

Conjugate Direction Methods

- First, consider a quadratic problem:

$$\min f(\mathbf{x}) = \frac{1}{2} \mathbf{x}' \mathbf{Q} \mathbf{x} - \mathbf{b}' \mathbf{x}$$

where \mathbf{Q} is positive definite

- Is it convex?
- What is the equivalent linear program?

How to solve it?

- Start gently
 - Consider the simplest case
 - When $Q = I$ ~~$= 0$~~
- Orthogonality of searching directions a must?
- Can we extend it to general Q ?

Conjugacy

- Given a positive definite matrix Q , a set of nonzero vectors d^1, \dots, d^k are *Q-conjugate* if
$$d^i{}' Q d^j = 0, \text{ for all } i \text{ and } j \text{ such that } i \neq j$$
- If d^1, \dots, d^k are Q-conjugate, they are *linearly independent*

Conjugate Direction Method for Quadratic Optimization

1. Start with arbitrary x^0
2. Get d^0, \dots, d^{n-1} which are *Q -conjugate*
3. Repeat

$$x^{k+1} = x^k + \alpha^k d^k$$

$$\text{Where } \alpha^k = \operatorname{argmin}_{\alpha} f(x^k + \alpha d^k)$$

for $k = 0, \dots, n-1$

- Intuition: dimensional decomposition
 - “orthogonal” w.r.t. Q

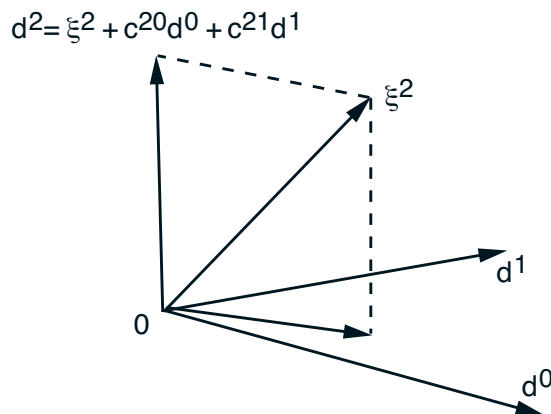
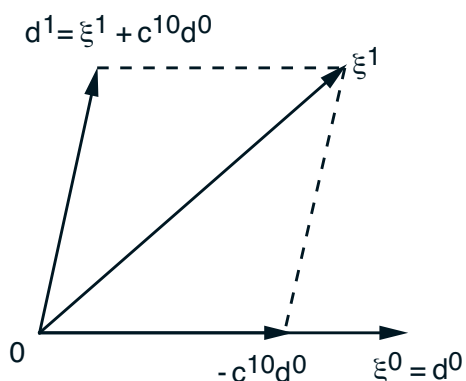
GENERATING Q -CONJUGATE DIRECTIONS

- Given set of linearly independent vectors ξ^0, \dots, ξ^k , we can construct a set of Q -conjugate directions d^0, \dots, d^k s.t. $\text{Span}(d^0, \dots, d^i) = \text{Span}(\xi^0, \dots, \xi^i)$
- *Gram-Schmidt procedure.* Start with $d^0 = \xi^0$. If for some $i < k$, d^0, \dots, d^i are Q -conjugate and the above property holds, take

$$d^{i+1} = \xi^{i+1} + \sum_{m=0}^i c^{(i+1)m} d^m;$$

choose $c^{(i+1)m}$ so d^{i+1} is Q -conjugate to d^0, \dots, d^i ,

$$d^{i+1'} Q d^j = \xi^{i+1'} Q d^j + \left(\sum_{m=0}^i c^{(i+1)m} d^m \right)' Q d^j = 0.$$



CONJUGATE GRADIENT METHOD

- Apply Gram-Schmidt to the vectors $\xi^k = -g^k = -\nabla f(x^k)$, $k = 0, 1, \dots, n - 1$. Then

$$d^k = -g^k + \sum_{j=0}^{k-1} \frac{g^{k'} Q d^j}{d^{j'} Q d^j} d^j$$

- **Key fact:** Direction formula can be simplified.

