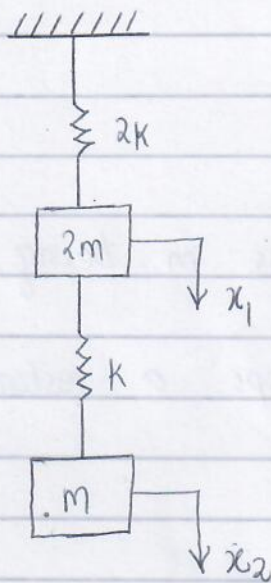


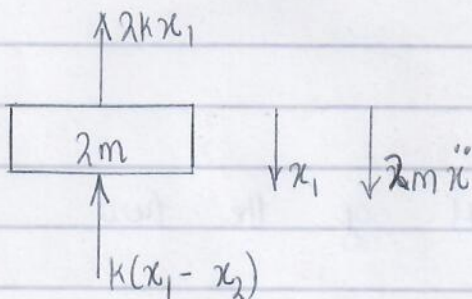
# Vibration of CHAPTER 2 = 2 degrees of freedom systems



- Find the natural frequencies of this system
- Determine the ratio of amplitudes
- Draw the mode shapes

solution

Give a displacement  $x_1$  to mass  $2m$  and a displacement  $x_2$  to mass  $m$



spring  $2k$  is stretched by  $x_1$  and develops a restoring force  $2kx_1$  (opposing the accn)  
spring  $k$  is compressed by  $(x_1 - x_2)$  and develops a restoring force  $k(x_1 - x_2)$

$$2m\ddot{x}_1 = -2kx_1 - k(x_1 - x_2)$$

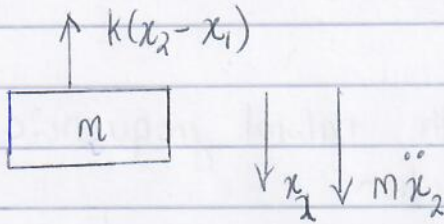
$$2m\ddot{x}_1 + 2kx_1 + k(x_1 - x_2) = 0 \quad 2m\ddot{x}_1 + 2kx_1$$

$$2m\ddot{x}_1 + 3kx_1 - kx_2 = 0 \quad \text{Ia}$$

$$2m\ddot{x}_1 = -2kx_1 - k(x_1 - x_2)$$

$$2m\ddot{x}_1 + 2kx_1 + k(x_1 - x_2) = 0$$

$$2m\ddot{x}_1 + 3kx_1 - kx_2 = 0$$



spring  $k$  is stretched  $(x_2 - x_1)$  by mass  $m$  being displaced by  $x_2$ . It thus develops a restoring force  $k(x_2 - x_1)$  that opposes  $m\ddot{x}_2$

$$m\ddot{x}_2 = -k(x_2 - x_1)$$

$$m\ddot{x}_2 + k(x_2 - x_1) = 0$$

$$m\ddot{x}_2 + kx_2 - kx_1 = 0 \quad 2a$$

Assume that the S.H.M of the two masses is of the form

$$x_1 = A \sin(\omega t + \phi)$$

$$x_2 = B \sin(\omega t + \phi)$$

$$\dot{x}_1 = A\omega \cos(\omega t + \phi)$$

$$\dot{x}_2 = B\omega \cos(\omega t + \phi)$$

$$\ddot{x}_1 = -A\omega^2 \sin(\omega t + \phi)$$

$$\ddot{x}_2 = -B\omega^2 \cos(\omega t + \phi)$$

(SHM)



