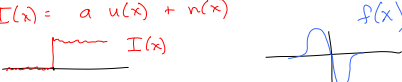


# lecture 10

- 2D edge detection
- "Corner" detection

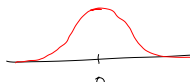
## REVIEW Edge detection (Canny)

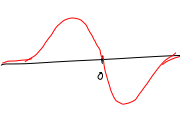
$$I(x) = a u(x) + n(x)$$


Compute  $f(x) * I(x)$   
and look for peak in response.

$$f(x) * I(x)$$


## Choosing $f(x)$

$$g(x) = e^{-\frac{x^2}{2}}$$


$$\frac{d}{dx} g(x) = -x e^{-\frac{x^2}{2}} = -f(x)$$


## Gaussian function ("Normal" distribution)

$$G(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{x^2}{2\sigma^2}}$$



$$G(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{x^2}{2\sigma^2}}, \quad g(x) = e^{-\frac{x^2}{2}}$$

How are the two related?

$$g_s(x) = e^{-\frac{s^2 x^2}{2}}$$

$$\frac{s}{\sqrt{2\pi}} g_s(x) = \frac{s}{\sqrt{2\pi}} e^{-\frac{s^2 x^2}{2}}$$

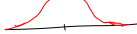
$$= G(x) \quad \text{where } \sigma = \frac{1}{s}$$

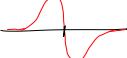
## Edge detection (Canny)

$$I(x) = a u(x) + n(x)$$

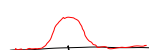
$$\text{compute } \frac{d}{dx} (g(x) * I(x))$$

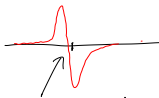
and look for peak in response.

$$g(x)$$


$$\frac{d}{dx} g(x)$$


$$I(x)$$


$$I(x) * \frac{dg(x)}{dx}$$


$$\frac{d}{dx} (I(x) * \frac{dg(x)}{dx})$$


estimated location of edge ("zero crossing")

## 2D Edge Detection



Edges can occur at any orientation.

## 2D convolution

$$I(x,y) * f(x,y)$$

$$\equiv \sum_{x'} \sum_{y'} I(x',y') f(x-x', y-y')$$

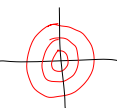
(discrete)

$$\equiv \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} I(x',y') f(x-x', y-y') dx' dy'$$

(continuous)

## 2D blur

$$g(x) = e^{-\frac{x^2}{2}}$$

$$g(x,y) = e^{-\frac{x^2}{2}} e^{-\frac{y^2}{2}} = e^{-\frac{1}{2}(x^2+y^2)}$$


## Vertical Edge detection

$$I(x,y) = a u(x-x_0) + n(x,y)$$

$$\text{Compute } \frac{\partial}{\partial x} (g(x,y) * I(x,y))$$



Look for pixels  $(x,y)$  where there is a peak in response in the  $x$  direction.

## Horizontal Edge detection

$$I(x,y) = a u(y-y_0) + n(x,y)$$

$$\text{Compute } \frac{\partial}{\partial y} (g(x,y) * I(x,y))$$



Look for pixels  $(x,y)$  where there is a peak in response in the  $y$  direction.

## Edge detection at any orientation

$$\left( \frac{\partial}{\partial x} g(x,y) * I(x,y), \frac{\partial}{\partial y} g(x,y) * I(x,y) \right)$$

$$= \nabla (g(x,y) * I(x,y))$$

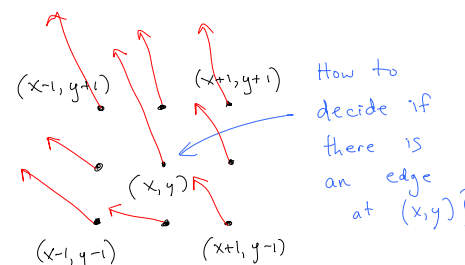
gradient operator

$$I(x,y)$$

$$\nabla (I(x,y) * g(x,y))$$



$$\nabla g(x,y) * I(x,y)$$



## 2D Edge Detection

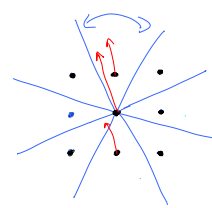
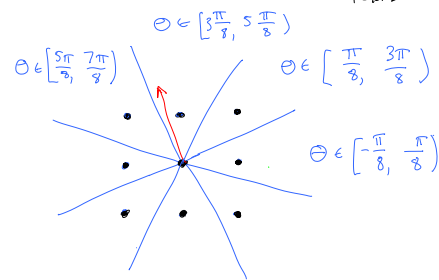
- compute  $\nabla (g(x,y) * I(x,y))$
- to decide if there is an edge at  $(x,y)$ , check for a local maxima of  $|\nabla (g * I)|$  in the direction of  $\nabla (g * I)(x,y)$

$$\nabla (g(x,y) * I(x,y))$$

$$= (\cos \theta, \sin \theta) \left| \nabla (g(x,y) * I(x,y)) \right|$$

To decide if there is an edge at  $(x,y)$   
 . compute  $\theta(x,y)$  and look  
 for maxima of  $|\nabla g * I|$  in  
 direction  $\theta$ .

