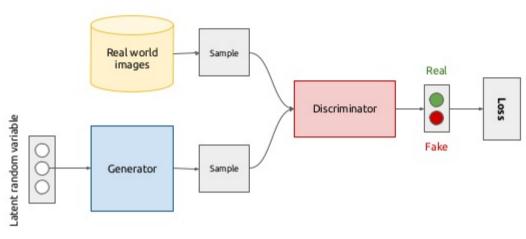
Generative Adversarial Networks for Cosmology Mass Maps (Simulation Emulation)

Mustafa Mustafa

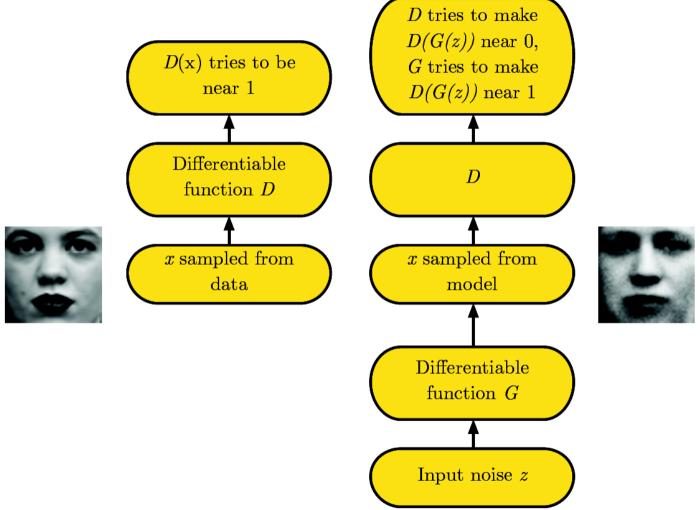
Berkeley Lab. 02/21/2017

Generative Adversarial Networks



Kevin McGuinness 5

Generative Adversarial Networks



(Goodfellow 2016)

Generative Adversarial Networks – Loss Functions

Saturating game (Minimax):

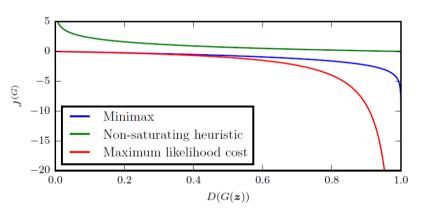
$$J^{(D)} = -\frac{1}{2} \mathbb{E}_{\boldsymbol{x} \sim p_{\text{data}}} \log D(\boldsymbol{x}) - \frac{1}{2} \mathbb{E}_{\boldsymbol{z}} \log (1 - D(G(\boldsymbol{z})))$$
$$J^{(G)} = -J^{(D)}$$

Ian Goodfellow arXiv:1701.00160

Generative Adversarial Networks – Loss Functions

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Generative Adversarial Networks – Loss Functions

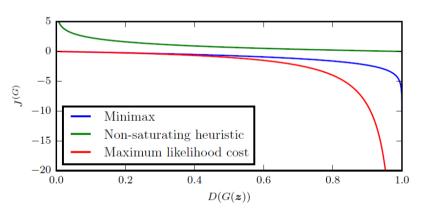
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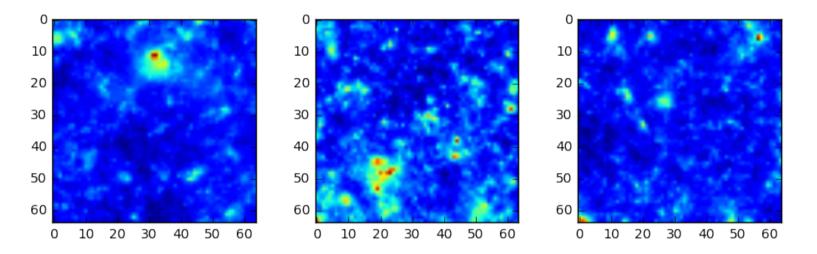
Non-saturating game (heuristic):