Replace the relevant terms from (HMI) into 1a and 2a

$$2m\ddot{x}_1 + 3kx_1 - kx_2 = 0 \quad 1a$$

$$-2m\omega^2 A \sin \omega t + 3kA \sin \omega t - kB \sin \omega t = 0$$

$$(3kA - 2m\omega^2 A) \sin \omega t = kB \sin \omega t$$

$$(3k - 2m\omega^2)A = kB$$

$$\frac{A}{B} = \frac{k}{3k - 2m\omega^2} \quad 1b$$

$$m\ddot{x}_2 + kx_2 - kx_1 = 0 \quad 2a$$

$$-m\omega^2 B \sin \omega t + kB \sin \omega t - kA \sin \omega t = 0$$

$$(kB - m\omega^2 B) \sin \omega t = kA \sin \omega t$$

$$(k - m\omega^2)B = kA$$

$$\frac{k - m\omega^2}{k} = \frac{A}{B} \quad 2b$$

$$1a = 2b \Rightarrow \frac{k}{3k - 2m\omega^2} = \frac{k - m\omega^2}{k}$$

$$(3k - 2m\omega^2)(k - m\omega^2) = k^2$$

$$3k^2 - 3km\omega^2 - 2km\omega^2 + 2m^2\omega^4 - k^2 = 0$$

$$2m^2\omega^4 - 5km\omega^2 + 2k^2 = 0$$

$$\omega^4 - \frac{5km\omega^2}{2m^2} + \frac{2k^2}{2m^2} = 0$$

$$\omega^4 - \frac{5k}{2m}\omega^2 + \frac{k^2}{m^2} = 0$$

$$\text{let } p = \omega^2 \Rightarrow p^2 = \omega^4$$

$$\omega^4 - \frac{5k}{2m}\omega^2 + \frac{k^2}{m^2} = 0 \Rightarrow p^2 - \frac{5k}{2m}p + \frac{k^2}{m^2} = 0$$

4a

To solve for  $p$  using the quadratic formula

$$a=1 \quad b=-\frac{5K}{2m} \quad c=\frac{K^2}{m^2}$$

$$P_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{5K}{4m} \pm \frac{1}{2} \sqrt{\left(\frac{5K}{2m}\right)^2 - \frac{4K^2}{m^2}}$$

$$= \frac{5K}{4m} \pm \frac{1}{2} \sqrt{\frac{25K^2}{4m^2} - \frac{4K^2}{m^2}}$$

$$= \frac{5K}{4m} \pm \frac{1}{2} \sqrt{\frac{25K^2 - 16K^2}{4m^2}} = \frac{5K}{4m} \pm \frac{1}{2} \sqrt{\frac{9K^2}{4m^2}}$$

$$= \frac{5K}{4m} \pm \frac{1}{2} \left( \frac{3K}{2m} \right)$$

$$= \frac{5K}{4m} \pm \frac{3K}{4m}$$

$$P_1 = \frac{5K}{4m} + \frac{3K}{4m} = \frac{8K}{4m} = \frac{2K}{m} \quad P_2 = \frac{5K}{4m} - \frac{3K}{4m} = \frac{2K}{4m} = \frac{1}{2} \frac{K}{m}$$

