第三次实验报告

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实验过程

首先手动实现 gcnconv 层,然后分别构建节点分类和链路预测的模型,并根据任务分别处理数据集,如链路预测需要额外的训练集的负样本采样,最后进行调参选取验证集准确率/AUC 最高的模型参数在测试集上测试

关键代码展示

```
import torch
import torch.nn as nn
def pair_norm(x):
        mean = x.mean(dim=0, keepdim=True)
        std = x.std(dim=0, keepdim=True)
        return (x - mean) / (std + 1e-6)
class GCNLayer(nn.Module):
    def __init__(self, in_channels, out_channels, normalize):
        super(GCNLayer, self).__init__()
        self.projection = nn.Linear(in_channels, out_channels)
        self.normalize = normalize
    def forward(self, node_feats, adj_matrix (parameter) adj_matrix: Any
        adj_matrix = adj_matrix + torch.eye(adj_matrix.size(0), device=adj_matrix.device)
        deg_matrix = torch.diag(torch.sum(adj_matrix, dim=1))
        deg_inv_sqrt = torch.pow(deg_matrix, -0.5)
        deg_inv_sqrt[deg_inv_sqrt == float('inf')] = 0
        adj_matrix_normalized = torch.mm(torch.mm(deg_inv_sqrt, adj_matrix), deg_inv_sqrt)
        node_feats = self.projection(node_feats)
        if self.normalize:
            node_feats = pair_norm(node_feats)
        node_feats = torch.mm(adj_matrix_normalized, node_feats)
        return node_feats
```

由图卷积的公式,根据邻接矩阵和度矩阵得到归一化拉普拉斯矩阵,以此进行图卷积

```
class GCN(nn.Module):
    def __init__(self, in_channels, hidden_channels, out_channels, dropout, layer_num, drop_prob=0.0, normalize=True)
    super(GCN, self).__init__()
    self.layers = nn.ModuleList()
    self.layers.append(GCNLayer(in_channels, hidden_channels, drop_prob))
    for __in range(layer_num - 2):
        self.layers.append(GCNLayer(hidden_channels, hidden_channels, drop_prob))
    self.layers.append(GCNLayer(hidden_channels, hidden_channels, drop_prob))
    self.activation = nn.ReLU()
    self.readout = nn.Linear(hidden_channels, out_channels)
    self.dropout = nn.Dropout(dropout)
    self.normalize = normalize

def forward(self, x, adj_matrix):
    for layer in self.layers:
        x = layer(x, adj_matrix, self.normalize)
        x = self.activation(x)
        x = self.dropout(x)
        x = self.readout(x)
        return x
```

通过实施的图卷积层进行信息聚合,最后通过 MLP 进行分类任务,可直接用于节点分类

```
class GCN LP(nn.Module):
   def __init__(self, in_channels, hidden_channels, out_channels, dropout, layer_num, normalize, drop_prob):
       super(GCN_LP, self).__init__()
       self.drop_edge = drop_prob
       self.layers = nn.ModuleList()
       self.layers.append(GCNLayer(in_channels, hidden_channels, normalize))
       for _ in range(layer_num - 2):
           self.layers.append(GCNLayer(hidden_channels, hidden_channels, normalize))
       self.layers.append(GCNLayer(hidden_channels, out_channels, normalize))
       self.activation = nn.ReLU()
       self.dropout = nn.Dropout(dropout)
   def encode(self, x, edge_index):
       num_nodes = x.size(0)
       adj_matrix = torch.zeros((num_nodes, num_nodes), device=edge_index.device)
       adj_matrix[edge_index[0], edge_index[1]] = 1
       adj_matrix = adj_matrix + torch.eye(adj_matrix.size(0), device=adj_matrix.device)
       adj_matrix = drop_edge(adj_matrix, self.drop_edge)
       deg_matrix = torch.diag(torch.sum(adj_matrix, dim=1))
       deg_inv_sqrt = torch.pow(deg_matrix, -0.5)
       deg_inv_sqrt[deg_inv_sqrt == float('inf')] = 0
       adj_matrix_normalized = torch.mm(torch.mm(deg_inv_sqrt, adj_matrix), deg_inv_sqrt)
       for i, layer in enumerate(self.layers):
           x = layer(x, adj_matrix_normalized)
           if i < len(self.layers) - 1:</pre>
              x = self.activation(x)
               x = self.dropout(x)
   def decode(self, z, edge_label_index):
       src = z[edge_label_index[0]]
       dst = z[edge_label_index[1]]
       r = (src * dst).sum(dim=-1)
   def forward(self, x, edge_index, edge_label_index):
       z = self.encode(x, edge_index)
       return self.decode(z, edge_label_index)
```

对于链路预测任务,则在模型中需要将边转化为邻接矩阵,最后通过邻接矩阵的预测得到 边的预测

参数分析

自环:在图中给结点添加一条自己到自己的边,可以降低卷积后特征值大小,从而缓解梯度爆炸,在本实验中准确率和 auc 提升显著

Pairnorm: 为解决过平滑问题而使用的 normalziaition, 但本实验图卷积层数少效果更佳, 是否使用 pairnorm 并没有什么区别

Dropedge: 在链路预测时解决过平滑问题, 在使用两层卷积层时同样没有什么效果

层数: 两层效果最好