$$J^{(G)} = -\frac{1}{2} \mathbb{E}_{z} \log D \left(G(z) \right)$$

Ian Goodfellow arXiv:1701.00160



Cosmology Mass Maps Simulator Emulator



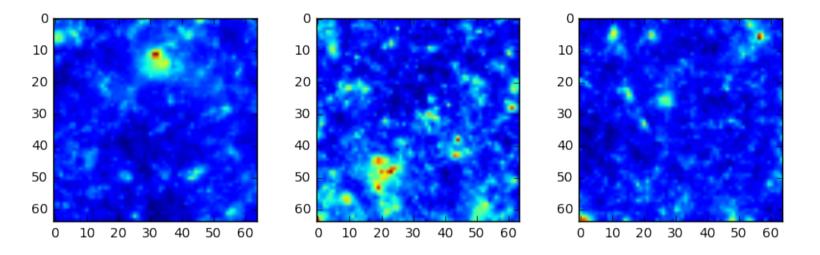
Basic idea:

Cosmologist need to run computationally expensive simulations of the mass density maps of the universe with different parameters $\sigma = (\sigma 1, \sigma 2, ...)$. The evolution of the universe is not deterministic, i.e. you can get "different" mass maps for the same set of parameters σ^* .

We want to explore if we can use GANs to help in reducing the computational time. A reliable GAN duet might also be used to extract features or summary statistics.

The fidelity of the generated images can be checked using a cosmologist metric ("summary statistics").

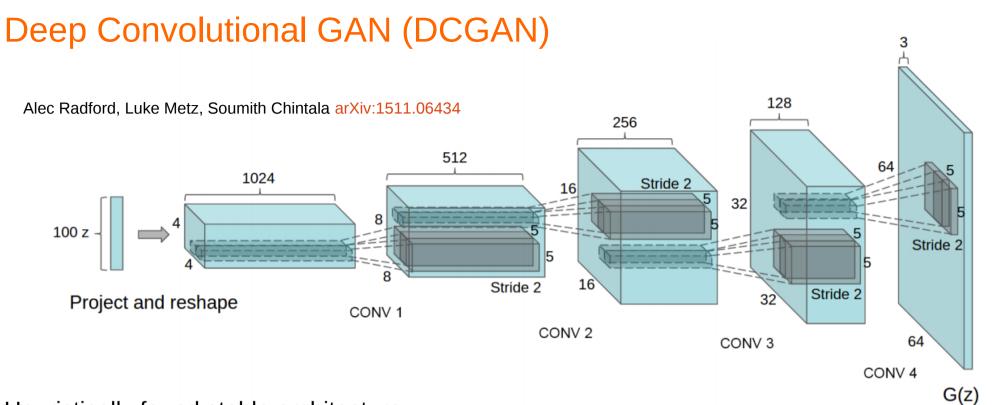
Cosmology Mass Maps Simulator Emulator



Dataset:

1000 1024x1024 mass maps generated at one σ^* point. It is possible to generate more if needed.

- → **Ultimate goal:** a conditional/parametric generator $G(\sigma, z)$, where σ is the cosmologists vector of parameters and z is a vector of random noise
- **Current goal:** G(z) which will generate images at the fixed point σ^* of our test sample