$$P_1 = \omega_{1n}^2 = \frac{2K}{m}$$

$$P_2 = \omega_{2n}^2 = \frac{K}{2m}$$

$$\omega_{1n} = \sqrt{\frac{2K}{m}}$$

$$\omega_{2n} = \sqrt{\frac{K}{2m}}$$

$\omega_{1n}$  and  $\omega_{2n}$  are the natural frequencies of the system



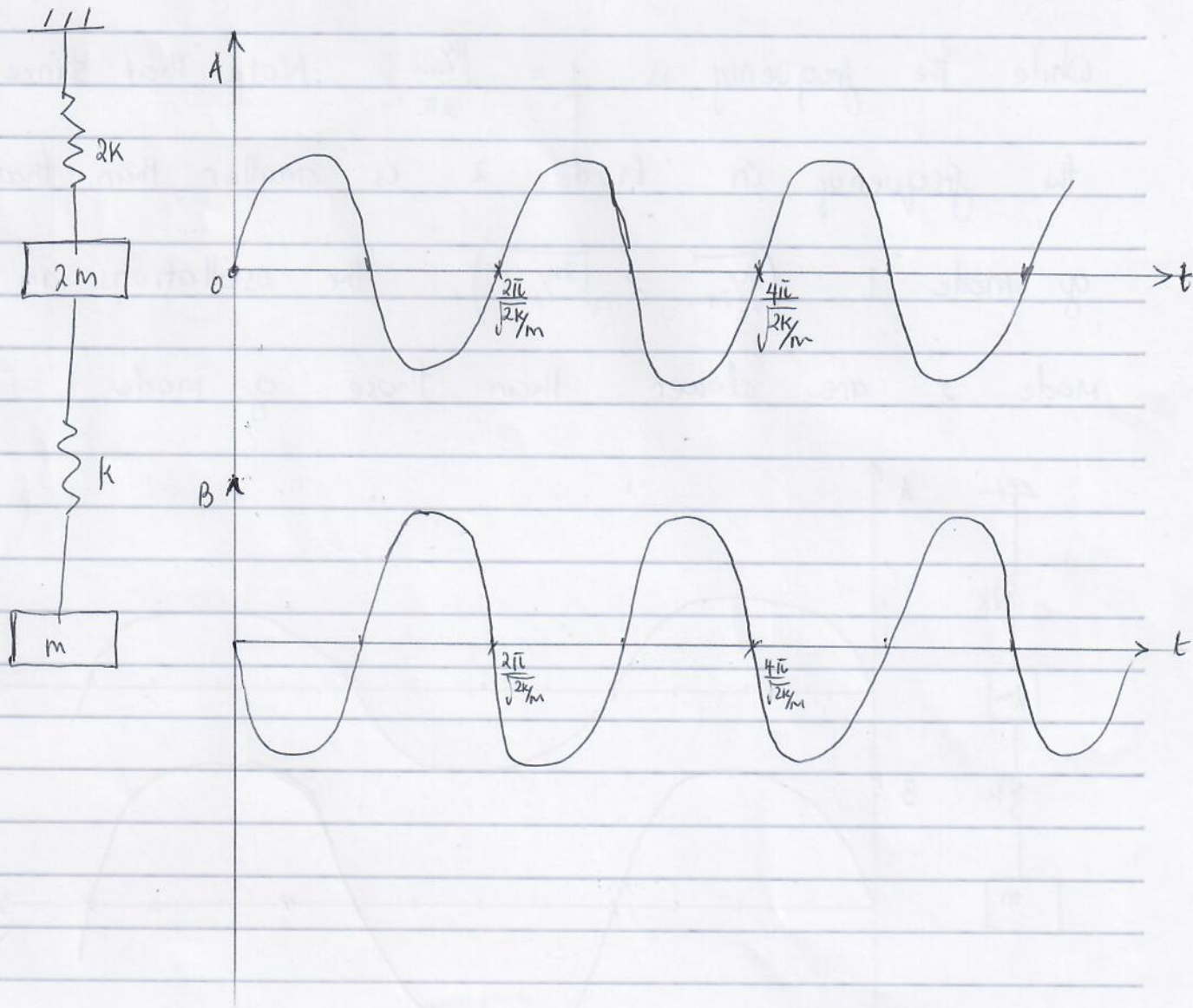
Mode shape 1

$$\frac{A}{B} = \frac{k}{3k - 2m\omega^2} \quad \text{when } \omega^2 = \omega_{in}^2 = \frac{2k}{m}$$

$$\Rightarrow \frac{A}{B} = \frac{k}{3k - 2m(2k/m)} = \frac{k}{3k - 4k} = \frac{k}{-k} = -1$$

The period of oscillation is  $\frac{2\pi}{\omega_{in}} = \frac{2\pi}{\sqrt{2k/m}}$

The frequency of oscillation is  $\frac{1}{T} = \frac{\sqrt{2k/m}}{2\pi}$



Mode shape 2

$$\frac{A}{B} = \frac{K - m\omega^2}{K} \quad \text{when } \omega^2 = \omega_{2n}^2 = \frac{K}{2m}$$

