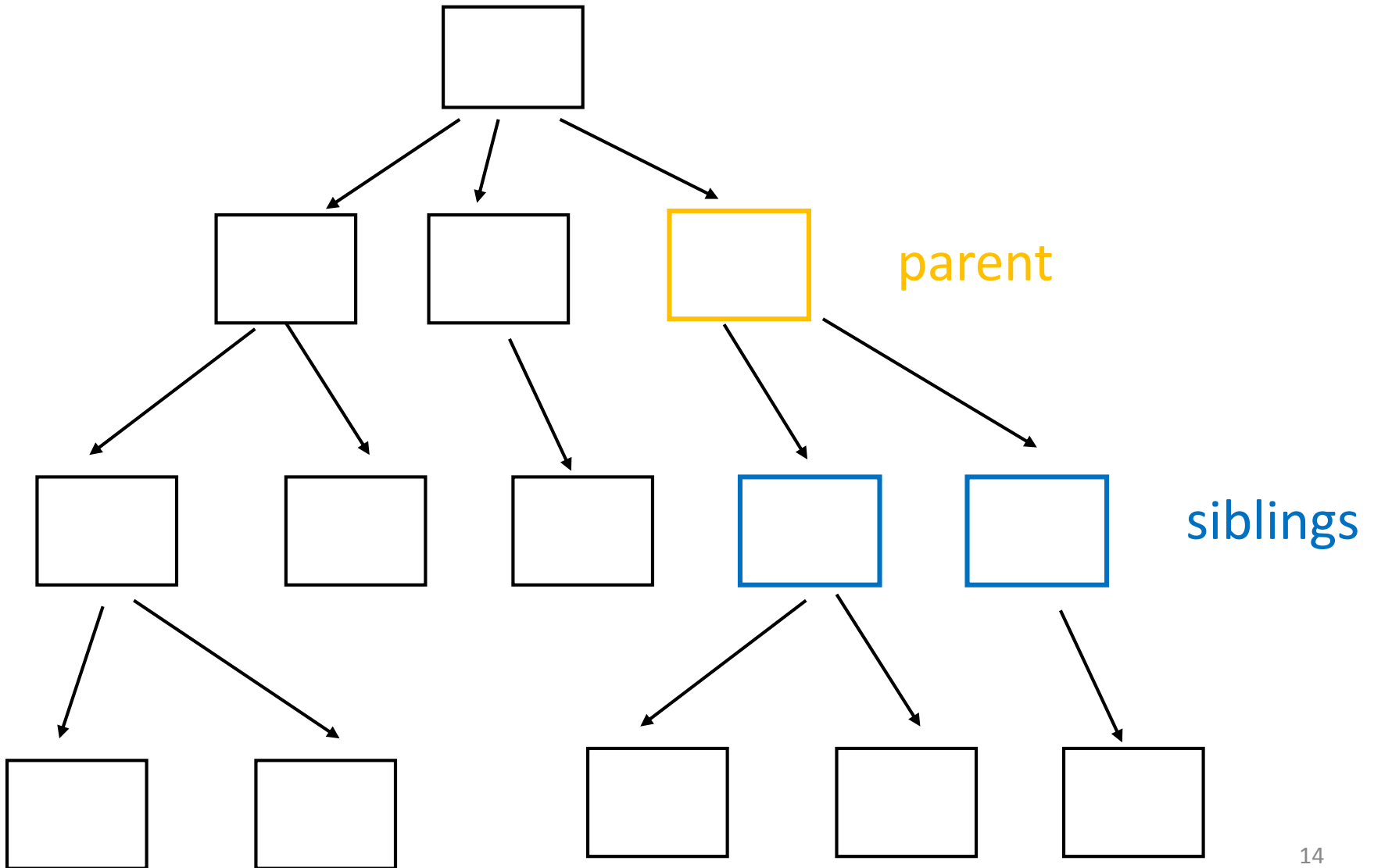
Q: If a tree has N nodes, how many edges does it have ?

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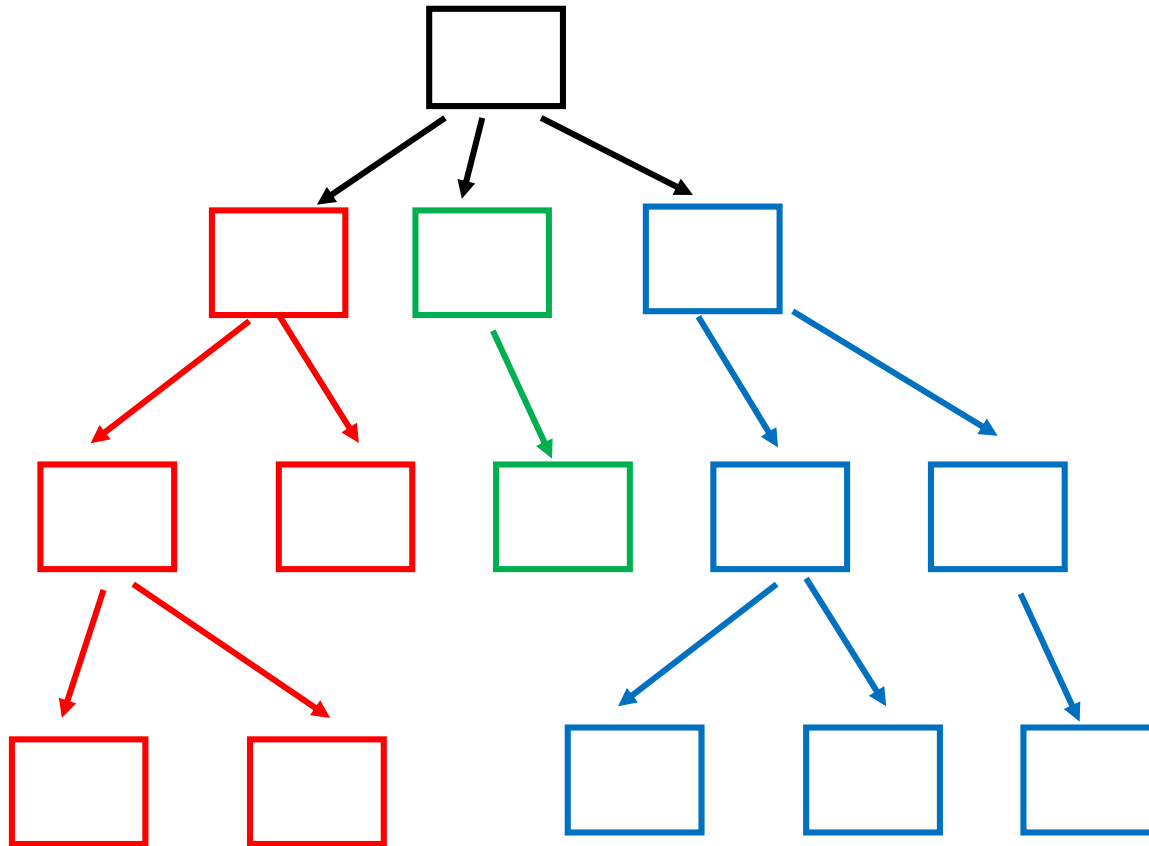
A: $N-1$

Since every edge is of the form (parent, child), and each node except the root is a child and each child has exactly one parent.

Two nodes are **siblings** if they have the same **parent**.



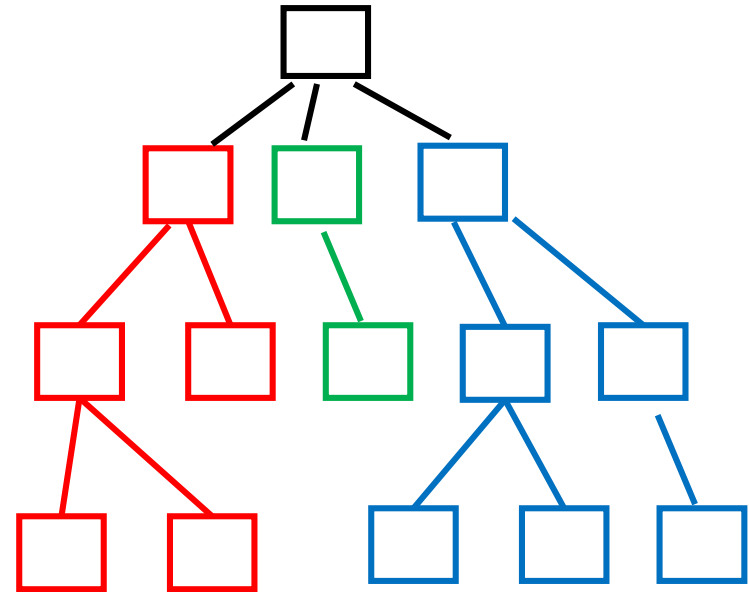
Recursive definition of rooted tree...