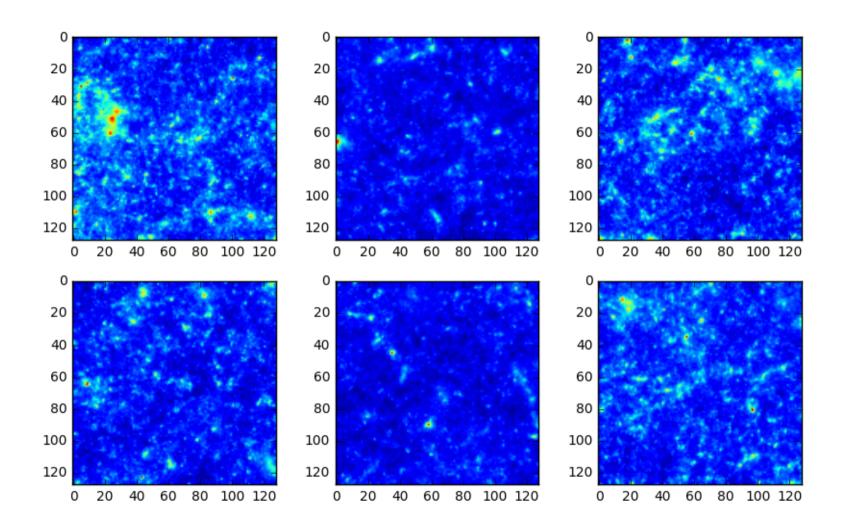


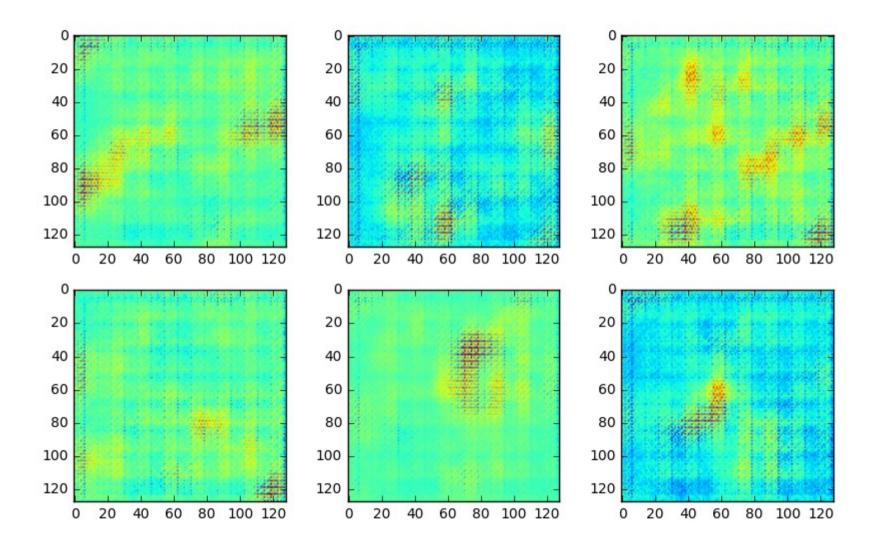
Heuristically found stable architecture

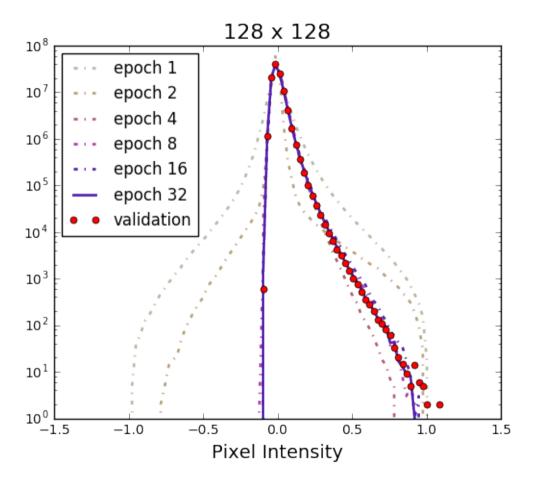
Architecture guidelines for stable Deep Convolutional GANs

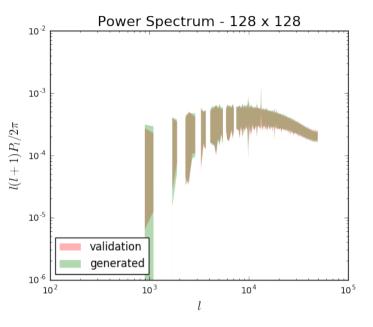
- Replace any pooling layers with strided convolutions (discriminator) and fractional-strided convolutions (generator).
- Use batchnorm in both the generator and the discriminator.
- Remove fully connected hidden layers for deeper architectures.
- Use ReLU activation in generator for all layers except for the output, which uses Tanh.

