

lecture 18

least squares, SVD

Least Squares: version 1

Given an $m \times n$ matrix A ,
find an n -vector \vec{x} that
minimizes $\|A\vec{x}\|^2$, subject
to $\|\vec{x}\| = 1$.

$$\begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix} = A \begin{bmatrix} x \\ \vdots \\ x \end{bmatrix} \quad m \geq n$$

Use method of Lagrange multipliers:

$$\text{Minimize } \|A\vec{x}\|^2 + \lambda(\vec{x}^T \vec{x} - 1)$$

Idea:

The expression to be minimized
is quadratic in \vec{x} and
has a unique minimum when
for any $\lambda \geq 0$.

Take derivatives with respect to each x_i
and set to 0, gives a set of equations:

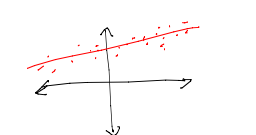
$$0 = \frac{\partial}{\partial \vec{x}} [\vec{x}^T A^T A \vec{x} + \lambda(\vec{x}^T \vec{x} - 1)]$$

$$= 2A^T A \vec{x} + 2\lambda \vec{x}$$

$$\Rightarrow A^T A \vec{x} = -\lambda \vec{x}$$

$$\Rightarrow \vec{x} \text{ is an eigenvector of } A^T A$$

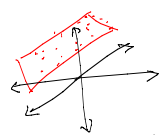
But minimizing $\|\vec{x}^T A^T A \vec{x}\|$
 $\Rightarrow \vec{x}$ is the eigenvector of $A^T A$
with smallest eigenvalue



Fit line to a set
of points in 2D.
Minimize the sum of
squares of:

$$\begin{bmatrix} x_1 - \bar{x} & y_1 - \bar{y} \\ \vdots & \vdots \\ x_n - \bar{x} & y_n - \bar{y} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

subject to
 $|a, b| = 1$



Fit plane to a
set of points in 3D.
Minimize the sum of
squares of:

$$\begin{bmatrix} x_1 - \bar{x} & y_1 - \bar{y} & z_1 - \bar{z} \\ \vdots & \vdots & \vdots \\ x_n - \bar{x} & y_n - \bar{y} & z_n - \bar{z} \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

subject to
 $\|(a, b, c)\| = 1$

Least Squares: Version 2:

Given $m \times n$ matrix A and
 m -vector $\vec{b} \neq 0$,

find \vec{x} that minimizes

$$\|A\vec{x} - \vec{b}\|^2$$

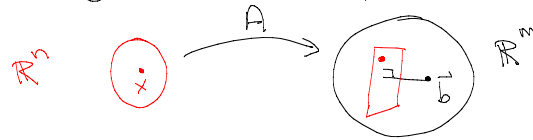
$$0 = \frac{\partial}{\partial \vec{x}} (A\vec{x} - \vec{b})^T (A\vec{x} - \vec{b})$$

$$\Rightarrow 0 = 2A^T A \vec{x} - 2A^T \vec{b}$$

$$\Rightarrow \underbrace{A^T A}_{n \times n} \vec{x} = \underbrace{A^T \vec{b}}_{n \times 1}$$

and solve for x using basic
linear algebra methods, assuming that
 A has rank n i.e. invertible.

Geometric Interpretation



\vec{b} can be written as the sum of a
vector in the column space of A
and a vector perpendicular to column
space of A . The solution is
the former, i.e. $A^T (A\vec{x} - \vec{b}) = \vec{0}$.

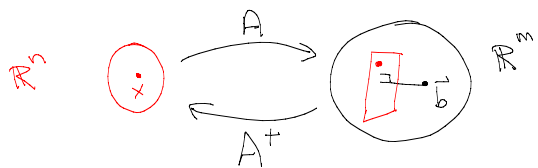
Suppose the columns of A are linearly
independent. Then $A^T A$ is
invertible (prove that on your own):

$$\therefore A^T A \vec{x} = A^T \vec{b}$$

$$\Rightarrow \vec{x} = \underbrace{(A^T A)^{-1} A^T}_{\text{called the "pseudo inverse"}}$$

$$= A^+ \vec{b}$$

i.e. gives the least squares solution.

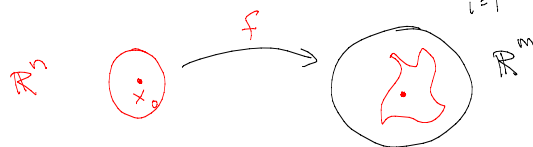


$A^+ A = I$ $n \times n$ always.
 But $A A^+ = I$ only if A is invertible ($m=n$, in particular)

Non-linear least squares

$$\vec{f} : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

Given $\vec{x}_0 \in \mathbb{R}^n$, we want a nearby x that minimizes $\|\vec{f}(\vec{x})\|$ is. minimize $\sum_{i=1}^m f_i(\vec{x})^2$.



Look at $\vec{f}(\vec{x})$ in local neighborhood of \vec{x}_0 .

"Jacobian"

$$\vec{f}(\vec{x}) \approx \vec{f}(\vec{x}_0) + \frac{\partial \vec{f}}{\partial \vec{x}} \bigg|_{\vec{x}=\vec{x}_0} (\vec{x} - \vec{x}_0)$$

Minimize

$$\|\vec{f}(\vec{x})\|^2 \approx \left\| \vec{f}(\vec{x}_0) + \frac{\partial \vec{f}}{\partial \vec{x}} \bigg|_{\vec{x}=\vec{x}_0} (\vec{x} - \vec{x}_0) \right\|^2$$

$$\vec{x}^{(k+1)} \leftarrow \vec{x}^{(k)} + \Delta x$$

i.e. $\vec{x} \rightarrow \vec{x}_0$

"Gauss-Newton" method

Example: minimize over \vec{h}

$$\sum \left(I(\vec{x} + \vec{h}) - J(\vec{x}) \right)^2$$

$x \in \mathcal{N}_\delta(x_0, y_0)$

Interpretation: $f_i(\vec{h}) = I(\vec{x}_i + \vec{h}) - J(\vec{x}_i)$

In our solution, we linearized $I(\vec{x} + \vec{h})$ at $h=0$, solved for \vec{h} , then iterated.

$$h^{(k+1)} \leftarrow h^{(k)} + h$$

Singular Value Decomposition (SVD)

Any $m \times n$ matrix A can be written

$$A = U \Sigma V^T$$

assume $m > n$ here

i.e. any linear transformation is composed of rotate/reflect, scale/embed, rotate/reflect.

$A^T A$ is symmetric, $n \times n$
 \therefore eigenvalues are non-negative, σ_i^2
 Without loss of generality, eigenvectors are orthonormal.

Define n eigenvectors V and n eigenvalues $\sigma_i = \sqrt{\lambda_{ii}}$.

$$A^T A V = V \Sigma^2$$

σ_i are the "singular values".

$$A^T A V = V \Sigma^2$$

$$\text{Define } \tilde{U} \equiv A V$$

$$\begin{aligned}
 \therefore \tilde{U}^T \tilde{U} &= V^T A^T A V \\
 &= V^T V \Sigma^2 \\
 &= \Sigma^2
 \end{aligned}$$

\therefore columns of \tilde{U} are orthogonal and have length σ_i

Define U to have normalized columns of \tilde{U} , i.e. $\tilde{U} = U \Sigma$.

$$\begin{aligned}
 \text{Then } \tilde{U} &= A V \Rightarrow U \Sigma = A V \\
 &\Rightarrow U \Sigma V^T = A
 \end{aligned}$$

Note: Matlab

$$[U, \Sigma, V] = \text{svd}(A)$$