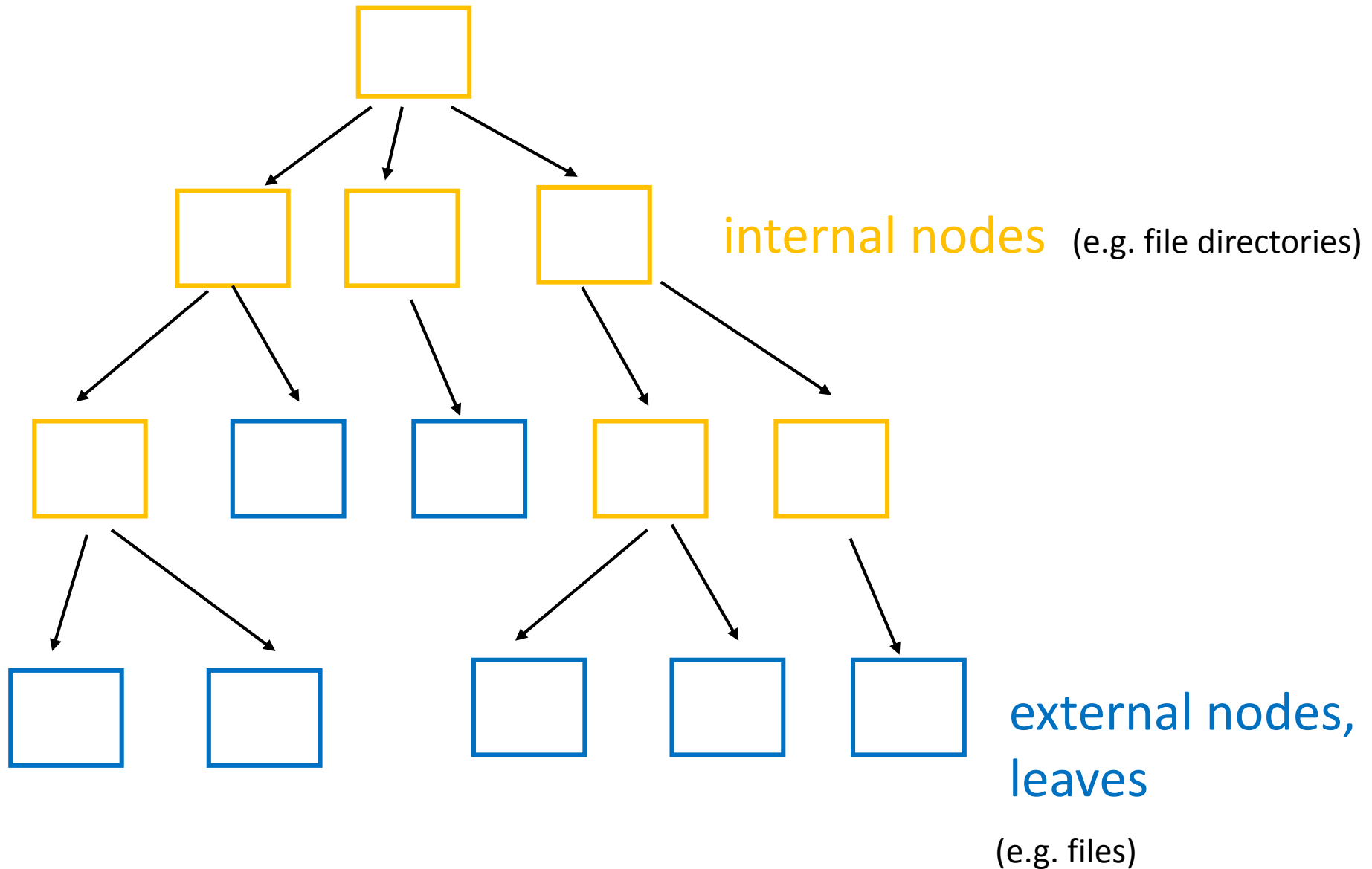
Recursive definition of rooted tree

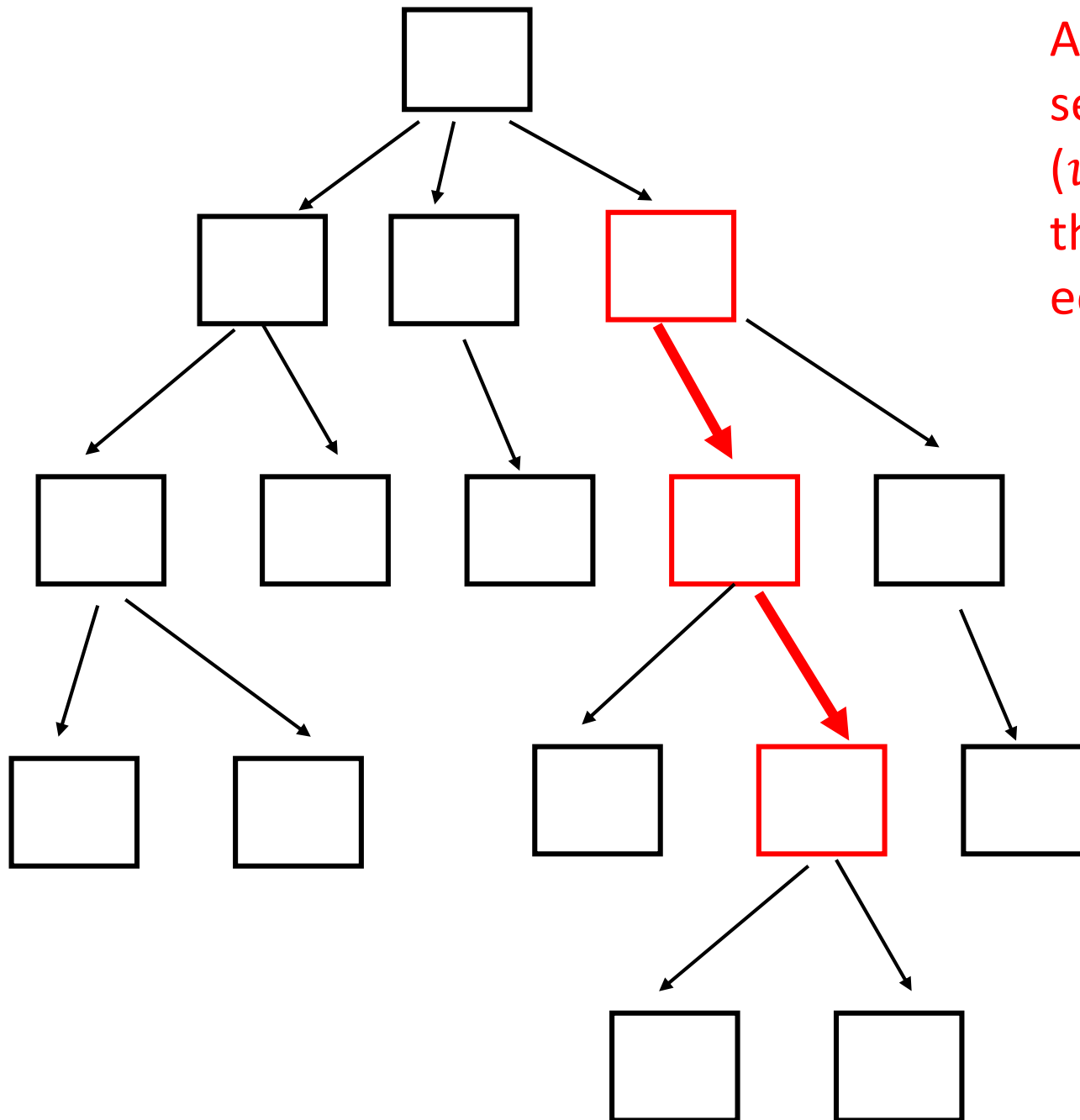
A tree T is a finite (& possibly empty) set of n nodes such that:

- if $n > 0$ then one of the nodes is the root r
- if $n > 1$ then the $n - 1$ non-root nodes are partitioned into (non-empty) subsets T_1, T_2, \dots, T_k , each of which is a tree (called a subtree”), and the roots of the subtrees are the children of root r .