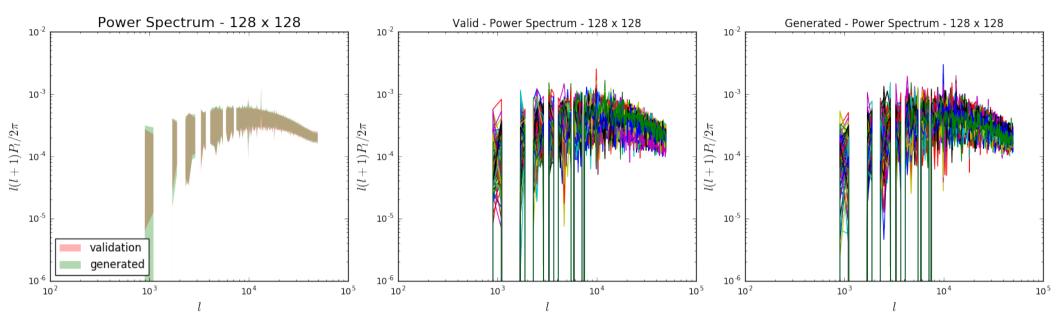
• Use LeakyReLU activation in the discriminator for all layers.

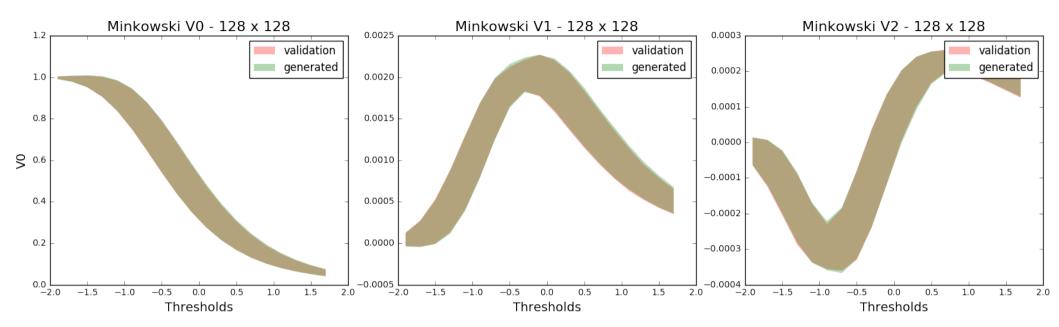


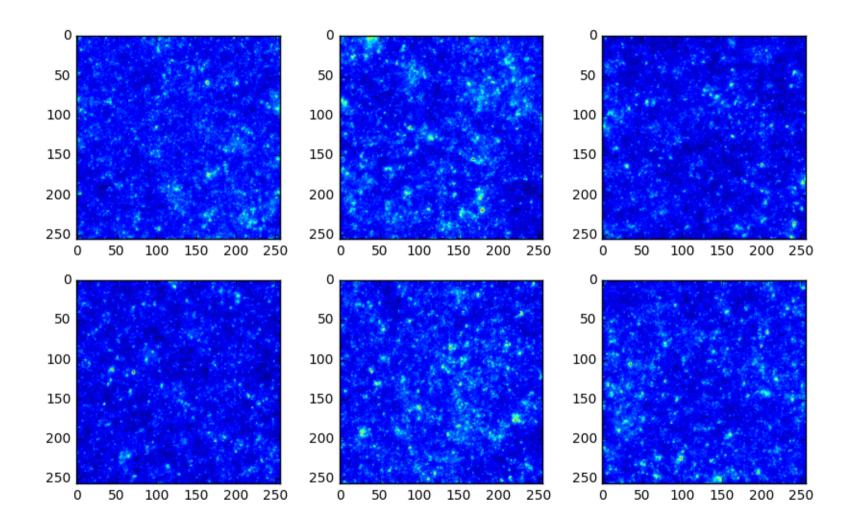


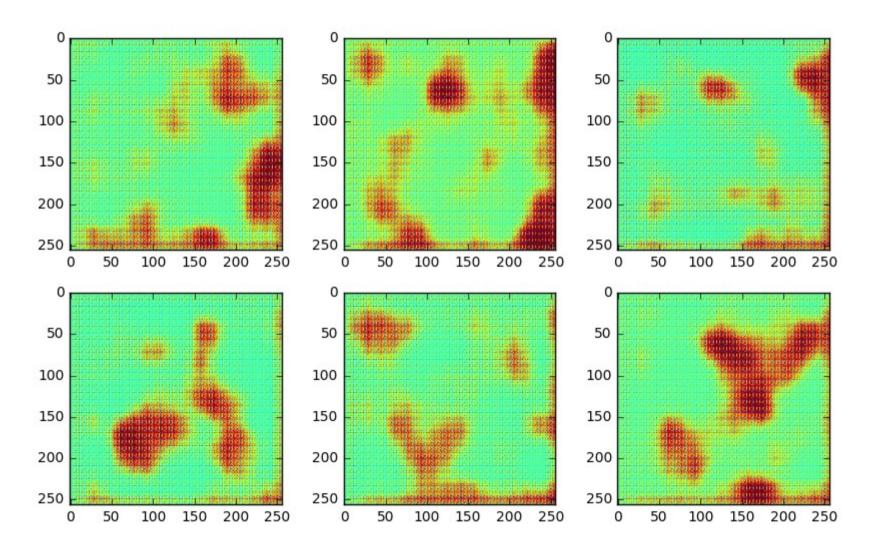


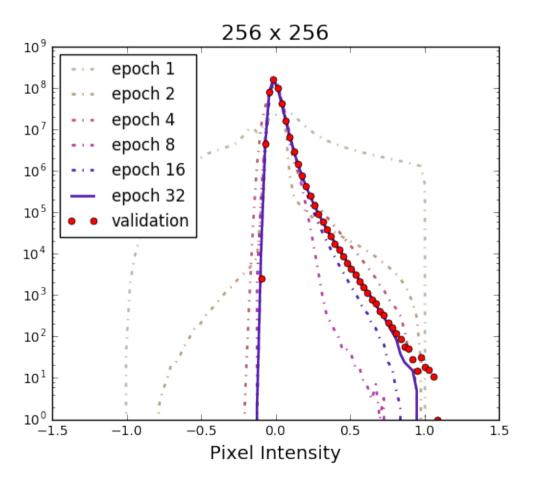