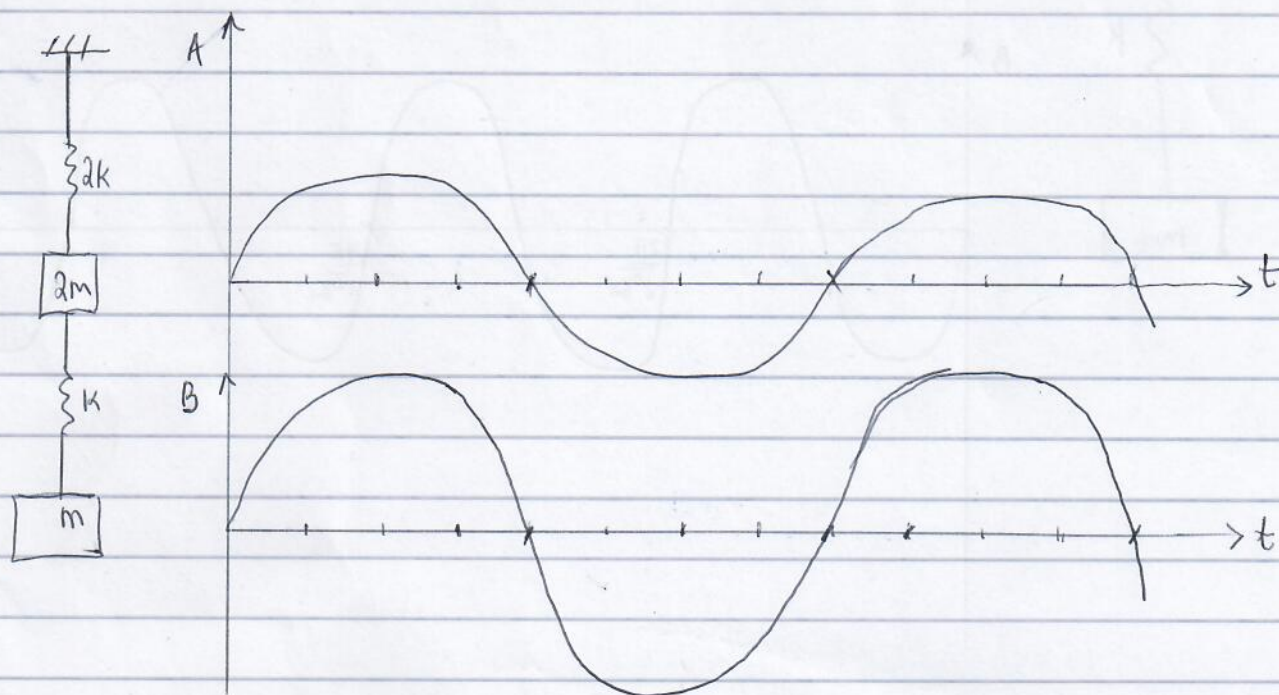
$$\frac{A}{B} = \frac{K - m(K/2m)}{K} = \frac{K - K/2}{K} = \frac{2K - K}{2K} = \frac{1}{2}$$

A and B are in phase but the amplitude of B is twice that of A.

The period of oscillation is  $\frac{2\pi}{\omega_{2n}} = \frac{2\pi}{\sqrt{K/2m}}$

while the frequency is  $\frac{1}{T} = \frac{\sqrt{K/2m}}{2\pi}$ . Note that since

the frequency in mode 2 is smaller than that of mode 1 ( $\sqrt{K/2m} < \sqrt{2K/m}$ ), the oscillations in mode 2 are slower than those of mode 1