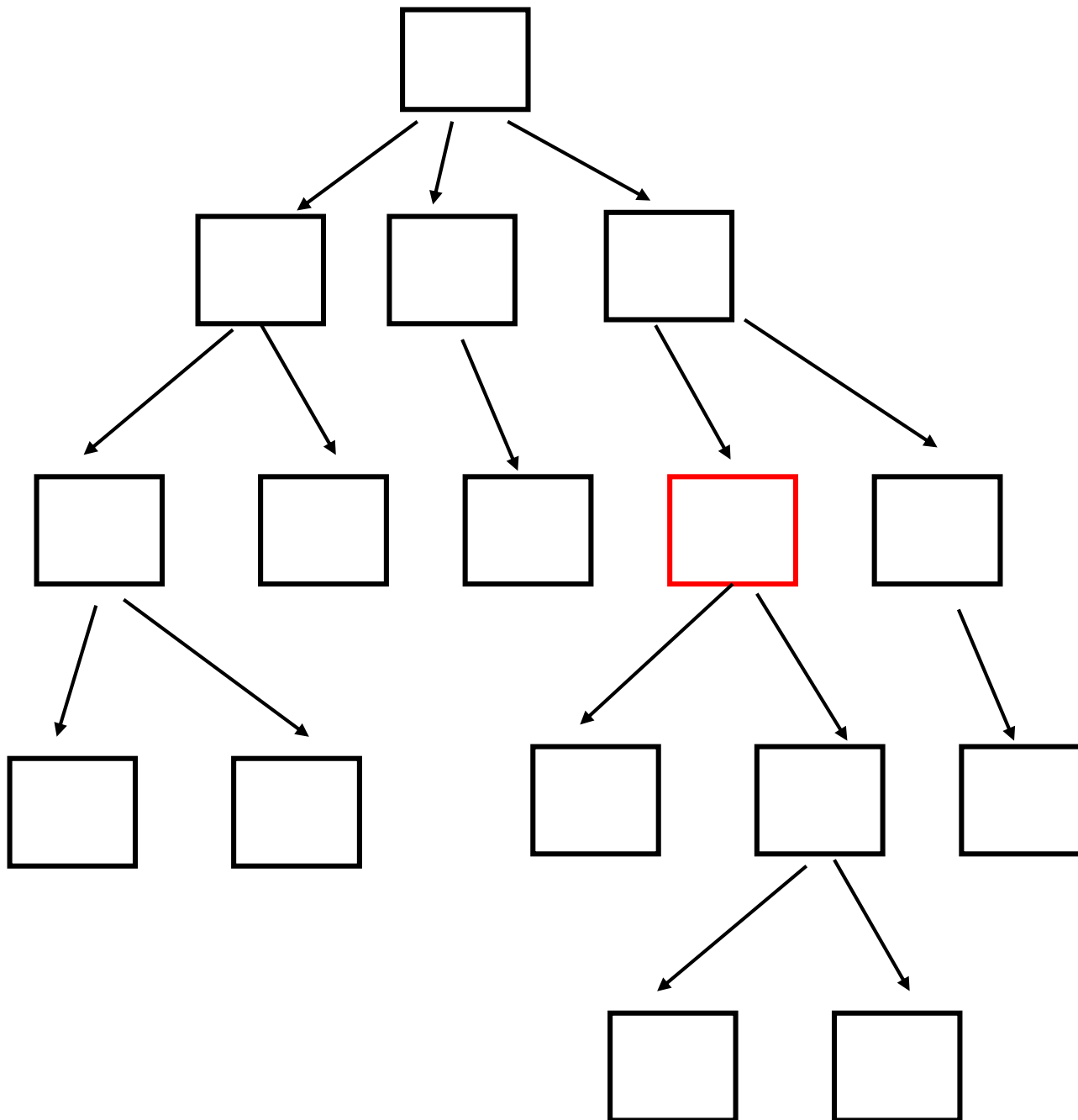
This definition does NOT assume edges are from parent to child.



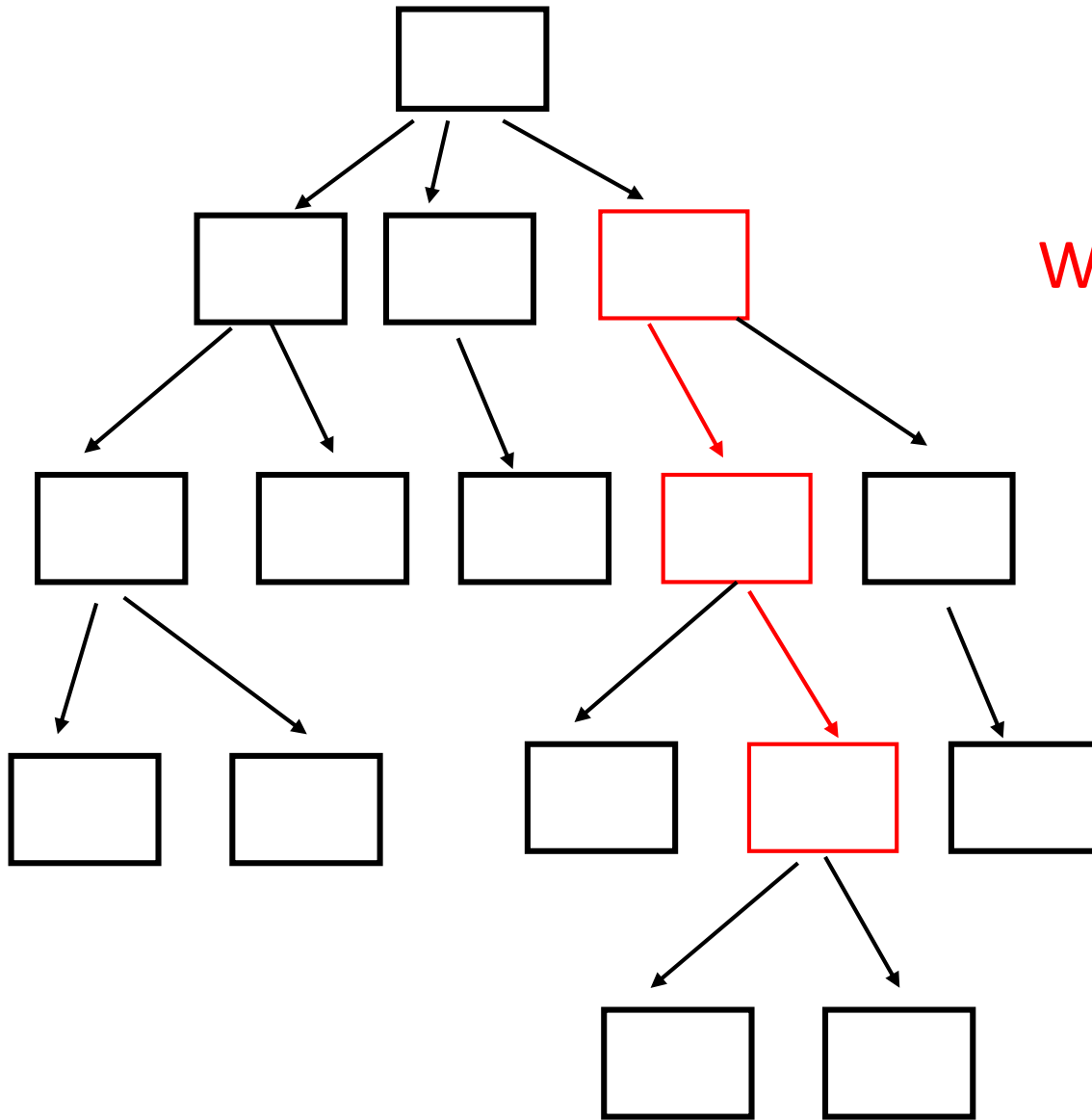


A **path** in a tree is a sequence of nodes (v_1, v_2, \dots, v_k) such that (v_i, v_{i+1}) is an edge.

The **length** of a path is *the number of edges in the path* (number of nodes $- 1$)

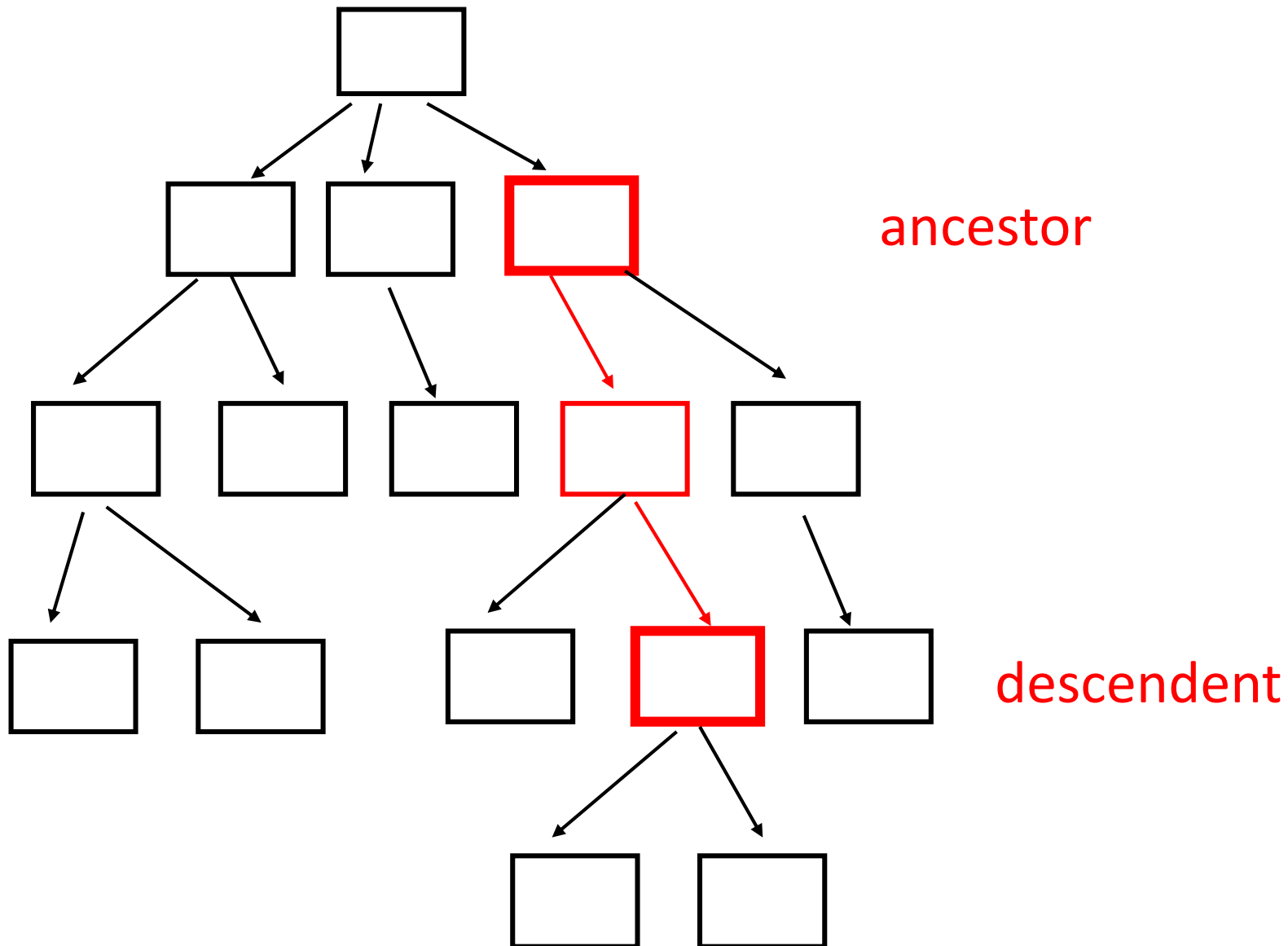


A path with just one node (v_1) has length = 0, since it has no edges.