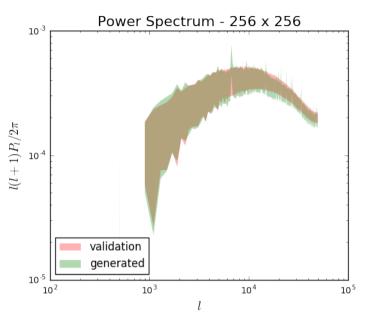


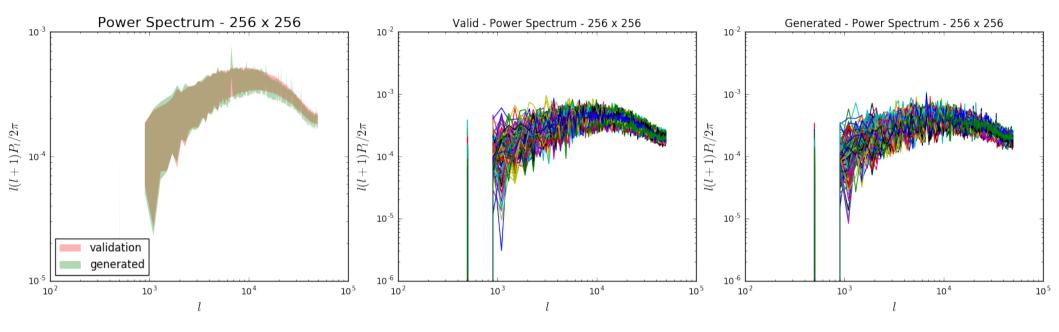


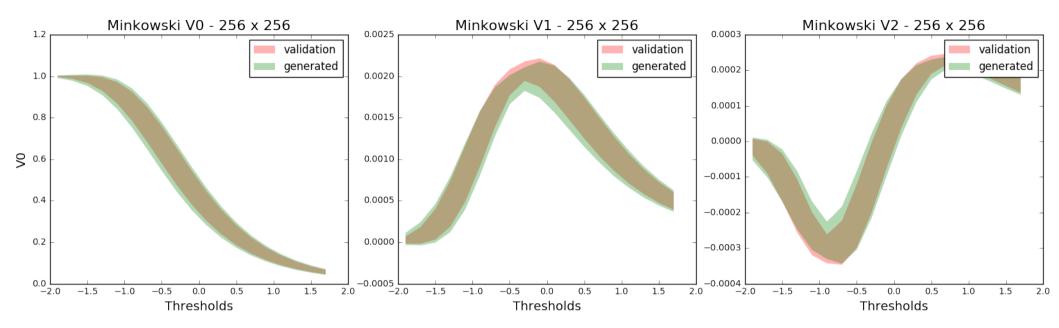


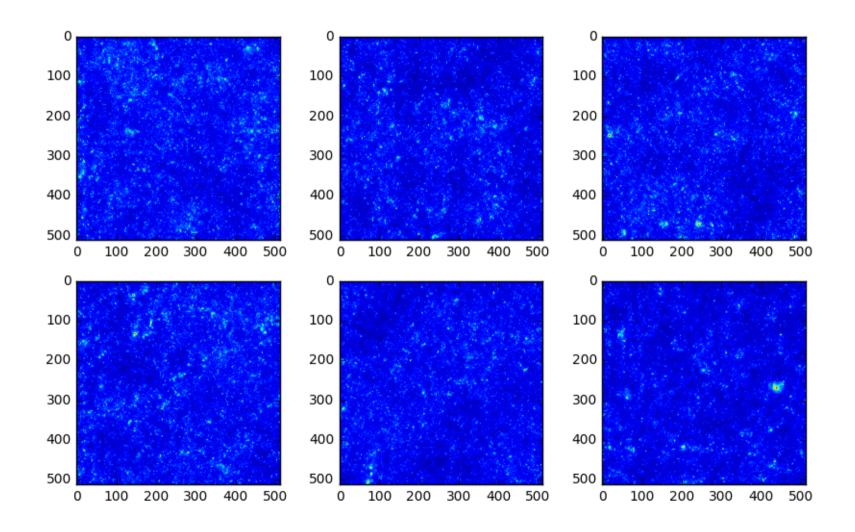


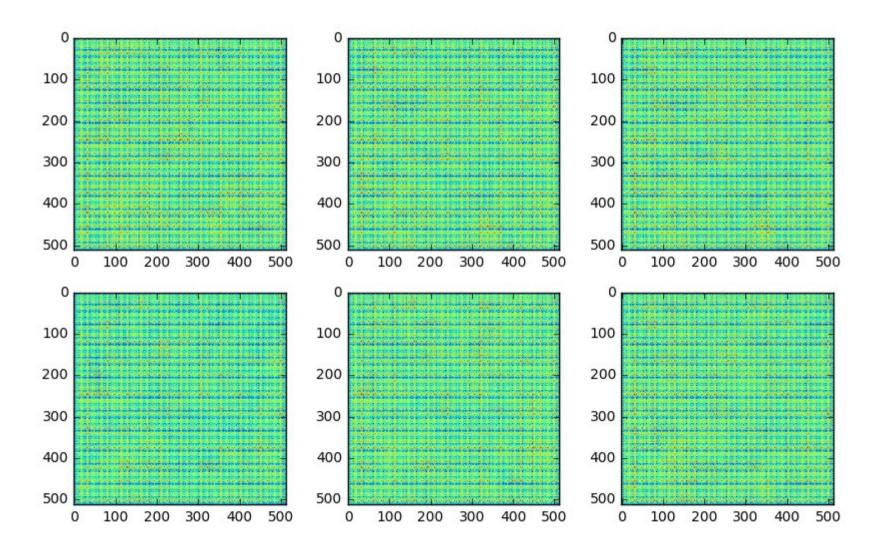


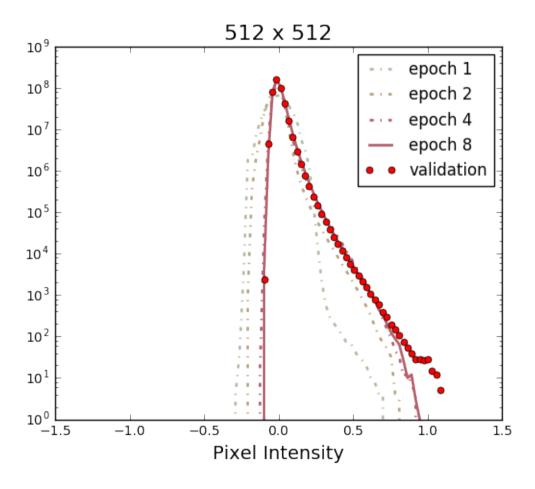