Alternative solution approach - Use <sup>of</sup> Eigen value & Eigen vector

Recall equations 1a and 2a

$$2m\ddot{x}_1 + 3kx_1 - kx_2 = 0 \quad 1a$$

$$m\ddot{x}_2 + kx_2 - kx_1 = 0 \quad 2a$$

The motion of undamped systems such as this one is sinusoidal of the form

$$x_1 = A \sin(\omega t + \phi)$$

$$\dot{x}_1 = A\omega \cos(\omega t + \phi)$$

$$\ddot{x}_1 = -A\omega^2 \sin(\omega t + \phi)$$

$$= -\omega^2 x_1$$

$$x_2 = B \sin(\omega t + \phi)$$

$$\dot{x}_2 = B\omega \cos(\omega t + \phi)$$

$$\ddot{x}_2 = -B\omega^2 \sin(\omega t + \phi)$$

$$= -\omega^2 x_2$$

substituting for  $\ddot{x}_1$  and  $\ddot{x}_2$  in 1a and 2a

$$-2m\omega^2 x_1 + 3kx_1 - kx_2 = 0$$

$$-m\omega^2 x_2 + kx_2 - kx_1 = 0$$

$$-\omega^2 x_1 + \frac{3k}{2m} x_1 - \frac{k}{2m} x_2 = 0$$

$$-\omega^2 x_2 + \frac{k}{m} x_2 - \frac{k}{m} x_1 = 0$$

$$\left( \frac{3k}{2m} - \omega^2 \right) x_1 - \left( \frac{k}{2m} \right) x_2 = 0$$

$$-\left( \frac{k}{m} \right) x_1 + \left( \frac{k}{m} - \omega^2 \right) x_2 = 0$$

6

$$\begin{bmatrix} \frac{3k}{2m} - \omega^2 & -\frac{k}{2m} \\ -\frac{k}{m} & \frac{k}{m} - \omega^2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad (Q)$$

A matrix is multiplied by a vector to yield the null/zero vector which is a form of the eigenvalue/eigen vector equation with  $\lambda = \omega^2$

$$(Q) = (A - I\lambda)(x) = 0 \Rightarrow \lambda = \text{eigen value}$$

The only way (Q) is possible is if the determinant of  $(A - I\lambda)$  is zero if we disregard the trivial solution  $[x] = 0$

$$\det(A - I\lambda) = 0$$

$$\begin{vmatrix} \frac{3k}{2m} - \omega^2 & -\frac{k}{2m} \\ -\frac{k}{m} & \frac{k}{m} - \omega^2 \end{vmatrix} = 0 \Rightarrow \begin{vmatrix} \frac{3k}{2m} - \lambda & -\frac{k}{2m} \\ -\frac{k}{m} & \frac{k}{m} - \lambda \end{vmatrix} = 0$$

$$\left(\frac{3k}{2m} - \lambda\right)\left(\frac{k}{m} - \lambda\right) - \frac{k^2}{2m^2} = 0$$



$$\frac{3K^2}{2m^2} - \frac{3K}{2m} \lambda - \frac{K}{m} \lambda + \lambda^2 - \frac{K^2}{m^2} = 0$$

$$\lambda^2 - \left[ \frac{3K}{2m} + \frac{K}{m} \right] \lambda + \frac{3K^2}{2m^2} - \frac{K^2}{m^2} = 0$$

$$\lambda^2 - \left[ \frac{3K+2K}{2m} \right] \lambda + \frac{K^2}{m^2} = 0$$

$$\lambda^2 - \frac{5K}{2m} \lambda + \frac{K^2}{m^2} = 0 \quad (Q_1)$$

We solved (Q<sub>1</sub>) earlier where it was a polynomial in p.

$$\Rightarrow \lambda_{1,2} = \frac{5K}{4m} \pm \frac{3K}{4m} \Rightarrow \lambda_1 = \frac{2K}{m} \quad \lambda_2 = \frac{K}{2m}$$

$$\lambda_1 = \omega_{1n}^2 \Rightarrow \omega_{1n} = \sqrt{\frac{2K}{m}} \quad \lambda_2 = \omega_{2n}^2 \Rightarrow \omega_{2n} = \sqrt{\frac{K}{2m}}$$