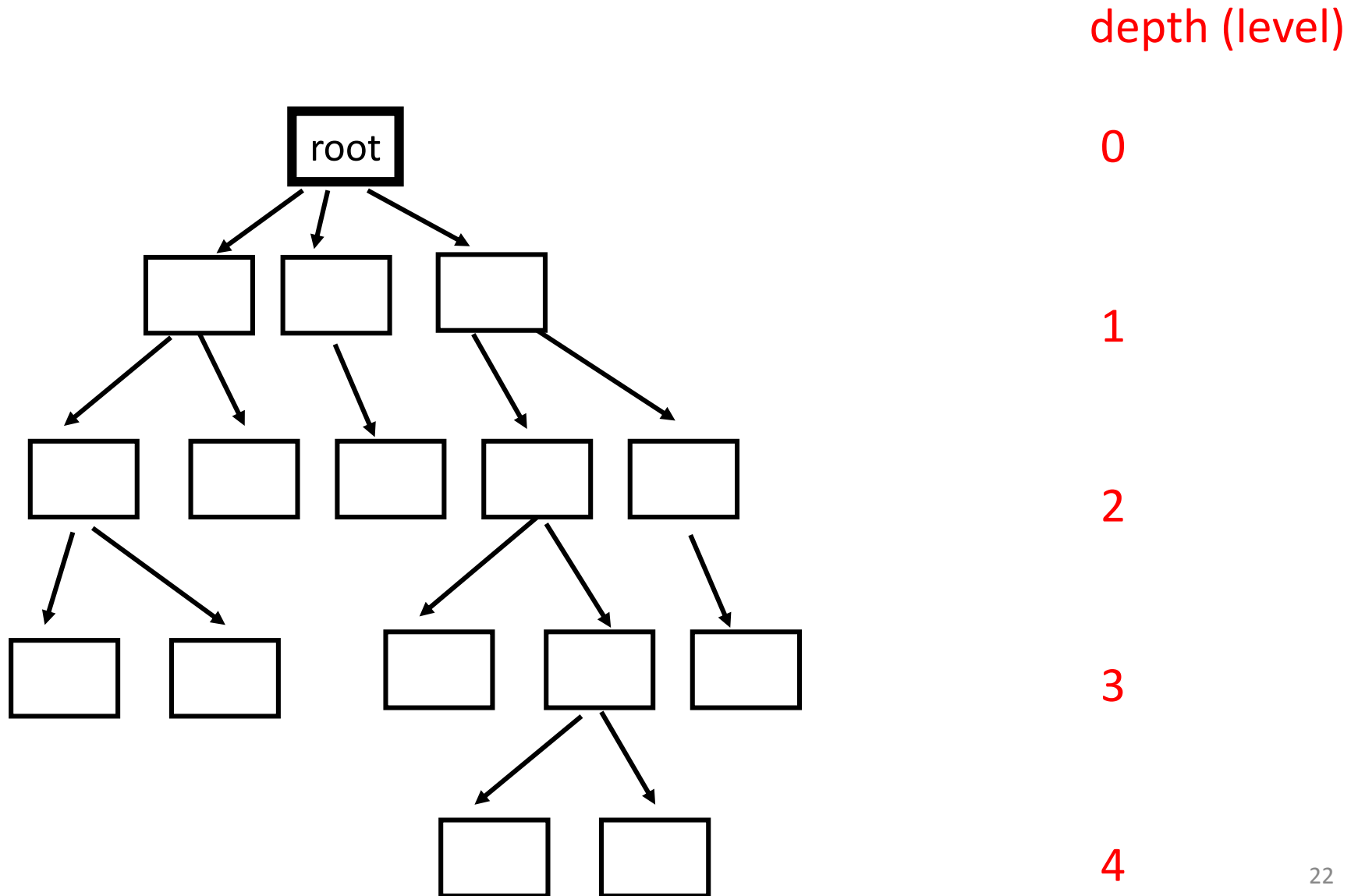


What is the path length?
(2 or 3?)

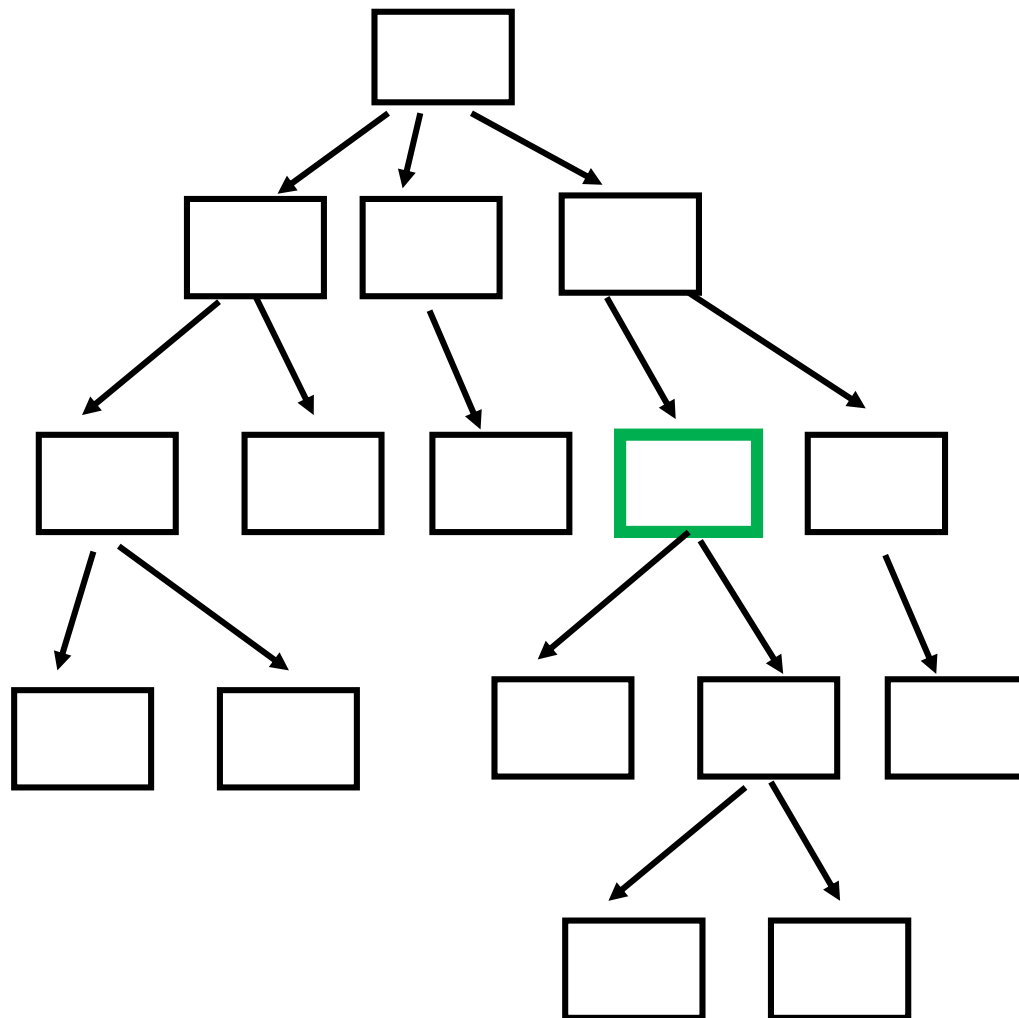
Node v is an **ancestor** of node w if there is a path from v to w.
Node w is a **descendent** of node v.



The **depth** or **level** of a node is the length of the path *from the root to the node*.



