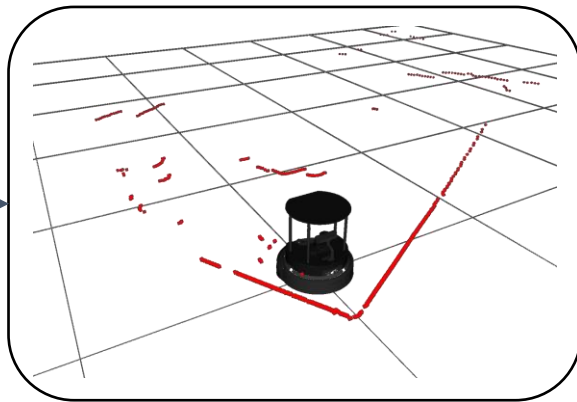
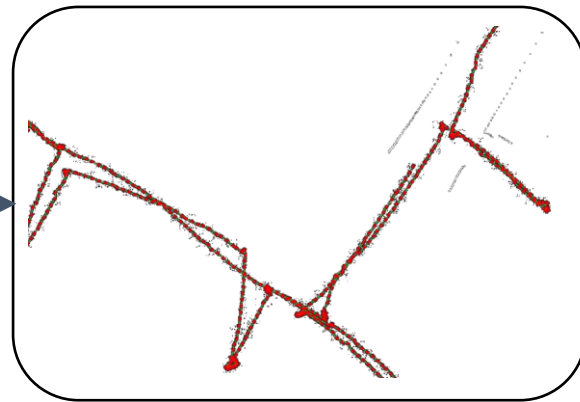




a) 2D Laser-Equipped Robots



b) Localized laser scan



c) Pose Graph



d) Map