Obtaining the eigen vectors corresponding to  $\lambda_1 = \frac{2K}{m}$  from Q

$$\left( \frac{3K}{2m} - \frac{2K}{m} \right) x_1 - \frac{K}{2m} x_2 = 0 \Rightarrow -\frac{K}{2m} x_1 - \frac{K}{2m} x_2 = 0 \quad (i)$$

$$-\frac{K}{m} x_1 + \left( \frac{K}{m} - \frac{2K}{m} \right) x_2 = 0 \Rightarrow -\frac{K}{m} x_1 - \frac{K}{m} x_2 = 0 \quad (ii)$$

You see that i) and ii) are multiples of each other and therefore we can use either to get  $x_1$  and  $x_2$

Using ii)

$$-\frac{k}{m}x_1 - \frac{k}{m}x_2 = 0 \Rightarrow -\frac{k}{m}x_1 = \frac{k}{m}x_2$$

$$-x_1 = x_2$$

$$\text{Choose } x_1 = 1 \Rightarrow x_2 = -1$$

The first eigen vector is thus  $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$  or if we had chosen  $x_1 = -1$  then  $x_2 = 1 \Rightarrow$  Eigen vector =  $\pm \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

obtaining the eigen vector corresponding to

$$\lambda_2 = \frac{k}{2m} \text{ from } Q$$

$$\begin{bmatrix} \frac{3k}{2m} - \frac{k}{2m} & -\frac{k}{2m} \\ -\frac{k}{m} & \frac{k}{m} - \frac{k}{2m} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$



$$\frac{2K}{2m} x_1 - \frac{K}{2m} x_2 = 0 \quad \text{iii)}$$

$$-\frac{K}{m} x_1 + \frac{K}{2m} x_2 = 0 \quad \text{iv)}$$

iii and iv are multiples of each other and we can use either. Using iv

$$\frac{K}{m} x_1 = \frac{K}{2m} x_2 \Rightarrow x_1 = \frac{1}{2} x_2$$

$$2x_1 = x_2$$

choosing  $x_1 = 1$ ,  $x_2 = 2$

Therefore the second eigen vector is  $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$

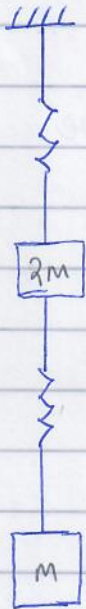
or  $\begin{pmatrix} -1 \\ -2 \end{pmatrix}$  if  $x_1 = -1$  and  $x_2 = -2$ . Therefore this eigen vector is  $\pm \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

Note that these eigen vectors are equal

to the amplitude ratios  $\frac{A}{B}$  in the previous solution to the problem. Therefore eigen vectors represent the mode shapes of the system.