How to compute $\text{depth}(v)$?



depth (level)

0

1

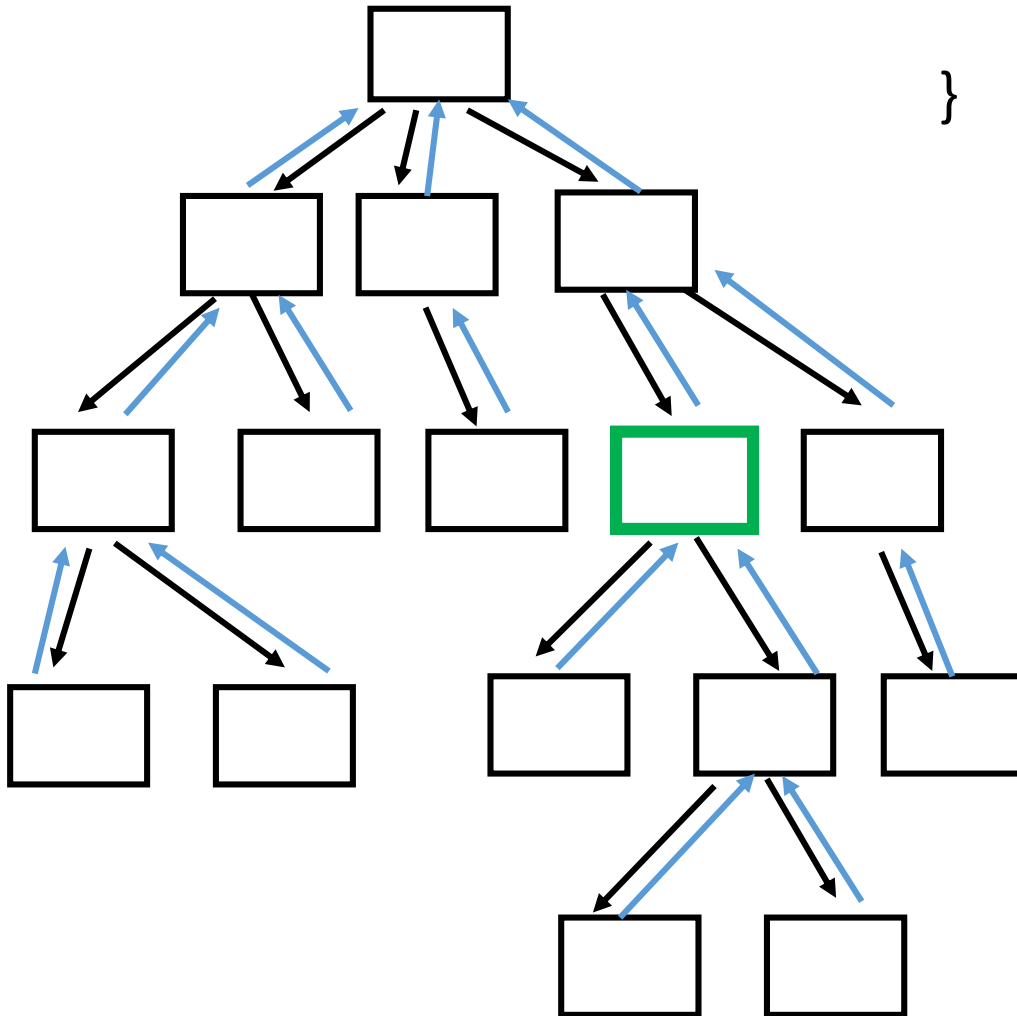
2

3

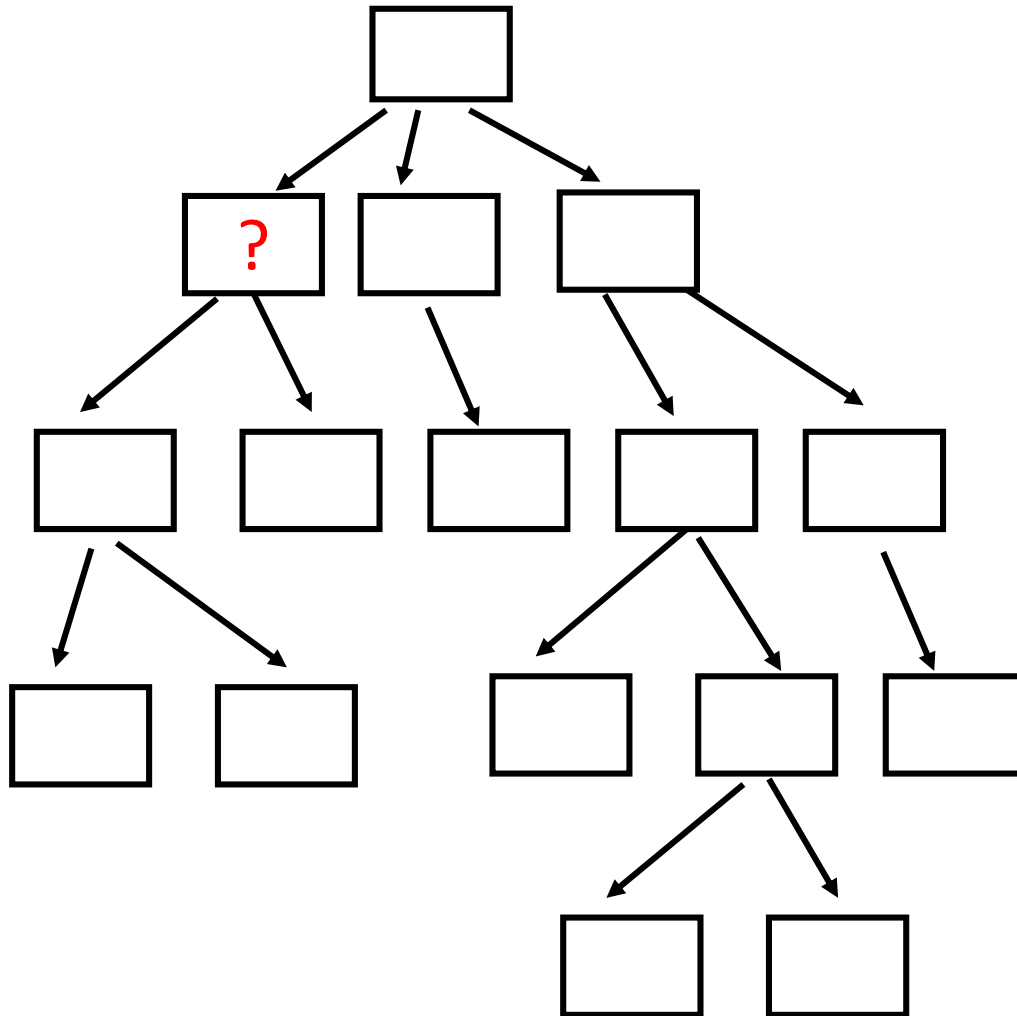
4

This requires parent links.
This is analogous to a 'prev'
link in a doubly linked list.

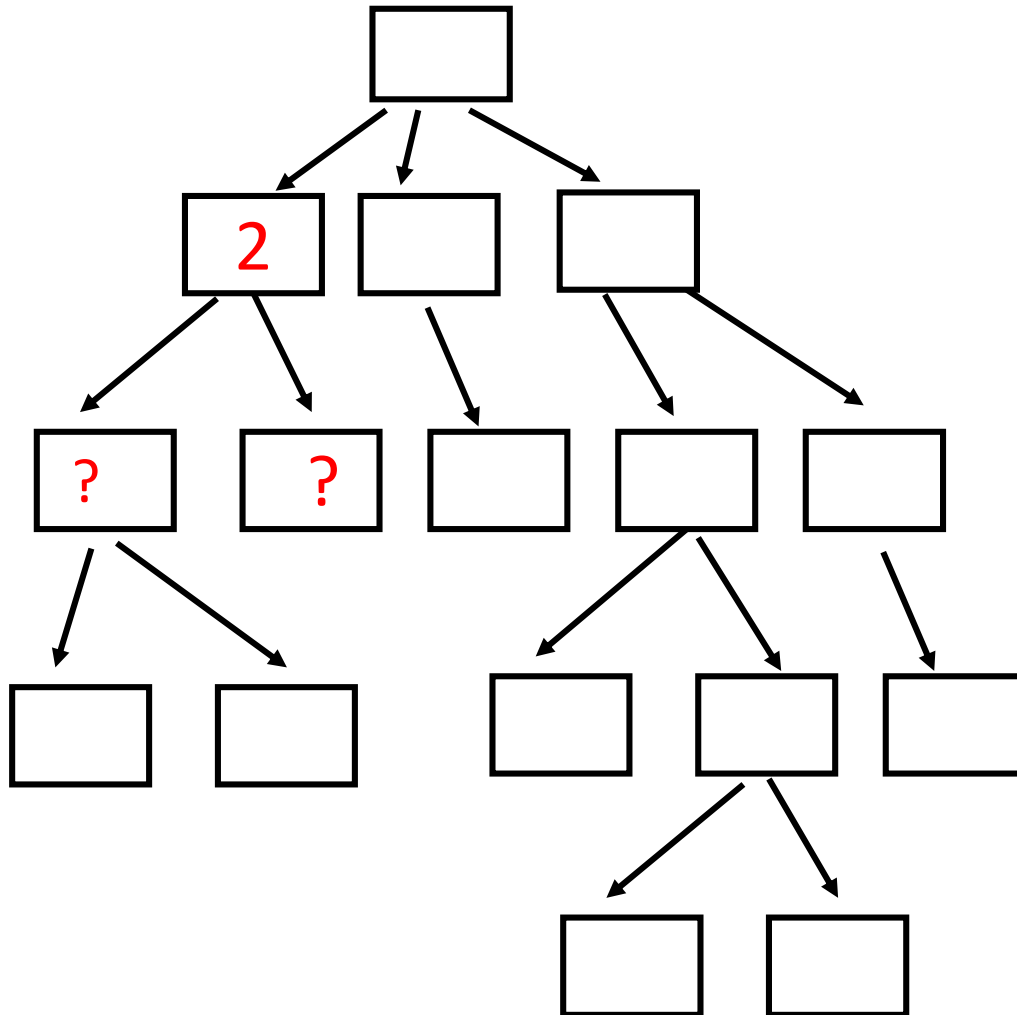
```
depth( v ){  
    if ( v.parent == null)    //root  
        return  0  
    else  
        return  1 + depth( v.parent )  
}
```