Proposition : The directions of the CGM are generated by $d^0 = -g^0$, and

$$d^k = -g^k + \beta^k d^{k-1}, \quad k = 1, \dots, n - 1,$$

where β^k is given by

$$\beta^k = \frac{g^{k'} g^k}{g^{k-1'} g^{k-1}} \quad \text{or} \quad \beta^k = \frac{(g^k - g^{k-1})' g^k}{g^{k-1'} g^{k-1}}$$

Furthermore, the method terminates with an optimal solution after at most n steps.

- Extension to nonquadratic problems.

Conjugate Gradient Methods applied to Nonquadratic Problems

- $\min f(x)$, where $f(x)$ is a general function
 - use the same algorithm
- $x^{k+1} = x^k + \alpha^k d^k$

Where $\alpha^k = \operatorname{argmin}_{\alpha} f(x^k + \alpha d^k)$
 $d^k = -g^k + \beta^k d^{k-1}$
- Approximation: $d0, d1, \dots$, gradually lose conjugacy. Remedies:
 - Restart every n iterations (with a steepest descent)
 - Restart when conjugacy is lost
- Line search may be expensive

Quasi-Newton Method

- Newton's method:
 - $d^k = - (H^k)^{-1} g^k$
 - But $(H^k)^{-1}$ is expensive to evaluate
- Can we approximate $(H^k)^{-1}$ given
 - x^0, x^1, \dots, x^{k-1}
 - f^0, f^1, \dots, f^{k-1}
 - g^0, g^1, \dots, g^{k-1}

QUASI-NEWTON METHODS

- $x^{k+1} = x^k - \alpha^k D^k \nabla f(x^k)$, where D^k is an inverse Hessian approximation.
- Key idea: Successive iterates x^k, x^{k+1} and gradients $\nabla f(x^k), \nabla f(x^{k+1})$, yield curvature info

$$q^k \approx \nabla^2 f(x^{k+1}) p^k,$$

$$p^k = x^{k+1} - x^k, \quad q^k = \nabla f(x^{k+1}) - \nabla f(x^k),$$

$$\nabla^2 f(x^n) \approx [q^0 \ \dots \ q^{n-1}] [p^0 \ \dots \ p^{n-1}]^{-1}$$

- Most popular Quasi-Newton method is a clever way to implement this idea

$$D^{k+1} = D^k + \frac{p^k p^{k'}}{p^{k'} q^k} - \frac{D^k q^k q^{k'} D^k}{q^{k'} D^k q^k} + \xi^k \tau^k v^k v^{k'},$$

$$v^k = \frac{p^k}{p^{k'} q^k} - \frac{D^k q^k}{\tau^k}, \quad \tau^k = q^{k'} D^k q^k, \quad 0 \leq \xi^k \leq 1$$

and $D^0 > 0$ is arbitrary, α^k by line minimization, and $D^n = Q^{-1}$ for a quadratic.

Summary of Gradient Methods

- Steepest Descent
 - 1 iteration for linear problems
- Newton's Method
 - 1 iteration for quadratic problems
- Conjugate gradient and quasi-Newton
 - n iterations for quadratic problems
- All solve non-quadratic problems heuristically
 - needs infinite number of iterations to converge

More comparisons

- **Advantages of Quasi-Newton over conjugate gradient for nonquadratic problems:**
 - Better local convergence since QN approximates Newton
 - Does not need to periodically restart
 - CGM loses conjugacy, while QN improves approximation
 - Experimentally, QN is less sensitive to linear search quality
- **Complexity per iteration:**
 - Newton: $O(n^3)$, f , gradient, Hessian, to generate H^{k-1}
 - QN: $O(n^2)$, f , gradient, to generate D^k
 - CGM: $O(n)$, f , gradient, to generate d^k
 - CGM is preferable when n is large and computing gradient is efficient