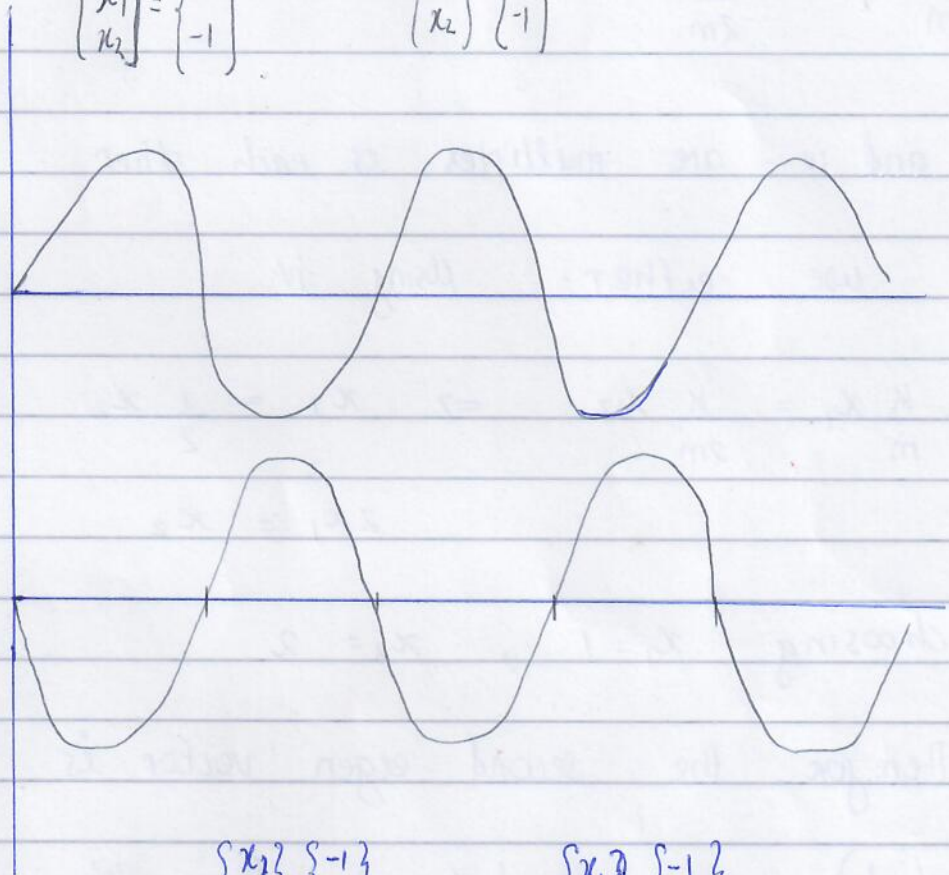
Also

The mode shape corresponding to  $\omega_1 = \sqrt{\lambda_1} = \sqrt{\frac{2k}{m}}$  is indicated by eigen vector  $V_1 = \pm \begin{pmatrix} 1 \\ -1 \end{pmatrix}$



$$\begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \begin{Bmatrix} 1 \\ -1 \end{Bmatrix}$$

$$\begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \begin{Bmatrix} 1 \\ -1 \end{Bmatrix}$$