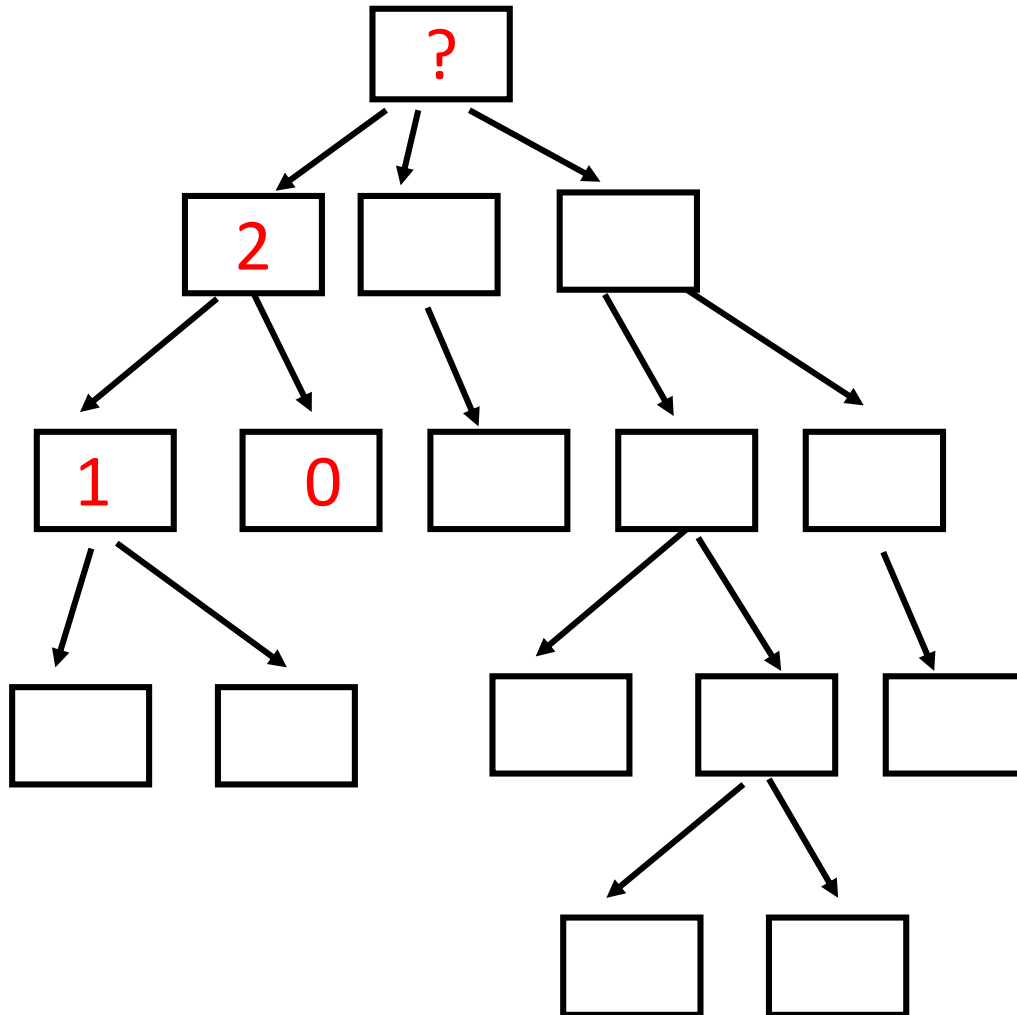
The **height** of a node is the maximum length of a path from that node to a leaf.



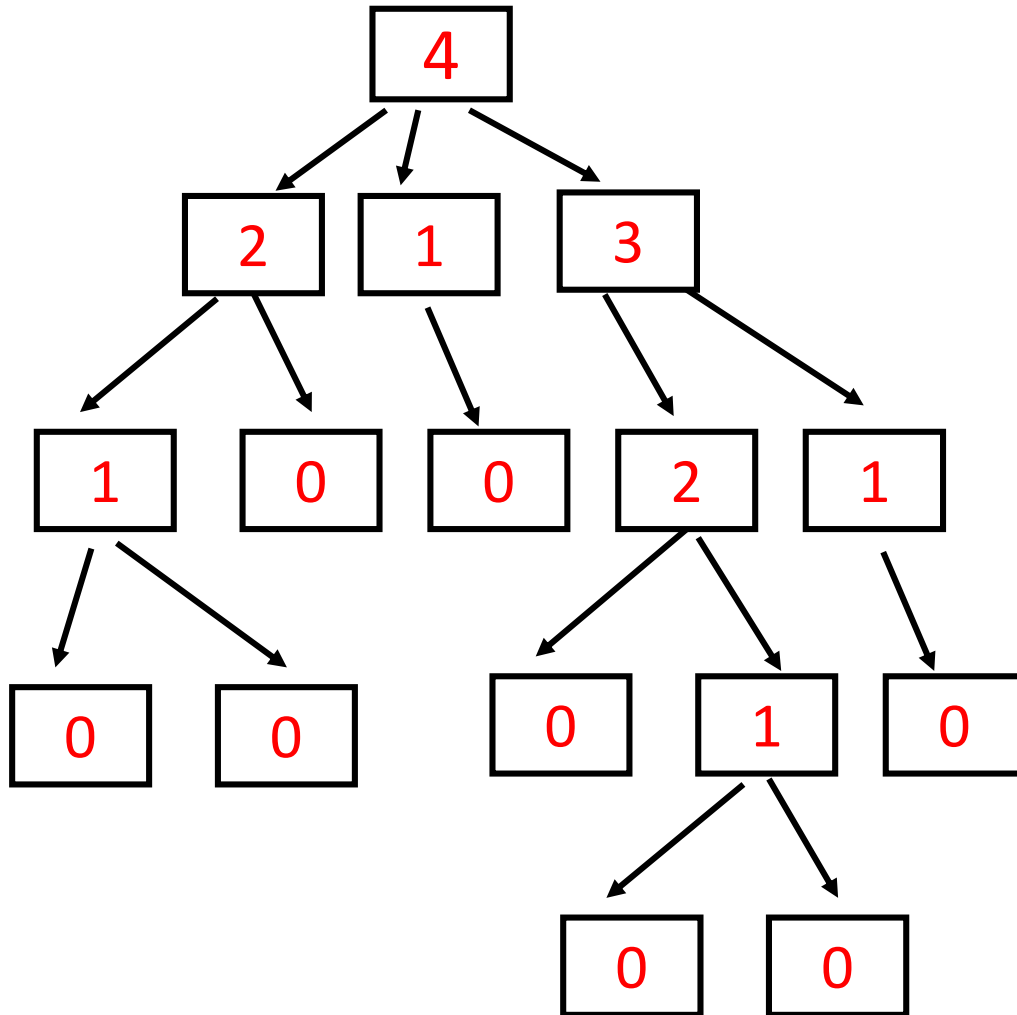
The **height** of a node is the maximum length of a path from that node to a leaf.

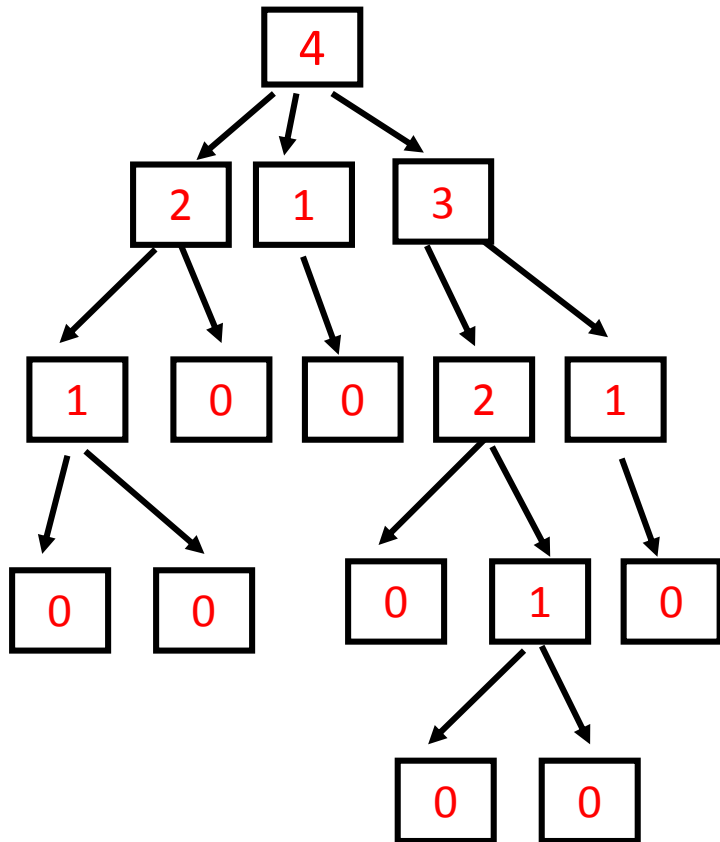


The **height** of a node is the maximum length of a path from that node to a leaf.



