```
view_frames Result

Recorded at time: 1697726899.023468
```

```
                          sim_link
              /                          \
   Broadcaster: default_authority    Broadcaster: default_authority
   Average rate: 100.196             Average rate: 20.199
   Buffer length: 5.02               Buffer length: 5.0
   Most recent transform: 1697726898.998599   Most recent transform: 1697726899.001429
   Oldest transform: 1697726893.978457        Oldest transform: 1697726894.001177
              |                                            |
          base_link                                    cup_link

   Broadcaster: default_authority
   Average rate: 18.346
   Buffer length: 4.96
   Most recent transform: 1697726898.959038
   Oldest transform: 1697726893.998708
              |
           turret

   Broadcaster: default_authority
   Average rate: 18.346
   Buffer length: 4.96
   Most recent transform: 1697726898.959038
   Oldest transform: 1697726893.998708
              |
          upperarm

   Broadcaster: default_authority
   Average rate: 18.346
   Buffer length: 4.96
   Most recent transform: 1697726898.959038
   Oldest transform: 1697726893.998708
              |
          forearm

   Broadcaster: default_authority
   Average rate: 18.346
   Buffer length: 4.96
   Most recent transform: 1697726898.959038
   Oldest transform: 1697726893.998708
              |
           wrist

   Broadcaster: default_authority
   Average rate: 18.346
   Buffer length: 4.96
   Most recent transform: 1697726898.959038
   Oldest transform: 1697726893.998708
              |
           hand
         /        \
Broadcaster: default_authority    Broadcaster: default_authority
Average rate: 18.346              Average rate: 18.346
Buffer length: 4.96              Buffer length: 4.96
Most recent transform: 1697726898.959038   Most recent transform: 1697726898.959038
Oldest transform: 1697726893.998708        Oldest transform: 1697726893.998708
   /                                            \
gripper_left                                 gripper_right
```