Example Approach (Trucco & Verri textbook)



In case  $\theta \in [\frac{\pi}{8}, \frac{5\pi}{8}]$ ,

check that  
 three conditions  
 are met :

- $|\nabla g * I(x,y+1)| < |\nabla g * I(x,y)|$
- $|\nabla g * I(x,y-1)| < |\nabla g * I(x,y)|$
- $|\nabla g * I(x,y)| > \text{threshold}$

edge

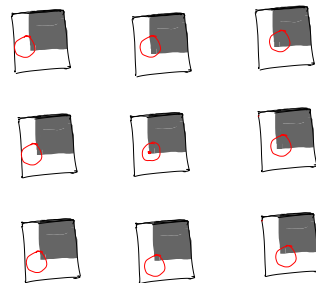


Pixels along an edge may be difficult to distinguish from each other.

Corner



Position is well defined.



Notation: write  $I(x,y)$   
 instead of  $g(x,y) * I(x,y)$ .

e.g.  $\nabla I(x,y)$  instead of  
 $\nabla g(x,y) * I(x,y)$

Is there a "corner" at  $(x_0, y_0)$ ?

Formulation #1:  $N_{gd}(x_0, y_0)$

How does:

$$\sum_{(x,y) \in N_{gd}(x_0, y_0)} (I(x,y) - I(x+\Delta x, y+\Delta y))^2$$

vary with  $(\Delta x, \Delta y) \in \{-1, 0, 1\} \times \{-1, 0, 1\}$ ?



Example:

$N_{gd}(x_0, y_0)$  could be  $5 \times 5$  pixels  
 or a disk of diameter 5 pixels.

Formulation #2

$$I(x+\Delta x, y+\Delta y)$$

$$\approx I(x,y) + \frac{\partial I(x,y)}{\partial x} \Delta x + \frac{\partial I(x,y)}{\partial y} \Delta y$$

$$\sum_{(x,y) \in N_{gd}(x_0, y_0)} (I(x,y) - I(x+\Delta x, y+\Delta y))^2$$

$$\approx \sum_{(x,y) \in N_{gd}(x_0, y_0)} \left( \frac{\partial I(x,y)}{\partial x} \Delta x + \frac{\partial I(x,y)}{\partial y} \Delta y \right)^2$$

$$\sum_{(x,y) \in N_{gd}(x_0, y_0)} \left( \frac{\partial I(x,y)}{\partial x} \Delta x + \frac{\partial I(x,y)}{\partial y} \Delta y \right)^2$$

$$= \sum_{(x,y) \in N_{gd}(x_0, y_0)} (\Delta x, \Delta y)^T \nabla I(x,y)^T \nabla I(x,y) \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$

$$= (\Delta x, \Delta y) \sum_{(x,y) \in N_{gd}(x_0, y_0)} \begin{bmatrix} \left( \frac{\partial I}{\partial x} \right)^2 & \frac{\partial I}{\partial x} \frac{\partial I}{\partial y} \\ \frac{\partial I}{\partial x} \frac{\partial I}{\partial y} & \left( \frac{\partial I}{\partial y} \right)^2 \end{bmatrix} \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$

$$\geq 0$$

Second Moment Matrix

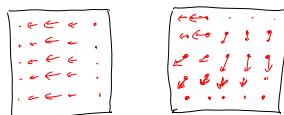
$$M = \sum_{(x,y) \in N_{gd}(x_0, y_0)} \begin{pmatrix} \frac{\partial I}{\partial x} \\ \frac{\partial I}{\partial y} \end{pmatrix} \begin{pmatrix} \frac{\partial I}{\partial x} & \frac{\partial I}{\partial y} \end{pmatrix}$$

$$= \sum_{(x,y) \in N_{gd}(x_0, y_0)} \begin{bmatrix} \left( \frac{\partial I}{\partial x} \right)^2 & \frac{\partial I}{\partial x} \frac{\partial I}{\partial y} \\ \frac{\partial I}{\partial x} \frac{\partial I}{\partial y} & \left( \frac{\partial I}{\partial y} \right)^2 \end{bmatrix}$$

$I(x)$



$\nabla I(x)$



$$M = \sum_{N_{gd}} \nabla I^T \nabla I \quad \begin{bmatrix} 23 & 0 \\ 0 & 0 \end{bmatrix} \quad \begin{bmatrix} 8 & 7 \\ 7 & 8 \end{bmatrix}$$

Is there a "corner" at  $(x_0, y_0)$ ?

Formulation #2:  $N_{gd}(x_0, y_0)$

How does quadratic form

$$(\Delta x, \Delta y) M \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$

vary with  $(\Delta x, \Delta y)$  on unit circle?