How to compute height(**v**) ?





```
height(v){  
  if (v is a leaf)  
    return 0  
  else{  
    h = 0  
    for each child w of v  
      h = max(h, height(w))  
    return 1 + h  
  }  
}
```

How to implement a tree ?

```
class TreeNode<T>{
```

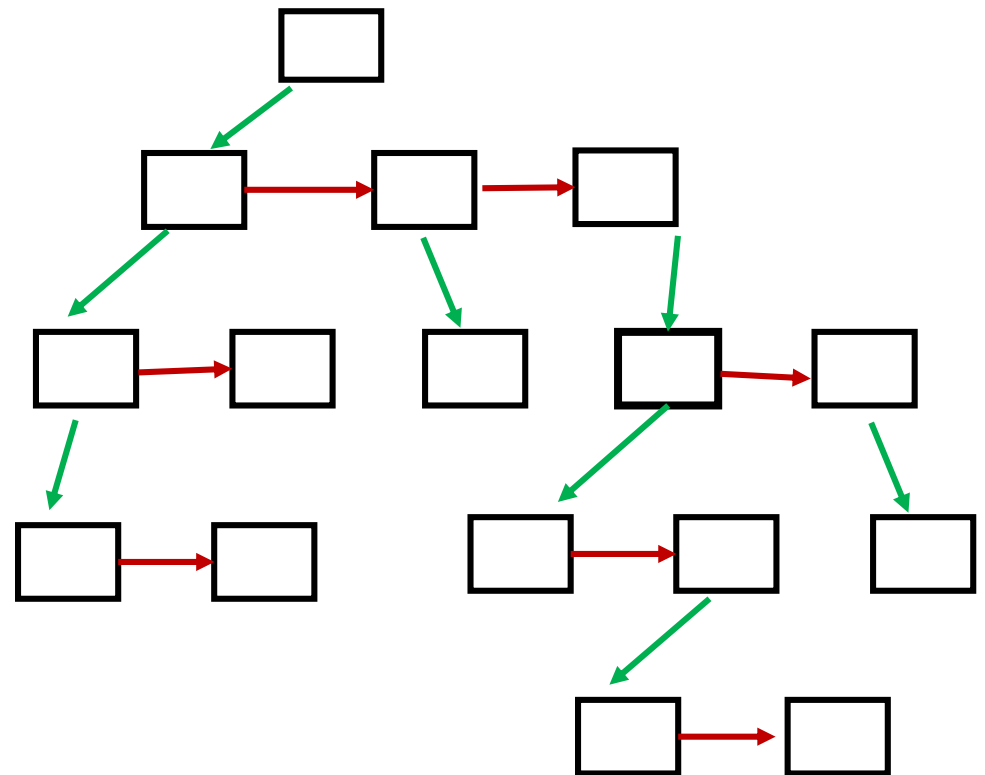
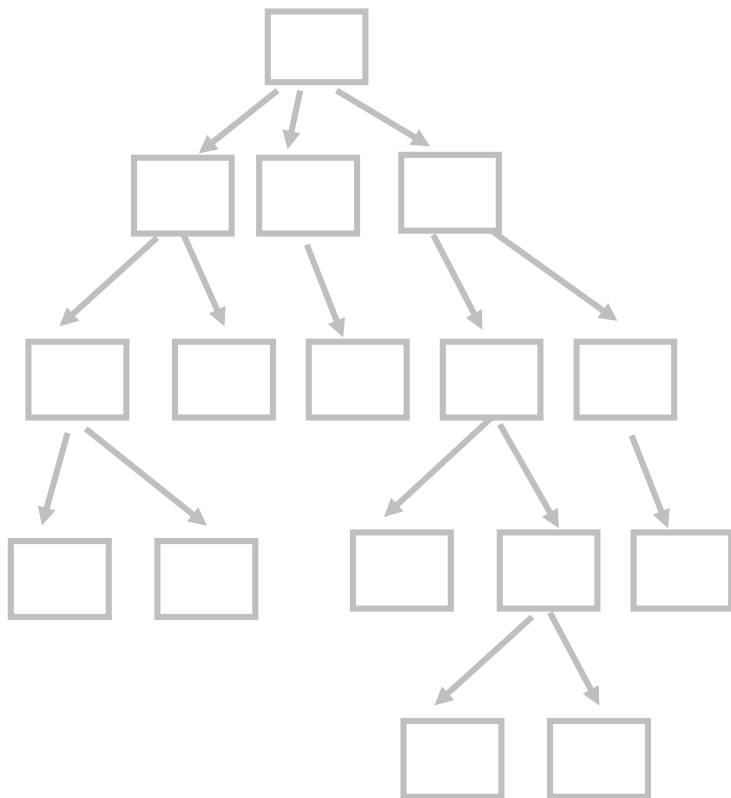
```
    T element;
```

```
}
```

How to implement a tree ?

```
class TreeNode<T>{  
    T element;  
  
    ArrayList< TreeNode<T> > children;  
  
    TreeNode<T> parent;  
}
```

Another common implementation:
'first child, next sibling'



More common implementation:

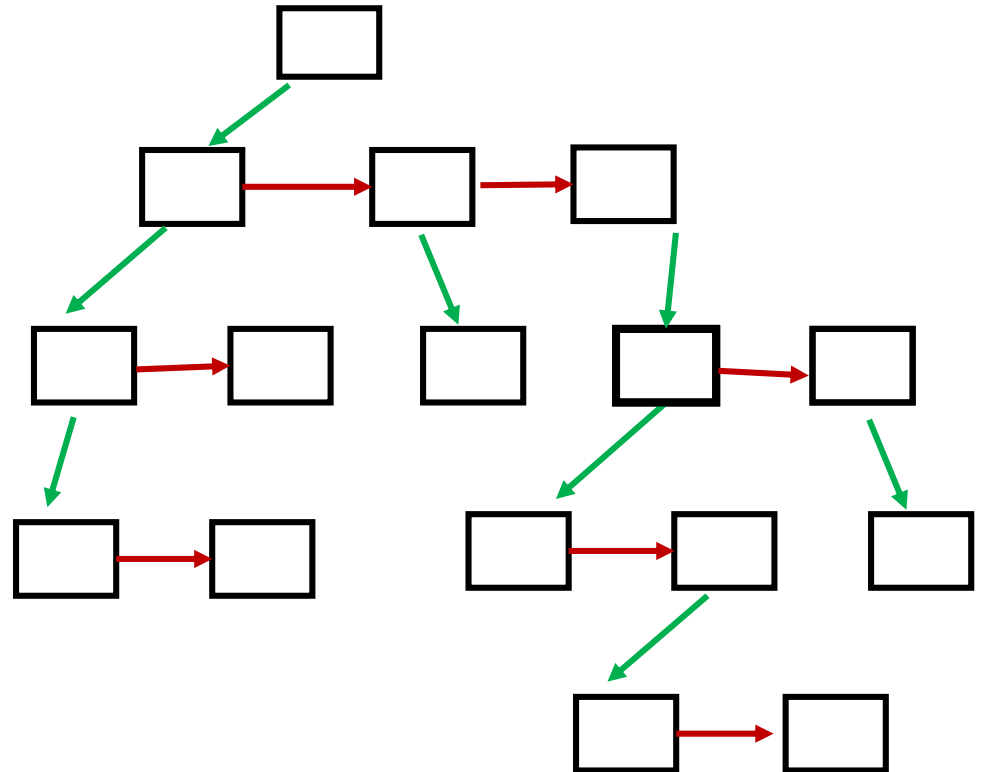
'first child, next sibling'