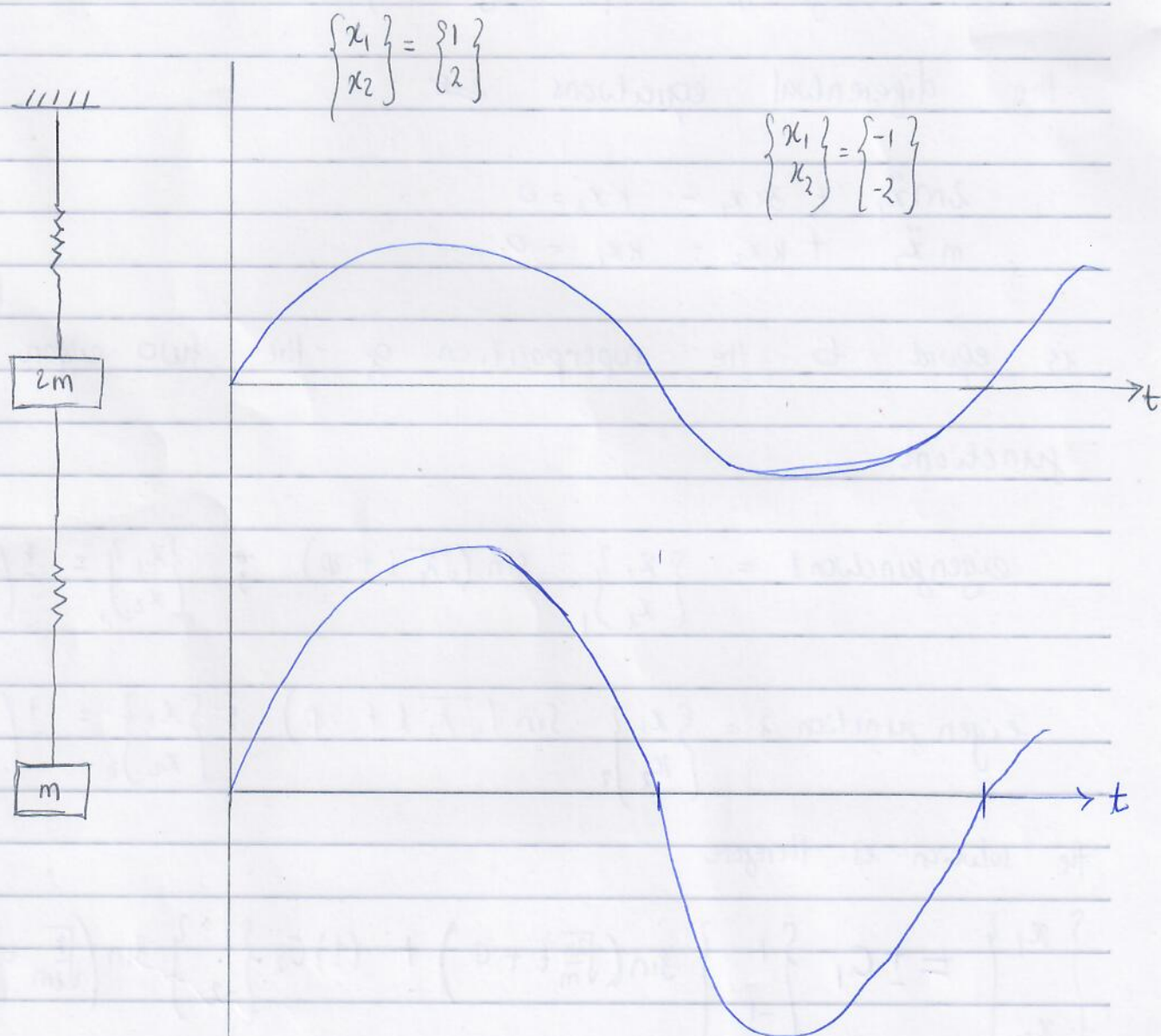


$$\begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \begin{Bmatrix} -1 \\ 1 \end{Bmatrix}$$

$$\begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \begin{Bmatrix} -1 \\ 1 \end{Bmatrix}$$



The mode shape corresponding to  $\omega_2 = \sqrt{\lambda_2} = \sqrt{\frac{K}{M}}$  is indicated by eigen vector  $V_2 = \pm \begin{pmatrix} 1 \\ 2 \end{pmatrix}$



Note that since  $\omega_2 = \sqrt{\frac{K}{M}} < \omega_1 = \sqrt{\frac{2K}{m}}$ , mode 1 has a higher frequency, i.e. more oscillations per second than mode 2.

An eigen function is a set of independent functions which are solutions to differential equations.

for this ~~system~~, coupled system, the solution to the differential equations is

$$\begin{aligned} 2m\ddot{x}_1 + 3kx_1 - kx_2 &= 0 \\ m\ddot{x}_2 + kx_2 - kx_1 &= 0 \end{aligned}$$

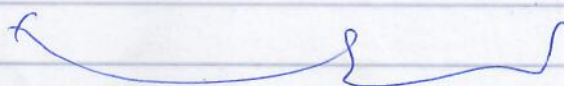
is equal to the superposition of the two eigen functions

$$\text{eigenfunction 1} = \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix}_1 \sin(\sqrt{\lambda_1} t + \phi) ; \quad \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix}_1 = \pm \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\text{eigenfunction 2} = \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix}_2 \sin(\sqrt{\lambda_2} t + \phi) ; \quad \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix}_2 = \pm \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

the solution is therefore

$$\begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \pm C_1 \begin{Bmatrix} 1 \\ -1 \end{Bmatrix} \sin\left(\sqrt{\frac{2k}{m}} t + \phi\right) + (\pm) C_2 \begin{Bmatrix} 1 \\ 2 \end{Bmatrix} \sin\left(\sqrt{\frac{k}{2m}} t + \phi\right)$$



mode 1



mode 2.