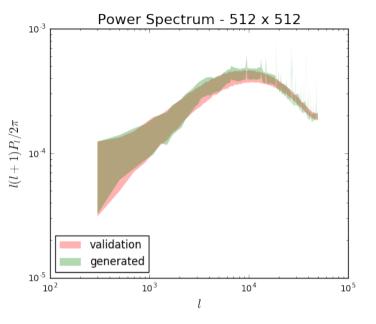


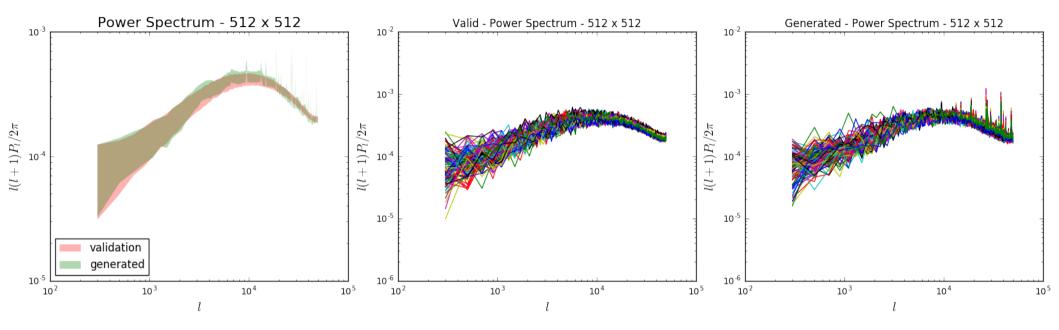


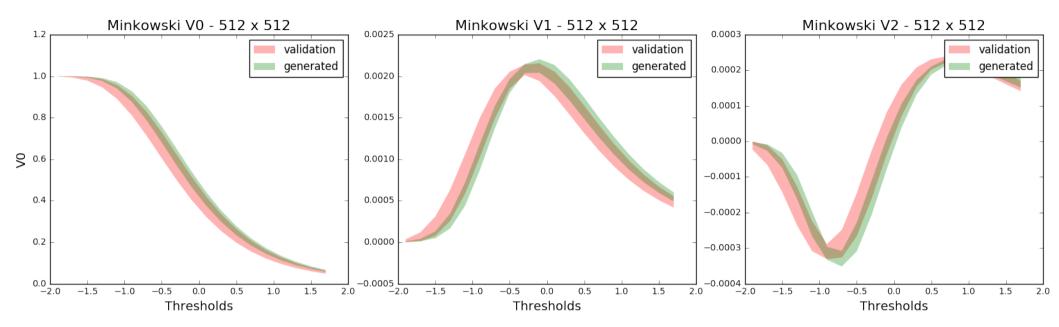












Publication plan

Stage - I

The purpose of the first stage is to highlight the potential capabilities of using Generative Models to accelerate scientific simulations.

A possible twist: How important is what we are doing to Deep Learning?

Stage - II

We continue with our scientific investigations. Most importantly:

- 1) Interpretation of what the network is learning about the physics
- 2) Parametric Generators