(similar to singly linked lists)

```
class Tree<T>{
    TreeNode<T>  root;
    :

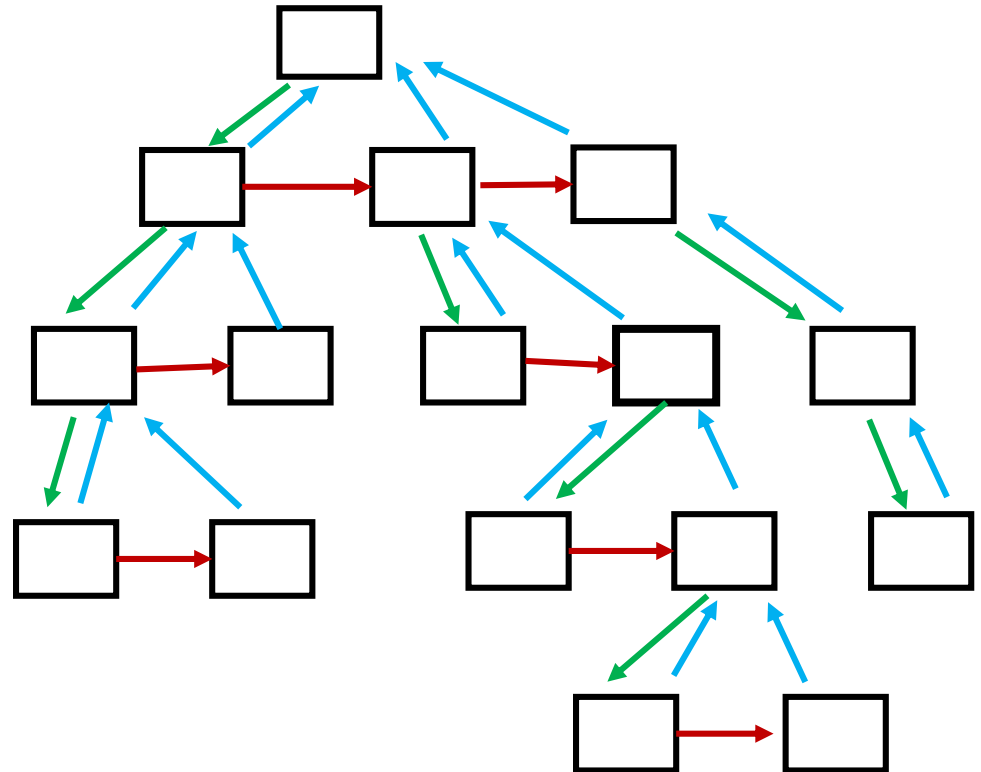
    // inner class

    class TreeNode<T>{
        T  element;
        TreeNode<T>  firstChild;
        TreeNode<T>  nextSibling;
        :
    }
}
```



More common implementation: 'first child, next sibling' (similar to singly linked lists)

```
class Tree<T>{  
    TreeNode<T> root;  
    :  
  
    // inner class  
  
    class TreeNode<T>{  
        T element;  
        TreeNode<T> firstChild;  
        TreeNode<T> nextSibling;  
        TreeNode<T> parent;    :  
    }  
}
```

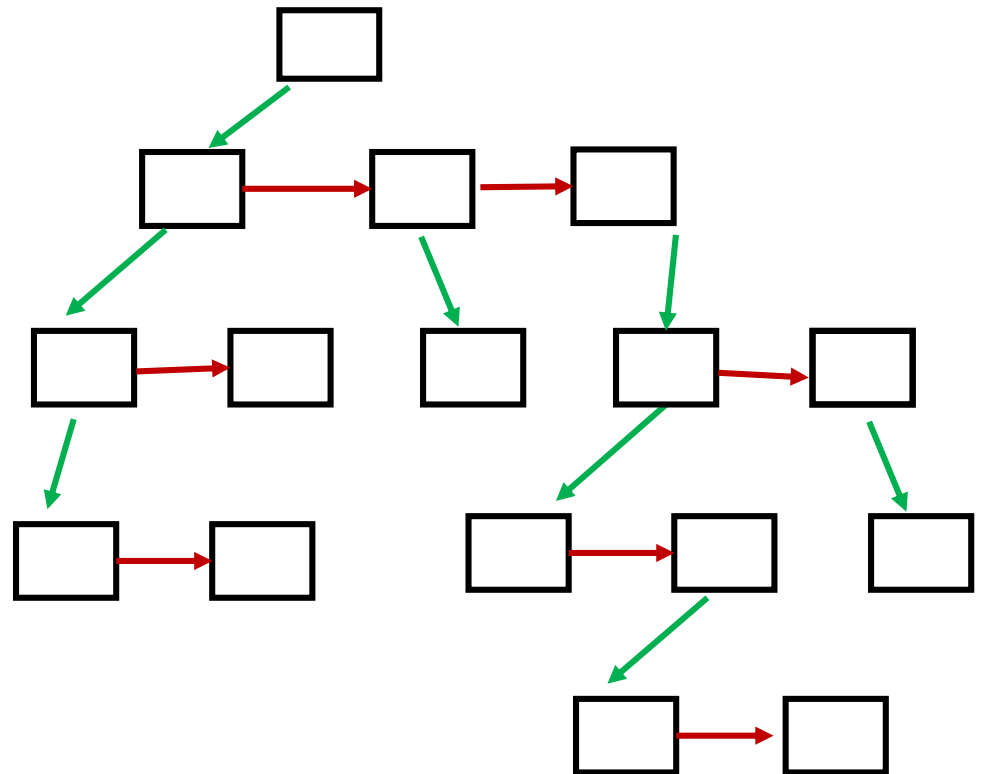


A tree of what? Each node has an element (not illustrated on right)

```
class Tree<T>{
    TreeNode<T>  root;
    :

    // inner class

    class TreeNode<T>{
        T element;
        TreeNode<T>  firstChild;
        TreeNode<T>  nextSibling;
        :
    }
}
```



Exercise

A tree can be represented using lists, as follows:

```
tree      =      root   |   ( root listOfSubTrees )
```

```
listOfSubTrees  =  tree | tree listOfSubTrees
```

Exercise

A tree can be represented using lists, as follows:

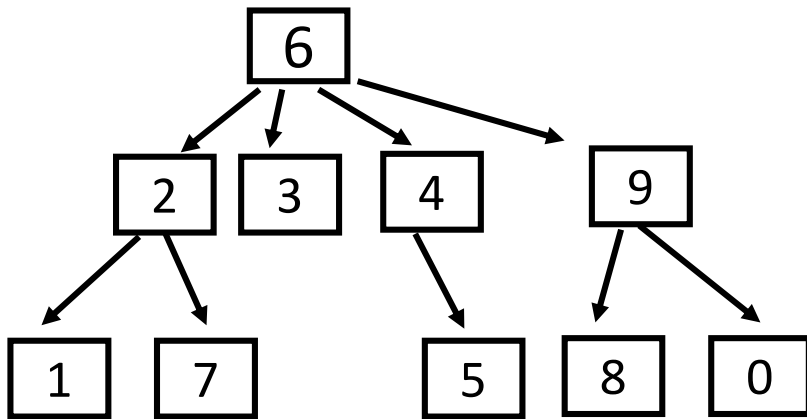
```
tree      =      root   |   ( root listOfSubTrees )
```

```
listOfSubTrees = tree | tree listOfSubTrees
```

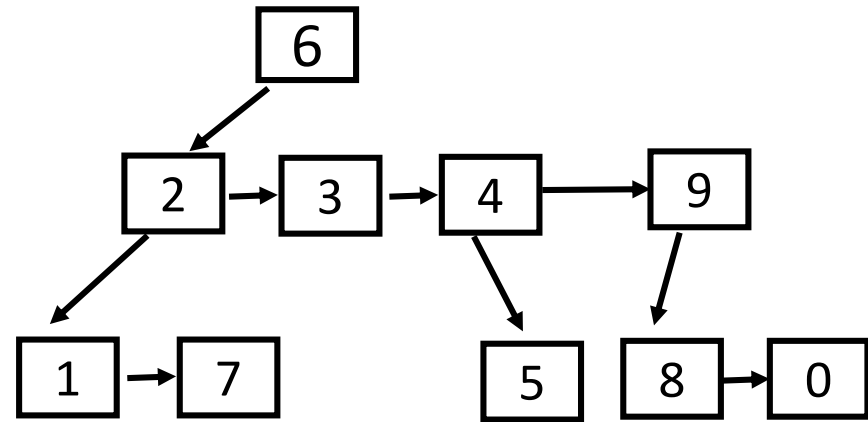
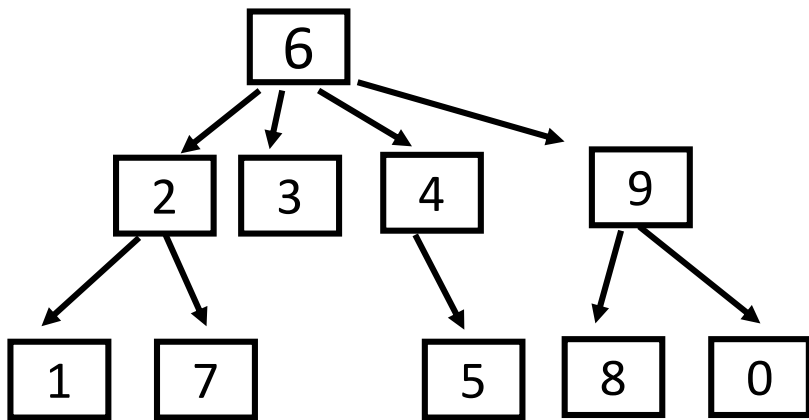
Draw the tree that corresponds to the following list, where the root elements are single digits.

```
( 6 ( 2 1 7 ) 3 ( 4 5 ) ( 9 8 0 ) )
```

(6 (2 1 7) 3 (4 5) (9 8 0))



(6 (2 1 7) 3 (4 5) (9 8 0))



ASIDE: Non-rooted trees

You will see non-rooted trees mostly commonly when edges are not directed, and there is no natural way to define the 'root'.

You will see examples in COMP 251.

Note the two trees below are the same.

